# SOME ADDITIONAL RESULTS ON PRINCIPAL COMPONENTS ANALYSIS OF THREE-MODE DATA BY MEANS OF ALTERNATING LEAST SQUARES ALGORITHMS 

Jos M. F. ten Berge<br>UNIVERSITY OF GRONINGEN<br>Jan de Leeuw and Pieter M. Kroonenberg<br>UNIVERSITY OF LEIDEN


#### Abstract

Kroonenberg and de Leeuw (1980) have developed an alternating least-squares method TUCKALS-3 as a solution for Tucker's three-way principal components model. The present paper offers some additional features of their method. Starting from a reanalysis of Tucker's problem in terms of a rank-constrained regression problem, it is shown that the fitted sum of squares in TUCKALS-3 can be partitioned according to elements of each mode of the three-way data matrix. An upper bound to the total fitted sum of squares is derived. Finally, a special case of TUCKALS-3 is related to the Carroll/Harshman CANDECOMP/PARAFAC model.


Key words: partitioning of least-squares fit, rank-constrained regression, Candecomp, Parafac.

## Introduction

Kroonenberg and de Leeuw (1980) have offered an alternating least-squares solution (TUCKALS-3) for the three-mode principal component model developed by Tucker (1963, 1964, 1966). Their solution is based on the observation that the optimal core matrix can be expressed uniquely and explicitly in terms of the data and the component matrices for the three modes. The latter component matrices are optimized by an alternating least-squares algorithm.

The present paper is aimed at offering some results for TUCKALS-3 in addition to those given by Kroonenberg and de Leeuw. First, it will be shown that the fitted sum of squares in TUCKALS-3 can be partitioned according to elements of each mode. This result is based on a rederivation of TUCKALS-3 in terms of a rank-constrained regression problem. Next, an upper bound to this fitted sum of squares will be derived. Finally, a relationship between a special case of TUCKALS-3 and the Carroll/Harshman CANDECOMP/PARAFAC model (see Harshman \& Lundy, 1984a, 1984b and Carroll \& Pruzansky, 1984) will be demonstrated.

In the next section the main features of TUCKALS-3, as given by Kroonenberg and de Leeuw (1980), will be revisited.

## The Tucker- 3 Model and the TUCKALS-3 Solution

Let $Z$ be a three mode data matrix of order $\ell \times m \times n$ with elements $z_{i j k}, i=1, \ldots$, $\ell ; j=1, \ldots, m ; k=1, \ldots, n$. The least-squares fitting of the Tucker- 3 model implies

[^0]minimizing the residual sum of squares
\[

$$
\begin{equation*}
\sum_{i, j, k}\left(z_{i j k}-\hat{z}_{i j k}\right)^{2}, \tag{1}
\end{equation*}
$$

\]

where $\hat{z}_{i j k}$ is a weighted sum of elements of an $\ell \times s$ matrix $G$, an $m \times t$ matrix $H$, an $n \times u$ matrix $E$, and an $s \times t \times u$ core matrix $C$ (Kroonenberg \& de Leeuw, 1980, p. 70). In TUCKALS-3 the matrices $G, H$ and $E$ are restricted to be column-wise orthonormal.

Let $Z_{\ell}$ be the $\ell \times m n$ matrix containing the $m$ lateral $\ell \times n$ planes of $Z$, then the associated fitted parts of $Z$ can be collected in the $\ell \times m n$ matrix

$$
\begin{equation*}
\hat{Z}_{\ell}=G C_{s}\left(H^{\prime} \otimes E^{\prime}\right) \tag{2}
\end{equation*}
$$

where $C_{s}$ is the $s \times t u$ matrix containing the $t$ lateral $s \times u$ planes of $C$, and $\otimes$ is the Kronecker product. Clearly, minimizing (1) is equivalent to minimizing

$$
\begin{equation*}
f(G, H, E, C)=\left\|Z_{\ell}-\hat{Z}_{\ell}\right\|^{2}=\left\|Z_{\ell}-G C_{s}\left(H^{\prime} \otimes E^{\prime}\right)\right\|^{2} \tag{3}
\end{equation*}
$$

For fixed $G, H$, and $E$ the minimizing $C_{s}$ is uniquely defined as

$$
\begin{equation*}
C_{s}=G^{\prime} Z_{\ell}(H \otimes E) \tag{4}
\end{equation*}
$$

(Penrose, 1956, p. 18). Hence minimizing (1) reduces to minimizing

$$
\begin{equation*}
g(G, H, E)=\left\|Z_{\ell}-G G^{\prime} Z_{\ell}\left(H H^{\prime} \otimes E E^{\prime}\right)\right\|^{2} \tag{5}
\end{equation*}
$$

which, in turn, is equivalent to maximizing

$$
\begin{equation*}
p(G, H, E)=\operatorname{tr} G^{\prime} Z_{\ell}\left(H H^{\prime} \otimes E E^{\prime}\right) Z_{\ell}^{\prime} G \stackrel{d}{=} \operatorname{tr} G^{\prime} P G \tag{6}
\end{equation*}
$$

In a completely parallel fashion, it can be shown that

$$
\begin{equation*}
p(G, H, E)=\operatorname{tr} H^{\prime} Z_{m}\left(E E^{\prime} \otimes G G^{\prime}\right) Z_{m}^{\prime} H^{\stackrel{d}{d}} \operatorname{tr} H^{\prime} Q H \tag{7}
\end{equation*}
$$

where $Z_{m}$ is the $m \times \ell n$ matrix containing the $n$ transposed frontal $\ell \times m$ planes of $Z$, and that

$$
\begin{equation*}
p(G, H, E)=\operatorname{tr} E^{\prime} Z_{n}\left(G G^{\prime} \otimes H H^{\prime}\right) Z_{n}^{\prime} E \stackrel{d}{=} \operatorname{tr} E^{\prime} R E, \tag{8}
\end{equation*}
$$

where $Z_{n}$ is the $n \times \ell m$ matrix containing the $\ell$ horizontal $n \times m$ planes of $Z$, (Kroonenberg \& de Leeuw, 1980, p. 72).

The TUCKALS- 3 solution consists of iteratively improving $G$ for fixed $H$ and $E, H$ for fixed $G$ and $E$, and $E$ for fixed $G$ and $H$, starting from Tucker's final solution for $G, H$ and $E$ (Tucker, 1966, p. 297). That is, initially $G$ consists of the principal $s$ eigenvectors of $Z_{\ell} Z_{\ell}^{\prime} ; H$ consists of the principal $t$ eigenvectors of $Z_{m} Z_{m}^{\prime}$, and $E$ consists of the principal $u$ eigenvectors of $Z_{n} Z_{n}^{\prime}$. The procedure terminates when a necessary condition for a maximum is satisfied, that is, when simultaneously $G$ contains the $s$ principal eigenvectors of $P, H$ contains the $t$ principal eigenvectors of $Q$, and $E$ contains the $u$ principal eigenvectors of $R$. We shall now rederive the TUCKALS-3 solution from a generalized perspective.

## An Alternative Approach to the Least Squares Fitting of the Tucker-3 Model

Kroonenberg and de Leeuw (1980, p. 70) noted that it is merely a matter of convenience to have $G, H$ and $E$ constrained to be orthonormal column-wise. This point will now be elaborated in a generalized approach to the Tucker-3 model, in which the orthonormality constraints are omitted. The derivation to be given below applies equally to $G$,
$H$ and $E$ but we shall only consider $G$ in full detail. The derivations for $H$ and $E$ are completely analogous.

Let $H$ and $E$ be fixed matrices of rank $t$ and $u$, respectively, and let $F \stackrel{d}{=} H \otimes E$. Then the TUCKALS- 3 problem can be reduced to the problem of minimizing

$$
\begin{equation*}
h\left(G, C_{s}\right) \stackrel{d}{\|}\left\|Z_{\ell}^{\prime}-F C_{s}^{\prime} G^{\prime}\right\|^{2} \tag{9}
\end{equation*}
$$

refer to (3). Although it is possible to express the minimizing $G$ in terms of $C_{s}$ and vice versa, we shall simply address the problem of finding the optimal product $C_{s}^{\prime} G^{\prime} \stackrel{d}{=} W$ and consider the function

$$
\begin{equation*}
h(W)=\left\|Z_{\ell}^{\prime}-F W\right\|^{2} . \tag{10}
\end{equation*}
$$

The solution to this problem depends critically on the relative sizes of $s, \ell$, and $t u$. Because $\ell \geq s$ and because $s \leq t u$ (Tucker, 1966, p. 288) we only need to consider the case $\ell \geq t u \geq s$ and the case $\overline{t u} \geq \ell \geq s$. In the former case, solving (10) as an ordinary unconstrained least squares problem yields the well-known minimizing solution $W=$ $\left(F^{\prime} F\right)^{-1} F^{\prime} Z_{\ell}^{\prime}$, which generally has rank $t u \geq s$, because $W$ is of order $t u \times \ell$. If $t u>s$ then this $W$ cannot possibly be expressed as $W=C_{s}^{\prime} G^{\prime}$ where $G^{\prime}$ has rank $s$. Therefore, the unconstrained least-squares solution is not generally valid as a solution for (10) in the case $\ell \geq t u \geq s$.

Conversely, if $t u \geq \ell \geq s$ then $\left(F^{\prime} F\right)^{-1} F^{\prime} Z_{\ell}^{\prime}$ generally has rank $\ell \geq s$ which is again incompatible with having a $W$ of rank $s$ or lower. In order to find a generally valid minimizing solution for (10) we shall want to minimize (10) subject to the constraint that $W$ have rank $s$ or lower. This constraint guarantees that $W$ can always be expressed as $C_{s}^{\prime} G^{\prime}$ with $G^{\prime}$ of rank $s$. Let $r$ denote the rank of the optimal $W, r \leq s$.

In order to minimize (10) subject to its constraint, let $W$ be expressed in terms of an $r$-dimensional basis $A$, orthonormal in the metric ( $F^{\prime} F$ ). That is, let

$$
\begin{equation*}
W=A B \tag{11}
\end{equation*}
$$

for some $t u \times r$ matrix $A$ satisfying $\left(A^{\prime} F^{\prime} F A\right)=I_{r}$, and some $r \times \ell$ matrix $B$. This takes care of the constraint on $W$, and makes for a straightforward solution. Combining (10) and (11) shows that we are to minimize

$$
\begin{equation*}
h(A, B)=\left\|Z_{\ell}^{\prime}-F A B\right\|^{2} . \tag{12}
\end{equation*}
$$

For any $A$ meeting the constraint the minimizing $B$ can be uniquely expressed as the unconstrained least squares solution

$$
\begin{equation*}
B=\left(A^{\prime} F^{\prime} F A\right)^{-1} A^{\prime} F^{\prime} Z_{t}^{\prime}=A^{\prime} F^{\prime} Z_{\ell}^{\prime} \tag{13}
\end{equation*}
$$

Therefore, it remains to minimize

$$
\begin{equation*}
h(A)=\left\|Z_{\ell}^{\prime}-F A A^{\prime} F^{\prime} Z_{\ell}^{\prime}\right\|^{2}=\operatorname{tr} Z_{\ell} Z_{\ell}^{\prime}-\operatorname{tr} A^{\prime} F^{\prime} Z_{\ell}^{\prime} Z_{\ell} F A \tag{14}
\end{equation*}
$$

or, equivalently, to maximize

$$
\begin{equation*}
h^{*}(A)=\operatorname{tr} A^{\prime} F^{\prime} Z_{\ell}^{\prime} Z_{\ell} F A \tag{15}
\end{equation*}
$$

Consider the singular value decomposition

$$
\begin{equation*}
\left(F^{\prime} F\right)^{-1 / 2} F^{\prime} Z_{\ell}^{\prime}=U \Gamma V^{\prime} \tag{16}
\end{equation*}
$$

with $U^{\prime} U=V^{\prime} V=I$ and $\Gamma$ diagonal, nonnegative, and ordered. Combining (15) and (16)
yields

$$
\begin{equation*}
h^{*}(A)=\operatorname{tr} A^{\prime}\left(F^{\prime} F\right)^{1 / 2} U \Gamma^{2} U^{\prime}\left(F^{\prime} F\right)^{1 / 2} A . \tag{17}
\end{equation*}
$$

Since $\left(F^{\prime} F\right)^{1 / 2} A$ is a column-wise orthonormal matrix of rank $r \leq s$, (17) is maximized if and only if $\left(F^{\prime} F\right)^{1 / 2} A$ contains the first $s$ columns of $U$, $\overline{\text { possibly }}$ rotated. Let $U_{s}$ be the $t u \times s$ matrix containing the first $s$ columns of $U$. Then (17) is maximized if and only if

$$
\begin{equation*}
A=\left(F^{\prime} F\right)^{-1 / 2} U_{s} T \tag{18}
\end{equation*}
$$

for some orthonormal $s \times s$ matrix $T$, and hence the maximizing $B$ is

$$
\begin{equation*}
B=T^{\prime} U_{s}^{\prime}\left(F^{\prime} F\right)^{-1 / 2} F^{\prime} Z_{l}^{\prime}=T^{\prime} U_{s}^{\prime} U \Gamma V^{\prime}=T^{\prime} \Gamma_{s} V_{s}^{\prime}, \tag{19}
\end{equation*}
$$

where $\Gamma_{s}$ is the upper left $s \times s$ submatrix of $\Gamma$, and $V_{s}$ is the $\ell \times s$ matrix containing the first $s$ columns of $V$. It follows that (9) is minimal for

$$
\begin{equation*}
C_{s}^{\prime} G^{\prime}=A B=\left(F^{\prime} F\right)^{-1 / 2} U_{s} \Gamma_{s} V_{s}^{\prime} \tag{20}
\end{equation*}
$$

This leaves us with an infinity of possibilities for determining $C_{s}$ and $G$. For instance, we may take

$$
\begin{equation*}
C_{s}^{\prime}=\left(F^{\prime} F\right)^{-1 / 2} U_{s} \quad \text { and } \quad G^{\prime}=\Gamma_{s} V_{s}^{\prime}, \tag{21}
\end{equation*}
$$

which implies that $C_{s}^{\prime}$ is column-wise orthonormal in the metric ( $F^{\prime} F$ ), or we may take

$$
\begin{equation*}
C_{s}^{\prime}=\left(F^{\prime} F\right)^{-1 / 2} U_{s} \Gamma_{s} \quad \text { and } \quad G^{\prime}=V_{s}^{\prime}, \tag{22}
\end{equation*}
$$

and so on.
Parallel expressions to (21) and (22) can be obtained for updating the pair ( $H, C$ ) and the pair $(E, C)$ by keeping $G$ and $E$ and $G$ and $H$ fixed, respectively. As a result, taking $G$, $H$, and $E$ column-wise orthonormal does not constrain the function (3). In addition, if $G$, $H$ and $E$ are taken column-wise orthonormal, then so is $F=H \otimes E$. In that case, $C_{s}$ in (22) reduces to a row-wise orthogonal matrix. Clearly, parallel expressions hold for the core matrix "flattened" in the other two directions, which means that after convergence of TUCKALS-3 with orthonormal $G, H$ and $E$ the core matrix $C$ is "orthogonal in every direction." This property of "all-orthogonality" has first been noted by Weesie and van Houwelingen (1983, p. 7), who derived an alternative for TUCKALS-3 which can handle missing data.

In TUCKALS- 3 only the matrices $G, H$ and $E$ are explicitly updated according to (22) with column-wise orthornormal $F$, and its parallel expressions. However, $C$ is not updated until convergence. This can be explained by the fact that $C$ can be expressed in terms of $G, H$ and $E$, see (4). When $G, H$ or $E$ is updated, $C$ is updated implicitly. Therefore, TUCKALS- 3 can be interpreted as an iterative procedure of updating the pairs ( $G, C$ ), ( $H, C$ ) and ( $E, C$ ), respectively.

The present rederivation of TUCKALS-3 provides us with certain explicit expressions which facilitate a further examination of the fit in TUCKALS-3. This will be elaborated below.

## Partitioning the Fit in TUCKALS-3

Since $p(G, H, E)$ is the sum of squares of $\hat{Z}$ it can be interpreted as a measure of fit in TUCKALS-3. It can be shown that, as in ordinary linear regression analysis, the residual sum of squares and the fit add up to the total observed sum of squares. That is,

$$
\begin{equation*}
\left\|\hat{Z}_{\ell}\right\|^{2}+\left\|Z_{\ell}-\hat{Z}_{\ell}\right\|^{2}=\left\|Z_{\ell}\right\|^{2} . \tag{23}
\end{equation*}
$$

Instead of proving (23) we shall prove a stronger result, based on a partitioning of the fit over separate elements of each of the three modes. Our argument strengthens and generalizes results of Harshman and Lundy (1984a, p. 198) on the interpretation of squared PARAFAC loadings as variances.

Proof. Let it be assumed that the pair ( $G, C$ ) has been updated by (20), thus minimizing (9) for fixed $H$ and $E$. Then the fitted part of $Z_{\ell}^{\prime}$ is

$$
\begin{equation*}
\hat{Z}_{t}^{\prime}=F\left(F^{\prime} F\right)^{-1 / 2} U_{s} \Gamma_{s} V_{s}^{\prime} . \tag{24}
\end{equation*}
$$

Consider the $i$-th column of $\hat{Z}_{\ell}^{\prime}$, which is the fitted part of $Z$ associated with the $i$-th element of the $\ell$-mode, $i=1, \ldots, \ell$. Let this column be denoted by $\hat{Z}_{\ell}^{\prime} e_{i}$, where $e_{i}$ is the $i$-th column of the $\ell \times \ell$ identity matrix. Then we have from (24)

$$
\begin{equation*}
\hat{Z}_{\ell}^{\prime} e_{i}=F\left(F^{\prime} F\right)^{-1 / 2} U_{s} \Gamma_{s} V_{s}^{\prime} e_{i} \tag{25}
\end{equation*}
$$

It will now be shown that the sum of squares of the $i$-th column of $Z_{\ell}^{\prime}$ equals the sum of fitted and residual sum of squares. That is,

$$
\begin{equation*}
\left\|Z_{\ell}^{\prime} e_{i}\right\|^{2}=\left\|\hat{Z}_{\ell}^{\prime} e_{i}\right\|^{2}+\left\|Z_{\ell}^{\prime} e_{i}-\hat{Z}_{\ell}^{\prime} e_{i}\right\|^{2} \tag{26}
\end{equation*}
$$

or, equivalently,

$$
\begin{equation*}
e_{i}^{\prime} Z_{l} \hat{Z}_{\ell}^{\prime} e_{i}=e_{i}^{\prime} \hat{Z}_{\ell} \hat{Z}_{\ell}^{\prime} e_{i} \tag{27}
\end{equation*}
$$

It follows at once from (25) that the right-hand side of (27) equals $e_{i}^{\prime} V_{s} \Gamma_{s}^{2} V_{s}^{\prime} e_{i}$. In addition, from (25) and (16) we have

$$
\begin{equation*}
e_{i}^{\prime} Z_{\ell} \hat{Z}_{\ell}^{\prime} e_{i}=e_{i}^{\prime} Z_{\ell} F\left(F^{\prime} F\right)^{-1 / 2} U_{s} \Gamma_{s} V_{s}^{\prime} e_{i}=e_{i}^{\prime} V \Gamma U^{\prime} U_{s} \Gamma_{s} V_{s}^{\prime} e_{i}=e_{i}^{\prime} V_{s} \Gamma_{s}^{2} V_{s}^{\prime} e_{i} \tag{28}
\end{equation*}
$$

which completes the proof of (27).
It follows that the fitted sum of squares can be partitioned over elements of the $\ell$-mode, when the pair ( $G, C$ ) has been updated according to ( 20 ). Parallel expressions can be derived for the $m$-mode and the $n$-mode. Hence after convergence of TUCKALS- 3 the fitted sum of squares can be partitioned over the elements of each mode. Obviously, (23) is an implication of this result. It should be noted that the result does not require columnwise orthonormality of $G, H$, and $E$.

A property that does require $G, H$ and $E$ to be column-wise orthonormal is the equality

$$
\begin{equation*}
\|C\|^{2}=\left\|C_{s}\right\|^{2}=p(G, H, E) \tag{29}
\end{equation*}
$$

which readily follows from (4) and (6). This property guarantees that squared elements of the core matrix can be interpreted as contributions to the fit, which parallels the interpretation of squared singular values as "portions of variance explained" in ordinary PCA. It should be noted that (29) merely requires $C_{s}$ to be optimal given orthonormal $G, H$ and $E$, see (4). The special two-mode case of this property is well-known from ordinary regression analysis. That is, for an orthonormal set of predictors the fit equals the sum of squared regression weights.

It should be noted that the overall fit partitioning (23) has been derived from the optimality of $C$ only, for fixed but not necessarily optimal $G, H$ and $E$. On the other hand, the element-wise fit partitioning (26) has been obtained from the joint optimality of $C$ and $G, C$ and $H$, and $C$ and $E$. Specifically, (26) was derived from (20), see (24). The question arises whether or not (26), like (23), could have been obtained from the optimality of $C$
only. If only $C$ is optimal then we have a minimum for a function of the form $f(X)=\| B$ $-A X C \|$, for fixed $A, B$ and $C$, in the notation of Penrose (1956, Corollary 1). It can be verified that the minimizing $X$ generates a best least squares approximation $\hat{B}=A X C$ which is orthogonal to $(B-\hat{B})$, when $B$ and $(B-\hat{B})$ are strung out as vectors. However, this does not imply that each column of $\hat{B}$ is orthogonal to the corresponding column of $(B-\widehat{B})$ and, in fact, counterexamples to this proposition can be constructed. For this reason, we do have to assume joint optimality of $C$ and $G, C$ and $H$ and $C$ and $E$ to justify the element-wise fit partitioning (26).

## An Upper Bound to the Fitted Sum of Squares

Tucker's original solution for the Tucker-3 model consists of performing a separate $s$-, $t$-, and $u$-dimensional component analysis on $Z_{\ell} Z_{\ell}^{\prime}, Z_{m} Z_{m}^{\prime}$, and $Z_{n} Z_{n}^{\prime}$, respectively. The sums of the largest $s, t$, or $u$ eigenvalues of these matrices can be taken as threepossibly different-measures of fit in Tucker's method. In TUCKALS-3 there is only one measure of fit (see (6), (7) or (8), and the previous section). The following lemma specifies a relationship between Tucker's three measures of fit and the fit in TUCKALS-3.

Lemma 1. Let $\lambda_{g h}$ denote the $g$-th eigenvalue of $Z_{h} Z_{h}^{\prime}, h=\ell, m$ or $n$, then

$$
\begin{equation*}
p\left(G, H, E \underline{\leq} \leq \min \left(\sum_{p=1}^{s} \lambda_{p l}, \sum_{q=1}^{t} \lambda_{q m}, \sum_{r=1}^{u} \lambda_{r n}\right),\right. \tag{30}
\end{equation*}
$$

where $G, H$, and $E$ are column-wise orthonormal matrices of order $\ell \times s, m \times t$, and $n \times u$, respectively.

Proof. Consider

$$
\begin{equation*}
p(G, H, E)=\operatorname{tr} G^{\prime} Z_{\ell}\left(H H^{\prime} \otimes E E^{\prime}\right) Z_{\ell}^{\prime} G \tag{31}
\end{equation*}
$$

as in (6). Since $\left(H H^{\prime} \otimes E E^{\prime}\right)$ is symmetric and idempotent, it has singular values which are either unity or zero, hence it is a suborthonormal matrix (ten Berge, 1983, Lemma 2). In addition, $G$ is a suborthonormal matrix of rank $s$. It follows at once from the $n=3$ case of Theorem 2 of ten Berge (1983) that

$$
\begin{equation*}
p(G, H, E) \leq \operatorname{tr}\left(\Lambda_{\ell s}^{1 / 2} \Lambda_{\ell s}^{1 / 2}\right)=\operatorname{tr} \Lambda_{\ell s}, \tag{32}
\end{equation*}
$$

where $\Lambda_{\ell s}^{1 / 2}$ is the diagonal matrix containing the first $s$ singular values of $Z_{\ell}$ in the upper left diagonal places, and zeroes elsewhere. Clearly, the squared singular values of $Z_{\ell}$ are eigenvalues of $Z_{\ell} Z_{\ell}^{\prime}$, hence

$$
\begin{equation*}
p(G, H, E) \leq \operatorname{tr} \Lambda_{\ell s}=\sum_{p=1}^{s} \lambda_{p \ell} . \tag{33}
\end{equation*}
$$

The remainder of the proof can be given in a parallel fashion, by expressing $p(G, H, E)$ in terms of $Z_{m}$ and $Z_{n}$, respectively, see (7) and (8). This completes the proof of Lemma 1.

It was pointed out by an anonymous reviewer and by J. C. van Houwelingen (personal communication) that Lemma 1 merely provides a formal proof for a result that is intuitively obvious. Consider the approximation of $Z_{\ell}$, for example, where TUCKALS-3 provides the best least squares estimate $\hat{Z}_{\ell}$, which is constrained to satisfy (2). In the parallel unconstrained case the best fitting $\hat{Z}_{\ell}$ entails $\left\|\hat{Z}_{\ell}\right\|^{2}=\operatorname{tr} \Lambda_{\ell s}$ (Eckart \& Young, 1936). It follows that $\operatorname{tr} \Lambda_{\epsilon s}$ is an upper bound to $p(G, H, E)$ in TUCKALS-3.

Lemma 1 can serve as a guideline for improving the fit in TUCKALS-3. That is, if the two-mode fit is relatively low in one particular mode, one might increase the rank of the component matrix $G, H$ or $E$ for that very mode in TUCKALS-3, as suggested by Kroonenberg (1983, p. 95).

## A Relationship Between TUCKALS-3 and CANDECOMP/PARAFAC

There has been much discussion in the recent literature of the relationship between the TUCKALS 3 model and the CANDECOMP/PARAFAC model of Carroll and Harshman (compare Kroonenberg, 1983, chap. 3; and Harshman \& Lundy, 1984a, pp. 169-178). One of the reasons for studying this relationship is that it may provide insights into the type of solution CANDECOMP/PARAFAC obtains, when it is applied to data that satisfy the TUCKER-3 model (Harshman \& Lundy, 1984b, pp. 271-280). Another reason is that in some special cases the relationship between the two models is rather simple.

Consider the case where the third mode in TUCKALS- 3 has only one component ( $u=1$ ) and the first two modes have the same number of components $(s=t)$. Then the core matrix contains only one frontal $s \times s$ plane $C_{1}=C$. There are some simple theoretical results in this case on the relationship between the TUCKALS- 3 and the CANDECOMP/PARAFAC model due to de Leeuw (compare Kroonenberg, 1983, pp. 57-60). Here we show that if $u=1$ and $s=t$, and TUCKALS-3 has converged to a global minimum of (1), then $C$ is a diagonal matrix. It follows that in this case the TUCKALS-3 program computes a PARAFAC solution.

Let it be assumed that TUCKALS-3 has converged to a global minimum. From (4) we have

$$
\begin{equation*}
C_{s}=G^{\prime} Z_{\ell}(H \otimes E), \tag{34}
\end{equation*}
$$

for certain column-wise orthonormal $G, H$ and $E$. Consider the $t u \times t u$ permutation matrix $\Pi_{1}$, which transforms $C_{s}$ into an $s \times t u$ matrix $C_{*}=C_{s} \Pi_{1}$, containing the $u$ frontal $s \times t$ planes of $C$. Also, consider the $m n \times m n$ permutation matrix $\Pi_{2}$, which transforms $Z_{\ell}$ into an $\ell \times m n$ matrix $Z_{*}=Z_{\ell} \Pi_{2}$, containing the $n$ frontal $\ell \times m$ planes of $Z$. It can be verified that

$$
\begin{equation*}
\Pi_{2}^{\prime}(H \otimes E) \Pi_{1}=(E \otimes H) . \tag{35}
\end{equation*}
$$

Hence we have

$$
\begin{equation*}
C_{*}=C_{s} \Pi_{1}=G^{\prime} Z_{\ell} \Pi_{2} \Pi_{2}^{\prime}(H \otimes E) \Pi_{1}=G^{\prime} Z_{*}(E \otimes H) \tag{36}
\end{equation*}
$$

as parallel expression to (34) in terms of frontal planes of $C$ and $Z$.
Consider the special case of TUCKALS-3 with $s=t$ and $u=1$. Then $C$ contains only one frontal plane $C=C_{*}$ and we have

$$
\begin{equation*}
C=G^{\prime} Z_{*}(E \otimes H)=G^{\prime}\left(\sum_{k=1}^{n} e_{k} Z_{k}\right) H, \tag{37}
\end{equation*}
$$

where $Z_{k}$ is the $k$-th frontal plane of $Z$ and $e_{k}$ is the $k$-th element of the $n \times 1$ vector $E$, $k=1, \ldots, n$. Consider the singular value decomposition

$$
\begin{equation*}
\left(\sum_{k=1}^{n} e_{k} Z_{k}\right)=M D N^{\prime} \tag{38}
\end{equation*}
$$

with $M^{\prime} M=N^{\prime} N=\mathrm{I}_{m}$ and $D$ diagonal, ordered, and nonnegative. Then we have, after
convergence of TUCKALS-3,

$$
\begin{equation*}
C=G^{\prime} M D N^{\prime} H, \tag{39}
\end{equation*}
$$

and the TUCKALS-fit equals

$$
\begin{equation*}
\operatorname{tr} C C^{\prime}=\operatorname{tr} G^{\prime} M D N^{\prime} H H^{\prime} N D M^{\prime} G=\operatorname{tr} M^{\prime} G G^{\prime} M D N^{\prime} H H^{\prime} N D, \tag{40}
\end{equation*}
$$

see (4), (6), and (39). The maximizing $G$ and $H$ satisfy the inequality

$$
\begin{equation*}
\operatorname{tr}\left(M^{\prime} G G^{\prime} M\right) D\left(N^{\prime} H \underline{H^{\prime}} N\right) D \leq \sum_{p=1}^{s} d_{p p}^{2} \tag{41}
\end{equation*}
$$

because ( $M^{\prime} G G^{\prime} M$ ) and $\left(N^{\prime} H H^{\prime} N\right)$ are suborthonormal and have rank $s$ at the most (ten Berge, 1983, Lemma 4, Theorem 2). Let it be assumed that the $s$ largest elements of $D$ are distinct. Then it can be shown that (41) holds as an equality if and only if

$$
M^{\prime} G G^{\prime} M=N^{\prime} H H^{\prime} N=\left(\begin{array}{cc}
I_{s} & 0  \tag{42}\\
0 & 0
\end{array}\right) .
$$

Because $G$ and $H$ are globally optimal, they must satisfy (42). From (42) it follows that

$$
\begin{equation*}
M^{\prime} G=\binom{T_{1}}{0} \quad \text { and } \quad N^{\prime} H=\binom{T_{2}}{0} \tag{43}
\end{equation*}
$$

for certain orthonormal $s \times s$ matrices $T_{1}$ and $T_{2}$. Therefore, we have

$$
\begin{equation*}
C=T_{1}^{\prime} D_{s} T_{2}, \tag{44}
\end{equation*}
$$

where $D_{s}$ is the upper left $s \times s$ submatrix of $D$. From the all-orthogonality of $C$ it follows that $T_{1}^{\prime} D_{s}^{2} T_{1}$ and $T_{2}^{\prime} D_{s}^{2} T_{2}$ are diagonal matrices. This implies that both $T_{1}$ and $T_{2}$ are diagonal and hence $C$ is a diagonal matrix.

From the diagonality of $C$ it follows that the fitted part of the $k$-th frontal plane of $Z$ can be expressed as

$$
\begin{equation*}
\hat{Z}_{k}=G C e_{k} H^{\prime}=G C_{k} H^{\prime}, \tag{45}
\end{equation*}
$$

where $C_{k} \stackrel{d}{=} e_{k} C, k=1, \ldots, n$. As a result, this special case of TUCKALS- 3 can be interpreted as a CANDECOMP/PARAFAC model, with the additional constraint that $G$ and $H$ be column-wise orthonormal, and that the $C_{k}$ be proportional (Harshman, 1970).

## References

Carroll, J. D., \& Pruzansky, S. (1984). The CANDECOMP/CANDELINC family of models and methods for multidimensional data analysis. In H. G. Law, C. W. Snyder, J. A. Hattie \& R. P. McDonald (Eds.), Research methods for multimode data analysis (pp. 372-402). New-York: Praeger.
Eckart, C. \& Young, G. (1936). The approximation of one matrix by another of lower rank. Psychometrika, 1, 211-218.
Harshman, R. A. (1970). Foundations of the Parafac procedure: Models and conditions for an 'explanatory' multi-mode factor analysis. (Working Papers in Phonetics No. 16). Los Angeles: University of California.
Harshman, R. A., \& Lundy, M. E. (1984a). The PARAFAC model for three-way factor analysis and multidimensional scaling. In H. G. Law, C. W. Snyder, J. A. Hattie \& R. P. McDonald (Eds.), Research methods for multimode data analysis (pp. 122-215). New-York: Praeger.
Harshman, R. A., \& Lundy, M. E. (1984b). Data preprocessing and the extended PARAFAC model. In H. G. Law, C. W. Snyder, J. A. Hattie \& R. P. McDonald (Eds.), Research methods for multimode data analysis (pp. 216-284). New York: Praeger.
Kroonenberg, P. M. (1983). Three-mode Principal Component Analysis. Leiden: DSWO-Press.
Kroonenberg, P. M., \& de Leeuw, J. (1980). Principal component analysis of three-mode data by means of alternating least squares algorithms. Psychometrika, 45, 69-97.

Penrose, R. (1956). On the best approximate solutions of linear matrix equations. Proc. Cambridge Phil. Soc., 52, 17-19.
ten Berge, J. M. F. (1983). A generalization of Kristof's theorem on the trace of certain matrix products. Psychometrika, 48, 519-523.
Tucker, L. R. (1963). Implications of factor analysis of three-way matrices for measurement of change. In C. W. Harris (Ed.), Problems in measuring change. Madison: University of Wisconsin Press.
Tucker, L. R. (1964). The extension of factor analysis to three-dimensional matrices. In H. Gulliksen \& N. Frederiksen (Eds.), Contributions to mathematical psychology. New-York: Holt, Rinehart \& Winston.
Tucker, L. R. (1966). Some mathematical notes on three-mode factor analysis. Psychometrika, 31, 279-311.
Weesie, H. M. \& van Houwelingen, J. C. (1983). GEPCAM User's Manual. Unpublished manuscript, University of Utrecht, Institute for Mathematical Statistics.

Manuscript received 5/23/85
Final version received 4/29/86


[^0]:    Requests for reprints should be sent to Jos M. F. ten Berge, Subfakulteit Psychologie, RU Groningen, Grote Markt 32, 9712 HV Groningen, THE NETHERLANDS.

