#### **TFAWS Active Thermal Paper Session**



#### Spacesuit Water Membrane Evaporator; An Enhanced Evaporative Cooling Systems for the Advanced Extravehicular Mobility Unit Portable Life Support System

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#### **Overview**

- SWME Design Criteria
- Previous Design
  - Pre Gen. 4 design
  - SWME Gen. 4 early concepts
- Current Design
  - Housing Modification
  - End cap Modifications
  - Back Pressure Valve Modifications
- Thermal Control Valve (TCV)
- Sensor Selection

#### **Scope and Background**



- Spacesuit Water Membrane Evaporator
- Baseline heat rejection technology for the Portable Life Support System of the Advanced EMU
  - Replaces sublimator in the current EMU
  - Contamination insensitive
  - Can work with Lithium Chloride Absorber Radiator in Spacesuit Evaporator Absorber Radiator (SEAR) to reject heat and reuse evaporated water

#### Background



The Spacesuit Water Membrane Evaporator (SWME) is being developed to replace the sublimator for future generation spacesuits.

Current PLSS	relies on a sublimator for LCVG and PLSS component cooling	<ul> <li>Sensitive to contaminants</li> <li>Only certified for 25 EVA's: Has failed before 25 EVAs (during EVA)</li> <li>Requires a separate feedwater loop</li> <li>Will not work on Mars due to increased atmospheric pressure</li> </ul>
Advanced PLSS	Create a new, robust heat rejection device for future:	<ul> <li>Reject at least 807W at 10° C (50° F) outlet water temperature at EOL</li> <li>Operate for at least 100 8-hour EVA's</li> <li>Function in multiple EVA environments (Lunar, Mars, Vehicle)</li> <li>Resist contaminant fouling</li> </ul>

#### **SWME Overview**

Warm water from LCVG

SWME is an evaporative cooler

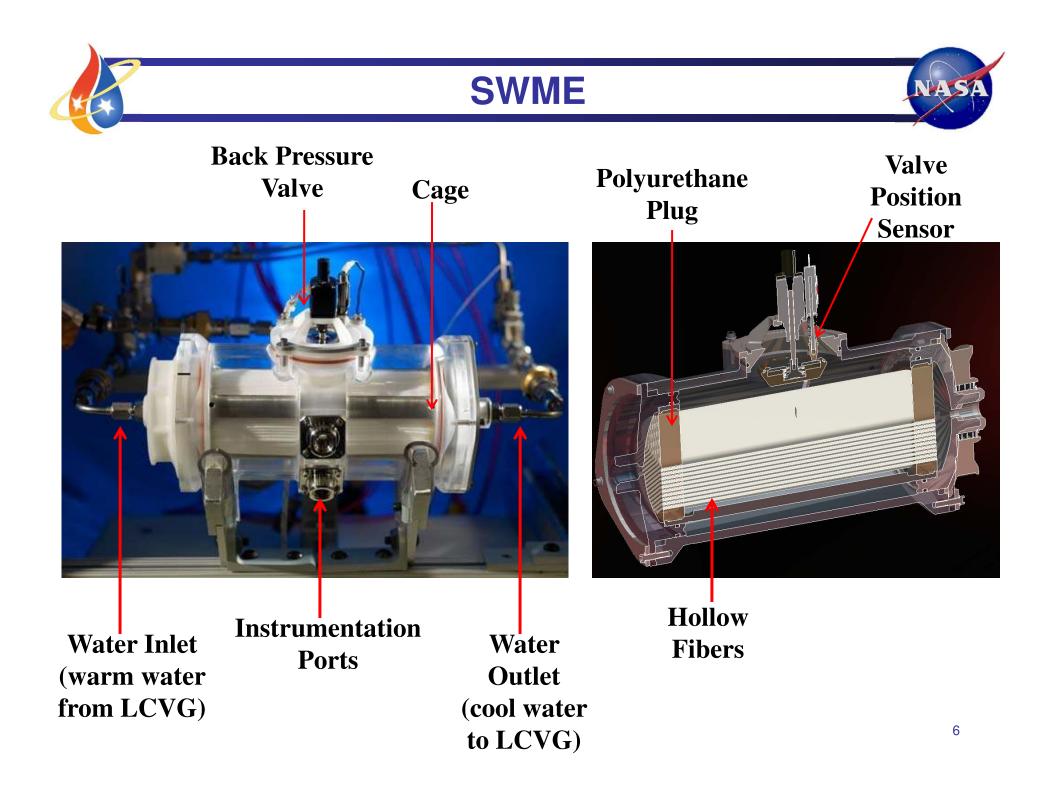
#### **Process**

- Water in LCVG absorbs body heat while circulating
- Warm water pumped through SWME
- SWME evaporates water vapor, while maintaining liquid water
  - Cools water
- Cooled water is then recirculated through LCVG.
- LCVG water lost due to evaporation (cooling) is replaced from feedwater

Water vapor is exhausted to space from SWME, removing heat

**SWME** 

Cooled water is pumped back into LCVG



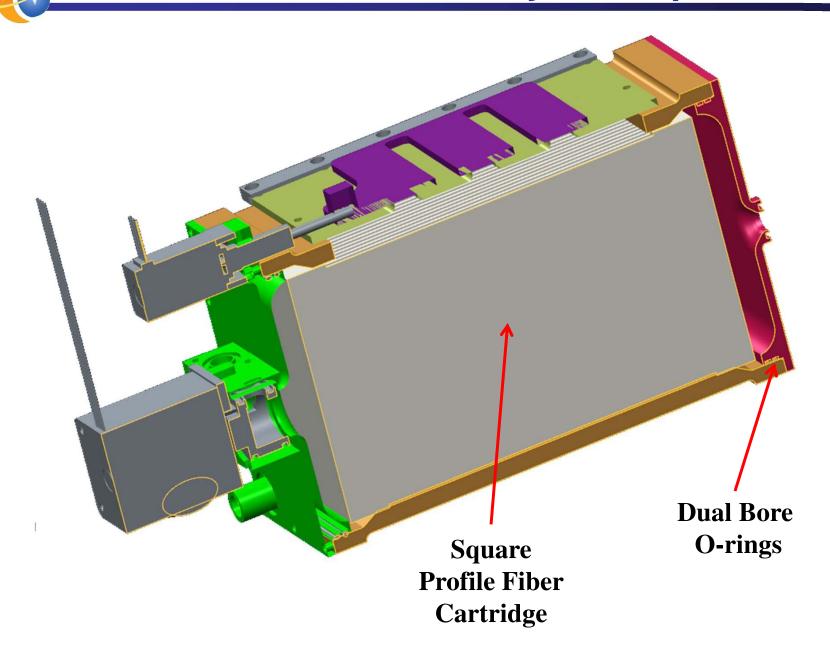
# **New Design Goals for Gen4 SWME**

#### • Function

- Meet or exceed earlier design requirements
- 810 W heat rejection at end-of-life
- Minimize or eliminate water vapor leak
- Protect for over/under pressure conditions
- Sense valve position
- Maximize controllability over the lower metabolic range; to increase crewmember comfort.
- Form
  - Maximize packaging efficiency for incorporation into PLSS 2.5
    - Square profile
    - Minimize volume of SWME housing
    - Integrate the Thermal Control Valve (TCV), delta pressure, and temperature sensors into the SWME assembly

# **SWME Gen. 4 Early Concept** NASA **Sliding Gate** Valve ` Integrated **TCV Port**

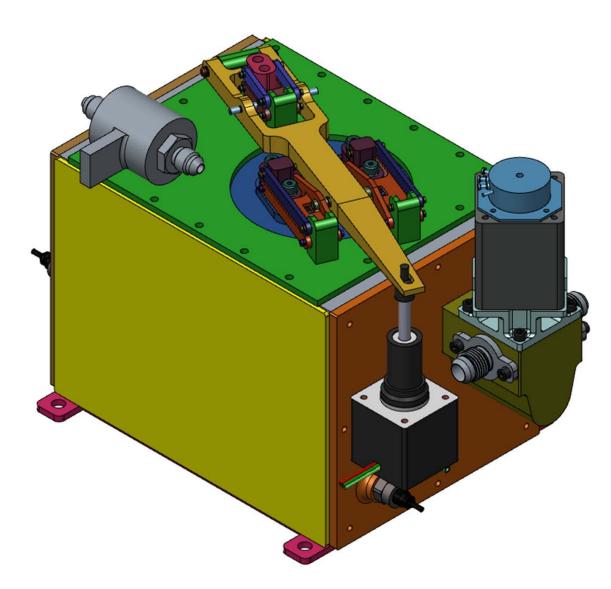
#### **SWME Gen. 4 Early Concept**

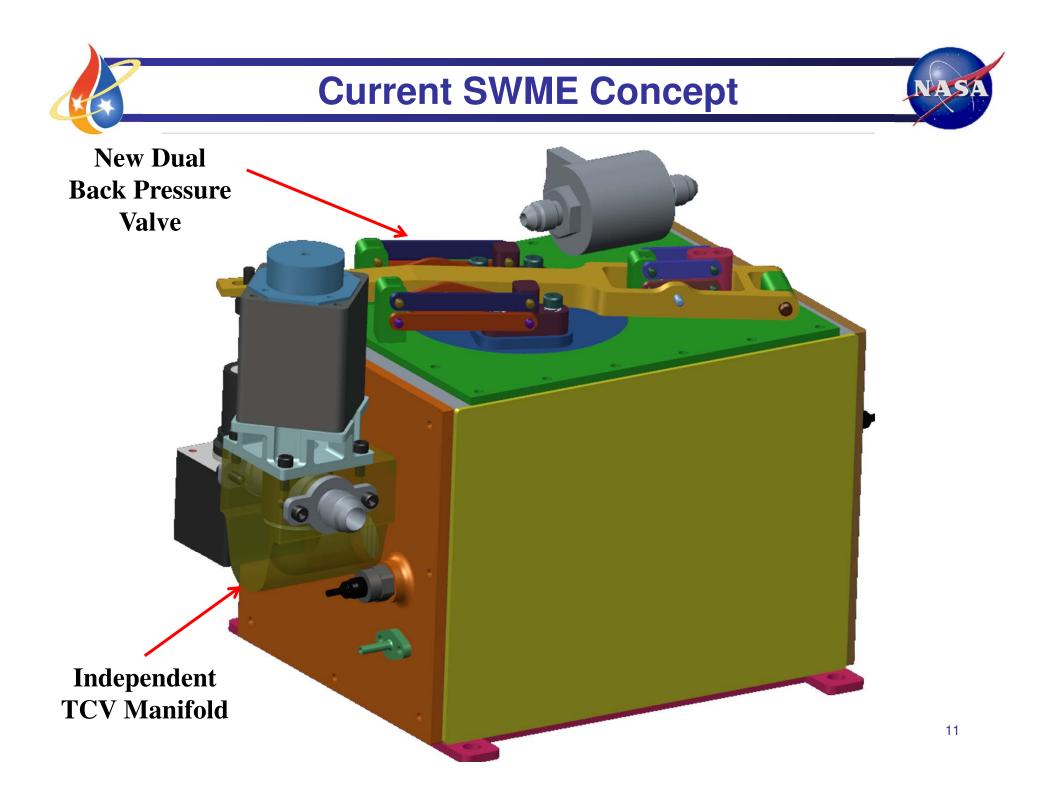


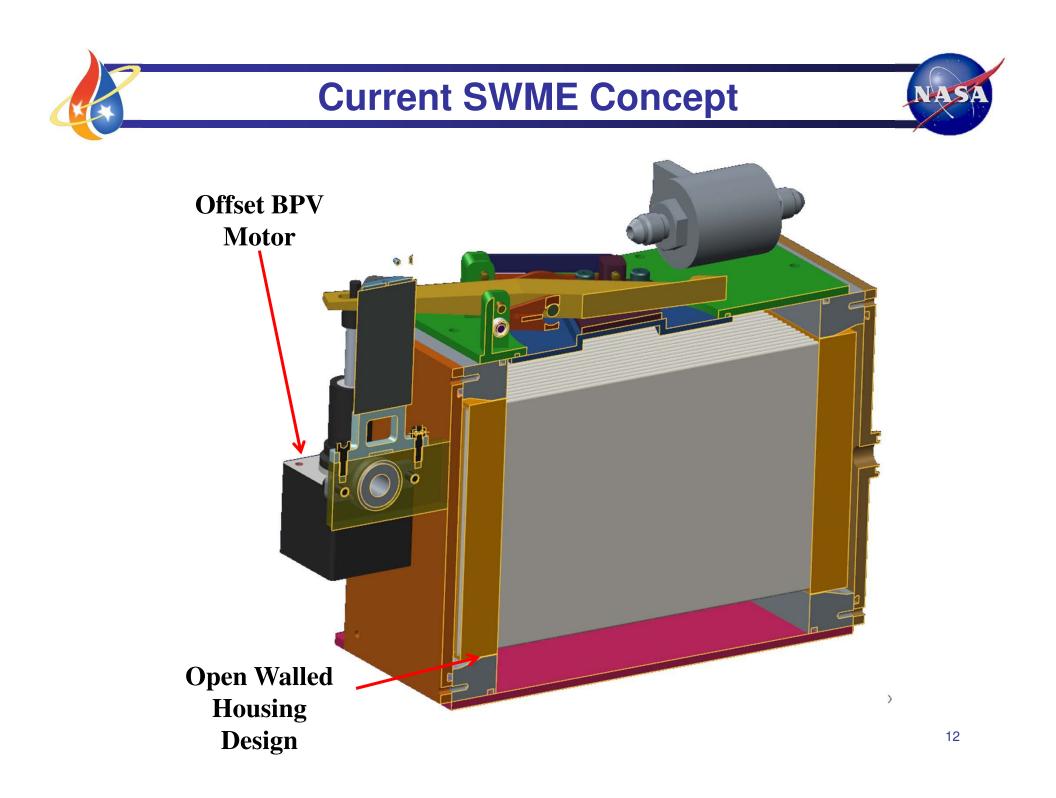
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# SWME Views (Cont.)

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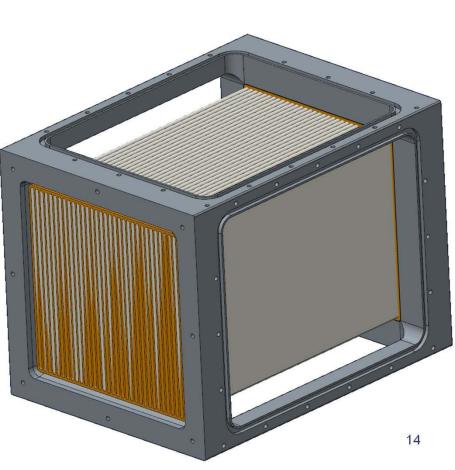
# **Design Modifications**



- The Independent TCV Manifold reduces design complexity and manufacturing difficulty of the SWME End Cap.
- The offset motor for the new BPV reduces the volume profile of the SWME by laying the motor flat on the End Cap alongside the TCV.

# **New Housing Design**



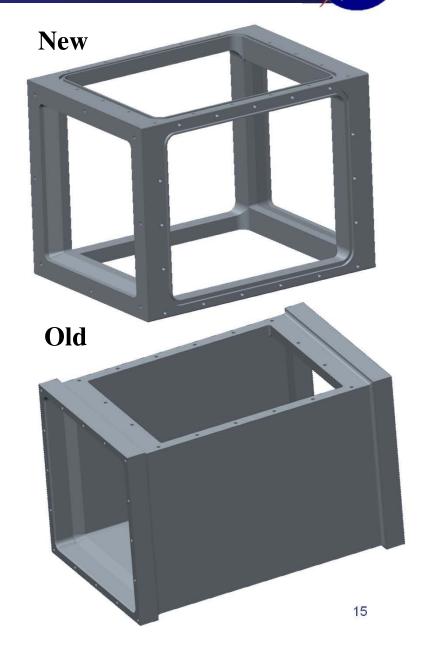


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#### **Housing Modification**



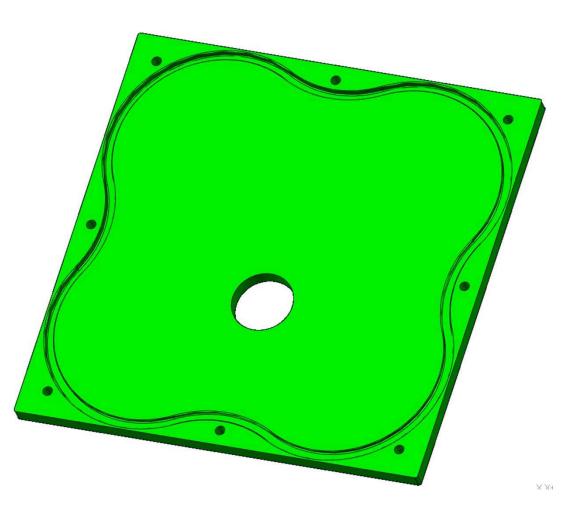
- Better access during assembly
  - A bead of polyurethane can be run on the inside of the cartridge now to prevent urethane leak during potting.
  - · Easier leak identification and repair.
- Ease of manufacturing
  - More generous tolerances
  - Standard and quicker machining methods can be used
- Modularity of design
  - 4 open sides allow for more options such as relief valves to equalize pressure in an off-nominal repress/depress







- Simplified End Cap with separation of TCV Manifold.
- Moved O-ring gland from bore O-ring on housing to face seal Oring on End Cap.
  - Better Sealing Method
  - Serpentine pattern allows for generous bend radii on square cross section and COTS o-ring
- Increased surface area
   to allow for face seal



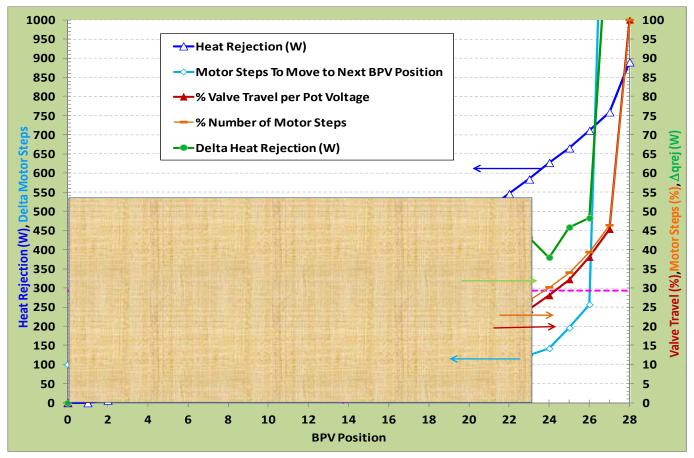
Note: Final design will have thicker edge distances on Orings

#### **Back Pressure Valve goals**

- Reduce total SWME volume envelope through low profile
  - Facilitates PLSS packaging
- Allow for pressure differential equalization
- No heat leak during non-op periods
- Finer control at lower metabolic rates
- High cycle life capability
- 4 in<sup>2</sup> open area

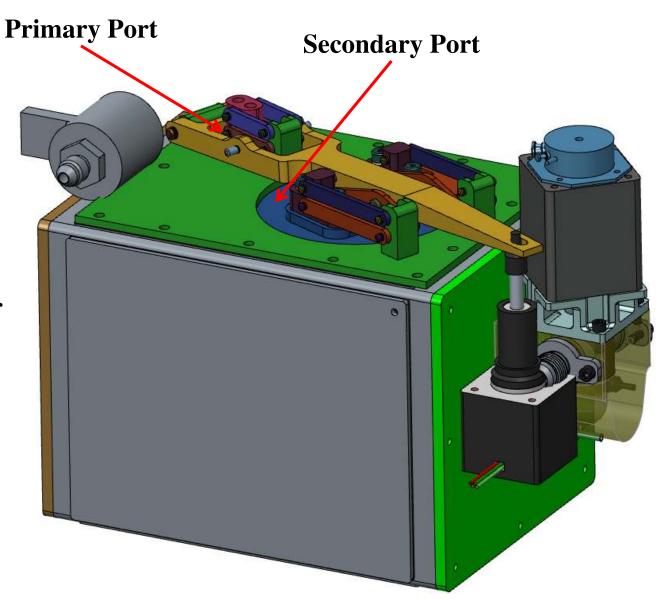
#### **Gen2 SWME BPV Characterization**

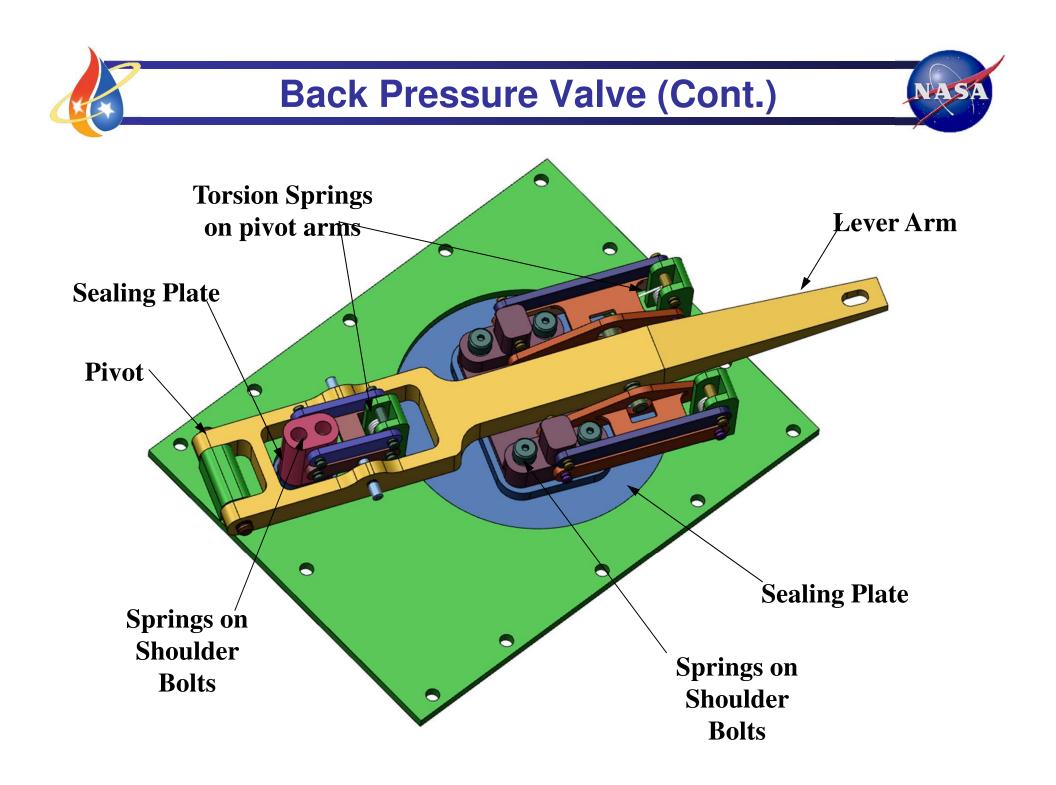
- Opening the valve 25% resulted in an SWME heat rejection of 66% of its full open BPV value
- The last 75% of valve poppet travel accounted for the final 34% of SWME heat- rejection capability.

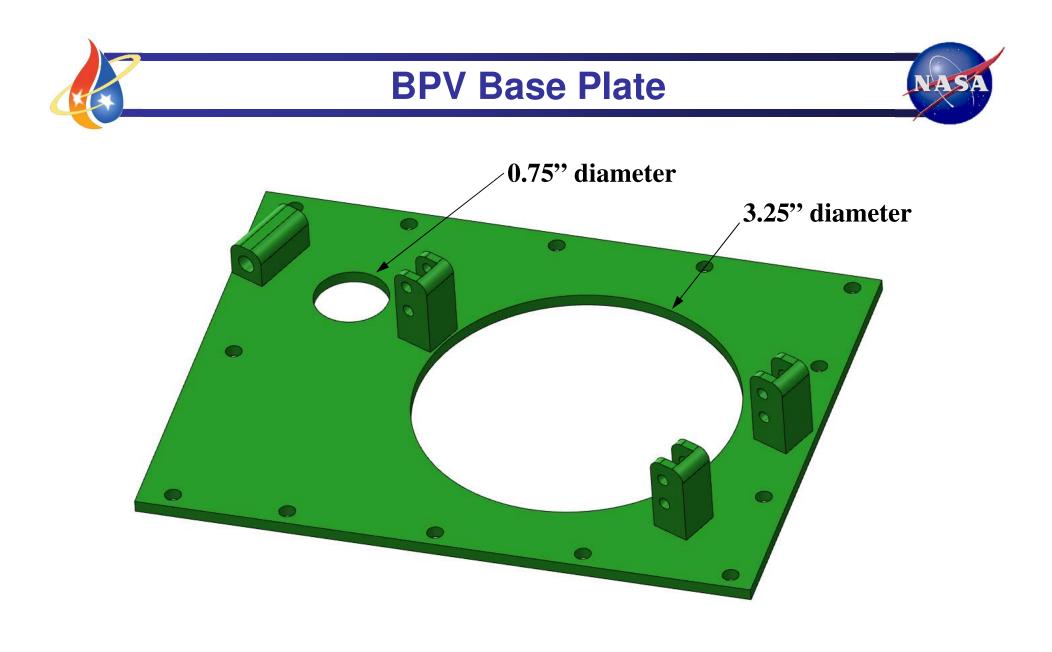


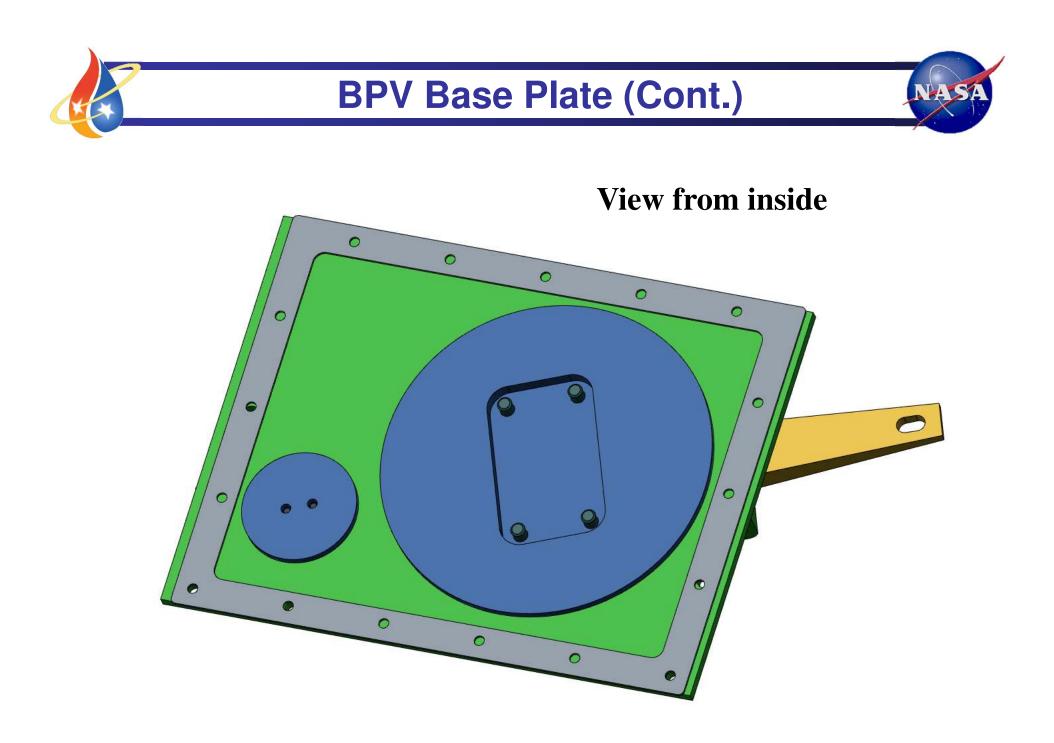
#### **Back Pressure Valve**

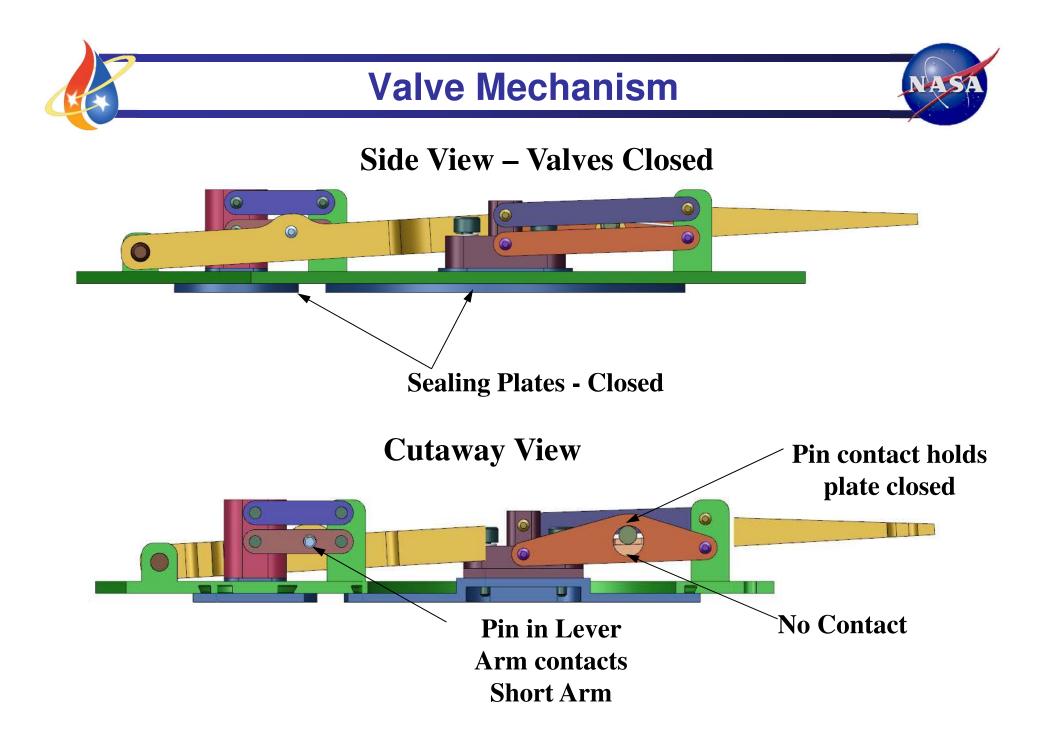
- Ports open sequentially.
- Smaller Primary port allows for finer control at lower metabolic rates.
- Larger Secondary port provides higher flow volumes when needed at higher metabolic rates.

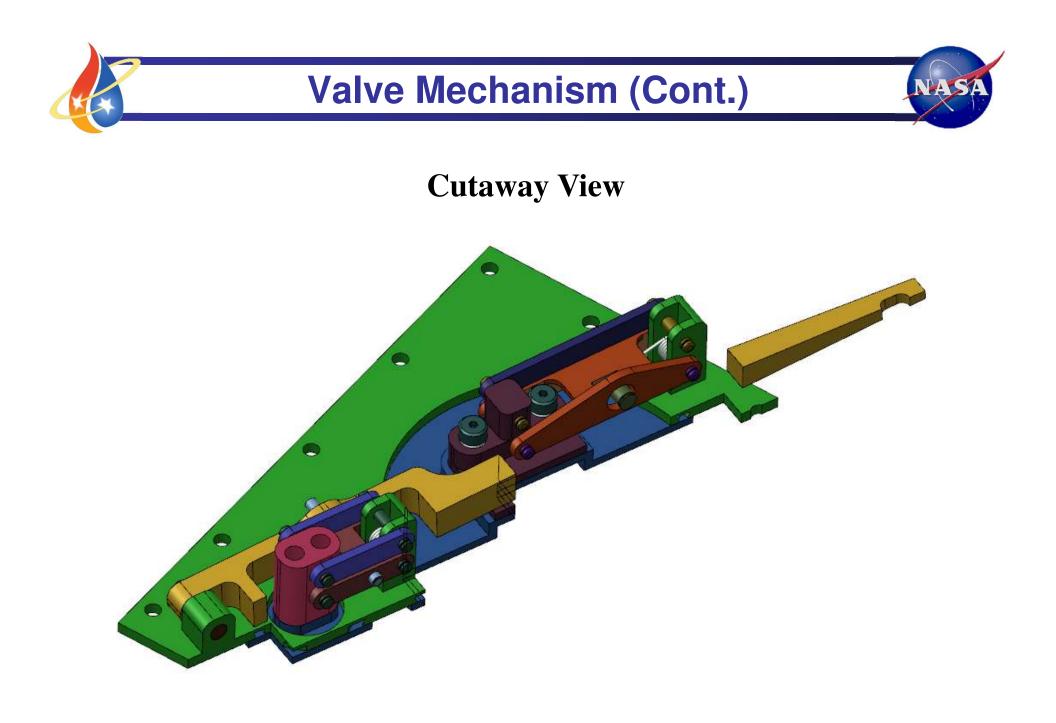


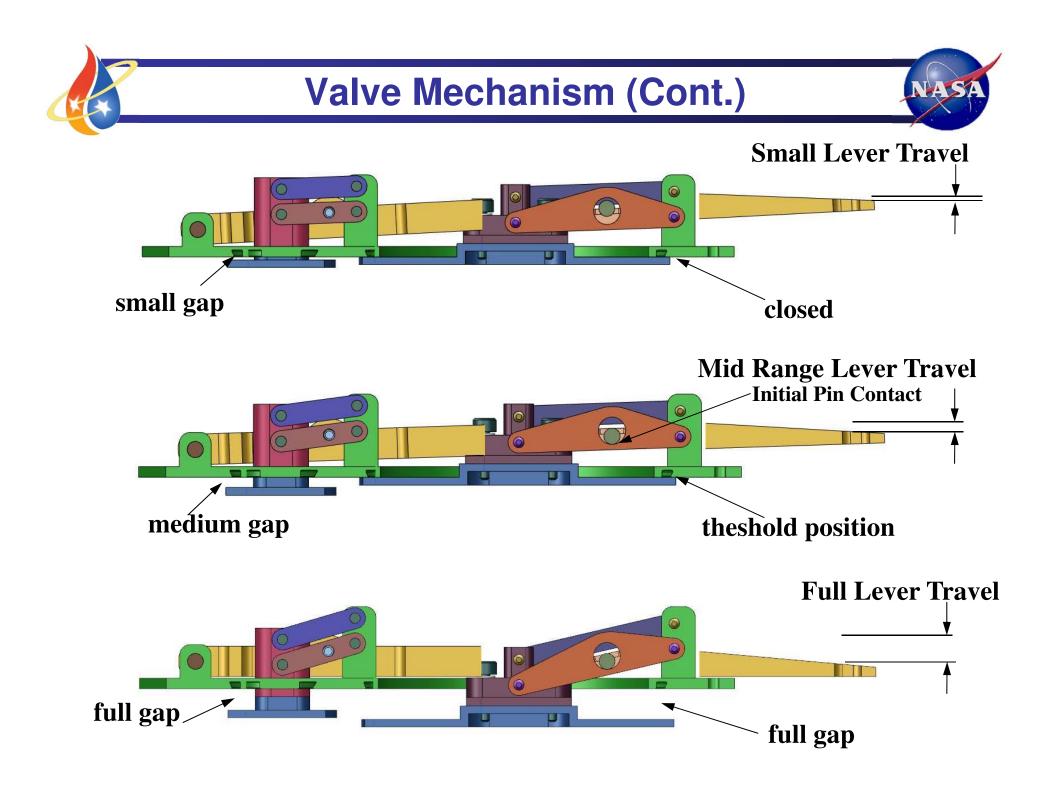












#### **BPV Pros and Cons**



#### **Pros:**

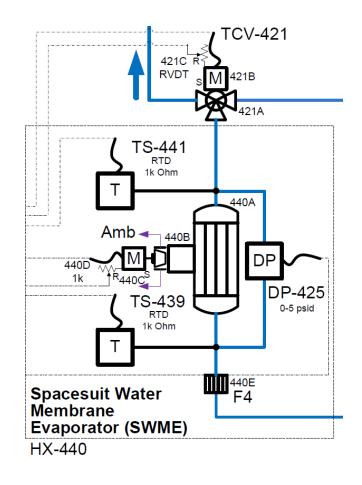
- Smaller Primary port allows for finer control at lower operation rates.
- Larger Secondary port provides higher flow volumes when needed.
- Parallel linkages keep the sealing plates from tilting.
- Multiple linkages stop sliding motion on O-rings when compared to single linkage.

**Cons:** 

- Multiple linkages increase part count and complexity
- Multiple pivots increase risk of valve "sticking"

#### **Integration - TCV**

- Improved PLSS Packaging
  - Fewer tubing runs
  - Fewer retaining brackets
- Less instrumentation
  - Removal of redundant temperature sensors
- Closer proximity of thermal loop controller to components



#### Integration – TS 439, 441



- Measure SWME inlet and outlet temps
  - TS-441 replaces TS-401 (TCV Inlet Temperature)
- COTS 1k RTDs
  - Standard temperature sensor for PLSS 2.5
  - O-ring Boss Port Interfaces

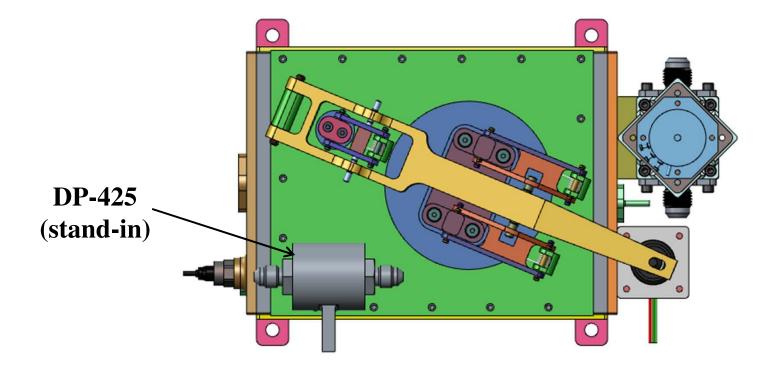
#### Integration – DP-425



- Measures dP across SWME
- Loss of flow triggers SWME safing
- Provides coarse thermal loop flow measurement
- 1/8 in tubing runs from inlet and outlet
- Sensor selection in-work

#### Integration – DP-425

- NASA
- Current volume constraints require sensor be placed on top of SWME

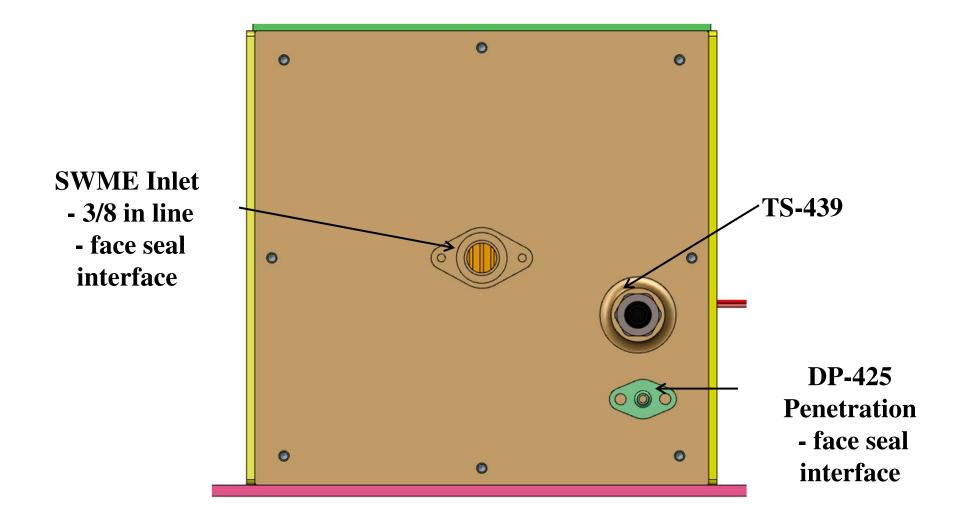


# **Integration - Endcaps**

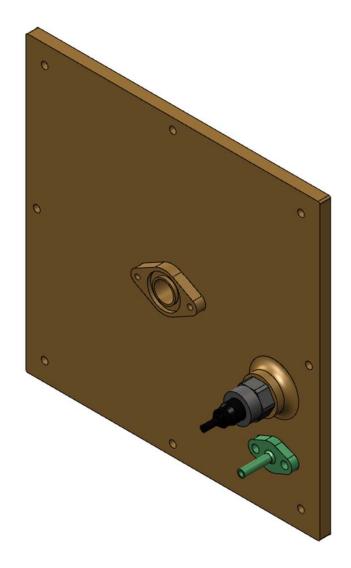


- Allow design of individual components in parallel with packaging and integration
- Reduced machining risk
  - Complexity of endcaps and risk of scrapping will not affect the entire SWME housing
- Pressure and temperature sensors can be placed
   anywhere
  - Allows optimal placement of SWME gate valve





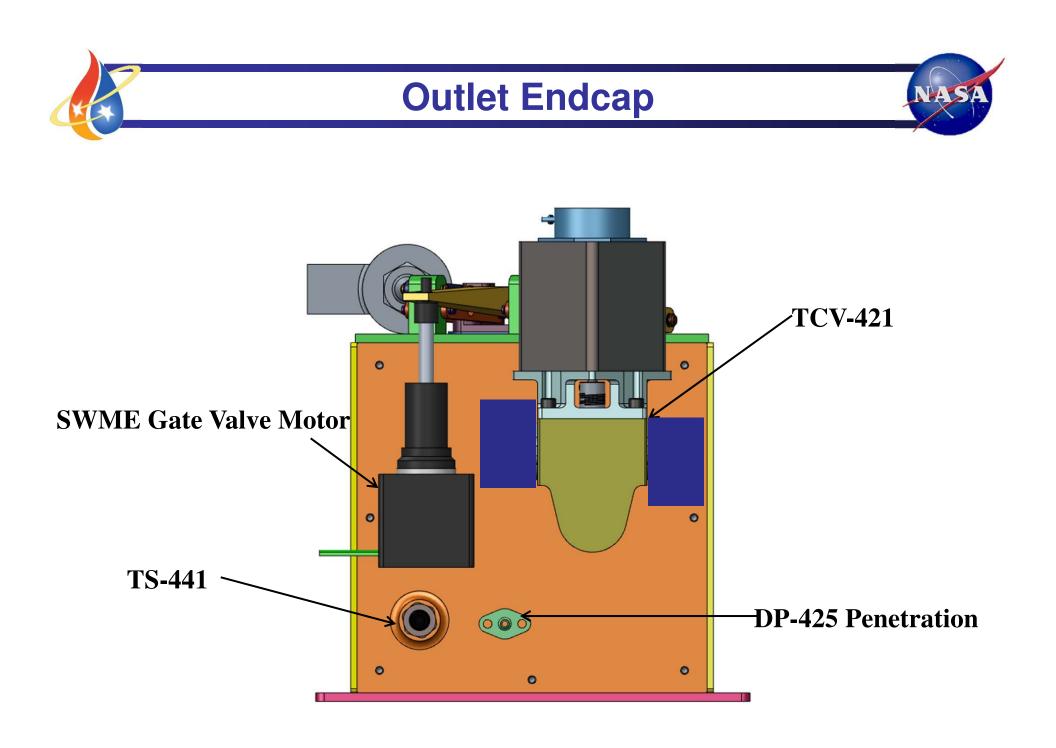




#### **Outlet Endcap**



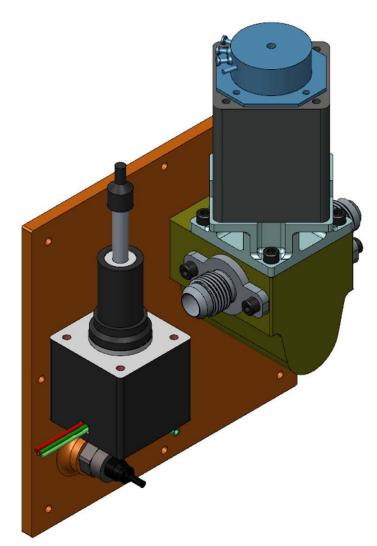
- Currently, length is most packaging-critical dimension
- All large-volume components kept on one endcap to minimize swept volume
  - Valve Motor
  - TCV-421





# **Outlet Endcap**

NASA



# **Integration Forward Work**



- Components still under development:
  - SWME Valve
  - SWME Fiber Count
    - FDTA testing
  - Mini-ME2
    - Will be based on lessons learned and data from Gen4
  - TCV-421
  - DP-425
- As these components continue to be developed and optimized, the integration concept will update as well