Speech interaction with personal assistive robots supporting aging-at-home for individuals with **Alzheimer's disease**

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Introduction

| Millions ¹⁰⁰ | |
|--|----|
| 90 - | |
| Alzheimer's disease (AD) is a neurodegenerative disorder usually affecting memory, then language, then executive function. | |
| At moderate stages, activities of daily living become difficul | t. |
| Caregivers often assist individuals with, either at home or in long-term care facilities. | |
| >\$100B are spent annually in the U.S. on caregiving A | D. |
| 1900 1910 1920 1930 1940 1950 1960 1970 1980 1990 2000 2010 2020 2030 2040 2050 2006 Projected | 5 |
| | |

The HomeLab

• 'COACH' automates support of daily activities.

- E.g., hand-washing, tooth-brushing.
- Uses partially-observable Markov decision processes (POMDPs) and camera-only input.
- But what if the user does not want to spend their whole day in front of the sink?





Early qualitative analysis indicated that **speech** is the most **desired** form of interaction with such a system.

Our **goal** is to implement two-way **spoken dialogue** that *identifies* and *recovers* from communication breakdowns.

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Related work

 There has been a *lot* of great work on supporting older adults with robots.



- However, speech interaction has been superficial.
- We know a lot about how AD affects language.
 - Repetition, disfluency, paraphrasing (Guinn and Habash, 2012).
 - Can be used for **diagnosis** (Fraser, Meltzer, and Rudzicz., 2015).

Communication difficulties and Trouble-Indicating Behaviors

| TYPICAL | In dialogue, people with AD have more discourse-related difficulties, including: |
|------------------|--|
| | inattention, Description for a string statement of the string strin |
| TIB 18% | Poor tracking of propositions and themes, and deficits in working memory. |
| AD TIB 33% | Trouble Indicating Behaviors (TIBs) (Watson, 1999). Difficulties can be phonological, morpho/syntactic, semantic (e.g., lexical access), or discourse (e.g., misunderstanding topic). Seniors with AD use TIBs significantly more (p<0.005) than matched controls (Watson, 1999). |

• What are these TIBs?

Some common TIBs

 Neutral or non-specific requests for repetition (local).
 E.g., What? Huh?

 2. <u>Request for confirmation –</u> <u>repetition with reduction</u>.
 E.g., Speaker 1: *I went to the museum last night*. Speaker 2: *Last night?*

. . .

Some common TIBs (cont.)

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8. Lack of uptake / lack of continuation. Include i) *minimal feedback* indicating nonunderstanding, ii) lack of contribution to topic extension; iii) overriding/*interrupting*; and iv) abrupt *switch of topic*. E.g., Speaker 1: Do you know what 'rhetorical' means? Speaker 2: Yes. Speaker 1: What? Speaker 2: Oh, its a bit too hard, bit late too late to.

Some common TIBs (cont.)

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11.<u>Reprise / minimal dysfluency</u>.

<u>Reprises</u>: partial or whole repetition/revision. <u>Minimal dysfluencies</u>: sound, syllable, or word repetition, pauses, and fillers. E.g., **Eerrr, I want to we went to** the river.

How do people avoid TIBs?

- ED should mimic **verbal strategies** of caregivers.
 - E.g., (Wilson et al., 2012) :
 - 1. Speak slowly.
 - 2. Repeat misunderstood prompts verbatim.
 - 3. Ask **closed-ended questions** (i.e., eliciting yes/no responses).
 - 4. Simplify sentences using **reduced syntactic complexity**.
 - 5. Give one question or **one direction at a time**.
 - 6. Use pronouns minimally.

How can we mimic this in a robot? How will people with AD respond?

Data





10 individuals (6 female) with AD recruited at Toronto Rehab.

- Age: 77.8 years ($\sigma = 9.8$)
- Education: 13.8 years ($\sigma = 2.7$)
- MMSE: 20.8/30 (σ =5.5)
- Three phases:

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- Familiar human-human dyad (during informed consent),
- Human-robot dyad (during *tea-making*), and
- Unfamiliar human-human dyad (during post-study interview).

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Speech interface

- Synthetic speech: 'David' voice from Cepstral.
 - Qualitative feedback was **positive**; 😃
 - Despite being '**robotic**', the voice was '*clear*' and '*confident*'.
- We **split** the tea-making task into **phases**.
 - **(1)** go to kitchen, ..., **(6)** put teabag in cup, ...
 - We recorded audio (+video) prompts for **each phase**, at several **levels of detail**.
- A human navigator followed a **flowchart** of **scripts**.
 - Respond to questions with pre-recorded prompts;
 - When possible, engage in **novel social conversation**.

Language use and interaction

- A speech-language pathologist (SLP) transcribed all of the data and annotated TIBs.
 - For sanity, a second SLP annotated 20%; Fleiss' $\kappa = 0.84$.



Understanding each other

- People with AD were much more likely^(*) to have no TIB when interacting with a robot (18.1%) than with a non-familiar human (6.7%).
- But it's not *really* interacting with a robot, is it?
 - A human is recognizing the speech.
 - A human is recovering from errors.
 - A human is choosing what to say next (albeit with a script).

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Rudzicz et al. Speech interaction with personal assistive robots...

(*) t(18) = -4.78,

p < 0.0001

Speech recognition and automation

- We developed methods that **automatically identify** TIBs in speech with >80% accuracy (Rudzicz et al., 2014).
 - Indicative features are mostly things like skewness of the derivatives of particular Mel-frequency cepstral coefficients, but some have more clinical value e.g., phonation rate.
- **ASR** is a standard HMM with mixtures of Gaussians.
 - Data are very noisy (SNR [-3.42..8.14] dB).
 - LSAE spectral noise subtraction





- Two LMs derived from English Gigaword corpus:
 - Large: 64,000 words Small: 5000 words

Speech recognition and cognition

• Clear increases in accuracy with MMSE. ANOVA: $F_1 = 47.07, p = 0.164$.



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Adapting ASR to older voices

• We adapted ASR using data from DementiaBank and Carolina Conversations, and varied model complexity.



Automating choice of response



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Silicon friends for golden years

Speech is increasingly important for interaction.

Our robot friends will need to be sensitive to differences in language as we age.

Special thanks: Raibul Huq & Colin Harry (robot builders), Jen Boger & Goldie Nejat (study design).



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SLPAT K

• Joint Special Interest Group of

the Association for Computational Linguistics (ACL) & the International Speech Communications Association (ISCA)

• Speech and Language Processing for Assistive Technologies.

- Yearly workshops (next: w/ Interspeech in SanFran).
- Recent special issue of TACCESS.
- Possible Jelinek JHU workshop.

www.slpat.org