

Spin-orbit torques in locally and globally noncentrosymmetric crystals: Antiferromagnets and ferromagnets

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One of the main obstacles that prevents practical applications of antiferromagnets is the difficulty of manipulating the magnetic order parameter. Recently, following the theoretical prediction [J. Železný *et al.*, *Phys. Rev. Lett.* **113**, 157201 (2014)], the electrical switching of magnetic moments in an antiferromagnet was demonstrated [P. Wadley *et al.*, *Science* **351**, 587 (2016)]. The switching is due to the so-called spin-orbit torque, which has been extensively studied in ferromagnets. In this phenomena a nonequilibrium spin-polarization exchange coupled to the ordered local moments is induced by current, hence exerting a torque on the order parameter. Here we give a general systematic analysis of the symmetry of the spin-orbit torque in locally and globally noncentrosymmetric crystals. We study when the symmetry allows for a nonzero torque, when is the torque effective, and its dependence on the applied current direction and orientation of magnetic moments. For comparison, we consider both antiferromagnetic and ferromagnetic orders. In two representative model crystals we perform microscopic calculations of the spin-orbit torque to illustrate its symmetry properties and to highlight conditions under which the spin-orbit torque can be efficient for manipulating antiferromagnetic moments.

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I. INTRODUCTION

Antiferromagnets (AFMs) have so far found little applications as active components of devices primarily due to their lack of net magnetization. With the development of spintronics, however, the net magnetization that couples strongly to the magnetic field becomes less important. In the latest generation of magnetic random access memories (MRAMs), for example, magnetic fields are used neither for writing nor for reading. Since AFMs possess a long-range magnetic order just like ferromagnets (FMs), they have been recently explored as new materials for spintronics (see Refs. [1–3] for recent reviews of antiferromagnetic spintronics). In particular, they could in principle be used for solid state memories in which bits of information are represented by the direction of the magnetic order parameter, similarly to FMs. Such memory functionalities were experimentally demonstrated in AFM tunneling [4] and ohmic devices [5–7].

Compared to FMs, AFMs have several potential advantages. They are insensitive to large magnetic fields and do not produce any stray fields. This makes them more challenging from an experimental and technological point of view, but it can also be an advantage. Stray fields can cause problems in densely packed devices, and the sensitivity to external magnetic fields means that a FM memory can be accidentally rewritten by external magnetic fields. AFM memory, on the other hand, is much less sensitive to external magnetic fields.

For example, a memory based on FeRh could not be erased by fields as high as 9 T [5]. Another advantage is that dynamics of magnetic moments in AFMs is much faster than in FMs. Switching of the AFM order parameter on a ps timescale was demonstrated, e.g., in a laser-induced-heating experiment [8].

A remarkable feature of AFMs is also the wide range of available AFM materials. This holds especially for semiconductors. FM semiconductors have attracted a lot of interest in the past since they enable the combination of spintronic and microelectronic functionalities. Yet, despite intensive research, FM semiconductors remain rare and tend to have Curie temperatures too low for practical applications. AFM semiconductors on the other hand are more common and tend to have magnetic order persisting above room temperature [3,9–11]. Materials that combine antiferromagnetism with ferroelectricity [12] or the parent compounds of the high- T_c superconductors [13] further highlight the broad and diverse range of AFMs.

For microelectronic memory and logic applications of AFMs, two basic functionalities have to be available: a method for detecting and manipulating electrically the magnetic order parameter. For readout, the anisotropic magnetoresistance (AMR) effect [9,10,14] and its tunneling counterpart TAMR have been demonstrated [4]. While AMR is usually rather small, with typical magnetoresistance ratios around a few percent, a $\sim 100\%$ TAMR has been already achieved, albeit at low temperatures.

Manipulating the magnetic order parameter in AFMs by practical means has been a major challenge. AFMs can be controlled by external magnetic fields, but this is impractical since it typically requires very large fields. The lowest uniform static field that can reorient an AFM is the so-called spin-flop field, which is proportional to $\sqrt{H_J H_{\text{an}}}$, where H_J is the inter-sublattice exchange field and H_{an} is the anisotropy field. Since the exchange interaction is typically much larger than the anisotropy, the spin-flop fields are large compared to FMs. Instead, an auxiliary exchanged-coupled FM layer is often used [4,9,15], which makes manipulation possible by smaller fields. This only works for thin AFM layers though, and it is highly dependent on interface properties.

While FMs can be manipulated by external magnetic fields, in microelectronic devices a direct electrical manipulation offers a more scalable approach. This is usually achieved using the so-called spin-transfer torque [16,17]. This torque occurs due to the absorption of angular momentum from a spin-polarized current generated by a fixed FM polarizer. On the other hand, due to spin-orbit coupling, a torque can be generated without the injection of a spin current from the FM polarizer [18–28]. Such torque is usually called a spin-orbit torque. In FMs it requires a broken inversion symmetry and can therefore occur either in crystals with no inversion symmetry in the unit cell or in heterostructures, where inversion symmetry is broken structurally.

Because of the insensitivity of AFMs to external fields, the electrical manipulation of AFMs is even more desirable. To manipulate a collinear AFM effectively, a staggered magnetic field (i.e., a field that is opposite on the two sublattices) is needed. In Ref. [29] it was shown that the analog of the FM spin-transfer torque in AFMs can generate effective fields that are staggered. However this requires very thin layers [30].

Reference [31] proposed that in bulk AFMs with specific symmetries, electrical current can create a torque by a similar mechanism to the spin-orbit torque in FMs. The work also showed that the effective field generating the torque can be staggered and the corresponding nonstaggered torque can thus be effective for manipulating AFMs. Switching of an AFM based on predictions in Ref. [31] was recently experimentally observed in AFM CuMnAs [7]. This opens up a way to applications of AFMs. The current densities needed for switching in Ref. [7] were comparable to current densities in FM spin-torque MRAMs.

In this paper we theoretically study the nature and characteristics of spin-orbit torques in AFMs in a systematic way. We give a general symmetry analysis for crystals that lack inversion symmetry (globally noncentrosymmetric crystals) as well as crystals in which the symmetry group of at least one site in the unit cell is noncentrosymmetric (in other words, there exists a site which is not an inversion center). We then say that such crystals are locally noncentrosymmetric. We consider both the AFM and FM order. We determine when the torque can exist, when it is effective for manipulating the magnetic order in AFMs, and also what form the torque has. In Ref. [31] the spin-orbit torque was calculated for two representative tight-binding models, one describing a three-dimensional (3D) lattice of Mn_2Au and the other one representing a two-dimensional (2D) crystal with Rashba spin-orbit coupling. Mn_2Au served as a model AFM system with globally centrosymmetric and locally

noncentrosymmetric crystal structure and inversion-partner lattice sites occupied by the two spin sublattices. In this model system, the so-called fieldlike torque, driven by a staggered, magnetization-independent current-induced field, is effective. (Note that the relevant crystal symmetries of Mn_2Au are the same as those of the recently experimentally studied CuMnAs and that the calculated magnitudes of the spin-orbit torques in Mn_2Au and CuMnAs are also comparable [7].) On the other hand, the so-called (anti)damping-like torque, driven by a staggered, magnetization-dependent effective field, was found to be the effective torque component in the 2D AFM crystal with a global inversion asymmetry modeled by the Rashba Hamiltonian.

Here we calculate all spin-orbit torque components in both models which allows us to generalize the result of Ref. [31]: All torque components driven by fields that are an even function of the sublattice magnetization are effective in the AFM 3D Mn_2Au model while torques driven by fields that are odd in magnetization are effective in the AFM 2D Rashba model. The calculations also reveal that the angular dependencies of the current-induced fields with respect to the applied current direction and the direction of magnetic moments are similar in the two model systems, due to similarities in the relevant symmetries of the two model crystals. Numerical and analytical calculations of the spin-orbit torque in the two tight-binding models are complemented by *ab initio* density-functional-theory (DFT) calculations and results for the AFM order are compared to calculations assuming the FM order in the same model crystals.

Our paper is organized as follows: In Sec. II we describe the two tight-binding models and the linear response formalism used for calculating the spin-orbit torque. In Sec. III we discuss the symmetry of the spin-orbit torque and apply the general symmetry arguments to our two models. A detailed derivation of symmetry properties of the spin-orbit torque is given in Appendix A. In Sec. IV we show the results of analytical and numerical calculations of the spin-orbit torque in the two models. In Sec. V we discuss the results, and in particular summarize the symmetry considerations.

II. MODELS

In some materials electrical current can induce nonequilibrium spin-polarization due to spin-orbit coupling [32–36]. This effect is called the inverse spin-galvanic effect or the Edelstein effect. For the presence of nonvanishing net spin polarization (i.e., integrated over the whole unit cell) a broken inversion symmetry is needed. In FMs, due to exchange interaction between carrier spins and magnetic moments, the current-induced spin polarization (CISP) will exert a torque on the magnetization. This effect is the spin-orbit torque. In AFMs the effect is similar. Since the carrier–magnetic moment exchange interaction is short-range, spin polarization generated by the electrical current on a sublattice will interact primarily with the magnetic moments on that sublattice. To evaluate the spin-orbit torque in AFMs we thus have to calculate the CISP locally on each magnetic sublattice.

Note that in the spintronics community two different effects are termed as the spin-orbit torque. Apart from the effect discussed here, there exists also a torque generated in

heavy-metal/FM heterostructures due to spin Hall effect. Lateral electrical current generates spin current in the perpendicular direction due to the spin Hall effect, which flows in the FM and exerts a torque via the spin-transfer torque mechanism. Since the heterostructures have broken inversion symmetry, the torque due to inverse spin galvanic effect coexists with the spin Hall torque, rendering the entire physics quite complex to analyze (see for instance Ref. [37], where both mechanisms are included). We only consider bulk systems in which the spin Hall effect does not generate any torque.

To calculate the CISP $\delta\mathbf{S}_a$ (a denotes the sublattice) we use the Kubo linear response formalism. We can define a response tensor χ_a such that $\delta\mathbf{S}_a = \chi_a \mathbf{E}$, where \mathbf{E} is the electrical field. We assume that the only effect of disorder is a constant band broadening Γ and we consider a weak disorder (i.e., small Γ). As discussed in Ref. [28], the tensor χ_a can then be expressed as a sum of three terms:

$$\chi_a = \chi_a^I + \chi_a^{II(a)} + \chi_a^{II(b)}, \quad (1)$$

$$\chi_{a,ij}^I = -\frac{e\hbar}{2\Gamma} \sum_{\mathbf{k},n} \langle \psi_{n\mathbf{k}} | \hat{S}_{a,i} | \psi_{n\mathbf{k}} \rangle \langle \psi_{n\mathbf{k}} | \hat{v}_j | \psi_{n\mathbf{k}} \rangle \times \delta(\varepsilon_{\mathbf{k}n} - E_F), \quad (2)$$

$$\chi_{a,ij}^{II(a)} = e\hbar \sum_{\mathbf{k},n \neq m} \text{Im}[\langle \psi_{n\mathbf{k}} | \hat{S}_{a,i} | \psi_{m\mathbf{k}} \rangle \langle \psi_{m\mathbf{k}} | \hat{v}_j | \psi_{n\mathbf{k}} \rangle] \times \frac{\Gamma^2 - (\varepsilon_{\mathbf{k}n} - \varepsilon_{\mathbf{k}m})^2}{[(\varepsilon_{\mathbf{k}n} - \varepsilon_{\mathbf{k}m})^2 + \Gamma^2]^2} (f_{\mathbf{k}n} - f_{\mathbf{k}m}), \quad (3)$$

$$\chi_{a,ij}^{II(b)} = 2e\hbar \sum_{\mathbf{k},n \neq m} \text{Re}[\langle \psi_{n\mathbf{k}} | \hat{S}_{a,i} | \psi_{m\mathbf{k}} \rangle \langle \psi_{m\mathbf{k}} | \hat{v}_j | \psi_{n\mathbf{k}} \rangle] \times \frac{\Gamma(\varepsilon_{\mathbf{k}n} - \varepsilon_{\mathbf{k}m})}{[(\varepsilon_{\mathbf{k}n} - \varepsilon_{\mathbf{k}m})^2 + \Gamma^2]^2} (f_{\mathbf{k}n} - f_{\mathbf{k}m}), \quad (4)$$

where n, m are band indices, $\psi_{n\mathbf{k}}$ and $\varepsilon_{n\mathbf{k}}$ denote Bloch eigenfunctions and eigenvectors, respectively, E_F is the Fermi energy, $f_{\mathbf{k},n}$ is the Fermi-Dirac distribution function, \hat{v} is the velocity operator, e is the (positive) elementary charge, and \hat{S}_a is the spin-operator projected on sublattice a . Throughout this text we use a dimensionless spin operator; i.e., for one electron $\hat{\mathbf{S}} = \boldsymbol{\sigma}$, where $\boldsymbol{\sigma}$ is a vector of Pauli matrices. The \mathbf{k} sums run over the first Brillouin zone. These equations are the same as in Ref. [28], except we replace the spin operator by the spin operator projected on a sublattice. We calculate the CISP for the AFM spin sublattices. However, the same formalism applies also for any sublattice in a FM or a nonmagnetic material. χ_a^I is called the intraband term and $\chi_a^{II(a)}$, $\chi_a^{II(b)}$ are the interband terms. The term χ_a^I could also be obtained from the Boltzmann formula with constant relaxation time (with the relaxation time $\tau = \hbar/2\Gamma$). It is diverging in the limit $\Gamma \rightarrow 0$, analogously to how, for example, the conductivity diverges in a perfectly periodic crystal. Thus to evaluate this term we always have to consider some disorder, i.e., a finite Γ . The term $\chi_a^{II(a)}$ is constant in the zero- Γ limit, while the term $\chi_a^{II(b)}$ is zero in this limit. The zero- Γ limit of the term $\chi_a^{II(a)}$ is called the intrinsic contribution since it is determined only by the electronic structure of the crystal and not by disorder. The intrinsic contribution has been studied extensively in the

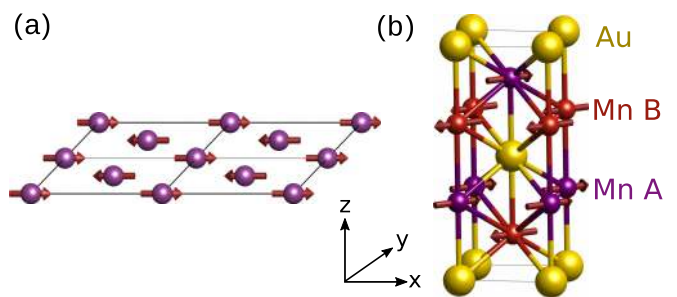


FIG. 1. Crystal structure of two model AFMs. (a) Crystal structure of the AFM 2D Rashba model. (b) Crystal structure of AFM Mn_2Au . Note that the unit cell shown is the conventional unit cell, which is as large as the primitive unit cell. All of the atoms with the same color are connected by a translation and are thus equivalent.

context of the anomalous Hall effect [38] and the spin Hall effect [39].

We calculated the CISP for the two tight-binding models from Ref. [31]. For completeness we give here a description of the models. The first one is a 2D tight-binding model with Rashba spin-orbit coupling, which simulates the structural inversion asymmetry at a surface or an interface. The model was chosen as a simplest AFM model in which the spin-orbit torque is expected. We consider a square AFM lattice [see Fig. 1(a)], where the d -orbital local magnetic moments are treated classically and only the conduction s electrons are treated quantum mechanically. The Hamiltonian can be written as

$$H = \sum_{\langle ij \rangle} J_{dd} \hat{\mathbf{M}}_i \cdot \hat{\mathbf{M}}_j + H^{tb} + \sum_i J_{sd} \hat{\mathbf{S}}_i \cdot \hat{\mathbf{M}}_i + H_R. \quad (5)$$

Here the indices i, j correspond to lattice sites; $\hat{\mathbf{M}}_i, \hat{\mathbf{M}}_j$ are directions of magnetic moments, J_{dd} and J_{sd} are the exchange constants for exchange interaction between the magnetic moments, and between the magnetic moments and conduction electron spins, respectively. H^{tb} contains the nearest-neighbor hoppings. H_R is the Rashba spin-orbit coupling, given by

$$H_R = \frac{\alpha}{2a_l} \sum_j [(c_{j\uparrow}^\dagger c_{j+\delta_x, \downarrow} - c_{j\downarrow}^\dagger c_{j+\delta_x, \uparrow}) - i(c_{j\uparrow}^\dagger c_{j+\delta_y, \downarrow} + c_{j\downarrow}^\dagger c_{j+\delta_y, \uparrow}) + \text{H.c.}], \quad (6)$$

where α is the Rashba parameter, a_l the lattice constant, c_j^\dagger, c_j are the creation and annihilation operators for electron on site j , and $j + \delta_x, j + \delta_y$ are nearest neighbors along the x and y directions, respectively. Reference [31] shows the band structure of this Hamiltonian. In all calculations we set $t = 3 \text{ eV}$, $J_{sd} = 1 \text{ eV}$, and $\frac{\alpha}{2a_l} = 0.1 \text{ eV}$, where t is the hopping parameter. Unless stated otherwise, the Fermi level is set to $E_F = -2 \text{ eV}$.

The torque is given by

$$\mathbf{T}_a = \mathbf{M}_a \times \mathbf{B}_a, \quad (7)$$

where \mathbf{M}_a is the magnetic moment on sublattice a and \mathbf{B}_a is the effective current-induced field, which for this model is given by [23]

$$\mathbf{B}_a = -J_{sd} \frac{\delta \mathbf{S}_a}{M_a}, \quad (8)$$

where M_a is the magnitude of magnetic moment on sublattice a .

The second model describes a 3D AFM Mn_2Au . The crystal structure of Mn_2Au is shown in Fig. 1(b). It is a collinear high Néel temperature AFM that has recently been identified as a promising material for AFM spintronics [40–42]. We describe Mn_2Au by an empirical tight-binding Slater-Koster model with s , p , and d electrons for each atom. We use the tight-binding parameters for single-element metals from Ref. [43] as a starting point and improve them so that the model agrees with the DFT calculation [31]. (See Ref. [44] for details of the method and the procedure for obtaining the tight-binding parameters.) The DFT calculation was done using the full-potential all-electron code Wien2k [45]. To improve the description of the Mn d states, we used the LDA+ U method with $U = 4.63$ eV and $J = 0.54$ eV [46].

For the tight-binding calculations of the CISP we add a \mathbf{k} -independent on-site spin-orbit coupling for both Mn and Au atoms with parameters obtained from atomistic Hartree-Fock calculations. The tight-binding model is not expected to be quantitatively as accurate as DFT calculation; however, it can be used to illustrate the origin and the symmetries of the spin-orbit torque in the AFM Mn_2Au crystal. A quantitative comparison to DFT spin-orbit torque calculations is presented in Sec. V.

In the DFT calculation it is possible to evaluate the effective field or directly the torque using the space-dependent exchange field [21,37]. In the case of the tight-binding calculation, we obtain only the CISP. To get an estimate of the effective field we can still use Eq. (8), which corresponds to taking a spatial average of the exchange field. In Ref. [31] the carrier–magnetic moment exchange constant was set to $J_{sd} = 1$ eV, which is a typical value estimated for transition metals [47].

In Ref. [31], only the terms $\chi_a^{II(a)}$ for the 2D Rashba model and χ_a^I for the Mn_2Au model were considered, respectively. Here we take into account all three terms for both models. Since we are primarily interested in the small- Γ limit, we mostly focus on terms χ_a^I , $\chi_a^{II(a)}$, but the term $\chi_a^{II(b)}$ is also discussed.

III. SYMMETRY CONSIDERATIONS

Symmetry is crucial for understanding when the spin-orbit torque can exist and what form it has. In Appendix A we give a derivation of the symmetry properties of the tensor χ_a . Here we summarize the main results and apply them to our two models. The following analysis applies both to the effective field and the CISP because they have the same symmetry properties. Since spin-orbit torque is a nonequilibrium process that includes dissipation, the tensor χ_a does not have a simple behavior under time reversal. To deal with this problem we separate the tensor into a part even in magnetic moments and a part odd in magnetic moments:

$$\chi_a^{\text{even}}(\mathbf{M}) = [\chi_a(\mathbf{M}) + \chi_a(-\mathbf{M})]/2, \quad (9)$$

$$\chi_a^{\text{odd}}(\mathbf{M}) = [\chi_a(\mathbf{M}) - \chi_a(-\mathbf{M})]/2, \quad (10)$$

where $[\mathbf{M}] = [\mathbf{M}_A, \mathbf{M}_B, \dots]$ denotes the directions of all magnetic moments in the magnetic unit cell. As shown in

the Appendix A it holds that

$$\chi_a^{\text{even}} = \chi_a^I + \chi_a^{II(b)}, \quad (11)$$

$$\chi_a^{\text{odd}} = \chi_a^{II(a)}. \quad (12)$$

In Appendix A, the following rules are derived for the transformation of χ_a under symmetry operation R :

$$\chi_{a'}^{\text{even}} = \det(D)D\chi_a^{\text{even}}D^{-1}, \quad (13)$$

$$\chi_{a'}^{\text{odd}} = \pm \det(D)D\chi_a^{\text{odd}}D^{-1}, \quad (14)$$

where a' is the sublattice to which the sublattice a transforms under symmetry operation R and D is a matrix representing the symmetry operation in real space as defined by Eq. (A13). The plus sign in Eq. (14) corresponds to a symmetry operation that does not contain time reversal and the minus to a symmetry operation that contains time reversal. These rules apply for any form of magnetic order as well as for nonmagnetic crystals. The same rules also apply for the tensor χ , which describes the net CISP.

Basic symmetry rules can be inferred from Eqs. (13) and (14). If the system has an inversion symmetry,

$$\chi_{a'} = -\chi_a. \quad (15)$$

If also inversion transforms the sublattice a into itself, then there can be no CISP on the sublattice a . We therefore reach an important conclusion: for the existence of the CISP (and thus also the spin-orbit torque) on sublattice a , the inversion symmetry has to be *locally* broken; i.e., the atomic site which forms the sublattice a must not be an inversion center. This means that current can generate spin polarization even in a material that has global inversion symmetry if inversion symmetry is broken locally. However, it is also important to note that if the inversion symmetry is locally broken, the CISP can still vanish due to other symmetries. For example, a diamond lattice has a global inversion symmetry, but the two different lattice sites in the diamond unit cell have inversion symmetry locally broken. Without any strain, the CISP will nevertheless vanish. However, when a uniaxial strain is present in the diamond lattice a CISP with opposite sign on the two different sites will appear [48].

In the 2D Rashba model, the inversion symmetry is broken globally due to the structural asymmetry of the assumed layered system. In the AFM Mn_2Au crystal, the inversion symmetry is broken by the magnetic order since the inversion partner lattice sites are occupied by Mn atoms with opposite moments. Even without magnetic moments, however, the inversion symmetry is locally broken for each sublattice. This can be seen in Fig. 1(b) and is discussed in more detail in Sec. V (see also Fig. 9).

Of particular interest in the case of AFMs is to determine how the CISPs on the AFM spin sublattices are related. This is because for the spin-orbit torque to be efficient, the current-induced effective magnetic field and thus also the CISP have to be staggered. Since the exchange interaction is much larger than any field typically acting on AFMs, we assume that during any dynamics the two magnetic moments stay approximately collinear (although any dynamics of the AFM order parameter induces a small magnetization). Then

in the AFM 2D Rashba model, a simultaneous translation and time inversion will always be a symmetry of the model that transforms one AFM spin-sublattice into the other. For such a symmetry operation, $D = I$, where I is the identity matrix, and therefore

$$\chi_A^{\text{even}} = \chi_B^{\text{even}}, \quad (16)$$

$$\chi_A^{\text{odd}} = -\chi_B^{\text{odd}}. \quad (17)$$

This implies that the efficient torque driven by a staggered field is generated by the odd component of the response tensor.

In the Mn_2Au type of crystal, the AFM spin sublattices are not connected by translation. Instead they are connected by inversion around the unit cell center so that a combination of inversion and time reversal is a symmetry of the model. Since in this case $D = -I$, we find

$$\chi_A^{\text{even}} = -\chi_B^{\text{even}}, \quad (18)$$

$$\chi_A^{\text{odd}} = \chi_B^{\text{odd}}, \quad (19)$$

and now it is the even component of the response tensor that generates the staggered CISP. The two models illustrate a general phenomenology of CISPs in collinear AFMs, in which the two AFM spin sublattices are typically connected either by a translation or by an inversion.

By considering the magnetic space group of a given material, one can find using the Eqs. (13) and (14) the most general form of the tensor χ_a as well as relations between tensors χ_a on different sublattices. Note that for the CISP projected on a sublattice it is not enough to consider the point group of the crystal because then the information on the relationship between the sublattices would be lost. We provide a free program which outputs the symmetry of the CISP for any type of crystal and magnetic structure [49]. See the Appendix B for a brief description of the code. Symmetry of the tensors, which describe the global spin-orbit torque, can be found in Ref. [50] for every magnetic point group. These also apply for the local spin-orbit torque, if one uses the site symmetry group (of the site which forms the sublattice), i.e., the group of symmetry operations of the whole crystal that leave the sublattice invariant.

In a magnetic material, the CISP in general depends on the direction of the magnetic moments. This is because the CISP is determined by the electronic structure and in the presence of spin-orbit coupling the electronic structure depends on the direction of magnetic moments. Understanding this dependence is important because it determines what kind of magnetic dynamics the spin-orbit torque will induce. Note that a CISP strongly dependent on the direction of magnetic moments has been observed experimentally [24]. To describe the dependence of the CISP on the direction of magnetic moments, it is useful to expand the linear response tensor in powers of magnetic moments. In general χ_a depends on the directions of all magnetic moments in the system. We consider only FMs and collinear two-sublattice AFMs. We again assume that the magnetic moments will always stay approximately collinear. Since the intra-spin-sublattice exchange is typically very large, we also assume that the magnitude of the spin-sublattice magnetic moments will not

change during dynamics. Then χ_a will be a function of only the spin-axis direction $\hat{\mathbf{n}}$. In the case of two-sublattice collinear AFMs, $\hat{\mathbf{n}} = \hat{\mathbf{L}} = \hat{\mathbf{L}}/|\mathbf{L}|$, where \mathbf{L} is the Néel vector: $\mathbf{L} = \mathbf{M}_A - \mathbf{M}_B$. In FMs $\hat{\mathbf{n}} = \mathbf{M}/|\mathbf{M}|$. We can then write the tensor χ_a in the following way [51]:

$$\chi_{a,ij}(\hat{\mathbf{n}}) = \chi_{a,ij}^{(0)} + \chi_{a,ij,k}^{(1)} \hat{n}_k + \chi_{a,ij,kl}^{(2)} \hat{n}_k \hat{n}_l + \dots \quad (20)$$

Here the Einstein summation notation is used. Note that since $\hat{\mathbf{n}}$ is a unit vector, the expansion could be done using two variables only. We find it more practical, however, to use all three components of $\hat{\mathbf{n}}$. The odd terms in the expansion correspond to the odd part of the CISP, while the even terms correspond to the even part.

To find the symmetry properties of the expansion (20) we have to consider the nonmagnetic site symmetry group. This is a group of symmetry operations of the nonmagnetic crystal that leave the sublattice a invariant. [See Appendix A for details on how to find the symmetry properties of the expansion (20).] Since there are only 21 nonmagnetic point groups with broken inversion symmetry, it is feasible to calculate all allowed leading terms of the expansion (20). This was done for the zeroth-order terms in Ref. [48] that focused on the CISP in FMs. The zeroth-order terms generate the fieldlike torque. In Table I we give all allowed first-order terms and for completeness we also show the zeroth-order terms. The zeroth-order term vanishes for several point groups. For those we also give the second-order terms in Table II. Together the tables give the lowest-order terms for the even and odd part of the CISP in all 21 noncentrosymmetric point groups.

The tensors in Tables I and II are given in Cartesian coordinate systems. The Cartesian systems are defined in terms of the conventional basis vectors $\mathbf{a}, \mathbf{b}, \mathbf{c}$ (see the *International Tables for Crystallography* [52]). The choice of the Cartesian system is straightforward for the orthorhombic, tetragonal, and cubic groups. The tensors for the triclinic group 1 have a completely general form and the choice of the coordinate system is thus irrelevant for this group. For hexagonal and trigonal groups, we choose the right-handed coordinate system that satisfies $\mathbf{x} = \mathbf{a}/|\mathbf{a}|$, $\mathbf{z} = \mathbf{c}/|\mathbf{c}|$. For the monoclinic groups we use the unique axis b setting [52] and choose the right-handed coordinate system that satisfies $\mathbf{x} = \mathbf{a}/|\mathbf{a}|$, $\mathbf{y} = \mathbf{b}/|\mathbf{b}|$.

The tensors in Tables I and II apply for two-sublattice collinear AFMs and FMs. In the case of AFMs the expansion only applies for the CISP on a sublattice and correspondingly the site symmetry group has to be used. In FMs, the tensors apply for the local as well as for the net CISP. In the latter case the point group of the whole crystal has to be used. Since the zeroth-order term is independent of magnetic moments it can be equally considered for any material, including noncollinear AFMs. In nonmagnetic materials, there is naturally no dependence on magnetic moments so the zeroth-order term describes the CISP completely in this case.

The zeroth-order terms that generate the fieldlike torque are particularly important since they are often dominant. As discussed in Ref. [48], the tensors corresponding to the fieldlike torque are in general composed of three distinct terms: generalized Rashba and Dresselhaus terms and a term

TABLE I. Zeroth- and first-order terms in the expansion (20) for the point groups with broken inversion symmetry. The tensors $\chi^{(1)}$ have the spin-axis direction included: $\chi_{ij}^{(1)} = \chi_{ijk}^{(1)} \hat{n}_k$. The x parameters can be chosen arbitrarily for each tensor. Note that the groups $-42m$ and $-4m2$, 312 and 321 , $3m1$ and $31m$, and $-6m2$ and $-62m$ are equivalent and differ only by a coordinate transformation. For completeness we also give the tensors for the equivalent groups.

Crystal system	Point group	$\chi^{(0)}$	$\chi^{(1)}$
triclinic	1	$\begin{pmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{pmatrix}$	$\begin{pmatrix} \hat{n}_x x_{111} + \hat{n}_y x_{112} + \hat{n}_z x_{113} & \hat{n}_x x_{121} + \hat{n}_y x_{122} + \hat{n}_z x_{123} & \hat{n}_x x_{131} + \hat{n}_y x_{132} + \hat{n}_z x_{133} \\ \hat{n}_x x_{211} + \hat{n}_y x_{212} + \hat{n}_z x_{213} & \hat{n}_x x_{221} + \hat{n}_y x_{222} + \hat{n}_z x_{223} & \hat{n}_x x_{231} + \hat{n}_y x_{232} + \hat{n}_z x_{233} \\ \hat{n}_x x_{311} + \hat{n}_y x_{312} + \hat{n}_z x_{313} & \hat{n}_x x_{321} + \hat{n}_y x_{322} + \hat{n}_z x_{323} & \hat{n}_x x_{331} + \hat{n}_y x_{332} + \hat{n}_z x_{333} \end{pmatrix}$
monoclinic	2	$\begin{pmatrix} x_{11} & 0 & x_{13} \\ 0 & x_{22} & 0 \\ x_{31} & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} \hat{n}_y x_1 & \hat{n}_x x_{13} + \hat{n}_z x_{12} & \hat{n}_y x_3 \\ \hat{n}_x x_5 + \hat{n}_z x_6 & \hat{n}_y x_{11} & \hat{n}_x x_4 + \hat{n}_z x_7 \\ \hat{n}_y x_{10} & \hat{n}_x x_8 + \hat{n}_z x_9 & \hat{n}_y x_2 \end{pmatrix}$
	m	$\begin{pmatrix} 0 & x_{12} & 0 \\ x_{21} & 0 & x_{23} \\ 0 & x_{32} & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_x x_{12} + \hat{n}_z x_9 & \hat{n}_y x_{14} & \hat{n}_x x_{13} + \hat{n}_z x_8 \\ \hat{n}_y x_3 & \hat{n}_x x_{11} + \hat{n}_z x_{10} & \hat{n}_y x_4 \\ \hat{n}_x x_7 + \hat{n}_z x_6 & \hat{n}_y x_5 & \hat{n}_x x_1 + \hat{n}_z x_2 \end{pmatrix}$
orthorhombic	222	$\begin{pmatrix} x_{11} & 0 & 0 \\ 0 & x_{22} & 0 \\ 0 & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} 0 & \hat{n}_z x_5 & \hat{n}_y x_4 \\ \hat{n}_z x_1 & 0 & \hat{n}_x x_6 \\ \hat{n}_y x_3 & \hat{n}_x x_2 & 0 \end{pmatrix}$
	$mm2$	$\begin{pmatrix} 0 & x_{12} & 0 \\ x_{21} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_z x_4 & 0 & \hat{n}_x x_6 \\ 0 & \hat{n}_z x_5 & \hat{n}_y x_7 \\ \hat{n}_x x_3 & \hat{n}_y x_2 & \hat{n}_z x_1 \end{pmatrix}$
tetragonal	4	$\begin{pmatrix} x_{11} & -x_{21} & 0 \\ x_{21} & x_{11} & 0 \\ 0 & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} \hat{n}_z x_6 & -\hat{n}_z x_2 & \hat{n}_x x_5 - \hat{n}_y x_7 \\ \hat{n}_z x_2 & \hat{n}_z x_6 & \hat{n}_x x_7 + \hat{n}_y x_5 \\ \hat{n}_x x_4 - \hat{n}_y x_3 & \hat{n}_x x_3 + \hat{n}_y x_4 & \hat{n}_z x_1 \end{pmatrix}$
	-4	$\begin{pmatrix} x_{11} & x_{21} & 0 \\ x_{21} & -x_{11} & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_z x_5 & \hat{n}_z x_1 & \hat{n}_x x_4 + \hat{n}_y x_6 \\ \hat{n}_z x_1 & -\hat{n}_z x_5 & \hat{n}_x x_6 - \hat{n}_y x_4 \\ \hat{n}_x x_3 + \hat{n}_y x_2 & \hat{n}_x x_2 - \hat{n}_y x_3 & 0 \end{pmatrix}$
	422	$\begin{pmatrix} x_{11} & 0 & 0 \\ 0 & x_{11} & 0 \\ 0 & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} 0 & -\hat{n}_z x_3 & -\hat{n}_y x_2 \\ \hat{n}_z x_3 & 0 & \hat{n}_x x_2 \\ -\hat{n}_y x_1 & \hat{n}_x x_1 & 0 \end{pmatrix}$
	$4mm$	$\begin{pmatrix} 0 & -x_{21} & 0 \\ x_{21} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_z x_4 & 0 & \hat{n}_x x_1 \\ 0 & \hat{n}_z x_4 & \hat{n}_y x_1 \\ \hat{n}_x x_3 & \hat{n}_y x_3 & \hat{n}_z x_2 \end{pmatrix}$
	$-42m$	$\begin{pmatrix} x_{11} & 0 & 0 \\ 0 & -x_{11} & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & \hat{n}_z x_3 & \hat{n}_y x_2 \\ \hat{n}_z x_3 & 0 & \hat{n}_x x_2 \\ \hat{n}_y x_1 & \hat{n}_x x_1 & 0 \end{pmatrix}$
	$-4m2$	$\begin{pmatrix} 0 & x_{21} & 0 \\ x_{21} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_z x_3 & 0 & \hat{n}_x x_1 \\ 0 & -\hat{n}_z x_3 & -\hat{n}_y x_1 \\ \hat{n}_x x_2 & -\hat{n}_y x_2 & 0 \end{pmatrix}$
trigonal	3	$\begin{pmatrix} x_{11} & -x_{21} & 0 \\ x_{21} & x_{11} & 0 \\ 0 & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} \hat{n}_x x_7 + \hat{n}_y x_2 + \hat{n}_z x_8 & \hat{n}_x x_2 - \hat{n}_y x_7 - \hat{n}_z x_3 & \hat{n}_x x_6 - \hat{n}_y x_9 \\ \hat{n}_x x_2 - \hat{n}_y x_7 + \hat{n}_z x_3 & -\hat{n}_x x_7 - \hat{n}_y x_2 + \hat{n}_z x_8 & \hat{n}_x x_9 + \hat{n}_y x_6 \\ \hat{n}_x x_5 - \hat{n}_y x_4 & \hat{n}_x x_4 + \hat{n}_y x_5 & \hat{n}_z x_1 \end{pmatrix}$
	312	$\begin{pmatrix} x_{11} & 0 & 0 \\ 0 & x_{11} & 0 \\ 0 & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} \hat{n}_y x_3 & \hat{n}_x x_3 - \hat{n}_z x_4 & -\hat{n}_y x_2 \\ \hat{n}_x x_3 + \hat{n}_z x_4 & -\hat{n}_y x_3 & \hat{n}_x x_2 \\ -\hat{n}_y x_1 & \hat{n}_x x_1 & 0 \end{pmatrix}$
	321	$\begin{pmatrix} x_{11} & 0 & 0 \\ 0 & x_{11} & 0 \\ 0 & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} \hat{n}_x x_3 & -\hat{n}_y x_3 - \hat{n}_z x_4 & -\hat{n}_y x_2 \\ -\hat{n}_y x_3 + \hat{n}_z x_4 & -\hat{n}_x x_3 & \hat{n}_x x_2 \\ -\hat{n}_y x_1 & \hat{n}_x x_1 & 0 \end{pmatrix}$

TABLE I. (Continued.)

Crystal system	Point group	$\chi^{(0)}$	$\chi^{(1)}$	
hexagonal	3m1	$\begin{pmatrix} 0 & -x_{21} & 0 \\ x_{21} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_y x_4 + \hat{n}_z x_5 & \hat{n}_x x_4 & \hat{n}_x x_2 \\ \hat{n}_x x_4 & -\hat{n}_y x_4 + \hat{n}_z x_5 & \hat{n}_y x_2 \\ \hat{n}_x x_3 & \hat{n}_y x_3 & \hat{n}_z x_1 \end{pmatrix}$	
	31m	$\begin{pmatrix} 0 & -x_{21} & 0 \\ x_{21} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_x x_3 + \hat{n}_z x_5 & -\hat{n}_y x_3 & \hat{n}_x x_1 \\ -\hat{n}_y x_3 & -\hat{n}_x x_3 + \hat{n}_z x_5 & \hat{n}_y x_1 \\ \hat{n}_x x_4 & \hat{n}_y x_4 & \hat{n}_z x_2 \end{pmatrix}$	
	6	$\begin{pmatrix} x_{11} & -x_{21} & 0 \\ x_{21} & x_{11} & 0 \\ 0 & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} \hat{n}_z x_6 & -\hat{n}_z x_2 & \hat{n}_x x_5 - \hat{n}_y x_7 \\ \hat{n}_z x_2 & \hat{n}_z x_6 & \hat{n}_x x_7 + \hat{n}_y x_5 \\ \hat{n}_x x_4 - \hat{n}_y x_3 & \hat{n}_x x_3 + \hat{n}_y x_4 & \hat{n}_z x_1 \end{pmatrix}$	
	-6	$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_x x_1 + \hat{n}_y x_2 & \hat{n}_x x_2 - \hat{n}_y x_1 & 0 \\ \hat{n}_x x_2 - \hat{n}_y x_1 & -\hat{n}_x x_1 - \hat{n}_y x_2 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	
	622	$\begin{pmatrix} x_{11} & 0 & 0 \\ 0 & x_{11} & 0 \\ 0 & 0 & x_{33} \end{pmatrix}$	$\begin{pmatrix} 0 & -\hat{n}_z x_3 & -\hat{n}_y x_2 \\ \hat{n}_z x_3 & 0 & \hat{n}_x x_2 \\ -\hat{n}_y x_1 & \hat{n}_x x_1 & 0 \end{pmatrix}$	
	6mm	$\begin{pmatrix} 0 & -x_{21} & 0 \\ x_{21} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_z x_4 & 0 & \hat{n}_x x_1 \\ 0 & \hat{n}_z x_4 & \hat{n}_y x_1 \\ \hat{n}_x x_3 & \hat{n}_y x_3 & \hat{n}_z x_2 \end{pmatrix}$	
	-6m2	$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_y x_1 & \hat{n}_x x_1 & 0 \\ \hat{n}_x x_1 & -\hat{n}_y x_1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	
	-62m	$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} \hat{n}_x x_1 & -\hat{n}_y x_1 & 0 \\ -\hat{n}_y x_1 & -\hat{n}_x x_1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	
	cubic	23	$\begin{pmatrix} x_{11} & 0 & 0 \\ 0 & x_{11} & 0 \\ 0 & 0 & x_{11} \end{pmatrix}$	$\begin{pmatrix} 0 & \hat{n}_z x_2 & \hat{n}_y x_1 \\ \hat{n}_z x_1 & 0 & \hat{n}_x x_2 \\ \hat{n}_y x_2 & \hat{n}_x x_1 & 0 \end{pmatrix}$
		432	$\begin{pmatrix} x_{11} & 0 & 0 \\ 0 & x_{11} & 0 \\ 0 & 0 & x_{11} \end{pmatrix}$	$\begin{pmatrix} 0 & -\hat{n}_z x_1 & \hat{n}_y x_1 \\ \hat{n}_z x_1 & 0 & -\hat{n}_x x_1 \\ -\hat{n}_y x_1 & \hat{n}_x x_1 & 0 \end{pmatrix}$
-43m		$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & \hat{n}_z x_1 & \hat{n}_y x_1 \\ \hat{n}_z x_1 & 0 & \hat{n}_x x_1 \\ \hat{n}_y x_1 & \hat{n}_x x_1 & 0 \end{pmatrix}$	

describing a response proportional to the electric field. They are described by the following tensors respectively:

$$\chi_a^{\text{gR}} = \begin{pmatrix} x_{11} & -x_{21} & 0 \\ x_{21} & x_{11} & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad (21)$$

$$\chi_a^{\text{gD}} = \begin{pmatrix} x_{11} & x_{21} & 0 \\ x_{21} & -x_{11} & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad (22)$$

$$\chi_a^E = \begin{pmatrix} x_{11} & 0 & 0 \\ 0 & x_{11} & 0 \\ 0 & 0 & x_{11} \end{pmatrix}. \quad (23)$$

The generalized Rashba and Dresselhaus CISPs lie in a plane and are only present for the current applied in the same plane. In Eqs. (21) and (22), it is the xy plane, but in general, it can be any plane. The generalized Rashba and Dresselhaus terms differ in how the CISP depends on the current direction, as illustrated in Figs. 2(a) and 2(b). In the case of the Rashba CISP, when the current direction is rotated the CISP rotates in the same way, while in the case of the Dresselhaus CISP the field rotates in the opposite direction. They differ from the conventional Rashba and Dresselhaus terms,

$$\chi_a^{\text{R}} = \begin{pmatrix} 0 & -x_{21} & 0 \\ x_{21} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad (24)$$

TABLE II. Second-order terms in the expansion (20) for the point groups which have no zeroth-order term allowed by symmetry. The x parameters can be chosen arbitrarily for each tensor.

Point group	$\chi^{(2)}$
-6	$\begin{pmatrix} \hat{n}_z(\hat{n}_x x_5 + \hat{n}_y x_4) & \hat{n}_z(\hat{n}_x x_4 - \hat{n}_y x_5) & \hat{n}_z^2 x_2 + 2\hat{n}_x \hat{n}_y x_0 - \hat{n}_y^2 x_2 \\ \hat{n}_z(\hat{n}_x x_4 - \hat{n}_y x_5) & -\hat{n}_z(\hat{n}_x x_5 + \hat{n}_y x_4) & \hat{n}_x^2 x_0 - 2\hat{n}_x \hat{n}_y x_2 - \hat{n}_y^2 x_0 \\ \hat{n}_x^2 x_1 + 2\hat{n}_x \hat{n}_y x_3 - \hat{n}_y^2 x_1 & \hat{n}_x^2 x_3 - 2\hat{n}_x \hat{n}_y x_1 - \hat{n}_y^2 x_3 & 0 \end{pmatrix}$
-6m2	$\begin{pmatrix} \hat{n}_x \hat{n}_z x_1 & -\hat{n}_y \hat{n}_z x_1 & x_2(\hat{n}_x^2 - \hat{n}_y^2) \\ -\hat{n}_y \hat{n}_z x_1 & -\hat{n}_x \hat{n}_z x_1 & -2\hat{n}_x \hat{n}_y x_2 \\ x_3(\hat{n}_x^2 - \hat{n}_y^2) & -2\hat{n}_x \hat{n}_y x_3 & 0 \end{pmatrix}$
-62m	$\begin{pmatrix} \hat{n}_y \hat{n}_z x_1 & \hat{n}_x \hat{n}_z x_1 & 2\hat{n}_x \hat{n}_y x_2 \\ \hat{n}_x \hat{n}_z x_1 & -\hat{n}_y \hat{n}_z x_1 & x_2(\hat{n}_x^2 - \hat{n}_y^2) \\ 2\hat{n}_x \hat{n}_y x_3 & x_3(\hat{n}_x^2 - \hat{n}_y^2) & 0 \end{pmatrix}$
-43m	$\begin{pmatrix} x_2(-\hat{n}_y^2 + \hat{n}_z^2) & \hat{n}_x \hat{n}_y x_1 & -\hat{n}_x \hat{n}_z x_1 \\ -\hat{n}_x \hat{n}_y x_1 & x_2(\hat{n}_x^2 - \hat{n}_z^2) & \hat{n}_y \hat{n}_z x_1 \\ \hat{n}_x \hat{n}_z x_1 & -\hat{n}_y \hat{n}_z x_1 & x_2(-\hat{n}_x^2 + \hat{n}_y^2) \end{pmatrix}$

$$\chi_a^D = \begin{pmatrix} x_{11} & 0 & 0 \\ 0 & -x_{11} & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad (25)$$

by a constant offset angle between the applied current and the CISP [see Figs. 2(c) and 2(d)].

The Rashba term or generalized Rashba term with nonzero x_{21} components occurs in polar point groups (groups 1, 2, m , $mm2$, 4, $4mm$, 3, $3m1$, 6, and $6mm$), i.e., in groups which allow the existence of a permanent electric dipole moment. In a polar group, there is a Rashba term in the

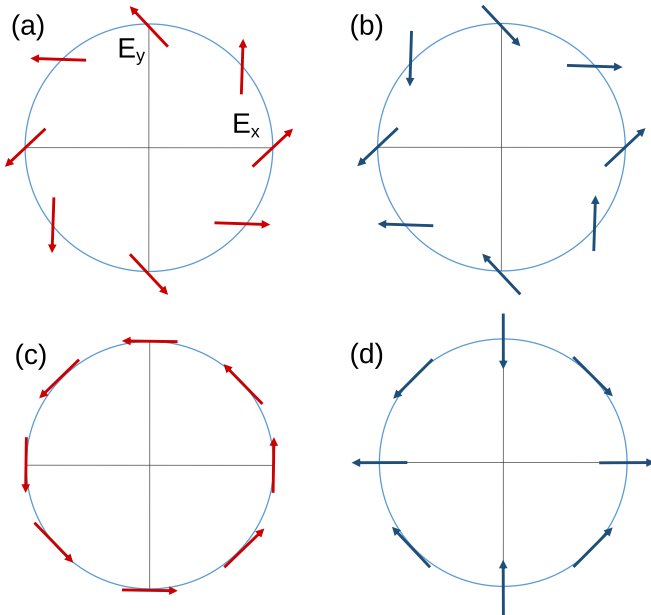


FIG. 2. Illustration of the Rashba and Dresselhaus CISPs. The figures show the dependence of CISP on the electric field direction. Adapted from [48]. (a) Generalized Rashba CISP. (b) Generalized Dresselhaus CISP. (c) Rashba CISP. (d) Dresselhaus CISP.

plane perpendicular to the electric dipole moment. The Rashba term can be written as $\delta\mathbf{S} \sim \hat{\mathbf{D}} \times \mathbf{E}$, where $\hat{\mathbf{D}}$ is the direction of the electric dipole moment. In all polar groups except for m and 1, $\hat{\mathbf{D}}$ is oriented along the polar direction (a direction invariant under all symmetry operations), which in the coordinate systems used in Table I is always oriented along the z axis. In group 1, $\hat{\mathbf{D}}$ can have any direction, and in the group m , it is oriented in the mirror plane. Polar point groups 1, 2, 4, 3, and 6 contain the generalized Rashba term (rather than just the Rashba term), which in addition also occurs in nonpolar point groups 222, 422, 312, and 622 with $x_{21} = 0$. The CISP described by χ_a^E in Eq. (23) occurs in enantiomorphic (also called chiral) crystals (point groups 1, 2, 222, 4, 422, 3, 312, 6, 622, 23, and 432), i.e., crystals in which no symmetry operation contains inversion. The CISP is an axial vector (even under inversion), while the electric field is a polar vector (odd under inversion). These two vectors can only be proportional in the enantiomorphic crystals since in these crystals there is no difference between an axial and polar vector. The generalized Dresselhaus term [Eq. (22)] occurs in point groups 1, 2, m , 222, $mm2$, -4 , and $-42m$, of which the groups 222 and $-42m$ have just the Dresselhaus term.

The nonmagnetic symmetry group of the magnetic sites in both the 3D Mn_2Au and the 2D Rashba model is $4mm$, which has a Rashba zeroth-order CISP of the form $\mathbf{z} \times \mathbf{E}$. Another example of an AFM with a Rashba zeroth-order CISP is CuMnAs [7]. Dresselhaus zeroth-order CISPs have been previously observed in FMs GaMnAs [24,25] and NiMnSb [48] (global point group $-42m$). AFM CuMnSb , in which the Mn atomic sites have symmetry group $-42m$ [53], is another example for which we expect the Dresselhaus zeroth-order CISP, according to our symmetry analysis.

The first-order term for the $4mm$ point group can be written in the following way:

$$\chi_a^{(1)} = X_1 + X_2 + X_3, \quad (26)$$

where

$$X_1 = C_1 \begin{pmatrix} -\hat{L}_z & 0 & 0 \\ 0 & -\hat{L}_z & 0 \\ \hat{L}_x & \hat{L}_y & 0 \end{pmatrix}, \quad (27)$$

$$X_2 = C_2 \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \hat{L}_x & \hat{L}_y & 0 \end{pmatrix}, \quad (28)$$

$$X_3 = \begin{pmatrix} 0 & 0 & C_3 \hat{L}_x \\ 0 & 0 & C_3 \hat{L}_y \\ 0 & 0 & C_4 \hat{L}_z \end{pmatrix}. \quad (29)$$

Note that in the 2D Rashba model the current cannot flow in the z direction, so the third column has no physical meaning in this case. The contribution to the CISP generated by the tensor X_1 can be constructed from the polar direction of the group $4mm$: $\hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E})$. The contribution to the CISP coming from the tensor X_2 can be written as $(\hat{\mathbf{L}} \cdot \mathbf{E}_{\parallel})\mathbf{z}$, where \mathbf{E}_{\parallel} is the in-plane (the plane here refers to the xy plane) component of the electric field.

Finally we note the connection of our general symmetry analysis of the CISP to the discussion in Ref. [54], where Rashba and Dresselhaus-like spin-orbit coupling effects in locally noncentrosymmetric crystals were studied on the level of equilibrium electronic structure. The local inversion symmetry breaking induces local band splittings, i.e., splittings that become apparent when the band structure is projected on sublattices. The local spin-orbit torque discussed here can be thought of as a consequence of the local band splittings, similarly to how global Rashba or Dresselhaus spin-orbit torques are caused by Rashba or Dresselhaus spin splittings in the full (unprojected) band structure.

IV. LINEAR RESPONSE THEORY

A. Analytical calculations

The CISP in the AFM 2D Rashba model can be calculated analytically when magnetic moments are oriented close to the out-of-plane (\mathbf{z}) direction and when the Fermi level is close to the bottom or the top of the bands so that only \mathbf{k} points close to the Γ point matter for the torque calculation. Here we describe the main aspects of the derivation; for more details see Appendix C. To the second order in k the Hamiltonian (5) can be expressed as

$$\hat{H} = \gamma_k \hat{\tau}_x - \alpha k \hat{\sigma} \cdot \boldsymbol{\mu} \hat{\tau}_x + J_{\text{sd}} \hat{\mathbf{L}} \cdot \hat{\sigma} \hat{\tau}_z, \quad (30)$$

where $\gamma_k = ta_l^2[k^2 - (2/a_l)^2]$; $\boldsymbol{\mu}$ is a unit vector perpendicular to the \mathbf{k} vector, expressed as $\boldsymbol{\mu} = (\sin \varphi_k, -\cos \varphi_k, 0)$, where φ_k is defined by $\mathbf{k} = k(\cos \varphi_k, \sin \varphi_k, 0)$. $\hat{\sigma}$ and $\hat{\tau}$ are Pauli matrices with $\hat{\sigma}/2$ representing the carrier spin degree of freedom and $\hat{\tau}$ the AFM spin-sublattice degree of freedom of carriers.

The unperturbed retarded Green's function, defined as $\hat{G}_0^R = (\epsilon - \hat{H} + i0^+)^{-1}$, reads

$$\hat{G}_0^R = \frac{1}{4S_k} \sum_{s,\eta=\pm 1} \frac{1}{\epsilon - \epsilon_{s,\eta} + i0^+} \times \left(S_k + s[\gamma_k(\hat{\sigma} \cdot \boldsymbol{\mu}) - J_{\text{sd}} \hat{\tau}_y(\hat{\sigma} \cdot \hat{\mathbf{L}} \times \boldsymbol{\mu})] \right)$$

$$+ \frac{1}{\epsilon_{s,\eta}} \left\{ (s\gamma_k^2 + sJ_{\text{sd}}^2 + \alpha k S_k)(\hat{\sigma} \cdot \boldsymbol{\mu}) \hat{\tau}_x + [\gamma_k \hat{\tau}_x + J_{\text{sd}}(\hat{\sigma} \cdot \hat{\mathbf{L}}) \hat{\tau}_z](S_k + s\alpha k) - sJ_{\text{sd}}(\hat{\mathbf{L}} \cdot \boldsymbol{\mu})[J_{\text{sd}}(\hat{\sigma} \cdot \hat{\mathbf{L}}) \hat{\tau}_x - \gamma_k \hat{\tau}_z + \alpha k(\hat{\sigma} \cdot \boldsymbol{\mu}) \hat{\tau}_z] \right\}, \quad (31)$$

where $\epsilon_{s,\eta}$ denotes the band structure given by

$$\epsilon_{s,\eta} = \eta \sqrt{\gamma_k^2 + J_{\text{sd}}^2 + \alpha^2 k^2 + 2s\alpha k S_k}, \quad (32)$$

$$S_k = \sqrt{\gamma_k^2 + J_{\text{sd}}^2 [1 - \sin^2 \theta \sin^2(\varphi_k - \varphi)]}. \quad (33)$$

Indices s,η refer to the spin chirality ($s = \pm 1$) and to the electron/hole bands ($\eta = \pm 1$). In the limit of vanishing α , both spin chiralities become degenerate. The angles θ, φ are spherical coordinates of the vector $\hat{\mathbf{L}}$. In order to get an analytically tractable expression for the CISP, we express in the following the Green's function in term of the projection operator $\mathcal{A}_{s,\eta} = |s,\eta\rangle\langle s,\eta|$ such that $\hat{G}_0^R = \sum_{s,\eta} \mathcal{A}_{s,\eta} / (\epsilon - \epsilon_{s,\eta} + i0^+)$.

We evaluate the intraband term using the expression (2), which applies for small Γ . For the interband term we take the $\Gamma \rightarrow 0$ limit in which the term $\chi_a^{\text{II(b)}}$ is zero and the term $\chi_a^{\text{II(a)}}$ is constant. The CISP can then be written as

$$\mathbf{S}^{\text{Intra}} = \frac{e\hbar}{2\Gamma V} \sum_{v,\mathbf{k}} \text{Re}\{\text{Tr}[(\hat{\mathbf{v}} \cdot \mathbf{E}) \mathcal{A}_v \boldsymbol{\sigma}_\zeta \mathcal{A}_v]\} \delta(\epsilon_{\mathbf{k},v} - \epsilon_F), \quad (34)$$

$$\mathbf{S}^{\text{Inter}} = \frac{e\hbar}{V} \sum_{v \neq v', \mathbf{k}} \text{Im}\{\text{Tr}[(\hat{\mathbf{v}} \cdot \mathbf{E}) \mathcal{A}_v \boldsymbol{\sigma}_\zeta \mathcal{A}_{v'}]\} \frac{(f_{\mathbf{k},v} - f_{\mathbf{k},v'})}{(\epsilon_{\mathbf{k},v} - \epsilon_{\mathbf{k},v'})^2}, \quad (35)$$

where $v = s,\eta$ for conciseness. We also set $\boldsymbol{\sigma}_\zeta = \boldsymbol{\sigma}(1 + \zeta \hat{\tau}_z)/2$, which defines the spin density operator on the spin sublattices A ($\zeta = +1$) and B ($\zeta = -1$). Since Eqs. (34) and (35) involve angular averaging over φ_k , it is convenient to evaluate the spin density in the limit $\theta \ll 1$ (i.e., $\hat{\mathbf{L}} \approx \mathbf{z}$). In this case, the energy dispersion becomes isotropic $\epsilon_{s,\eta} = \eta(\sqrt{\gamma_k^2 + J_{\text{sd}}^2} + s\alpha k)$.

As shown in Appendix C, by taking the small- α limit and replacing the discrete summation in Eqs. (34) and (35) with continuous integration ($\sum_{\mathbf{k}} \rightarrow V \int d^2\mathbf{k}/4\pi^2$), one obtains in the linear order in α

$$\mathbf{S}^{\text{Intra}} = \frac{m\alpha}{8\pi\hbar^2\Gamma} \left(1 + 2 \frac{J_{\text{sd}}^2}{\epsilon_F^2} \left[2 - \frac{\epsilon_0}{\sqrt{\epsilon_F^2 - J_{\text{sd}}^2}} \right] \right) (\mathbf{z} \times e\mathbf{E}), \quad (36)$$

$$\mathbf{S}^{\text{Inter}} = -\zeta \frac{m\alpha J_{\text{sd}}}{4\pi\hbar^2\epsilon_F^2} \left(1 - \frac{\epsilon_0}{\sqrt{\epsilon_F^2 - J_{\text{sd}}^2}} \right) [\hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E})], \quad (37)$$

where we defined $\epsilon_0 = ta_l^2 k_0^2$. These formulas hold for $\epsilon_F, J_{\text{sd}} \gg \alpha k_F \gg \Gamma$ (k_F is the Fermi wave vector). Note that to derive these formulas we have neglected the vertex corrections in order to obtain a tractable analytical result. Such corrections

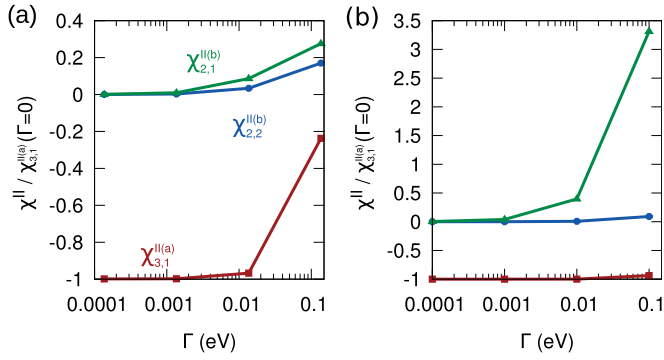


FIG. 3. Γ dependence of terms $\chi^{II(a)}$, $\chi^{II(b)}$ in the two models for magnetic moments oriented along the [110] direction. Components that are not shown are zero or related to those shown by symmetry. The results are scaled to make the comparison between the two tight-binding models easier. (a) Mn_2Au . (b) The 2D model.

will be considered in a future work. As predicted from symmetry considerations in the previous section, the intraband contribution produces an effective field along the vector $\mathbf{z} \times \mathbf{E}$, i.e., independently of the magnetic moments direction, while the (intrinsic) interband contribution results in a staggered effective field along the vector $\zeta \hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E})$ that depends on the direction of magnetic moments and has opposite sign on the two spin sublattices. These results are the AFM counterparts to the formulas obtained in the case of a FM 2D Rashba model [28] and demonstrate that the torque enabling efficient electrical manipulation of the AFM order arises in this model from the odd interband contribution to the CISP which has a finite value in the $\Gamma \rightarrow 0$ limit; i.e., it is intrinsic in nature.

B. Numerical calculations

In this section we show results of numerical calculations of the CISP in the two models described in Sec. II. The intraband term χ_a^I for Mn_2Au and the interband term $\chi_a^{II(a)}$ for the 2D model were already presented in Ref. [31]. Here we calculate also the interband term for Mn_2Au and the intraband term for the 2D model. We are primarily interested in the small- Γ limit. For zero Γ the interband term $\chi_a^{II(b)}$ vanishes. This is illustrated in Fig. 3. Figure 3(a) shows the terms $\chi_a^{II(a)}$ and $\chi_a^{II(b)}$ as a function of Γ for Mn_2Au for magnetic moments oriented along the [110] direction. Figure 3(b) shows the same calculation for the 2D model. In both cases as Γ goes to zero, the term $\chi_a^{II(b)}$ goes to zero, while the term $\chi_a^{II(a)}$ becomes constant. In the following we choose Γ so that the term $\chi_a^{II(b)}$ is small and the term $\chi_a^{II(a)}$ is close to its zero- Γ limit. We use $\Gamma \approx 0.0013$ eV in Mn_2Au and $\Gamma = 0.01$ eV in the 2D model.

As discussed in the symmetry analysis in Sec. III, the part of CISP that is even under time reversal is in the 2D model the same on the two AFM spin sublattices, while the odd part of the CISP is opposite. Conversely in Mn_2Au , the even CISP is opposite and the odd CISP is the same. This is a key result since it shows that in both models the effective current-induced field has a staggered component and can therefore switch the AFM moments efficiently. In the following, we focus on the dependence of the CISP on the direction of magnetic moments. Since in our model systems the CISP is always either exactly

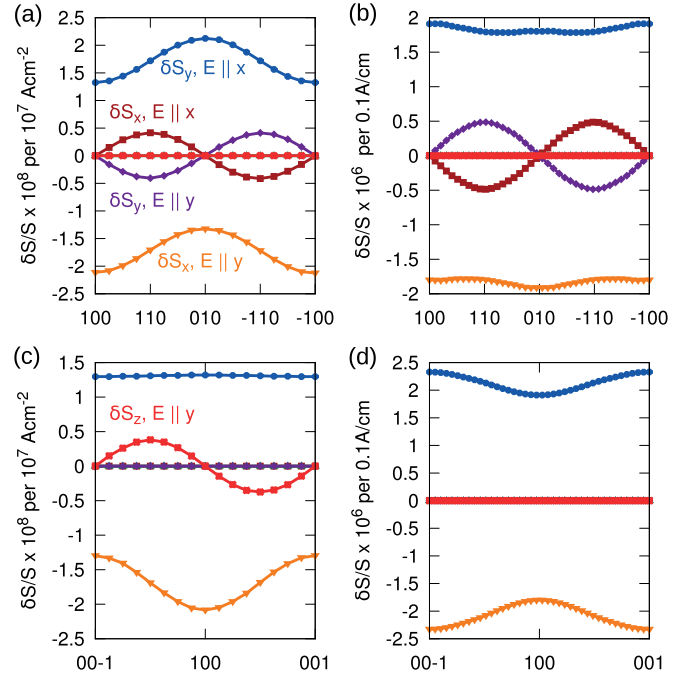


FIG. 4. Calculations of the intraband term χ_a^I . Only results for one sublattice are shown. Plots show the intraband CISP normalized by the equilibrium spin polarization per 10^7 A cm $^{-2}$ current density. (a) Mn_2Au and in-plane rotation of magnetic moments [31]. (b) 2D model, in-plane rotation. (c) Mn_2Au , out-of-plane rotation [31]. (d) 2D model, out-of-plane rotation.

the same or opposite on the two sublattices, we show results for one sublattice only.

We normalize all CISPs by current density calculated using the linear response theory formula analogous to (2). Since both the intraband term and the conductivity scale as $1/\Gamma$, the normalized intraband term is independent of Γ . For small Γ , the normalized term $\chi_a^{II(a)}$ scales as Γ . We also normalize the CISP by the ground-state spin polarization (on each sublattice). When this quantity is multiplied by J_{sd}/μ_B we get directly the effective field.

The results for the intraband term for one sublattice are shown in Fig. 4. For comparison we present the results for Mn_2Au and the 2D model side by side. Figures 4(a) and 4(c) show results for Mn_2Au , while Figs. 4(b) and 4(d) show the 2D model. In Figs. 4(a) and 4(b) the magnetic moments were rotated from the [100] direction to the $[-100]$ direction through the [010] direction (the moments lie in-plane). In Figs. 4(c) and 4(d) the magnetic moments were rotated from the [00-1] direction to the [001] direction through the [100] direction (the moments lie out-of-plane). Only results for current along the x and y directions are shown. For Mn_2Au , there can also be current along the z direction, but we found that the CISPs for such a current are at least 2 orders of magnitude smaller than for the in-plane current. Note that the CISP for current in the z direction is in general allowed by symmetry and only vanishes at certain high-symmetry directions of magnetic moments. On one sublattice, the two models give qualitatively similar results. In both cases the CISP is not strongly dependent on the direction of magnetic moments and the dominant component is always in-plane and perpendicular to the current.

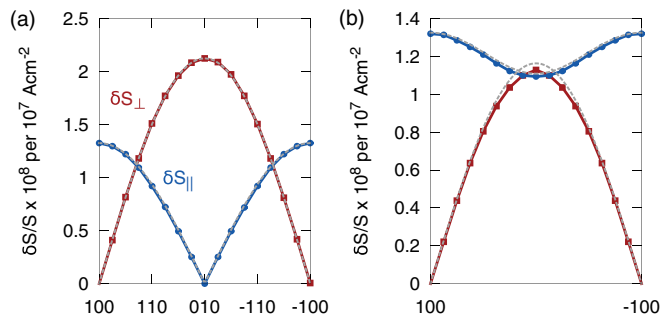


FIG. 5. Magnitude of perpendicular and longitudinal parts of the intraband CISP in Mn₂Au. Gray lines show perpendicular and longitudinal parts of the expression $\mathbf{z} \times \mathbf{E}$. (a) In-plane rotation of magnetic moments. (b) Nonsymmetrical rotation: magnetic moments rotate along a path given by $\hat{\mathbf{L}} = (\cos(\varphi), \sqrt{0.3} \sin(\varphi), \sqrt{0.7} \sin(\varphi))$.

The CISP and thus also the effective current-induced field are approximately aligned along the vector $\mathbf{z} \times \mathbf{E}$.

Since the torque is a cross product of the effective field and the magnetic moment, only the component of the effective field which is perpendicular to the magnetic moment is relevant. In our models the effective field is proportional to the CISP so the same holds for the CISP. When the perpendicular component of the intraband CISP for Mn₂Au is plotted, a peculiar feature is discovered. While the total CISP differs from the expression $\mathbf{z} \times \mathbf{E}$ significantly, the perpendicular part is very close to the perpendicular part of $\mathbf{z} \times \mathbf{E}$. This is already manifested in Fig. 4(c), where the longitudinal component of the CISP is zero due to symmetry for current along the x direction. To illustrate this feature we plot the magnitude of the perpendicular part of the intraband CISP for the in-plane rotation of the moments in Fig. 5(a). In gray, the perpendicular component of the expression $\mathbf{z} \times \mathbf{E}$ is plotted. All directions of magnetic moments discussed so far lay in high-symmetry planes. To confirm that this feature is not due to some particular symmetry but rather a general feature of the model, we also rotated the moments along a nonsymmetrical path. As shown in Fig. 5(b) this rotation shows the same behavior.

Interestingly, the same holds for the longitudinal part of the CISP; i.e., the longitudinal part of the CISP is very close to the longitudinal part of $\mathbf{z} \times \mathbf{E}$, which is also shown in Figs. 5(a) and 5(b). The proportionality constants are, however, different in the two cases, which is why the total intraband CISP vector deviates from $\mathbf{z} \times \mathbf{E}$. Since only the perpendicular part is relevant for the torque, the torque will be closely approximated by $\hat{\mathbf{M}}_a \times (\mathbf{z} \times \mathbf{E})$. This behavior only occurs in Mn₂Au. In the 2D model, the perpendicular component of CISP is not significantly closer to $\mathbf{z} \times \mathbf{E}$ than the total CISP.

In Fig. 6, we show results for the interband term $\chi_a^{II(a)}$ for one sublattice, organized similarly to the intraband results in Fig. 4. The Mn₂Au results are in Figs. 6(a) and 6(c) and the 2D model results in Figs. 6(b) and 6(d). In Figs. 6(a) and 6(b) the CISP is plotted as a function of magnetic moments rotating in-plane, while in Figs. 6(c) and 6(d), the magnetic moments are rotated out-of-plane. Again, the two models are qualitatively similar. In this case, however, the CISP depends strongly on the direction of magnetic moments. We only plot the non-negligible components of the CISP. In particular, the CISP

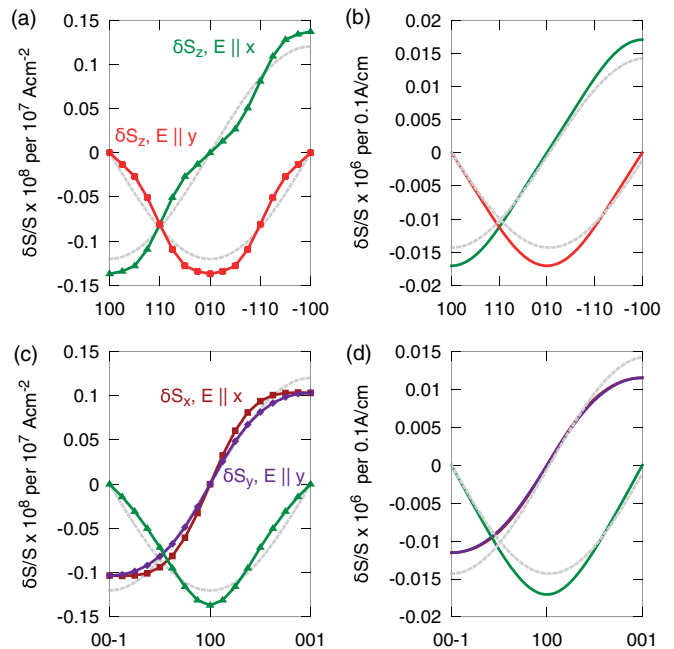


FIG. 6. Calculations of the interband term $\chi_a^{II(a)}$. Only results for one sublattice are shown. Plots show the interband CISP normalized by equilibrium spin polarization per 10^7 A cm⁻² current density. Gray lines show a fit to the expression $\hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E})$. (a) Mn₂Au and in-plane rotation of magnetic moments. (b) 2D model, in-plane rotation [31]. (c) Mn₂Au, out-of-plane rotation. (d) 2D model, out-of-plane rotation [31].

for the current along the z direction in Mn₂Au is again very small. In both models the CISP can be closely approximated by the lowest order term given by Eq. (26). As shown by gray lines, the main contribution is of the form $\hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E})$, which corresponds to the tensor X_1 . A deviation from this form is mainly due to the presence of the tensor X_2 . In Mn₂Au also higher order terms are present, but are less important than the lowest order terms. In Mn₂Au, the contribution from the tensor X_3 is also present, but we do not plot it since it is oriented approximately along the direction of magnetic moments and thus does not contribute to the torque.

In Fig. 7 we show how the CISP in the 2D model depends on the Fermi level. The dependence of the magnitude of the interband term on the Fermi level was already studied in Ref. [31]. Here we focus instead on how the dependence of the CISP on the direction of magnetic moments changes when the Fermi level is varied. When the Fermi level approaches the bottom of the bands, the intraband term becomes independent of the direction of magnetic moments and can be described by the vector $\mathbf{z} \times \mathbf{E}$ very accurately. This is illustrated in Fig. 7(a). This behavior is expected because when the Fermi level is close to the bottom of the bands, only small \mathbf{k} points matter for the calculations and as seen from Eq. (32) the energy dispersion becomes isotropic when \mathbf{k} is small. Results for the interband term $\chi_a^{II(a)}$ are shown in Fig. 7(b). For all Fermi level values, it can be described by Eq. (26), but the ratio C_1/C_2 depends strongly on the Fermi level. For the Fermi level close to the band gap (see Ref. [31] for the band structure), C_1 is much larger than C_2 . When the Fermi level approaches the bottom

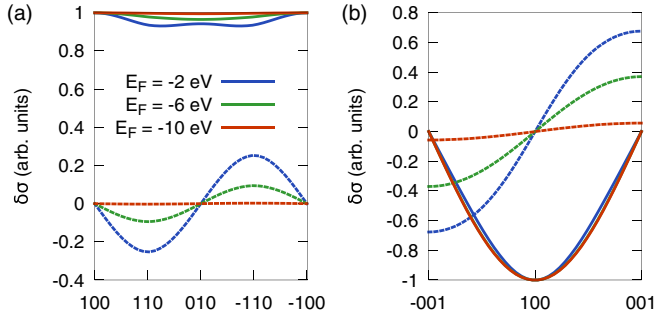


FIG. 7. The dependence of the CISP in the AFM 2D Rashba model on the direction of magnetic moments for different Fermi levels. We scale results to highlight the change in shape. Only results for current along the x direction are shown. $\Gamma = 0.0001$ eV was used in this calculation. (a) Intraband term, in-plane rotation, solid lines show the y component, dashed lines show the x component. (b) Interband term, out-of-plane rotation, solid lines show the z component, dashed lines show the x component.

of bands, C_2 becomes much larger than C_1 . The dependence of the CISP on the direction of magnetic moments is then no longer of the form $\hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E})$. Instead, for $C_1 \ll C_2$, it can be described by $(\hat{\mathbf{L}} \cdot \mathbf{E}_\perp)\mathbf{z}$. This is in agreement with the analytical calculations. Equation (37) describes the contribution from the tensor X_1 . When the Fermi level is at the bottom of bands the term given by Eq. (37) is zero. Equation (37) does not capture the contribution from tensor X_2 since tensor X_2 is zero for $\hat{\mathbf{L}} = \mathbf{z}$.

Finally, we compare results for our two models with AFM and FM order. Spin-orbit torques have been previously calculated in a FM 2D Rashba model analogous to our AFM 2D Rashba model [20,28,55]. Those calculations used models with a parabolic band dispersion, which in our model corresponds to the Fermi level close to the bottom (top) of bands. As shown in Fig. 7(a), for our model the intraband CISP then becomes proportional to $\mathbf{z} \times \mathbf{E}$. This is a form that the FM has when $J_{sd} \gg \alpha$ [28]. We find that the AFM has this form regardless of J_{sd}/α (when the Fermi level is close to bottom of the bands). In all calculations discussed so far $\alpha \ll J_{sd}$. For such a case, the FM has the intraband term of the form $\mathbf{M} \times [(\mathbf{z} \times \mathbf{E}) \times \mathbf{M}]$. This results in the same torque as the $\mathbf{z} \times \mathbf{E}$ term since $\mathbf{M} \times [(\mathbf{z} \times \mathbf{E}) \times \mathbf{M}]$ is precisely the component of $\mathbf{z} \times \mathbf{E}$ perpendicular to \mathbf{M} . The FM interband term $\chi_a^{II(a)}$ differs from the AFM case as well. For $\alpha \ll J_{sd}$ in the FM it has the form $\mathbf{M} \times (\mathbf{z} \times \mathbf{E})$, while for the AFM the dependence is $(\hat{\mathbf{L}} \cdot \mathbf{E}_\perp)\mathbf{z}$, as shown in Fig. 7(b). This is a form the FM has when $J_{sd} \gg \alpha$.

The AFM model thus has many similarities with the FM model; however, the dependence on the parameters of the model is different. In particular, in the FM the results depend significantly on the ratio J_{sd}/α , while in the AFM this ratio does not play a large role. This is because, in the FM, the spin-up and spin-down bands are split by both the Rashba spin-orbit coupling and by the exchange interaction. In the AFM on the other hand, only the Rashba spin-orbit coupling splits the spin-up and spin-down bands.

For comparison we also calculated the CISP in hypothetical FM Mn_2Au . The model differs from AFM Mn_2Au only in

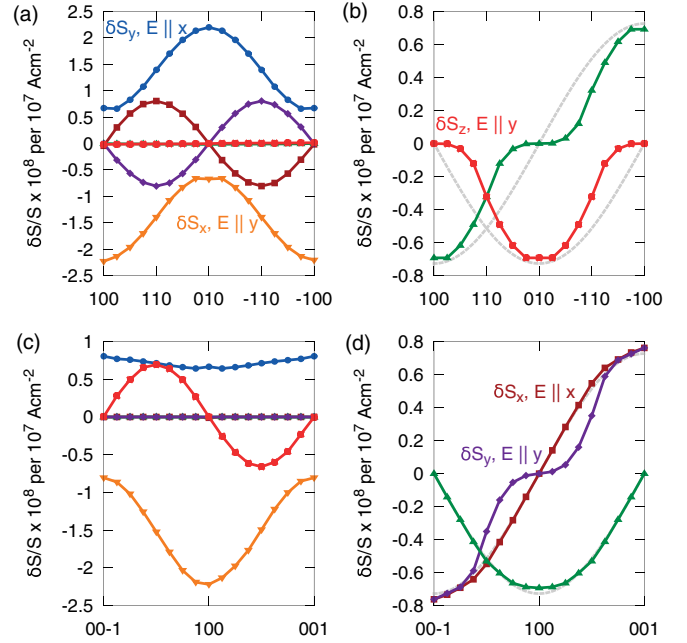


FIG. 8. Calculations of the CISP in FM Mn_2Au for one inversion-partner sublattice. (a) Intraband term, in-plane rotation of moments. (b) Interband term $\chi_a^{II(a)}$, in-plane rotation of moments. (c) Intraband term, out-of-plane rotation of moments. (d) Interband term $\chi_a^{II(a)}$, out-of-plane rotation of moments.

the direction of the moments; all other parameters are the same. Both intraband and interband CISPs in FM Mn_2Au have opposite sign on the two inversion-partner lattice sites occupied by Mn, as expected from symmetry considerations and confirmed in our microscopic calculations. The intraband CISP in the FM is very close to the AFM case both in terms of the magnitude and the dependence on the direction of magnetic moments, as shown in Figs. 8(a) and 8(c). The interband term is shown in Figs. 8(b) and 8(d). It has a similar dependence on the direction of magnetic moments; however, it is an order of magnitude larger than in the AFM Mn_2Au .

V. DISCUSSION

The AFM 2D Rashba and 3D Mn_2Au models differ in one key aspect. In the 2D model, the odd CISP is staggered and the even CISP is uniform, while in Mn_2Au the even CISP is staggered and the odd CISP is uniform. This is so because in the 2D model the AFM spin sublattices are connected by translation, while in Mn_2Au they are connected by inversion. However, as shown in Figs. 4 and 6, when we look at one sublattice only, the CISP in the two models has a similar dependence on the direction of magnetic moments and the direction of the current. This may seem surprising since the electronic structures of the two models are very different, including the way spin-orbit coupling enters the band-structure calculations.

The reason for the similarity is the same symmetry of the magnetic sites in the two models. As discussed in Sec. III, it is the site symmetry that determines the symmetry of the CISP on a sublattice. The symmetry group of the magnetic sites is the same in both models and in both models the results can be

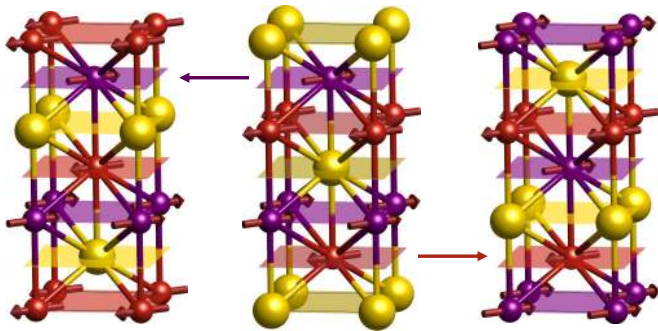


FIG. 9. Local inversion symmetry breaking in Mn_2Au . The middle picture shows the crystal structure of Mn_2Au with highlighted atomic layers. Left and right pictures show inversion around Mn A and Mn B atoms [as defined in Fig. 1(b)], respectively.

quite accurately described by lowest orders in expansion (20). Since the site symmetry is the same, the expansions are also the same in the two models.

The local inversion symmetry breaking in Mn_2Au is illustrated in Fig. 9. Mn_2Au is a layered crystal; under inversion around one of the Mn atoms, the layers remain the same, but the order of the layers changes. Because of this, each sublattice has the inversion symmetry locally broken and the inversion symmetry breaking is along the z axis. The inversion symmetry breaking thus resembles that of the 2D Rashba system.

Despite the above similarity in the local CISP symmetries of the two models, the dynamics of magnetic moments will be different. This is because only the staggered component of the CISP can generate an efficient torque on an AFM. In Mn_2Au , the staggered component of the CISP corresponds to the intraband term, which results in a fieldlike torque. The effect of such a torque is comparable to the effect of an external magnetic field in a FM. In particular, the magnitude of the staggered effective field necessary to switch the AFM moments will be determined by the magnetic anisotropy energy barrier just like in the case of a FM and a uniform external magnetic field. In the 2D model, since the sublattices are connected by translation, the staggered component of the CISP is odd in magnetic moments. Therefore it always depends strongly on the magnetic moments' direction and cannot be fieldlike. When the Fermi level is such that the CISP has the $\hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E})$ form, the corresponding torque acting on the AFM can be called, in analogy with FMs, (anti)damping-like. The critical value of the switching effective field will then depend both on the anisotropy barrier and on the damping factor [29].

These results demonstrate the importance of symmetry for understanding the spin-orbit torque. Symmetry determines which component of the effective field is staggered and thus also which component is efficient for manipulating the AFM order. Symmetry also governs the dependence of the effective field on the direction of the current and the magnetic moments. This is especially so because we find in our two models that the effective field can be very well described by the lowest order terms in the expansion (20). Although this conclusion does not have to be generally valid, it is consistent with previous studies on different systems [7,24,25,48].

We used the tight-binding models of the 3D Mn_2Au and 2D Rashba AFMs to illustrate the symmetries of CISPs and

the corresponding AFM spin-orbit torques. In the remaining paragraphs we discuss the strength of the spin-orbit torque in the Mn_2Au crystal. In Ref. [31], the magnitude of the effective field driving the spin-orbit torque in Mn_2Au was estimated from the tight-binding value of the CISP by estimating the exchange coupling strength between carrier and local moment spins to $J_{sd} = 1$ eV. The intraband field was found to be 0.22 mT per 10^7 A cm^{-2} for magnetic moments lying along the [100] direction. For comparison, we performed *ab initio* calculations based on the electronic structure obtained from the DFT. The method is described in detail in Ref. [37]. Here the spin-orbit torque is calculated directly using the exchange potential from the DFT. From the torque the effective magnetic field is then obtained using Eq. (7): $\mathbf{B}_a = (\mathbf{T}_a \times \hat{\mathbf{M}}_a)/M_a$. This way we only obtain the component of the effective field perpendicular to the magnetic moments. For magnetic moments along the [100] direction the longitudinal component of the effective field is zero. We found that the effective current-induced field in the *ab initio* spin-orbit torque calculation has a magnitude 1.98 mT per 10^7 A cm^{-2} [7].

The DFT value is by a factor of 8 larger than the tight-binding value. To find out where the discrepancy originates from, we also calculated the CISP directly using the DFT method. Then using Eq. (8) and the above DFT torque calculation we obtain a value of the effective exchange constant $J_{sd} = 1.2$ eV. This is similar to the estimated value of J_{sd} used in the tight-binding calculation of the effective current-induced field. The difference between tight-binding and DFT calculations is therefore primarily in the CISPs, which differ by a factor of ~ 6 . The remaining discrepancy between the tight-binding and DFT effective fields is due to different magnetic moments in the two approaches. These differ because the tight-binding Hamiltonian was fitted to a LDA+ U DFT calculation, while for the torque calculation a DFT calculation without U was used. Including the Hubbard U increases the moments by about 20%.

The DFT magnitude of the effective staggered field in Mn_2Au is comparable to that of the CuMnAs AFM where current-induced switching has been recently observed in experiment [7]. Highly conductive Mn_2Au is therefore a potentially favorable material for exploring and exploiting current-induced spin-orbit torques in AFMs.

VI. CONCLUSION

We have presented a symmetry analysis of spin-orbit torques in AFMs and FMs and discussed in detail results obtained in two complementary model systems with locally and globally broken inversion symmetry, respectively. We have pointed out that the existence and form of the spin-orbit torque on the given spin sublattice is determined by the sublattice symmetry. We have also shown that in AFMs, symmetry operations that connect the two spin sublattices determine the relation between the spin-orbit torques on the two sublattices. Our two models illustrate two main cases with the sublattices connected either by a translation or by an inversion. Consequently, in the AFM 2D Rashba model representing the former case, the efficient component of the torque has an antidamping character, while in AFM Mn_2Au

representing the latter case, the efficient spin-orbit torque has a fieldlike character.

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APPENDIX A: SYMMETRY OF SPIN-ORBIT TORQUE

We give here an overview of the symmetry of spin-orbit torque. Symmetry of transport coefficients in magnetic systems has been studied before, primarily in the context of electrical and heat conductivity [56–59], but also for the spin-orbit torque [50]. Here we expand the analysis to account for sublattice projections. We use the microscopic Eqs. (2), (3), (4) as a starting point. Our approach is similar to that of [57] where a more general version of the Kubo formula was used. The results do not depend on the exact form of the formulas: it is only important that the formulas describe linear response. Additionally, the results apply only assuming a single-electron (i.e., noninteracting) Hamiltonian.

As discussed in [59], there has been a considerable controversy surrounding the symmetry of tensors describing transport phenomena. The difficulty lies in understanding the effect of the time-reversal symmetry operation [59,60]. This is because transport phenomena are nonequilibrium processes that include dissipation. We define a time-reversal operator as $\mathcal{T} = i\sigma_y K$, where K is the complex conjugation. This is how the time-reversal operator is conventionally defined in quantum mechanics. Note that such defined time-reversal operator reverses direction of magnetic moments, but does not in general reverse direction of electrical currents (see the discussion in [60]).

Let R be a symmetry of the Hamiltonian, i.e.,

$$H = RHR^{-1}. \quad (\text{A1})$$

Symmetry operations that do not contain time reversal are represented by a unitary R . Symmetry operations that contain time reversal are represented by antiunitary R since K is an antiunitary operator. If $\psi_{n\mathbf{k}}$ is an eigenfunction of the Hamiltonian, then $R\psi_{n\mathbf{k}}$ is also an eigenfunction with the same

eigenvalue. Since the result cannot depend on the choice of eigenfunctions, we can use the transformed eigenfunctions to evaluate the CISP. The transformed eigenfunction correspond to a different \mathbf{k} point, but the sums will always run over all \mathbf{k} points. The only part of the microscopic equations that depends on the eigenfunctions are the matrix elements; the rest depend only on the eigenvalues. Transformation of the matrix elements depends on whether R is a unitary operator or an antiunitary operator. For unitary R and an observable \hat{A}

$$\langle R(\psi_{n\mathbf{k}}) | \hat{A} | R(\psi_{m\mathbf{k}}) \rangle = \langle \psi_{n\mathbf{k}} | R^{-1} \hat{A} R | \psi_{m\mathbf{k}} \rangle, \quad (\text{A2})$$

while for antiunitary R

$$\langle R(\psi_{n\mathbf{k}}) | \hat{A} | R(\psi_{m\mathbf{k}}) \rangle = \langle \psi_{n\mathbf{k}} | R^{-1} \hat{A} R | \psi_{m\mathbf{k}} \rangle^*. \quad (\text{A3})$$

We represent the transformation of operators $\hat{\mathbf{S}}$ and $\hat{\mathbf{v}}$ by 3×3 matrices D^s, D^v :

$$R^{-1} \hat{S}_{a',i} R = D_{ik}^s \hat{S}_{a,k}, \quad (\text{A4})$$

$$R^{-1} \hat{v}_j R = D_{jl}^v \hat{v}_l, \quad (\text{A5})$$

where a' is the sublattice in which a transforms under R . Note that the matrix D^s does not depend on a . For unitary R we find for the transformation of χ_a

$$\chi_{a',ij} = D_{ik}^s D_{jl}^v \chi_{a,kl}. \quad (\text{A6})$$

For antiunitary R , the various terms of (1) will transform differently depending on whether they contain a real or imaginary part of the matrix elements. To group together the terms that transform in the same way, we separate the spin polarization into parts even and odd under time reversal. Since time reversal switches the direction of all moments, this is equivalent to

$$\chi_a^{\text{even}}(\mathbf{[M]}) = [\chi_a(\mathbf{[M]}) + \chi_a(-\mathbf{[M]})]/2, \quad (\text{A7})$$

$$\chi_a^{\text{odd}}(\mathbf{[M]}) = [\chi_a(\mathbf{[M]}) - \chi_a(-\mathbf{[M]})]/2, \quad (\text{A8})$$

where $\mathbf{[M]} = [\mathbf{M}_A, \mathbf{M}_B, \dots]$ denotes the directions of all magnetic moments in the unit cell. Since both $\hat{\mathbf{S}}$ and $\hat{\mathbf{v}}$ anticommute with time reversal and since $\chi_a^I, \chi_a^{II(b)}$ contain the real part of the matrix elements, while $\chi_a^{II(a)}$ contains the imaginary part of the matrix elements,

$$\chi_a^{\text{even}} = \chi_a^I + \chi_a^{II(b)}, \quad (\text{A9})$$

$$\chi_a^{\text{odd}} = \chi_a^{II(a)}. \quad (\text{A10})$$

We find for the transformation of each part under antiunitary R

$$\chi_{a',ij}^{\text{even}} = D_{ik}^s D_{jl}^v \chi_{a,kl}^{\text{even}}, \quad (\text{A11})$$

$$\chi_{a',ij}^{\text{odd}} = -D_{ik}^s D_{jl}^v \chi_{a,kl}^{\text{odd}}. \quad (\text{A12})$$

We now show how to express the matrices D^s, D^v . Let D be a 3×3 matrix that represents how a point transforms under R :

$$\mathbf{x}_R = D\mathbf{x} + \mathbf{s}. \quad (\text{A13})$$

The shift \mathbf{s} is due to translations. It is irrelevant for matrices D^s, D^v , but the translations cannot be ignored altogether because they influence which sublattice a transforms to. Note

that the time-reversal symmetry operation does not influence the matrix D either since it only affects the magnetic moments. Thus D represents the nonmagnetic point group.

For unitary R

$$D^s = \det(D)D, \quad D^v = D, \quad (\text{A14})$$

and for antiunitary R

$$D^s = -\det(D)D, \quad D^v = -D. \quad (\text{A15})$$

This is because $\hat{\mathbf{v}}$ is a polar vector, while $\hat{\mathbf{S}}$ is an axial vector and both change sign under time reversal. Then Eq. (A6) can be rewritten as

$$\chi_{a'} = \det(D)D\chi_a D^T \quad (\text{A16})$$

and analogously for antiunitary R ,

$$\chi_{a'}^{\text{even}} = \det(D)D\chi_a^{\text{even}}D^T, \quad (\text{A17})$$

$$\chi_{a'}^{\text{odd}} = -\det(D)D\chi_a^{\text{odd}}D^T. \quad (\text{A18})$$

Equations (A16), (A17), (A18) together determine the transformation properties of the tensor χ_a . They hold, however, only in a Cartesian coordinate system. This is because the formulas (2), (3), (4) hold only in a Cartesian system. In any coordinate system, for example, the CISP corresponding to the term χ_a^I can be written as

$$\delta\mathbf{S}_a = -\frac{e\hbar}{2\Gamma} \sum_{\mathbf{k}, n} \langle \psi_{n\mathbf{k}} | \hat{\mathbf{S}}_a | \psi_{n\mathbf{k}} \rangle \langle \psi_{n\mathbf{k}} | \hat{\mathbf{v}} \cdot \mathbf{E} | \psi_{n\mathbf{k}} \rangle \delta(\varepsilon_{\mathbf{k}n} - E_F). \quad (\text{A19})$$

The terms corresponding to $\chi_a^{II(a)}, \chi_a^{II(b)}$ can be expressed analogously. In a non-Cartesian coordinate system, tensor χ_a would not satisfy $\delta\mathbf{S}_a = \chi_a \mathbf{E}$ since in a non-Cartesian coordinate system $\hat{\mathbf{v}} \cdot \mathbf{E} \neq \hat{v}_i E_i$. While it is natural to express the tensors χ in Cartesian coordinate systems, the symmetry operations are usually expressed in the conventional coordinate systems, which for the case of monoclinic, hexagonal, and trigonal groups are not Cartesian. For completeness we provide here a generalization to non-Cartesian systems. This can be derived by using a microscopic expression for χ_a valid in non-Cartesian systems, but a simpler way is to transform the linear response tensor from a non-Cartesian system to Cartesian.

Let T be a coordinate transformation matrix, i.e., a matrix such that $x' = Tx$, where x are coordinates in a Cartesian system and x' are coordinates in a different, in general non-Cartesian, coordinate system. Then $\chi_a = T^{-1}\chi'_a T$. We first consider a unitary symmetry operation R . Using Eq. (A16), which holds in the Cartesian system,

$$T^{-1}\chi'_a T = \det(D)DT^{-1}\chi'_a T D^T, \quad (\text{A20})$$

$$\chi'_a = \det(D)T D T^{-1}\chi'_a T D^T T^{-1}. \quad (\text{A21})$$

In a Cartesian system, D has to be orthogonal, so $D^T = D^{-1}$. Since $D' = T D T^{-1}$ and $\det(D') = \det(D)$, we find

$$\chi'_{a'} = \det(D')D'\chi'_a D'^{-1}. \quad (\text{A22})$$

Analogously, we find for antiunitary R

$$\chi_{a'}^{\text{even}} = \det(D')D'\chi_a^{\text{even}}D'^{-1}, \quad (\text{A23})$$

$$\chi_{a'}^{\text{odd}} = -\det(D')D'\chi_a^{\text{odd}}D'^{-1}. \quad (\text{A24})$$

These formulas determine how χ transforms in any coordinate system. This result is quite general and holds for any linear response formula. One just has to replace the matrices D^s, D^v by matrices that describe transformation of the corresponding operators.

The results for Cartesian coordinate systems are the same as in Ref. [57], except that we separate the tensor into the even and odd parts. Such separation is also commonly done for other tensors describing transport phenomena [56,59]. It is quite natural since the even and the odd parts have different properties. For example, they have a different dependence on disorder and cause very different magnetic dynamics.

To find out symmetry properties of the expansion terms in (20) we have to consider the symmetry operations of the nonmagnetic crystal, since these are symmetry operations that connect different magnetic configurations of a given crystal. If R is such symmetry operation then $H([\mathbf{M}]_R) = RH([\mathbf{M}])R^{-1}$, where $[\mathbf{M}]_R$ denotes directions of all magnetic moments transformed by R . By using a procedure very similar to that for deriving Eq. (A22), we can show that

$$\chi_{a'}([\mathbf{M}]_R) = \det(D)D\chi_a([\mathbf{M}])D^{-1}. \quad (\text{A25})$$

Since the nonmagnetic symmetry operations do not contain time reversal we do not have to separate χ_a into the even and odd parts. Considering that Eq. (A25) has to hold for each expansion term in (20) we find

$$\chi_{a,ij,mn\dots}^{(i)} = \det(D)^{i-1} D_{ik} D_{jl}^{-T} D_{mo}^{-T} D_{np}^{-T} \dots \chi_{a,kl,op\dots}^{(i)}, \quad (\text{A26})$$

where D^{-T} denotes the inverse of a transpose of matrix D . We consider here only the symmetry operations that keep the sublattice invariant. The symmetry operations that connect the two sublattices do not give any more information about the form of $\chi_a^{(i)}$. The form of the expansion (20) is thus given by the nonmagnetic local point group.

In FMs Eq. (A26) applies also for the expansion of the net CISP, if the global point group is used instead. In AFMs, the net tensor χ transforms in general differently. This is because a symmetry operation that transforms one sublattice into the other can reverse the sign of the Néel vector and this is not taken into account in Eq. (A26). For example in Mn_2Au , inversion is a symmetry of the nonmagnetic crystal. As a consequence, the net CISP in the FM Mn_2Au vanishes as correctly predicted by Eq. (A26) applied for the net CISP. In AFM Mn_2Au , there is, however, a net CISP, yet Eq. (A26) is the same as for the FM. It is straightforward to derive the analog of Eq. (A26) for the net CISP in AFMs; however, in AFMs the net CISP is not a very useful quantity. In AFMs with more than two sublattices, spin-axis direction is not enough to describe the magnetic state of the AFM. Then the expansion (20) should be performed in more parameters than just $\hat{\mathbf{n}}$. However, if we assume that all the other parameters are fixed during dynamics then expansion (20) can still be used and Eq. (A26) applies.

APPENDIX B: THE CODE FOR ANALYZING THE SYMMETRY

We provide a code that can analyze the symmetry of spin-orbit torque in a given crystal structure automatically [49]. It can find the symmetry-restricted form of a tensor χ_a and also of the expansion (20). Here, we give a brief overview of the code. The code is written in Python and uses the symbolic library Sympy [61]. It uses as an input a list of symmetry operations for the given crystal structure, generated by the program Findsymb [62]. From these symmetry operations we first choose the ones which form the local point group, i.e., the symmetry operations that leave the selected sublattice invariant. For each such symmetry operation we then construct a system of linear equations (13), (14) [resp. (A26) for the expansions] that have to hold for components of the tensor. We solve this system of equations by transforming it to the reduced row echelon form. The code can also find relations between tensors χ_a projected on different sublattices and between tensors χ_a for different equivalent magnetic configurations.

APPENDIX C: ANALYTICAL DERIVATION OF SPIN-ORBIT TORQUES

In this section, we present the details of the derivation of the computation of Eqs. (36) and (37). As mentioned in Sec. IV A, we need to calculate the expressions

$$\mathbf{S}^{\text{Intra}} = \frac{e\hbar}{2\Gamma V} \sum_{v, \mathbf{k}} \text{Re}\{\text{Tr}[(\hat{\mathbf{v}} \cdot \mathbf{E})\mathcal{A}_v \sigma_\zeta \mathcal{A}_v]\} \delta(\epsilon_{\mathbf{k},v} - \epsilon_F), \quad (\text{C1})$$

$$\mathbf{S}^{\text{Inter}} = \frac{e\hbar}{V} \sum_{v \neq v', \mathbf{k}} \text{Im}\{\text{Tr}[(\hat{\mathbf{v}} \cdot \mathbf{E})\mathcal{A}_v \sigma_\zeta \mathcal{A}_{v'}]\} \frac{(f_{\mathbf{k},v} - f_{\mathbf{k},v'})}{(\epsilon_{\mathbf{k},v} - \epsilon_{\mathbf{k},v'})^2}. \quad (\text{C2})$$

Since evaluating the transport properties involves an angular averaging over φ_k , it is convenient to rewrite the projection operator in the form $\mathcal{A}_{s,\eta} = \mathcal{A}_{s,\eta}^e + \mathcal{A}_{s,\eta}^o$, where the first term is even in \mathbf{k} , while the second term is odd in \mathbf{k} . Furthermore, from now on we will only focus on the limit case of $\theta \ll 1$ (i.e., $\hat{\mathbf{L}} \approx \mathbf{z}$) in order to get rid of the angular dependence of the Fermi surface contained in ζ_k , Eq. (33). This way, the energy dispersion reduces to $\epsilon_{s,\eta} = \eta(\sqrt{\gamma_k^2 + J_{\text{sd}}^2} + s\alpha k)$ and we find explicitly

$$\mathcal{A}_{s,\eta}^e = (1/4)[1 + \eta \cos \theta_k \hat{t}_x + \eta \sin \theta_k (\hat{\sigma} \cdot \hat{\mathbf{L}}) \hat{t}_z], \quad (\text{C3})$$

$$\mathcal{A}_{s,\eta}^o = (s/4) \hat{\sigma} \cdot [\cos \theta_k \boldsymbol{\mu} - \sin \theta_k \hat{t}_y (\hat{\mathbf{L}} \times \boldsymbol{\mu}) + \eta \boldsymbol{\mu} \hat{t}_x], \quad (\text{C4})$$

where we defined $\cos \theta_k = \gamma_k / \sqrt{\gamma_k^2 + J_{\text{sd}}^2}$ and $\sin \theta_k = J_{\text{sd}} / \sqrt{\gamma_k^2 + J_{\text{sd}}^2}$. Using the definitions of Eqs. (C1) and (C2) we notice that the heart of the physics is contained in the trace

$$\text{Tr}[(\hat{\mathbf{v}} \cdot \mathbf{E})\mathcal{A}_v \hat{\sigma}_\zeta \mathcal{A}_{v'}] = \langle v | \hat{\sigma}_\zeta | v' \rangle \langle v' | (\hat{\mathbf{v}} \cdot \mathbf{E}) | v \rangle. \quad (\text{C5})$$

The velocity operator $\hat{\mathbf{v}} \cdot \mathbf{E} = \partial_{\mathbf{k}} \hat{H} \cdot \mathbf{E} / \hbar$ reads

$$\hbar \hat{\mathbf{v}} \cdot \mathbf{E} = [2ta_l^2 \mathbf{k} \cdot \mathbf{E} + \alpha(\mathbf{z} \times \mathbf{E}) \cdot \hat{\sigma}] \hat{t}_x. \quad (\text{C6})$$

The trace Eq. (C5) has then two contributions that do not vanish upon φ_k integration,

$$\text{Tr}_d^{v,v'} = \frac{2ta_l^2}{\hbar} (\mathbf{k} \cdot \mathbf{E}) \text{Tr}[\hat{t}_x (\mathcal{A}_v^o \hat{\sigma}_\zeta \mathcal{A}_{v'}^e + \mathcal{A}_v^e \hat{\sigma}_\zeta \mathcal{A}_{v'}^o)], \quad (\text{C7})$$

$$\text{Tr}_a^{v,v'} = \frac{\alpha}{\hbar} \text{Tr}[(\mathbf{z} \times \mathbf{E}) \cdot \hat{\sigma} \hat{t}_x (\mathcal{A}_v^o \hat{\sigma}_\zeta \mathcal{A}_{v'}^o + \mathcal{A}_v^e \hat{\sigma}_\zeta \mathcal{A}_{v'}^e)]. \quad (\text{C8})$$

After some algebra, we obtain the following expression for the real and imaginary parts of the trace defined in Eq. (C5),

$$\text{ReTr}^{s,\eta} = \frac{\eta}{2\hbar} [2sta_l^2 \cos \theta_k + \alpha/k] \cos \theta_k (\mathbf{k} \cdot \mathbf{E}) \boldsymbol{\mu}, \quad (\text{C9})$$

$$\text{ImTr}^{s,\eta} = -s\zeta \frac{ta_l^2}{\hbar} \sin \theta_k (\mathbf{k} \cdot \mathbf{E}) (\hat{\mathbf{L}} \times \boldsymbol{\mu}) \delta_{s'+s}, \delta_{\eta'+\eta}, \quad (\text{C10})$$

where Eq. (C9) involves only intraband transitions ($s, \eta = s', \eta'$), while Eq. (C10) involves only interband transitions ($-s, -\eta = s', \eta'$). We can now proceed with the φ_k integration. Since the energy $\epsilon_{\mathbf{k},s,\eta}$ is isotropic (independent of φ_k), Eqs. (C9) and (C10) can be further simplified by performing the angular integration

$$\int d\varphi_k \text{ReTr}^{s,\eta} = \frac{\eta\pi}{2\hbar} [2sta_l^2 k \cos \theta_k + \alpha] \cos \theta_k (\mathbf{z} \times \mathbf{E}), \quad (\text{C11})$$

$$\int d\varphi_k \text{ImTr}^{s,\eta} = -s\pi\zeta \frac{ta_l^2 k}{\hbar} \sin \theta_k [\hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E})] \delta_{s'+s}, \delta_{\eta'+\eta}. \quad (\text{C12})$$

Using Eqs. (C1) and (C2) and noticing that $\delta(\epsilon_{\mathbf{k},s,\eta} - \epsilon_F) = |2t_N a_l^2 k \cos \theta_k + s\alpha|^{-1} \delta_{k-k_F^s}$ (where k_F^s is the solution of $\epsilon_{\mathbf{k},s,\eta} = \epsilon_F$), we obtain

$$\mathbf{S}^{\text{Intra}} = \frac{\mathbf{z} \times e\mathbf{E}}{16\pi\Gamma} \int dk k \cos \theta_k (\delta_{k-k_F^+} - \delta_{k-k_F^-}), \quad (\text{C13})$$

$$\mathbf{S}^{\text{Inter}} = -\zeta \frac{J_{\text{sd}} t a_l^2}{8\pi} [\hat{\mathbf{L}} \times (\mathbf{z} \times e\mathbf{E})] \int_{k_F^-}^{k_F^+} \frac{k^2 dk}{(\gamma_k^2 + J_{\text{sd}}^2)^{3/2}}. \quad (\text{C14})$$

We consider the Fermi energy close to the top of the upper bands, so that the lower bands remain fully occupied $f_{\mathbf{k},s,-} = 1$. Furthermore, we recognize that to the linear order in α

$$k_F^s \approx k_F^0 + \alpha k_F^\alpha + O(\alpha^2) \quad (\text{C15})$$

$$= \frac{1}{\sqrt{ta_l^2}} \sqrt{4t - \sqrt{\epsilon_F^2 - J_{\text{sd}}^2}} + s \frac{\alpha}{2ta_l^2} \frac{\epsilon_F}{\sqrt{\epsilon_F^2 - J_{\text{sd}}^2}}. \quad (\text{C16})$$

Then, the integral in Eq. (C14) can be rewritten

$$\int_{k_F^-}^{k_F^+} \frac{k^2 dk}{(\gamma_k^2 + J_{\text{sd}}^2)^{3/2}} \approx 2\alpha k_F^\alpha \frac{k_F^{02}}{(\gamma_{k_F^0}^2 + J_{\text{sd}}^2)^{3/2}}. \quad (\text{C17})$$

Finally, we find that the current-driven spin densities read

$$\mathbf{S}^{\text{Intra}} = \frac{m\alpha}{8\pi\hbar^2\Gamma} \left(1 + 2 \frac{J_{\text{sd}}^2}{\epsilon_{\text{F}}^2} \left[2 - \frac{\epsilon_0}{\sqrt{\epsilon_{\text{F}}^2 - J_{\text{sd}}^2}} \right] \right) \mathbf{z} \times \mathbf{eE}, \quad (\text{C18})$$

$$\mathbf{S}^{\text{Inter}} = -\zeta \frac{m\alpha J_{\text{sd}}}{4\pi\hbar^2\epsilon_{\text{F}}^2} \left(1 - \frac{\epsilon_0}{\sqrt{\epsilon_{\text{F}}^2 - J_{\text{sd}}^2}} \right) \hat{\mathbf{L}} \times (\mathbf{z} \times \mathbf{E}), \quad (\text{C19})$$

where we defined $\epsilon_0 = ta_l^2 k_0^2$.

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