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# SPL: A Language and Compiler for DSP Algorithms

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# Overview

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- SPL: A domain specific language
  - DSP core algorithms
  - Matrix factorization
- SPL Compiler:
  - SPL  $\Rightarrow$  Fortran/C programs
  - Efficient implementation
- Part of SPIRAL([www.ece.cmu.edu/~spiral](http://www.ece.cmu.edu/~spiral)):
  - Adaptive framework for optimizing DSP libraries
  - Search over different SPL formulas using SPL compiler.



# Outline

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- Motivation
- Mathematical formulation of DSP algorithms
- SPL Language
- SPL Compiler
- Performance Evaluation
- Conclusion



# Motivation

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- What affects the performance?
  - Architecture features:
    - pipeline, FU, cache, ...
  - Compiler:
    - Ability to take advantage of architecture features
    - Ability to handle large / complicated programs
- Ideal compiler
  - Perform perfect optimization based on the architecture
  - Practical compilers have limitations

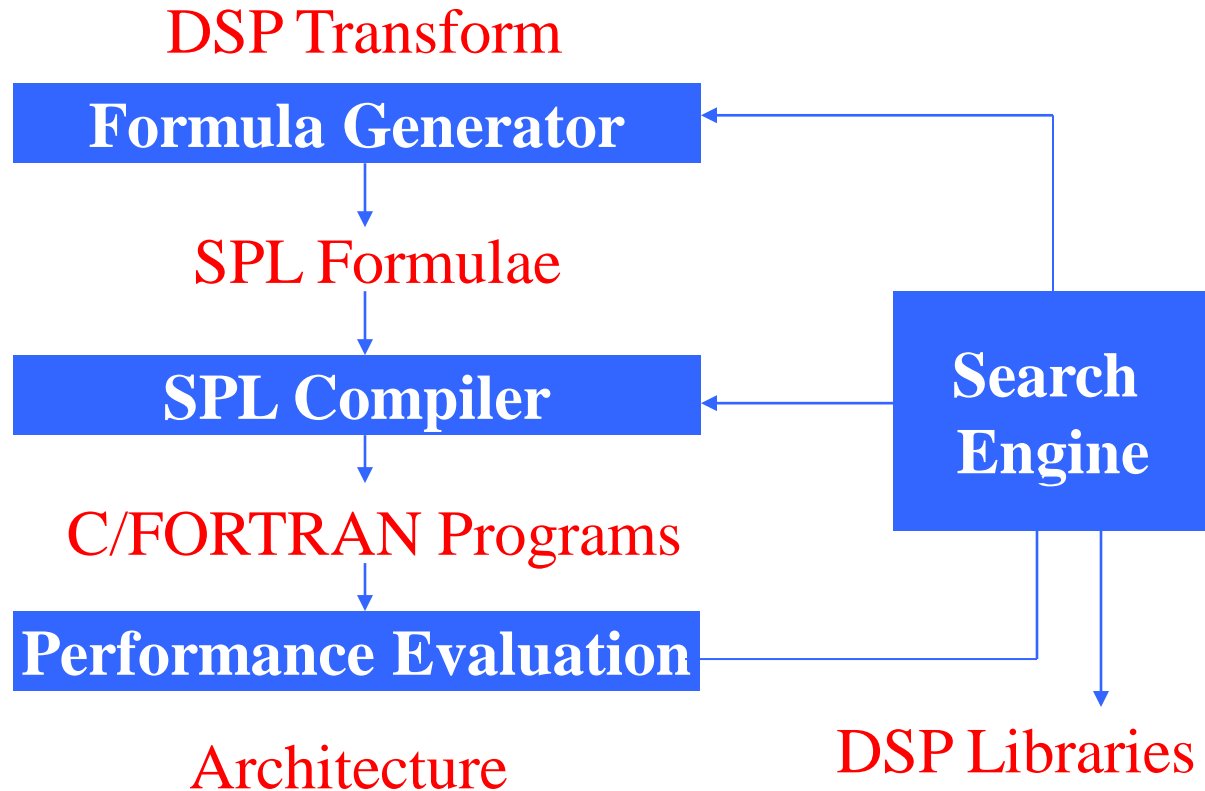


## Motivation (continue)

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- Manual Performance Tuning
  - Modify the source based on profiling information
  - Requires knowledge about the architecture features
  - Requires considerable work
  - The performance is not portable
- Automatic performance tuning?
  - Very difficult for general programs
  - DSP core algorithms: SPIRAL.

# SPIRAL Framework



# Fast DSP Algorithms as Matrix Factorizations

- A DSP Transform:
  - $y = Mx \Rightarrow y = M_1 M_2 \dots M_k x$
- Example: n-point DFT  $y = F_n x$

$$F_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & i & -1 & -i \\ 1 & -1 & 1 & -1 \\ 1 & -i & -1 & i \end{bmatrix}$$

$$F_4 = (F_2 \otimes I_2) T_2^4 (I_2 \otimes F_2) L_2^4$$

$$= \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & i \end{bmatrix} \begin{bmatrix} 1 & 1 & & \\ & 1 & -1 & \\ & & 1 & 1 \\ & & & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

# Tensor Product

- A linear algebra operation for representing repetitive matrix structures

$$A_{m \times n} \otimes B_{m' \times n'} = \begin{bmatrix} a_{11}B & \cdots & a_{1n}B \\ \vdots & \ddots & \vdots \\ a_{m1}B & \cdots & a_{mn}B \end{bmatrix}_{mm' \times nn'}$$

- Loop

$$I \otimes B = \begin{bmatrix} B & & \\ & \ddots & \\ & & B \end{bmatrix}$$





# Tensor Product (continue)

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- Vector operations

$$A \otimes I = \begin{bmatrix} \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} & \dots & \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \\ \vdots & \ddots & \vdots \\ \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} & \dots & \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \end{bmatrix}$$



# Rules for Recursive Factorization

- Cooley-Tukey factorization for DFT

$$F_{rs} = (F_r \otimes I_s) T_s^{rs} (I_r \otimes F_s) L_r^{rs}$$

- General K-way factorization for DFT

$$F_n = \prod_{i=1}^k \left[ (I_{n_{i-}} \otimes F_{n_i} \otimes I_{n_{i+}}) (I_{n_{i-}} \otimes T_{n_{i+}}^{n_i n_{i+}}) \right] \cdot \prod_{i=k}^1 (I_{n_{i-}} \otimes L_{n_i}^{n_i n_{i+}})$$

where  $n = n_1 \dots n_k$ ,  $n_{i-} = n_1 \dots n_{i-1}$ ,  $n_{i+} = n_{i+1} \dots n_k$



# Formulas

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- Variations of DFT(8)

$$\mathbf{F}_8 = (\mathbf{F}_2 \otimes \mathbf{I}_4) \mathbf{T}_4^8 (\mathbf{I}_2 \otimes \mathbf{F}_2) \mathbf{L}_2^8$$

$$\mathbf{F}_8 = (\mathbf{F}_2 \otimes \mathbf{I}_4) \mathbf{T}_4^8 (\mathbf{I}_2 \otimes ((\mathbf{F}_2 \otimes \mathbf{I}_2) \mathbf{T}_2^4 (\mathbf{I}_2 \otimes \mathbf{F}_2) \mathbf{L}_2^4)) \mathbf{L}_2^8$$

$$\mathbf{F}_8 = (\mathbf{F}_2 \otimes \mathbf{I}_4) \mathbf{T}_4^8 (\mathbf{I}_2 \otimes \mathbf{F}_2 \otimes \mathbf{I}_2) (\mathbf{I}_2 \otimes \mathbf{T}_2^4) (\mathbf{I}_4 \otimes \mathbf{F}_2) \mathbf{R}_8$$



# The SPL Language

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- Domain-specific programming language for describing matrix factorizations

$$\mathbf{F}_4 = (\mathbf{F}_2 \otimes \mathbf{I}_2) \mathbf{T}_2^4 (\mathbf{I}_2 \otimes \mathbf{F}_2) \mathbf{L}_2^4$$

( **compose**

( **tensor** ( **F** 2 ) ( **I** 2 ) )

( **T** 4 2 )

( **tensor** ( **I** 2 ) ( **F** 2 ) )

( **L** 4 2 )

matrix operations

primitives: parameterized special matrices



# SPL In A Nut-shell

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- SPL expressions
  - General matrices
    - `(matrix (a11...a1n) ... (am1 ... amn))`
    - `(diagonal (a11...ann))`
    - `(sparse (i1 j1 a1) ... (ik jk ak))`
  - Parameterized special matrices
    - `(I n)`, `(L mn n)`, `(T mn n)`, `(F n)`
  - Matrix operations
    - `(compose A1 ... Ak )`
    - `(tensor A1 ... Ak )`
    - `(direct_sum A1 ... Ak )`
- Others: definitions, directives, template, comments

$$A \oplus B = \text{diag}(A, B)$$



# A Simple SPL Program

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Definition

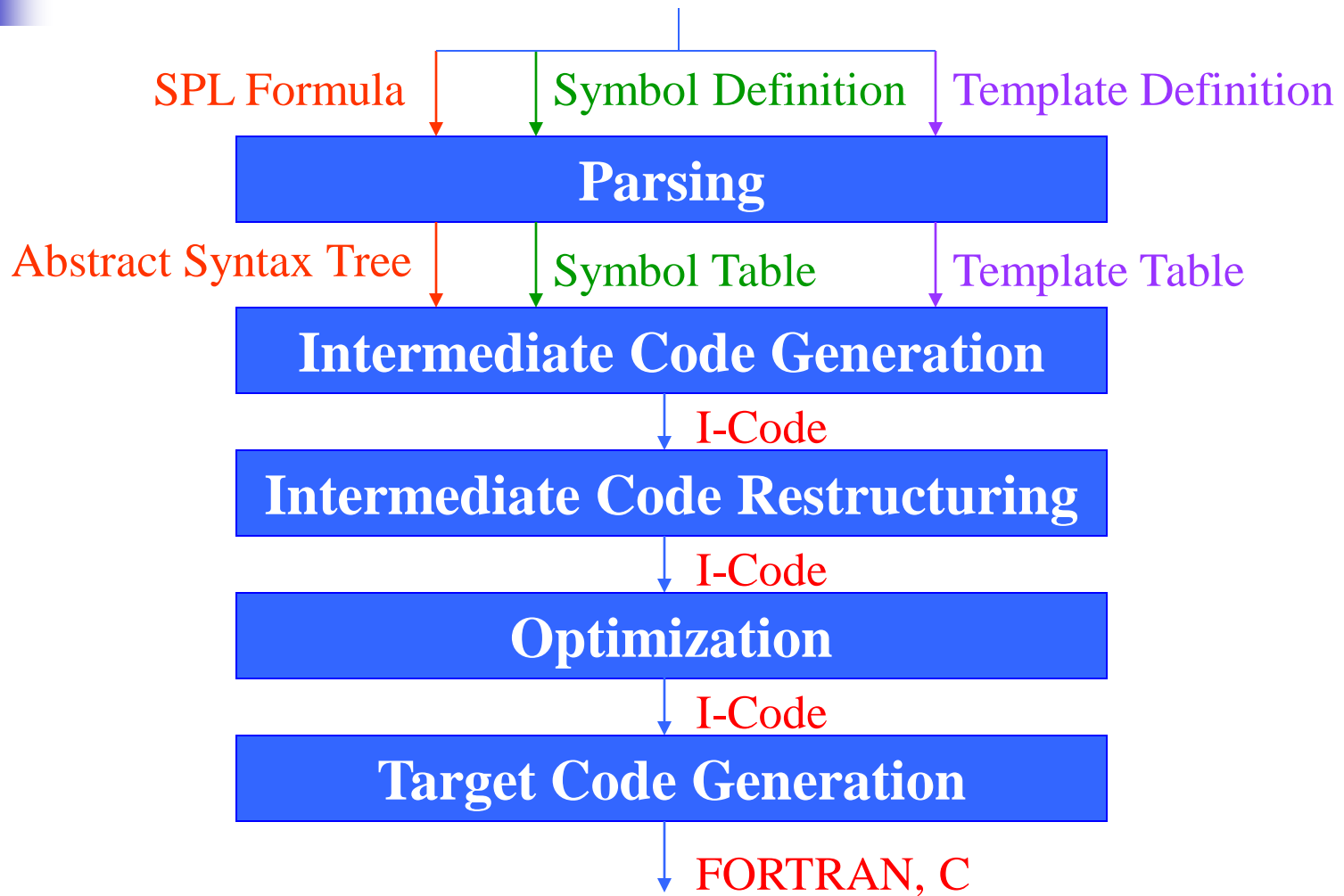
Formula

Directive

Comment

```
; This is a simple SPL program  
(define A (matrix(1 2)(2 1)))  
(define B (diagonal(3 3)))  
#subname simple  
(tensor (I 2)(compose A B))  
;; This is an invisible comment
```

# The SPL Compiler





# Template Based Intermediate Code Generation

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- Why use template?
  - User-defined semantics
  - Language extension
  - Compiler extension without modifying the compiler
  - Be integrated into the search space
- Structure of a template
  - Pattern, condition, code
- Template match
  - Generate I-code from matching template
  - Template matching is a recursive procedure





# I-Code

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- I-code is the intermediate code of the SPL compiler
- Internally I-code is four-tuples
  - $\langle \text{op}, \text{src1}, \text{src2}, \text{dest} \rangle$
- The external representation of I-code
  - Fortran-like
  - Used in template



# Template

---

```
( template
  (F n) [ n >= 1 ]
  (do i=0,n-1
    y(i)=0
    do j=0,n-1
      y(i)=y(i)+W(n,i*j)*x(j)
    end
  end ))
```

Pattern

Condition

I-code

# Code Generation and Template Matching

(**F** 2) matches pattern (**F** n) and assigns 2 to n.

Because  $n=2$  satisfies the condition  $n \geq 1$ , the following i-code is generated from the template:

```
do i = 0,1
  y(i) = 0
  do j = 0,1
    y(i) = y(i)+W(2,i*j)*x(j)
  end
end
end
```

```
Y(0)=x(0)+x(1)
y(1)=x(0)-x(1)
```

Unrolling & Optimization

# Define A Primitive

```
(primitive J)
(template
  (J n)
  [ n >= 1 ]
  ( do i=0,n-1
      y(i) = x(n-1-i)
    end ))
```

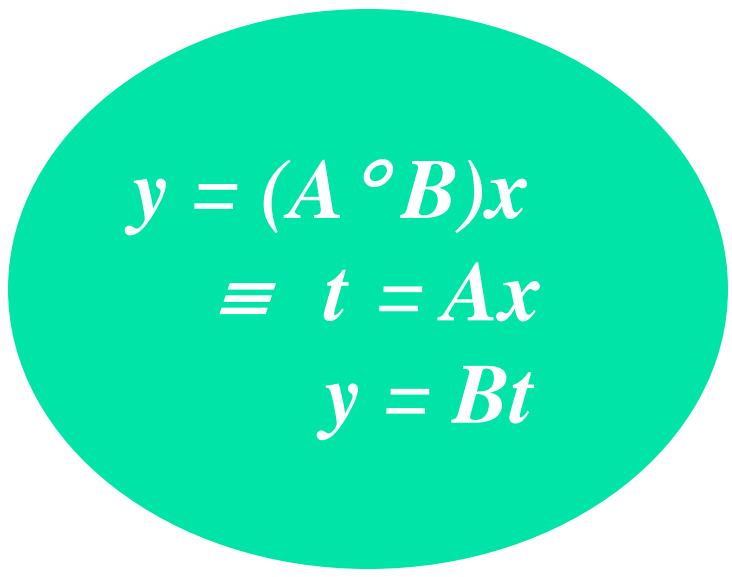
$$J_n = \begin{bmatrix} & & & & 1 \\ & & & & \\ & & \ddots & & \\ & & & \ddots & \\ 1 & & & & \end{bmatrix}_{n \times n}$$



# Define An Operation

---

```
(operation rcompose)
(template
  (rcompose A B)
  [ B.nx == A.ny ]
  ( t = A(x)
    y = B(t) ))
```


$$\begin{aligned}y &= (A \circ B)x \\ &\equiv t = Ax \\ & \quad y = Bt\end{aligned}$$

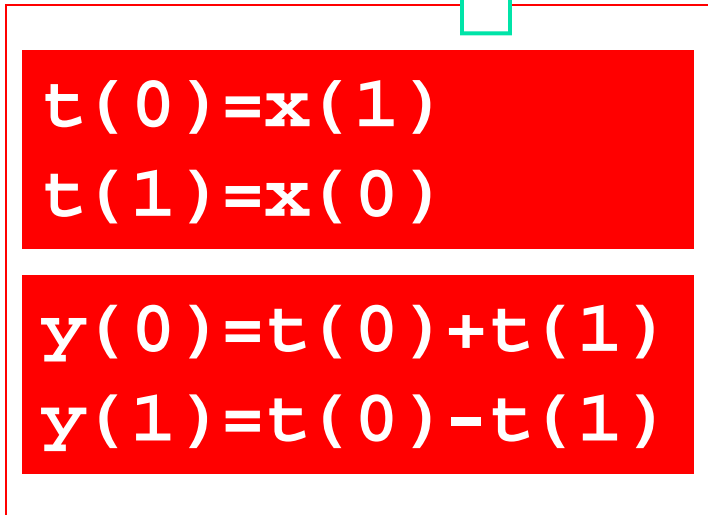
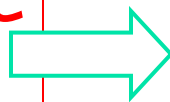
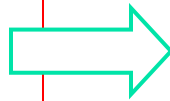
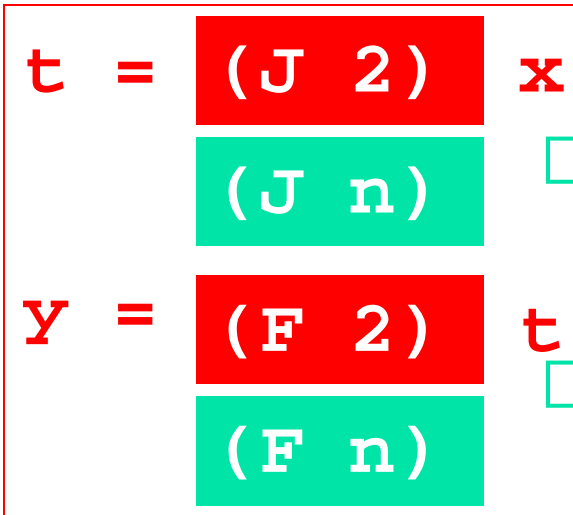
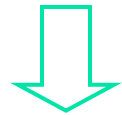
# Compound Template Matching

`(rcompose (J 2)(F 2))`

`(rcompose A B)`

$y(0) = x(1) + x(0)$

$y(1) = x(1) - x(0)$





# Intermediate Code Restructuring

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- Loop unrolling
  - Degree of unrolling can be controlled globally or case by case
- Scalar function evaluation
  - Replace scalar functions with constant value or array access
- Type conversion
  - Type of input data: real or complex
  - Type of arithmetic: real or complex
  - Same SPL formula, different C/Fortran programs



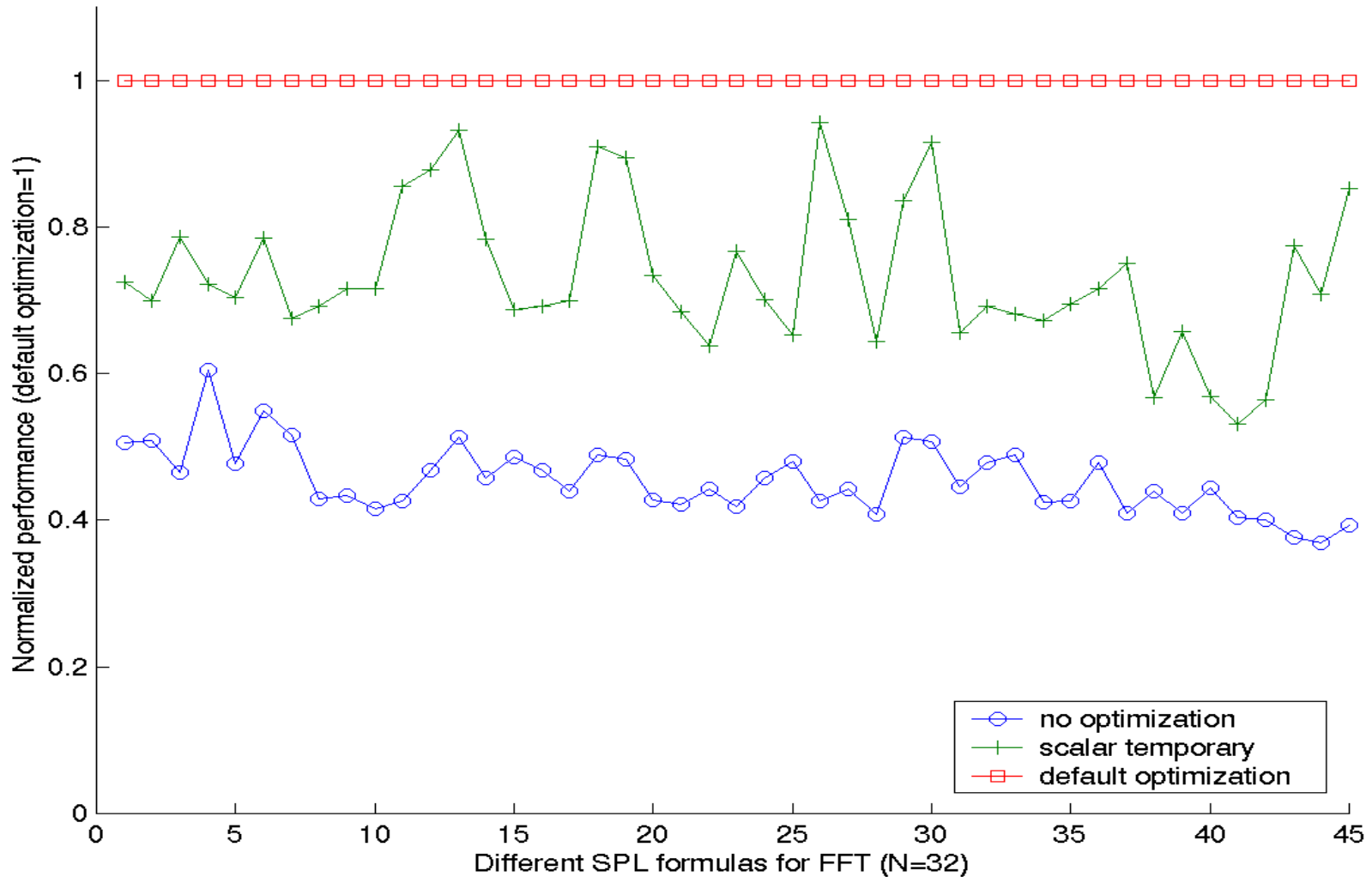
# Optimizations

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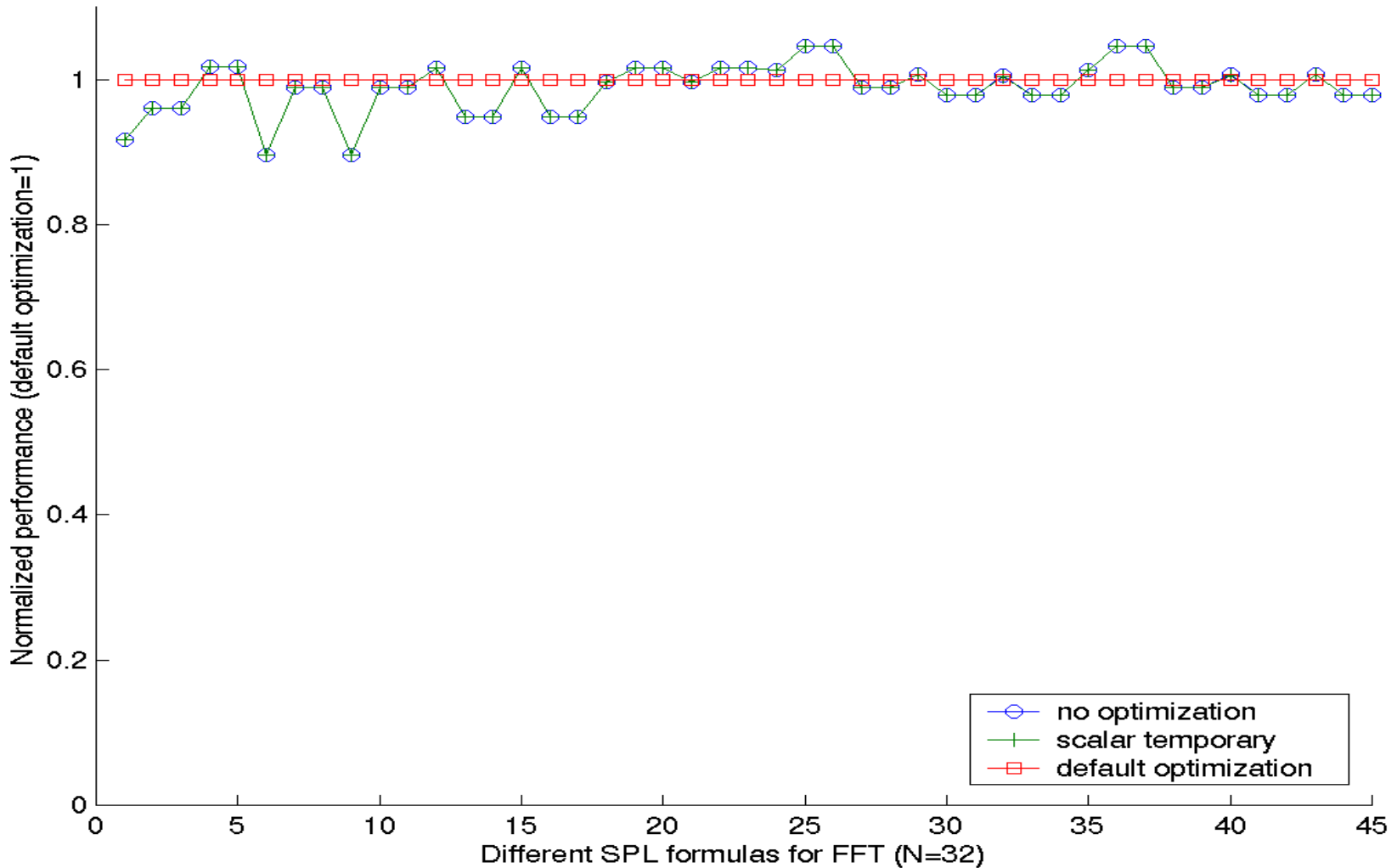
- Low-level optimizations:
  - Instruction scheduling, register allocation, instruction selection, ...
  - Leave them to the native compiler
- Basic high-level optimizations:
  - Constant folding, copy propagation, CSE, dead code elimination,...
  - The native compiler is supposed to do the dirty work, but not enough.
- High-level scheduling, loop transformations:
  - Formula transformation
  - Integrated into the search space



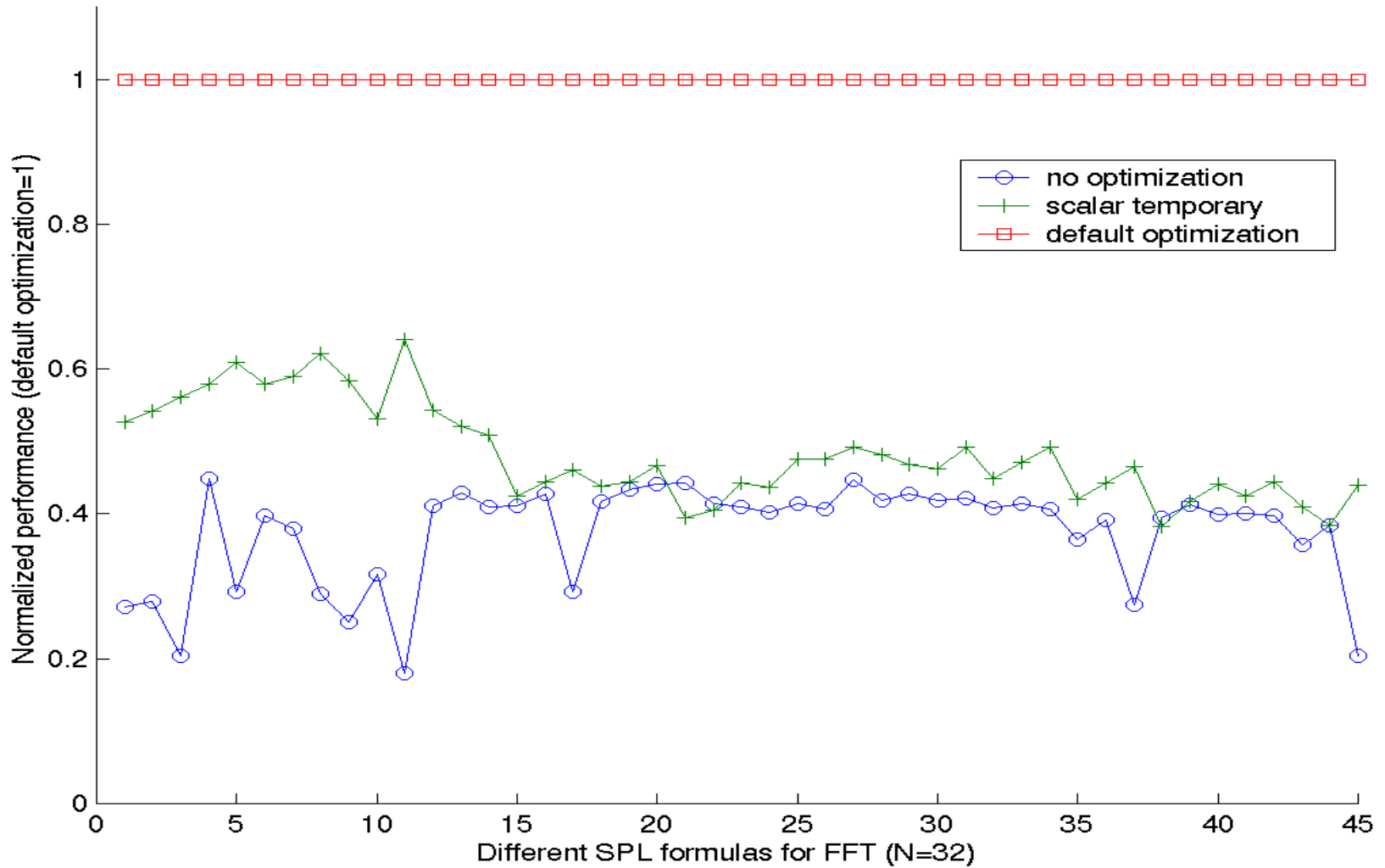
# Basic Optimizations(FFT, $N=2^5$ ,Ultra5)



# Basic Optimizations(FFT, $N=2^5$ , Origin200)



# Basic Optimizations(FFT,N=2<sup>5</sup>,PC)





# Performance Evaluation

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- Platforms: Ultra5, Origin 200, PC
- Small-size FFT ( $2^1$  to  $2^6$ )
  - Straight-line code
  - K-way factorization
  - Dynamic programming
- Large-size FFT ( $2^7$  to  $2^{20}$ )
  - Loop code
  - Binary right-most factorization
  - Dynamic programming
- Accuracy, memory requirement

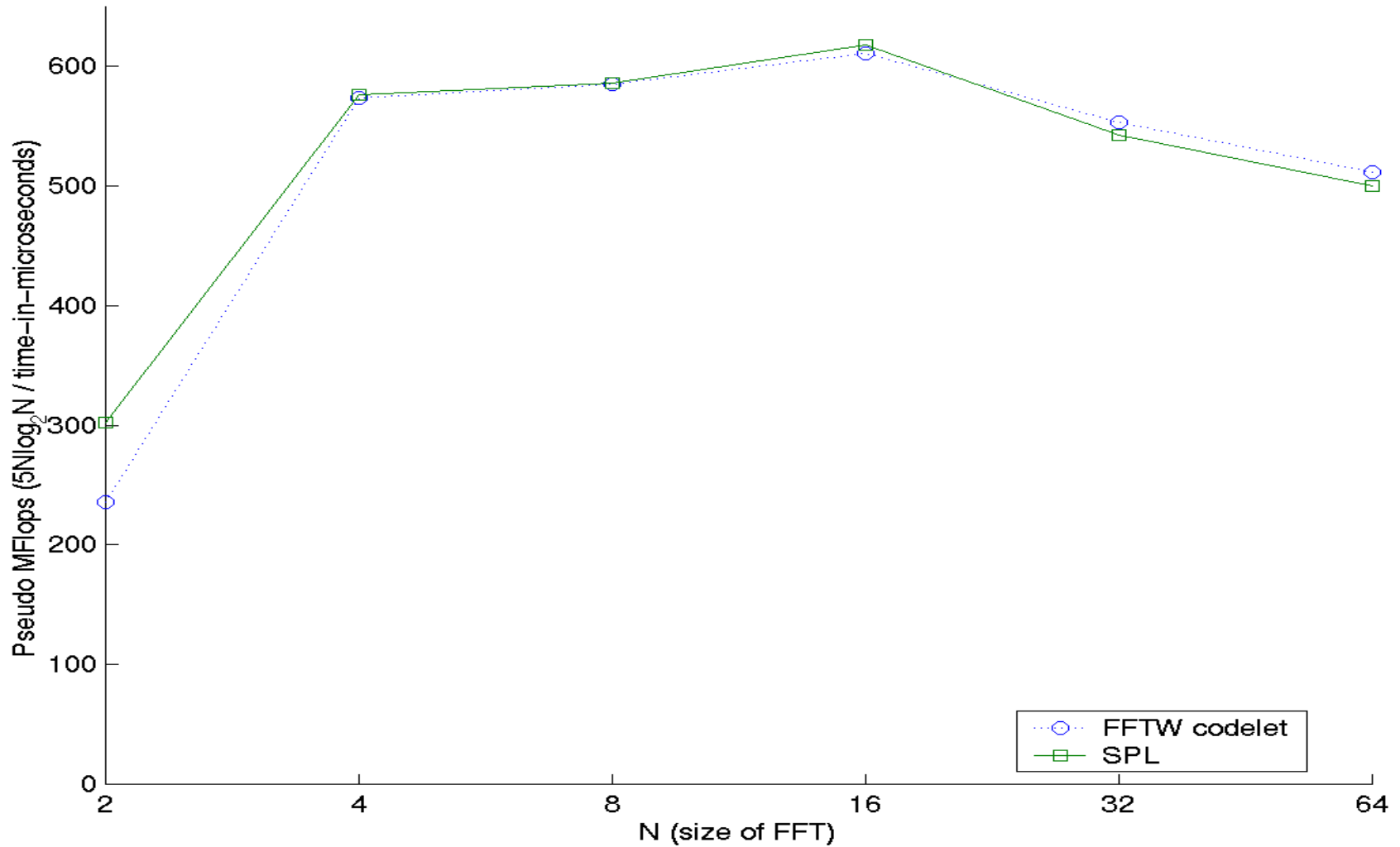


# FFTW

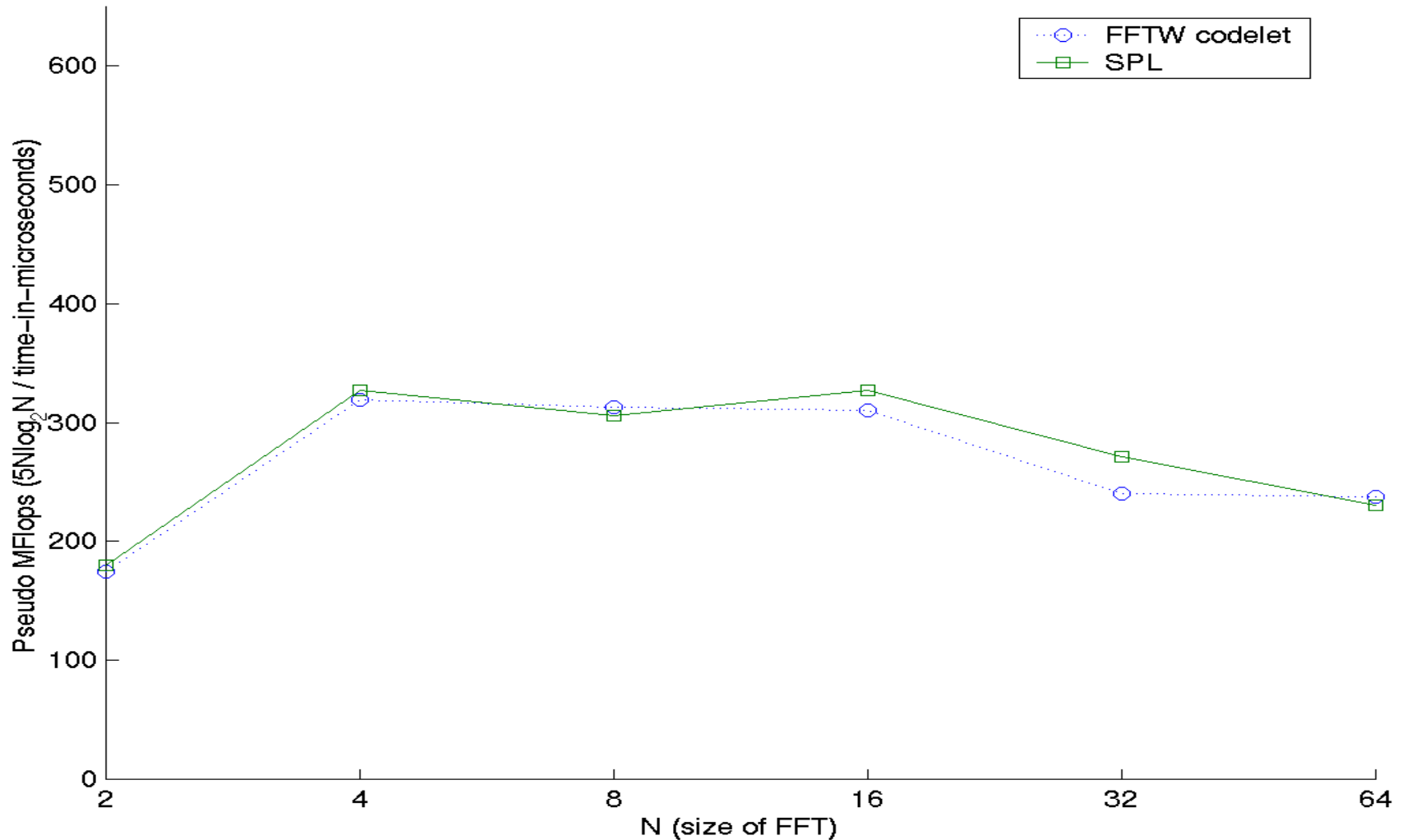
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- A FFT package
  - Codelet: optimized straight-line code for small-size FFTs
  - Plan: factorization tree
  - Use dynamic programming to find the plan
  - Make recursive function calls to the codelet according to the plan
- Measure and estimate

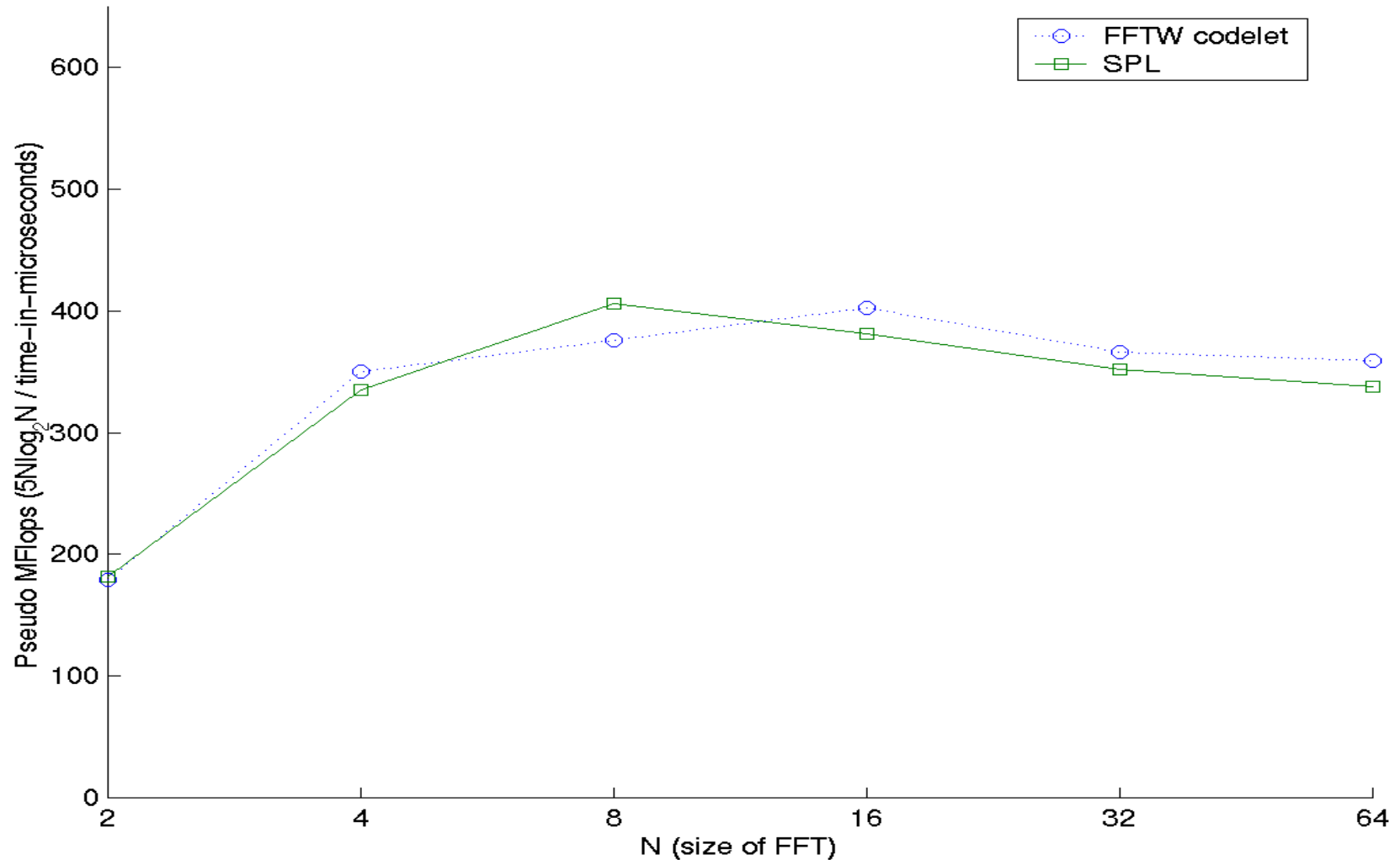
# FFT Performance (N=2<sup>1</sup> to 2<sup>6</sup>, Ultra5)



# FFT Performance (N=2<sup>1</sup> to 2<sup>6</sup>, Origin200)

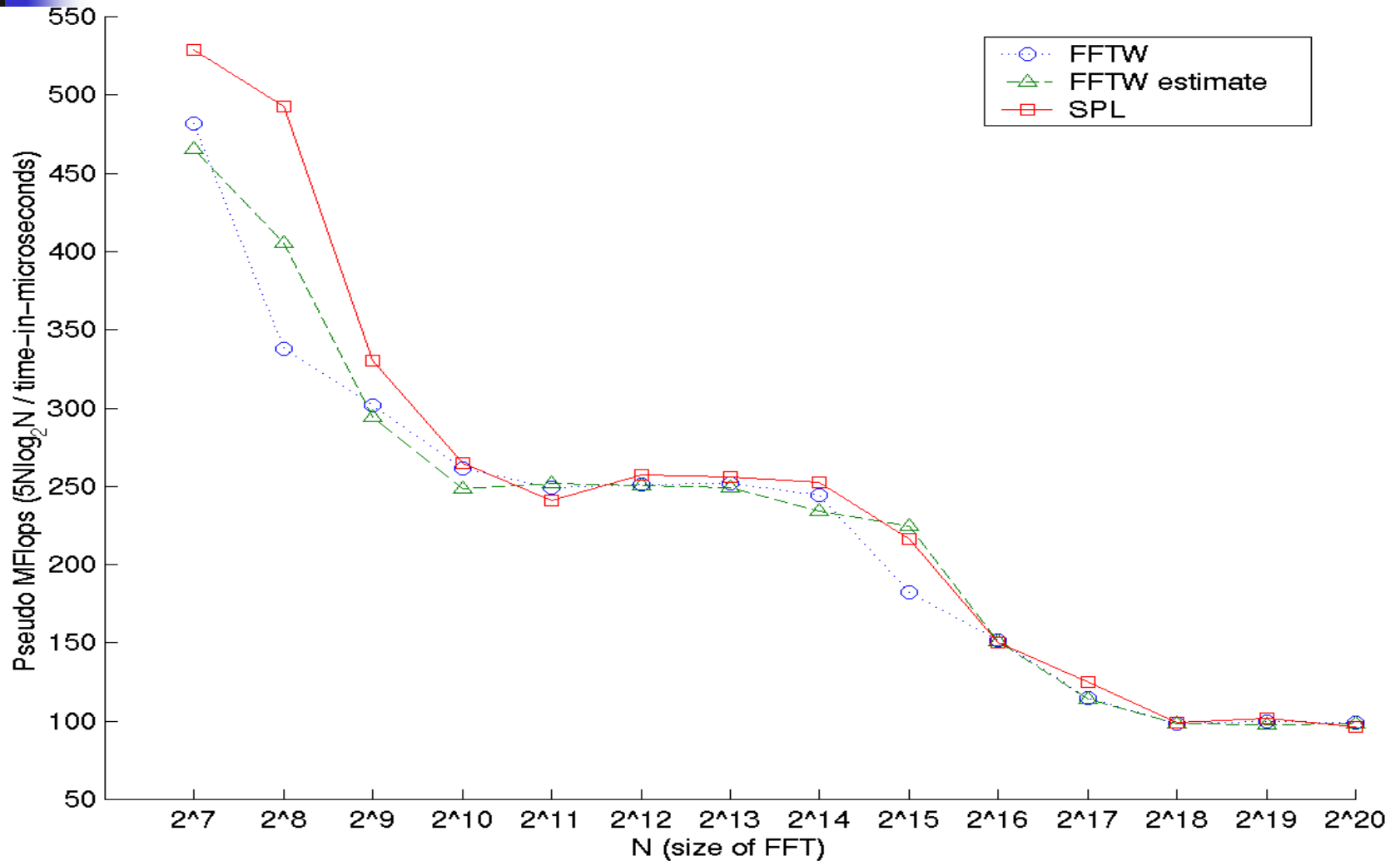


# FFT Performance (N=2<sup>1</sup> to 2<sup>6</sup>, PC)

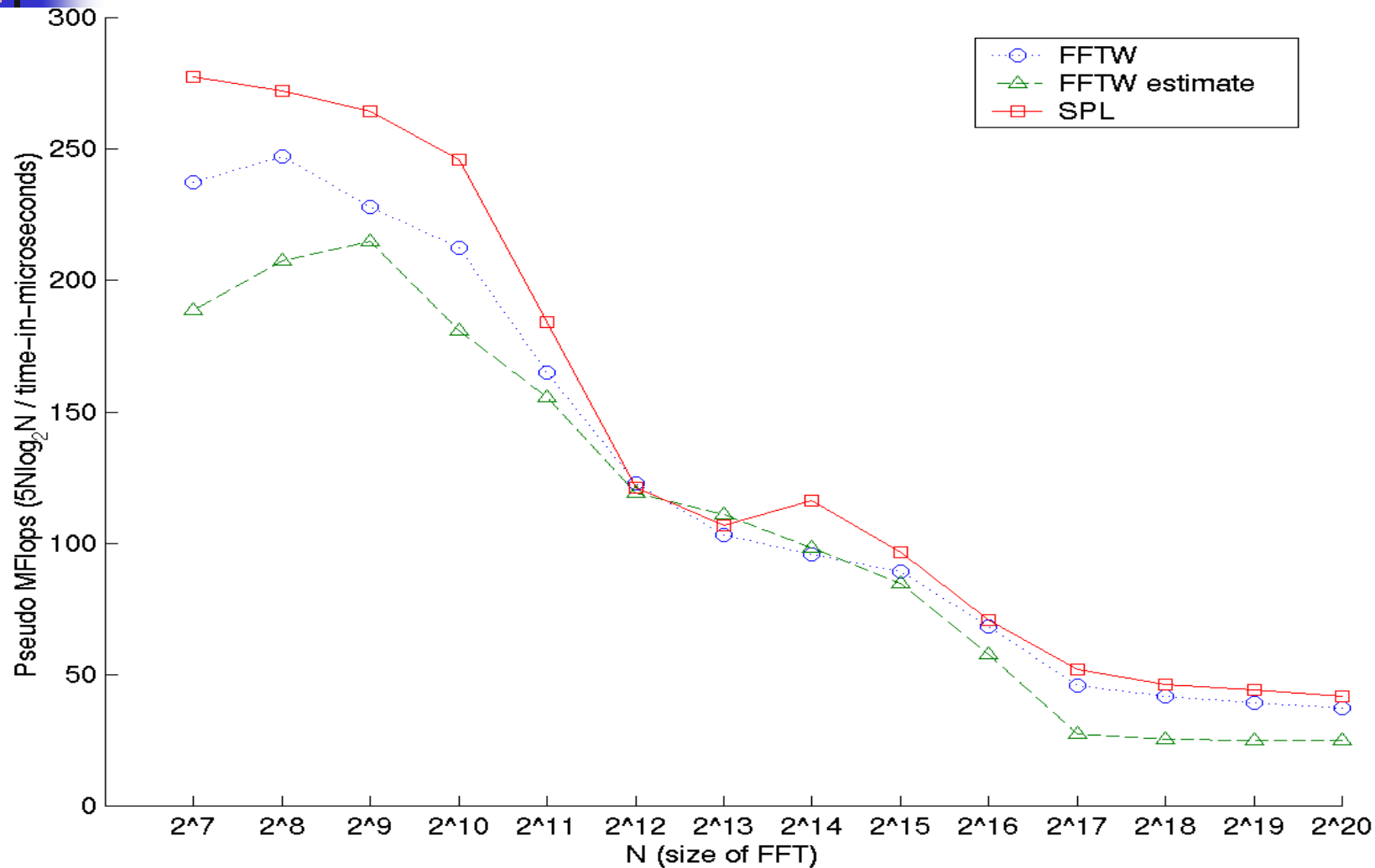




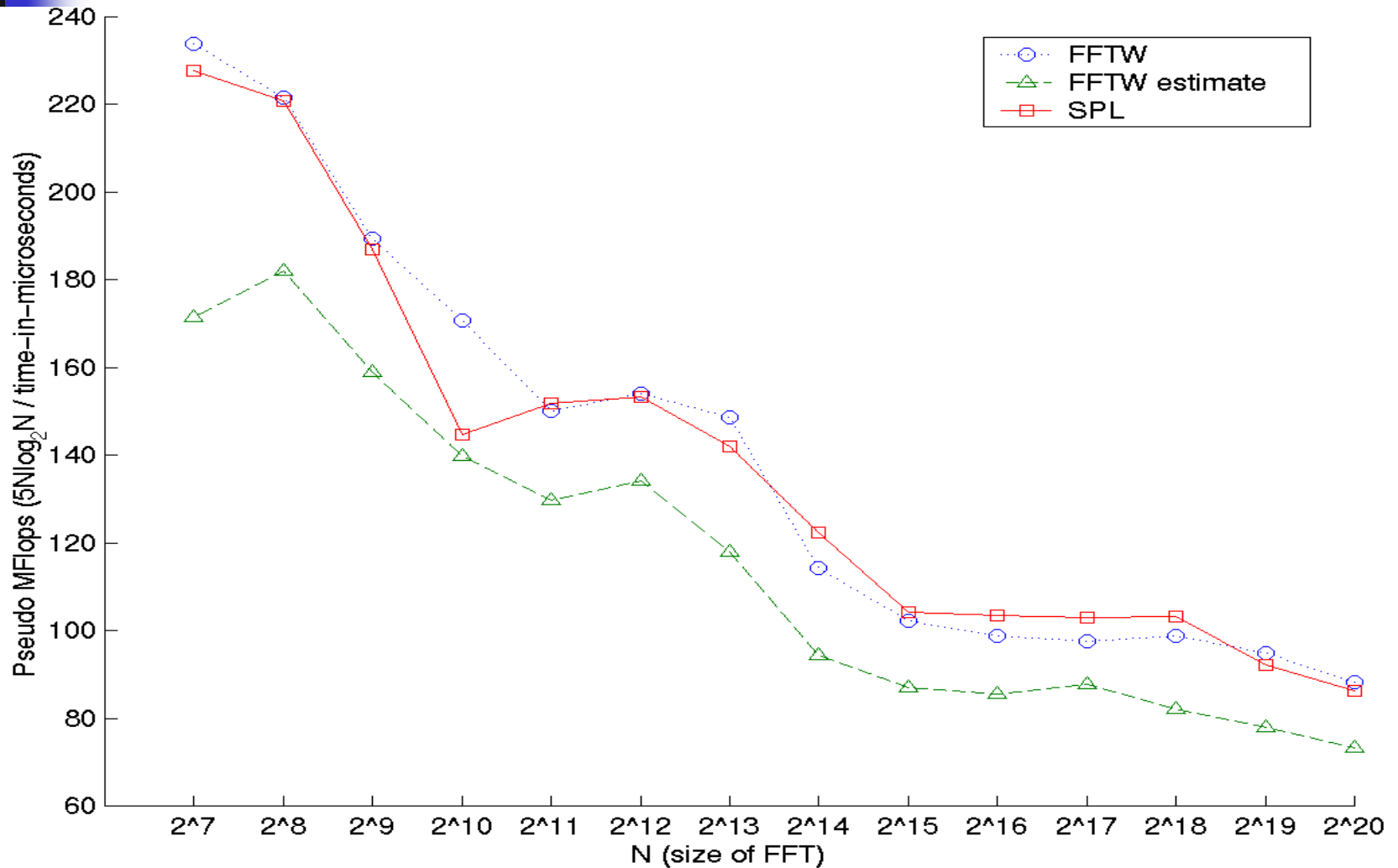
# FFT Performance (N=2<sup>7</sup> to 2<sup>20</sup>, Ultra5)



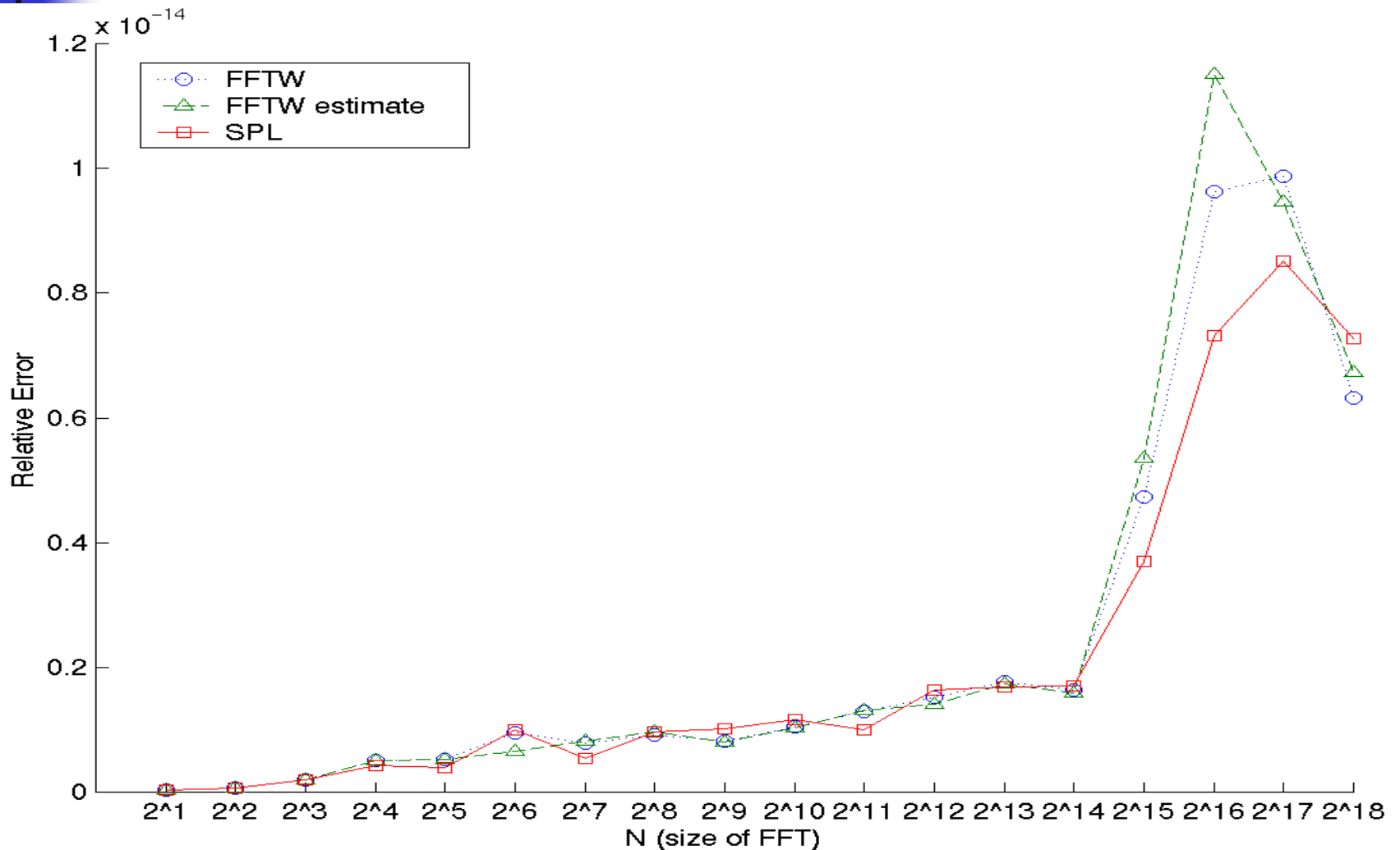
# FFT Performance (N=2<sup>7</sup> to 2<sup>20</sup>, Origin200)



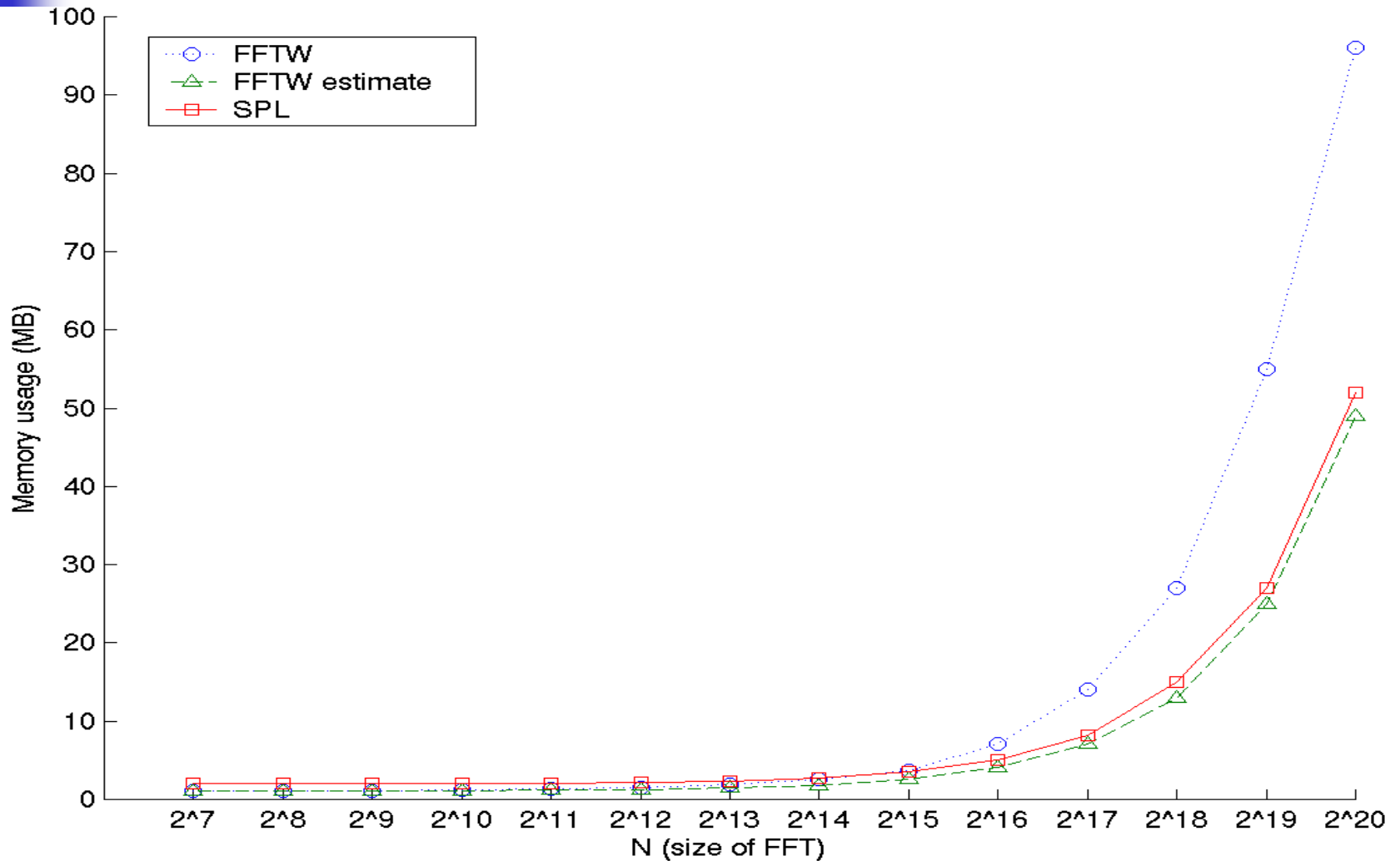
# FFT Performance (N=2<sup>7</sup> to 2<sup>20</sup>, PC)



# FFT Accuracy (N=2<sup>1</sup> to 2<sup>18</sup>)



# FFT Memory Utilization (N=2<sup>7</sup> to 2<sup>20</sup>)





## Conclusion

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- The SPL compiler is capable of producing efficient code on a variety of platforms.
- The standard optimizations carried out by the SPL compiler are necessary to get good performance.
- The template mechanism makes the SPL language and the SPL compiler highly extensible



## Related Work

	<b>Domain</b>	<b>Code Generator</b>	<b>Tuning</b>
FFTW	FFT	Fix algorithms	DP
WHT Package	WHT	Built-in	DP, GA
EXTENT	Block recursive	Built-in	Manual
ATLAS	BLAS	Hand coded, Blocking, unrolling	Search
PHiPAC	BLAS	Hand coded	Search
Iterative Compilation	Compiler option	N/A	Search



# Performance Evaluation: Platforms

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- Ultra5
  - Solaris 7, Sun Workshop 5.0
  - 333MHz UltraSPARC Iii, 128MB, 16KB/16KB/2MB
- Origin 200
  - IRIX64 6.5, MIPSpro 7.3.1.1m
  - 180MHz MIPS R10000, 384MB, 32KB/32KB/1MB
- PC
  - Linux kernel 2.2.18, egcs 1.1.2
  - 400MHz Pentium II, 256MB, 16K/16K/512KB