

Stack Trace Analysis for Large Scale Debugging

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Abstract

We present the Stack Trace Analysis Tool (STAT) to aid in debugging extreme-scale applications. STAT can reduce problem exploration spaces from thousands of processes to a few by sampling stack traces to form process equivalence classes, groups of processes exhibiting similar behavior. We can then use full-featured debuggers on representatives from these behavior classes for root cause analysis.

STAT scalably collects stack traces over a sampling period to assemble a profile of the application's behavior. STAT routines process the samples to form a call graph prefix tree that encodes common behavior classes over the program's process space and time. STAT leverages MRNet, an infrastructure for tool control and data analyses, to overcome scalability barriers faced by heavy-weight debuggers.

We present STAT's design and an evaluation that shows STAT gathers informative process traces from thousands of processes with sub-second latencies, a significant improvement over existing tools. Our case studies of production codes verify that STAT supports the quick identification of errors that were previously difficult to locate.

1. Introduction

Lawrence Livermore National Laboratory's (LLNL's) BlueGene/L (BG/L) is the current benchmark for extremely large scale systems with 131,072 processors, while other supercomputer class systems like the Cray XT3 promise to

operate with more than 60,000 processing cores. On the most recent Top 500 list [1], 228 systems (45.6%) had over 1,024 processors and 18 systems had over 8,192. With government initiatives for petaflop scale systems in the United States, Europe, Japan, and China, high-performance computing (HPC) systems with 10^4 and 10^5 processors will become common and 10^6 processor systems soon will exist. Yet tools for debugging and analyzing programs, even at existing scales, are non-existent. For example, on BG/L, TotalView [12], arguably the best parallel debugger, takes above one and two minutes to collect and merge stack traces from 2048 and 4096 processes (4,096 is 3% of BG/L).

We target the identification and diagnosis of application behavior, addressing questions like: what is the application doing? Is it in a deadlock or infinite loop? As noted by Roth, Arnold and Miller [25], developing a scalable diagnosis tool presents several challenges:

- *Overwhelming channels of control:* In most parallel debuggers, a front-end process controls the interactions between back-end tool daemon processes and the debugged application's processes. The front-end can spend unacceptably long times managing the connections to the back-end daemons at large process counts.
- *Large data volumes:* As the number of debugged processes increases, the volume of data becomes prohibitively expensive to gather.
- *Excessive data analysis overhead:* Even if the debug data can be gathered in acceptable time, the time to process and to present it becomes excessive, often causing users to resort to targeted print statements.
- *Scalable presentation of results:* Finally, presenting a standard source code trace for individual processes overwhelms the user and prevents quick anomaly detection; alternative presentation paradigms that synthesize across the set of processes are essential.

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To address these challenges, we present the Stack Trace Analysis Tool (STAT), which manages the scalable collection, analysis and visualization of stack trace profiles used to depict application behavior. Specifically, we sample application stack traces to form *process equivalence classes*, groups of processes exhibiting similar behavior. Our experience shows that processes of parallel computations, even erroneous ones, often can be grouped into few subsets, or even a single subset, of processes with similar runtime behavior. Errors then can be detected through spatial differentiation of the process space. However, unexpected behavior often also has a temporal aspect – the behavior is erroneous not because it occurs but because it persists. Our mechanisms detect these equivalence classes quickly, allowing the user to focus on a single representative of each.

Once we identify the equivalence classes, we present the user a call graph prefix tree that distinguishes them visually. We achieve scalability by leveraging the MRNet implementation [25] of the tree-based overlay network (TBON) model, which exploits the logarithmic scaling properties of trees for tool control and data analyses. Our scalable, lightweight diagnosis approach can effectively reduce the exploration space from thousands or even millions of processes to a handful of behavior classes (and class representatives). Once the problem space is reduced, we can perform root cause analysis with a full-featured debugger, since now it is only necessary that this debugger attach to a small subset of the processes.

This paper details our four main contributions: In Section 2, we present case studies of two production codes that motivate our stack trace analysis approach. Our second contribution is a simple, effective stack trace analysis technique that reduces debug exploration spaces from thousands to a handful of processes with sub-second latencies; we present its details in Section 3. That section also details our third, process group visualizations that can effectively guide users to problem diagnoses by displaying both spatial and temporal relationships. Section 4 then describes the design, implementation, and performance of our fourth contribution, a scalable STAT prototype that implements our analysis and visualization. In that section, we also apply the STAT to the case studies and discuss future research. Related tools and research are discussed in Section 5. Finally, we summarize the expected impact of this work in Section 6.

2. Motivating Case Studies

To motivate the need for our technology, we consider two large-scale debugging case studies. These studies involve problems with elusive root causes in CCSM and ViSUS, two parallel applications. In both cases, the defects manifested themselves as hangs at relatively large scales on LLNL machines. These case studies capture a current

manual approach for large-scale debugging, highlight its effectiveness, and present its scalability limitations. They demonstrate the need for better tools that automatically apply similar techniques much more quickly and scalably.

2.1. Pthread deadlock exposed by CCSM

The Community Climate System Model (CCSM) [7] is a widely used application that comprises multiple climatic simulators representing the atmosphere, ocean, sea ice and land surface connected by a coupling module. For several years, scientists have used CCSM and its components to improve climate predictions. Recently, an LLNL climate scientist reported intermittent hangs when running CCSM with 472 MPI tasks on the Thunder machine [17], an Itanium2 cluster with Quadrics Elan4 interconnect [24]. Several factors made the diagnostic process extremely challenging. For instance, CCSM consists of multiple programs and multiple data (MPMD). More importantly, the malfunction only occurred at large scale and non-deterministically manifested itself at apparently random program locations if at all.

During ten days of repeated attempts to reproduce the problem in a more controlled environment, the hang only occurred twice. Data analysis from the first reproduction of the hang suggested a pthread deadlock in an MPI task. Additional data from the second reproduction confirmed this.

Figure 1 depicts the manual data gathering and post-mortem analysis that we applied during the first reproduction of the error. We attached to all 472 MPI tasks using TotalView to gather several call graphs that capture the dynamic behavior of all tasks, an enhancement prototyped at LLNL. TotalView’s call graph display provides a view into a program’s spatial behavior (i.e., across job processes). The left graph in Figure 1 shows the top of the agglomerated call graph from all MPI tasks’ stack traces. This view reveals a characteristic known by the user: the job has five first-level process clusters depicted by the five sub-graphs rooted at `main`: 96 ocean model tasks; 16 land model tasks; 16 ice model tasks; 8 coupler tasks; and 336 atmosphere model tasks. The center graph of Figure 1 suggests an interesting behavior: the set of 336 atmosphere tasks form two clusters rooted at the `stepon` function node. One cluster consists of task 201; the other contains the remaining atmospheric model tasks. A comparison of the details of task 201 and task 200, an arbitrary representative of the second cluster, indicates a possible deadlock in task 201. Specifically, task 201 reentered the `pthread_mutex_lock` function in the ELAN4 library after an asynchronous interrupt due to a UNIX signal handler invocation, as indicated by the right graph in Figure 1. As a consequence, the other tasks were stalled at `MPI_Waitall`. Multiple stack trace snapshots taken over time for task 201 were almost identical, further supporting the deadlock theory. Direct support for time-

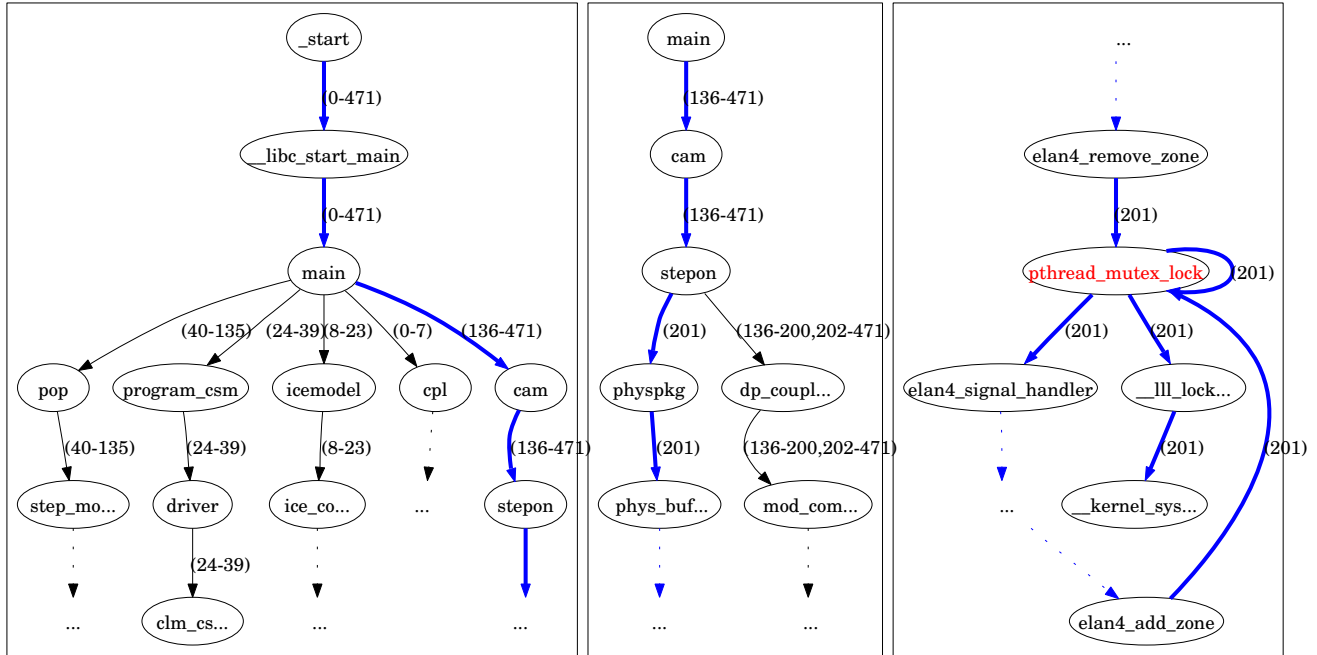


Figure 1. Manual debugging of the first CCSM hang at 472 MPI tasks

varying stack traces would have simplified this verification.

This high-level analysis aided our second round of debugging during which we immediately noticed that two tasks formed a similar anomalous cluster. TotalView analysis revealed that the anomalous tasks were attempting to re-lock a mutex. Further, the mutex type was `PTHREAD_MUTEX_NORMAL`, which results in a deadlock under Linux. We theorize that Quadrics QsNet^{II} software’s internal interconnect management raised a UNIX signal. Regardless, it is clear that the `elan4_remove_zone` function must be made signal safe.

2.2. Integer overflow in ViSUS

Visualization Streams for Ultimate Scalability (ViSUS) is a research project that develops data streaming techniques for progressive processing and visualization of large scientific data sets [23]. About a year ago, an LLNL developer reported a hang during a scaling test on BG/L. The hang occurred deterministically at scales of at least 8192 tasks. Since this was beyond the capability of any available debugger, the developer was forced to debug using print statements. Ad-hoc parsers were written to process the voluminous output; changes to the printed output demanded parser changes. Ultimately, this strategy proved ineffective.

Eventually, a more scalable version of TotalView became available. Even so, the scale continued to pose a challenge. Debugging 8,192 tasks was twice TotalView’s warranted

upper limit on BG/L. However, careful provisioning and the avoidance of non-scalable operations allowed the tool to be used at requisite scales. Once a debugging tool was available, diagnosis of the root cause of the hang was relatively simple. The debugger allowed the discovery of an unintentionally formed infinite loop due to 32-bit integer overflow.

The case studies show that some program errors only show up beyond certain scales and that errors may be non-deterministic and difficult to reproduce. Stack traces can provide useful insight, but current tools either do not provide enough information or cannot run effectively at the requisite scale. STAT addresses these deficiencies with a scalable, lightweight approach for collecting, analyzing, and rendering the spatial *and* temporal information necessary to reduce the problem to a manageable subset of processes.

3. Scalable Stack Trace Analysis

Motivated by debugging practices as in Section 2, we propose an automated, lightweight technique for scalably reducing problem exploration spaces. Our approach analyzes process stack traces to discover process equivalence classes – processes exhibiting similar behavior based on executing functions. This approach facilitates scalable data analysis as well as scalable visualizations that guide the user in the diagnosis process. This section details our stack trace analysis approach. We discuss existing techniques for processing stack traces from distributed applications and then

expand these techniques into ours, which uses traces collected over time and (process) space to profile applications.

For this discussion, we introduce a simple MPI program that we use as the target of our problem diagnosis. In this program, process ranks are organized into a virtual ring within which each process performs an asynchronous receive from its predecessor in the ring and an asynchronous send to its successor. Each process then blocks for the I/O requests to complete (via `MPI_Waitall`). A whole program synchronization point (`MPI_Barrier`) follows the ring communication. The code includes a bug that permanently blocks one task before its send operation.

Singleton Stack Traces Figure 2 illustrates the fundamental data object in our analysis, a stack trace, which depicts the caller/callee relationships of the functions being executed by a process. In our model, we distinguish functions by invocation paths; in other words, if the same function is invoked multiple times via different call paths, it occurs multiple times in our stack trace. We believe that functions invoked via different call paths (including recursively) may demonstrate different application semantics to the user that would not be visible without this distinction. Also, distinction by invocation means that merged stack traces result in a tree, which is easier to analyze both algorithmically and manually than a more general directed graph. Such singleton stack traces are supported by most if not all debuggers, typically using a textual representation. Singleton traces do not allow effective evaluation large applications: clearly, a thousand processes would generate a thousand stack traces – beyond the threshold of human comprehensibility.

2D-Trace/Space Analysis To address the deficiency of singleton traces, tools like TotalView and Prism support what we call a 2D-Trace/Space analysis, merging a single stack trace from each application process into a call graph prefix tree that maps stack traces into the application processes’ space. The presumption, as well as the common reality, is that there will be significant overlap amongst the individual stack traces such that many processes will merge into a relatively small call graph prefix tree. This data object is illustrated in Figure 3, which compares our call graph prefix tree to TotalView’s call graph. To help users quickly focus on a small number of individual processes, STAT analyzes the traces to depict process equivalence classes – processes in the same class are shown in the same color. In contrast, TotalView presents this information using a call

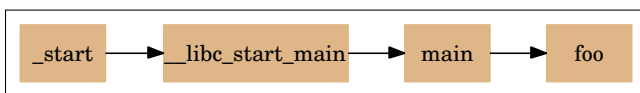


Figure 2. A stack trace showing caller/callee relationships of executing functions.

graph that does not distinguish the invocation path for each function leading to a general directed graph that cannot be as easily partitioned into equivalence classes.

2D-Trace/Time Analysis While our 2D-Trace/Space call graph prefix trees are well-suited for analyzing static scenarios like examining core dumps, they do not include the temporal information necessary to help answer questions about application progress, deadlock/livelock conditions, or performance. To address these issues, we introduce 2D-Trace/Time analyses: we merge and analyze a sequence of stack traces from a single process collected over a sampling interval. Figure 4(a) shows how this analysis renders a profile of a process’s behavior over time. Allowing the user to specify the length of the sampling period in terms of the number of samples to collect and the interval between samples, STAT allows the user to control the granularity at which traces are sampled and thus tool overhead as well as the coverage of the collected profile.

3D-Trace/Space/Time Analysis 2D-Trace/Time analysis allows a user to profile an individual process quickly, just like singleton stack traces; however, it is an ineffective method for understanding the collective behavior of many thousands of processes. The solution is a 3D-Trace/Space/Time analysis that combines both previous analysis techniques: we merge and analyze sequences of stack traces from multiple processes to assemble a global application profile. As seen in Figure 4(b), the identified process equivalence classes distinguish the sets of process behaviors exhibited by the application.

Our visualizations are influenced by Miller’s criteria for good parallel program visualization [19]. We briefly discuss how the visualization results of our 3D-Trace/Space/Time analysis observe some of these guiding principles:

- *Visualizations should guide, not rationalize:* By presenting a profile of the applications behavior for the sampling period and identifying equivalence classes of similar process behavior, the user quickly can extract new knowledge about program behavior.
- *Scalability is crucial:* For thousands of processes, it would not be scalable to display call graphs for each process. Instead, we merge these graphs into a single, compact tree. Further, as discussed below, the use of color to distinguish classes of process behavior helps the user to navigate complicated graphs.
- *Color should inform, not entertain:* We use color to distinguish process behavior classes. Nodes of identical color represent stack frames from groups of processes executing the same instructions in the program.
- *Visualizations should provide meaningful labels:* Node labels identify executing functions, and edge labels identify the number (and set) of processes traversing that edge. Together the labels show single process behavior or a view of dominant global behavior.

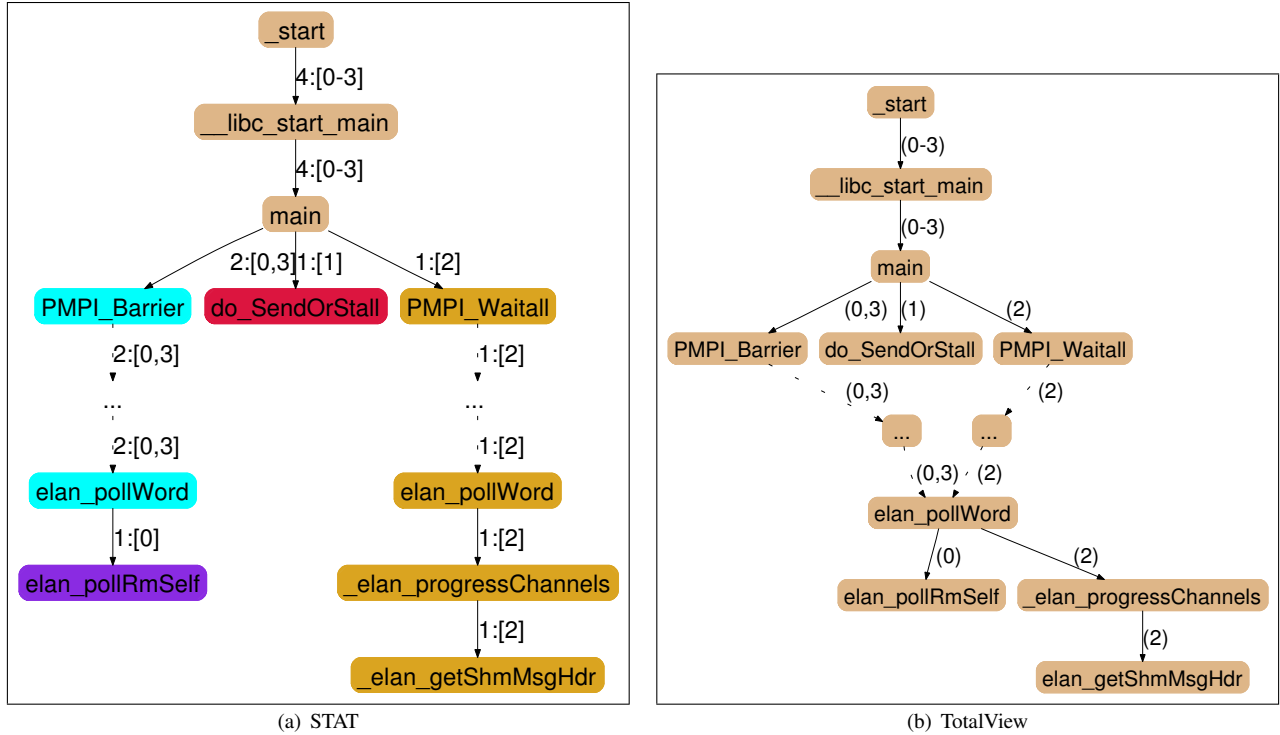


Figure 3. 2D-Trace/Space call graphs from (a) STAT, distinguishing nodes based on call paths, and (b) TotalView, representing nodes without call path history. STAT uses its tree representation to create equivalence classes of processes and displays them intuitively.

4. STAT: The Stack Trace Analysis Tool

We describe STAT’s scalable implementation of 3D-Trace/Space/Time analysis and present its performance as well as its application to Section 2’s case studies. We also discuss scalable visualization and future enhancements.

4.1. STAT design and implementation

STAT is composed of three main components: the tool front-end, the tool daemons, and the stack trace analysis routine. The front-end controls the collection of stack trace samples by the tool daemons, and the collected traces are processed by our stack trace analysis routine. The front-end renders the result, a single call graph prefix tree. STAT utilizes MRNet [25], a TBÖN-based multicast/reduction network infrastructure from the University of Wisconsin. A TBÖN (tree-based overlay network) is a network of hierarchically-organized processes that exploits the logarithmic scaling properties of trees to provide scalable application control, data collection, and data analyses. The STAT front-end and back-ends communicate via the MRNet process tree. MRNet filters are used to implement the stack trace analysis algorithm, which parent nodes executes on

input from children nodes. Back-ends merge local samples, which the TBÖN combines into a whole-program view.

The front-end, STAT’s driver, first instantiates the MRNet tree and tool daemon back-ends. Once the TBÖN is established, the front-end, via the MRNet API, dynamically loads the TBÖN processes with STAT’s custom filter, which processes the collected stack trace samples. The front-end then instructs each daemon to attach to the application processes local to that daemon’s compute node. After the attach phase, the front-end instructs each daemon to sample the application’s stack traces for a period defined by a count and sampling interval. Finally, the front-end color-codes the process equivalence classes in the call graph prefix tree comprised of the collected samples and exports the graph as an AT&T dot format file.

Each STAT back-end has the following capabilities: attach to application processes; sample process stack traces; merge/analyze collected samples; and propagate analysis results up the tree. The Dyninst library [8] allows us to debug unmodified applications. STAT back-ends use the core function described below to process locally collected samples before propagating results through the TBÖN.

The STAT filter inputs a vector of packets, one from each child of the executing internal node, and outputs a single

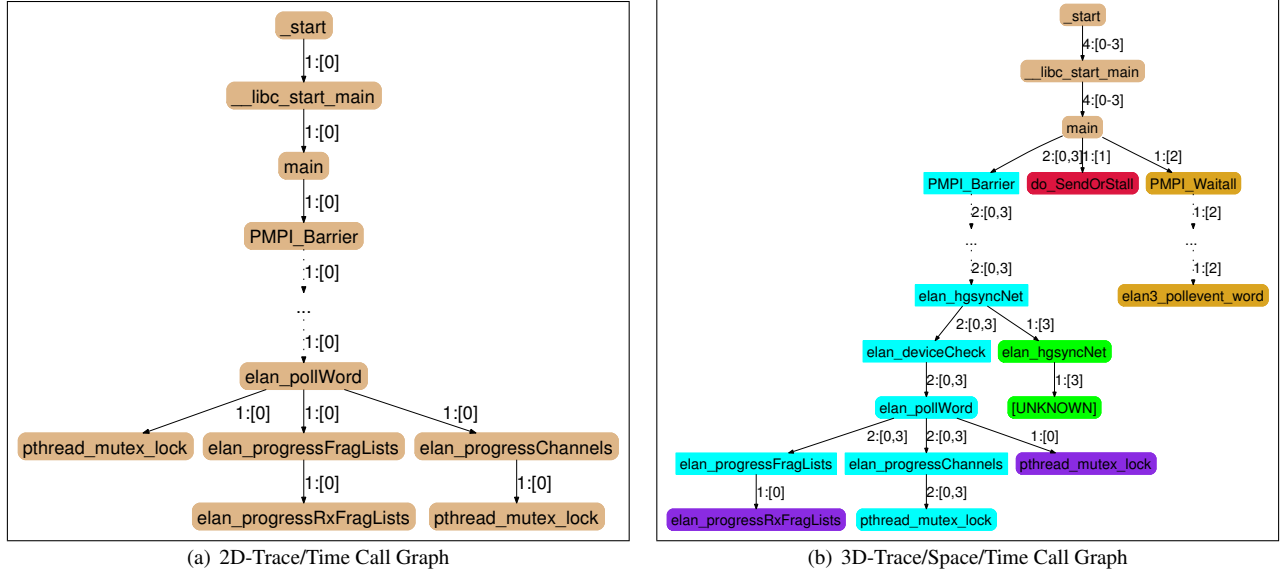


Figure 4. STAT Call Graph Prefix Trees. (a) A 2D-Trace/Time graph showing the call paths that a process has exhibited over a sampling period. (b) A 3D-Trace/Space/Time call graph prefix tree showing a global profile and distinguishing unique behaviors as process equivalence classes.

packet. Each STAT packet encapsulates a call graph prefix tree. The core function of the filter inputs two call graph prefix trees and outputs a single, merged call graph prefix tree that is further propagated through the TBÖN to yield a single global tree at the front-end.

4.2. Performance evaluation

We test STAT’s performance on Thunder, a 1,024 node cluster at LLNL. Each node has four 1.4 GHz Intel Itanium2 CPUs and 8 GB of RAM connected by a Quadrics QsNet^{II} interconnect using the Quadrics Elan 4 network processor.

For our experiments, we debug the MPI message ring program described in Section 3 at various scales. The application is run on an allocation with four MPI tasks per node. For debugging, STAT daemons must be co-located with the application processes. We place one tool daemon process on each node of the application’s allocation: one tool daemon debugs four application processes. The front-end and internal nodes are placed on a separate allocation.

We evaluate STAT’s performance by measuring the latency from the front-end’s broadcast to collect stack trace samples until the global call graph prefix tree is available at the front-end. We omit the sampling duration since this is determined by the number of samples and sampling interval as chosen by the user. For our experiments, we collected 10 samples from each process with a 1 second interval between samples. Dyninst micro-benchmark experiments show that stack trace sampling costs can vary from thousandths to

tenths of a second based on several factors including the platform, the target application’s characteristics (e.g. the libraries it includes), and what the target application is doing at the instant the sample is requested.

We compare the performance of 1-deep trees, the standard tool organization in which the front-end is directly connected to the tool-daemons, and 2-deep trees with an intermediate level of internal nodes¹. The 2-deep trees are completely balanced: all parent processes have the same number of children. The results of our experiments debugging up to 3844 application processes are shown in Figure 5. As the size of the debugged application increases, the latency of the 1-deep tree grows quadratically with the number of processes being debugged. Latencies in the 2-deep trees increase slowly due to the controlled fan-out.

4.3. STAT on real applications

We apply STAT to two real large-scale debugging cases presented in Section 2. The results of our empirical evaluation demonstrate that our tool provides insights into dynamic behavior of real anomalies.

4.3.1. Applying STAT to ViSUS

We apply the tool to ViSUS after reintroducing the bug into the code. We consider a reduced scale, 162 tasks, based

¹As scale increases, it is natural to increase tree depth to maintain scalable performance. For our experiments, 2-deep trees were sufficient.

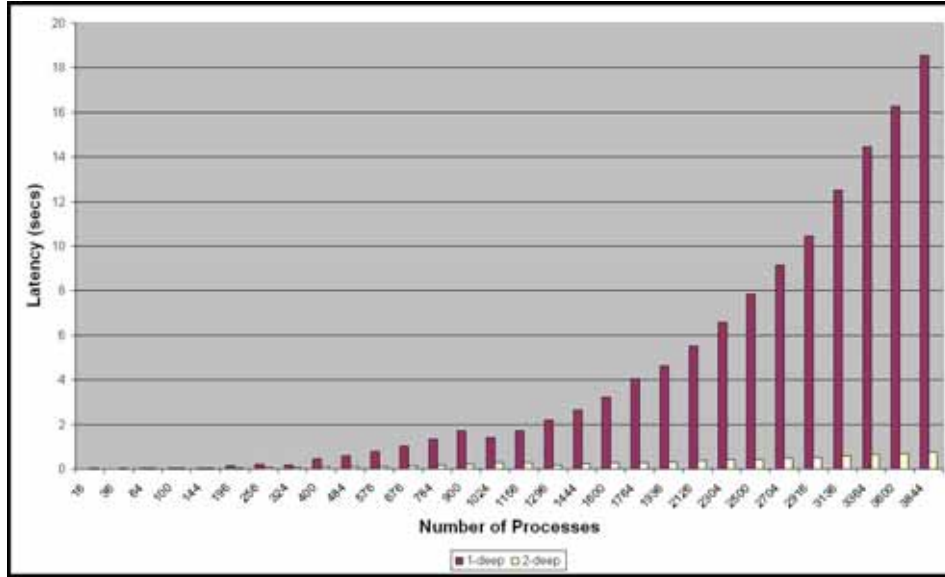


Figure 5. STAT Performance. 1-deep trees directly connect the tool front-end to the back-end daemons. 2-deep trees have an intermediate level of TBÖN processes.

on a subsequently found reproduction of the hang at much lower scales. When the program hangs, we attach STAT all tasks and sample ten stack traces with an interval of 100 milliseconds between samples.

Figure 6 shows a portion of the STAT graph capturing both spatial and temporal behavior. The figure indicates that all tasks behave homogeneously before entering the `composite` function, which invokes three functions: `handle_src`, which produces task-specific local data; `handle_cmp`, which composites the local data into global data; and `handle_mux`, which writes the global data to a file. A node coloring scheme then reveals the first-level cluster refinement at this function, yielding three sub-clusters. The label of each link forked off of the `composite` node shows the rank membership for each sub-cluster: a majority of tasks are producing local data, while only 14 tasks are compositing them and just one task, rank 1, is both compositing local data and writing the global data to disk. This cluster refinement correctly uncovers an important characteristic of ViSUS: all tasks form a virtual tree network to composite local data efficiently into global data. While all tasks produce local data, only a small subset composites them. Once all local data are composited, only the root task writes to the file. The graph shows that the anomaly does not perturb this normal cluster.

The removed bottom of the STAT graph indicates that only those member tasks of the second cluster carry out MPI communication calls. Unlike the CCSM case, however, examining further refinements of that cluster does not identify outlier tasks that would be a likely root cause of the

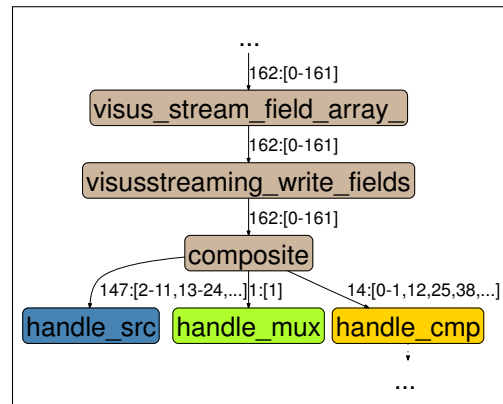


Figure 6. 3D-Trace/Space/Time ViSUS graph

hang. The graph naturally guides our attention rather to the `composite` function next. Examining a small code section of the `composite` function provides an insight into a possible infinite loop: the three function invocations occur in a while loop. For further root cause analysis, we pick three representative processes, rank 0, rank 1 and rank 2, one from each cluster. We then probe those tasks with a full-featured debugger and quickly locate a 32 bit integer overflow using debugging features like lock-stepping and evaluation points. The overflow prevented the `handle_src` function from returning a loop terminating code.

4.3.2. Applying STAT to CCSM

We apply STAT to CCSM when it hangs with the original configuration. STAT’s temporal behavior analysis effectively guides detection of the deadlock condition in an MPI task. Figure 7 is the graph capturing both spatial and temporal aspects of the program. The graph depicts that the offending task does not make progress over the sample period, after separating itself from the other tasks at the `parutilitiesmodule_mp_parexchagevec` function. For example, its call path does not contain any function node that has more than one immediate child node.

4.4. Scalable visualization

Even though our stack trace analysis results in drastically reduced graphs compared to visualizing all nodes’ stack traces individually, the previous examples have shown that even those reduced graphs can be large and complex. In most cases, however, the detection of equivalence classes and their coloring coding provides enough structure in the display. If this is insufficient, we can further reduce the complexity of the presented graphs without losing detailed information. One way to reduce the size of the displayed graphs is to provide optional pruning. With this method, we will default to displaying an easily comprehensible representation, the pruned graph. However, we will still allow users to expand pruned segments on demand to analyze relevant components more deeply.

The use of trees instead of directed graphs in STAT implicitly leads to the generation of hierarchical equivalence classes: each subtree of the complete stack trace information can be seen as one equivalence class, which can then be further subdivided into sub classes represented by lower branches in the tree. This property provides a natural abstraction for pruning larger trees since any pruning of a sub-

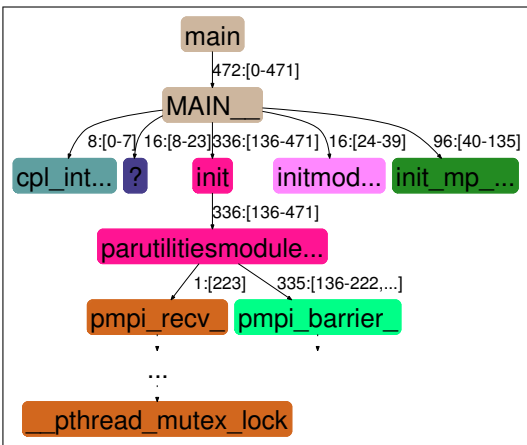


Figure 7. 3D-Trace/Space/Time CCSM graph

tree results in aggregating finer-grain equivalence classes into a more coarse grain one, but will not destroy the abstraction produced by STAT. This mechanism therefore provides a true level of detail selection mechanism without the possibility of misleading the user at higher levels of abstraction. A similar approach based on general directed graphs would require complex, expensive node coloring schemes.

An additional pruning criteria for call graphs is any transition from the user’s application to library functions that are normally opaque to the user. For example, we could prune the subgraphs of any nodes that represent MPI routines. As the above examples demonstrate, this will significantly reduce the size of the graphs in many cases since call graph variations are likely to occur within the MPI library.

Since we have shown that the errors often occur after or across these transitions, this pruning criteria would emphasize the need not only to reduce the graph but also to expand it on demand. This functionality is easily supported since we would apply our reduction operations when the data is displayed. The collected and stored data would still include the full merged stack trace information. Thus, we would extend the idea of pruning further to let the user dynamically prune the tree at any level. At first the user will only see a very high-level view of a tree (for example, a fixed number of branches starting at the root node or stopping at any library transitions) and can then interactively select to expand any existing branch. Such an interactive selection of zoom detail can be supported within a traditional graph viewer or through a file browser like display or other hierarchical representations supporting dynamic expansion/contraction.

A second major source for complexity in the graph visualization is the list of process ranks associated with each edge. Especially for large node counts, these lists can get long and fragmented and hence difficult to interpret. Since the concrete list is often not required to obtain a first overview, we suggest replacing the textual representation with a graphical one, for example, in the form of a bar code or digital fingerprint. This will allow users to identify and compare node sets quickly and visually without having to compare individual rank numbers. On-demand, such representations can be expanded to the actual rank lists.

4.5. Future enhancements

Our current tool provides a powerful abstraction of the state of a parallel application, but the actual problem diagnosis or anomaly detection is still up to the user of the tool. As a next step, we plan to integrate the tool with analysis techniques to automate the process of problem identification. For example, statistical clustering of call trees from all ranks can help identify processes with distinct and potentially anomalous behavior. Similarly, we can target performance problems like load imbalances or excessive waits.

To further support automatic analysis, we plan to extend our tool to compare data from multiple runs. This will add an additional dimension to our stack traces and, combined with a manual tagging of runs, for instance, as good or erroneous, provide an easy way to find the cause of anomalies.

5 Related Work

Our work focuses on strategies for diagnosing problems in large parallel applications. Much research in this area exists. In this section, we present related work in three categories: parallel debuggers; problem diagnosis via data analysis; and automated debugging techniques.

In the context of the Paradyn performance tool [20], Roth and Miller have studied the use of merging graph structures for efficient performance diagnosis. In their *deep start* diagnosis strategy [26], they fold stack trace sample trees collected from multiple processes to guide their problem search. They also implement a sub-graph folding algorithm that, like STAT, uses MRNet for scalable computation [27].

Over the years, many parallel debuggers have targeted a variety of programming languages and hardware platforms including Fx2 [2], Ladebug [5], Mantis [18], mpC [4], p2d2 [13], pdbx [14], Prism [28], and TotalView [12]. All at least have the capability of viewing individual process stack traces. Both the Prism and TotalView debuggers aggregate individual process stack traces into a single call graph tree. However, neither tool accommodates the time-varying views of call graphs necessary to answer questions about the programs behavior over time. Both also use a non-scalable, single level hierarchy with the tool front-end directly connected to the back-end processes. While Ladebug does not support aggregated stack traces, it does use a TBON and data aggregation for responsive tool control and data collection. Mantis supports a colored process grid visualization in which node colors reflect process status, for example, running, stopped, error. The fully-functional nature of these debuggers is partially what renders them non-scalable. We view STAT as complementary to such tools: we reduce the exploration space to scales heavy-weight tools can tolerate.

Several projects have investigated the use of statistical methods for automated application analysis. In the work of Dickenson et al [11], they collect call profiles from program runs and use several distance metrics to cluster similar profiles. Profiles from each cluster are analyzed to determine whether or not the cluster represents an anomaly. Yuan et al [30] apply a supervised classification algorithm to classify system call traces based on their similarity to previously analyzed traces with already diagnosed problems. Magpie [6] uses a string-edit distance metric, a measure of two string's difference, to cluster events. Events that do not belong to a sufficiently large cluster are considered anomalous. Mirgorodskiy et al [21] also use distance met-

rics to categorize data from control-flow traces, identifying traces that substantially differ from the others. They perform root cause diagnosis by, for instance, identifying which call path contributed most to the profile dissimilarity. Pinpoint [9] uses both clustering and decision trees on client-server traces to correlate request failures with any failures occurring in the components used to service the requests. Finally, Ahn and Vetter use multivariate statistics to cluster large performance data sets for scalable analysis and visualization [3]. Like our stack trace analysis, these approaches analyze collected run-time data to identify anomalies. These approaches are designed to run post mortem – after the application has exited. Our analysis is light-weight making it scalable and suitable for diagnosing program behavior as the application is running.

Several researchers have explored techniques to locate specific types of errors automatically. Umpire [29], Marmot [16], and the Intel Message Checker [10] trace MPI executions and detect violations of the MPI standard, including resource leaks, deadlocks and type mismatches. Intel Thread Checker (formerly Assure) [15] simulates OpenMP directives and automatically identifies race conditions and other common OpenMP errors. Finally, several tools, including Valgrind [22] and TotalView [12] automatically detect memory usage errors including leaks and stray writes. These tools provide precise information about the locations of coding errors costing significant overhead; they are not targeted to production, large scale jobs but rather as final step in the development process. Rather than expensive techniques that locate certain classes of errors precisely, we explore fast, scalable, automated techniques to find problem code regions and tasks.

6 Conclusion

We have presented the design and implementation of STAT, the scalable Stack Trace Analysis Tool. This tool addresses an issue that is becoming increasingly important for large scale parallel platforms: how do we diagnosis program errors that emerge only under production runs at very high processor counts. Specifically, we provide a method for assembling stack traces across the processes of a parallel job into a 3D-Trace/Space/Time diagram. While previous tools have focused on 2D-Trace/Space analyses, we analyze samples collected over time to distinguish behavior that is erroneous not because it exists, but because it persists. This diagram captures the hierarchical equivalence classes of execution paths across those processes, allowing users to focus on subsets of tasks and code regions quickly.

STAT builds upon the scalable MRNet tool infrastructure. STAT's tree of intermediate tool processes assembles 3D-Trace/Space/Time diagrams in a highly scalable manner. Our performance results demonstrate that STAT signif-

icantly improves our ability to examine stack traces across a parallel job: it achieves sub-second latencies at thousands of processes, compared to the multiple seconds with existing tools. This performance is critical since the current high latencies are sufficient to make most programmers give up for all but the most mission critical tasks. More importantly, we have presented several real debugging case studies showing that STAT can improve substantially our ability to locate the root causes of these errors quickly and accurately.

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