

STUDY OF MAGNETIC FIELD DEPENDENT VISCOSITY ON A SORET DRIVEN FERROTHERMOHALINE CONVECTION IN A ROTATING POROUS MEDIUM

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The effect of a magnetic field dependent viscosity on a Soret driven ferro thermohaline convection in a rotating porous medium has been investigated using the linear stability analysis. The normal mode technique is applied. A wide range of values of the Soret parameter, magnetization parameter, the magnetic field dependent viscosity, Taylor number and the permeability of porous medium have been considered. A Brinkman model is used. Both stationary and oscillatory instabilities have been obtained. It is found that the system stabilizes only through oscillatory mode of instability. It is found that the magnetization parameter and the permeability of the porous medium destabilize the system and the Soret parameter, the magnetic field dependent viscosity and the Taylor number tend to stabilize the system. The results are presented numerically and graphically.

Key words: Soret parameter, field dependent viscosity, oscillatory instability, linear stability, Taylor number, permeability of porous medium.

1. Introduction

Ferrofluids are single-magnetic-domain, two-phase three component fluids (Rosensweig, 1985), where the core represents the single domain, the core and carrier fluid represent the two phases, the surfactant and carrier fluids represent the three components. A distinguishing feature of a ferrofluid is its promising applications in various disciplines. Some practical applications of ferrofluids are dynamic sealing, heat dissipation, damping and doping of technological materials.

Ferroconvection studies were initiated by Cowley and Rosensweig (1947) followed by Finlayson (1970) and Lalas and Carmi (1971). Finlayson (1970) studied the convective instability of a single component ferrofluid heated from below in the presence of a vertical uniform magnetic fluid and explained the concept of thermo mechanical interaction in a ferrofluid. Bernard convection (Chandrasekhar, 1961) in magnetic fluids has been analyzed by Schechter and Velarde (1974) and Schwab *et al.* (1993).

Double diffusive convection is of great importance in various fields such as high quality crystal production, oceanography, production of pure medicine, solidification of molten alloys, geothermally heated lakes and magmas. Double diffusive convection occurs when the above system is heated up. In this convection, mass transfer is included and the density variation is caused by two different components which have different rates of diffusion (Huppert and Turner 1981; Turner, 1974). Vaidyanathan *et al.* (1995; 1997) investigated the ferrothermohaline convection in the presence and absence of a porous medium. The solute is ferromagnetic, which modifies the magnetic field established as a perturbation. They obtained the conditions for the onset of thermal stability through stationary and oscillatory modes.

When a salty fluid gets heated up two types of interdiffusive phenomena occur. They are known as (i) the Soret effect, (ii) Dufour effect. Thermodiffusion, also called the Soret effect, is characterized by the Soret coefficient. Thermodiffusion in a ferrofluid in the presence of a magnetic field was investigated by Voelker and Odenbach (2005).

Hurle and Jakeman (1971) analyzed the Soret-driven thermosolutal convection. They experimentally analyzed the non-linear stability of double diffusive phenomena. Self-oscillatory convection caused by the Soret effect was studied by Shliomis and Souhar (2000). They analyzed the influence due to magnetophoresis and the Soret effect in the convective instability of magnetized ferrofluids. By considering the magnetic fluid as a binary mixture, thermodiffusive problems in magnetic fluids in the presence of magnetic fields were analyzed by Lange (2004). Shevtsova *et al.* (2006) carried out a study on the onset of convection in Soret driven instability. Soret – driven convection in a horizontal porous layer was analytically and numerically studied by Charier – Mojtabi *et al.* (2007). They found that for a cell heated from below the monocellular flow loses stability and when it is heated from above it remains stable.

Soret driven ferrothermohaline convection in the presence and absence of a porous medium was investigated by Vaidyanathan *et al.* (2005) and Sekar *et al.* (2006). They also analyzed the effect of dust particles in ferrothermohaline convection due to the Soret effect (Sekar *et al.*, 2008 and 2009) and (Hemalatha *et al.*, 2011). A linear stability analysis on the onset of Soret driven motion in nanoparticles suspension was made by Kim (2011).

The effect of rotation on ferrothermohaline convection saturating a porous medium was analyzed by Sekar *et al.* (1998). A non linear stability analysis of a rotating double diffusive magnetized ferrofluid was carried out by Sunil *et al.* (2011). The effect of porosity on revolving ferrofluid flow with a rotating disk was analyzed by Kushal Sharma *et al.* (2011a).

It is interesting to study the nature of variable viscosity on fluids. Viscosity may depend on temperature (Ramanathan and Mukhil, 2006) and the magnetic field also. Thermal convection in a ferromagnetic fluid in the presence of a magnetic field dependent viscosity was investigated by many authors (Kushal Sharma *et al.*, 2010; 2011b) and (Vaidyanathan *et al.*, 2002a; 2002b and 2002c). The effect of a magnetic field dependent viscosity on ferroconvection and ferrothermohaline convection in the presence and absence of dust particles was studied by Sunil *et al.* (2005 and 2006). Nanjundappa *et al.* (2009) analyzed the effect of a magnetic dependent viscosity on the onset of a ferromagnetic fluid layer heated from below and cooled from above with constant heat flux. The effect of a magnetic field dependent viscosity on ferroconvection in an anisotropic porous medium in the presence of a horizontal thermal gradient was studied by Hemalatha and Sivapra (2012).

Vaidyanathan *et al.* (2007) discussed the effect of Coriolis force on a Soret driven ferrothermohaline convection in a medium of sparse particle suspension. In the present work, it is intended to include the effect of a magnetic field dependent viscosity, Coriolis force and Soret effect in a ferrofluid saturating a porous medium. A linear stability analysis has been carried out. A Brinkman model is used. It is found that the system stabilizes only through oscillatory mode. The values are presented graphically.

2. Mathematical formulation

A horizontal layer of an incompressible Boussinesq ferromagnetic fluid of thickness ‘ d ’ in the presence of a transversely applied magnetic field heated from below and salted from below and above is considered. The temperature and salinity at the bottom and top surfaces $z = \pm d/2$ are $T_0 \mp \Delta T/2$ and $S_0 \pm \Delta S/2$ respectively. Both boundaries are taken to be free and perfect conductors of heat and solute. Considering the Soret effect on the temperature gradient the mathematical equations governing the above investigation are as follows.

The fluid is assumed to be an incompressible fluid having a variable viscosity given by

$$\mu = \mu_l (1 + \delta \cdot B) \quad (2.1)$$

where μ_l is taken as the viscosity of the fluid when the applied magnetic field is absent. The variation in the coefficient of the magnetic field dependent viscosity δ has been taken to be isotropic $\delta_1 = \delta_2 = \delta_3$. Hence the component wise μ can be written as

$$\mu_x = \mu_l (1 + \delta B_1),$$

$$\mu_y = \mu_l (1 + \delta B_2),$$

$$\mu_z = \mu_l (1 + \delta B_3).$$

The continuity equation for an incompressible Boussinesq fluid is

$$\nabla \cdot \mathbf{q} = 0. \quad (2.2)$$

The momentum equation as given by Finlayson (1970) is

$$\rho_0 \frac{D\mathbf{q}'}{Dt} = -\nabla p + \rho \mathbf{g} + \nabla \cdot (\mathbf{HB}) + \mu \nabla^2 \mathbf{q}' + 2\rho_0 (\mathbf{q}' \times \boldsymbol{\Omega}) - \frac{\mu}{k} \mathbf{q}'. \quad (2.3)$$

The temperature equation for an incompressible ferrofluid is

$$\left[\rho_0 C_{v,H} - \mu_0 \mathbf{H} \cdot \left(\frac{\partial \mathbf{M}}{\partial T} \right)_{v,H} \right] \frac{dT}{dt} + \mu_0 T \left(\frac{\partial \mathbf{M}}{\partial T} \right)_{v,H} \cdot \frac{d\mathbf{H}}{dt} = K_I \nabla^2 T + \phi. \quad (2.4)$$

The mass flux equation is given by

$$\frac{DS}{Dt} = K_S \nabla^2 S + S_T \nabla^2 T \quad (2.5)$$

where K_I, K_S, ϕ , and S_T are the thermal conductivity, concentration diffusivity, viscous dissipation factor containing second order terms in velocity and the Soret coefficient respectively.

Using Maxwell's equations for non-conducting fluids, one can assume that the magnetization is aligned with the magnetic field and depends on the magnitude of the magnetic field, temperature and salinity, so that

$$\mathbf{M} = \frac{\mathbf{H}}{H} M(H, T, S). \quad (2.6)$$

The magnetic equation of state is linearized about the magnetic field H_0 , the average temperature T_0 and the average salinity S_0 to become

$$M = M_0 + \chi(H - H_0) - K(T - T_0) + K_2(S - S_0) \quad (2.7)$$

where $\chi = \left[\frac{\partial M}{\partial H} \right]_{H_0, T_0}$, $K = - \left[\frac{\partial M}{\partial T} \right]_{H_0, T_0}$, $K_2 = \left[\frac{\partial M}{\partial S} \right]_{H_0, S_0}$ are the magnetic susceptibility, the pyromagnetic coefficient and the salinity magnetic coefficient, respectively.

The density equation of state for a Boussinesq two-component fluid is

$$\rho = \rho_0 \left(1 - \alpha_t (T - T_0) + \alpha_s (S - S_0) \right) \quad (2.8)$$

where α_t is the thermal coefficient and α_s the solute analog of α_t . The basic state is assumed to be a quiescent state and the basic state quantities are obtained by substituting the velocity of the quiescent state in the governing Eqs (2.1)-(2.5) and the solutions of Eqs (2.1)-(2.8) are obtained using the techniques of the linear stability analysis and normal mode technique.

Normal mode solution of all dynamical variables can be written as

$$f(x, y, z, t) = f(z, t) \exp i(k_x x + k_y y) \quad (2.9)$$

where $f(z, t)$ represents $[w(z, t), \theta(z, t), S(z, t), z(z, t), \phi(z, t)]$.

The wave number k_0 is given by

$$k_0^2 = k_x^2 + k_y^2. \quad (2.10)$$

The modified Fourier heat conduction equation is

$$\begin{aligned} \left[\rho_0 C_{V,H} \frac{\partial \theta}{\partial t} - \mu_0 K T_0 \frac{\partial}{\partial t} \left(\frac{\partial \phi}{\partial z} \right) \right] = & \left[K_l \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) \theta + \right. \\ & \left. + \left[\rho_0 C \beta_t - \left(\frac{\mu_0 K^2 T_0^2 \beta_t}{I + \chi} \right) + \left(\frac{\mu_0 K K_2 T_0 \beta_s}{I + \chi} \right) \right] w \right] \end{aligned}$$

where $\rho_0 C = \rho_0 C_{V,H} + \rho_0 K H_0. \quad (2.11)$

The vertical component of the momentum equation can be written as

$$\begin{aligned} \rho_0 \frac{\partial}{\partial t} \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) w = & \left(\frac{\mu_0 K \beta_t}{I + \chi} \right) \left[(I + \chi) \frac{\partial \phi}{\partial z} - K \theta (I - S_T) \right] k_0^2 - \rho_0 g \alpha_t k_0^2 \theta + \\ & + \left(\frac{\mu_0 K_2 \beta_s}{I + \chi} \right) \left[(I + \chi) \frac{\partial \phi}{\partial z} + K_2 S \right] k_0^2 + \rho_0 g \alpha_s k_0^2 S + \\ & - \left(\frac{\mu_0 K K_2}{I + \chi} \right) \left[\beta_s (I - S_T) \theta - \beta_t S \right] k_0^2 - \mu_l \delta \mu_o (M_o + H_o) \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) k_0^2 w + \\ & + \mu \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right)^2 w - 2 \rho_o \Omega \frac{\partial \zeta}{\partial z} - \frac{\mu}{k} \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) w. \end{aligned} \quad (2.12)$$

The z component of the vorticity equation can easily be obtained as

$$\rho_0 \frac{\partial \zeta}{\partial t} = \mu \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) \zeta + 2 \rho_o \Omega \frac{\partial w}{\partial z} - \frac{\mu}{k} \zeta \quad (2.13)$$

where $\zeta = \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$, is the z component of vorticity.

The pressure term, the magnetic body force term vanish from the vorticity equation.
The salinity equation is

$$\frac{\partial S}{\partial t} + \beta_s w = K_S \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) S + S_T \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) \theta. \quad (2.14)$$

The magnetic potential equation is

$$(1 + \chi) \frac{\partial^2 \phi}{\partial z^2} - \left(1 + \frac{M_0}{H_0} \right) k^2 \phi - K \frac{\partial \theta}{\partial z} + K_2 \frac{\partial S}{\partial z} + S_T K \frac{\partial \theta}{\partial z} = 0. \quad (2.15)$$

Following the normal mode analysis, the linearized perturbation dimensionless equations for the thermosolutal convection due to Soret effect in a ferrofluid are

$$\begin{aligned} \left(\frac{\partial}{\partial t^*} + \frac{1}{k^*} \right) (D^2 - a^2) w^* = & - (Ta)^{1/2} D \zeta^* + aR^{1/2} [M_I D \phi^* - (1 + M_I (1 - S_T)) T^*] + \\ & + M_I M_5 a R^{1/2} D \phi^* - M_I M_5 a R^{1/2} (1 - S_T) T^* + (D^2 - a^2)^2 w^* + \\ & + a R_s^{1/2} \left(1 + M_4 + \frac{M_4}{M_5} \right) S^* - a^2 \delta^* M_3 (D^2 - a^2) w^*, \end{aligned} \quad (2.16)$$

$$\left(\frac{\partial}{\partial t^*} + \frac{1}{k^*} \right) \zeta^* = (D^2 - a^2) \zeta^* + (Ta)^{1/2} D w^*, \quad (2.17)$$

$$\text{Pr} \left[\frac{\partial T^*}{\partial t^*} - M_2 \frac{\partial}{\partial t^*} (D \phi^*) \right] = (D^2 - a^2) T^* + aR^{1/2} [(1 - M_2 - M_2 M_5)] w^*, \quad (2.18)$$

$$\text{Pr} \frac{\partial S^*}{\partial t^*} = \tau (D^2 - a^2) S^* - aR_s^{1/2} M_6 w^* + S_T \left(\frac{M_5}{M_6} \right) R_s^{1/2} (D^2 - a^2) T^*, \quad (2.19)$$

$$D^2 \phi^* - a^2 M_3 \phi^* - (1 - S_T) D T^* + \left(\frac{M_5}{M_6} \right) \left(\frac{R}{R_s} \right)^2 D S^* = 0 \quad (2.20)$$

where the non-dimensional variables can be written as

$$t^* = \frac{\nu t}{d^2}, \quad w^* = \frac{wd}{\nu}, \quad T^* = \left(\frac{K_I a R^{1/2}}{\rho_0 C_{V,H} \beta_I \nu d^2} \right) \theta, \quad \phi^* = \left(\frac{(1 + \chi) K_I a R^{1/2}}{K \rho_0 C_{V,H} \beta_I \nu d^2} \right) \phi,$$

$$z^* = \frac{z}{d}, \quad a = k_0 d, \quad D = \frac{\partial}{\partial z^*}, \quad S^* = \left(\frac{K_S a R_s^{1/2}}{\rho_0 C_{V,H} \beta_S \nu d} \right) S, \quad k^* = \frac{k}{d^2}$$

where the dimensionless parameters used are

$$\begin{aligned}
 M_1 &= \frac{\mu_0 K^2 \beta_t}{(1+\chi) \rho_0 g \alpha_t}, & M_2 &= \frac{\mu_0 K^2 T_0}{(1+\chi) \rho_0 C_{v,H}}, & M_3 &= \frac{\left(1 + \frac{M_0}{H_0}\right)}{(1+\chi)}, \\
 M_4 &= \frac{\mu_0 K^2 \beta_s}{(1+\chi) \rho_0 g \alpha_s}, & \text{Pr} &= \frac{\mu C_{v,H}}{K_l}, & R &= \frac{\rho_0 C_{v,H} \beta_t \alpha_t g d^4}{\nu K_l}, \\
 M_5 &= \frac{K_2 \beta_s}{K \beta_t}, & R_S &= \frac{\rho_0 C_{v,H} \beta_s \alpha_s g d^4}{\nu K_S}, & \tau &= \rho_0 C_{v,H} \left(\frac{K_S}{K_l}\right), \\
 M_6 &= \frac{K_S}{K_l}, & \text{Ta} &= \left(\frac{2\Omega d^2}{\nu}\right)^2, & \delta^* &= \delta \mu_0 H_0 (1+\chi) M_3
 \end{aligned} \tag{2.21}$$

where R, R_S, Pr and S_T are, respectively, the critical thermal Rayleigh number, salinity Rayleigh number, the Prandtl number, Soret coefficient and other parameters to represent non dimensional parameters used appropriately.

3. Exact solution for free boundaries

The boundary conditions on velocity, temperature, salinity and the magnetic potential are

$$w^* = D^2 w^* = T^* = D\varphi^* = S^* = 0 \quad \text{at} \quad z^* = \pm \frac{1}{2}. \tag{3.1}$$

The exact solutions satisfying Eq.(3.1) are

$$\begin{aligned}
 W^* &= A_l e^{\sigma t^*} \cos \pi z^*, & T^* &= B_l e^{\sigma t^*} \cos \pi z^*, & S^* &= C_l e^{\sigma t^*} \cos \pi z^*, \\
 \varphi^* &= \frac{F_l}{\pi} e^{\sigma t^*} \sin \pi z^*, & D\varphi^* &= F_l e^{\sigma t^*} \cos \pi z^*
 \end{aligned} \tag{3.2}$$

where A_l, B_l, C_l , and F_l are constants and σ is the growth rate. In the above solution, the lowest mode of $\sin(n\pi z)$, for $n=1$ is assumed as a solution. The solution can be odd or even modes compatible with boundary conditions. In the present case of choosing the reference at the centre enables one to choose the lowest even mode, namely $\cos(n\pi z)$ for all dynamical variables. Substitution of Eqs (3.2) in Eqs (2.16) - (2.20) leads to

$$\begin{aligned}
 &A_l \left[\left(\pi^2 + a^2\right)^2 + \left(\sigma + \frac{1}{k}\right) \left(\pi^2 + a^2\right) + \frac{\text{Ta} \pi^2}{\sigma + \frac{1}{k} + \pi^2 + a^2} + a^2 \delta M_3 \left(\frac{1}{k} + \pi^2 + a^2\right) \right] + \\
 &- B_l [1 + M_1(1 - S_T) + M_l M_5 (1 - S_T)] a R^{1/2} + \\
 &+ C_l (1 + M_4 + M_4 M_5^{-1}) a R_S^{1/2} + F_l a R^{1/2} M_l (1 + M_5) = 0,
 \end{aligned} \tag{3.3}$$

$$A_1 a R^{1/2} (1 - M_2 - M_2 M_5) - B_1 \left((\pi^2 + a^2) + \text{Pr} \sigma \right) + F_1 \text{Pr} M_2 \sigma = 0, \quad (3.4)$$

$$A_1 a R_S^{1/2} M_6 + B_1 \left(\frac{R_S}{R} \right)^{1/2} \frac{M_5}{M_6} (\pi^2 + a^2) S_T + C_1 \left(\tau (\pi^2 + a^2) + \text{Pr} \sigma \right) = 0, \quad (3.5)$$

$$-B_1 \pi^2 (1 - S_T) R_S^{1/2} + C_1 \pi^2 \frac{M_5}{M_6} R^{1/2} + F_1 (\pi^2 + a^2 M_3) R_S^{1/2} = 0. \quad (3.6)$$

For the existence of non-trivial eigen functions the determinant of the coefficients of A_1 , B_1 , C_1 , and F_1 in Eqs (3.3) - (3.6) must vanish. Following the techniques and analysis of Finlayson on Eqs (3.3) - (3.6) leads to

$$U \sigma^4 + V \sigma^3 + W \sigma^2 + X \sigma + Y = 0 \quad (3.7)$$

where

$$U = x_1 \text{Pr}^2, \quad V = c_1 (c_2 + x_1) \text{Pr}^2 + x_1^2 \text{Pr} (1 + \tau),$$

$$W_1 = \text{Pr} c_1 (c_2 + x_1) x_1 (1 + \tau) + \tau x_1^3 + \text{Ta} \pi^2 \text{Pr}^2 + \text{Pr}^2 c_1^2 c_2 - a^2 R_S x_4 M_6 \text{Pr},$$

$$W_2 = a^2 \left[x_3 x_2^{-1} \pi^2 \text{Pr} \left((1 - S_T) + M_5 \right) - \text{Pr} (1 + x_3 (1 - S_T)) \right],$$

$$X_1 = \tau x_1^3 c_1 (c_2 + x_1) + x_1 \text{Pr} (1 + \tau) \left(\text{Ta} \pi^2 + c_1^2 c_2 \right) - a^2 R_S x_4 \left(x_1 S_T \frac{M_5}{M_6} + M_6 (\text{Pr} c_1 + x_1) \right),$$

$$X_2 = a^2 \left[x_2^{-1} x_3 \pi^2 \left(x_1 S_T \frac{M_5^2}{M_6^2} + (\tau x_1 + \text{Pr} c_1) (1 - S_T) + M_5 (x_1 + \text{Pr} c_1) \right) + \right. \\ \left. - (x_1 \tau + \text{Pr} c_1) (1 + x_3 (1 - S_T)) \right],$$

$$Y_1 = x_1^2 \tau \left(\text{Ta} \pi^2 + c_1^2 c_2 \right) - a^2 R_S x_4 c_1 x_1 \left(S_T \frac{M_5}{M_6} + M_6 \right),$$

$$Y_2 = a^2 \left[x_2^{-1} x_3 \pi^2 x_1 c_1 \left(S_T \frac{M_5^2}{M_6^2} + \tau (1 - S_T) + M_5 \right) - \tau c_1 x_1 (1 + x_3 (1 - S_T)) \right]$$

$W = W_1 + W_2 R$, $X = X_1 + X_2 R$, $Y = Y_1 + Y_2 R$, where R is the thermal critical Rayleigh number. Also,

$$x_1 = \pi^2 + a^2, \quad x_2 = \pi^2 + a^2 M_3, \quad x_3 = M_1 (1 + M_5),$$

$$x_4 = \left(1 + M_4 + \frac{M_4}{M_5} \right), \quad c_1 = \frac{1}{k} + x_1, \quad c_2 = \delta + x_1.$$

For obtaining stationary instability the time independent term is made equal to zero. The critical thermal Rayleigh number for stationary instability is obtained from Eq.(3.8), using the formula

$$R_{SC} = \frac{Nr}{Dr} \quad (3.8)$$

where

$$Nr = \left(\frac{\text{Ta}\pi^2 x_1}{c_1} + x_1 c_1 c_2 \right) - a^2 R_S x_4 \left(S_T \frac{M_5}{M_6} + M_6 \right) \tau^{-1},$$

$$Dr = a^2 \left[\left(1 + x_3 (1 - S_T) \right) - x_2^{-1} x_3 \pi^2 \tau^{-1} \left(S_T \frac{M_5^2}{M_6^2} + \tau (1 - S_T) + M_5 \right) \right].$$

It is worthwhile to mention that in the absence of the magnetic field dependent viscosity, the Taylor number and the permeability of the porous medium, the critical thermal Rayleigh number given by Eq.(3.8), reduces to the critical thermal Rayleigh number obtained by Vaidyanathan *et al.* (2005). In the absence of the field dependent viscosity and the Soret parameter this Eq.(3.8) reduces to the thermal Rayleigh number obtained by Vaidyanathan *et al.* (1997). For very large M_1 , one gets the results for the magnetic mechanism, and the critical thermomagnetic Rayleigh number for stationary mode is obtained using

$$N_{SC} = RM_1 = \frac{Nr}{Dr} \quad (3.9)$$

where

$$Nr = \left(\frac{\text{Ta}\pi^2 x_1}{c_1} + x_1 c_1 c_2 \right) - a^2 R_S x_4 \left(S_T \frac{M_5}{M_6} + M_6 \right) \tau^{-1},$$

$$Dr = a^2 (1 + M_5) \left[(1 - S_T) - \frac{\pi^2 \tau^{-1} \left(S_T \frac{M_5^2}{M_6^2} + \tau (1 - S_T) + M_5 \right)}{x_2} \right].$$

The conditions for the onset of oscillatory stabilities are obtained as follows. Taking $\sigma = i\sigma_1$ and $\sigma_1^2 > 0$ in (28) we get

$$R_{0SC} = \frac{Nr}{Dr}$$

where,

$$R_{0SC} = \frac{UW_2\sigma_1^4 + (VX_2 - W_1W_2)\sigma_1^2 - X_1X_2}{X_2^2 + \sigma_1^2W_2^2} \quad \text{and} \quad \sigma_1^2 = \frac{(X_2W_1 - X_1W_2)}{X_2U - VW_2} \quad (3.10)$$

where if $R_{0C} > R_{SC}$, then the system stabilizes through stationary mode. If $R_{0C} < R_{SC}$, then the system stabilizes through oscillatory mode, where R_{0C} and R_{SC} are the critical thermal Rayleigh numbers for the oscillatory and stationary convection system.

4. Results and discussions

The Soret-driven convective instability of a two component ferrofluid in the presence of a magnetic field dependent viscosity in a rotating sparsely distributed porous medium has been analyzed. A Brinkman model is used. A Linear stability analysis has been carried out as the perturbations are assumed to be small. The magnetization parameter M_1 is taken to be 1000. The Soret parameter S_T is allowed to vary from -0.002 to 0.002. The salinity Rayleigh number R_S is assumed to take values from -500 to 500 and the magnetization parameter M_3 is varied from 5 to 25. The ratio of mass transport to heat transport τ is assumed to have values from 0.05 to 0.13. The Prandtl number Pr is assumed to be 0.01. For these fluids M_2 will have a negligible value and hence is taken as zero. The magnetic field dependent viscosity δ is allowed to take values from 0.01 to 0.07. The Taylor number Ta which decides about the amount of rotation is allowed to vary from 10 to 10^8 . The permeability of the porous medium k is given values ranging from 0.1 to 0.9.

Figure 1 represents the variation of the critical thermal Rayleigh number R_c versus the permeability of the porous medium k for different values of δ , the dependent viscosity. It is seen from the figure that the system destabilizes as the permeability of the porous medium k increases. This is indicated by a decrease in R_c values. The reason is that as the pore size increases, it becomes easier for the flow to destabilize the system. It is observed from the figure that the dependent viscosity δ is found to stabilize the system.

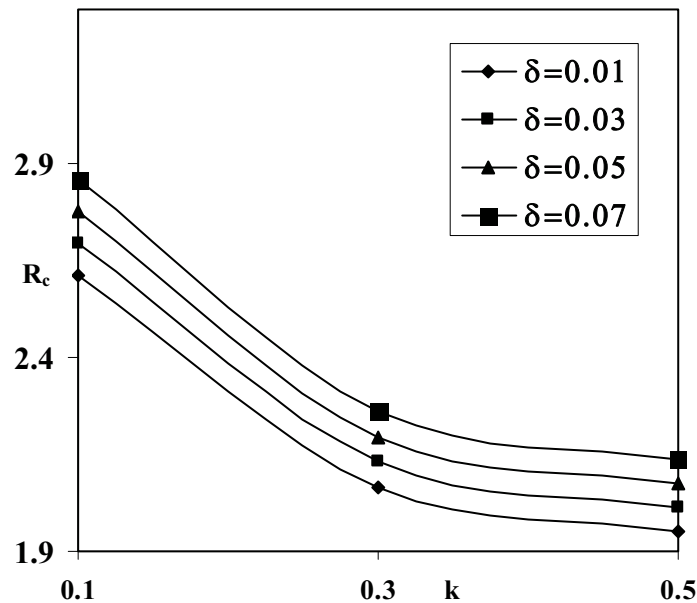


Fig.1. Variation of R_c versus k for different values of δ .

From Fig.2, the critical thermal Rayleigh number variation with respect to the magnetization parameter M_3 for different values of the permeability of the porous medium k indicates that the system destabilizes as the magnetization parameter M_3 increases. This is seen by a decrease in R_c values. A destabilizing trend of k is also seen in this figure.

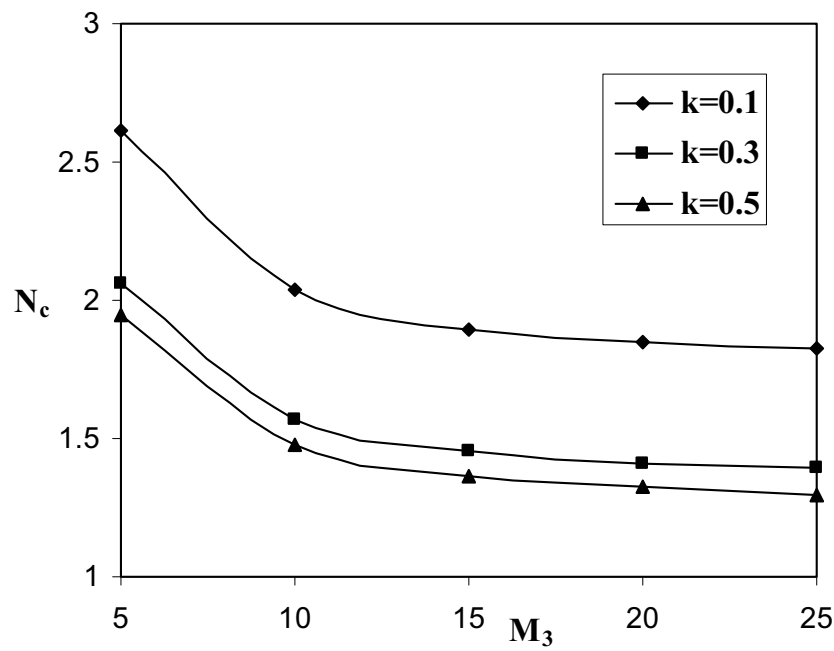


Fig.2. Variation of R_c versus M_3 for different values of k .

It is observed from Figs 3a, 3b and 3c that the Soret parameter S_T stabilizes the system, thereby delaying the onset of convection. All the three graphs exhibit a stabilizing trend. This is due to the fact that the modulation of the salinity gradient by the temperature gradient promotes stabilization. Positive values of S_T stabilize the system more. The destabilizing trend of M_3 and k is also seen from Figs 3a and 3b. A stabilizing behaviour of δ is seen from Fig.3c.

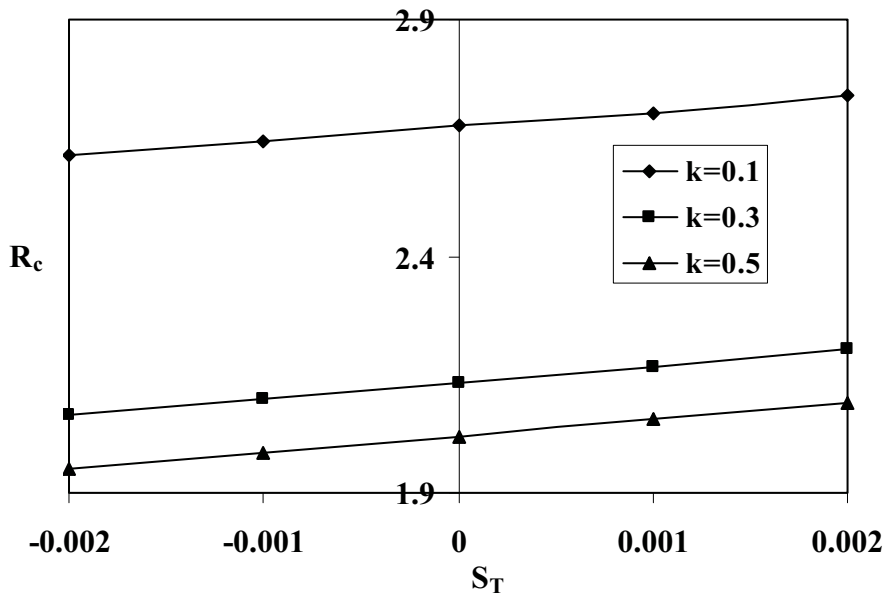


Fig.3a. Variation of R_c versus S_T for different values of k .

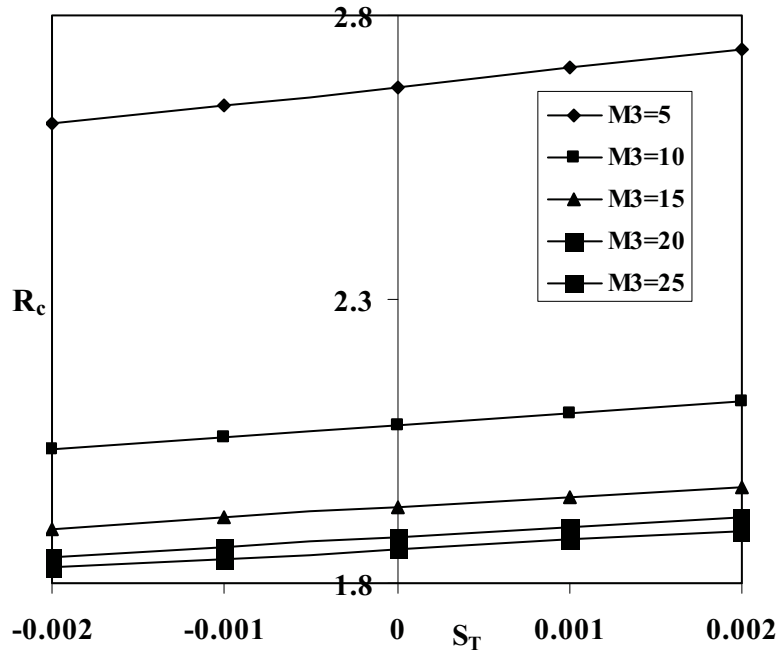


Fig.3b. Variation of R_c versus S_T for different values of M_3 .

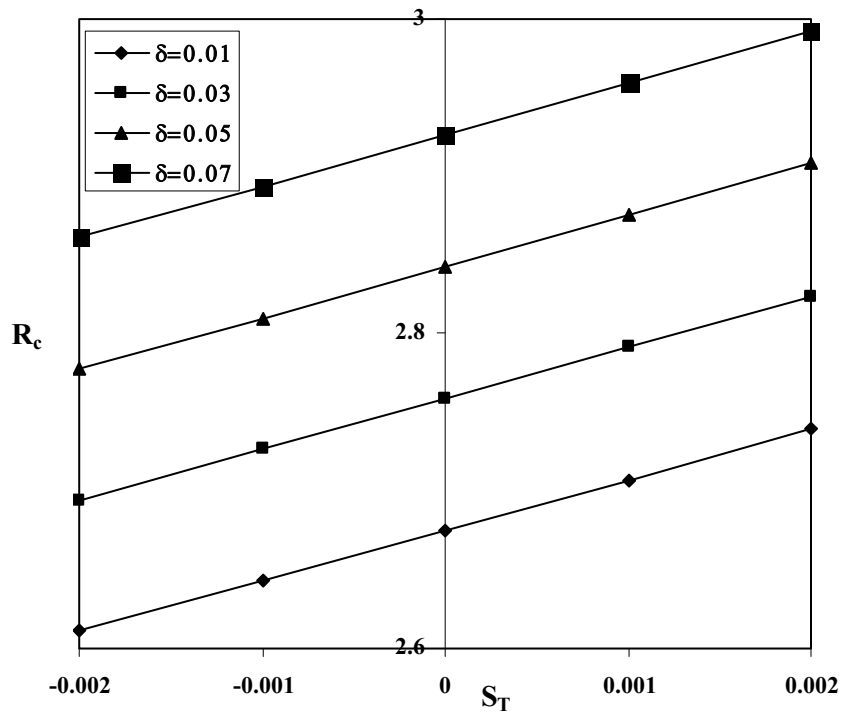


Fig.3c. Variation of R_c versus S_T for different values of δ .

Figures 4a, 4b and 4c analyze the variation of R_c versus $\text{Log}Ta$ for different values of M_3 , k and δ . When $\text{Log}Ta$ increases from 1 to 5, the stabilization is not much pronounced. But when it takes values from 6 to 8, the increase in R_c values is maximum.

Figures 5a and 5b investigate the variation of R_c versus M_3 for different values of δ and R_c versus δ for different values of M_3 . Both figures illustrate that as M_3 increases, the values of R_c decrease for small values of δ , whereas for higher values of δ , R_c decreases for lower values of M_3 , and then increases for higher values of M_3 .

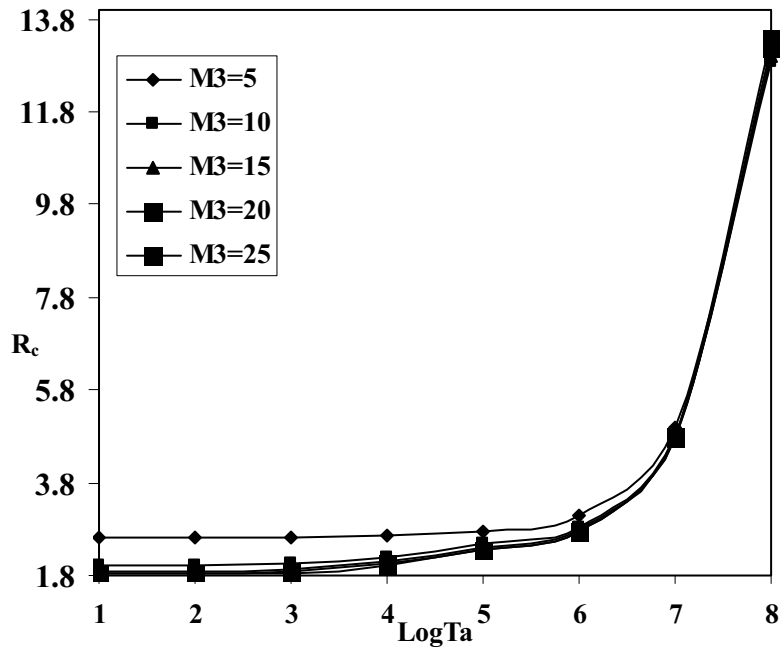


Fig.4a. Variation of R_c versus LogTa for different values of M_3 when $\text{Pr}=0.01$.

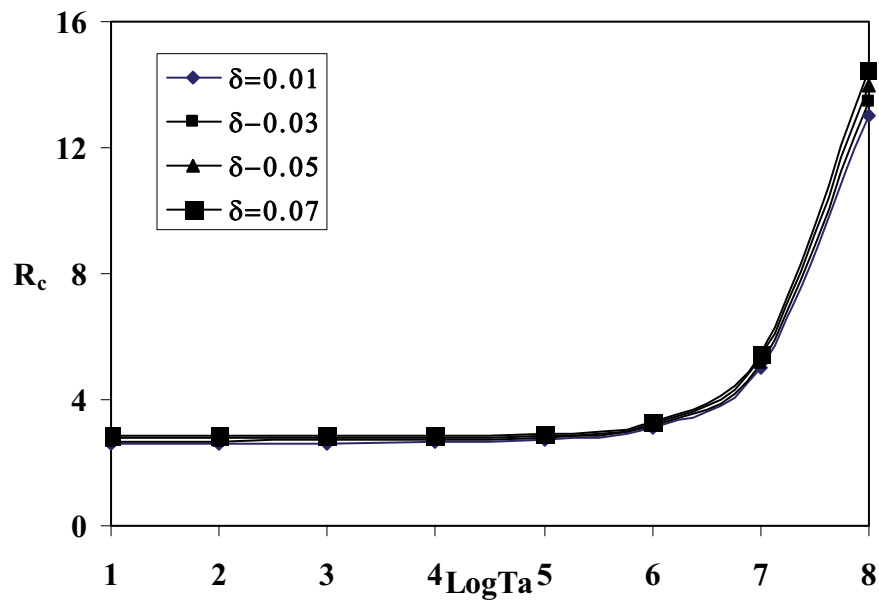


Fig.4b. Variation of R_c versus LogTa for different values of δ .

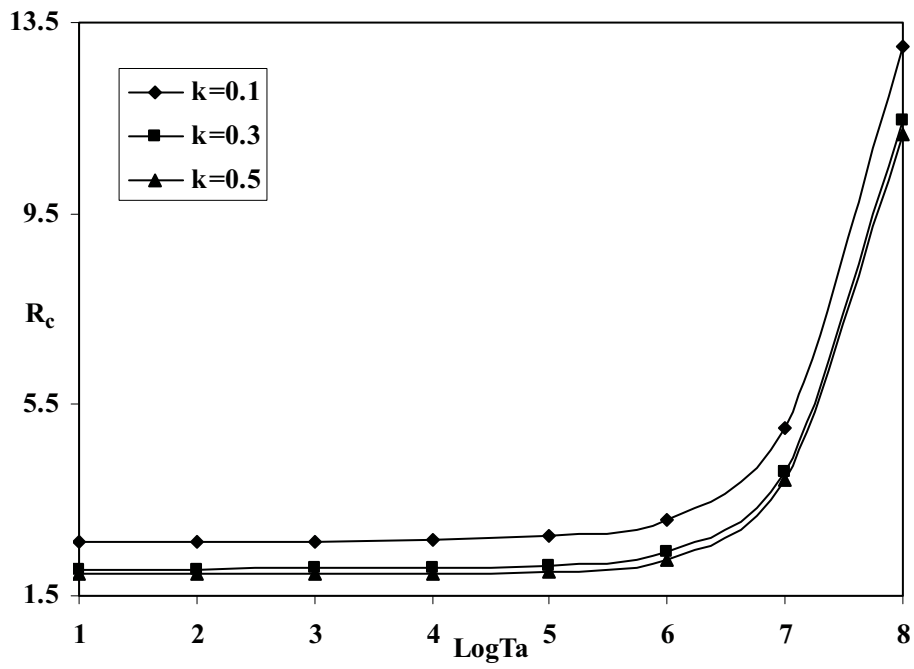


Fig.4c. Variation of R_c versus LogTa for different values of k .

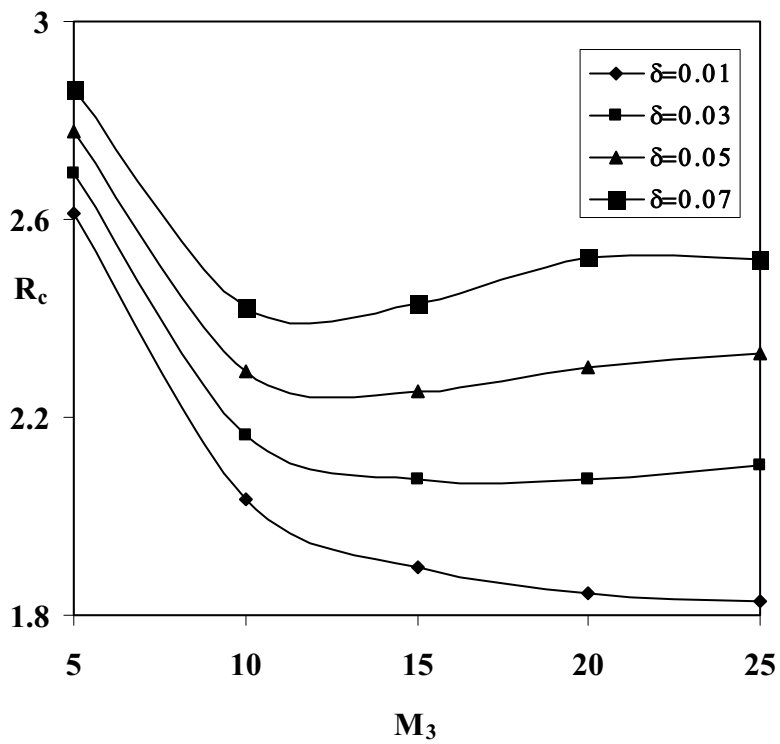


Fig.5a. Variation of R_c versus M_3 for different values of δ .

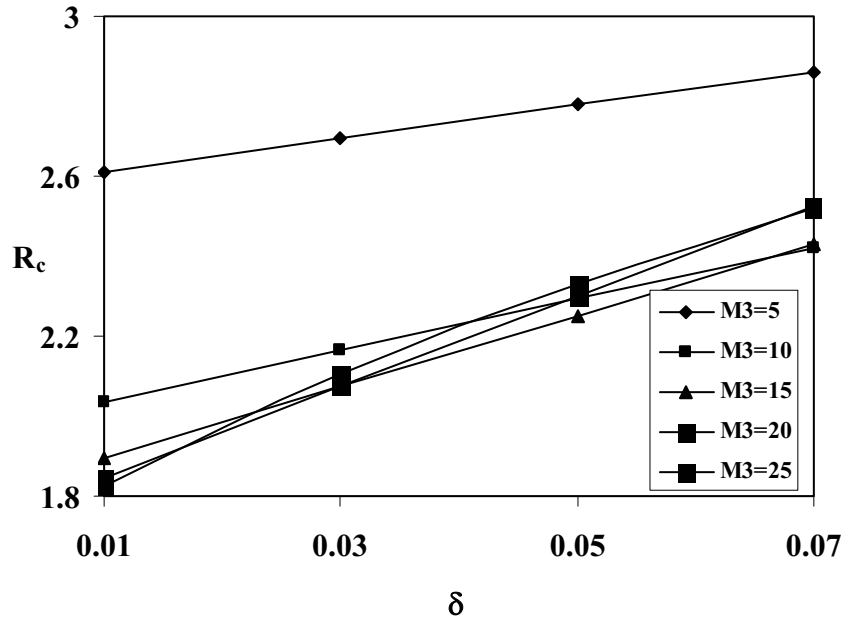


Fig.5b. Variation of R_c versus δ for different values of M_3 .

Figure 6 analyzes the variation of R_c versus δ for different values of Ta . The figure exhibits a stabilizing behaviour. The stabilization is minimal when the Taylor number Ta assumes values from 10 to 10^5 , and then it increases phenomenally. This is indicated by an increase in R_c values.

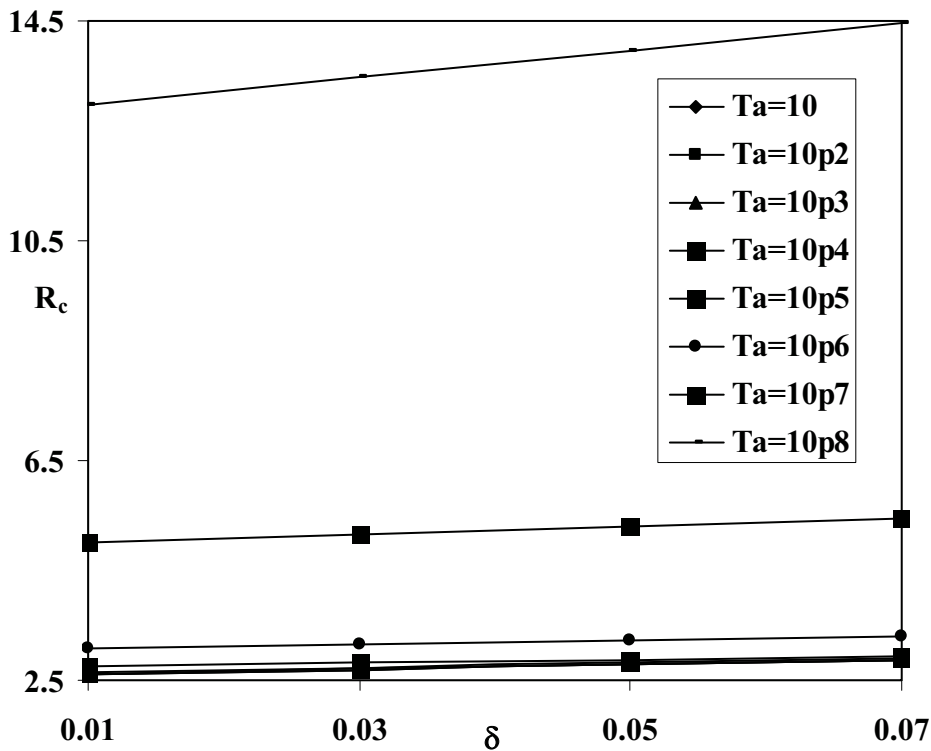


Fig.6. Variation of R_c versus δ for different values of Ta .

In this figures 10^{pn} indicates 10 to the power of n , where $n=2, 3, 4, 5, 6, 7, 8$.

Nomenclature

a	– particle radius m
\mathbf{B}	– magnetic induction T
b	– subscript; basic state
$C_{v,H}$	– specific heat at constant volume and magnetic field $kJm^{-3}K^{-1}$
$D/Dt=(\partial/\partial t+\mathbf{q}\cdot\nabla)$	– the convective derivative s^{-1}
d	– thickness of the ferrofluid layer m
\mathbf{g}	– acceleration due to gravity $\mathbf{g}=(0,0,-g) ms^{-2}$
\mathbf{H}	– magnetic field intensity $Ampm^{-1}$
k	– permeability of porous medium
k_x, k_y	– wave number in the x and y direction m^{-1}
$k_0^2=k_x^2+k_y^2$	– resultant wave number m^{-1}
\mathbf{M}	– magnetization $Ampm^{-1}$
\mathbf{q}	– velocity of the ferrofluid ms^{-1}
$q' = \frac{q'}{\varepsilon}$	– perculatory velocity ms^{-1}
S	– solute concentration kg
T	– temperature K
t	– time s
α_s	– analogous solvent coefficient of expansion K^{-1}
α_t	– coefficient of thermal expansion K^{-1}
β_s	– uniform concentration gradient kgm^{-1}
β_t	– uniform temperature gradient Km^{-1}
μ	– dynamic viscosity $kgm^{-1}s^{-2}$
ρ	– fluid density kgm^{-3}
ρ_0	– mean density of the fluid kgm^{-3}
σ	– growth rate s^{-1}
ϕ	– magnetic potential Amp

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