

Submodular Dictionary Learning for Sparse Coding



1. Overview

• Goal

- Present a supervised algorithm for *efficiently* learning a compact and discriminative dictionary for sparse representation.

• Approach

- A dataset is mapped into an undirected k -nearest neighbor graph $G=(V, E)$. The discriminative dictionary learning is modeled as a graph topology selection problem.
- A *monotonic* and *submodular* objective function for dictionary learning consists of two terms: the entropy rate of a random walk on a graph and a discriminative term.
- The objective function is optimized by a highly efficient greedy algorithm by using the submodularity and monotonic increasing properties of the objective function and the *matroid* constraint.
- This simple greedy algorithm gives a near-optimal solution with a $(1/2)$ -approximation bound [5].

2. Related Work

- Sparse Coding has been successfully applied to a variety of problems in computer vision such as face recognition [1]. The SRC algorithm [1] employs the entire set of training samples to form a dictionary.
- K-SVD [2]: Efficiently learn an over-complete dictionary with a small size. It focuses on representational power, but it does not consider discrimination.
- Discriminative dictionary learning approaches:
 - Constructing a separate dictionary for each class.
 - Adding discriminative terms into the objective function of dictionary learning [3].
- The diminishing return property of a submodular function has been employed in applications such as sensor placement, clustering and superpixel segmentation [4].

3. Preliminaries

• Submodularity

Let E be a finite set. A set function $F: 2^E \rightarrow \mathbb{R}$ is submodular if $F(A \cup \{a_1\}) - F(A) \geq F(A \cup \{a_1, a_2\}) - F(A \cup \{a_2\})$ for all $A \subseteq E$ and $a_1, a_2 \in E \setminus A$. (diminishing returns property)

• Matroid

Let E be a finite set and \mathcal{I} a collection of subsets of E . A matroid is an ordered pair $\mathcal{M} = (E, \mathcal{I})$ satisfying three conditions:
(a) $\emptyset \in \mathcal{I}$; (b) if $A \subseteq B$ and $B \in \mathcal{I}$, then $A \in \mathcal{I}$; (c) if $A \in \mathcal{I}, B \in \mathcal{I}$ and $|A| < |B|$, then there is an element $x \in B - A$ such that $A \cup x \in \mathcal{I}$.

4. Submodular Dictionary Learning

• Monotonic and Submodular Objective Function

- Consists of an entropy rate term $\mathcal{H}(A)$ and a discriminative term $\mathcal{Q}(A)$:

$$\max_A \mathcal{F}(A) = \mathcal{H}(A) + \lambda \mathcal{Q}(A) \text{ s.t. } A \subseteq E \text{ and } N_A \geq K,$$

A : selected subset of edge set E ; N_A : number of connected components induced by A

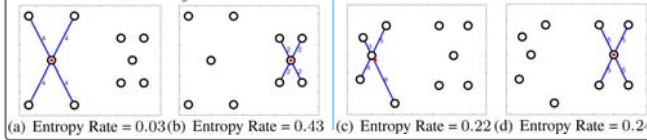
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4. Submodular Dictionary Learning

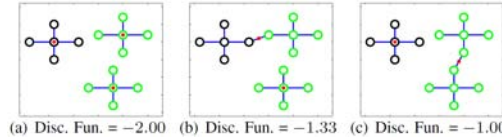
• Entropy Rate of a Random Walk

$$\mathcal{H}(A) = - \sum_i \mu_i \sum_j P_{i,j}(A) \log P_{i,j}(A) \quad \mu_i: \text{Stationary probability of vertex } v_i \\ P_{i,j}: \text{Transition probability from } v_i \text{ to } v_j$$



• Discriminative Term

$$\mathcal{Q}(A) = \frac{1}{C} \sum_{i=1}^N \max_y N_y^i - N_A \quad N_y^i: \text{Number of elements from class } y \text{ in cluster } i$$



• Optimization

- The cycle free constraint and connected component constraint, $N_A \geq K$, induces a matroid $\mathcal{M} = (E, \mathcal{I})$. Dictionary learning is achieved via maximizing a submodular function subject to a matroid constraint: $\max_A \mathcal{F}(A) \text{ s.t. } A \in \mathcal{I}$

Algorithm 1 Submodular Dictionary Learning (SDL)

Input: $G = (V, E)$, w , K , λ and \mathcal{N}
Output: D
 Initialization: $A \leftarrow \emptyset$, $D \leftarrow \emptyset$
for $N_A > K$ **do**
 $\tilde{e} = \operatorname{argmax}_{A \cup \{e\} \in \mathcal{I}} \mathcal{F}(A \cup \{e\}) - \mathcal{F}(A)$
 $A \leftarrow A \cup \{\tilde{e}\}$
end for
for each subgraph S_i in $G = (V, A)$ **do**
 $D \leftarrow D \cup \{\frac{1}{|S_i|} \sum_{j: v_j \in S_i} v_j\}$
end for

• Classification

□ Face and Object recognition

For a test image y , first compute its sparse representation:

$$z_i = \arg \min_z \|y_i - Dz_i\|_2^2 \text{ s.t. } \|z_i\|_0 \leq s$$

Then the label of y_i is the index i corresponding to the largest element of a class label vector $l = Wz_i$.

□ Action Classification

First compute a sparse representations for each frame, then employ dynamic time warping to align two sequences in the sparse representation domain; next a K-NN classifier is used for recognition.



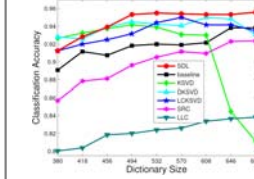
5. Experiments

• Experimental Setup

- **Random face-based features**
- dims: 504 (Extended Yale)
- **Spatial pyramid features**
- 1024 bases
- dims: 3000 (Caltech101)
- **Joint Shape and Motion features**
- dims: 512 (Keck Gesture)

• Extended Yale

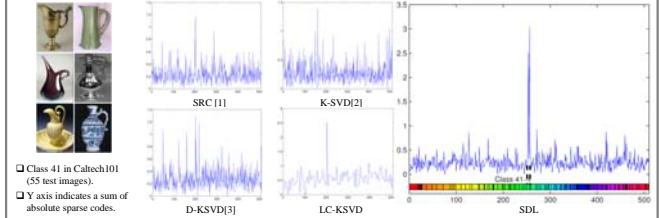
- Classification accuracy comparison



- Computation time (s) for dictionary training

Dict. size	418	456	494	532	570	608	646	684
SRL	0.9	1.0	0.9	0.9	0.9	1.0	0.9	0.9
K-SVD[1]	32.6	56.1	59.8	64.9	67.9	72.2	76.2	78.0
D-KSVD[15]	53.1	56.9	60.5	65.8	68.1	74.9	77.6	79.2
LK-KSVD[12]	67.2	72.6	78.3	86.5	90.7	97.8	104.4	112.3

• Examples of sparse codes



□ Class 41 in Caltech101 (55 test images).

□ Y axis indicates a sum of absolute sparse codes

6. Key References

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