

Submodular Function Minimization

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Submodular Functions and Polyhedra

$$f : 2^V \rightarrow \mathbf{R} \quad f(\emptyset) = 0$$

$$f(X) + f(Y) \geq f(X \cup Y) + f(X \cap Y), \quad \forall X, Y \subseteq V$$

Submodular Polyhedron

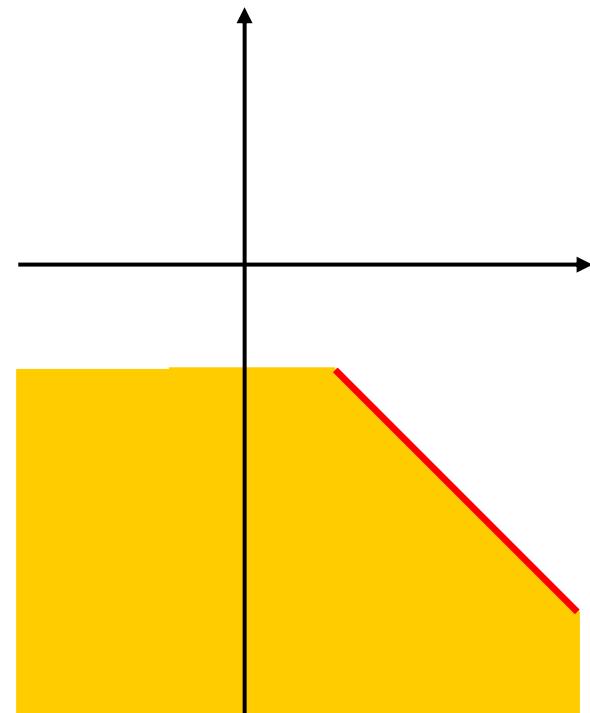
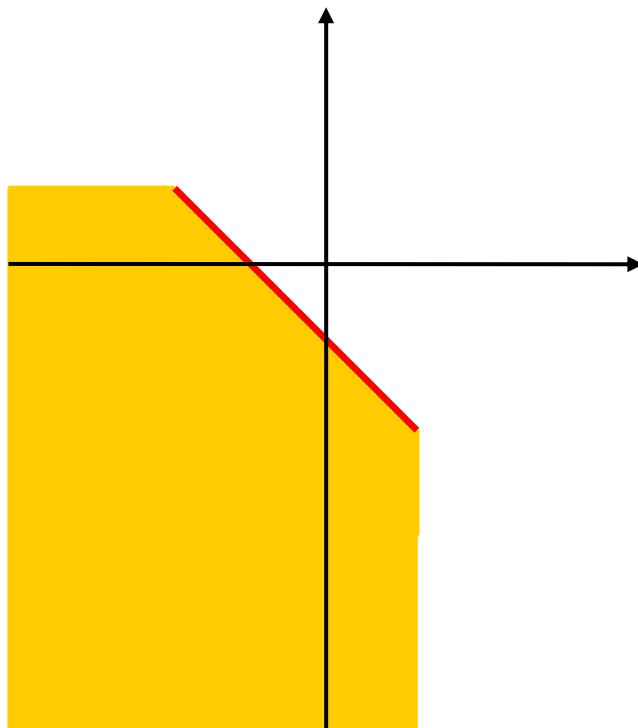
$$P(f) = \{x \mid x \in \mathbf{R}^V, \forall Y \subseteq V, x(Y) \leq f(Y)\}$$

Base Polyhedron

$$B(f) = \{x \mid x \in P(f), x(V) = f(V)\}$$

Combinatorial Approach

$$\min_{Y \subseteq V} f(Y) = \max \{ x^-(V) \mid x \in B(f) \}$$



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Convex Combination

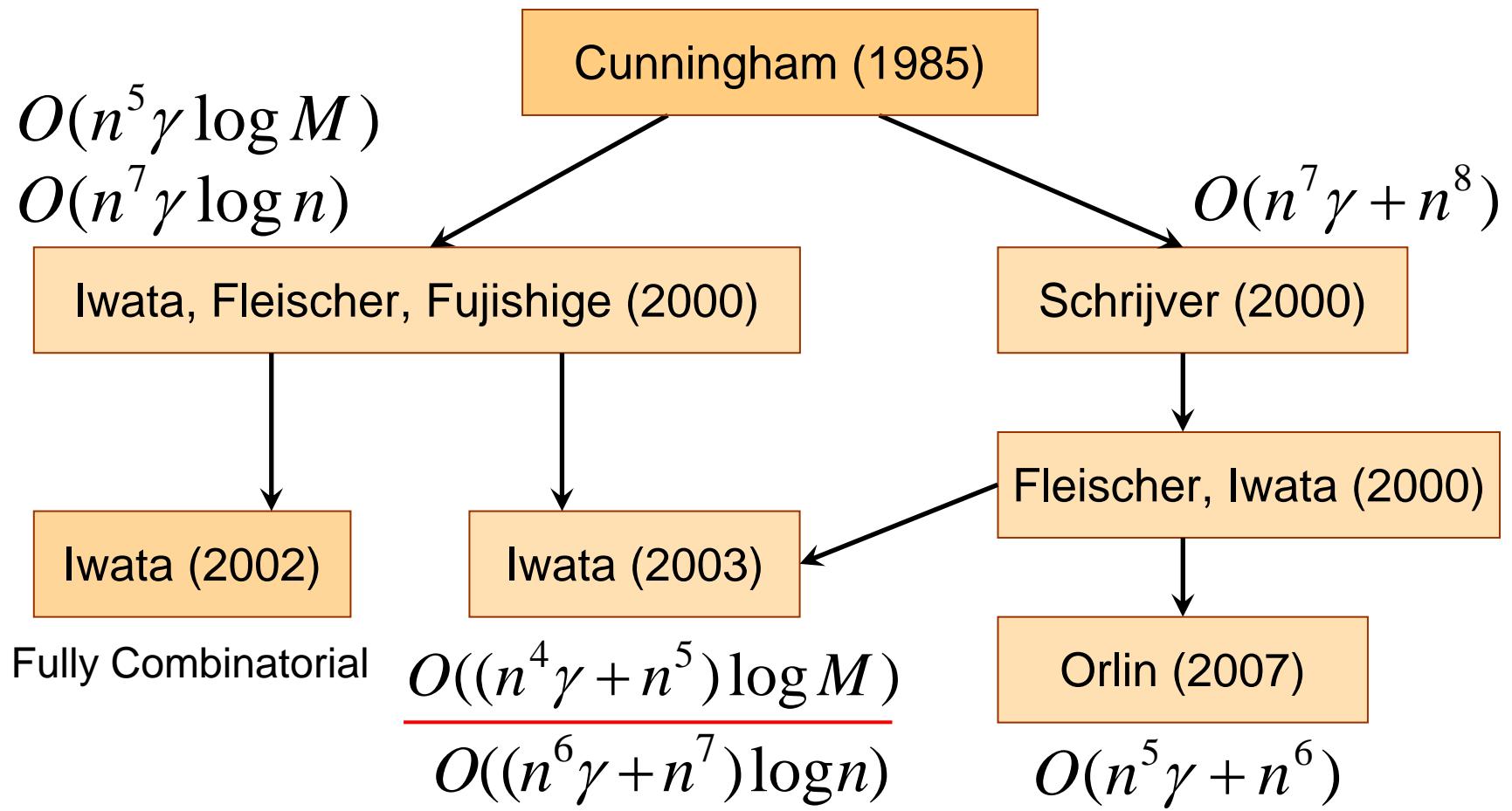
$$x = \sum_{i \in I} \lambda_i y_i$$

$y_i \in B(f)$: Extreme Base Generated by
the Greedy Algorithm with an
Linear Ordering L_i in V .

Submodular Function Minimization

Grötschel, Lovász, Schrijver (1981, 1988)

Ellipsoid Method



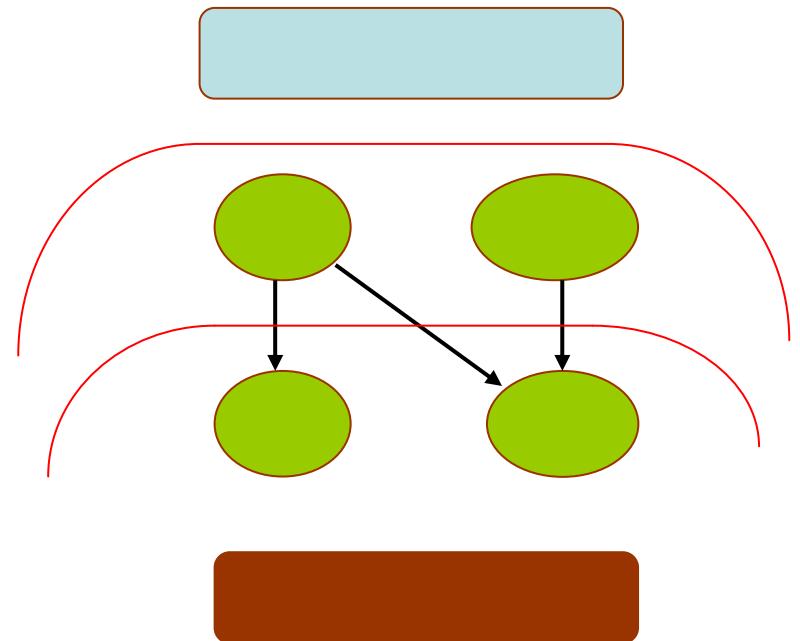
Finding All Minimizers

$X, Y : \text{Minimizer} \rightarrow X \cup Y, X \cap Y : \text{Minimizer}$

The set of minimizers forms a distributive lattice.

[G.Birkhoff]

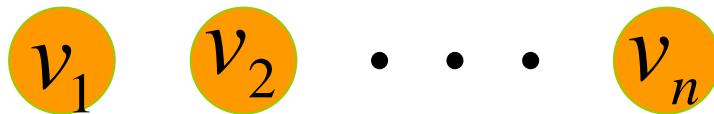
Any distributive lattice can be represented as the set of ideals of a partial ordered set.



Partial Order of an Extreme Base

$y \in B(f)$: Extreme

Bixby, Cunningham, Topkis (1985)



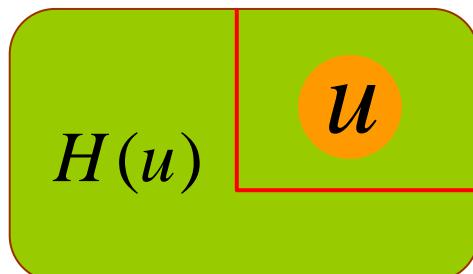
$$y(L(v)) = f(L(v)), \forall v \in V$$

X : Tight $y(X) = f(X)$

Represent all tight sets

$\longrightarrow G(y)$

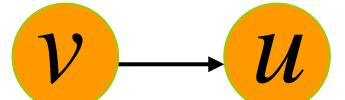
v



$H(u)$: Maximal Ideal Excluding u .

Test if $H(u) \cup \{v\}$ is tight.

If not, then $v \rightarrow u$.



Finding All Minimizers

Extreme Base

$$y_i \in B(f)$$

Partial Order (DAG)

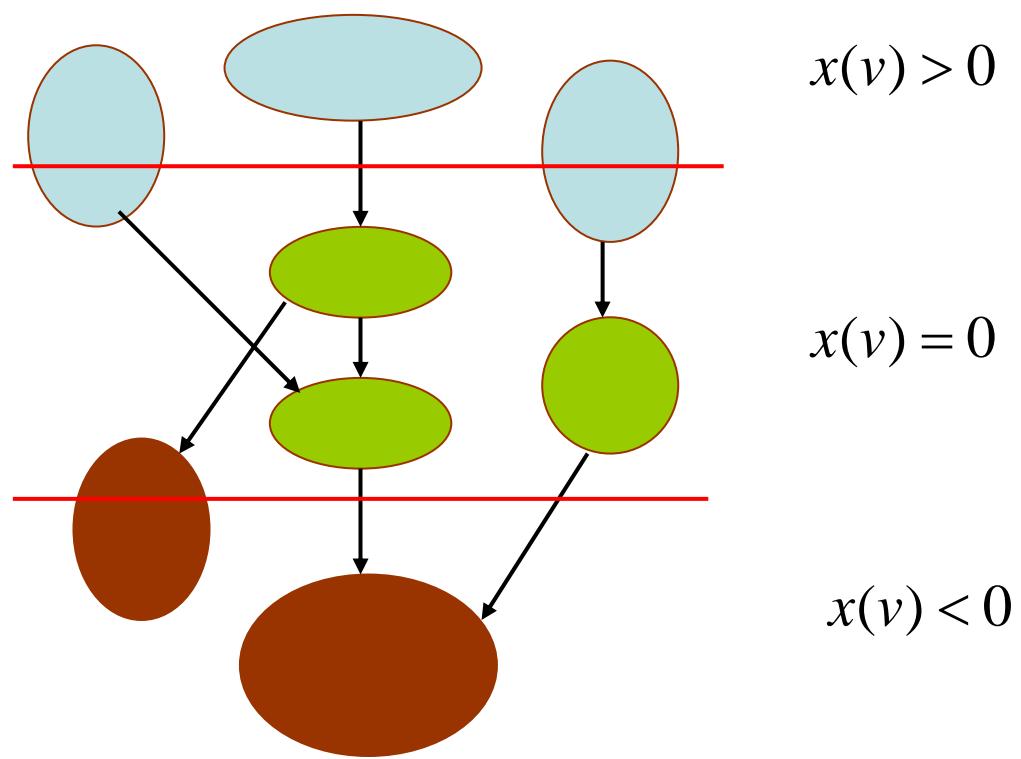
$$G(y_i)$$

Convex Combination

$$x = \sum_{i \in I} \lambda_i y_i$$

$$(\lambda_i > 0, \forall i \in I)$$

$G(x)$: Superposition of $G(y_i)$
SCC Decomposition



Applications

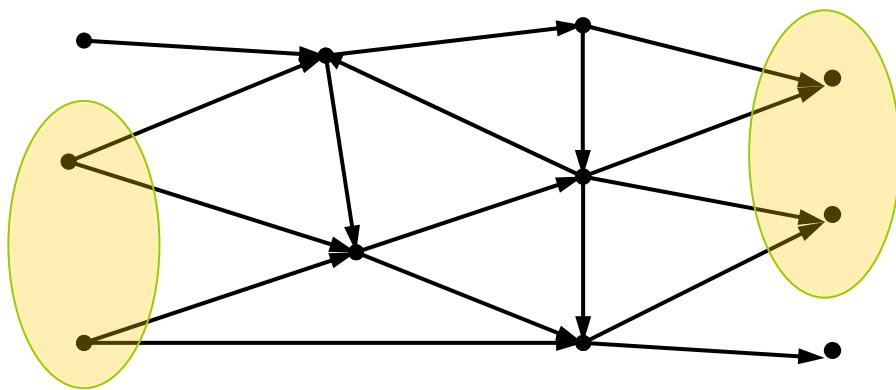
- Evacuation Problem
- Multi-terminal Source Coding
- Multi-class Queueing System
- Constraint Satisfaction Problem
- Potts Model (Anglès d'Auriac, Iglói, Preissmann, Sebő [2002])
- Testing Brach-width
(Oum & Seymour [2007])

Evacuation Problem (Dynamic Flow)

S

T

Hoppe, Tardos (2000)



$c(a)$: Capacity

$\tau(a)$: Transit Time

$b(v)$: Supply/Demand

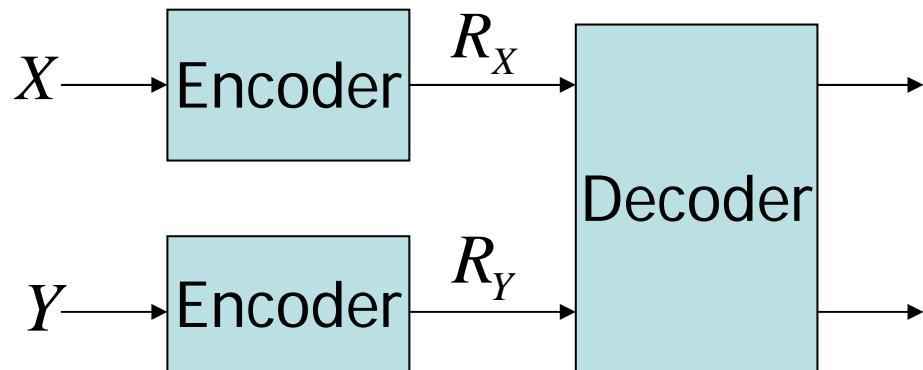
$o(X)$: Maximum Amount of Flow from $X \cap S$ to $T \setminus X$.

Feasible

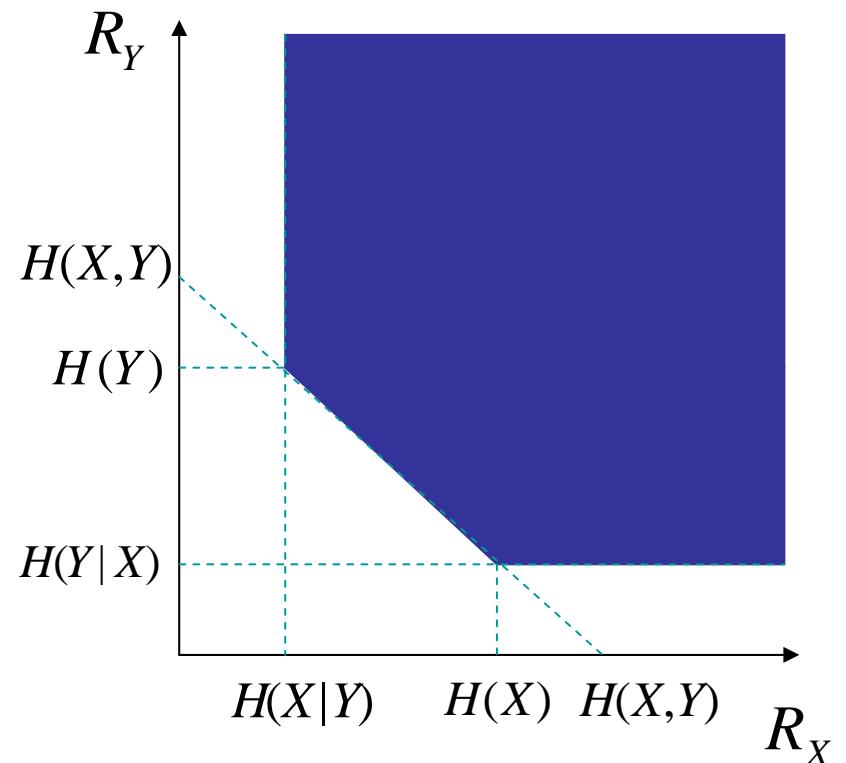


$b(X) \leq o(X), \forall X \subseteq S \cup T$

Multi-terminal Source Coding

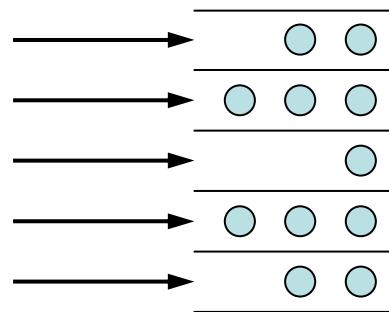


Slepian, Wolf (1973)

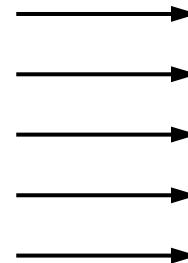


Multi-class Queueing Systems

Arrival Interval



Service Time



Arrival Rate λ_i

μ_i Service Rate

Multiclass M/M/1
Preemptive

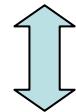
Control Policy

Performance Region

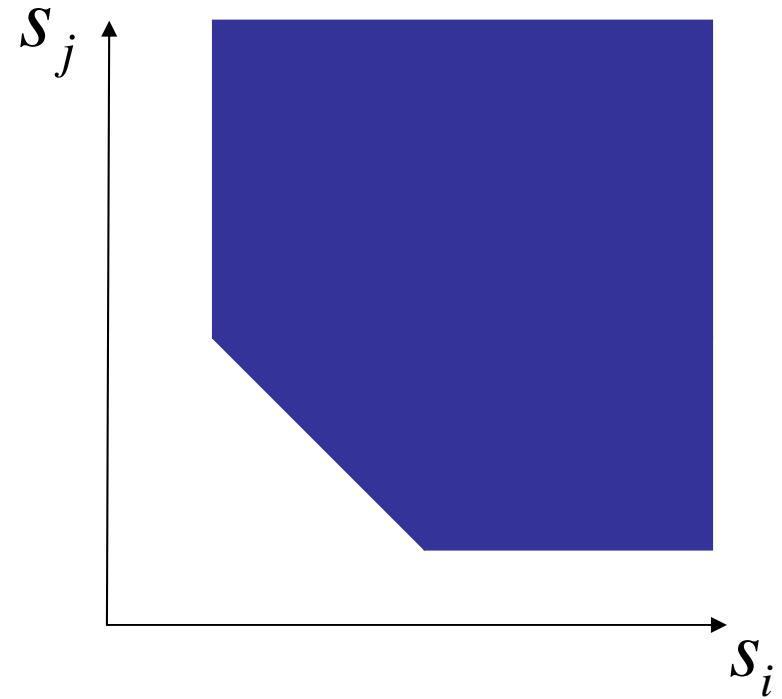
S_j : Expected Staying Time of a Job in j

S : Achievable

$$\rho_i := \lambda_i / \mu_i, \quad \sum_{i \in V} \rho_i < 1$$



$$\sum_{i \in X} \rho_i S_i \geq \frac{\sum_{i \in X} \rho_i / \mu_i}{1 - \sum_{i \in X} \rho_i}, \forall X \subseteq V$$



Coffman, Mitrani (1980)

A Class of Submodular Functions

$$x, y, z \in \mathbf{R}_+^V$$

Itoko & Iwata (2005)

h : Nonnegative, Nondecreasing, Convex

$$f(X) = z(X) - y(X)h(x(X)) \quad (X \subseteq V)$$

Submodular

$$\sum_{i \in X} \rho_i S_i \geq \frac{\sum_{i \in X} \rho_i / \mu_i}{1 - \sum_{i \in X} \rho_i}, \forall X \subseteq V$$

$$\begin{aligned} z_i &:= \rho_i S_i & y_i &:= \frac{\rho_i}{\mu_i} \\ x_i &:= \rho_i & h(x) &:= \frac{1}{1-x} \end{aligned}$$

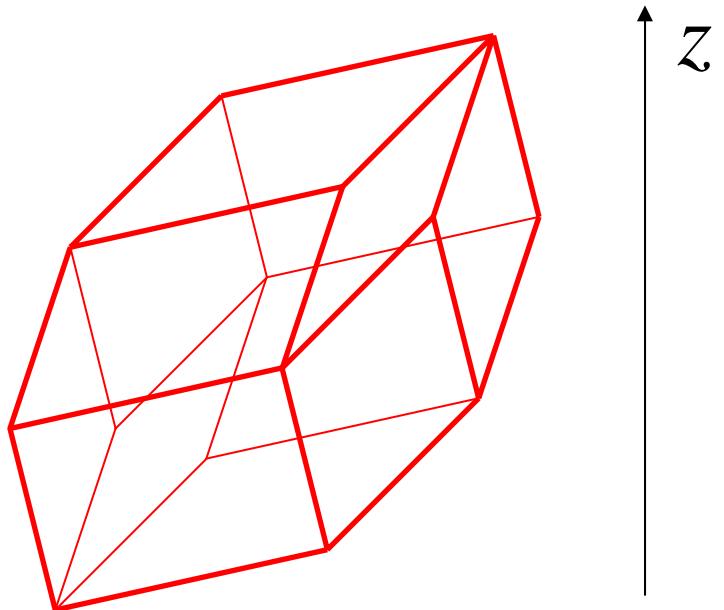
Zonotope in 3D

$$w(X) = (x(X), y(X), z(X))$$

$$Z = \text{conv}\{w(X) \mid X \subseteq V\}$$

Zonotope

$$\tilde{f}(x, y, z) = z - yh(x)$$

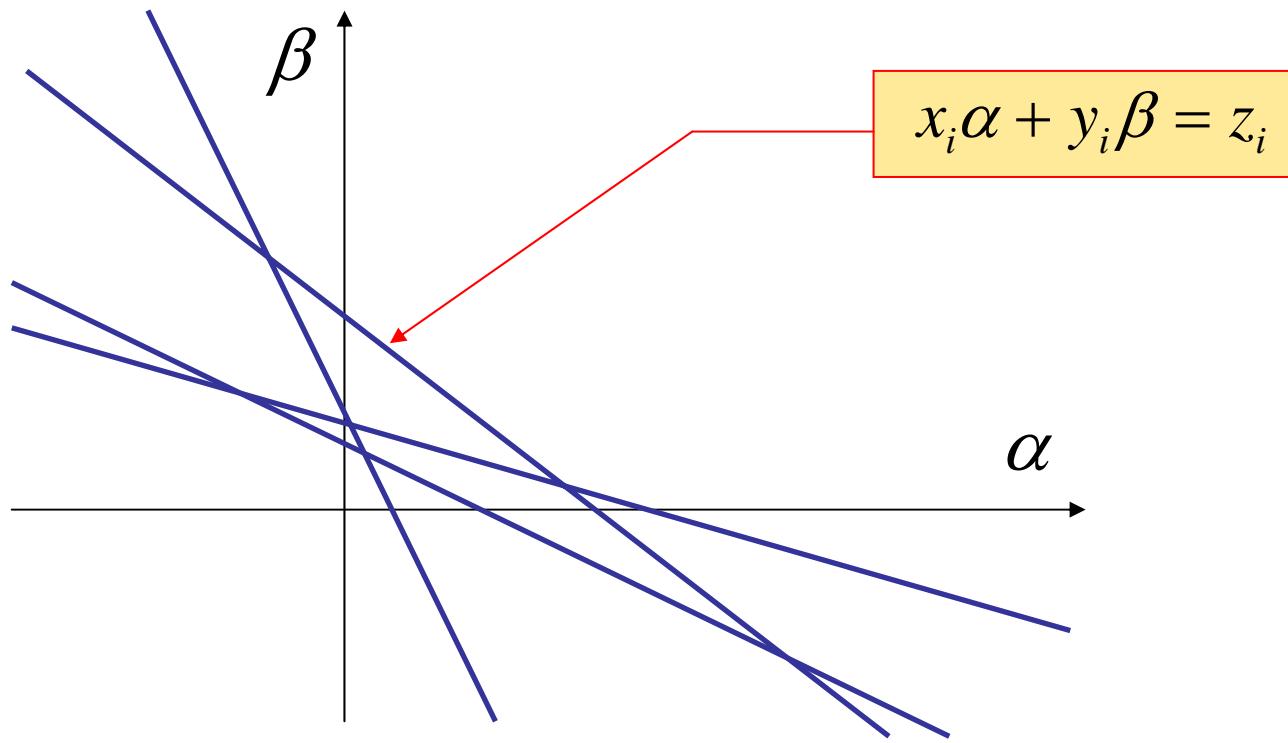


$$\min\{f(X) \mid X \subseteq V\}$$

$$= \min\{\tilde{f}(x, y, z) \mid (x, y, z) : \text{Lower Extreme Point of } Z\}$$

Remark: $\tilde{f}(x, y, z)$ is NOT concave!

Line Arrangement



Enumerating All the Cells

Topological Sweeping Method
Edelsbrunner, Guibas (1989)

$O(n^2)$