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1 **Surface EMG amplitude does not identify differences in neural drive to synergistic**
2 **muscles**

3
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21 **Running Head:**

22 Motor unit size and EMG of synergistic muscles
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29 **Key words**

30 Surface electromyography; Motor unit; amplitude; motor unit action potential; high-density
31 surface EMG: synergistic muscles
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34

35 **ABSTRACT**

36

37 Surface electromyographic (EMG) signal amplitude is typically used to compare the neural
38 drive to muscles. We experimentally investigated this association by studying the motor unit
39 (MU) behavior and action potentials in the vastus medialis (VM) and vastus lateralis (VL)
40 muscles. Eighteen participants performed isometric knee extensions at four target torques
41 [10, 30, 50 and 70% of the maximum torque (MVC)] while high-density EMG signals were
42 recorded from the VM and VL. The absolute EMG amplitude was greater for VM than VL
43 ($p < 0.001$) while the EMG amplitude normalized with respect to MVC was greater for VL
44 than VM ($p < 0.04$). Because differences in EMG amplitude can be due to both differences in
45 the neural drive and in the size of the MU action potentials, we indirectly inferred the neural
46 drives received by the two muscles by estimating the synaptic inputs received by the
47 corresponding motor neuron pools. For this purpose, we analyzed the increase in discharge
48 rate from recruitment to target torque for motor units matched by recruitment threshold in the
49 two muscles. This analysis indicated that the two muscles received similar levels of neural
50 drive. Nonetheless, the size of the MU action potentials was greater for VM than VL
51 ($p < 0.001$) and this difference explained most of the differences in EMG amplitude between
52 the two muscles (~63% of explained variance). These results indicate that EMG amplitude,
53 even following normalization, does not reflect the neural drive to synergistic muscles.
54 Moreover, absolute EMG amplitude is mainly explained by the size of MU action potentials.

55

56 **New and Noteworthy**

57 EMG amplitude is widely used to indirectly compare the strength of neural drive received by
58 synergistic muscles. However, there are no studies validating this approach with motor unit
59 data. Here, we compared between-muscles differences in surface EMG amplitude and motor
60 unit behavior. The results clarify the limitations of surface EMG to interpret differences in
61 neural drive between muscles.

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69 INTRODUCTION

70

71 Surface electromyography (EMG) amplitude depends on the level of muscle activation
72 (number of muscle fiber action potentials) and it is typically used to infer the strength of
73 neural drive (number of motor neuron action potentials) received by muscles (6). Changes in
74 the relative activations of synergistic muscles are believed to be associated to the
75 development of musculoskeletal disorders (19). For example, researchers argue that
76 pathologies such as patellofemoral joint pain and Achilles tendinopathy might occur due to
77 misbalanced activation of the vasti and calf muscles, respectively (17, 19). For patellofemoral
78 joint pain, it is assumed that a greater activation of the vastus lateralis (VL) compared to the
79 vastus medialis (VM) muscle induces a lateral shift of the patella, leading to misalignment of
80 the patellofemoral joint (17, 19). Although these explanations seem plausible, there is still no
81 consensus in the literature (7, 31), mainly because of limitations of surface EMG amplitude in
82 measuring the neural drive (6). While normalization of EMG amplitude with respect to its
83 value during a maximal voluntary contraction (MVC) may increase reliability when
84 comparing between subjects (4), normalization may cancel out changes in muscle activation
85 following, e.g., training interventions. It has been recently shown that high-density EMG
86 (HDEMG) systems provide more reliable estimates of signal amplitude without the need for
87 normalization (14, 34). This is possible due to the large number of observation sites (tens of
88 electrodes) over the muscle belly that compensate for the variability of EMG with electrode
89 location. However, the use of several electrodes does not solve the problem of comparing
90 between muscles and subjects.

91 In addition to the neural drive to the muscle, EMG amplitude estimates are influenced by
92 several other factors, such as muscle architecture, geometry, EMG crosstalk, and
93 subcutaneous tissue thickness (11). Although normalization could help to improve between-
94 muscle amplitude estimates, it is still not known if such measures really reflect differences in
95 neural drive to the muscles. The direct way to access the neural drive to muscles is by motor
96 unit recordings. Recent research has shown the possibility to identify large populations of
97 motor units non-invasively, with HDEMG (25, 27). However, even sampling relatively large
98 numbers of motor units, it is not possible to directly compare the strength of the neural drive
99 to different muscles since the decomposition cannot identify the entire pool of active motor
100 units. Rather, the number of decomposed motor units varies among muscles, with a weak
101 relation with the actual number of active units. For this reason, in this study we propose a
102 way to indirectly infer differences in neural drive between muscles by estimating the synaptic

103 inputs received by their motor neuron pools. Assuming similar intrinsic properties of the
104 motor neurons between the muscles, we analyzed the increase in discharge rate from
105 recruitment to target torque for motor units matched by recruitment threshold in the two
106 muscles. Differences in the increase of discharge rate for motor units with the same
107 recruitment thresholds would indicate differences in synaptic input received by the
108 corresponding motor neurons and therefore differences in the generated neural drive to the
109 muscles. In addition, we estimated the amplitude of the individual motor unit action
110 potentials to examine the associations between interference EMG amplitude and either motor
111 unit action potential size or neural drive. Therefore, the aim of the study was to assess the
112 strengths of neural drives received by VM and VL muscles and investigate their relations
113 with EMG amplitude. We hypothesized that differences in EMG amplitude between VM and
114 VL muscles would be largely determined by the size of the motor unit action potentials
115 (MUAPs) rather than differences in neural drive to the two muscles, and that normalization
116 would not completely compensate for this influence.

117

118 **MATERIALS AND METHODS**

119 Participants

120 Eighteen healthy and physically active men (mean (SD) age: 29 (3) years, height: 178 (6) cm,
121 mass: 79 (9) kg) were recruited. None of the participants reported any history of
122 neuromuscular disorders or previous lower limb surgery. Subjects were asked to avoid any
123 strenuous activity 24 h prior to the measurements. The ethics committee of the Universität
124 Potsdam approved the study (approval number 26/2015), in accordance with the declaration
125 of Helsinki (2004). All participants gave written, informed consent.

126 Experimental protocol

127 The participants performed submaximal and maximal knee extension contractions on an
128 isokinetic dynamometer (CON-TREX MJ, PHYSIOMED, Regensdorf, Switzerland). The
129 isometric knee extensions were exerted with the knee flexed to 90°. After placement of the
130 surface EMG electrodes (see Data acquisition), subjects performed three maximal voluntary
131 contractions (MVC) of knee extension each over a period of 5 s. Each of these trials was
132 separated by 2 min of rest. The highest MVC value served as a reference to define the
133 submaximal torque levels. After 5 min of rest, and following familiarization trials at low
134 torque levels (10 and 30% MVC), subjects performed submaximal isometric knee extension
135 contractions at 10, 30, 50 and 70% MVC in random order. Contractions at 10 and 30% MVC
136 were maintained for 20 s, while the contractions at 50 and 70% MVC were sustained for 15

137 and 10 s respectively. In each trial, the participants received visual feedback of the torque
138 applied by the leg to the dynamometer, which was displayed as a trapezoid (5 s ramps with
139 hold-phase durations as specified above). Each contraction level was performed twice with a
140 rest of 2 min following each contraction.

141 Data Acquisition

142 The surface EMG signals of VM and VL were recorded in monopolar derivation with a two-
143 dimensional adhesive grid (SPES Medica, Salerno, Italy) of 13×5 equally spaced electrodes
144 (1 mm diameter, inter-electrode distance of 8 mm). EMG signals were initially recorded
145 during a brief voluntary contraction during which a linear non-adhesive dry electrode array of
146 8 silver-bar electrodes (1-mm diameter, 5-mm length, 5 mm interelectrode distance; SA 8/5,
147 OT Bioelettronica, Torino, Italy) was moved over the skin to detect the location of the
148 innervation zone and tendon regions (23). After the skin was shaved and cleansed with
149 abrasion and water, the electrode cavities of the grids were filled with conductive paste
150 (SPES Medica, Salerno, Italy). Grids were positioned between the proximal and distal
151 tendons of the VM and VL muscles with the electrode columns (comprising 13 electrodes)
152 oriented along the muscle fibers. Therefore, the VM grid was positioned $\sim 50^\circ$ with respect to
153 a line between the anterior superior iliac spine and the medial side of the patella while the VL
154 grid was positioned $\sim 30^\circ$ with respect to a line between the anterior superior iliac spine and
155 the lateral side of the patella ((1, 22, 24, 25) (Figure 1). Reference electrodes were positioned
156 over the malleoli and patella of the dominant leg.

157 EMG and torque signals were sampled at 2048 Hz and converted to digital data by a 12-bit
158 analogue to digital converter (EMG-USB 2, 256-channel EMG amplifier, OT Bioelettronica,
159 Torino, Italy, 3dB, bandwidth 10-500 Hz). EMG signals were amplified by a factor of 2000,
160 1000, 500, 500 and 500 for the 10, 30, 50, 70 and 100% MVC contractions, respectively.
161 Data were analysed offline using Matlab (The Mathworks Inc., Natick, Massachusetts, USA).
162 The 64-monopolar EMG channels were re-referenced offline to form 59 bipolar channels as
163 the differences between adjacent electrodes in the direction of the muscle fibers.

164 Signal analysis

165 *Motor unit analysis.* The EMG signals recorded during the submaximal isometric
166 contractions (from 10 to 70% MVC) were decomposed offline with a method that has
167 undergone extensive validation (28). The accuracy of the decomposition was tested with the
168 silhouette measure, which was set to ≥ 0.90 (28). The signals were decomposed throughout
169 the whole duration of the submaximal contractions and the discharge times of the identified
170 motor units were converted into binary spike trains. The mean discharge rate and discharge

171 rate variability (coefficient of variation of the inter-spike-interval, CoVisi), were calculated
172 during the stable plateau torque region. Discharge rate at recruitment was calculated using the
173 first six discharges of the motor units (9). The motor unit recruitment threshold was defined
174 as the knee extension torque (%MVC) at the time when the motor unit began discharging
175 action potentials. Discharges that were separated from the next by <33.3 ms or >200 ms (30
176 and 5 Hz, respectively) were discarded from the mean discharge rate and CoVisi calculation
177 since such discharges are usually considered decomposition errors (24). Motor unit
178 conduction velocity (MUCV) was measured from a minimum of three to a maximum of nine
179 double-differential channels (manual selection) (25). Channels that had the clearest
180 propagation of MUAPs, with the highest amplitude in the columns of the grid and a
181 coefficient of correlation between channels ≥ 0.9 , were selected for further analysis. Finally,
182 the amplitude of the MUAPs was calculated as the MUAP RMS averaged over all channels
183 of the grid (MURMS). VM and VL motor units were matched by their recruitment threshold
184 with a tolerance of $\pm 0.5\%$ MVC. The matched motor units were then grouped in four classes,
185 according to their recruitment thresholds ([0-10] % MVC, [10-30] % MVC, [30-50] % MVC,
186 [50-70] % MVC).

187 The discharge rate of motor units with the same recruitment thresholds (i.e., with a difference
188 in threshold <0.5% MVC) in the two muscles was used as a measure to compare the synaptic
189 inputs received by the pools of motor neurons. This measure corresponds to the increase in
190 discharge rate from recruitment to the target torque relative to the increase in torque from the
191 recruitment threshold [target torque (10, 30, 50 and 70% MVC) – recruitment threshold
192 torque]. A difference in the relative rate of increase in discharge rate between motor units in
193 the two muscles indicates differences in synaptic input received by the motor neuron pools of
194 the two muscles. It was then assumed that the neural drive to the muscles depended on the
195 synaptic input.

196 *Interference EMG.* The root mean square values (RMS) obtained from submaximal and
197 maximal contractions, were averaged over all channels of the electrode grid (22). During the
198 submaximal isometric contractions, the RMS was computed from the HDEMG signals in
199 intervals of 1 s. These values were extracted from the stable-torque region of the contractions
200 (e.g., hold-phase of 15 seconds at 50% MVC). RMSs of the maximal (MVC) contractions
201 were analyzed in a time window of 250 ms centered at the peak EMG activity (22). The
202 average conduction velocity (referred in the following as muscle fiber conduction velocity)
203 was calculated from the interference EMG in double differential derivations obtained along
204 the fiber direction (columns of the grid). In order to maximize the accuracy of muscle fiber

205 conduction velocity estimates, three contiguous columns with four to six channels with the
206 highest cross-correlation in propagation were selected (10). Muscle fiber conduction velocity
207 estimation was obtained with a multichannel maximum-likelihood algorithm that was
208 previously shown to provide accurate estimates (standard deviation <0.1 ms) (13).

209 *Amplitude normalization.* Both absolute RMS and MURMS were normalized to the RMS
210 value obtained during the MVC in order to analyze the effects of normalization on
211 submaximal RMS amplitude of the interference EMG (absolute RMS) as well as on MURMS
212 between muscles.

213

214 Statistical Analysis

215 The Shapiro-Wilk test was used to check the normality of all variables. Sphericity was
216 checked by the Mauchly's test and if violated, the Greenhouse-Geisser correction was
217 applied to the degrees of freedom. Statistical significance was set at $p < 0.05$. Results are
218 expressed as mean and standard deviation (SD).

219 EMG (absolute RMS, normalized RMS and muscle fiber conduction velocity) and motor unit
220 variables (MURMS, discharge rate, CoVisi, motor unit conduction velocity and normalized
221 MURMS) were compared between muscles at each torque level with a two-way repeated
222 measures analysis of variance (ANOVA) with factors muscle (VM and VL) and torque (10,
223 30, 50 and 70% MVC). When the repeated measures ANOVA was significant, pairwise
224 comparisons were performed with a Student-Newman-Keuls (SNK) post-hoc test. Linear
225 regression was used to characterize the association for each motor unit between the
226 differences in discharge rate at the target torque (mean discharge rate at 10, 30, 50 and 70%
227 MVC) and at recruitment (calculated from the first 6 motor unit discharges) and between the
228 target torque (10, 30, 50 and 70% MVC) and motor unit recruitment threshold. The slopes of
229 these linear regressions were compared between the two muscles by analysis of covariance
230 (ANCOVA) (35). The same analysis was applied to VM and VL MURMS vs. recruitment
231 threshold.

232 Finally, a multiple linear regression (stepwise) analysis was performed on EMG/motor unit
233 parameters to identify the variables that predicted the differences between VM and VL
234 absolute RMS. Therefore, the percent (%) difference in absolute RMS between VM and VL
235 was used as the predictor variable and the % differences in MU behavior/properties were
236 regarded as independent variables. Each torque level was analyzed independently (e.g.
237 absolute RMS % difference between VM and VL at 30% MVC was compared with motor
238 unit variables obtained at the same torque level). The partial eta-squared (η^2) for ANOVA

239 was used to examine the effect size of the differences between EMG and motor unit
240 parameters between muscles. A η^2 less than 0.06 was classified as “small”, 0.07-0.14 as
241 “moderate”, and greater than 0.14 as “large” (5).

242

243 **RESULTS**

244

245 Interference EMG

246 Absolute RMS (Figure 2a) was significantly greater for VM than VL at 30, 50 and 70%
247 MVC (interaction: muscle-torque, $p < 0.0001$, $\eta^2 = 0.79$). However, muscle fiber conduction
248 velocity (Figure 2b) was similar for the two muscles (interaction: muscle-torque, $p = 0.96$,
249 $\eta^2 = 0.019$).

250

251 Decomposed motor unit populations

252 The average number of motor units accurately identified (with a $SIL \geq 0.90$) per subject at
253 each torque level was 8 (0.7) and 7 (1.2) in VM and VL, respectively.

254 According to their recruitment threshold, 340 motor units were matched between VM and
255 VL. Per subject, an average of 6.2 (3.0), 5.0 (2.5), 5.7 (2.8) and 3.3 (2.0) motor units were
256 matched between VM and VL at 10, 30, 50 and 70% MVC, respectively. The average
257 recruitment threshold of the matched motor units at 10, 30, 50 and 70% MVC was 7.5, 23.3,
258 38.2 and 56.2% MVC, respectively. Figure 3 shows the histograms of the number of matched
259 motor units according to their recruitment thresholds.

260

261 Discharge rate and discharge rate variability

262 The mean motor unit discharge rate (at target torque) of VM was greater than for VL motor
263 units as revealed by a significant effect of muscle ($p = 0.009$, $\eta^2 = 0.38$) (Figure 4). However,
264 the regression lines of delta discharge rate [mean discharge rate at target torque – discharge
265 rate at recruitment] vs. delta torque [target torque – recruitment threshold] were not different
266 between muscles (slope of the regression lines, $p > 0.35$, intercepts, $p > 0.08$) at all target
267 torques (10, 30, 50 and 70% MVC) (Figure 5). Finally, there was no difference in discharge
268 rate variability between muscles as CoVisi (Figure 6) remained similar at all torque levels
269 (interaction: muscle-torque, $p = 0.4$, $\eta^2 = 0.07$).

270

271 Size and conduction velocity of MUAPs

272 MURMS (Figure 7a) was significantly greater for VM than VL at 30, 50 and 70% MVC
273 (interaction: muscle-torque, $p<0.0001$, $\eta^2=0.57$). Moreover, MURMS increased at a greater
274 rate with recruitment threshold for VM than for VL ($p<0.0001$, Figure 7b). Motor unit
275 conduction velocity (Figure 8) was significantly higher at 70% MVC for VM than VL
276 (interaction: muscle-torque, $p=0.023$, $\eta^2=0.46$).

277

278 Multiple linear regression

279 Motor unit variables that significantly differed between muscles were entered into the
280 multiple linear regression analysis to explain the differences in absolute EMG amplitude
281 between muscles. Therefore, the difference (%) in VM-VL MURMS, discharge rate, and
282 motor unit conduction velocity were regarded as independent variables. Table 1 reports the
283 results of the multiple regression. At 10% MVC, only MURMS was entered in the model,
284 explaining 71% of the variance for the difference (%) in VM-VL absolute RMS. At 30%,
285 both MURMS and discharge rate entered in the model, however MURMS explained most of
286 the variance (53% MURMS vs. 13.2% for discharge rate). Similar results were obtained at
287 50% MVC where MURMS explained 72% of the difference between VM-VL absolute RMS,
288 with discharge rate only explaining 7.7% of the variance. Finally, at 70% MVC, only
289 MURMS was entered in the model, explaining 57% of the %difference in VM-VL absolute
290 RMS.

291

292 Normalized amplitude

293 Normalized RMS (Figure 9) showed systematically higher values for VL across all torque
294 levels (effect: muscle, $p=0.039$, $\eta^2=0.23$). Conversely, normalized MURMS did not show
295 any difference between muscles at any torque level (effect: muscle, $p=0.46$, $\eta^2=0.04$,
296 interaction: torque-muscle, $p=0.12$, $\eta^2=0.11$).

297

298 DISCUSSION

299

300 This study shows that differences in EMG amplitude between synergistic muscles are mostly
301 explained by differences in MUAP size (MURMS), with little influence of other motor unit
302 properties. Moreover, EMG normalization does not provide clear explanation of differences
303 in muscle activation between the vasti. The observed differences in EMG amplitude between
304 muscles (in absolute values or normalized) contrasted with the similar neural drive estimated
305 for VM and VL. Taken together, the results suggest that EMG amplitude (in absolute values

306 or normalized) should not be used to infer differences in neural drive between synergistic
307 muscles.

308

309 Neural drive to VM and VL muscles

310 Due to current limitations in EMG decomposition, it is not possible to identify the full
311 populations of active motor units. For this reason, the neural drives cannot be directly
312 compared between muscles. We compensated for this limitation by an indirect assessment of
313 the strength of the neural drive. Matching synergistic muscles motor units by recruitment
314 threshold allows a direct comparison of motor unit discharge rates across muscles. Because
315 the discharge rate depends on the torque relative to the recruitment threshold, we focused on
316 the rate of change in discharge rate (mean discharge rate at target torque – discharge rate at
317 recruitment) with respect to the difference between exerted torque (10, 30, 50 or 70% MVC)
318 and recruitment threshold across the decomposed motor unit populations. This analysis
319 provides an estimate of the synaptic input received by the motor neuron pools of VM and VL,
320 since discharge rates indicate the nonlinear transformation of synaptic inputs into motor
321 neuron outputs (20). This approach indicated a similar change in motor unit discharge rate
322 with torque (figure 5) despite a difference in absolute discharge rates that can be due to the
323 random sampling of motor units in the two muscles (Figure 4). This suggests that the net
324 excitatory synaptic input to the pool of motor neurons of the vasti was similar. Assuming that
325 the intrinsic properties of the motor neuron pools in the two muscles were similar, this
326 observation was interpreted as reflecting similar drives from the motor neurons to the muscle
327 units. This conclusion is in agreement with a previous study that showed that VM and VL
328 share most of their synaptic input (21).

329 We also did not observe differences in discharge rate variability (CoVisi) between the two
330 muscles (Figure 6), in agreement with previous results (34). The present results show that,
331 despite a difference in mean absolute discharge rates between motor units of the VM and VL,
332 the two muscles did receive similar strengths of neural drives. Differences in VM and VL
333 surface EMG amplitude therefore do not reflect differences in the neural drive between the
334 vasti, as also confirmed by the multiple regression analysis.

335

336 EMG amplitude and muscle fiber conduction velocity

337 Surface EMG amplitude is commonly used to infer the magnitude of the neural drive to
338 muscles. However, EMG amplitude depends on both motor unit behavior (recruitment,
339 discharge rate and discharge rate variability) and muscle fiber properties (MUAP size and

340 conduction velocity) (11, 12). In this study, despite similar neural drives to the VM and VL,
341 the EMG amplitude for VM was significantly greater than for VL for torques in the range
342 30%-70% MVC (Figure 7). These results are consistent with other reports on absolute EMG
343 amplitude for these two muscles (15, 22, 34). EMG amplitude is influenced by muscle's
344 geometry, architecture, crosstalk and subcutaneous tissue thickness (11, 29). Since the
345 observed differences in EMG amplitude between muscles did not correspond to differences in
346 neural drive, they are mainly explained by these anatomical factors, as confirmed by the
347 differences in MUAP sizes. Although previous research has reported similar subcutaneous
348 tissue thickness for the distal VM and VL (3), it has also been shown that the distal VM has a
349 larger cross sectional area and greater fascicle angle compared to the distal VL (2). Indeed,
350 recent research has shown that differences in muscle architecture can influence EMG
351 amplitude, even when the muscle is activated at a similar intensity (32).

352 Muscle fiber conduction velocity estimated from the interference EMG was similar between
353 the vasti, in agreement with previous studies (3). However, motor unit conduction velocity
354 differed between muscles. Muscle fiber conduction velocity is associated to fiber diameter
355 (16) but also depends on the level of muscle acidosis (30), temperature (8), muscle
356 fatigability (23), subcutaneous tissue thickness (33), exercise training (25, 33), discharge rate
357 (26). Because of these factors of influence, the relation between average and motor unit
358 muscle fiber conduction velocity is not exactly linear.

359

360 EMG amplitude and MUAP size

361 As for absolute EMG amplitude, the size of MUAPs was significantly greater for VM in the
362 range of torques above or equal to 30% MVC. Moreover, MURMS increased at a faster rate
363 with recruitment threshold for VM than VL (Figure 7). This is consistent with a recent report
364 comparing VM and VL MUAP peak-to-peak amplitude (24). As for EMG amplitude,
365 MURMS is also influenced by muscle's geometry, architecture and subcutaneous tissue
366 thickness (11, 29); therefore it is not surprising to find similar results for absolute RMS and
367 MURMS. Accordingly, results from the multiple linear regression (Table 1) showed that
368 most of the variance of the difference between absolute RMS of VM and VL was explained
369 by MURMS. This result directly indicates that the neural drive has a relatively small
370 influence on EMG amplitude with respect to the MUAP waveforms.

371

372 Amplitude normalization

373 Since a vast number of studies apply normalization of the surface EMG prior to comparing
374 levels of muscle activations (4, 17), we analyzed the effect of normalization of both EMG
375 amplitude and MUAP size with respect to MVC. Even though normalization decreased the
376 VM/VL activation ratio and cancelled out the differences in MUAP size between muscles,
377 normalized EMG amplitude was greater for VL compared to VM that is contrary to the result
378 without normalization. This result does not correspond to the estimated similar neural drive to
379 the two muscles (figure 5) and explains the divergent results across studies on normalized
380 activations of the VM and VL in healthy subjects (31) and patients with musculoskeletal
381 disorders (e.g. patellofemoral pain syndrome) (18). Taken together, our findings suggest that
382 neither absolute nor normalized EMG amplitude (even when recorded from HDEMG
383 electrodes) are appropriate for inferring differences in neural drive between muscles.

384

385 Conclusion

386 The difference in surface EMG amplitude between VM and VL muscles was mostly
387 explained by differences in MUAP size, with little effect of motor unit properties associated
388 to the neural drive to muscles. EMG amplitude is therefore mainly determined by peripheral
389 properties rather than by the neural activation. Normalization of the EMG compensates for
390 the differences in MUAP sizes but is still a poor determinant of neural activation.

391

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491

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512 **Figure captions**

513

514 Figure 1. Placement of the HDEMG electrodes. Vastus medialis (VM) electrode grid was
515 placed $\sim 50^\circ$ with respect to a line between the anterior superior iliac spine and the medial side
516 of the patella (dashed lines, left) while the VL grid was positioned $\sim 30^\circ$ with respect to a line
517 between the anterior superior iliac spine and the lateral side of the patella (dashed lines,
518 right).

519

520 Figure 2. Interference EMG parameters [mean (SD)] for vastus medialis (VM, white dots)
521 and vastus lateralis (VL, black dots) at 10, 30, 50 and 70% of the maximum voluntary
522 contraction torque (MVC). A) Absolute root mean square (ABS RMS). B) Muscle fiber
523 conduction velocity. Presented values were averaged for each subject and presented at each
524 submaximal target torque. * $P < 0.001$.

525

526 Figure 3. Two subsets of motor units identified from the vastus medialis and lateralis muscles
527 were matched for recruitment threshold. The histograms of the motor unit recruitment
528 thresholds in these subsets are shown for the vastus medialis (left) and vastus lateralis (right)
529 motor units.

530

531 Figure 4. Motor unit (MU) average discharge rate (target torque discharge rate) calculated
532 from recruitment-threshold matched MUs from vastus medialis (VM, white dots) and vastus
533 lateralis (VL, black dots) at 10, 30, 50 and 70% of the maximum voluntary contraction torque
534 (MVC). MU discharge rate values [mean (SD)] were averaged for each subject and presented

535 at each submaximal target torque (10, 30, 50 and 70% MVC), # main effect of muscle
536 $P=0.009$.

537

538 Figure 5. Linear regression analysis of the difference between VM and VL mean discharge
539 rate at target torque and discharge rate at recruitment (Y-axis) and the difference between
540 target torque (10, 30, 50 and 70% MVC) and MU recruitment threshold (X-axis) at 10%
541 (upper left), 30% (upper right), 50% (lower left) and 70% (lower right) of the MVC torque.
542 Linear regression equations are shown in the figure. All regression lines had positive slopes
543 ($P<0.03$) and their R^2 values were 0.1 and 0.15 (10% MVC), 0.16 and 0.08 (30% MVC), 0.05
544 and 0.05 (50% MVC), and 0.17 and 0.14 (70% MVC) for VM and VL respectively. None of
545 the regression lines (slopes and intercepts) differed significantly between muscles ($p>0.09$).
546 DR, discharge rate.

547

548 Figure 6. Motor unit (MU) coefficient of variation of the inter-spike interval (CoVisi)
549 calculated from recruitment-threshold matched MUs from vastus medialis (VM, white dots)
550 and vastus lateralis (VL, black dots) at 10, 30, 50 and 70% of the maximum voluntary
551 contraction torque (MVC). Presented values were averaged for each subject and presented at
552 each submaximal target torque.

553

554 Figure 7. Motor unit (MU) root mean square amplitude (MURMS) [mean (SD)] extracted
555 from recruitment-threshold matched MUs from vastus medialis (VM, white dots) and vastus
556 lateralis (VL, black dots) at 10, 30, 50 and 70% of the maximum voluntary contraction torque
557 (MVC). A) MURMS values [mean (SD)] were averaged for each subject and presented at
558 each submaximal target torque (10, 30, 50 and 70% MVC), * $P<0.01$. B) VM and VL
559 MURMS vs. recruitment threshold regression lines. Both lines increased significantly with
560 torque ($P<0.0001$) and displayed significantly different slopes ($P<0.0001$); R^2 values are
561 shown in the figure.

562

563 Figure 8. Motor unit (MU) conduction velocity [mean (SD)] extracted from recruitment-
564 threshold matched MUs from vastus medialis (VM, white dots) and vastus lateralis (VL,
565 black dots) at 10, 30, 50 and 70% of the maximum voluntary contraction torque (MVC).
566 Presented values were averaged for each subject and presented at each submaximal target
567 torque. * $P<0.01$.

568

569 Figure 9. Normalized EMG and motor unit (MU) amplitude [mean (SD)] for vastus medialis
570 (VM, white dots) and vastus lateralis (VL, black dots) at 10, 30, 50 and 70% of the maximum
571 voluntary contraction torque (MVC). A) Normalized root mean square EMG (EMG RMS
572 NORM), B) Normalized MU root mean square (MURMS NORM). # Main effect of muscle
573 P=0.039.

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Figure 1

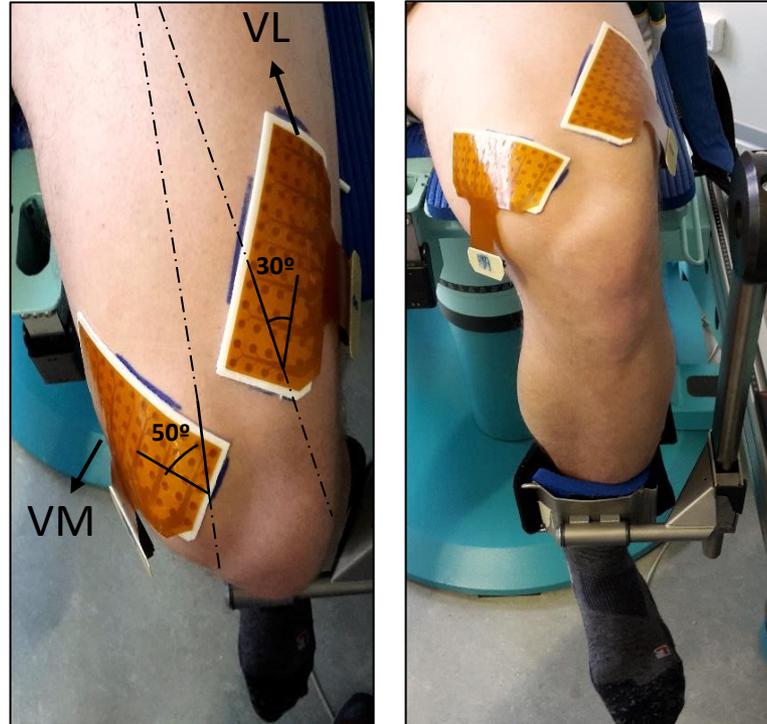
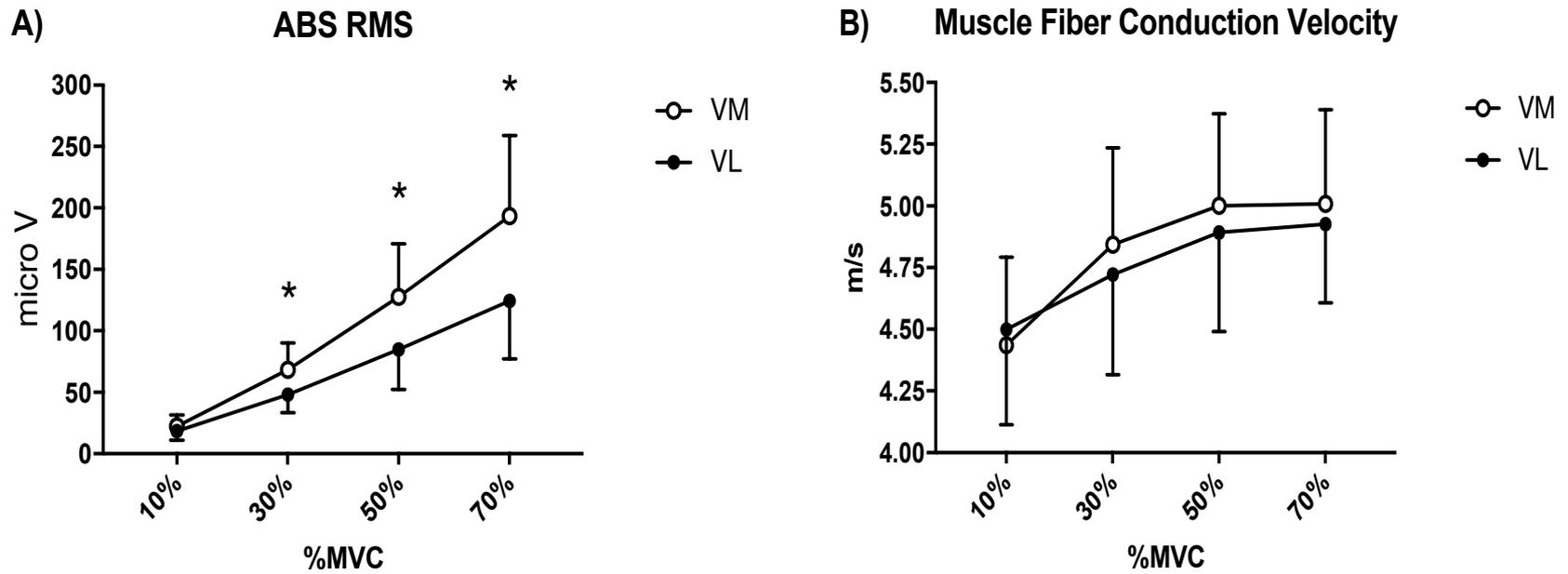
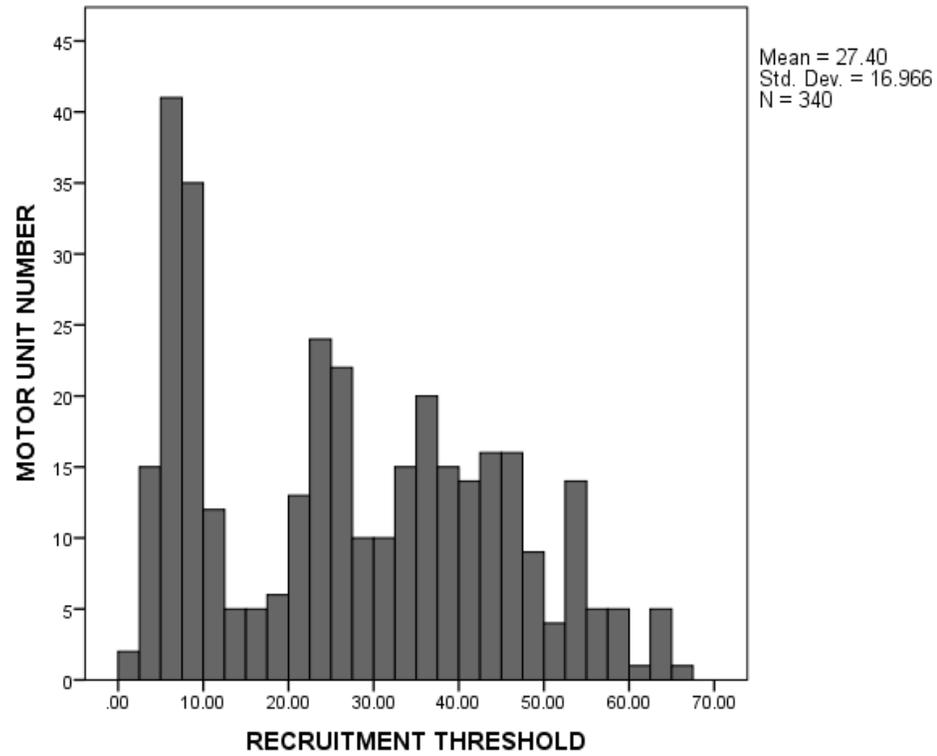


Figure 2



Vastus Medialis



Vastus Lateralis

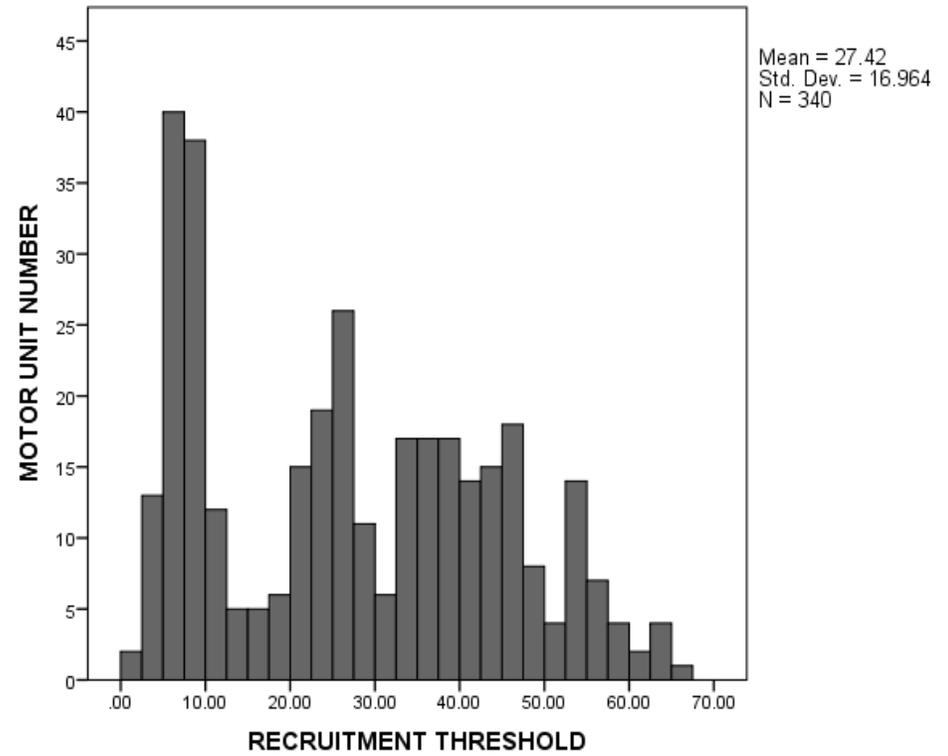


Figure 4

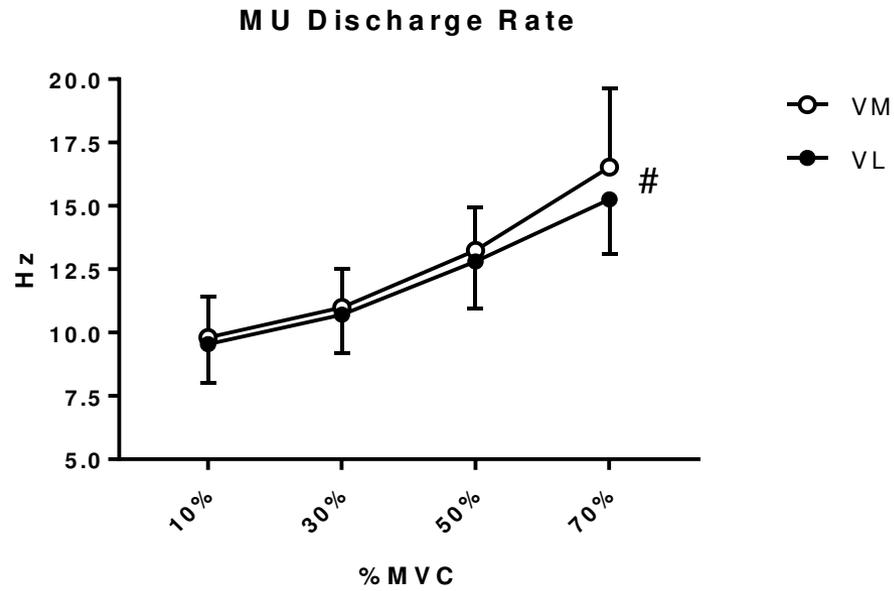


Figure 5

▲ Discharge rate vs. ▲ Recruitment

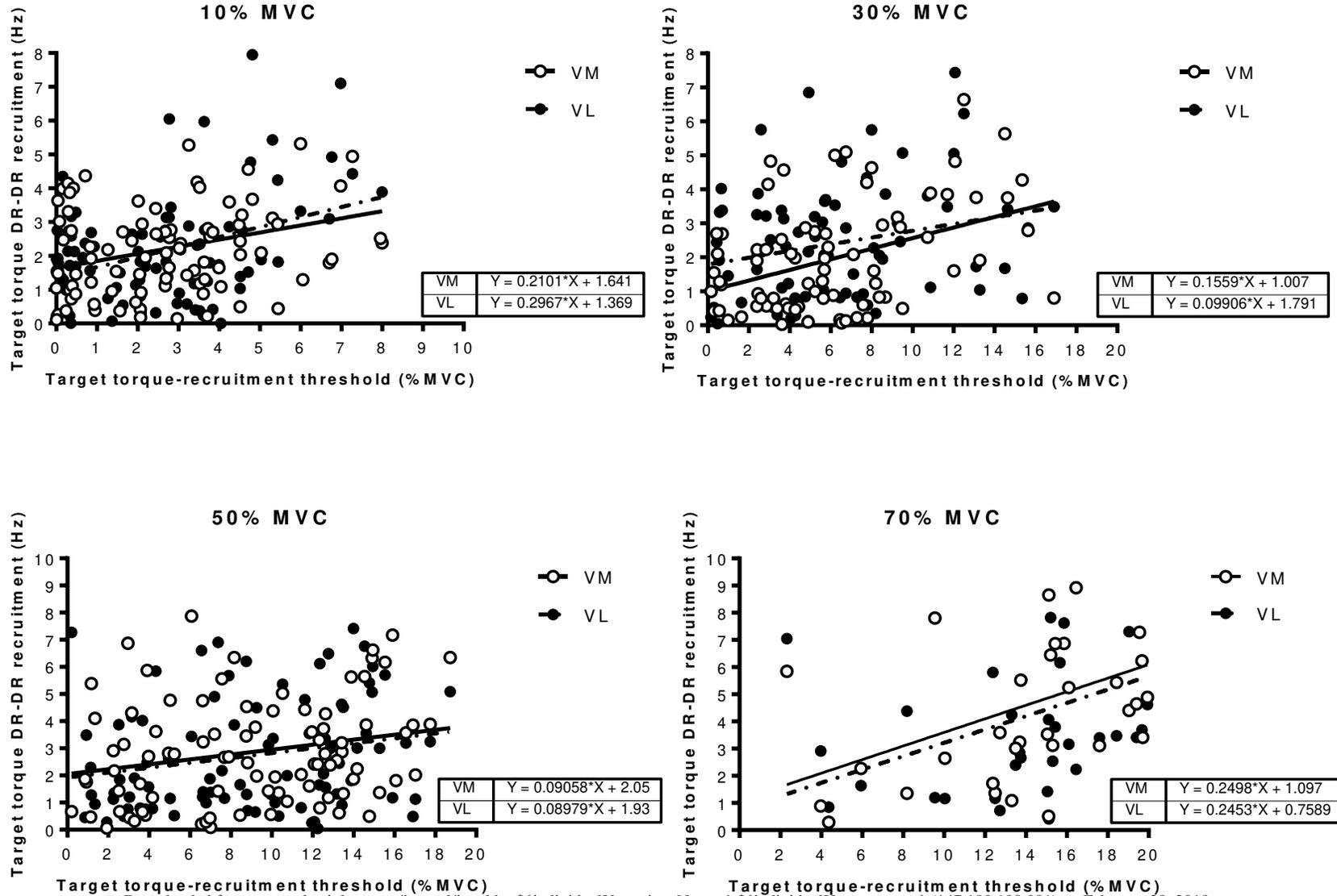


Figure 6

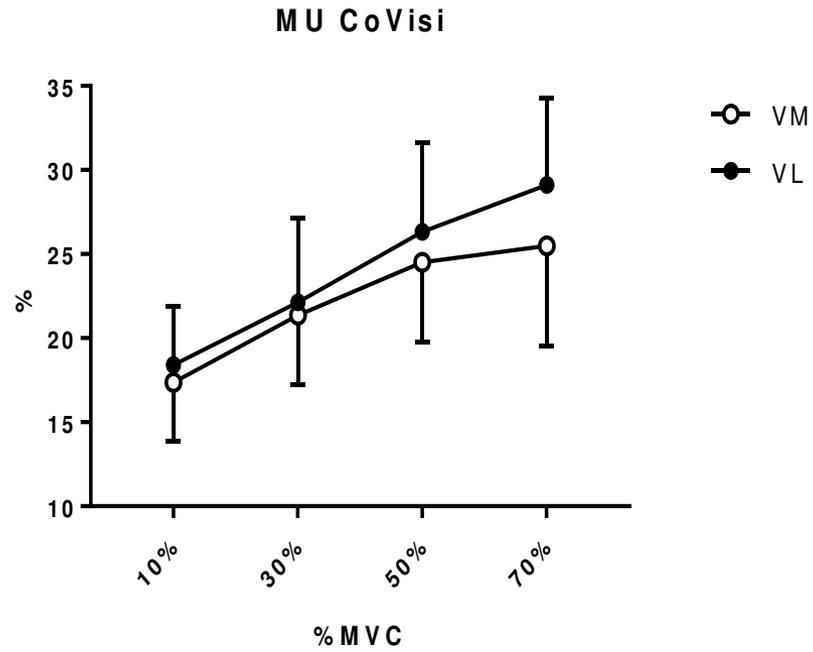


Figure 7

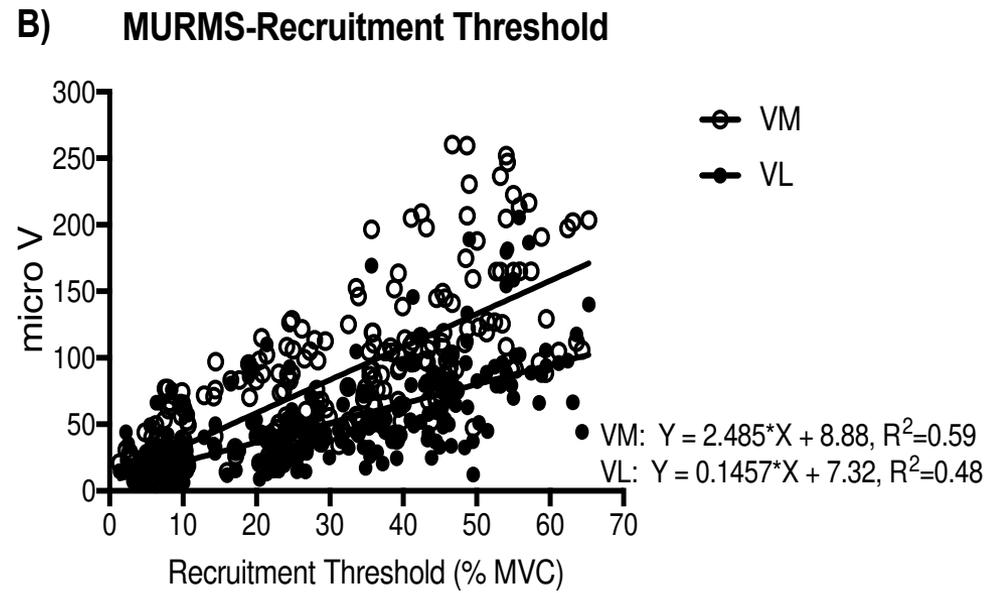
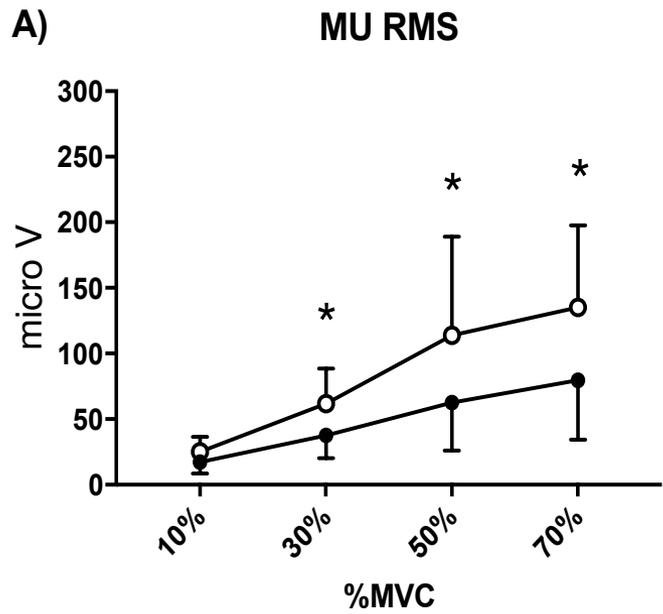


Figure 8

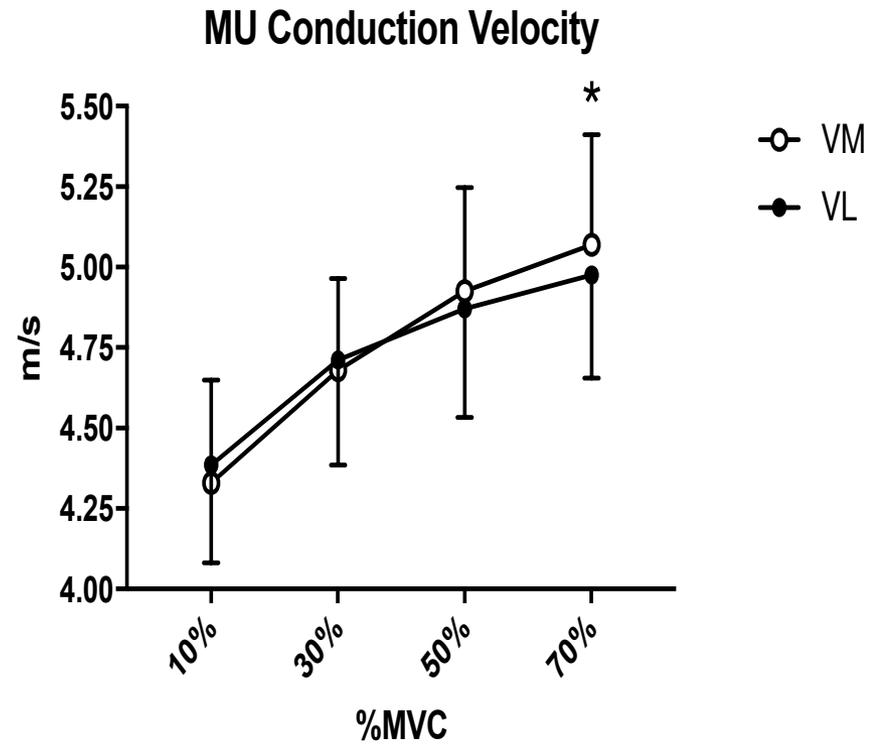


Figure 9

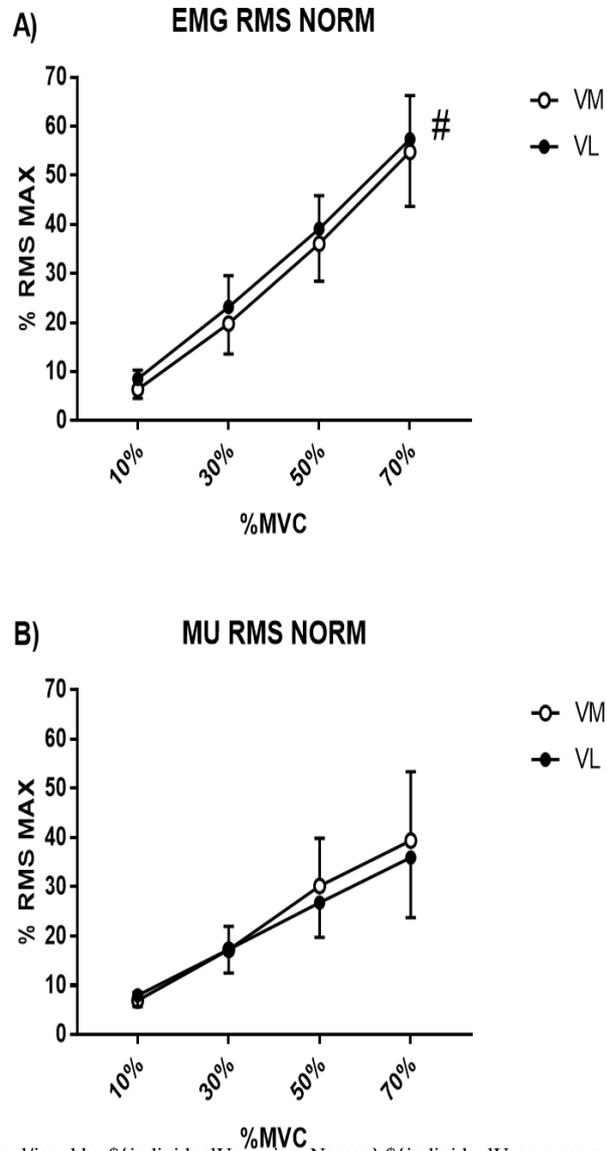


Table 1. Percent difference [%, mean (SD)] and bivariate correlation coefficients (*r*) between predictor variable (% change in VM-VL EMG RMS) and independent variables: %change in VM-VL motor unit (MU) RMS, %change in VM-VL in MU discharge rate (DR) and %change in VM-VL MU conduction velocity (CV)

Torque Level (%MVC)	%Difference in EMG RMS	% Difference in MU RMS	% Difference in MU DR	% Difference in MU CV
10%	14.8 (25.3)	25.2 (34.1), <i>r</i> = 0.84**	2.3 (7.8), <i>r</i> =-0.48	-1.4(4.9), <i>r</i> =-0.27
30%	27.2 (19.4)	36.5 (25.4), <i>r</i> =0.73**	2.3 (7.8), <i>r</i> =0.14	-0.7 (2.5), <i>r</i> =0.12
50%	32.8 (12.5)	42.3 (19.6), <i>r</i> =0.85**	4.1 (9.5), <i>r</i> =0.02	1.3 (3.1), <i>r</i> =-0.2
70%	34.9 (15.8)	42.2 (19.1), <i>r</i> =0.76**	6.2 (13.3), <i>r</i> =0.26	1.8 (3.9), <i>r</i> =0.07

** Significant correlation ($p < 0.0001$)