Survey on Security Threats and Protection Mechanisms in Embedded Automotive Networks

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1 The Automotive Network

2 Threats

3 Protection mechanisms

4 Conclusion



Embedded networks

Modern cars embed

- An internal network...
 - Between 30 and 70 ECUs
 - Several communication protocols: CAN, LIN, MOST, FlexRay...



Source: [Checkoway et al., 2011]



Embedded networks

Modern cars embed

- An internal network...
 - Between 30 and 70 ECUs
 - Several communication protocols: CAN, LIN, MOST, FlexRay...
- ... with external connections
 - On Board Diagnostic (OBD) port
 - USB port
 - Bluetooth
 - WiFi
 - GSM
 - 3G/4G
 - Car2Car



Source: [Checkoway et al., 2011]



CAN & Security

SOF	Identifier	Control	Data	CRC	ACK	EOF
1 bit	12/30 bits	6 bits	0 - 64 bits	16 bits	2 bits	7 bits
Content of a CAN frame						

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- \rightarrow Broadcast only
- \rightarrow Easy DOS
- \rightarrow No authentication



The Automotive Network

2 Threats

Operation Protection mechanisms

4 Conclusion





Attack goals

• Challenge



- Challenge
- Theft



- Challenge
- Theft
- Tuning



- Challenge
- Theft
- Tuning
- Sabotage



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- Privacy breach



Local attacks

Direct access to the bus

- Additional device plugged in
- Through the OBD port



Local attacks

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Results

- Many documented attacks
- Impersonation, reflashing, "virus"...
- Up to complete takeover

A	BOIND
Eeo	120
Pwned by CARSHARI	CarShark KED X-X D 3 2 1

Remote attacks

[Rouf et al., 2010]

Target: Tire Pressure Monitoring System

- Eavesdropping from up to 40m
- Spoofed messages sent to monitoring ECU

[Francillon et al., 2010]

Target: Passive Keyless Entry and Start

- Relay attack
- Car unlocked and started 50m away from the owner



Remote/Indirect takeover

[Checkoway et al., 2011]

Vulnerabilities found in

- Physical indirect range: CD player, OBD plug-in device, infected smartphone...
- Short wireless range: Bluetooth
- Long range: GSM/3G unit

One communication device compromised \rightarrow Complete takeover of the car



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A major concern









Constraints

• Hardware limitations



- Hardware limitations
- Real Time



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- Autonomy: (almost) no interaction required



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- Physical constraints



Protections (1/2)

Cryptography

- Authentication, integrity checks, encryption
- Dedicated hardware for cryptography [Wolf and Gendrullis, 2012]



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Cryptography

- Authentication, integrity checks, encryption
- Dedicated hardware for cryptography [Wolf and Gendrullis, 2012]

Software integrity

- Secure boot
- Virtualization [Groll et al., 2009]



Protections (2/2)

Intrusion detection

- Anomaly-based
 - Tainting tool [Schweppe and Roudier, 2012]
 - Restricted headers & self-checking [Matsumoto et al., 2012]
 - Entropy variations [Muter and Asaj, 2011]
- Signature-based IDS [Muter et al., 2010]



Protections (2/2)

Intrusion detection

- Anomaly-based
 - Detects unknown attacks
 - Requires a very thorough model
- Signature-based
 - Very few false positives
 - Regular updates required



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Conclusion

Threats

- Lack of security mechanisms in current automotive networks
- More exposure with wireless communication capacities
- Several documented attacks



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Trends

- A key issue for manufacturers
- Security enforcement
 - Cryptography
 - Software integrity
 - Anomaly detection



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