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SYMPLECTIC FILLINGS OF SEIFERT FIBERED SPACES

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ABSTRACT. We give finiteness results and some classifications up to diffeomorphism of minimal strong symplectic fillings of Seifert fibered spaces over S^2 satisfying certain conditions, with a fixed natural contact structure. In some cases we can prove that all symplectic fillings are obtained by rational blowdowns of a plumbing of spheres. In other cases, we produce new manifolds with convex symplectic boundary, thus yielding new cut-and-paste operations on symplectic manifolds containing certain configurations of symplectic spheres.

1. Introduction

There are now a number of constructions of symplectic 4-manifolds coming from cutting out a neighborhood of a nice configuration of symplectic curves and replacing that neighborhood with a new piece. In the case that this piece is a rational homology ball, this technique is called a rational blow-down. The fact that some rational blow-downs can be done symplectically was first shown by Symington [31], [32]. This is interesting both from the perspective of understanding the geography of symplectic 4-manifolds, and because of the information this yields about the Seiberg Witten invariants of the underlying smooth 4-manifold. A number of recent papers have explored when it is possible to replace a neighborhood of more general configurations of symplectic curves with Milnor fibers and symplectic rational homology balls (see [6], [10], [11], [30]).

The goal here is to understand not only when a neighborhood of a configuration of curves can be replaced by a specific symplectic or complex manifold, but what are all *possible* symplectic fillings that can replace such a neighborhood of curves. Following a method of argument used by Lisca [17] and Bhupal and Stipsicz [6], we can produce a finite list of all possible diffeomorphism types that may replace a convex neighborhood of certain configurations of symplectic spheres, while preserving the existence of a symplectic structure. Namely, this is a classification of convex symplectic fillings of the contact boundary of a convex neighborhood of these spheres.

Similar classifications have been made for lens spaces with their standard tight contact structures (Lisca [17]), other tight contact structures on L(p,1) (Plamenevskaya and Van Horn-Morris [27]), and some links of simple singularities (Ohta and Ono [21]). By contrast, there are now many results which show that there are contact manifolds with infinitely many non-diffeomorphic Stein or strong symplectic fillings satisfying various properties (see [29], [24], [22], [4], [1], [3], [5]). We obtain some finiteness results in this paper, but it remains an open

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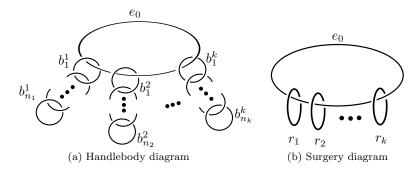


FIGURE 1. Handlebody diagram for a neighborhood of spheres, which can also be seen as a surgery diagram for the boundary of such a neighborhood which is a Seifert fibered space over S^2 .

question of how to characterize contact three manifolds which have finitely many versus infinitely many non-diffeomorphic Stein or strong symplectic fillings.

The proof technique limits the configurations of curves for which we are able to solve this problem. The most obvious conditions necessary for these arguments are the following:

- (1) The curves are symplectic spheres that intersect each other ω -orthogonally. (Note that it suffices to assume the spheres intersect positively and transversely since then they can be isotoped through symplectic spheres to be ω -orthogonal [12].)
- (2) The spheres are configured in a star-shaped graph (there is a unique vertex of valence > 2) with k arms.
- (3) The decoration representing the self-intersection number on the central vertex is at most -k-1, and the decorations on the vertices in the arms are at most -2.

Because these conditions ensure that the dual graph (in the sense of Stipsicz, Szabó, and Wahl [30]) is a star-shaped graph whose central vertex has positive decoration (see section 2.1), we will say configurations satisfying these conditions are dually positive.

A neighborhood of such spheres has a handlebody diagram given in Figure 1a where $e_0 \leq -k-1$ and $b_i^j \leq -2$. Note that the boundary of such a neighborhood of spheres is a Seifert fibered 3-manifold over S^2 , with surgery diagram given by Figure 1a. This surgery diagram is equivalent to that in Figure 1b when

$$r_i = b_1^i - \frac{1}{b_2^i - \frac{1}{\ddots - \frac{1}{b_{n_i}^i}}}.$$

In general, a choice of $e_0 \in \mathbb{Z}$ and $r_1, \dots, r_k \in \mathbb{Q}$ such that $r_i < -1$ for all i uniquely determines a Seifert fibered space by surgery as in Figure 1b. We denote the manifold described by the surgery diagram by $Y(e_0; r_1, \dots, r_k)$.

We will say a Seifert fibered space is *dually positive* if it arises as the boundary of a dually positive plumbing of spheres. Any neighborhood of a dually positive configuration of symplectic spheres contains a symplectically convex neighborhood

of the spheres (by [11] or [9]; see section 2.2) whose boundary inherits a fixed contact structure. As this contact structure arises as the boundary of a symplectic plumbing of spheres, we will refer to this contact structure as ξ_{pl} (we suppress the Seifert invariants for simplicity). Therefore the results here provide a method for the classification of convex symplectic fillings of dually positive Seifert fibered spaces, with the contact structures ξ_{pl} .

In the case of dually positive Seifert fibered spaces, the result of Mark and Gay will show that these contact structures which are induced on the convex boundary are supported by planar open books. These open book decompositions make it clear that the contact structures ξ_{pl} coincide with those studied much earlier by Schönenberger [28] and Etgü and Ozbagci [8] and are shown to be horizontal contact structures in [23]. By a result of Park and Stipsicz in [25], the contact structure ξ_{pl} is contactomorphic to the contact structure induced by the complex tangencies on the link of a complex singularity. This contact structure is sometimes referred to as the canonical contact structure in the literature.

In specific cases, we are able to state explicit classifications of the diffeomorphism types of possible symplectic fillings. Under less specific assumptions, we can find some loose upper bounds to obtain the following finiteness result.

Theorem 1.1. If Y is a dually positive Seifert fibered space with k singular fibers and either $k \in \{3,4,5\}$ or $e_0 \leq -k-3$, then (Y,ξ_{pl}) has finitely many minimal strong symplectic fillings up to diffeomorphism. If Y is any dually positive Seifert fibered space, then the minimal strong symplectic fillings of (Y,ξ_{pl}) realize only finitely many values of Euler characteristic and signature. Loose upper bounds in both cases can be determined from the Seifert invariants.

Note that the fact that the minimal symplectic fillings realize finitely many values of Euler characteristic and signature follows from the fact that these contact structures are supported by planar open book decompositions by a result of Kaloti [16]. It is frequently possible to obtain tight upper bounds on the number of diffeomorphism types of minimal symplectic fillings or their values of Euler characteristic and signature in specific examples, by analyzing the dual graph associated to the Seifert fibered space as will be described in section 2.

In some simple families of examples, we explicitly work out the possible diffeomorphism types of the minimal symplectic fillings. In some cases, all fillings are related to the original plumbing of spheres by a rational blow-down of a subgraph of the original configuration.

Theorem 1.2. If (Y, ξ_{pl}) is the boundary of a dually positive plumbing of spheres, where the star-shaped graph has exactly three arms, the central vertex has self-intersection coefficient -4, and

- (1) each arm has arbitrary length, but each sphere in any arm has self-intersection coefficient -2
- (2) each arm has length one, and each sphere in each arm has self-intersection coefficient strictly less than -4,

then (Y, ξ_{pl}) has exactly two minimal strong symplectic fillings up to diffeomorphism, given by the original symplectic plumbing and the manifold obtained by rationally blowing down the central -4 sphere.



FIGURE 2. Graph referred to in Theorem 1.4.

In the previous cases the central vertex had the largest possible coefficient to satisfy the dually positive condition. When the coefficient on the central vertex $e_0 \leq -k-3$ where k is the number of arms in the graph, we can prove a similar theorem for any value of $k \geq 3$.

Theorem 1.3. If (Y, ξ_{pl}) is the boundary of a dually positive plumbing of spheres with k arms, where the coefficient on the central vertex is $e_0 \le -k - 3$, and the coefficients on the spheres in the arms are all -2, then all diffeomorphism types of minimal strong symplectic fillings are obtained from the original plumbing of spheres by a rational blow-down of the central vertex sphere together with $-e_0 - 4$ spheres of square -2 in one of the arms.

In special cases, as determined in [30], the entire star-shaped graph can be rationally blown down. The simplest example which is dually positive is shown in Figure 2. We can show that the expected rational blow-downs provide a complete classification for this graph.

Theorem 1.4. If (Y, ξ_{pl}) is the boundary of a dually positive plumbing of spheres in the configuration of Figure 2, there are exactly three diffeomorphism types of minimal strong symplectic fillings of (Y, ξ_{pl}) : the original plumbing of spheres, the rational blow-down of the central -4 sphere, and the rational blow-down of the entire configuration.

The configuration in the previous theorem generalizes to the family $W_{p,q,r}$ studied in [30]. We classify the symplectic fillings corresponding to this family of graphs in section 4. In this case, all convex fillings are obtained by a rational blow-down of a subgraph or the entire graph.

The method used to obtain these classification results (proven to work in section 2 and demonstrated in a simple example in section 3) applies to some extent to any dually positive plumbing of spheres. The method produces a list of handlebody diagrams representing 4-manifolds that are likely to support convex symplectic structures inducing ξ_{pl} on the boundary. In many cases, all of these handlebody diagrams can be shown to correspond to actual convex symplectic fillings, which completes the classification. In the previous theorems, all of these convex fillings are obtained from the original plumbing by rationally blowing down a subset of the core spheres in the plumbing. However, there are new manifolds arising as handlebody diagrams obtained by this method, as possible fillings that are not obtained by a rational blow-down of a subgraph. Note that these replacements still have smaller Euler characteristic than the original plumbing.

Theorem 1.5. If (Y, ξ_{pl}) is the boundary of a dually positive plumbing of spheres, with k = 4 or k = 5 arms, whose central vertex has coefficient -k - 1, and all the vertices in the arms have coefficient -2 and each arm has length at least k - 3, then all possible diffeomorphism types of symplectic fillings determined by this process

(listed as handlebody diagrams in section 5) are realized as strong symplectic fillings of (Y, ξ_{pl}) .

Some of these diffeomorphism types cannot be obtained by a rational blow-down, or by replacing a neighborhood of a linear plumbing of spheres with a different symplectic filling of its lens space boundary. Namely, these are genuinely new diffeomorphism types that may be convex symplectic fillings. Note that if the arms have length less than k-3, some of the diffeomorphism types cannot be realized, but the classification can still be made.

The main argument that provides the set-up for all these results will be given in section 2, with the proof of Theorem 1.1 at the end of that section. For concreteness, we follow this in section 3 by a detailed proof of the classification of fillings of a simple family of examples, proving part (1) of Theorem 1.2. We follow this by classification results that can be stated in terms of rational blow-downs in section 4, proving Theorem 1.3, part (2) of Theorem 1.2, Theorem 1.4, and its generalization to the family $W_{p,q,r}$. In section 5, we give explicit descriptions of the new 4-manifolds which strongly symplectically fill the dually positive Seifert fibered spaces in Theorem 1.5. Section 6 contains some further observations and questions.

2. Upper bounds on diffeomorphism types of strong symplectic fillings

The main argument here gives upper bounds (in terms of explicit diffeomorphism types) of strong symplectic fillings of dually positive Seifert fibered spaces with the contact structure ξ_{pl} . First, using a construction of Stipsicz, Szabó and Wahl [30], we will build the symplectic plumbing of spheres inside a closed symplectic manifold, such that the complement is also a symplectic plumbing of spheres, now with concave boundary. The dually positive condition will allow us to ensure that the concave piece contains a sphere of self-intersection number +1. Then we cut out the original plumbing of spheres and glue in an arbitrary convex symplectic filling to form a closed symplectic manifold which still contains a sphere of self-intersection number +1 (analogous to Lisca's method to classify symplectic fillings of $(L(p,q),\xi_{std})$. A theorem of McDuff implies that this closed manifold is a symplectic blow-up of $\mathbb{C}P^2$ with its standard Kahler structure. To identify the topology of the unknown convex symplectic filling, it suffices to understand how the concave cap can symplectically embed into the blow-up of $\mathbb{C}P^2$, since the convex filling must be its complement. Using arguments of Lisca [17], we obtain homological restrictions coming from the adjunction formula and intersection information of the spheres. Under certain conditions, we can show that the homology classes these spheres represent uniquely determine a symplectic embedding of their neighborhood into a blow-up of $\mathbb{C}P^2$. By deleting the possible embeddings of the concave cap from blow-ups of $\mathbb{C}P^2$, we obtain the diffeomorphism types of all possible convex symplectic fillings of the given dually positive Seifert fibered space with contact structure ξ_{pl} .

2.1. The dual graph construction. First we describe the dual graph construction of Stipsicz, Szabó, and Wahl [30], which provides a symplectic embedding of the neighborhood of dually positive spheres into a blow-up of $\mathbb{C}P^2$ whose complement is the concave cap we need.

U d 3-handles, 1 4-handle

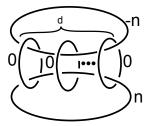


FIGURE 3. A handlebody diagram for the sphere bundle B_n . The relevant spheres (the zero section, infinity section, and d fibers) are represented by the cores of the 2-handles together with the pushed-in Seifert surfaces for the attaching circles.

The construction of the dual graph begins by looking at a sphere bundle over a sphere, which has a standard symplectic structure. Each fiber will have self-intersection number 0, and will intersect each section of the bundle in a single point. The zero and infinity sections have self-intersection numbers n and -n respectively. It is convenient to have a handlebody diagram for the sphere bundle B_n , in which the 0-section, d distinct fibers, and the ∞ -section are all visible. Such a diagram is given by Figure 3.

To obtain the dual plumbing, we build the original plumbing inside a symplectic blow-up of B_n . We will allow blow-ups to be performed along the intersections of the various spheres in the picture. The proper transforms of these spheres will remain symplectic, and new exceptional spheres are symplectic submanifolds as well. At the beginning the spheres we keep track of are just the 0-section, the ∞ -section, and the d fibers. As we blow up, we include the new exceptional spheres in the picture. Figure 4 shows an example, keeping track of both the standard short-hand notation to keep track of these blow-ups, as well as the corresponding handlebody diagrams. Note that each exceptional fiber will contain at least one sphere of self-intersection -1, which is the exceptional sphere from the most recent blow-up of that fiber. We perform the blow-ups so that if we remove the vertices corresponding to these spheres in the resulting plumbing graph, we will get a two component graph, one of which is Γ and the other is the dual graph Γ' .

To see that the plumbings coming from Γ and Γ' glue together to give the blowup of our original sphere bundle, imagine cutting the blown-up sphere bundle as shown above, along an equator of each regular fiber, and along the equator of the last exceptional sphere in each exceptional fiber, so that these equators all match up smoothly to form a 3-manifold. Note that each sphere in either graph is a symplectic submanifold since it is either one of the distinguished sections, a fiber, an exceptional sphere, or the proper transform of one of these objects.

2.1.1. Dually positive graphs. The condition that a configuration of spheres is dually positive, ensures that one can build a dual configuration which is a star-shaped graph whose central vertex has self-intersection number +1. To see this, suppose the central vertex of the dually positive configuration has square $e_0 \leq -k-1$, where k is the number of arms in the original graph. Start with a sphere bundle with zero section of self-intersection number -1, and infinity section of self-intersection

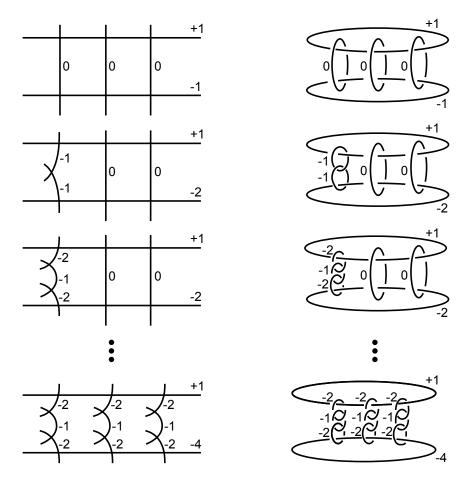


FIGURE 4. A sequence of blow-ups, keeping track of the spheres whose neighborhoods are plumbings. In the last stage we can see the star-shaped plumbing with 4 vertices, where the central vertex is labelled with -4 and the three arms are labelled with -2, and its dual plumbing which is also star-shaped with 4 vertices, but where the central vertex is labelled with +1 and the three arms are labelled with -2. The two plumbings are glued together along equators of the regular fibers and equators of the -1 spheres on the exceptional fibers.

number +1, and keep track of $d = -e_0 - 1$ fibers (of self-intersection number 0). Blow up once at the intersections of each of the $-1 - e_0$ fibers with the zero section. The proper transform of the zero section now has self-intersection number e_0 , the exceptional spheres and proper transforms of the fibers have self-intersection number -1, and the infinity section is unchanged so it still has self-intersection number +1. Next, in k of these singular fibers, blow up at the intersection of the new exceptional sphere with the proper transforms of the original fiber. By continuing to blow up at points where an exceptional sphere of square -1 intersects an adjacent sphere, it is possible to build the dually positive graph emanating from

the zero section and ending just before the most recent exceptional -1 spheres in each fiber, without ever blowing up at a point on the infinity section. Therefore the dual graph has central vertex with coefficient +1, and $-1-e_0$ arms, whose vertices have all negative coefficients.

Note that when $e_0 < -k - 1$, the dual graph contains $d = -e_0 - 1 > k$ arms, but only k of them are used to construct the singular fibers. Each of the remaining $-e_0 - 1 - k$ arms shows up in the dual graphs construction as two -1 spheres, one of which is adjacent to the proper transform of the zero section and will be cut in half to split the graph from the dual graph. The remaining -1 sphere (the proper transform of a regular fiber after one blow-up at its intersection with the 0-section) persists in the dual graph as a short arm.

2.2. Cut and paste for symplectic manifolds. The easiest way to ensure one can glue together two symplectic manifolds with orientation reversing diffeomorphic boundary is by showing that one piece has convex boundary and the other has concave boundary. A concave or convex boundary inherits a contact structure, and a concave boundary will glue to a contactomorphic convex boundary to give a closed symplectic manifold (after possibly rescaling the symplectic form on one piece). Therefore we would like to show that a neighborhood of our dually positive configuration of spheres has convex boundary. In some cases, we will need to recognize the contact structure induced on the boundary in terms of an open book decomposition. For these results we use a theorem of Gay and Mark.

Their set-up starts with a configuration of symplectic surfaces $\mathcal{C} = C_1 \cup \cdots \cup C_n$ intersecting ω -orthogonally according to a negative definite graph Γ with no edges from a vertex to itself. For each vertex v_j , let s_j be the sum of the valence of that vertex with the self-intersection number of the corresponding symplectic surface. Assume $s_j \leq 0$ for all vertices v_j (a.k.a. no bad vertices). Let Σ be the surface obtained from connect summing $|s_j|$ copies of D^2 to each C_j and then connect summing these surfaces together according to the graph. Let $\{c_1, \cdots, c_k\}$ be simple closed curves, with one around each connected sum neck, and τ the product of right handed Dehn twists around c_1, \cdots, c_k .

Theorem 2.1 (Gay and Mark [9, Theorem 1.1]). Any neighborhood of C contains a neighborhood (Z, η) of C with strongly convex boundary, that admits a Lefschetz fibration $\pi : Z \to D^2$ having regular fiber Σ and exactly one singular fiber $\Sigma_0 = \pi^{-1}(0)$. The vanishing cycles are c_1, \dots, c_k , and C is the union of the closed components of Σ_0 . The induced contact structure ξ on ∂Z is supported by the induced open book (Σ, τ) .

For dually positive configurations of spheres, the hypothesis that $s_j \leq 0$ is satisfied and Σ is a disk with holes.

Note that the fact that such neighborhoods of symplectic surfaces have convex neighborhoods was proven (under the weaker assumption that the plumbing graph be negative definite instead of the condition on the s_j) by Gay and Stipsicz in [11]. While this result is sufficient to allow us to make a gluing argument, we need the information about the open book decomposition to identify the contact structure in some of the more difficult cases (see section 5).

Now we may choose an arbitrarily small convex neighborhood of the dually positive configuration of spheres to cut out, and then (after possibly rescaling the symplectic form) glue in any strong symplectic filling of the contact boundary, which has the canonical contact structure ξ_{pl} , to obtain a closed symplectic manifold containing a symplectic embedding of the concave cap.

2.3. McDuff's classification for closed symplectic manifolds. As explained in section 2.1.1, our condition that the configuration of spheres be dually positive ensures that the concave cap coming from the dual graph construction contains a sphere of self-intersection number +1. This condition is useful due to the following classification theorem.

Theorem 2.2 (McDuff [20]). If (V^4, C^2, ω) is a minimal symplectic pair (namely $V \setminus C$ contains no exceptional curves), where C is a rational curve with self-intersection $C \cdot C = p \geq 0$, then (V, ω) is symplectomorphic either to $\mathbb{C}P^2$ with its usual Kahler form or to a symplectic S^2 bundle over a compact surface M. Further, this symplectomorphism may be chosen so that it takes C either to a complex line or quadric in $\mathbb{C}P^2$, or to a fiber of the S^2 bundle, or (if $M = S^2$) to a section of this bundle.

In our case, this classification simplifies to a single manifold up to blowing up symplectically.

Corollary 2.3. If (V^4, C^2, ω) is a minimal symplectic pair where C is a 2-sphere of self-intersection number +1, then (V, C, ω) is symplectomorphic to $(\mathbb{C}P^2, \mathbb{C}P^1, \omega_{std})$.

By gluing any strong symplectic filling of a dually positive Seifert fibered space with contact structure ξ_{pl} to a neighborhood of its dual configuration, we obtain a symplectic pair (V, C, ω) satisfying all hypotheses of the theorem except minimality. After blowing down exceptional spheres in $V \setminus C$, it follows that such a convex filling embeds symplectically (up to rescaling the symplectic form) in a blow-up of $(\mathbb{C}P^2, \omega_{std})$ where the blow-ups are disjoint from the standard $\mathbb{C}P^1 \subseteq \mathbb{C}P^2$. The complement of the embedded convex filling is symplectomorphic to the corresponding plumbing of spheres described by the dual graph, and +1 sphere corresponding to the central vertex of the dual graph is identified with $\mathbb{C}P^1$.

2.4. Homological restrictions on embeddings of the cap. Denote by (X_M, ω_M) the closed symplectic manifold $\mathbb{C}P^2 \# M \mathbb{C}P^2$ with symplectic form ω_M given by some symplectic blow-up of the standard Kahler form on $\mathbb{C}P^2$. We would like to determine all possible symplectic embeddings of the positive dual graph plumbings corresponding to the concave cap. To understand possible embeddings, we use some homological restrictions.

First fix a standard orthogonal basis (ℓ, e_1, \dots, e_M) for $H_2(X_M; \mathbb{Z})$ where ℓ is represented by the complex projective line so $\ell^2 = +1$, and the e_i are represented by the exceptional spheres created in the blow-ups, so $e_i^2 = -1$, and $\ell \cdot e_i = e_i \cdot e_j = 0$ for $i \neq j$. Because these are represented by symplectic surfaces, we can determine how the first Chern class of X_M evaluates on each of these homology classes via the adjunction formula:

$$\langle c_1(X_M), \ell \rangle = \ell^2 + 2 = 3,$$

 $\langle c_1(X_M), e_i \rangle = e_i^2 + 2 = 1.$

Now we would like to analyze what the spheres in the plumbing for the cap could represent in $H_2(X_M; \mathbb{Z})$ in terms of this basis. We will refer to the embedded sphere representing the central vertex as C_0 , the symplectic spheres representing the vertices adjacent to the central vertex as C_1, \dots, C_d , and the symplectic spheres

representing the other vertices in the dual graph by C_{d+1}, \dots, C_m . We know that these spheres are also symplectic, so they must also satisfy the adjuction formula:

$$\langle c_1(X_M), [C_j] \rangle = [C_j]^2 + 2.$$

Furthermore, we know that the sphere C_0 which has self-intersection number +1 is sent to the complex projective line so $[C_0] = \ell$. The intersection data implies that spheres whose vertices are joined by an edge have homological intersection number +1, other distinct spheres have homological intersection number 0, and the square of the homology class represented by each sphere is given by the decoration on the graph (which is negative for all but C_0).

Now suppose that for $j \in \{1, \dots, m\}$

$$[C_j] = a_0^j \ell + \sum_{i=1}^M a_i^j e_i.$$

For $j \in \{1, \dots, d\}$ we have $1 = [C_j] \cdot [C_0] = [C_j] \cdot \ell$, so $a_0^j = 1$. Using the adjunction formula, and our knowledge of how $c_1(X_M)$ evaluates on the standard basis, we get the following formula for the coefficients a_i^j :

$$3 + \sum_{i=1}^{M} a_i^j = 1 - \sum_{i=1}^{M} (a_i^j)^2 + 2,$$

SO

$$\sum_{i=1}^{M} (a_i^j)^2 + a_i^j = 0.$$

Note that since a_i^j are integers, we have $(a_i^j)^2 + a_i^j \geq 0$ with equality if and only if $a_i^j \in \{0, -1\}$. Therefore $a_i^j \in \{0, -1\}$ for all $i \in \{1, \dots, M\}$, $j \in \{1, \dots, d\}$. Furthermore, since $-n_j = [C_j]^2 = 1 - \sum_{i=1}^M (a_i^j)^2$, there are precisely $n_j + 1$ values of i for which a_i^j is -1. Thus we can write for $j \in \{1, \dots, d\}$:

$$[C_j] = \ell - e_{i_1^j} - \dots - e_{i_{n_j+1}^j}.$$

We have further data given by the fact that $[C_j] \cdot [C_{j'}] = 0$ when $j \neq j' \in \{1, \dots, d\}$:

$$\begin{split} 0 &= (\ell - e_{i_1^j} - \dots - e_{i_{n_j+1}^j}) \cdot (\ell - e_{i_1^{j'}} - \dots - e_{i_{n_{j'}+1}^{j'}}) \\ &= 1 - |\{i_1^j, \dots, i_{n_j+1}^j\} \cap \{i_1^{j'}, \dots, i_{n_{j'}+1}^{j'}\}|. \end{split}$$

We conclude that

Lemma 2.4. If C_j and C'_j are distinct symplectic spheres in the dual graph configuration which are adjacent to the central vertex sphere, then $[C_j]$ and $[C_{j'}]$ share exactly one common basis element e_i with coefficient -1.

If the graph we are considering has k arms, corresponding to the k singular fibers in the Seifert fibered space, then the coefficient on the central vertex of the graph, e_0 , determines the relationship between k and d. As discussed in section 2.1.1, the number of arms in the dual graph is $d=-e_0-1$, and the dually positive assumption implies $k \leq -e_0-1$. When $d=-e_0-1$ is strictly larger than k, there are d-k additional short arms each made up of a single symplectic sphere of self-intersection number -1. Therefore $[C_j] = \ell - e_{i_j^j} - e_{i_2^j}$ for $j \in \{k+1, \cdots, d\}$.

Lemma 2.5. If $d = -e_0 - 1 > k + 1$, then the symplectic spheres C_0, C_1, \dots, C_d represent one of the following sets of homology classes in terms of the standard basis for $H_2(\mathbb{C}P^2 \# M\mathbb{C}P^2)$ (up to relabelling):

$$[C_0] = \ell$$

$$[C_1] = \ell - e_1 - e_1 - e_2 - \cdots - e_k - e_{k+1} - \cdots - e_d - e_k - e_{k+1} - \cdots - e_d - e_k - e_{k+1} - \cdots - e_d - e_k - e_k$$

Here e. indicates that there can be additional distinct e_i 's with coefficient -1 in these homology classes if the corresponding square is sufficiently negative. They should all be distinct from each other and distinct from all labelled e_i 's.

Furthermore, if d = k + 1 we have the above cases together with additional possibilities given as follows where 1 < j < k (by a symmetry we may actually assume $j \le k/2$):

$$\begin{aligned} [C_0] &= & \ell \\ [C_1] &= & \ell - e_1 - e_{i(1,j+1)} - e_{i(1,j+2)} \cdots - e_{i(1,k)} - e_{\cdot} - \cdots - e_{\cdot} \\ &\vdots \\ [C_j] &= & \ell - e_1 - e_{i(j,j+1)} - e_{i(j,j+2)} \cdots - e_{i(j,k)} - e_{\cdot} - \cdots - e_{\cdot} \\ [C_{j+1}] &= & \ell - e_2 - e_{i(1,j+1)} - e_{i(2,j+1)} - \cdots - e_{i(j,j+1)} - e_{\cdot} - \cdots - e_{\cdot} \\ &\vdots \\ [C_k] &= & \ell - e_2 - e_{i(1,k)} - e_{i(2,k)} - \cdots - e_{i(j,k)} - e_{\cdot} - \cdots - e_{\cdot} \\ [C_{k+1}] &= & \ell - e_1 - e_2. \end{aligned}$$

Here i(a,b) are distinct for distinct pairs (a,b), and are distinct from 1, 2.

Proof. First notice that there must be a common element e_i with coefficient -1 in all the classes $[C_{k+1}], \cdots, [C_d]$. This is trivial in the case that k+1=d, and follows immediately from Lemma 2.4 when k+2=d. When d>k+2, Lemma 2.4 implies that $[C_{k+1}]$ and $[C_{k+2}]$ share a unique element with coefficient -1, so without loss of generality $[C_{k+1}] = \ell - e_1 - e_2$ and $[C_{k+2}] = \ell - e_1 - e_3$. If $[C_{k+3}]$ does not have -1 coefficient for e_1 , then Lemma 2.4 implies $[C_{k+3}] = \ell - e_2 - e_3$, but then there is no way that $[C_1]$ can have e_i 's with -1 coefficient for exactly one of $\{1,2\}$, exactly one of $\{1,3\}$, and exactly one of $\{2,3\}$, which is a contradiction. Since $[C_j]$ and $[C_{j'}]$ share only one element e_i with coefficient -1, we find that $[C_{k+1}] = \ell - e_1 - e_{k+1}, \cdots, [C_d] = \ell - e_1 - e_d$ for e_{k+1}, \cdots, e_d all distinct.

Now consider the homology classes $[C_1], \dots, [C_k]$. Each such class must either have -1 coefficient for e_1 or -1 coefficient for all of the classes e_{k+1}, \dots, e_d (not both). If d > k+1, then there can be at most one of the spheres C_1, \dots, C_k , whose homology class has coefficient -1 for all the classes e_{k+1}, \dots, e_d , since no two $[C_j]$ can share more than one e_i with coefficient -1. This proves the first part of the lemma.

When d=k+1 and $[C_{k+1}]=\ell-e_1-e_2$, some of the classes $[C_1],\cdots,[C_k]$ must have coefficient -1 for e_1 and the rest must have coefficient -1 for e_2 . Without loss of generality we assume the first j have -1 coefficient for e_1 , and the rest have -1 coefficient for e_2 . Then for each pair $(a,b)\in\{1,\cdots,j\}\times\{j+1,\cdots,k\}$ we must add another $e_{i(a,b)}$ which occurs with -1 coefficient in $[C_a]$ and $[C_b]$. If i(a,b)=i(a',b') for $(a,b)\neq(a',b')$, then either $a\neq a'$ so $[C_a]$ and $[C_{a'}]$ both have coefficient -1 for both e_1 and $e_{i(a,b)}$ or $b\neq b'$ so $[C_b]$ and $[C_{b'}]$ both have coefficient -1 for e_2 and $e_{i(a,b)}$, but homology classes of distinct pairs of spheres can only share one common element with coefficient -1.

For $j \in \{d+1, \dots, m\}$, we know that $0 = [C_j] \cdot [C_0] = [C_j] \cdot \ell$. Therefore $a_0^j = 0$ for all $j \in \{d+1, \dots, m\}$. In this case the adjuction formula yields the following formula:

$$\sum_{i=1}^{M} a_i^j = -\sum_{i=1}^{M} (a_i^j)^2 + 2,$$

SO

$$\sum_{i=1}^{M} (a_i^j)^2 + a_i^j = 2.$$

Thus, all but one of the a_i^j 's is either 0 or 1, and exactly one a_i^j is either 1 or -2 for for each $j \in \{d+1, \cdots, m\}$. An inductive argument of Lisca [17, Proposition 4.4] implies that a_i^j can never be equal to -2, so there is always a unique a_i^j equal to 1. Note that Lisca's statement refers to linear graphs of symplectic spheres embedded in a blow-up of $\mathbb{C}P^2$, but each arm of the star-shaped graph (starting at the central vertex) is a linear graph satisfying the necessary hypotheses.

In conclusion the symplectic spheres in the dual graph represent homology classes of the following form:

$$\begin{aligned} [C_0] &= & \ell \\ [C_1] &= & \ell - e_{i_1^1} - \dots - e_{i_{n_1+1}^1} \\ &\vdots \\ [C_k] &= & \ell - e_{i_1^k} - \dots - e_{i_{n_k+1}^k} \\ [C_{k+1}] &= & \ell - e_{i_1^{k+1}} - e_{i_2^{k+1}} \\ &\vdots \\ [C_d] &= & \ell - e_{i_1^d} - e_{i_2^d} \\ [C_{d+1}] &= & e_{i_0^{k+1}} - e_{i_1^{k+1}} - \dots - e_{i_{n_k+1}^{k+1-1}} \\ &\vdots \\ [C_m] &= & e_{i_0^m} - e_{i_1^m} - \dots - e_{i_{n_m-1}^m}. \end{aligned}$$

Here $i_h^j \neq i_{h'}^j$ when $h \neq h'$, and the values n_j are determined by the square of $[C_j]$. Up to relabeling the e_i , the only remaining question is when i_h^j can coincide with $i_{h'}^{j'}$ for $j \neq j'$. Additional restrictions on $[C_1], \dots, [C_d]$ are given by Lemmas 2.4 and 2.5. Other intersection restrictions imply other relations between the sets

 $\{i_0^j,\cdots,i_{n_j}^j\}$ for different values of $j\in\{1,\cdots,m\}$, which can be exploited in specific examples.

2.5. Translating homological restrictions into embeddings. Given a finite list of homology classes that a symplectic embedding of the spheres of the dual graph into $\mathbb{C}P^2\# M\overline{\mathbb{C}P^2}$ can represent, we would like to say that there are finitely many symplectic embeddings of the dual graph up to isotopy. There are two main steps to this process. The first is to follow the arguments of Lisca [17] to carefully blow-down to $\mathbb{C}P^2$, while keeping track of how this affects the embedded spheres of the dual graph. The second step is to analyze this blown-down embedding, and to try to understand the isotopy classes of a regular neighborhood of the blown-down dual graph in $\mathbb{C}P^2$.

2.5.1. Blowing down ($\mathbb{C}P^2 \# M\overline{\mathbb{C}P^2}$, dual graph). The following theorem was used by Lisca to solve this part of the problem when classifying symplectic fillings of lens spaces. In that case, the plumbing of spheres providing the concave cap is linear.

Theorem 2.6 (Lisca [17, Theorem 4.2]). Let ω_M be a symplectic form on $\mathbb{C}P^2 \# M \overline{\mathbb{C}P^2}$ obtained from the standard Kahler form by symplectic blow-ups. Let $\Gamma = C_0 \cup \cdots \cup C_j$ be a union of ω_M -orthogonal symplectic spheres, in the configuration of a linear graph, with self-intersection numbers $(1, 1-b_1, -b_2, \cdots, -b_j)$, such that C_0 is a complex line. Then there is a sequence of symplectic blow-downs,

$$(\mathbb{C}P^2 \# M \overline{\mathbb{C}P^2}, \omega_M) \to (\mathbb{C}P^2 \# (M-1) \overline{\mathbb{C}P^2}, \omega_{M-1}) \to \cdots \to (\mathbb{C}P^2, \omega_0),$$

with ω_0 diffeomorphic to the standard Kahler form and such that Γ descends to two ω_M orthogonal symplectic spheres, each of self-intersection number 1.

In our situation, the dual graph is star-shaped instead of linear. However, a star-shaped graph is simply the union of its k arms, each of which is a linear graph emanating from the central vertex. Therefore Lisca's theorem applies to each of the arms of the star-shaped dual configuration. We would like to keep track of all of these arms at once as we blow-down the manifold. Though we do not need a new argument here, a summary of Lisca's proof is included here to make it clear how it applies in the star-shaped case.

In our case, the dual configuration of spheres $\Gamma = C_0 \cup \cdots \cup C_m$ (in the shape of a star-shaped graph) is assumed to be symplectically embedded in $(\mathbb{C}P^2 \# M \mathbb{C}P^2, \omega_M)$. Here C_0 is identified with the complex projective line (by McDuff's theorem). First, choose an almost complex structure tamed by ω_M , for which the spheres C_0, \cdots, C_m are all *J*-holomorphic. This allows us to have more control over intersections of spheres with any *J*-holomorphic sphere we blow down.

Relying on analysis of J-holomorphic curves by McDuff, Lisca proves a lemma (Lemma 4.5 in [17]) which says that as long as M>0, there exists a J-holomorphic sphere Σ such that $[\Sigma] \cdot [C_0] = 0$ and $[\Sigma]^2 = -1$. Furthermore, we can find Σ disjoint from Γ if and only if there is a symplectic sphere S of square -1 such that $[S] \cdot [C_j] = 0$ for $j = 0, 1, \dots, m$. Note that Lisca stated this in the case that Γ is a linear plumbing, but the proof is unchanged for any configuration of symplectic spheres intersecting ω -orthogonally. Therefore, it is possible to blow down J-holomorphic spheres Σ until X_M is blown down to $\mathbb{C}P^2$. Using the lemma, we can first blow down any Σ 's disjoint from Γ , until there exists Σ for which $[\Sigma] \cdot [C_j] \neq 0$ for some j. Because C_0, \dots, C_m are J-holomorphic, Σ must intersect them non-negatively. In our standard basis for $H_2(X_M; \mathbb{Z})$ as in the previous section, the

fact that $[\Sigma] \cdot [C_0] = 0$ and $[\Sigma]^2 = -1$ implies $[\Sigma] = \pm e_i$. Given the analysis in the previous section of how to write $[C_j]$ in terms of this standard basis, we find that $[\Sigma] \cdot [C_j] \in \{-1,0,1\}$ for every $j=0,\cdots,m$. Since Σ and C_j must intersect positively, either $\Sigma = C_j$ for some j, or $[\Sigma] \cdot [C_j] \in \{0,1\}$ for all $j=0,\cdots,m$. Lisca analyzes the relations between the e_i 's showing up with non-zero coefficients in different $[C_j]$'s within a linear plumbing, and proves that blowing down Σ either reduces the length of the linear plumbing or reduces the absolute value of one of the self-intersection numbers of a C_j (j>0), but the linear plumbing remains linear. This implies the conclusion of Lisca's theorem by induction.

In our case, we blow down a J-holomorphic sphere Σ , which may intersect any number of arms in the star-shaped graph. After blowing down, at least one arm is reduced in complexity, and each linear chain of symplectic spheres (originally these are the k arms) remains linear. It is possible that two of these linear chains intersect after a blow-down, so the graph would no longer be star-shaped. Because of the existence of a J-holomorphic sphere to blow down and that the homological properties of the C_j do not depend on any assumptions about the non-intersection of the various arms, this does not prevent us from applying induction as in the linear case. We simply need to keep track of each linear chain separately, even as the chains intersect each other.

The conclusion is that each arm eventually descends to two symplectic spheres each of self-intersection number 1, one of which is the original C_0 (since all blowdowns were done disjointly from C_0). Therefore in total we have d+1 symplectic spheres of self-intersection number 1 inside ($\mathbb{C}P^2, \omega_0$). Depending on choices of symplectic blow-ups determining ω_M , the resulting symplectic form ω_0 may no longer be the same as the standard Kahler form on $\mathbb{C}P^2$. However, if we only want to classify these symplectic fillings up to diffeomorphism, we may assume that $\omega_0 = \omega_{std}$.

2.5.2. Uniqueness of the pair after blowing down. We need to analyze possible smooth isotopy classes of a regular neighborhood of d+1 symplectic spheres in $(\mathbb{C}P^2, \omega_{std})$, each homologous to $\mathbb{C}P^1 \subset \mathbb{C}P^2$. We also have that our original J descends to an almost-complex structure J_0 on $\mathbb{C}P^2$, which is tamed by $\omega_0(=\omega_{std})$, and the remaining d+1 spheres in the reduction of the dual graph are J_0 holomorphic. We cannot assume that J_0 is the standard almost complex structure on $\mathbb{C}P^2$ since we had to choose J originally so that each of the curves $C_0 \cdots C_m$ were J-holomorphic. However, because J_0 is tamed by ω_{std} , it is homotopic through almost complex structures tamed by ω_{std} to the standard almost complex structure J_{std} . This homotopy will allow us to isotope our symplectic spheres to complex projective lines in the following lemma.

Working with curves which are J-holomorphic for some J ensures that we need not worry about algebraically cancelling intersection points between curves since all intersections are positive. We want to control the way these d+1 spheres intersect, because a smooth isotopy of each of the d+1 spheres will extend to a smooth isotopy of a regular neighborhood of their union only when the way these spheres intersect is preserved. Because all of these spheres must represent the homology class ℓ and they are all J_0 -holomorphic, each pair of spheres must intersect at a single point. Because the blow-downs were disjoint from C_0 and each of the other d spheres intersected C_0 in a different point initially, this remains true after blowing down. The other d spheres may intersect each other at multi-points if before blowing

down, a group of them intersected a common exceptional sphere. We will use the notation \mathcal{I}_j^d to refer to a particular intersection configuration of d+1 spheres for which each pair intersects uniquely and positively. The intersection configuration \mathcal{I}_j^d is specified by a diagram depicting d+1 (real) lines in the plane (each representing a sphere in $\mathbb{C}P^2$) as in Figure 5, where the multi-points of intersection are the relevant information.

First we would like to smoothly isotope our J_0 holomorphic spheres to complex projective lines, while keeping the intersection configuration fixed. A theorem of Gromov allows us to isotope each of the spheres through J-holomorphic curves to complex projective lines, but unfortunately we cannot always preserve the intersection configuration in sufficiently complicated configurations. However, we are able to control this for the configurations given by Figure 5. These configurations will cover all of those we will obtain by blowing down dual graphs for dually positive Seifert fibered spaces with 3,4 or 5 singular fibers or with k singular fibers and $e_0 \leq -k-3$ (the more complicated configurations can arise when $e_0 = -k-1$ or -k-2 and k is large).

The reason we have control over the configurations when $e_0 \leq -k - 3$ comes from the formula for the homology classes in Lemma 2.5. After blowing down the exceptional spheres, the proper transforms of a subset of the spheres C_0, C_1, \dots, C_d will have a common intersection if they previously intersected the same exceptional sphere. Such intersections are determined by the homology classes (due to J-holomorphicity). If we also take into account the fact that C_0 intersects each of the other spheres in a distinct double point, then the only possible configurations to consider are \mathcal{I}_1^d and \mathcal{I}_2^d (Figures 5a and 5b) containing $d+1 \geq 4$ spheres. However, throughout our proof that we can isotope J_0 holomorphic spheres in such a configuration to complex projective lines in this configuration, we will also need to consider the intersection configuration \mathcal{I}_3^d in Figure 5c.

We can also manage all the possible configurations of a small number of lines, which allows us to classify fillings of dually positive Seifert fibered spaces with k=3,4 or 5 singular fibers. The possible intersection relations which can arise (keeping in mind that C_0 intersects each of the other spheres in a different point) are given by \mathcal{I}_1^d , \mathcal{I}_2^d , \mathcal{I}_4^4 , \mathcal{I}_5^5 , \mathcal{I}_6^5 , and \mathcal{I}_7^d . We will additionally use \mathcal{I}_3^d , \mathcal{I}_8^d , and \mathcal{I}_9^d throughout the proof, though they will not arise as initial intersection configurations. See Figure 5.

Lemma 2.7. Let J_0 be an almost complex structure on $\mathbb{C}P^2$ tamed by ω_{std} . Suppose $C_0, C_1, \dots C_d$ are J_0 -holomorphic spheres homologous to $\mathbb{C}P^1 \subset \mathbb{C}P^2$ such that C_0, C_1, \dots, C_d intersect according to one of the configurations given by one of $\mathcal{I}_1^d, \mathcal{I}_2^d, \mathcal{I}_4^d, \mathcal{I}_5^5, \mathcal{I}_6^5$, or \mathcal{I}_7^d as given by Figure 5. Then a regular neighborhood of $\bigcup_{i=0}^d C_i$ is isotopic to a regular neighborhood of complex projective lines in the same intersection configuration.

Proof. Because J_0 and J_{std} are both tamed by ω_{std} , there exists a family of almost complex structures $\{J_t\}$ on $\mathbb{C}P^2$ starting at J_0 and ending at $J_1 = J_{std}$. A theorem of Gromov [15] states that for any J tamed by the standard symplectic structure on $\mathbb{C}P^2$, any two points $v_1 \neq v_2 \in \mathbb{C}P^2$ lie on a unique non-singular rational (i.e. diffeomorphic to S^2) J-holomorphic curve homologous to $\mathbb{C}P^1 \subset \mathbb{C}P^2$. Therefore for each J_t in our homotopy, we can find a unique J_t -holomorphic sphere through two given points.

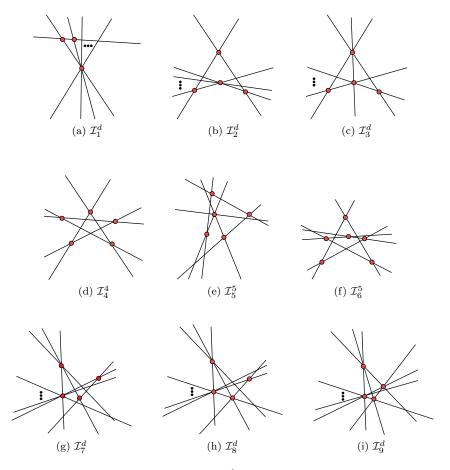


FIGURE 5. Each configuration \mathcal{I}_j^d represents a union of d+1 spheres C_0, C_1, \cdots, C_d for which each pair intersects at a single point. In our cases, C_0 will always intersect each of the other lines in a distinct double point. The diagrams represent how some of the other intersections can coincide at multi-points in the configurations we need to consider. We assume $d \geq 3$ for $\mathcal{I}_1^d, \mathcal{I}_2^d$, and \mathcal{I}_3^d and that $d \geq 5$ for $\mathcal{I}_7^d, \mathcal{I}_8^d$, and \mathcal{I}_9^d . (Color available online.)

This provides an isotopy of each sphere C_0, C_1, \dots, C_d to a complex projective line (since these are the unique J_{std} -holomorphic spheres homologous to $\mathbb{C}P^1$). During this isotopy we can fix exactly two points on each sphere. This allows us to control the changes in the intersection configurations. At all times during this isotopy, each pair C_i, C_j intersect positively at a unique point (since they will both be J_t -holomorphic). We will first analyze precisely what changes can can occur in the intersection configuration throughout this isotopy.

For the configuration \mathcal{I}_1^d , there are precisely two intersection points on each of C_1, \dots, C_d , so for $i = 1, \dots, d$, we will choose the corresponding sphere C_i^t to be the unique J_t -holomorphic sphere homologous to $\mathbb{C}P^1$ through those fixed points.

Table 1. Possible degenerations of each configuration that can occur during an isotopy through J_t holomorphic spheres fixing the intersection points corresponding red dots in Figure 5.

Original configuration	\mathcal{I}_1^d	\mathcal{I}_2^d	\mathcal{I}_3^d	\mathcal{I}_4^4
Possible degenerations	none	\mathcal{I}_3^d	none	$\mathcal{I}_2^4,\mathcal{I}_3^4$

Original configuration	\mathcal{I}_5^5	\mathcal{I}_6^5	\mathcal{I}_7^d	\mathcal{I}_8^d	\mathcal{I}_9^d
Possible degenerations	$\mathcal{I}_2^5, \mathcal{I}_3^5, \mathcal{I}_7^5, \mathcal{I}_8^5, \mathcal{I}_9^5$	$\mathcal{I}_5^5, \mathcal{I}_7^5, \mathcal{I}_8^5, \mathcal{I}_9^5$	$\mathcal{I}_8^d, \mathcal{I}_9^d$	\mathcal{I}_9^d	none

Let C_0^t be the unique J_t holomorphic sphere homologous to $\mathbb{C}P^1$ through the points where $C_0^0 = C_0$ intersects $C_1^0 = C_1$ and where it intersects $C_2^0 = C_2$. Then for all $0 \leq t \leq 1, C_1^t, \cdots, C_d^t$ must continue to pass through a common point, and cannot intersect anywhere else. The intersections of C_0^t with C_1^t and C_2^t are similarly fixed. While the intersections of C_0^t with C_i^t for $i \geq 3$ are not fixed points, these pairs must continue to intersect at double points since no two C_i^t for $i = 1, \cdots, d$ can intersect at any point away from their common d-fold intersection point, and C_0 cannot pass through this d-fold intersection because it intersects C_1 uniquely at a different point.

In general, if at a given intersection point, we choose to fix that point throughout the isotopy on every sphere C_i^t for which C_i^0 passes through that point, then that intersection is preserved (though potentially other spheres may pass through that point during the isotopy if they are not otherwise constrained). In Figure 5 we indicate such points by a red dot. We are allowed to fix these points as long as there are no more than two red dots on each sphere. Each of the configurations we are considering have the key property that no sphere passes through more than two multi-points, so we can place red dots on all the multi-points. This means that if the intersection configuration changes during the isotopy $\{\bigcup_{i=0}^d C_i^t\}_{t\in[0,1]}$, at worst it becomes a less generic intersection configuration.

We may analyze how double point intersections which are not fixed can move through the isotopy onto a third sphere, as in the argument above showing that the intersection configuration \mathcal{I}_1^d is fixed under the isotopy through J_t -holomorphic spheres. The constraints we have are that each pair of spheres intersects at a unique point, and each sphere must pass through its two points we choose to keep fixed. These points include those indicated by a red dot in Figure 5, and the other fixed points do not provide particularly useful information except to provide the isotopy via Gromov's theorem. Analyzing this information, we obtain the information given by Table 1.

Now suppose we have any of these starting intersection configurations and we have chosen two points on each sphere such that any sphere passing through a point corresponding to a red dot in Figure 5 has that point chosen. These points together with the homotopy $\{J_t\}$ define an isotopy of the d+1 spheres which may change the intersection configuration as allowed by Table 1. If at some point in the isotopy the intersection configuration changes, redefine the isotopy from the time that the first degeneration occurs onwards by changing the choice of two points on

each sphere so that they include the points corresponding to red dots in the new (more degenerate) configuration. Then repeat this again at a later time value if the intersection configuration changes again. Notice that after finitely many steps (at most three in these cases), the intersection configuration must remain fixed under the isotopy. Therefore we obtain an isotopy from our original configuration of d+1 J_0 -holomorphic spheres to d+1 complex projective lines where the intersection configuration changes at most by finitely many degenerations.

Now we will show that we can modify an isotopy that degenerates once to an isotopy that preserves the intersection configuration and passes through J_t -holomorphic spheres for all but a small interval near the time where the degeneration originally occured.

Each of these possible degenerations occurs when a sphere $C_{i_0}^t$ which originally intersected other spheres $C_{i_1}^t, \dots, C_{i_\ell}^t$ generically in double points for $t < t_0$ is isotoped so that it intersects $C_{i_1}^t, \dots, C_{i_\ell}^t$ at their common intersection point $(\ell \geq 2)$ for $t \geq t_0$, or when this occurs in finitely many different places at the same time t_0 .

Because the intersection points corresponding to red dots are fixed and distinct, $C_{i_0} \cap C_{i_j}$ for $j=1,\cdots,\ell$ cannot be points marked by a red dot. However, the intersection $C_{i_1} \cap \cdots \cap C_{i_\ell}$ can be (and usually will be) marked by a red dot, as the sphere $C_{i_0}^t$ approaches that fixed intersection point. Notice that in the intersection configurations we are considering, no sphere has more than three intersection points that are not marked by a red dot, except in $\mathcal{I}_1^d, \mathcal{I}_2^d, \mathcal{I}_3^d, \mathcal{I}_7^d, \mathcal{I}_8^d$ and \mathcal{I}_9^d . The configurations $\mathcal{I}_1^d, \mathcal{I}_3^d$, and \mathcal{I}_9^d cannot degenerate at all, the configurations \mathcal{I}_2^d and \mathcal{I}_8^d can only degenerate at one place, and none of the spheres in \mathcal{I}_7^d containing four intersection points not marked by a red dot can degenerate in a way that brings two pairs of these four points together. Therefore, if degenerations occur in multiple places at once in any of the configurations, the corresponding C_{i_0} 's will be distinct. Therefore we can perform all our modifications to the isotopy near degenerations in distinct places independently.

After a degeneration at $t=t_0$, the isotopy is defined by fixing pairs of points on each sphere including all the red dots on the more degenerate intersection configuration. Therefore one of the two fixed points on $C_{i_0}^t$ is at its intersection with $C_{i_1}^t \cap \cdots \cap C_{i_\ell}^t$ for all $t \geq t_0$.

Choose an injective parametrization of the spheres $\bigcup_{i=0}^{d} C_i^t$,

$$F: \bigsqcup_{i=0}^{d} S_i^2 \times I \to \mathbb{C}P^2,$$

so that $F(S_i^2,t)=C_i^t$. Let $p\in S_{i_1}^2$ be the unique preimage in $S_{i_1}^2$ of $v_1=C_{i_0}^t\cap C_{i_1}^t\cap \cdots\cap C_{i_\ell}^t\in \mathbb{C}P^2$ for $t\geq t_0$ (note that one can choose the parameterization F so that p is the same for all $t\geq t_0$ since its image is fixed as $t\geq t_0$ varies). Let $v_0\in \mathbb{C}P^2$ be the other point on $C_{i_0}^{t_0}$ which is fixed during the isotopy as $t\geq t_0$ varies. Choose a sufficiently small injective parametrized path $\gamma:I\to S_{i_1}^2$ with coordinate $s\in I$, such that $\gamma(0)=p$. We will extend our isotopy F to a two parameter isotopy G depending on s and t for all $t\geq t_0$ as follows. For $t\geq t_0$ and $s\in I$, let $G(S_{i_0},t,s)=C_{i_0}^{(t,s)}$ be the unique J_t -holomorphic sphere homologous to $\mathbb{C}P^1$ that passes through v_0 and let $F(\gamma(s),t)\in C_{i_1}$. Let G(x,t,s)=F(x,t) for $x\in S_i^2$ where $i\neq i_0$. Then for s=0 and $t\geq t_0$, $C_{i_0}^{(t,0)}=C_{i_0}^t$. We claim that for

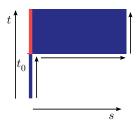


FIGURE 6. A schematic for the isotopies F and G. The blue indicates where F and G map into the original less degenerate configuration, and the red indicates where F and G map into the more degenerate configuration. (Color available online.)

s>0 and $t\geq t_0,$ $C_{i_0}^{(t,s)}$ intersects each $C_{i_j}^{(t,s)}$ for $j=1,\cdots,\ell$ in a distinct double point so the degeneration is undone. This is because $C_{i_0}^{(t,s)}$ necessarily intersects $C_{i_1}^{(t,s)}$ at $F(\gamma(s),t)\neq F(p,t)=C_{i_1}^{(t,s)}\cap\cdots\cap C_{i_\ell}^{(t,s)}$, so $C_{i_0}^{(t,s)}$ cannot intersect $C_{i_j}^{(t,s)}$ at its intersection with $C_{i_{j'}}^{(t,s)}$ for $j,j'\in\{1,\cdots,\ell\}$. By choosing γ to be a sufficiently small path, the intersections of C_{i_0} with other C_i will be preserved (as generic double points except possibly at v_0 which is fixed). Additionally, note that $C_{i_0}^{(t,s)}$ is distinct from $C_{i_0}^{(t,s')}$ for $s\neq s'$ since their intersections with $C_{i_1}^{(t,s)}$ are different by injectivity of γ .

Now we can define an isotopy of the d+1 spheres which preserves the original intersection configuration except at a single point during the isotopy where it degenerates by following the original isotopy until time t_0 , then following the isotopy through $\bigcup C_i^{(t,s)}$ for $t=t_0, s\in[0,1]$, and then through $s=1, t\in[t_0,1]$. (See Figure 6 for a schematic.) We can modify this isotopy in a small neighborhood of the single degeneration point, by briefly moving out of the space of J_t -holomorphic curves. Consider the space of all smooth immersions of d+1 spheres, each homologous to $\mathbb{C}P^1$ with given intersection data. This space includes all the J-holomorphic configurations we have considered as a subspace. The main problem with working with smooth but not J-holomorphic spheres, is that a generic isotopy through d+1smooth embeddings of such spheres passes through points where the number of geometric intersections between any two spheres can increase by adding an algebraically cancelling pair. However, if we stay sufficiently close to J-holomorphic configurations we can avoid this, since algebraically cancelling pairs are introduced after a tangency between two spheres which is a closed condition. By construction we have two paths from the degenerate point in our isotopy out into the space of d+1 spheres intersecting in the configuration \mathcal{I} that we are interested in. Choosing a sufficiently small ε , we will find a path through embeddings of d+1 spheres homologous to $\mathbb{C}P^1$ intersecting according to \mathcal{I} , from $F(\bigsqcup_{i=0}^d S_i^2, t_0 - \varepsilon) = \bigcup_{i=0}^d C_i^{(t_0 - \varepsilon, 0)}$ to $G(\bigsqcup_{i=0}^d S_i^2, \underline{t_0}, \varepsilon) = \bigcup_{i=0}^d C_i^{(t_0, \varepsilon)}$. Let N_1, N_2 be small connected neighborhoods in $S_{i_0}^2$ so that $\overline{N_1} \subset N_2$ and the images $F(N_q, t) \subset C_{i_0}^t$ for $t \in [t_0 - \varepsilon, t_0], q = 1, 2$ contain the intersections of $C_{i_0}^t$ with $C_{i_j}^t$ for $j=1,\cdots,\ell$ but no other intersections, and similarly $G(N_q,t_0,s)\subset C_{i_0}^{(t,s)}$ contains the intersections of $C_{i_0}^{(t_0,s)}$ with $C_{i_j}^{(t_0,s)}$ for $j=1\cdots,\ell,\ s\in[0,\varepsilon]$ and no other intersections. We construct the isotopy

 $I: \prod_{i=0}^n S_i^2 \times I \to \mathbb{C}P^2$ as follows:

$$I(x,r) = \begin{cases} F(x,t_0 - \varepsilon + 2r\varepsilon) & \text{for } x \notin N_1, r \in [0,\frac{1}{2}], \\ G(x,t_0,2\varepsilon(r-\frac{1}{2})) & \text{for } x \notin N_1, r \in [\frac{1}{2},1], \\ H(x,r) & \text{for } x \in N_2. \end{cases}$$

Here $H: N_2 \times I \to \mathbb{C}P^2$ is a generic isotopy everywhere close to, and for r = 0, 1 or $x \in N_2 \setminus N_1$ agreeing with, the isotopy $\widehat{H}: N_2 \times I \to \mathbb{C}P^2$ defined by

$$\widehat{H}(x,r) = \begin{cases} F(x,t_0 - \varepsilon + 2r\varepsilon) & \text{for } r \in [0,\frac{1}{2}], \\ G(x,t_0,2\varepsilon(r - \frac{1}{2})) & \text{for } r \in [\frac{1}{2},1]. \end{cases}$$

Note that a generic (1-parameter) isotopy mapping N_2 (which is 2-dimensional) into $\mathbb{C}P^2$ (which is 4-dimensional) will avoid the (0-dimensional) point $v_1 \in \mathbb{C}P^2$ where $C_{i_1}^{(t,s)}$ intersects $C_{i_2}^{(t,s)}, \cdots, C_{i_\ell}^{(t,s)}$ for all (t,s) (identifying C_i^t with $C_i^{(t,0)}$ for $t < t_0$). By taking H generic and close to \widehat{H} we can ensure that N_2 maps into a small neighborhood of v_1 (thus avoiding introducing new intersections with other spheres) for each r and $H(N_2, r)$ uniquely intersects each $H(S_{i_j}^2, r)$ in a distinct double point.

Therefore I provides an isotopy we can append between $F(\cdot,t)$ for $t\in[0,t_0-\varepsilon]$ and $G(\cdot,t_0,s)$ for $s\in[\varepsilon,1]$ followed by $G(\cdot,t,1)$ for $t\in[t_0,1]$. Putting these all together we find an isotopy of the spheres C_0,\cdots,C_d which preserves the intersection configuration.

We conclude our argument by dealing with the possibility that multiple degenerations occur as we go through the homotopy $\{J_t\}$. If the intersection configuration changes at times t_0, t_1, \dots, t_n during the isotopy defined by $\{J_t\}$, then repeat the process above starting at the most degenerate configuration $(t \in [t_n, 1])$. Use the process above to create an isotopy for $t \in [t_{n-1}, 1]$ that preserves the intersection configuration of the spheres that occurs at time t_{n-1} . Then repeat the process to obtain an isotopy over successively larger time intervals $[t_{n-1}, 1] \supset [t_{n-1}, 1] \supset \cdots \supset [t_0, 1] \supset [0, 1]$, which fix the intersection configuration that occurs at the initial point of the interval.

This tells us that, up to isotopy of a regular neighborhood, we may assume that the blow-down of our dual graph is a set of complex projective lines in $\mathbb{C}P^2$. We would like to know that the intersection information of the complex projective lines determines the isotopy type of a regular neighborhood of their union. It suffices to show that we can get from any collection of complex projective lines to any other of the same intersection configuration through such collections of lines.

Lemma 2.8. The space of d+1 lines of intersection with configuration $\mathcal{I}_1^d, \mathcal{I}_2^d, \mathcal{I}_4^d, \mathcal{I}_5^5, \mathcal{I}_6^5$, or \mathcal{I}_7^d is connected and non-empty.

Proof. Fix $(a,d) \in \{(1,d), (2,d), (4,4), (5,5), (5,6), (d,7)\}$. Order the lines in the configuration C_0, C_1, \dots, C_d where C_0 intersects all other lines in double points. For $1 \leq n \leq d$, let $S_n(\mathcal{I}_a^d)$ denote the intersection configuration formed by the subset of lines $C_0 \cup \dots \cup C_n$. Note that $S_d(\mathcal{I}_a^d) = \mathcal{I}_a^d$, and increasing n corresponds to placing additional lines in the configuration as a subset of \mathcal{I}_a^d . Let M_n denote the moduli space of complex projective lines intersecting according to the configuration $S_n(\mathcal{I}_a^d)$.

Any complex projective line is determined by choosing two distinct points in $\mathbb{C}P^2$. Through a diffeomorphism given by an element in $PGL(2,\mathbb{C})$ we may assume that two of the lines are standardly given as $C_0 = \{[0:z_1:z_2]\}$ and $C_1 = \{[z_0:0:z_2]\}$. Therefore, when n=1, \mathcal{M}_n is a point after we mod out by the $PGL(2,\mathbb{C})$ action on $\mathbb{C}P^2$.

Any other line intersects each of C_0 and C_1 in a single point. Because C_0 intersects each line in a distinct point, there are no other C_i passing through $C_0 \cap C_1$. Therefore C_2 intersects C_0 and C_1 each away from $C_0 \cap C_1$, therefore (regardless of our choice of (a, d)) \mathcal{M}_2 is parametrized by $[C_0 \setminus (C_0 \cap C_1)] \times [C_1 \setminus (C_0 \cap C_1)]$.

Now, we proceed by induction on $1 \leq n \leq d$. Here it will be important that (a,d) is one of the choices specified in the statement. In particular, no line in the configuration contains more than two multi-points of intersection (where multi-point means a point where at least three lines pass through the same point).

Inductively assume that the moduli space \mathcal{M}_{n-1} of configurations of projective lines $C_0, C_1, \cdots, C_{n-1}$ is a non-empty connected subset of $[C_0 \setminus (C_0 \cap C_1)]^{a_{n-1}} \times [C_1 \setminus (C_0 \cap C_1)]^{b_{n-1}}$. There are three cases for how C_n is determined. The first is that C_n meets C_j in a double point for all $0 \leq j \leq n-1$. The second is that C_n passes through the common intersection of $C_{j_1} \cap \cdots \cap C_{j_\ell}$ for $\ell \geq 2$, $1 \leq j_1 < j_2 < \cdots < j_\ell \leq n-1$, and C_n meets C_j at a double point for $j \neq j_1, \cdots, j_\ell$. The third is that C_n passes through $C_{j_1} \cap \cdots \cap C_{j_\ell}$ and $C_{j_{\ell+1}} \cap \cdots \cap C_{j_{\ell+\ell'}}$ for $\ell \geq 2$, $1 \leq j_i \leq n-1$, and j_i distinct, but C_n intersects C_j at a double point for $j \in \{1, \cdots, n-1\} \setminus \{j_1, \cdots, j_{\ell'}\}$. Note that these are all the possibilities we must consider, because in all of the configurations listed in the statement of the theorem, each line contains no more than two multi-intersection points.

In the first case, C_n is determined by choosing its intersection points on $C_0 \setminus (C_0 \cap C_1)$ and $C_1 \setminus (C_0 \cap C_1)$, but some pairs $(v_1, v_2) \in [C_0 \setminus (C_0 \cap C_1)] \times [C_1 \setminus (C_0 \cap C_1)]$ will determine a line that passes through some intersection point $C_j \cap C_{j'}$ for $0 \leq j, j' < n$. However, this is a real codimension 4 phenomenon because there is a real 2-parameter family of projective lines that pass through points on C_j in a neighborhood of $C_j \cap C_{j'}$. Therefore the subset of $\{(x, v_1, v_2) \in \mathcal{M}_{n-1} \times [C_0 \setminus (C_0 \cap C_1)] \times [C_1 \setminus (C_0 \cap C_1)]\}$ corresponding to configurations where C_n does not intersect each C_j for j < n in a double point is a codimension 2 subset, so its complement, \mathcal{M}_n , is connected and satisfies the inductive hypothesis.

In the second case, C_n is required to pass through $C_{j_1} \cap \cdots \cap C_{j_\ell}$ and must avoid other intersections of the C_j , for j < n. The point $C_{j_1} \cap \cdots \cap C_{j_\ell}$ together with a point on $C_0 \setminus (C_0 \cap C_1)$ determines a unique line, and the configuration space of lines C_0, \cdots, C_{n-1} together with this line is parameterized by $\mathcal{M}_{n-1} \times [C_0 \setminus (C_0 \cap C_1)]$, which is connected by the inductive assumption. Again, we must remove points from this space for which the last line passes through intersections of the $C_j, j < n$, other than $C_{j_1} \cap \cdots \cap C_{j_\ell}$, but this is a real codimension 2 phenomenon, so the complement, \mathcal{M}_n is connected and satisfies the inductive hypothesis.

In the third case, C_n is required to pass through two points, $C_{j_1} \cap \cdots \cap C_{j_\ell}$ and $C_{j_{\ell+1}} \cap \cdots \cap C_{j_{\ell+\ell'}}$, which are completely determined by the point in \mathcal{M}_{n-1} . Because this case only occurs when a line in the final configuration, \mathcal{I}_a^d , passes through two multi-intersection points, this case only arises when $\mathcal{I}_a^d = \mathcal{I}_7^d$. Since a line is determined by two points, we gain no additional parameters. However, to get \mathcal{M}_n , we may need to cut out a subspace of \mathcal{M}_{n-1} for which the intersection points

 $C_{j_1} \cap \cdots \cap C_{j_\ell}$ and $C_{j_{\ell+1}} \cap \cdots \cap C_{j_{\ell+\ell'}}$ are collinear with an additional intersection point $C_j \cap C_{j'}$ for $(j,j') \notin \{j_1,\cdots,j_\ell\}^2 \cup \{j_{\ell+1},\cdots,j_{\ell+\ell'}\}^2$.

In \mathcal{I}_7^d there are exactly two intersection points of multiplicity > 2, and there is one C_n passing through both of these multi-intersection points. Therefore, case 3 occurs only at the induction at stage n, if the ordering is chosen such that these multi-intersection points are determined by points of intersection x_i and x_j of the lines $C_0, C_1, \cdots, C_{n-1}$. Notice that C_0 is the only line in the intersection configuration which does not pass through these multi-intersection points (C_0 is necessarily a line which only has double point intersections in our chosen ordering). Therefore any point x_m which is an intersection point of $\{C_0, C_1, \cdots, C_{n-1}\}$ must lie on at least one of the lines C_1, \cdots, C_{n-1} . Since each of C_1, \cdots, C_{n-1} either passes through x_i but not x_j or passes through x_j but not x_i , x_m cannot be collinear with x_i and x_j . Therefore, in this case $\mathcal{M}_n \cong \mathcal{M}_{n-1}$.

Inductively this proves that \mathcal{M}_d is parameterized by a non-empty, connected subspace of $[C_0 \setminus (C_0 \cap C_1)]^{a_d} \times [C_1 \setminus (C_0 \cap C_1)]^{b_d}$.

Remark. In contrast, if we considered a configuration where some of the lines passed through three or more multi-points, the fact that such a line exists puts a constraint on the variables determining the earlier lines. These yield polynomial relations on the homogeneous coordinates of the points determining the lines. With sufficiently many lines, one can construct intersection configurations for which the space of complex projective lines in that configuration is disconnected or empty.

We conclude that for the listed configurations, the homology representation of the dual graph determines a unique embedding of a regular neighborhood of the dual graph. This is because the regular neighborhood of the dual graph can be obtained by blowing up one of the above-discussed configurations at points specified by the homology representation.

Note that although this provides an embedding of this dual configuration of spheres into a symplectic manifold, it does not ensure that there is a concave neighborhood of this configuration (it is not known whether this always exists). Therefore we only obtain upper bounds on the number of symplectic fillings, and will find lower bounds through other means in our examples.

2.6. **Proof of Theorem 1.1.** We can now obtain the finiteness results of Theorem 1.1 as a corollary.

Proof. Given any symplectic filling, it can be glued to the concave neighborhood of the dual configuration to give $(\mathbb{C}P^2\# M\overline{\mathbb{C}P^2},\omega_M)$ by sections 2.1, 2.2, and 2.3. The homology classes the spheres in the dual configuration can represent in $H_2(\mathbb{C}P^2\# M\overline{\mathbb{C}P^2})$ are restricted as discussed in section 2.4. If the number of singular fibers is k=3,4 or 5 and $e_0=-k-1$, the number of arms in the dual graph d is sufficiently small so the only possible intersection configurations of the image of the spheres in the dual graph after blowing down are $\mathcal{I}_1^3, \mathcal{I}_2^3, \mathcal{I}_1^4, \mathcal{I}_2^4, \mathcal{I}_4^4, \mathcal{I}_1^5, \mathcal{I}_2^5, \mathcal{I}_5^5, \mathcal{I}_6^5$, or \mathcal{I}_7^5 . When $e_0=-k-2$ and k=3,4,5, the results of Lemma 2.5 imply that the only possible intersection configurations are $\mathcal{I}_1^4, \mathcal{I}_2^4, \mathcal{I}_1^5, \mathcal{I}_2^5, \mathcal{I}_7^5, \mathcal{I}_1^6, \mathcal{I}_2^6$, and \mathcal{I}_7^6 . When $e_0 \leq -k-3$, Lemma 2.5 implies that the only possible intersection configurations are \mathcal{I}_1^d and \mathcal{I}_2^d where $d=-e_0-1$. Therefore, Lemmas 2.7 and 2.8 imply that a regular neighborhood of the image of the spheres in the dual graph after blowing down embeds uniquely up to isotopy into $\mathbb{C}P^2$. Therefore the embedding of a regular neighborhood of the dual graph is uniquely determined

up to isotopy by blowing up at the points dictated by the homology classes each sphere in the dual graph represents in $H_2(\mathbb{C}P^2\# M\overline{\mathbb{C}P^2})$. The number of possible embeddings of a neighborhood of the dual graph into $\mathbb{C}P^2\# M\overline{\mathbb{C}P^2}$ provides an upper bound on the number of convex symplectic fillings of the corresponding Seifert fibered space with contact structure ξ_{pl} .

By section 2.4, in terms of a standard basis (ℓ, e_1, \dots, e_M) for $H_2(\mathbb{C}P^2 \# M \overline{\mathbb{C}P^2})$, the homology classes $[C_0], \dots, [C_m]$ must have the form

$$\begin{aligned} [C_0] &=& \ell \\ [C_1] &=& \ell - e_{i_1^1} - \dots - e_{i_{n_1+1}^1} \\ & \vdots \\ [C_k] &=& \ell - e_{i_1^k} - \dots - e_{i_{n_k+1}^k} \\ [C_{k+1}] &=& \ell - e_{i_1^{k+1}} - e_{i_2^{k+1}} \\ & \vdots \\ [C_d] &=& \ell - e_{i_1^d} - e_{i_2^d} \\ [C_{d+1}] &=& e_{i_0^{k+1}} - e_{i_1^{k+1}} - \dots - e_{i_{n_k+1}-1} \\ & \vdots \\ [C_m] &=& e_{i_0^m} - e_{i_1^m} - \dots - e_{i_{n_m-1}^m}, \end{aligned}$$

so up to symmetry of relabelling the e_i , the only possible differences are determined by the pairs (j,p),(j',p') for which $i_p^j=i_{p'}^{j'}$. There are significant restrictions determined by the intersection data of the spheres, but we can easily get a very loose upper bound on the number of possibilities. If $N=\sum_{j=1}^m(n_j+1)$, then there are less than N different e_i which have non-zero coefficient in any $[C_j]$. Thus there are at less than N^N arrangements of these e_i into the slots above. We also may assume that a minimal symplectic filling is the complement of one of these embeddings in $\mathbb{C}P^2\# M\overline{\mathbb{C}P^2}$ where $M\leq N$, because N is the largest number of exceptional spheres which intersect the dual configuration of spheres. Therefore there are certainly no more than N^{N+1} diffeomorphism types of minimal symplectic fillings of a given Seifert fibered space satisfying the hypotheses of the theorem with the contact structure ξ_{nl} .

For a general dually positive Seifert fibered space (no restrictions on k or e_0 other than $e_0 \leq -k-1$), the results discussed in sections 2.1, 2.2, 2.3, and 2.4 still hold, though we no longer have a proof that the dual graph has a unique embedding into $\mathbb{C}P^2\# M\overline{\mathbb{C}P^2}$ for each homology representation. However, we still have that any strong symplectic filling glues to the dual graph to give $\mathbb{C}P^2\# M\overline{\mathbb{C}P^2}$, so the homology of the filling fits into the following long exact sequence by the Mayer-Vietoris theorem:

$$0 \to H_4(\mathbb{C}P^2 \# \overline{\mathbb{C}P^2}) \to H_3(Y) \to H_3(\text{dual graph}) \oplus H_3(\text{filling}) \to H_3(\mathbb{C}P^2 \# \overline{\mathbb{C}P^2}).$$

This immediately implies $H_3(\text{filling}) = 0$ after noting which terms are closed manifolds of the correct dimension. The rest of the Mayer-Vietoris sequence over rational

coefficients is as follows:

$$H_{3}(\mathbb{C}P^{2}\#M\overline{\mathbb{C}P^{2}};\mathbb{Q}) \to H_{2}(Y;\mathbb{Q}) \to H_{2}(\text{dual graph};\mathbb{Q}) \oplus H_{2}(\text{filling};\mathbb{Q})$$
$$\to H_{2}(\mathbb{C}P^{2}\#M\overline{\mathbb{C}P^{2}};\mathbb{Q}) \to H_{1}(Y;\mathbb{Q})$$
$$\to H_{1}(\text{dual graph};\mathbb{Q}) \oplus H_{1}(\text{filling};\mathbb{Q}) \to H_{1}(\mathbb{C}P^{2}\#M\overline{\mathbb{C}P^{2}}).$$

Since Y is a 3-manifold, Poincaré duality implies $H_2(Y;\mathbb{Q}) \cong H_1(Y;\mathbb{Q}) \cong \mathbb{Q}^{b_1(Y)}$. Note that the homology of the dual graph is generated by the m+1 spheres that are plumbed together. Filling in known terms of the sequence gives

$$0 \to \mathbb{Q}^{b_1(Y)} \to \mathbb{Q}^{m+1} \oplus H_2(\text{filling}; \mathbb{Q}) \to \mathbb{Q}^{M+1} \to \mathbb{Q}^{b_1(Y)} \to H_1(\text{filling}; \mathbb{Q}) \to 0.$$

Exactness at the end of the sequence implies $b_1(\text{filling}) \leq b_1(Y)$. Chasing through the rest of the sequence gives the following equation:

$$b_1(\text{filling}) + M + 1 = m + 1 + b_2(\text{filling}).$$

Therefore the Euler characteristic and signature satisfy

$$\chi(\text{filling}) = M - m + 1$$

and

$$|\sigma(\text{filling})| \leq b_2(\text{filling}) \leq M - m + b_1(Y).$$

If the symplectic filling is minimal, then every exceptional sphere in $\mathbb{C}P^2\#M\overline{\mathbb{C}P^2}$ must intersect the dual graph. Since there is some almost complex structure J for which the spheres in the dual graph are J-holomorphic and we can find J-holomorphic representatives of the exceptional spheres (as argued in section 2.5.1), the algebraic and geometric intersection numbers of these spheres coincide. In particular, every basis element $e_i \in H_2(\mathbb{C}P^2\#M\overline{\mathbb{C}P^2})$ of square -1 must appear with non-zero coefficient in the homology class $[C_j]$ of some sphere in the dual graph. As mentioned for the first half of the theorem, if $[C_j]^2 = -n_j$ for $j = 1, \dots, m$, the number of e_i showing up with non-zero coefficient in the homology of the dual graph is bounded above by $N = \sum_{j=1}^m (n_j + 1)$. Therefore

$$\chi(\text{filling}) \leq M - m + 1 \leq N$$

and

$$|\sigma(\text{filling})| \leq M - m + b_1(Y) \leq N + b_1(Y).$$

Note that N is determined by the dual graph, which can be generated given the Seifert invariants of Y.

Of course, the bound given here is far from sharp. Note that one can obtain tighter bounds in specific cases when the possible homology representations of the dual graph are known. Homology representations which are "more efficient" (namely they can be written using few distinct e_i) will yield fillings with stricter bounds on χ , σ . We will see in examples that the homology representations yielding the filling given by the original plumbing are the least efficient with the e_i 's, so it is not surprising that our examples will give alternate fillings with smaller Euler characteristic than the original plumbing.

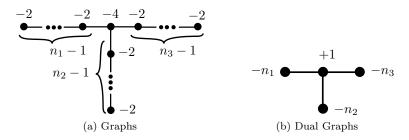


FIGURE 7. The graphs and dual graphs representing a simple family of plumbings.

3. Simplest examples

In order to see how this argument produces a list of diffeomorphism types of possible symplectic fillings of a given dually positive (Y, ξ_{pl}) , it is useful to look at concrete examples. Because the number of symplectic fillings is determined by possible ways of writing the homology classes of the spheres in the dual graph, one can obtain a simple family of examples by insisting that the dual graph is starshaped with three arms, and each arm has length one as in Figure 7b. These graphs arise as the dual graphs of three-armed graphs with central vertex decorated by -4 and all other vertices decorated by -2. These graphs depend on three positive integer parameters n_1 , n_2 , and n_3 which determine the lengths of the arms as in Figure 7a, and are the negations on the coefficients of the spheres in the arms of the dual graph. We work through the classification of convex fillings for this example in full detail to make it clear how to obtain the possible diffeomorphism types of symplectic fillings from the homological restrictions.

Now we need to determine the possible ways to write $[C_0]$, $[C_1]$, $[C_2]$, $[C_3]$ in terms of the standard basis (ℓ, e_1, \dots, e_M) for $H_2(X_M; \mathbb{Z})$. By section 2.4, we know that they must have the form

$$\begin{aligned} [C_0] &= \ell \\ [C_1] &= \ell - e_{i_1^1} - \dots - e_{i_{n_1+1}^1} \\ [C_2] &= \ell - e_{i_1^2} - \dots - e_{i_{n_2+1}^2} \\ [C_3] &= \ell - e_{i_1^3} - \dots - e_{i_{n_3+1}^3}, \end{aligned}$$

and by Lemma 2.4, $|\{i_1^j, \cdots, i_{n_j+1}^j\} \cap \{i_1^{j'}, \cdots, i_{n_{j'+1}}^{j'}\}| = 1$ for $j \neq j' \in \{1, 2, 3\}$. There are exactly two different ways three sets can have each pairwise intersection be a unique element. The first is that they all share a single element in common, and the second is that each of the three pairs has a different common element. Up to relabeling, the two possibilities are as follows:

Case A Case B
$$\begin{bmatrix}
 C_0 \end{bmatrix} = \ell \\
 \begin{bmatrix}
 C_1 \end{bmatrix} = \ell - e_1 - e_1^1 - \dots - e_{n_1}^1 \\
 \begin{bmatrix}
 C_1 \end{bmatrix} = \ell - e_1 - e_2^2 - e_1^1 - \dots - e_{n_1-1}^1 \\
 \begin{bmatrix}
 C_2 \end{bmatrix} = \ell - e_1 - e_1^2 - \dots - e_{n_2}^2 \\
 \begin{bmatrix}
 C_2 \end{bmatrix} = \ell - e_1 - e_3 - e_1^2 - \dots - e_{n_2-1}^2 \\
 \begin{bmatrix}
 C_3 \end{bmatrix} = \ell - e_1 - e_3 - e_1^3 - \dots - e_{n_2-1}^3
 \end{bmatrix}$$

Note here all of the e_i^j are all distinct from each other and from the e_m 's.

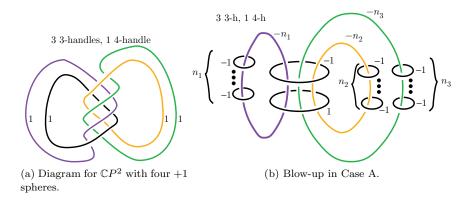
Now we can see how each of these translates into an embedding of the dual configuration. After blowing down all exceptional spheres, the proper transform of the image of the dual graph spheres under the embedding will be four symplectic spheres homologous to $\mathbb{C}P^1$, and by section 2.5.2 we may assume that they are four complex projective lines. In Case A, e_1 appears in $[C_1]$, $[C_2]$ and $[C_3]$ with non-zero coefficient, so when we blow up the sphere representing e_1 , it will be at a point of intersection of three of the original +1 spheres (the complex projective lines after blowing down must therefore be in configuration \mathcal{I}_1^3). The remaining blow-ups are done on a point of a single one of these three spheres, so that the resulting proper transforms have sufficiently negative self-intersection numbers.

In a Kirby diagram, the original four complex projective lines are represented by four +1 framed unknots with a single positive twist as in Figure 8a. In order to ensure this is a diagram for $\mathbb{C}P^2$, we cancel the extra three 2-handles with three 3-handles, and close off the manifold with a 4-handle. The first blow-up in Case A introduces a new -1 framed unknot which links three of the four original link components, untwists these three components, and reduces the framing coefficients on each by 1. The remaining blow-ups in Case A introduce more -1 framed unknots which link once with one of the three untwisted original link components and reduce the corresponding framing coefficient by 1. The resulting diagram is shown in Figure 8b.

Similarly in Case B, the blow-ups corresponding to e_1, e_2, e_3 are done at intersections of the three pairs of the three original spheres that are not C_0 , and the other blow-ups are done at points on only one of their proper transforms. In the Kirby diagram, these are visible in Figure 8c.

The symplectic dual configuration is visible in each of the previous diagrams for X_M as the union of the cores of four 2-handles together with their Seifert surfaces pushed into the 0-handle. We wish to find the diffeomorphism types of the complements of these embeddings, since these are the potential symplectic fillings.

Because the union of the Seifert surfaces of the four attaching circles for C_0, C_1 , C_2, C_3 is connected, their complement in the 0-handle retracts to a subset of the boundary of the 0-handle. Therefore the complement of the dual configuration is given by deleting the 0-handle and the four 2-handles corresponding to C_0, C_1, C_2, C_3 . It is easier to understand the diffeomorphism type of the resulting manifold with boundary by turning the manifold upside down so the boundary appears on the top instead of on the bottom. Since both possible diagrams (Figures 8b and 8c) have three 3-handles, the resulting upside down handlebody in the complement of the dual configuration will have three 1-handles, together with 2-handles corresponding to all the extra 2-handles in the diagram which are not part of the dual configuration. The boundary of the 0-handle and 1-handles is $\#_3S^2 \times S^1$. This appears as a surgery diagram given by the mirror image of the original diagram with surgery coefficients the negations of the framings. Surgery coefficients are put in brackets, $\langle \cdot \rangle$. An attaching circle of an upside down 2-handle will be a 0 framed meridian of the surgery circle corresponding to the attaching circle of the original 2-handle (see [14] for more details on turning handlebodies upside down). In order to get the diagram into a more standard form, we perform diffeomorphisms on the boundary between the 1-handlebody and the 2-handles until the boundary looks standard (like 0-surgery on the three component unlink). Once the boundary of the



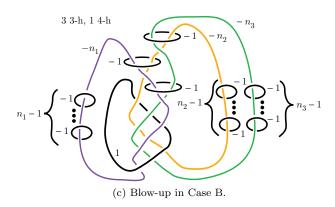


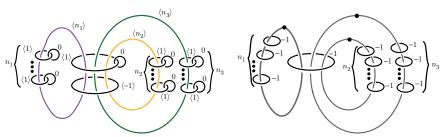
Figure 8. (Color available online.)

1-handlebody looks standard, we can replace each zero surgered unlink component with a dotted circle representing a 1-handle. The corresponding diagrams are in Figures 9a and 9b. Further handleslides and 1-2 handle cancellations yield Figure 9c.

Notice that the diagram in Figure 9c is the original plumbing of spheres, which we know has a standard symplectic structure with convex boundary inducing ξ_{pl} by Theorem 2.1.

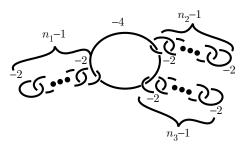
In the embedding in Figure 8c determined by Case B, we find a different possible diffeomorphism type for a symplectic filling. The complement of the dual configuration turned upside down is given by Figure 10a. Figures 10b, 10c, and 10d are obtained by surgery and handle moves.

Note that the resulting manifold in Figure 10d for Case B can be obtained from the resulting manifold in Figure 9c by a rational blow-down of the -4 framed sphere (the 1-handle and the black 2-handle form a rational homology ball). Because the symplectic structure on the manifold in Figure 9c has the -4 framed sphere as a symplectic submanifold, by an observation of Gompf [12] we can cut out this -4 framed sphere and replace it with the rational homology ball as in Figure 10d such that the symplectic structure extends over the rational homology ball. Note that



(a) Upside down complement of dual configuration in Case A

(b) Dotted circle notation

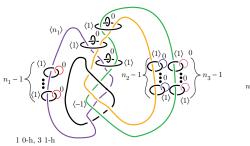


(c) Handleslides and cancellations

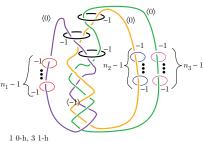
FIGURE 9. The diffeomorphism type of the possible symplectic filling from Case A. (*Color available online*.)

this does not change the symplectic structure in a neighborhood of the boundary of the plumbing of spheres in Figure 9c, so the boundary remains convex and induces the same contact structure ξ_{nl} .

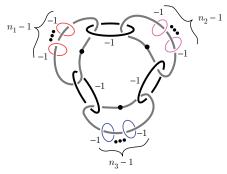
Alternatively we can arrange this diagram to be a Stein handlebody. If we arrange that the Kirby diagram is in a standard form such that all the 2-handles are contained in a rectangular box, the two attaching balls for each of the 1-handles are aligned on opposite sides of the box, and the 2-handles are attached along Legendrian tangles inside the box such that the framing coefficient is given by 1 less than the Thurston-Bennequin number of the attaching circle, then there exists a Stein structure on this 4-manifold (by [7], [13]). Replacing the dotted circle in Figure 10d with two attaching balls, and keeping track of framings carefully, after isotopies we can achieve a diagram where the 2-handles are attached along Legendrian knots with framing coefficients given by tb-1 in Figure 11. To verify that the contact structure is correct, we look at the classification of contact structures on these Seifert fibered spaces. In these cases, there are three distinct contact structures which are distinguished from each other by their Euler class. We can compute the Euler class of the induced contact structure on the boundary of a Stein manifold in a standard way involving rotation numbers of the attaching circles (see [13]). To check this matches the Euler class of the contact manifold we started with, track $PD(e(\xi))$ through a diffeomorphism taking this diagram representing the 3-manifold to the standard one as the boundary of a star-shaped plumbing of spheres.



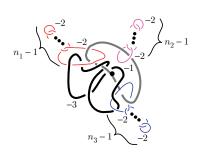
(a) Upside down complement of dual configuration in Case B



(b) Moves on surgery diagram



(c) Dotted circle notation



(d) Handle cancellation

FIGURE 10. The diffeomorphism type of the possible symplectic filling from Case B. (*Color available online*.)

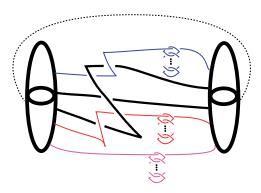


FIGURE 11. Stein handlebody for Figure 10d. Framings on 2-handles are given by 1 less than the Thurston-Bennequin number of the attaching circle. (*Color available online*.)

A third way to see the convex symplectic structure on this manifold is to view it as a Lefschetz fibration over a disk. An isotopy of the diagram in Figure 10b gives Figure 13a. We claim this diagram represents Lefschetz fibrations which induce an open book decomposition on its boundary that support the contact structure

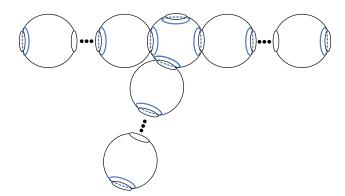
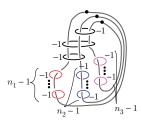


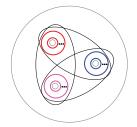
FIGURE 12. A page of the open book decomposition supporting ξ_{pl} given by [9]. A product of Dehn twists about the blue curves gives the monodromy. (*Color available online*.)

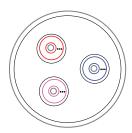
 ξ_{pl} . The Lefschetz fibration will have base D^2 and regular fibers 3-hold disks, $D_3 = D^2 \setminus \{N(p_1), N(p_2), N(p_3)\}$, where $\{N(p_i)\}$ are disjoint neighborhoods of points contained in the interior of D^2 . We obtain a handlebody diagram for $D^2 \times D_3$ from the 3 disjoint parallel dotted circles, because one can think of a dotted circle as the removal of a 2-handle from the interior of the 0-handle. If we view the 0-handle as $D^2 \times D^2$, we can view the dotted circles as removing a neighborhood of $D^2 \times \{p_i\}$. Then we attach the -1 framed 2-handles along the boundary of $D^2 \times D_3$. We can see a trivial open book decomposition with pages D_3 on $\partial(D^2 \times D_3) = S^1 \times D_3 \cup D^2 \times [\partial D^2 \sqcup \partial N(p_1) \sqcup N(p_2) \sqcup \partial N(p_3)]$. Note that each attaching circle of a 2-handle lies in a page of this trivial open book and the Seifert framing in the handlebody diagram agrees with the page framing coming from this open book decomposition. Therefore the framing on the 2-handles is -1 relative to the page framing, so the attaching circles are vanishing cycles in a Lefschetz fibration.

It is useful to understand the open book decomposition supporting ξ_{pl} given to us by Theorem 2.1. The construction of Gay and Mark tells us that the pages of the open book are given by the surface obtained by connect summing $|s_j|$ copies of D^2 to each sphere C_j in our graph, and then connect summing these surfaces according to the plumbing graph. In our case, the central sphere C_0 has $s_0 = -4 + 3 = -1$, the spheres in the arms but not on the ends have $s_j = -2 + 2 = 0$, and the spheres on the ends have $s_j = -2 + 1 = -1$. Therefore the pages are surfaces as in Figure 12. The monodromy is given by a product of positive Dehn twists about the simple closed curves around each connect sum neck, shown as the blue curves in Figure 12. Note that the order of these Dehn twists does not matter, because the curves are all disjoint from each other so that the corresponding Dehn twists commute in the mapping class group.

On the other hand, our Lefschetz fibration induces an open book decomposition on its boundary whose pages are disks with three holes and whose monodromy is a product of positive Dehn twists about the vanishing cycles ordered starting at the bottom of the picture to the top, as in Figure 13b. This monodromy is equivalent by a lantern relation to positive Dehn twists about the curves in Figure 13c, which is equivalent to the open book decomposition determined by Figure 12 which we know supports ξ_{pl} . Therefore our filling has the structure of a Lefschetz







(a) Lefschetz fibration

(b) Open book decomposition

(c) Equivalent open book

FIGURE 13. The Lefschetz fibration is visible in this handlebody description of the second symplectic filling, and the open book decomposition induced on the boundary has monodromy given by a product of positive Dehn twists about the curves pictured here. (Color available online.)

fibration which induces an open book decomposition on its boundary that supports the contact structure ξ_{pl} we are interested in.

A Lefschetz fibration is allowable if the vanishing cycles are non-zero in the homology of the page. It was shown in [2] and [18] that an allowable Lefschetz fibration admits a Stein structure, and verified in [26] that the contact structure induced on the boundary is supported by an open book decomposition whose pages are diffeomorphic to the regular fibers of the Lefschetz fibration and whose monodromy is a product of Dehn twists about the vanishing cycles. Since the vanishing cycles in this Lefschetz fibration are homologically essential, this 4-manifold supports a Stein structure, inducing ξ_{pl} on the boundary. The Stein structure induces a convex symplectic structure on this filling.

This proves (in multiple ways) part (1) of Theorem 1.2.

4. Classifications given by rational blow-downs

4.1. A simple family with $e_0 \leq -k - 3$. We can provide a complete classification for a similar family to our simplest family in the case where e_0 is sufficiently negative.

Proof of Theorem 1.3. When the central vertex on our graph is labeled by $e_0 \le -k-3$ where k is the number of arms in our graph, the dual graph will have $d=-e_0-1$ arms, where d-k of these arms are made up of a single symplectic sphere of square -1. If we assume all the arms of the dual graph have length one, the possible homology classes each dual graph sphere can represent is completely determined by Lemma 2.5. The graphs that these correspond to have central vertex with coefficient e_0 and k arms, each made up of some number of spheres of square -2 as in Figure 14.

When $\max\{n_1+1,\dots,n_k+1\} < d-1 = -e_0-2$, only one of the homology representations in Lemma 2.5 is possible, and this corresponds to the diffeomorphism type of the original plumbing of disk bundles over spheres. When $\max\{n_1+1,\dots,n_k+1\} \ge d-1 = -e_0-2$, we have other diffeomorphism types

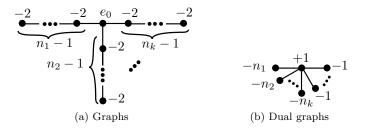


FIGURE 14. A simple family of graphs and their dual graphs $(e_0 \le -k-3 \text{ and } n_1, n_2, \cdots, n_k \ge 2)$.

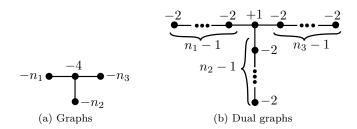


FIGURE 15. Another simple family of graphs and their dual graphs $(n_1, n_2, n_3 \ge 1)$.

obtained from the original plumbing of disk bundles over spheres by a rational blowdown of a linear subgraph consisting of the central vertex and the next $-e_0 - 4$ spheres of square -2 in one of the arms. Such rational blow-downs were shown to be symplectic operations by Symington in [31]. Since we can perform this operation on the interior of the filling, this will not change the convex symplectic structure near the boundary. Therefore we can realize all these diffeomorphism types as convex symplectic fillings.

4.2. A simple family whose dual graphs have long arms. In the first example, there were only four spheres in the dual graph to keep track of, which restricted the number of different ways of writing their homology classes. Another restrictive condition on the possibilities for homology of the dual graph is to require that the spheres have small self-intersection numbers. If we look at three-armed dual graphs where every sphere except the central vertex has self-intersection number -2 as in Figure 15b, we can understand fillings of Seifert fibered spaces $Y(-4; -n_1, -n_2, -n_3)$ that bound plumbings according to the graphs in Figure 15a. Note that when $n_1 = n_2 = n_3 = 2$, we are back in example 1. Therefore we can assume at least one of the arms in the dual graph has length at least 2.

Proof of Theorem 1.2, part (2). We consider what each sphere in the dual graph can represent in $H_2(X_M; \mathbb{Z})$. The central vertex and its adjacent vertices must represent one of two possible homology choices, as in the previous example. Let C_0

represent the central vertex, and C_1 , C_2 , and C_3 represent the adjacent vertices.

Case A	Case B
$[C_0] = \ell$	$[C_0] = \ell$
$[C_1] = \ell - e_1 - e_2 - e_3$	$[C_1] = \ell - e_1 - e_2 - e_4$
$[C_2] = \ell - e_1 - e_4 - e_5$	$[C_2] = \ell - e_1 - e_3 - e_5$
$[C_3] = \ell - e_1 - e_6 - e_7$	$[C_3] = \ell - e_2 - e_3 - e_6$

The remaining spheres in the concave cap have the form $e_{i_1} - e_{i_2}$. Suppose C_4 is adjacent to C_1 . Then since $[C_1] \cdot [C_4] = 1$, and $[C_j] \cdot [C_4] = 0$ for j = 0, 2, 3, one of the e_i which has -1 coefficient in $[C_1]$ must have +1 coefficient in $[C_4]$. In Case A, up to relabeling, this determines $[C_4] = e_2 - e_8$ (if e_1 appeared in $[C_4]$ it would be impossible to cancel the algebraic intersection of C_4 with both C_2 and C_3 since only two e_i 's can appear with non-zero coefficient in $[C_4]$). Continuing with the assumption that we are in Case A for now, if C_5 is adjacent to C_4 , then the intersection relations imply $[C_5] = e_8 - e_9$ or $[C_5] = e_3 - e_2$. However, if there is another sphere C_6 adjacent to C_5 , then we cannot have $[C_5] = e_3 - e_2$, because there is no way to write $[C_6] = e_{i_1} - e_{i_2}$ such that $[C_6] \cdot (e_3 - e_2) = 1$ and $[C_6] \cdot [C_1] = 0$. The homology of the spheres in the other arms is determined independently in the same way. Therefore if we are in Case A, and each arm in the dual graph has length at least four (i.e. $n_1, n_2, n_3 > 4$), the homology of the spheres is unique up to relabeling the e_i .

If the first four spheres are configured as in Case B, and C_4 is adjacent to C_1 , then the intersection relations imply $[C_4] = e_4 - e_7$ or $[C_4] = e_1 - e_5$ (up to symmetric relabeling). If C_5 is adjacent to C_4 , then we cannot have $[C_4] = e_1 - e_5$. This is because it is not possible to find $[C_5] = e_{i_1} - e_{i_2}$ such that $[C_5] \cdot (e_1 - e_5) = 1$, $[C_5] \cdot [C_2] = 0$, and $[C_5] \cdot [C_3] = 0$. Therefore if C_5 is adjacent to C_4 , $[C_4] = e_4 - e_7$. Furthermore, $[C_5] = e_7 - e_8$, since if $[C_5] = e_i - e_4$ it is not possible to ensure $[C_5] \cdot [C_1] = 0$ and $[C_5] \cdot [C_2] = [C_5] \cdot [C_3] = 0$ simultaneously. In conclusion, if the lengths of all of the arms in the dual graph are at least three (i.e., $n_1, n_2, n_3 > 3$), the homology of all of the spheres are determined, up to obvious symmetries, by the choice that the first four spheres are as in Case B.

This implies that when $n_1, n_2, n_3 > 4$, there are at most two diffeomorphism types of strong symplectic fillings of the Seifert fibered space arising as the boundary of the plumbing in Figure 15a. It is clear from the previous analysis in section 3 that the diffeomorphism types obtained from Case A and Case B differ by a rational blow-down of the central -4 sphere. Furthermore, we know that the original symplectic plumbing and the rational blow-down of the -4 sphere provide two non-diffeomorphic symplectic fillings.

4.3. A special case. When some of n_1 , n_2 , and n_3 take values 3 or 4, some more interesting fillings can appear. The most interesting case is when $n_1 = n_2 = n_3 = 3$, which we discuss here. (When some of the $n_j = 4$, one can perform rational blowdowns of any disjoint collection of -4 spheres. If only one or two of the $n_j = 3$, nothing new appears.)

Proof of Theorem 1.4. When $n_1 = n_2 = n_3 = 3$, each arm in the dual graph has length 2. Following the analysis of the previous proof, the four spheres C_0, C_1, C_2, C_3 represent in homology one of two possibilities referred to as Case A and Case B. There are three more spheres in the dual graph, C_4, C_5, C_6 adjacent to C_1, C_2, C_3 respectively. As described above, if the first four spheres represent the homology in

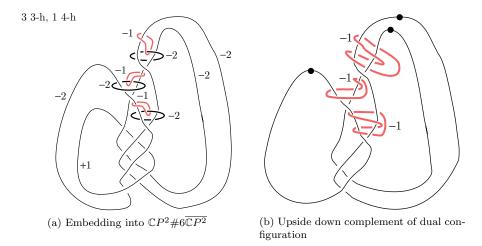


FIGURE 16. The embedding of the concave cap and its complement which is a rational homology ball. (*Color available online*.)

Case A, the homology classes of C_4 , C_5 , C_6 are determined up to symmetries. The resulting embedding determined by this homology will have complement diffeomorphic to the original plumbing of spheres.

If the first four spheres are configured as in Case B, there are two possibilities for each adjacent sphere. However, because $[C_4] \cdot [C_5] = [C_5] \cdot [C_6] = [C_4] \cdot [C_6] = 0$, these choices cannot be made independently of each other. Up to permutation of the indices there are only two possibilities if the first four spheres represent the homology as in Case B, given as follows:

$$\begin{array}{ccc|c} [C_4] & = & e_4 - e_7 \\ [C_5] & = & e_5 - e_8 \\ [C_6] & = & e_6 - e_9 \\ \end{array} \begin{array}{ccc|c} [C_4] & = & e_1 - e_5 \\ [C_5] & = & e_3 - e_6 \\ [C_6] & = & e_2 - e_4 \\ \end{array}$$

The first of these gives rise to the rational blow-down of the -4 sphere in the original plumbing. The second gives rise to a rational blow-down of the entire original plumbing. The embedding of the concave cap into $\mathbb{C}P^2\#6\overline{\mathbb{C}P^2}$ is visible in Figure 16a. By turning the complement upside down, one obtains a manifold built from a 0-handle, three 1-handles, and three 2-handles, as in Figure 16b. One can cancel two of the 1-handles with two of the 2-handles, and the remaining 2-handle links nine times with the 1-handle, and it is thus a diagram for a rational homology ball.

It is known that a smoothing of a complex singularity gives this rational homology ball whose boundary is Y(-4; -3, -3, -3). The complex structure gives a convex symplectic structure to this smooth manifold, filling the same contact structure ξ_{pl} (by [30] and [25]). Therefore all three of these diffeomorphism types must be strong symplectic fillings of $(Y(-4; -3, -3, -3), \xi_{pl})$.

4.4. The family $W_{p,q,r}$. The special case in the previous example generalizes to a family of dually positive symplectic plumbings of spheres that can be completely rationally blown down, given by the graphs in Figure 17a. This is the only family

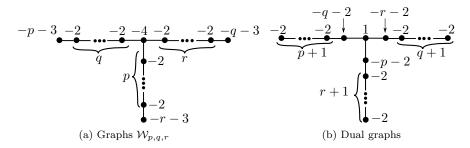


FIGURE 17. $W_{p,q,r}$ and dual graphs.

of dually positive graphs which has a symplectic rational blow-down (of the entire configuration) due to the classifications in [6] and [30].

We can classify the convex symplectic fillings completely for these graphs. Let $Y(W_{p,q,r})$ denote the boundary of the plumbing of spheres according to the graph $W_{p,q,r}$.

Theorem 4.1. The convex symplectic fillings of $(Y(W_{p,q,r}), \xi_{pl})$ are of the following diffeomorphism types:

- (1) The original symplectic plumbing of spheres according to the graph $W_{p,q,r}$.
- (2) A rational blow-down of the central -4 sphere in the original plumbing of spheres.
- (3) A rational blow-down of a subset of the spheres in the first arm, the first with square -p-3 and the next (p-1) spheres with square -2 (assuming $p-1 \le q$).
- (4) A rational blow-down of a subset of the spheres in the second arm, the first with square -r-3 and the next (r-1) spheres with square -2 (assuming $r-1 \le p$).
- (5) A rational blow-down of a subset of the spheres in the third arm, the first with square -q-3 and the next (q-1) spheres with square -2 (assuming $q-1 \le r$).
- (6) Any combination of (3), (4), and/or (5) assuming all the necessary hypotheses given above on p, q, r are met. Also, any combination of (3), (4), and (5) with (2), but in that case we require the stronger conditions on (3), (4), and (5) that $p \leq q$, $r \leq p$ and $q \leq r$ respectively (this ensures the rational blow-downs can all be done disjointly).
- (7) A rational blow-down of the entire graph.

Proof. First note that all the above diffeomorphism types are realized as convex symplectic fillings of ξ_{pl} because these rational blow-downs are known to be symplectic operations by [31], [30]. Furthermore, all of these rational blow-downs produce non-diffeomorphic manifolds which can be distinguished by their intersection forms (except when there are obvious symmetries of the three arms). Therefore it suffices to provide an upper bound on the number of convex fillings which matches the number of diffeomorphism types provided in the statement of the theorem.

By section 2, an upper bound is given by the number of ways to represent the homology classes of the spheres in the dual graph in terms of a standard basis for $H_2(\mathbb{C}P^2 \# M \overline{\mathbb{C}P^2})$ of the form given in section 2.4. The dual graph for $W_{p,q,r}$ is given in Figure 17b.

Denote the sphere representing the central vertex by C_0 , and the three spheres intersecting C_0 by C_1, C_2, C_3 . Denote the string of spheres of square -2 whose first sphere is adjacent to C_j by C_1^j, \dots, C_{p+1}^j for j=1,2,3. There are two possibilities for the homology classes of the first four spheres, as in previous computations. Throughout this computation, all e_i^n will be distinct basis elements for $H_2(\mathbb{C}P^2 \# M \mathbb{C}P^2; \mathbb{Z})$ of square -1.

The remaining strings of spheres each have two possible configurations that can occur in either Case A or B. They can each occur independently of each other, but one of each of these two choices requires some inequality between p,q,r to be true. The configurations are:

Note that the bottom choices are only possible if there are enough e^n_i for n=1,2,3, namely we need $p+1 \leq q+2$, $r+1 \leq p+2$, or $q+1 \leq r+2$ if we want the bottom choice for the homology classes of $\{C^1_j\}$, $\{C^2_j\}$ or $\{C^3_j\}$ respectively, and the first four spheres represent the homology given by Case A. We need $p+1 \leq q+1$, $r+1 \leq p+1$, or $q+1 \leq r+1$ if we want the bottom choice for the homology classes of $\{C^1_j\}$, $\{C^2_j\}$ or $\{C^3_j\}$ respectively, and the first four spheres represent the homology given by Case B.

As in all previous examples, the effect of choosing the first four spheres to represent the homology in Case B versus Case A is to rationally blow down the central -4 sphere. The conditions for when one can choose the lower representation of the homology of the j^{th} arm of the dual graph match up precisely with the conditions for when one can rationally blow down a linear subgraph of the j^{th} arm in the original graph in Case A. In Case B, these conditions on when we have a second choice for the homology of the j^{th} arm of the dual graph match the conditions needed to rationally blow down a linear subgraph of the j^{th} arm disjointly from the central -4 sphere.

Additionally, the symmetries which make the rational blow-down of one arm diffeomorphic to the rational blow-down of another arm, correspond to symmetries in the e_i^j which permute the values of j.

There is one additional way to represent the homology of the arms in the dual graphs, when the first four spheres represent homology given by Case B. We know that $[C_1^j] = e_{i_1}^{m_1} - e_{i_2}^{m_2}$, where $e_{i_1}^{m_1}$ must show up with coefficient -1 in $[C_j]$. In Case A, we cannot have $e_{i_1}^{m_1} = e_1^0$ and still have $[C_1^j] \cdot [C_{j'}] = 0$ for $j \neq j' \in \{1, 2, 3\}$. However, in Case B, this can occur, but it uniquely determines the remaining homology classes as follows:

$$\begin{bmatrix} C_1^1 \end{bmatrix} & = & e_1^0 - e_1^2 \\ \begin{bmatrix} C_2^1 \end{bmatrix} & = & e_3^0 - e_1^3 \\ \begin{bmatrix} C_2^1 \end{bmatrix} & = & e_3^0 - e_1^3 \\ \begin{bmatrix} C_2^2 \end{bmatrix} & = & e_1^3 - e_2^3 \\ \vdots & & & \vdots \\ \begin{bmatrix} C_{p+1}^1 \end{bmatrix} & = & e_p^2 - e_{p+1}^2 \\ \end{bmatrix} \begin{bmatrix} C_1^2 \end{bmatrix} & = & e_1^3 - e_2^3 \\ \end{bmatrix} \begin{bmatrix} C_1^3 \end{bmatrix} & = & e_1^0 - e_1^1 \\ \vdots & & & \vdots \\ \begin{bmatrix} C_{p+1}^1 \end{bmatrix} & = & e_p^2 - e_{p+1}^2 \\ \end{bmatrix} \begin{bmatrix} C_{p+1}^2 \end{bmatrix} & = & e_p^3 - e_{p+1}^3 \\ \end{bmatrix} \begin{bmatrix} C_{p+1}^3 \end{bmatrix} & = & e_1^4 - e_{p+1}^1.$$

This gives an embedding of the dual configuration of symplectic spheres into $\mathbb{C}P^2\#(p+q+r+6)\overline{\mathbb{C}P^2}$. Note that the dual graph has p+q+r+7 vertices, so a regular neighborhood N of the corresponding configuration of spheres has $b_2(N) = p+q+r+7 = b_2(\mathbb{C}P^2\#(p+q+r+6)\overline{\mathbb{C}P^2})$. The first and second homology of $\partial N = Y(W_{p,q,r})$ are both torsion, and N and $\mathbb{C}P^2\#(p+q+r+6)\overline{\mathbb{C}P^2}$ are simply connected, so their first homologies are zero. Therefore, the Mayer-Vietoris theorem implies that the first and second homologies of the complement of N in this embedding are both torsion. Therefore this is the diffeomorphism type of a rational homology ball. Since this is the unique possible rational homology ball which can strongly symplectically fill its contact boundary, it must be diffeomorphic to the smoothing of the normal surface singularity studied in [30].

Therefore the number of ways to represent the homology of the spheres in the dual graph is in direct correspondence with the diffeomorphism types we can realize by starting with the original symplectic plumbing, and rationally blowing down a subgraph or the entire graph, so these are all possible convex symplectic fillings of (Y, ξ_{pl}) .

5. FILLINGS OF SEIFERT FIBERED SPACES WITH MORE THAN THREE SINGULAR FIBERS

We have completed the classification of the simplest cases of symplectic fillings of Seifert fibered spaces with k>3 singular fibers when $e_0 \leq -k-3$ in section 4.1. Here we consider the simplest cases when k>3, but $e_0=-k-1$ and $e_0=-k-2$. We are prevented from giving full classifications for all such examples because we need Lemmas 2.7 and 2.8 to say that each homology representation of the spheres in the dual graph uniquely determines a symplectic filling. These lemmas do not apply when $e_0=-k-1$ or -k-2 except when $k\in\{3,4,5\}$. However, we can still get a hold on what happens when k=4,5, and the resulting fillings provide new symplectic operations as opposed to the previous examples.

We look at the case where $e_0 = -k - 1$ with k = 4 or 5 arms, with coefficients as in Figure 18a. The boundary of the corresponding plumbing is $Y(-k-1; \frac{-n_1}{n_1-1}, \cdots, \frac{-n_k}{n_k-1})$. The dual graph is in Figure 18b.

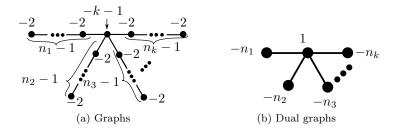


FIGURE 18. The dually positive graphs for which the boundary of the corresponding plumbing is $Y(-k-1; \frac{-n_1}{n_1-1}, \cdots, \frac{-n_k}{n_k-1})$ and their dual graphs.

By gluing an arbitrary convex filling to the concave neighborhood of the dual graph, we obtain an embedding of $C_0 \cup \cdots \cup C_k$ into $\mathbb{C}P^2 \# M \overline{\mathbb{C}P^2}$. By Lemma 2.4, the homology of these spheres in terms of the standard basis for $H_2(\mathbb{C}P^2 \# M \overline{\mathbb{C}P^2}; \mathbb{Z})$ has the following form:

$$[C_0] = \ell$$

$$[C_1] = \ell - e_{i_1^1} - \dots - e_{i_{n_1+1}^1}$$

$$\vdots$$

$$[C_k] = \ell - e_{i_1^k} - \dots - e_{i_{n_k+1}^k}$$

and $|\{i_1^j, \cdots, i_{n_j+1}^j\} \cap \{i_1^{j'}, \cdots, i_{n_{j'}+1}^{j'}\}| = 1$ for all $j \neq j' \in \{1, \cdots, k\}$. When k = 4 this can occur in 3 different ways, and when k = 5 this can occur in 5 different ways (up to symmetries). After blowing down the corresponding embeddings into $\mathbb{C}P^2 \# M \overline{\mathbb{C}P^2}$, these dual graphs descend to the configurations \mathcal{I}_1^4 , \mathcal{I}_2^4 , and \mathcal{I}_4^4 when k = 4, and the configurations \mathcal{I}_1^5 , \mathcal{I}_2^5 , \mathcal{I}_5^5 , \mathcal{I}_6^5 , and \mathcal{I}_7^5 when k = 5 (see Figure 5). The spheres which share a common intersection point after blowing down, will share a common e_i with coefficient -1 in their homology representations in the blow-up.

Note that if the n_j are not sufficiently large, it may not be possible to realize all possible homology configurations. It suffices to assume $n_j \geq k-2$ for all $j \in \{1, \dots, k\}$ to obtain all possibilities. It will be clear which homology representations and thus diffeomorphism types of fillings cannot be realized when the n_j are smaller.

We first produce diagrams which depict the embeddings of the dual graph into $\mathbb{C}P^2\# M\overline{\mathbb{C}P^2}$ that correspond to these different representations of the homology, and then use them to generate diagrams of the complement of these embeddings. Then we show that these diffeomorphism types have the structure of an appropriate Lefschetz fibration to prove that these diffeomorphism types are actually realized as convex symplectic fillings.

The result of blowing up according to one of the possible homology representations gives an embedding represented by one of the choices in Figures 19a and 20. The attaching circles of the k+1 spheres in the dual configuration which are proper transforms of the original k+1 complex projective lines are shown in red, and the attaching circles for the 2-handles corresponding to the exceptional spheres are shown in black.

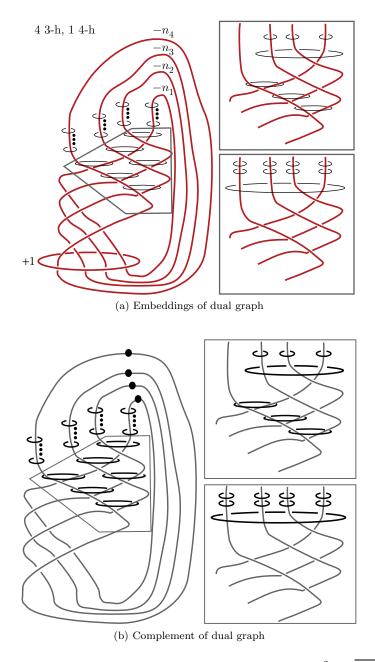


FIGURE 19. Embeddings of the dual graph into $\mathbb{C}P^2 \# M \overline{\mathbb{C}P^2}$ when k=4, and the complement of the embedding. Alternate embeddings (and their complements) can be obtained by replacing the boxed portion with one of the adjacent boxes. All framings on the black attaching circles are -1. (Color available online.)

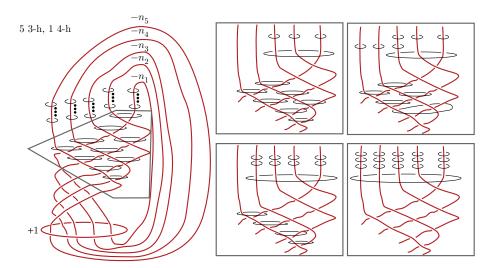


FIGURE 20. The embeddings of the dual graph when k=5. Alternate embeddings can be obtained by replacing the boxed portion with one of the adjacent boxes. All framings of the black attaching circles are -1. (Color available online.)

We obtain the diffeomorphism type of the potentially convex symplectic filling by cutting out the dual configuration, and turning the manifold upside down. Cutting out the dual configuration corresponds to deleting the 0-handle, and the 2-handles corresponding to the spheres in the dual graph (those whose attaching circles are shown in red). To turn the resulting manifold upside down, we take the mirror image of the original link formed by all attaching circles (which we can do by reversing all the crossings), change all the framing coefficients to surgery coefficients with the opposite sign, attach 2-handles along 0-framed meridians of the black surgery circles (since we cut out the other 2-handles with the dual graph), and replace the k 3-handles by k 1-handles. After a diffeomorphism of the boundary (performing all the blow-downs along the surgery curves with coefficients ± 1), all of the crossings are reversed back to their original orientation (the lower half of the crossings are reversed when the surgery curve coming from the red +1 framed curve is blown down, and the upper half of the crossings are reversed when performing the blow-downs along the surgery curves corresponding to the exceptional spheres that intersect more than one sphere in the dual configuration), and the only 2handles are -1 framed in the same position as in the embedding. Representing the k 1-handles by dotted circles we obtain diagrams like that in Figure 19b. Rotating the plane we are projecting the link onto by 90° about the vertical axis, we obtain diagrams for the possible fillings given by Figures 21a and 21b.

As in our simplest examples in section 3, these diagrams represent Lefschetz fibrations, now over D^2 with fibers k-holed disks. The vanishing cycles are given by the -1-framed 2-handles (note that the Seifert framing agrees with the page framing in this diagram, so this is indeed a positive Lefschetz fibration). Now we need to check that the open book decomposition induced on the boundary of the Lefschetz fibration supports the contact structure ξ_{pl} .

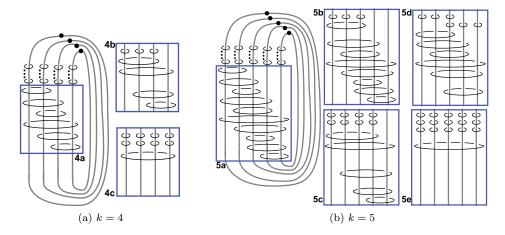


FIGURE 21. The rotated diagrams giving all possible diffeomorphism types of these symplectic fillings. All 2-handles (shown in black) have framing coefficient -1. (Color available online.)

Proposition 5.1. The open book decompositions arising as the boundary of these Lefschetz fibrations supports ξ_{pl} .

Proof. The open book decompositions on the boundaries of these Lefschetz fibrations have pages which are disks with k holes, and the monodromy is given by positive Dehn twists around the vanishing cycles, ordered from the lowermost vanishing cycle in the figure to the uppermost. If we place the holes on the page on the vertices of a regular k-gon contained in the disk, we can isotope the attaching circles so that its projection onto a page has convex interior and contains some non-empty subset of the k-holes. We will denote a Dehn twist about a curve on this standard k-holed disk that convexly contains holes $\{h_1, \dots, h_j\}$ by D_{h_1, \dots, h_j} . We will label the holes corresponding to the dotted circles $1, \dots, k$ from the leftmost dotted circle to the right-most. Then the monodromy M_k of the open books on the boundary of the above given Lefschetz fibrations in Figure 21 is given as follows:

$$\begin{split} &M_{4a} = D_{3,4}D_{2,4}D_{1,4}D_{2,3}D_{1,3}D_{1,2}D_1^{n_1-2}D_2^{n_2-2}D_3^{n_3-2}D_4^{n_4-2}\\ &M_{4b} = D_{3,4}D_{2,4}D_{1,4}D_{1,2,3}D_1^{n_1-1}D_2^{n_2-1}D_3^{n_3-1}D_4^{n_4-2}\\ &M_{4c} = D_{1,2,3,4}D_1^{n_1}D_2^{n_2}D_3^{n_3}D_4^{n_4}\\ &M_{5a} = D_{4,5}D_{3,5}D_{3,4}D_{2,5}D_{1,5}D_{2,4}D_{1,4}D_{2,3}D_{1,3}D_{1,2}D_1^{n_1-3}D_2^{n_2-3}D_3^{n_3-3}D_4^{n_4-3}D_5^{n_5-3}\\ &M_{5b} = D_{4,5}D_{3,5}D_{3,4}D_{2,5}D_{1,5}D_{2,4}D_{1,4}D_{1,2,3}D_1^{n_1-2}D_2^{n_2-2}D_3^{n_3-2}D_4^{n_4-3}D_5^{n_5-3}\\ &M_{5c} = D_{4,5}D_{3,5}D_{2,5}D_{1,5}D_{1,2,3,4}D_1^{n_1-1}D_2^{n_2-1}D_3^{n_3-1}D_4^{n_4-1}D_5^{n_5-3}\\ &M_{5d} = D_{3,4,5}D_{2,5}D_{1,5}D_{2,4}D_{1,4}D_{1,2,3}D_1^{n_1-2}D_2^{n_2-2}D_3^{n_3-1}D_4^{n_4-2}D_5^{n_5-2}\\ &M_{5e} = D_{1,2,3,4,5}D_1^{n_1}D_2^{n_2}D_3^{n_3}D_4^{n_4}D_5^{n_5}. \end{split}$$

Theorem 2.1 tells us that ξ_{pl} is supported by an open book decomposition whose pages are k-holed disks, and whose monodromy consists of boundary parallel curves, n_j of them about each hole, and one parallel to the outer boundary. Note that this

is identical to the monodromy given by M_{4c} and M_{5e} . We will show that the other elements are just other factorizations of the same monodromy.

Elements in the mapping class group of the disk with k holes placed on the vertices of a regular k-gon inside the disk satisfy the lantern relations. These relations say that if A, B, and C are disjoint collections of holes, then $D_A D_B D_C D_{A \cup B \cup C} = D_{A \cup B} D_{B \cup C} D_{A \cup C}$, where A, B, C are subsets of the holes $\{1, \dots, k\}$ (see [19]). We first prove a lemma which gives us more general moves obtained from a sequence lantern relations.

Lemma 5.2. Suppose B_0, B_1, \dots, B_m are disjoint subsets of the k holes on the disk $(m \ge 2)$. Then

$$D_{B_0}^{m-1}D_{B_1}\cdots D_{B_m} = D_{B_0\cup B_1}D_{B_0\cup B_2}\cdots D_{B_0\cup B_m}D_{B_1\cup\cdots\cup B_m}D_{B_0\cup B_1\cup\cdots\cup B_m}^{-1}.$$

Proof. This relation can be obtained by performing m-1 lantern relations, and using the fact that Dehn twists around disjoint curves commute. In the notation above, for the j^{th} lantern relation in this sequence, let $A = \{B_1, \dots, B_j\}$, $B = B_0$, and $C = B_{j+1}$.

Now we can use these moves to show that $M_{4a}=M_{4b}=M_{4c}$ and $M_{5a}=M_{5b}=M_{5c}=M_{5d}=M_{5e}$. A simple lantern relation shows that $M_{4a}=M_{4b}$. An application of the lemma with $B_0=4$, $B_1=3$, $B_2=2$, $B_3=1$ shows that $M_{4b}=M_{4c}$.

One lantern relation gives that $M_{5a} = M_{5b}$, and two lantern relations gives that $M_{5a} = M_{5d}$. We can commute Dehn twists about disjoint curves so we can commute $D_{3,4}$ past $D_{2,5}$ and $D_{1,5}$. Therefore,

$$M_{5b} = D_{4,5}D_{3,5}D_{2,5}D_{1,5}D_{3,4}D_{2,4}D_{1,4}D_{1,2,3}D_1^{n_1-2}D_2^{n_2-2}D_3^{n_3-2}D_4^{n_4-3}D_5^{n_5-3}.$$

Then an application of the lemma with $B_0 = 4$, $B_1 = 3$, $B_2 = 2$, $B_3 = 1$ gives $M_{5b} = M_{5c}$. A final application of the lemma with $B_0 = 5$, $B_1 = 4$, $B_2 = 3$, $B_3 = 2$, $B_4 = 1$ implies $M_{5c} = M_{5d}$

As in the examples in section 3, we can stabilize this Lefschetz fibration to an allowable Lefschetz fibration, so by [2], [18], and [26] this manifold supports a Stein structure inducing a contact structure on its boundary that is supported by the boundary open book decomposition, which is ξ_{pl} by the previous proposition.

Note that the diffeomorphism types of the fillings 4a, 4b, and 4c can be distinguished by Euler characteristic:

$$\chi(4a) = (n_1 - 2 + n_2 - 2 + n_3 - 2 + n_4 - 2 + 6) - (4) + (1)
= n_1 + n_2 + n_3 + n_4 - 5,
\chi(4b) = n_1 + n_2 + n_3 + n_4 - 4,
\chi(4c) = n_1 + n_2 + n_3 + n_4 - 2.$$

Similarly, we can distinguish 5a, 5b, 5c, 5d, and 5e:

$$\chi(5a) = n_1 + n_2 + n_3 + n_4 + n_5 - 9,
\chi(5b) = n_1 + n_2 + n_3 + n_4 + n_5 - 8,
\chi(5c) = n_1 + n_2 + n_3 + n_4 + n_5 - 6,
\chi(5d) = n_1 + n_2 + n_3 + n_4 + n_5 - 7,
\chi(5e) = n_1 + n_2 + n_3 + n_4 + n_5 - 3.$$

Note that the homology representation yielding the possible diffeomorphism type given by 4a can only occur when $n_1, n_2, n_3, n_4 \geq 2$, and 4b requires $n_4 \geq 2$. In general, since we are classifying fillings whose arms have length $n_j - 1$, we have implicitly assumed $n_j \geq 1$. The restrictions for 5a are that $n_j \geq 3 \,\,\forall j$; for 5b we need $n_1, n_2, n_3 \geq 2$ and $n_4, n_5 \geq 3$; for 5c we need $n_5 \geq 3$; for 5d we need $n_1, n_2, n_4, n_5 \geq 2$.

This completes the classification of symplectic fillings of

$$(Y(-k-1;\frac{n_1}{n_1-1},\cdots,\frac{n_k}{n_k-1}),\xi_{pl})$$

when k = 4, 5, thus proving Theorem 1.5. Note that 4c and 5e are diagrams for the original plumbing after handle-slides and cancellations. 4b and 5c are obtained from these plumbings by performing a rational blow-down of the central vertex (a sphere of square -k-1) together with k-4 spheres of square -2 in one of the arms. However, 4a, 5a, 5b, and 5d are new diffeomorphism types. Note that the restrictions on the n_i for these diffeomorphism types imply that their Euler characteristics are always strictly greater than 1, so none of these are rational homology balls. Furthermore, these cannot be obtained by a rational blow-down of any subgraph containing the central vertex because by varying the n_j , we have classified all fillings of subgraphs containing the central vertex, so any such rational blow-down would give back one of our original diffeomorphism types (4a, 4b, 4c, 5a, 5b, 5c, 5d, 5e). Each of these diffeomorphism types is distinguished from the others by Euler characteristic, so there cannot be any non-trivial rational blow-downs of a subgraph containing the central vertex. Any subgraph not containing the central vertex is a union of linear subgraphs of spheres of square -2, which are known to have no rational blow-downs. Therefore these diffeomorphism types cannot be obtained by any rational blow-down of a subgraph of the original plumbing of spheres. Note, however that their Euler characteristics are still strictly smaller than those of the original plumbing.

6. Further observations and questions

Note that in many of the examples we have considered, each possible diffeomorphism type of a strong symplectic filling was actually realized by a Stein filling. This is not surprising, because each of the contact manifolds we consider are supported by planar open book decompositions (Theorem 2.1), and a result of Wendl in [33] says that any minimal strong symplectic filling of a contact structure supported by a planar open book can be deformed through a homotopy of strong symplectic fillings to a Stein filling. Thus any diffeomorphism type supporting a convex symplectic structure also supports a Stein structure.

In all the examples we have considered, we have been able to prove that each possible diffeomorphism type allowed by the homological restrictions of section 2 has a symplectic structure with convex boundary by direct construction. While it is valuable to understand explicit symplectic manifolds of each diffeomorphism type which can convexly fill a given contact manifold, we can only provide these constructions on a case-by-case basis. It would be useful to know abstractly that every diffeomorphism type produced by the arguments in section 2 are actually realized as strong symplectic fillings. One way to show this would be to prove that any symplectic embedding of the dual configurations of spheres has a concave neighborhood. Since the blow-up construction gives a symplectic embedding of the dual configuration into a blow-up of $\mathbb{C}P^2$, if we could ensure this dual configuration has a concave neighborhood, the complement would necessarily have a symplectic structure with convex boundary.

Additional complications in the opposite direction arise in the cases when k is large and $e_0 = -k-2, -k-1$, since we do not understand the possible embeddings of the dual graph into a blow-up of $\mathbb{C}P^2$. While the space of complex projective lines in a complicated intersection configuration may be disconnected or empty, it is not clear what the space of smoothly embedded spheres in this intersection configuration looks like. It would be interesting to understand what information is generally implied about the classification of minimal strong symplectic fillings by the representations of the homology classes of the spheres in the dual graph into the second homology of a blow-up of $\mathbb{C}P^2$.

Question 6.1. Are there dually positive Seifert fibered spaces for which the number of diffeomorphism types of minimal strong symplectic fillings is strictly less than or strictly greater than the number of homology representations of the dual graph into the homology of a blow-up of $\mathbb{C}P^2$?

One phenomenon that is apparent from all the examples we have computed is that the original plumbing of spheres has the highest Euler characteristic of all the symplectic fillings of its boundary. Thus replacing these plumbings with alternate fillings could be useful in searching for symplectic manifolds with small Euler characteristic. One may ask if this phenomenon is true in greater generality.

Question 6.2. Does a (dually positive or more general) symplectic plumbing of spheres have the highest Euler characteristic of any symplectic filling of its contact boundary?

Finally, we have shown in Theorem 1.1 that dually positive Seifert fibered spaces with the contact structure ξ_{pl} have finitely many strong symplectic fillings. Similar boundaries of other symplectic plumbings have been shown to admit infinitely many symplectic fillings (see in particular the work of Akhmedov and Ozbagci [5]). However, these plumbings involve curves of higher genus at the central vertex. While those examples and the ones considered here provide some information about when symplectic plumbings can be replaced by only finitely many versus infinitely many symplectic fillings, there is still plenty of unknown ground. Since every negative definite graph (with each vertex decorated by the genus and self-intersection of the corresponding curve) corresponds to a symplectic plumbing of spheres with convex boundary inducing a contact structure ξ_{pl} (by [11]), these contact boundaries are natural manifolds to start with.

Question 6.3. Which manifolds, (Y, ξ_{pl}) , arising as the boundary of a negative definite symplectic plumbing have only finitely many strong symplectic fillings?

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