



The CALIPSO version 4 automated aerosol classification and lidar ratio selection algorithm

Man-Hae Kim¹, Ali H. Omar², Jason L. Tackett³, Mark A. Vaughan², David M. Winker², Charles R. Trepte², Yongxiang Hu², Zhaoyan Liu², Lamont R. Poole³, Michael C. Pitts², Jayanta Kar³, and Brian E. Magill³

¹NASA Postdoctoral Program (USRA), Hampton, VA, USA

²NASA Langley Research Center, Hampton, VA, USA

³Science Systems and Applications, Inc., Hampton, VA, USA

Correspondence: Man-Hae Kim (manhae@snu.ac.kr)

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Abstract. The Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) version 4.10 (V4) level 2 aerosol data products, released in November 2016, include substantial improvements to the aerosol subtyping and lidar ratio selection algorithms. These improvements are described along with resulting changes in aerosol optical depth (AOD). The most fundamental change in the V4 level 2 aerosol products is a new algorithm to identify aerosol subtypes in the stratosphere. Four aerosol subtypes are introduced for stratospheric aerosols: polar stratospheric aerosol (PSA), volcanic ash, sulfate/other, and smoke. The tropospheric aerosol subtyping algorithm was also improved by adding the following enhancements: (1) all aerosol subtypes are now allowed over polar regions, whereas the version 3 (V3) algorithm allowed only clean continental and polluted continental aerosols; (2) a new “dusty marine” aerosol subtype is introduced, representing mixtures of dust and marine aerosols near the ocean surface; and (3) the “polluted continental” and “smoke” subtypes have been renamed “polluted continental/smoke” and “elevated smoke”, respectively. V4 also revises the lidar ratios for clean marine, dust, clean continental, and elevated smoke subtypes. As a consequence of the V4 updates, the mean 532 nm AOD retrieved by CALIOP has increased by 0.044 (0.036) or 52 % (40 %) for nighttime (daytime). Lidar ratio revisions are the most influential factor for AOD changes from V3 to V4, especially for cloud-free skies. Preliminary validation studies show that the AOD discrepancies between CALIOP and AERONET–MODIS (ocean) are reduced in V4 compared to V3.

1 Introduction

The Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) flown aboard the Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observations (CALIPSO) platform has been providing unique vertical profile measurements of the Earth’s atmosphere on a global scale since June 2006 (Winker et al., 2010). Data products derived from the CALIOP measurements are distributed worldwide from the Atmospheric Science Data Center (ASDC) located at the National Aeronautics and Space Administration (NASA) Langley Research Center (LaRC). In addition to detailed spatial and optical properties of detected layers, CALIOP also provides essential information on layer types for both clouds and aerosols.

Currently, CALIOP is the only space-based sensor that observes and reports the vertical distributions of aerosol spatial and optical properties over the globe, and thus CALIOP data products offer substantial research advantages in aerosol studies. For example, CALIOP aerosol data have been widely used to evaluate aerosol model simulations for several aerosol types (e.g., Yu et al., 2010; Ford and Heald, 2012; Koffi et al., 2012, 2016; Nabat et al., 2013) and to investigate spatiotemporal distribution and transport of several major aerosol types, such as dust and smoke aerosols (e.g., Mona et al., 2012; Guo et al., 2017; Senghor et al., 2017; Marinou et al., 2017; Wu et al., 2017). While CALIOP’s aerosol subtype classifications are useful as a wholly independent data product (e.g., Nowottnick et al., 2015; Sun et al., 2018), knowledge of aerosol subtype is also critically important for the CALIOP level 2 (L2) retrievals of aerosol op-

tical properties. The aerosol lidar ratio, a key parameter for the extinction retrieval, is determined for each aerosol subtype based on measurements, modeling, and the cluster analysis of a multiyear Aerosol Robotic Network (AERONET) dataset (Omar et al., 2005, 2009). Because the lidar ratio is one of the largest sources of uncertainty in the CALIOP aerosol optical depth (AOD) estimates, the CALIOP aerosol classification and lidar ratio selection algorithm plays a critical role in the aerosol extinction retrieval and resulting AOD (Young et al., 2013).

In version 3 (V3) and earlier, the CALIOP level 2 aerosol classification and lidar ratio selection algorithm defined six aerosol types: clean marine, dust, polluted continental, clean continental, polluted dust, and smoke (Omar et al., 2009). Each type is assigned an extinction-to-backscatter ratio (i.e., lidar ratio) with an associated uncertainty that defines the limits of its expected natural variability. Since the V3 release, several limitations of the V3 aerosol subtyping algorithm have come to light. For instance, mixtures of dust and marine aerosol were frequently classified as polluted dust (Burton et al., 2013), which is intended to be a mixture of dust and smoke or urban pollution. In polar regions, Asian dust and smoke from boreal fires were forced to be classified as either clean continental or polluted continental, the only aerosol subtypes allowed over snow, ice, or tundra. The algorithm for identifying smoke also caused some layers at the bases of elevated smoke plumes to be misclassified as clean marine (Nowottnick et al., 2015). Finally, all features detected above the tropopause were generically classified as “stratospheric features” and were not given aerosol subtypes, thereby missing an opportunity to identify volcanic aerosol in the stratosphere.

The conclusions from numerous studies assert that the AOD reported in the CALIOP V3 data products typically underestimates coincident AOD measurements and/or retrievals acquired using various spaceborne, airborne, and ground-based instruments (e.g., Redemann et al., 2012; Schuster et al., 2012; Kim et al., 2013; Omar et al., 2013; Rogers et al., 2014). Additional CALIOP analyses using opaque water clouds as a constraint in the retrieval (Hu, 2007) show similar results (Liu et al., 2015). However, the Moderate Resolution Imaging Spectroradiometer (MODIS) AOD retrievals (collection 5) are subject to several sources of error, which mostly tend to produce high biases in AOD (Kittaka et al., 2011). Campbell et al. (2012) compared with the US Navy Aerosol Analysis and Prediction System (NAAPS), which assimilates a quality-screened version of MODIS AOD, and find that the V3 CALIOP AOD is consistent with NAAPS over ocean and somewhat higher over land.

There are two primary sources for the CALIOP AOD differences relative to other measurements and retrievals: aerosol layer detection failures and inaccurate lidar ratios. Rogers et al. (2014) compared CALIOP AOD with NASA LaRC airborne High Spectral Resolution Lidar (HSRL) and found that the undetected aerosols in the free troposphere in-

troduce a mean underestimate of 0.02 in the CALIOP column AOD in the dataset examined. Kim et al. (2017) retrieved aerosol extinction for the undetected aerosol layers and found a global mean undetected layer AOD of 0.031. Toth et al. (2018) reported that 45 % of daytime cloud-free V3 level 2 aerosol profiles have no aerosol detected within the profile (AOD = 0). They found the mean collocated MODIS and AERONET AODs at 550 nm are near 0.06 and 0.08, respectively, for the CALIOP profiles without aerosols. Several other studies also suggest that the weakly backscattering aerosols that are undetected by CALIOP’s layer detection algorithm can contribute to a low CALIOP AOD estimate relative to other sensors (Kacenelenbogen et al., 2011, 2014; Thorsen et al., 2017). Whereas layer detection failure always contributes to low bias, misclassification of aerosol subtypes and inaccurate aerosol lidar ratios can result in both high and low biases in CALIOP AOD. Burton et al. (2013) compared the CALIOP V3 aerosol subtype product with NASA LaRC airborne HSRL measurements. They compared 109 underflights of the CALIOP orbit track and found that 80 % of the CALIOP desert dust layers, 62 % of the marine layers, and 54 % of the polluted continental layers agreed with HSRL classification results. However, the agreement was less for smoke (13 %) and polluted dust (35 %) layers. Recent studies suggest that the lidar ratios assigned by the V3 CALIOP aerosol classification and lidar ratio selection algorithm are at least partially responsible for biases in the CALIOP V3 AOD for clean marine (Bréon, 2013; Rogers et al., 2014; Dawson et al., 2015) and dust aerosols (Burton et al., 2012; Schuster et al., 2012; Amiridis et al., 2013; Nisantzi et al., 2015; Liu et al., 2015).

The CALIOP version 4.10 (V4) level 2 aerosol data products, released in November 2016, contain substantial updates to aerosol type classification and to aerosol lidar ratio assignments, made in response to many of the results reported in the studies described above. The primary purpose of this paper is to introduce the V4 updates in the CALIOP level 2 aerosol subtyping algorithms and changes to the characteristic lidar ratios for different aerosol subtypes. This is discussed in Sect. 2. The resulting AOD differences between V3 and V4 are investigated in Sect. 3 by categorizing the factors that can contribute to the AOD changes. Lastly, in Sect. 4, we compare CALIOP AOD with AERONET and MODIS for both versions as an initial validation of the CALIOP V4 AOD.

2 Algorithm updates for CALIOP version 4 aerosol level 2 products

The CALIOP V4 level 2 data products contain substantial refinements over V3 and earlier releases (Liu et al., 2018; Avery et al., 2018; Young et al., 2018). The most fundamental changes in V4 level 2 aerosol products are the introduction of a new “dusty marine” aerosol subtype in the tropo-

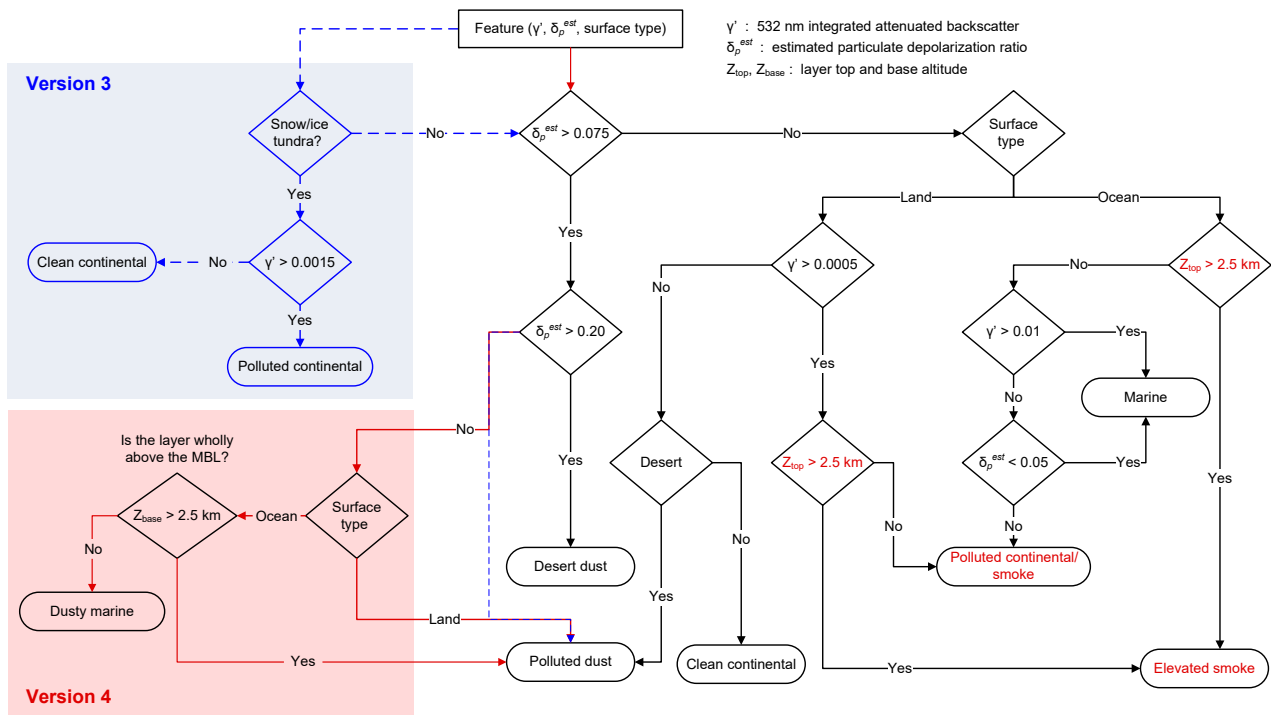


Figure 1. Flowchart of the CALIPSO aerosol subtype selection scheme for tropospheric aerosols. The blue-shaded region and blue-dotted arrows are used in V3 but removed in V4. The red-shaded region and solid red arrows are newly added in V4. The nomenclatures for “polluted continental” and “smoke” are revised to “polluted continental/smoke” and “elevated smoke” in V4. The definition for “elevated” is revised in V4 to mean layers with tops higher than 2.5 km above ground level (see Sect. 2.1.3).

sphere and the addition of new aerosol subtypes to classify aerosol layers newly identified in the stratosphere. Because the cloud aerosol discrimination (CAD) algorithm is now applied to all layers detected (Liu et al., 2018), those features that were previously classified as generic “stratospheric” layers in V3 and earlier are now identified as either clouds or aerosols. Consequently, the V4 level 2 aerosol subtyping algorithm now distinguishes between tropospheric and stratospheric aerosols. An entirely new algorithm has been implemented to identify aerosol subtypes in the stratosphere, and the algorithm for identifying tropospheric aerosol types has been substantially updated. The changes made to the tropospheric algorithm are described in detail first, followed by details on the new stratospheric aerosol subtyping algorithm.

2.1 Aerosol subtypes in the troposphere

The CALIOP V3 aerosol classification algorithm uses altitude, location, surface type, estimated particulate depolarization ratio (δ_p^{est}), and integrated attenuated backscatter (γ') to identify the aerosol subtype (Omar et al., 2009). Figure 1 shows the decision tree used to determine the V3 and V4 tropospheric aerosol subtypes. The major updates implemented in the V4 tropospheric aerosol subtyping algorithm include introducing the dusty marine aerosol subtype (by adding the red-shaded region in Fig. 1), allowing all aerosol subtypes

over polar regions (by removing the blue-shaded region in Fig. 1), and revising the operational definitions for the polluted continental and smoke aerosol types.

At this time the integrated attenuated color ratio ($\chi' = \gamma'_{1064} / \gamma'_{532}$) is not used for aerosol subtyping in the troposphere because the low signal-to-noise ratio (SNR) for optically thin layers, especially in the daytime, makes it an inconsistent discriminator among tropospheric aerosol types. However, it is useful for stratospheric aerosol typing in which the number of types is fewer (Sect. 2.2).

2.1.1 A new aerosol subtype: dusty marine

In V4, a new dusty marine aerosol type is introduced to identify mixtures of dust and marine aerosol and thus account for the frequent occurrence of mixtures of dust and marine aerosols that are misclassified as polluted dust over global oceans in V3. Dusty marine occurs most frequently when Saharan dust is transported across the Atlantic Ocean and settles into the marine boundary layer (MBL) as it approaches North and Central America (Liu et al., 2008; Groß et al., 2016; Kuciauskas et al., 2018). In V3, many of these layers are misclassified as polluted dust, an aerosol type intended to represent mixtures of dust + smoke and dust + polluted continental aerosols. In both V3 and V4, polluted dust is assigned a lidar ratio of 55 ± 22 sr. Using data acquired

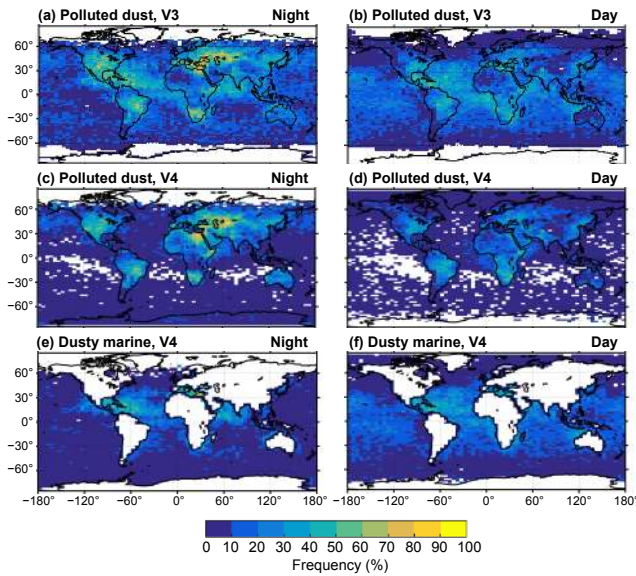


Figure 2. Frequency of occurrence of aerosol samples classified as polluted dust in V3 at night and during the day (a, b), polluted dust in V4 at night and during the day (c, d) and dusty marine in V4 at night and during the day (e, f). June–August 2007.

during CALIPSO validation flights over the Caribbean Sea, Burton et al. (2013) compared CALIOP V3 aerosol classifications with measurements made by the NASA LaRC airborne HSRL on the NASA B200 aircraft. For those layers that CALIOP V3 classified as polluted dust, the HSRL measured a median lidar ratio of 35 sr, thus strongly suggesting that these aerosols were a combination of dust + marine aerosol, and not the combination of dust + smoke modeled by the CALIOP polluted dust type. As shown in Fig. 2a, 40 % to 50 % of aerosol samples over the Caribbean in JJA at night are classified as polluted dust in V3. During the daytime in V3 (Fig. 2b), polluted dust accounts for 10 % to 30 % of aerosol samples identified over remote oceanic regions (e.g., the South Pacific Ocean) where the occurrence of mixtures of dust and smoke is less probable.

The polluted dust classification occurred in V3 because these layers are mildly depolarizing, having estimated particulate depolarization ratios (δ_p^{est}) between 0.075 and 0.20 (Omar et al., 2009). The estimated particulate depolarization ratio is the layer-integrated volume depolarization ratio, which is corrected to account for the molecular contribution, defined as

$$\delta_p^{\text{est}} = \frac{\delta_v [(R_{\text{mas}} - 1)(1 + \delta_m) + 1] - \delta_m}{(R_{\text{mas}} - 1)(1 + \delta_m) + \delta_m - \delta_v}, \quad (1)$$

where δ_v is the layer-integrated volume depolarization ratio, R_{mas} is the mean attenuated scattering ratio, and δ_m is the molecular depolarization ratio (Omar et al., 2009). Here, δ_v is defined as

$$\delta_v = \frac{\sum_{z_{\text{base}}}^{z_{\text{top}}} [\beta_{\perp}'(z)]}{\sum_{z_{\text{base}}}^{z_{\text{top}}} [\beta_{\parallel}'(z)]}, \quad (2)$$

where z is altitude and the subscripts “top” and “base” refer to the top and base of the detected aerosol layer.

When a dust layer, having $\delta_p^{\text{est}} > 0.20$, mixes with non-depolarizing marine aerosol, the layer-averaged δ_p^{est} decreases below 0.20 and the aerosol is classified as polluted dust in V3. This explains the enhanced frequency of V3 polluted dust classifications over the Caribbean in JJA (Fig. 2a). In other oceanic regions where dust + marine or dust + smoke mixtures are less probable (again, the remote South Pacific Ocean), the frequency of polluted dust is overestimated in V3 for at least two reasons. First, δ_p^{est} is a noisy quantity that is asymmetrically distributed, with a large positively skewed tail that can be considerably increased by solar background noise during the daytime. Additionally, occasional high biases can arise from residual single-shot-resolution cloud contamination within the MBL. This makes the 0.075 lower δ_p^{est} threshold easier to exceed in these situations. Second, δ_p^{est} is overestimated in V3 because attenuation from overlying layers was not accounted for in the δ_p^{est} computation (Burton et al., 2013) in V3. This oversight has been corrected in V4.

To identify dust + marine aerosol mixtures in V4, dusty marine layers are defined as moderately depolarizing ($0.075 < \delta_p^{\text{est}} < 0.20$) aerosol layers over ocean having base altitudes below 2.5 km above mean sea level (an upper limit for the MBL; Winning et al., 2017). After implementation of this new aerosol subtype, the frequency of oceanic layers classified as polluted dust decreased substantially. Given that the CALIOP polluted dust subtype is explicitly modeled as a mixture of dust and smoke (Omar et al., 2009), the V4 spatial distributions of polluted dust over the Caribbean and remote Pacific Ocean shown in Fig. 2c and d present a more likely scenario than the V3 distributions shown in Fig. 2a and b. A total of 30 %–50 % of aerosol samples over the Caribbean are classified as dusty marine in JJA as shown in Fig. 2e–f. Note that the dusty marine frequency is enhanced over remote oceanic regions during the daytime (Fig. 2f). This is due to the noisiness of δ_p^{est} in daytime. The AOD differences from misclassifying pure marine (lidar ratio of 23 sr) as dusty marine (37 sr) are substantially smaller than they would otherwise be if these same layers were instead misclassified as polluted dust (55 sr).

2.1.2 Aerosol subtypes in polar regions

As indicated in Fig. 1, the V3 aerosol classification algorithm allows only clean continental and polluted continental subtypes over the polar regions when the surface type is snow, ice, or tundra. This was based on the assumption that the aerosol found in the polar regions – particularly in the Arctic in winter – are predominantly pollutants from industri-

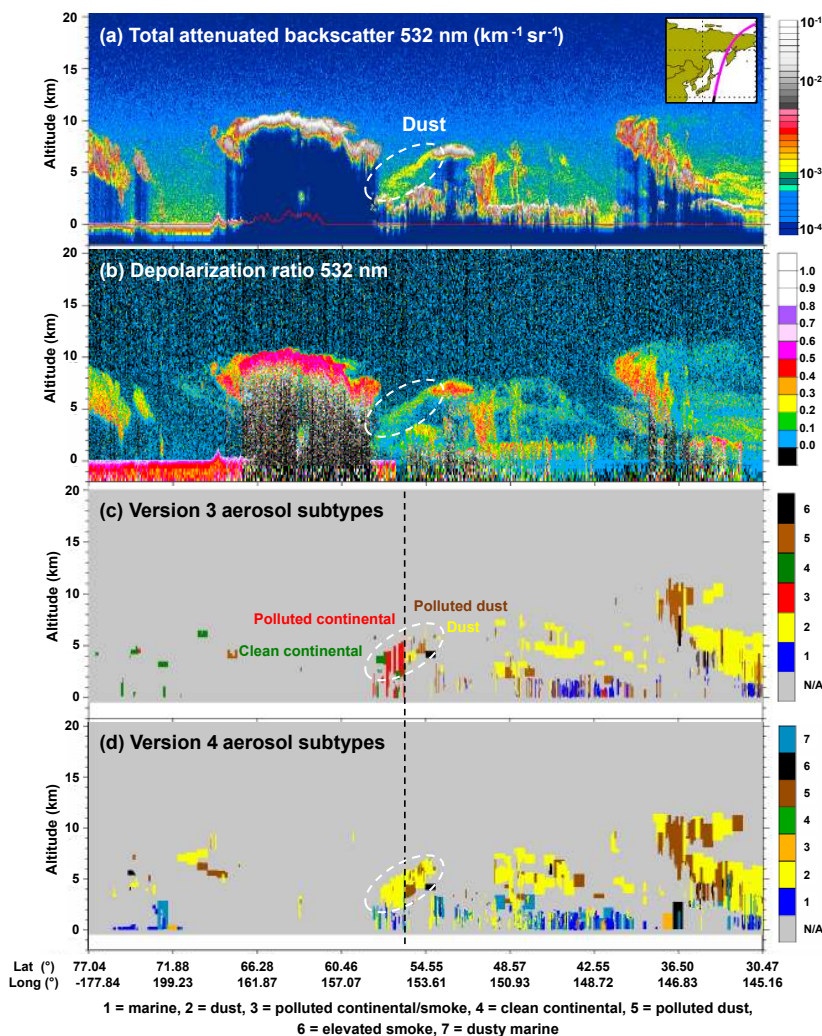


Figure 3. CALIOP observations of dust plume on 22 March 2010 between 16:11 and 16:25 UTC. **(a)** Total attenuated backscatter at 532 nm, **(b)** depolarization ratio at 532 nm, and aerosol subtypes in **(c)** V3 and **(d)** V4. The white dashed ellipse shows dust plume and the black dashed line represents the boundary for “snow/ice, tundra” used for polar regions in V3.

alized areas transported poleward (Stohl, 2006; Stone et al., 2008). During the spring phase of the ARCTAS campaign (Jacob et al., 2010), however, the poleward transport of multiple plumes of Asian dust and smoke from boreal fires was observed, highlighting the importance of these other aerosol types. The contribution of smoke to the aerosol found in the Arctic – primarily from boreal forest fires and high-latitude agricultural fires – is now well documented (e.g., Stohl et al., 2007; Warneke et al., 2010; Di Pierro et al., 2011; Markowicz et al., 2016). Records in polar ice and snow cores show that dust has been transported to the Arctic and Antarctic since geologic times (e.g., Lunt and Valdes, 2001; Fischer et al., 2007). While there are dust sources at high latitudes in both the Northern Hemisphere (Alaska, Canada, Greenland, and Iceland) and Southern Hemisphere (Antarctica, New Zealand, and Patagonia) (Bullard et al., 2016), they are

minor sources and the primary source of dust transported to the Arctic is the Asian deserts. Huang et al. (2015) investigate a large-scale dust storm that occurred in East Asia using ground-based and spaceborne remote-sensing measurements, NCEP/NCAR reanalysis data, and a HYSPLIT trajectory analysis. They found that the dust storm was rapidly transported to the Arctic from its source region within 5 days.

Because of the recent realization of the importance of smoke and dust over the Arctic, the V4 aerosol classification algorithm no longer uses snow, ice, and tundra as decision points, but instead uses uniform aerosol typing criteria for the entire Earth (Fig. 1). As a consequence, all CALIOP aerosol subtypes may now be identified in polar regions. Figure 3 shows the dust plume reported by Huang et al. (2015). The plume is well captured by CALIOP, as shown in total attenuated backscatter (Fig. 3a) and depolarization ratio

(Fig. 3b) with the white dashed ellipse. However, the V3 algorithm identifies the plume as dust/polluted dust at latitudes less than 56° N but as polluted continental/clean continental above 56° N (Fig. 3c). The sea surface changes from open water to ice at this point, and hence the aerosol subtyping, is forced by the V3 polar region loop (Fig. 1). In V4, this plume is correctly classified as dust (Fig. 3d). Note too that the V3 analysis fails to detect a substantial fraction of the plume, whereas the V4 algorithm captures the whole plume well (Fig. 3d), thus demonstrating the layer detection improvements in V4 (Sect. 3.2).

2.1.3 Revised aerosol subtype: elevated smoke and polluted continental/smoke

The interpretation and nomenclature of layers identified in V3 as smoke and polluted continental have been revised in V4. As in previous versions, elevated non-depolarizing aerosols are assumed to be smoke that has been injected above the planetary boundary layer (PBL). The definition for elevated is revised in V4 to mean layers with tops higher than 2.5 km above ground level (i.e., a simple approximation of a region above the PBL; McGrath-Spangler and Denning, 2013). For clarity, the name of the smoke aerosol subtype is changed to “elevated smoke” to emphasize that these layers are identified as smoke because they are elevated above the PBL. Within the PBL, the optical properties measured by CALIOP (depolarization and color ratio) are practically identical for the smoke and polluted continental subtypes, making them indistinguishable. To acknowledge the optical similarity of polluted continental and smoke, the name of this aerosol type is changed in V4 to “polluted continental/smoke”. The V4 lidar ratios used in the CALIOP retrieval algorithm are identical for polluted continental/smoke and elevated smoke (70 sr at 532 nm and 30 sr at 1064 nm). However, one limitation of identifying smoke layers according to altitude is that pollution lofted by convective processes or other vertical transport mechanisms can be misclassified as elevated smoke.

2.2 Stratospheric aerosols

In V4, the CAD algorithm is applied at all altitudes, including in the stratosphere. By contrast, previous versions only applied the CAD algorithm below the tropopause, classifying layers detected above the tropopause as stratospheric features rather than as clouds or aerosols. As a consequence, aerosol existing above the tropopause was not identified explicitly as aerosol. However, it is well documented that certain aerosol types exist in the stratosphere. Volcanic eruptions inject ash and sulfate to high altitudes (e.g., Vernier et al., 2011; Bourassa et al., 2012). Smoke due to intense combustion or from pyro-cumulonimbus events can also breach the tropopause (e.g., Fromm et al., 2005, 2010; Trentmann et al., 2006). In the polar winter, polar stratospheric clouds (PSCs)

form and the PSC composed of supercooled ternary solution (STS) is an aerosol (Pitts et al., 2009). In V4, features identified by the CAD algorithm as aerosol having 532 nm attenuated backscatter centroids (Garnier et al., 2015) above the tropopause from the Modern-Era Retrospective analysis for Research and Applications version 2 (MERRA-2) reanalysis data (Gelaro et al., 2017) outside of the polar regions are classified as “stratospheric aerosols”. Distinguishing among the different types of stratospheric aerosol relies primarily on latitude, temperature, and the measured properties of each layer: γ' and δ_p^{est} at 532 nm and χ' .

V4 identifies four stratospheric aerosol subtypes: volcanic ash, sulfate/other, elevated smoke, and polar stratospheric aerosol (PSA). Volcanic ash is defined as an aspherical volcanic aerosol that depolarizes the 532 nm backscatter, whereas sulfate/other is defined primarily as a non-depolarizing volcanic aerosol. The “other” component of this aerosol type is the catchall for stratospheric aerosol layers that are either weakly scattering or cannot be classified as any other type within the stratospheric aerosol algorithm. Weakly scattering layers are not evaluated by the stratospheric aerosol subtyping algorithm because the noisy values of δ_p^{est} and χ' at low signal levels inhibit robust classifications with the threshold-based technique employed. The PSA subtype is introduced in V4 to assign a reasonable aerosol type for features detected in the polar regions during polar winter and subsequently classified as aerosol by the CAD algorithm due to their low values of χ' and γ' . Comparison with the CALIOP L2 PSC mask product shows that PSAs are spatially correlated with the STS PSC composition class (Pitts et al., 2009; Liu et al., 2018). However, layers assigned the PSA subtype should be interpreted carefully. For in-depth studies, the CALIPSO team recommends using the CALIOP L2 PSC mask product for analyses related to PSC composition since it is a more specialized product (Pitts et al., 2009).

The stratospheric aerosol subtyping algorithm is summarized by the flowchart in Fig. 4. PSAs are identified first by determining if the stratospheric aerosol layer’s latitude, season, and temperature at its 532 nm attenuated backscatter centroid altitude are consistent with that of PSCs. A centroid altitude temperature threshold of -70°C is implemented based on the occurrence frequency distribution of aerosol mid-layer temperatures during the Arctic and Antarctic PSC season in 2008 (Fig. 5). The -70°C temperature threshold captures the increased aerosol occurrence frequency at colder temperatures, corresponding to the possible formation of STS PSCs (e.g., temperatures of less than -75°C correspond to temperatures consistent with PSC formation in this region; Rosen et al., 1997). Latitude and seasonal constraints are applied to ensure the PSA type is assigned where and when PSC formation occurs. PSA classification is only allowed for latitudes poleward of 50° S or N, and PSC seasons for the Arctic and Antarctic regions are assumed to be December–February and May–October, respectively (Poole and Pitts, 1994).

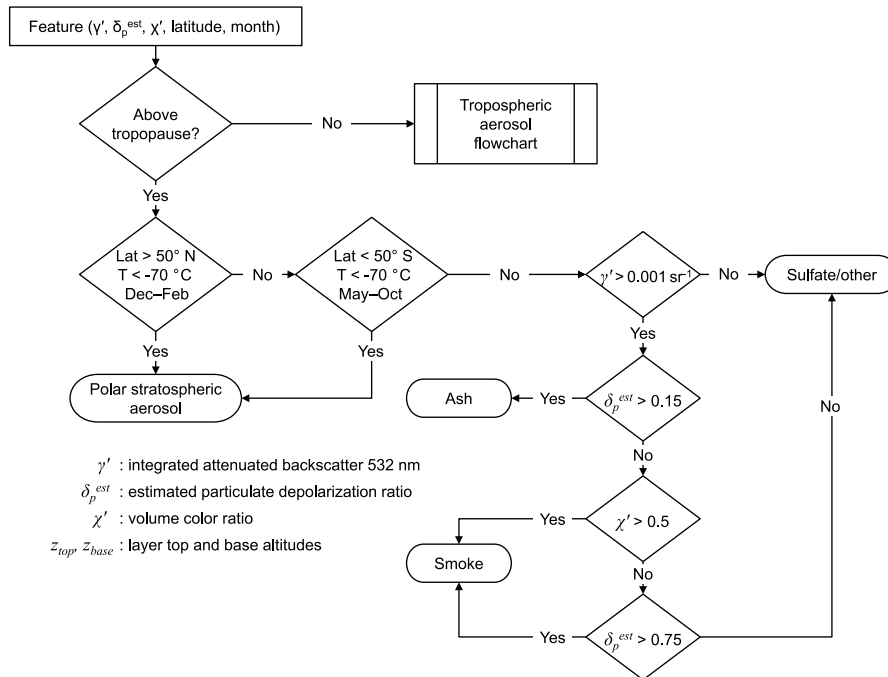


Figure 4. Flowchart of the CALIPSO aerosol subtype selection scheme for stratospheric aerosols.

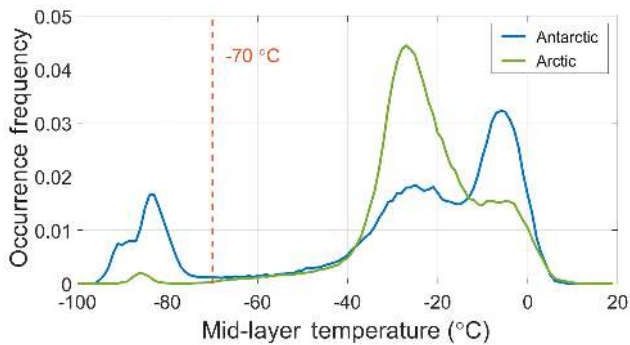


Figure 5. Occurrence frequency of mid-layer temperatures for V4 aerosol layers detected poleward of 50° during PSC season; June–September 2008 for the Antarctic and December 2007–February 2008 for the Arctic at night.

Next, in order to discriminate between volcanic ash, sulfate, and elevated smoke, the stratospheric aerosol typing algorithm evaluates layer-averaged δ_p^{est} and χ' against empirically derived thresholds. These thresholds were derived from frequency distribution analysis of δ_p^{est} and χ' measurements obtained from a manually identified subset of volcanic ash, sulfate, and high-altitude smoke layers (Fig. 6). The number of unique layers detected by CALIOP, geophysical events, and dominant aerosol types contributing to this subset are summarized in Table 1. Note that, as previously mentioned, weakly scattering stratospheric aerosol layers (layers with $\gamma' < 0.001 \text{ sr}^{-1}$) are directly classified as sulfate/other

due to their low SNR. As shown in Fig. 6a–c, volcanic ash and volcanic sulfate are fairly well separated with respect to δ_p^{est} , with ash typically having $\delta_p^{\text{est}} > 0.15$ and sulfate with $0.075 < \delta_p^{\text{est}} < 0.15$. Smoke layers are less depolarizing than volcanic ash (Fig. 6d), with $\delta_p^{\text{est}} < 0.15$. However, smoke layers can be either non-depolarizing or moderately depolarizing (Fig. 6e–f). An example of a moderately depolarizing smoke event is the February 2009 “Black Saturday” Australian bush fire for which δ_p^{est} frequently exceeded 0.10. Non-depolarizing smoke layers ($\delta_p^{\text{est}} < 0.075$) typically have $\chi' > 0.5$, whereas χ' is more frequently lower for moderately depolarizing smoke layers ($0.075 < \delta_p^{\text{est}} < 0.15$). Based on this analysis, the stratospheric aerosol typing algorithm depicted in Fig. 4 was constructed using the thresholds indicated by the red lines in Fig. 6.

The following examples demonstrate the strengths and limitations of the stratospheric aerosol typing algorithm. Volcanic ash is well separated from the other types in terms of δ_p^{est} and χ' , which often leads to robust subtype classifications. Figure 7 shows a scene in which the algorithm correctly classifies the bulk of a volcanic ash plume from the Puyehue-Cordón Caulle eruption in June 2011. Though the northernmost layers near 42–45° S are automatically classified as sulfate/other due to their low γ' , these layers are optically thin and the more optically thick layers of the ash plume are classified correctly. Also note that portions of the ash plume having backscatter centroids below the tropopause are misclassified as dust. This occurs because aerosol layers below the tropopause are assigned tropospheric aerosol sub-

Table 1. Number of layers detected by CALIOP used to determine V4 stratospheric aerosol typing thresholds. The dominant aerosol type for volcanic events is determined according to the references given in the table.

N layers	Geophysical event	Dominant aerosol type
2274	Puyehue-Cordón Caulle eruption, June 2011	Volcanic ash (Bignami et al., 2014)
69	Okmok eruption, July 2008	Volcanic ash (Prata et al., 2010)
58	Chaitén eruption, May 2008	Volcanic ash (Prata et al., 2010)
2439	Kasatochi eruption, August 2008	Volcanic sulfate (Krotkov et al., 2010)
256	Nabro, June 2011	Volcanic sulfate (Theys et al., 2013)
813	Siberian fires, May–June 2012	Smoke
399	Canadian fires, July–August 2007	Smoke
1624	Australian bush fire, February 2009	Smoke, depolarizing (de Laat et al., 2012)
161	Canadian fires, May 2007	Smoke, depolarizing

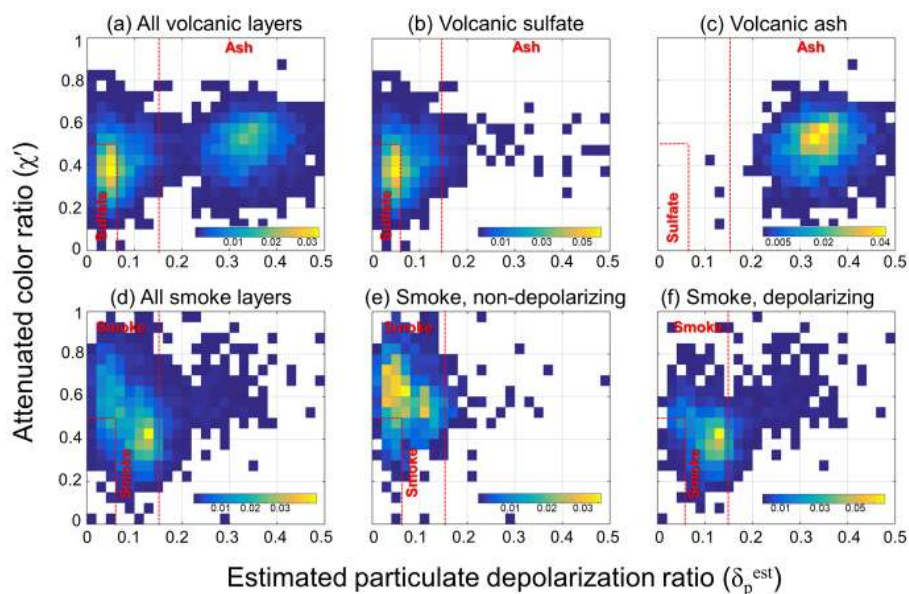


Figure 6. Two-dimensional frequency distributions of attenuated total color ratio and estimated particulate depolarization ratio for layers in Table 1. Distributions are normalized independently by the sum of samples in the subset: (a) all volcanic layers, (b) volcanic sulfate, (c) volcanic ash, (d) all smoke layers, (e) non-depolarizing smoke, and (f) depolarizing smoke. Only layers having integrated attenuated backscatter $>0.001 \text{ sr}^{-1}$ contribute. Red dashed lines denote the V4 stratospheric aerosol typing thresholds.

types that do not include ash. Because the noise-broadened distributions of δ_p^{est} for ash and dust measured by CALIOP have very similar characteristics, we know of no robust way to discriminate the two within the troposphere (Winker et al., 2012). However, the lidar ratio assigned for ash is identical to that for dust (Table 2) so potential misclassifications will have minimal impact on the extinction products.

Figure 8 presents a scene in which the bulk of the Nabro volcano plume from June 2011 (Theys et al., 2013) is correctly classified as sulfate. In this example, most of the layer has $\gamma' > 0.001$ and low depolarization, yielding a sulfate classification for the more optically thick segments. However, a small number of layers within the plume are misclassified as smoke. This is expected because of the overlap in the frequency distributions of δ_p^{est} and χ' for sulfate (Fig. 6b) and

smoke (Fig. 6d). The optical properties used for these two types are not as well separated from each other as they are from volcanic ash, so some misclassifications can occur. Additionally, volcanic sulfate within the troposphere will be assigned a tropospheric aerosol type, usually elevated smoke or clean continental if weakly scattering. The last example in Fig. 9 shows an observation of a depolarizing smoke plume from the Black Saturday Australian bush fire in February 2009 (Pumphrey et al., 2011; de Laat et al., 2012). The majority of the plume above the tropopause is correctly classified as smoke, with the minority misclassified as ash due to δ_p^{est} exceeding 0.15. The remainder of the plume below the tropopause is misclassified as dust and polluted dust, again due to elevated depolarization. In all of these examples, the V3 data products classified the layers detected above the

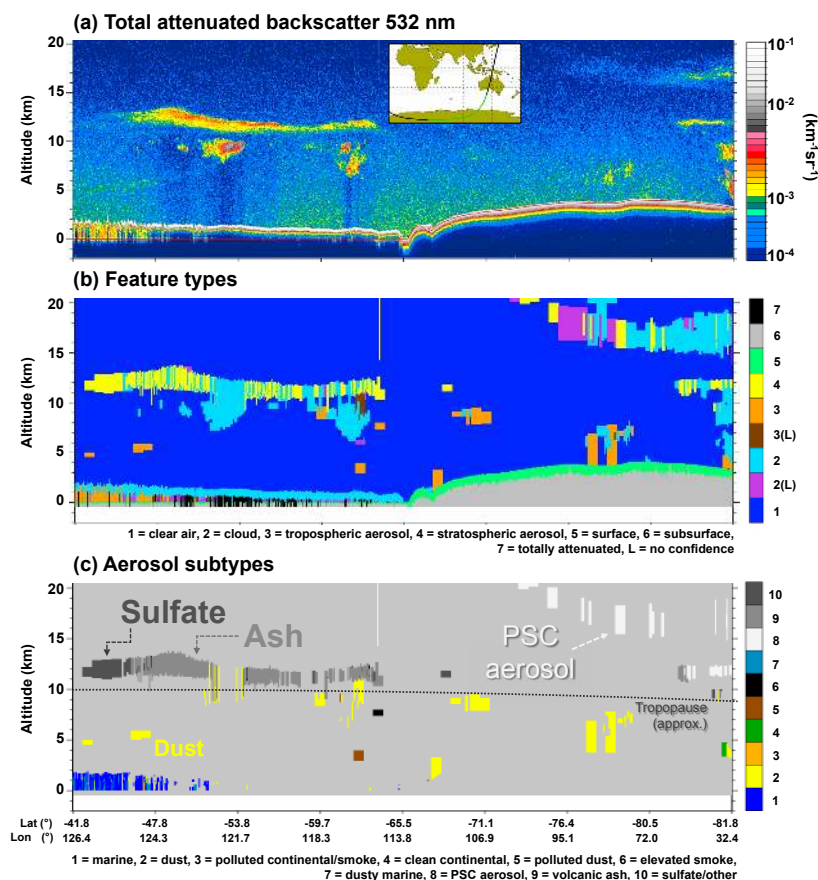


Figure 7. CALIOP observations of the Puyehue-Cordón Caulle volcano plume on 20 June 2011 between 16:50 and 17:00 UTC. (a) Total attenuated backscatter at 532 nm, (b) V4 feature type classification, and (c) V4 aerosol subtypes, where the dashed line indicates the approximate location of the tropopause. The satellite ground track is indicated by the green section on the inset map in panel (a). Additional imagery for this scene, including 532 nm depolarization ratios and attenuated backscatter color ratios, can be found at https://www-calipso.larc.nasa.gov/products/lidar/browse_images/show_detail.php?s=production&v=V4-10&browse_date=2011-06-20&orbit_time=16-22-13&page=3&granule_name=CAL_LID_L1-Standard-V4-10.2011-06-20T16-22-13ZN.hdf (last access: 26 September 2018).

tropopause as a generic stratospheric layer without applying any further subtyping. In V4, these same layers are most often correctly classified as aerosols by the new CAD algorithm (Liu et al., 2018). Similarly, the new stratospheric aerosol subtyping algorithm is largely successful in identifying the correct aerosol subtype.

2.3 Subtype Coalescence Algorithm for AeRosol Fringes (SCAARF)

In previous data releases, “fringes” at the bases of dense aerosol plumes were at times misclassified as an aerosol subtype inconsistent with the parent plume. These fringes typically lie below rapidly attenuating aerosol layers and are detected at the coarser horizontal resolutions (20 and 80 km) employed by CALIOP’s iterated, multi-resolution layer detection scheme (Vaughan et al., 2009). An example is shown in Fig. 10a–b, in which fringes at the base of an elevated

smoke plume are misclassified as clean marine aerosol. In this case, the fringes are misclassified because the layers are non-depolarizing and have top altitudes just below the 2.5 km altitude threshold that would have otherwise caused them to be correctly classified as elevated smoke according to the revised definition of elevated in V4 (Sect. 2.1.3). Given that this is an elevated plume not in contact with any aerosol beneath, it is reasonable to expect that the misclassified fringes at the base of the plume have the same aerosol subtype as the adjacent smoke layers. This same argument can be made for other aerosol types that contiguously span large horizontal distances (e.g., dust plumes, marine aerosol, volcanic ash, and volcanic sulfate).

In general, aerosol layers detected by CALIOP that are in contact with other aerosol layers are assumed to be of the same aerosol type. For this reason, V4 implements the Subtype Coalescence Algorithm for AeRosol Fringes (SCAARF), which reclassifies the aerosol subtype of these

Table 2. Aerosol lidar ratios with expected uncertainties for tropospheric and stratospheric aerosol subtypes at 532 and 1064 nm in CALIOP version 3 and 4 aerosol retrieval algorithms.

Aerosol subtype	$S_{532}(\text{sr})$		$S_{1064}(\text{sr})$	
Tropospheric aerosols				
	V3	V4	V3	V4
Clean marine	20 ± 6	23 ± 5	45 ± 23	23 ± 5
Dust	40 ± 20	44 ± 9	55 ± 17	44 ± 13
Polluted continental/smoke	70 ± 25	70 ± 25	30 ± 14	30 ± 14
Clean continental	35 ± 16	53 ± 24	30 ± 17	30 ± 17
Polluted dust	55 ± 22	55 ± 22	48 ± 24	48 ± 24
Elevated smoke	70 ± 28	70 ± 16	40 ± 24	30 ± 18
Dusty marine	–	37 ± 15	–	37 ± 15
V4 stratospheric aerosols				
Polar stratospheric aerosol	50 ± 20		25 ± 10	
Volcanic ash	44 ± 9		44 ± 13	
Sulfate/other	50 ± 18		30 ± 14	
Smoke	70 ± 16		30 ± 18	

lower fringes to match the dominant subtype of the adjacent overlying layers. According to SCAARF, fringes are defined as aerosol layers detected at 20 or 80 km horizontal resolutions that are vertically adjacent to the base(s) of aerosol layers detected at finer spatial resolution (i.e., they are adjacent to more strongly scattering features). At least 50 % of the horizontal extent of the fringe candidate must be in contact with aerosol overhead. SCAARF is applied to all tropospheric and stratospheric aerosol layers meeting this fringe criteria. The dominant adjacent aerosol subtype is determined from the number of 5 km resolution samples vertically adjacent to the fringe. When two adjacent aerosol subtypes exist with equal frequency (i.e., neither is dominant in terms of number), the fringe is changed to match the subtype of the adjacent layers that are most similar to the fringe in terms of δ_p^{est} and χ' . This is the subtype with the minimum Euclidian distance r_i between δ_p^{est} and $\bar{\chi}'$ of the parent and δ_p^{est} and χ' of the fringe; i.e.,

$$r_i = \sqrt{\left(\delta_{p,\text{fringe}}^{\text{est}} - \bar{\delta}_{p,\text{subtype } i}^{\text{est}}\right)^2 + \left(\chi'_{\text{fringe}} - \bar{\chi}'_{\text{subtype } i}\right)^2},$$

for $i \in [1, 2]$. (3)

Here, $\bar{\delta}_{p,\text{subtype } i}^{\text{est}}$ and $\bar{\chi}'_{\text{subtype } i}$ are the average values of δ_p^{est} and χ' for all adjacent layers having unique subtypes $i \in [1, 2]$. The fringe is changed to match subtype i where $r_i = \text{minimum}(r_1, r_2)$. If three or more unique subtypes are adjacent to the fringe with equal frequency, SCAARF is not applied.

In effect, SCAARF aids in vertically homogenizing aerosol subtype classification along plume bases. Figure 10c demonstrates that the fringes misclassified as clean marine have been correctly classified as elevated smoke after SCAARF is implemented. Similar improvement occurs for

volcanic ash layers straddling the tropopause. Lower fringes of these plumes below the tropopause would otherwise be misclassified as dust (Sect. 2.2), yet SCAARF helps retain the volcanic ash classification.

2.4 Aerosol lidar ratios in version 4

Table 2 shows the lidar ratios that characterized the V3 aerosol types and the revised values used in V4 for tropospheric aerosols and the newly introduced stratospheric aerosols. Except for polluted continental and polluted dust, V4 aerosol lidar ratios have been updated to reflect the improved knowledge from measurements reported in recent literature. In addition, lidar ratios have been defined for the new aerosol types: dusty marine and the stratospheric aerosol types. The modifications and new lidar ratios are based on the latest available measurements, from both CALIPSO and other researchers and field measurement campaigns.

2.5 Clean marine

The lidar ratio and uncertainties for clean marine aerosol are modified from 20 ± 6 sr in V3 to 23 ± 5 sr at 532 nm in V4. This change is consistent with results reported from numerous field campaigns since the launch of CALIPSO. Papa- giannopoulos et al. (2016) report a lidar ratio of 23 ± 3 sr for marine aerosol from the European Aerosol Research Lidar Network (EARLINET), based mainly on multiwavelength Raman lidar systems. Müller et al. (2007) also show that the mean lidar ratio for marine aerosols in the PBL is 23 ± 3 sr from the Second Aerosol Characterization Experiment (ACE 2) and 23 ± 5 sr from the Indian Ocean Experiment (INDOEX). In an analysis of collocated HSRL measurements acquired during dedicated CALIPSO underflights, Rogers et

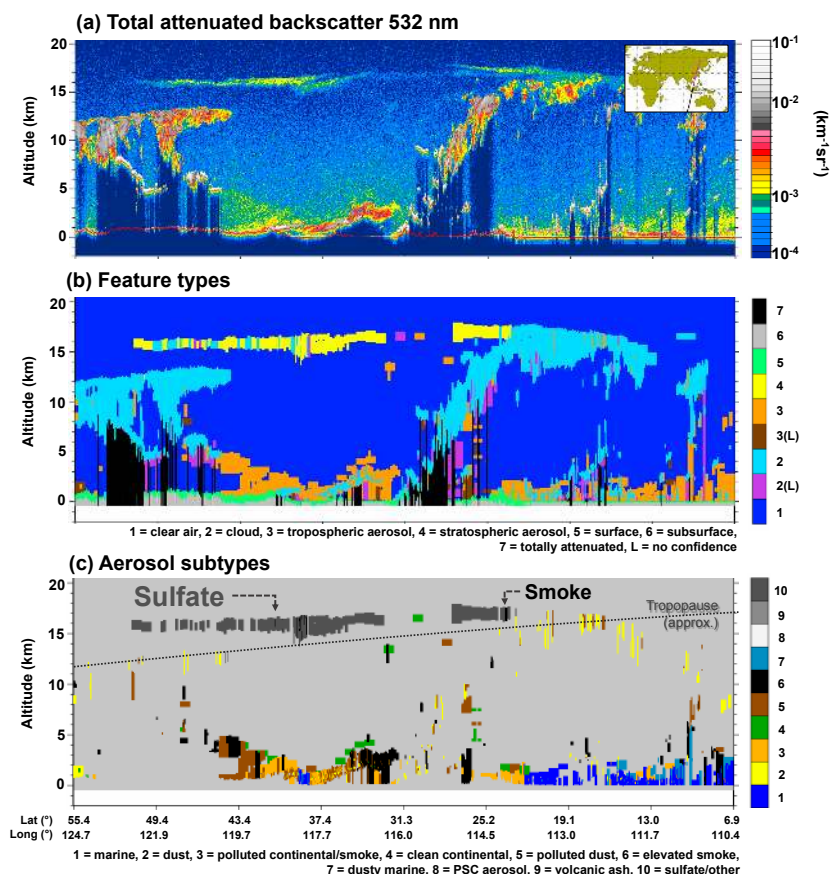


Figure 8. CALIOP observations of the Nabro volcano plume on 18 June 2011 between 18:13 and 18:26 UTC. (a) Total attenuated backscatter at 532 nm, (b) V4 feature type classifications, and (c) V4 aerosol subtypes; the dashed line indicates approximate location of the tropopause. The satellite ground track is indicated by the magenta section on the inset map in panel (a). Additional imagery for this scene, including 532 nm depolarization ratios and attenuated backscatter color ratios, can be found at https://www-calipso.larc.nasa.gov/products/lidar/browse_images/show_detail.php?s=production&v=V4-10&browse_date=2011-06-18&orbit_time=18-13-27&page=1&granule_name=CAL_LID_L1-Standard-V4-10.2011-06-18T18-13-27ZN.hdf (last access: 26 September 2018).

al. (2014) find that the median lidar ratio for layers identified as marine aerosol is 23 sr. Haarig et al. (2017b) observed lidar ratios for marine aerosols as a function of relative humidity with a multiwavelength polarization Raman lidar and found that the 532 nm lidar ratios increased from 23 sr for spherical sea salt particles to 25 sr for cubic-like particle ensembles.

With respect to marine lidar ratios at 1064 nm, Josset et al. (2012) applied the Synergized Optical Depth of Aerosols (SODA) technique (Josset et al., 2011) to CALIOP measurements at both 532 and 1064 nm and found no spectral dependence in the retrieved lidar ratios. Similarly, Sayer et al. (2012) calculate lidar ratios for marine aerosols from AERONET island sites, spread throughout the world's oceans, and find little spectral dependence. Based on these studies, the CALIOP lidar ratio for clean marine at 1064 nm is changed from 45 ± 23 sr in previous versions to 23 ± 5 sr, which is same value used at 532 nm in V4.

2.5.1 Dust

There are multiple studies reporting dust lidar ratios larger than 40 ± 20 sr at 532 nm, the value used in previous versions of the CALIOP algorithm (e.g., Liu et al., 2002; Müller et al., 2007; Wandinger et al., 2010; Schuster et al., 2012; Papiannopoulos et al., 2016; Haarig et al., 2017a). Liu et al. (2015) derive the dust lidar ratio directly from the CALIOP measurements using a constrained opaque water cloud technique (Hu, 2007) and find mean and median lidar ratios of 45.1 and 44.4 ± 8.8 sr for moderately dense Sahara dust layers. Furthermore, from measurements of ground-based Raman lidars and airborne HSRL, no wavelength dependence of dust lidar ratio is found at 355, 532, and 1064 nm (Tesche et al., 2009). Based on these studies, dust lidar ratios in V4 are modified to 44 ± 9 sr at 532 nm and 44 ± 13 sr at 1064 nm. Though lidar ratios for dust show regional variability ranging mostly from 35 to 60 sr (Cattrall et al., 2005; Schuster et

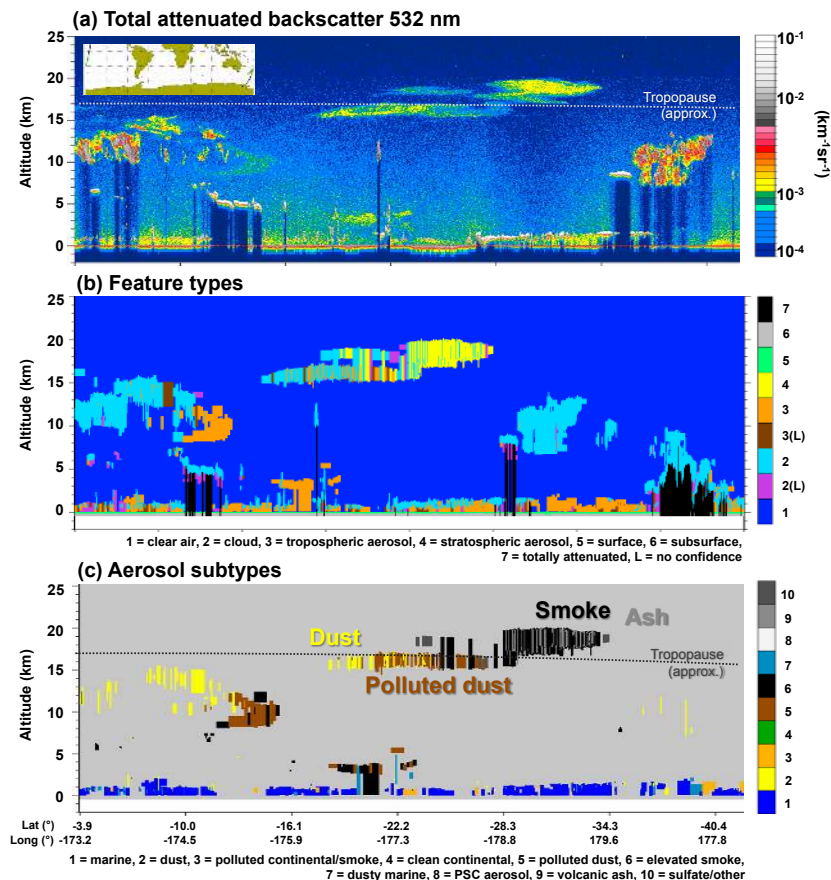


Figure 9. CALIOP observations of smoke plumes from the Australian bush fire on 15 February 2009 between 13:19 and 13:32 UTC. (a) Total attenuated backscatter 532 nm, (b) V4 feature type classification, and (c) V4 aerosol subtypes, where the dashed line indicates the approximate location of the tropopause. The satellite ground track is indicated by the green section on the inset map in panel (a). Additional imagery for this scene, including 532 nm depolarization ratios and attenuated backscatter color ratios, can be found at https://www-calipso.larc.nasa.gov/products/lidar/browse_images/show_detail.php?s=production&v=V4-10&browse_date=2009-02-15&orbit_time=12-52-14&page=3&granule_name=CAL_LID_L1-Standard-V4-10.2009-02-15T12-52-14Z.hdf (last access: 26 September 2018).

al., 2012; Mamouri et al., 2013; Nisantzi et al., 2015), only a single value is used in the V4 algorithm. Implementing a regionally varying lidar ratio for dust is complicated due to uncertainties in determining the dust source regions for transported dust and introducing unnatural discontinuities in global dust AOD. The uncertainty in the V4 dust lidar ratio of 20 % (30 %) at 532 nm (1064 nm) accounts for the regional variability.

2.5.2 Polluted continental and elevated smoke

Polluted continental lidar ratios at 532 nm and 1064 nm are unchanged from V3 to V4, at 70 ± 25 sr and 30 ± 14 sr, respectively. For elevated smoke, the 532 nm lidar ratio is the same in both versions, but, based on a study by Liu et al. (2015), the uncertainty is reduced from 70 ± 28 sr in V3 to 70 ± 16 sr in V4. The lidar ratio at 1064 nm for elevated smoke is changed from 40 ± 24 sr in V3 to 30 ± 14 sr in V4 (Sayer

et al., 2014), so that the V4 value for smoke now matches that of polluted continental. Elevated smoke detected in the stratosphere also uses these same lidar ratios.

2.5.3 Clean continental

In V3, the lidar ratios used for the clean continental subtype were 35 ± 16 sr at 532 nm and 30 ± 17 sr at 1064 nm. The 532 nm value is generally consistent with the background aerosol lidar ratios being reported in the literature available at the start of the mission (e.g., Voss et al., 2001; Ansmann et al., 2001). However, in an extensive CALIPSO validation study, Rogers et al. (2014) found that the mean 532 nm lidar ratio measured by the LaRC HSRL in layers identified by CALIOP as clean continental was 53 ± 11 sr. In V4, the 532 nm lidar ratio for clean continental aerosols is therefore changed to 53 ± 11 sr. Because the LaRC HSRL only measures lidar ratio at 532 nm, no additional information on lidar

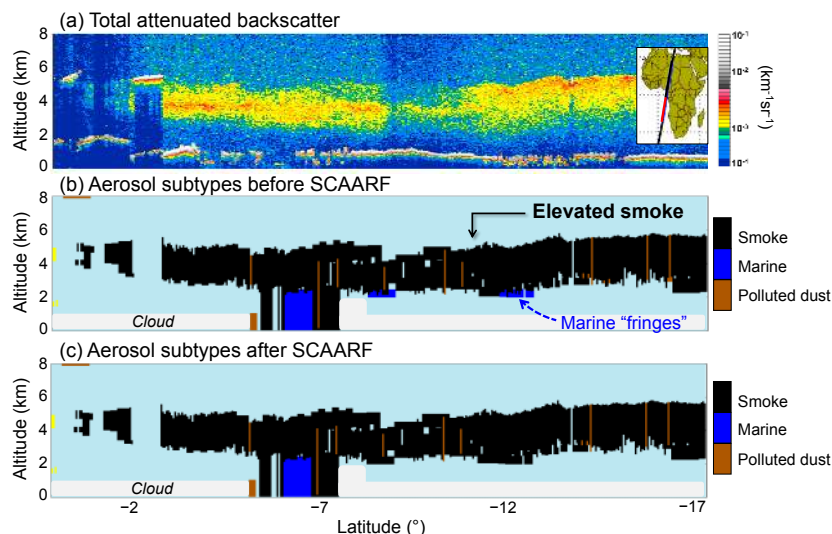


Figure 10. CALIOP observations of a smoke plume off the west coast of Africa on 14 September 2008 from approximately 01:08 to 01:10 UTC. **(a)** Total attenuated backscatter 532 nm and aerosol subtype classification **(b)** before and **(c)** after SCAARF is implemented. The inset map in **(a)** shows the CALIOP ground track in red. Aerosol subtypes elevated smoke (black), clean marine (blue), and polluted dust (brown).

ratios at 1064 nm is available from Rogers et al. (2014). Consequently, the V4 lidar ratio for clean continental aerosol at 1064 nm remains unchanged from V3.

2.5.4 Polluted dust and dusty marine

Validation with MODIS and airborne HSRL measurements shows that CALIOP V3 AODs and lidar ratios appear to be biased high for layers in some regions which are classified as polluted dust (Kim et al., 2013; Burton et al., 2013; Rogers et al., 2014). This is especially true over the ocean. Since CALIOP V3 did not account for mixtures of dust and sea salt, which are frequent in the MBL, the bias is likely a result of dust + marine misclassified as dust + smoke. For this reason, the lidar ratios for polluted dust remain the same in V4 as in V3, and a new aerosol subtype, dusty marine, is introduced to reflect the correct mixture. The lidar ratios for polluted dust are unchanged from their V3 values, at 55 ± 22 sr at 532 nm and 48 ± 24 sr at 1064 nm. Based on an assumed external mixture of dust and marine aerosol (mixing ratio of 65 : 35 by surface area), the lidar ratios for dusty marine are fixed at 37 ± 15 sr at both wavelengths, using mean lidar ratios of 44 and 23 sr for pure dust and clean marine, respectively. Using the NASA HSRL in the MBL in the Caribbean region, Rogers et al. (2014) found lidar ratios of 37 ± 11 sr for mixtures of dust and marine aerosols. As is the case for both dust and marine, the lidar ratios for dusty marine combination are spectrally independent. However, the lidar ratio uncertainties ascribed to the dusty marine type are larger than either dust or marine alone. The range of uncertainty of the dusty marine lidar ratio in V4 (15 sr) is greater than the uncertainty for these mixtures in Rogers et al. (2014) and accounts for a

large range of possible surface area mixing ratios of dust and marine aerosols in the ambient MBL.

2.5.5 Volcanic ash

Default lidar ratios for volcanic ash are set in V4 to match that of the dust subtype: 44 ± 9 sr at both 532 and 1064 nm. These lidar ratios were selected following Winker et al. (2012), in which it is shown that the size distribution, composition, and shape of transported volcanic ash particles are similar to desert dust. This was based on comparisons of in situ aircraft measurements by Schumann et al. (2011) during the April 2010 Eyjafjallajökull volcano eruption and Saharan dust properties described by Omar et al. (2010). In reality, lidar ratios for volcanic ash vary depending on the composition of the plume and circumstances of the eruption (water vapor content, mineralogy, plume age, injection height, etc.). Recent studies have found higher lidar ratios for volcanic ash (Table 3). For example, lidar ratios of 50 ± 10 sr were retrieved for volcanic ash transported over Europe during the April 2010 Eyjafjallajökull volcano eruption (Ansmann et al., 2011; Groß et al., 2012), with mean lidar ratios of 60 ± 5 sr at Leipzig on 16 April 2010 (Ansmann et al., 2010). Recently, Prata et al. (2017) used constrained CALIOP retrievals to estimate mean particulate lidar ratios of 69 ± 13 sr for volcanic ash from the June 2011 Puyehue-Cordón Caulle eruption. The results of these studies suggest that 44 sr is likely near the lower limit of natural variability. Given the large variability in lidar ratios for volcanic ash and the evolving state of knowledge, the CALIPSO team is further studying the representativeness of this lidar ratio based

Table 3. Mean 532 nm lidar ratios reported in the literature for volcanic ash and volcanic sulfate.

Mean lidar ratio (532 nm)	Volcanic eruption	Reference
Ash-dominant aerosol		
50 ± 10 sr	Eyjafjallajökull, 2010	Ansmann et al. (2011); Groß et al. (2012)
60 ± 5 sr	Eyjafjallajökull, 2010	Ansmann et al. (2010)
69 ± 13 sr	Puyehue-Cordón Caulle, 2011	Prata et al. (2017)
Sulfate-dominant aerosol		
30–50 sr	Kasatochi, 2008; Sarychev Peak, 2009	Mattis et al. (2010)
48 sr	Nabro, 2011	Sawamura et al. (2012)
55 sr	Mt. Etna, 2002	Pappalardo et al. (2004)
55 ± 4 sr	Sarychev Peak, 2009	O'Neill et al. (2012)
63 ± 14 sr	Sarychev Peak, 2009	Prata et al. (2017)
65 ± 10 sr	Kasatochi, 2008	Hoffmann et al. (2010)
66 ± 19 sr	Kasatochi, 2008	Prata et al. (2017)

on information gained since the 2016 release of the version 4 level 2 products.

2.5.6 Sulfate/other

Default lidar ratios for sulfate/other are 50 ± 18 sr and 30 ± 14 sr at 532 and 1064 nm, respectively. Researchers have previously reported independent lidar measurements of sulfate-rich volcanic plumes from the Mt. Etna 2002, Kasatochi 2008, Sarychev Peak 2009, and Nabro 2011 eruptions, summarized in Table 3. Lidar ratios from these studies range from 30 to 66 sr, with CALIOP-constrained lidar ratio retrievals reported by Prata et al. (2017) on the high end: 63 ± 14 sr and 66 ± 19 sr for the Kasatochi and Sarychev Peak eruptions, respectively. The 532 nm lidar ratio for sulfate is consistent with these studies given the variability in measured lidar ratios and the 35 % uncertainty implemented with the default lidar ratio, yielding 50 ± 18 sr. Independent measurements of 1064 nm lidar ratios for volcanic sulfate are sparse in the literature. The default lidar ratio value of 30 sr, however, is consistent with Jäger and Hofmann (1991), who reported measured background stratospheric aerosol levels of 35 and 39 sr for years 1979–1980 and 1986–1987, respectively. The 1064 nm lidar ratio is also consistent with that of the CALIOP model for polluted continental aerosol, which is, in part, modeled after sulfate (Omar et al., 2009).

2.5.7 Polar stratospheric aerosol

Default lidar ratios for PSA are 50 ± 20 sr at 532 nm and 25 ± 10 sr at 1064 nm. As discussed in Sect. 2.3, these aerosol layers exhibit a qualitative spatial correlation with the STS composition class in the CALIPSO level 2 PSC mask product. These lidar ratios and their wavelength dependence are consistent with theoretical Mie scattering calculations for STS droplets at pressures typical of the Arctic stratosphere.

3 Aerosol subtyping changes from version 3 to version 4

The performance and final results delivered by the V4 aerosol subtyping algorithm are affected by V4 changes to several other algorithms that occur earlier in the level 2 processing scheme. The CALIOP V4 level 1 data significantly improved the calibration of the CALIOP attenuated backscatter coefficients (β') at both 532 and 1064 nm (Getzewich et al., 2018; Kar et al., 2018; Vaughan et al., 2018a). In particular, calibration coefficients at 532 nm decreased by $\sim 3\%$ to $\sim 12\%$, depending on latitude and season, resulting in a concomitant increase in β' at 532 nm. The increased magnitude of β' at 532 nm subsequently yields an increase in the number of tenuous layers detected by the CALIOP feature finder. The V4 CAD algorithm features entirely new probability distribution functions (PDFs) that are now more sensitive to the presence of lofted aerosols (Liu et al., 2018). As a consequence, the V4 data products show improvements in the identification of high-altitude smoke plumes and Asian dust layers, which in earlier versions were often classified as cirrus clouds. Also, the V4 analyses use a completely new algorithm to detect the Earth's surface detection (Vaughan et al., 2018b). This new technique demonstrates an improvement over the V3 method in turbid atmospheres, while maintaining equal or better performance in clear skies. As a result of this improved surface detection scheme, there are fewer opaque layers identified in V4 than there were in V3, especially at night. Because regions below layers previously classified as opaque are now scanned for the presence of atmospheric features, there is also a slight increase in the number of cloud and aerosol layers reported. Taken together, these changes yield an increase in the absolute number of layers classified as aerosols in V4 relative to V3.

The feature type changes from/to aerosol, aerosol subtyping changes, and resulting AOD changes between V3 and

Table 4. Feature type and aerosol subtype changes in the CALIOP level 2 atmospheric volume description (AVD) between version 3 (V3) and version 4 (V4) from 2007 to 2009. Each (i,j) component of the table represents what fraction (expressed as a percentage) of type i in V3 changes to type j in V4; thus the summation of each column equals 100 (%). Since the total number of each type is different, relative total amounts for each type are shown as normalized total for both columns and rows, which are normalized to total number of bins for V3 aerosol.

V3 (columns) V4 (rows)	Total atten.	Clear	Cloud	Surface	Aerosol	CM*	Dust	PC*	CC*	PD*	Smoke	Strato. feature	Normalized total
Total atten.	84.30	0.03	1.42	12.98	0.09	0.13	0.06	0.06	0.01	0.11	0.02	0.00	2.09
Clear	7.14	98.97	1.92	7.81	6.28	4.43	4.99	8.88	14.87	7.10	8.61	4.11	34.18
Cloud	3.49	0.34	92.39	7.76	6.99	5.35	4.64	9.59	11.56	7.85	13.29	61.56	3.08
Surface	3.68	0.03	0.23	56.45	0.35	0.15	0.51	0.70	0.38	0.43	0.35	–	0.17
Tropo. aerosol	1.40	0.48	3.76	15.00	85.22	89.94	89.78	80.66	63.86	84.37	70.90	0.30	1.18
CM*	0.35	0.10	0.50	10.63	33.78	80.83	0.40	21.99	11.60	6.15	0.12	–	0.41
Dust	0.35	0.09	1.68	0.90	17.16	0.19	73.25	1.74	5.02	6.63	0.89	0.10	0.26
PC*/smoke	0.08	0.04	0.18	0.84	5.66	0.93	0.48	33.08	9.69	5.20	18.13	–	0.08
CC*	0.01	0.02	0.02	0.11	0.66	0.00	0.05	0.58	8.82	0.54	0.65	0.02	0.01
PD*	0.16	0.11	0.75	0.66	10.81	0.02	10.45	5.45	11.26	32.36	6.94	0.07	0.17
Elev. smoke	0.15	0.07	0.36	0.11	7.53	4.09	0.27	11.60	10.17	4.72	43.67	0.11	0.12
DM*	0.31	0.05	0.27	1.76	9.62	3.87	4.89	6.23	7.31	28.78	0.50	–	0.13
Strato. aerosol	0.00	0.16	0.27	–	1.07	0.00	0.01	0.11	9.31	0.14	6.84	34.03	0.13
PSA	0.00	0.02	0.11	–	0.06	–	–	0.01	1.21	0.00	0.01	13.84	0.04
Volcanic ash	0.00	0.00	0.01	–	0.00	–	0.00	–	0.01	0.00	0.00	0.25	0.00
Sulfate/other	0.00	0.13	0.14	–	1.00	0.00	0.01	0.11	8.06	0.13	6.81	19.73	0.10
Smoke	0.00	0.00	0.01	–	0.01	–	–	0.00	0.04	0.01	0.02	0.21	0.00
Total	100	100	100	100	100	100	100	100	100	100	100	100	
Normalized total	2.40	34.22	2.90	0.11	1.00	0.38	0.21	0.06	0.05	0.22	0.08	0.18	40.82

* CM: clean marine; PC: polluted continental; CC: clean continental; PD: polluted dust; DM: dusty marine; PSA: polar stratospheric aerosol.

V4 are analyzed using the atmospheric volume description (AVD) reported in the level 2 aerosol profile product. AVD reports both feature type and aerosol/cloud subtype for each $5\text{ km} \times 60\text{ m}$ ($5\text{ km} \times 180\text{ m}$ for above 20.2 km) range bin. The feature types include clear air, cloud, tropospheric aerosol, stratospheric feature/aerosol (V3/V4, respectively), surface, subsurface, and totally attenuated regions (i.e., beneath layers classified as opaque in V3 but reclassified as transparent in V4). Table 4 shows changes in feature type and aerosol subtype between V3 and V4 using the AVD data in the level 2 profile products. Though the table contains all changes among feature types and aerosol subtypes, in this study we focus solely on changes in the distribution of aerosol subtypes and the downstream effects of these changes in the global and regional distributions of AOD.

3.1 Feature type changes

Feature type changes between V3 and V4 are predominantly due to extensive changes in the calibration coefficients reported in the CALIOP level 1 product, which in turn required major revisions of the PDFs that drive the CAD algorithm (Liu et al., 2018). Changes to the surface detection algorithm (Vaughan et al., 2018b) also contribute, but to a significantly lesser extent. In order to quantify how the occurrence frequency of aerosol types has changed, Table 4 reports the

percent changes in “feature type” and “aerosol subtype” between V3 and V4 for all 60 m range bins in the CALIOP level 2 profile product from 2007 to 2009. Salient statistics drawn from Table 4 are given here and in subsequent sections. Within the 3-year analysis period, the classification of 13.7 % of the layers identified as tropospheric aerosols in V3 has changed to totally attenuated (0.1 %), clear air (6.3 %), cloud (7.0 %), or surface (0.4 %) in V4. In spite of this reduction, however, tropospheric aerosols in V4 increase by 18 % due to newly identified aerosols from regions that were identified in V3 as totally attenuated layer, clear air, cloud, or surface. The V3 CAD algorithm did not separate aerosols from clouds for layers detected in the stratosphere; instead, it identified these layers generically as stratospheric features. In V4, however, the CAD algorithm is applied in both the troposphere and stratosphere, and thus aerosol layers are identified and classified in the stratosphere. When including newly introduced stratospheric aerosol layers (13 %), aerosols increase by 31 % in V4 compared to V3. The CALIOP V4 algorithm detects more aerosol, resulting in an increase in AOD. Additionally, the improved surface detection scheme of V4 results in fewer opaque layers than in V3 (Vaughan et al., 2018b). Thus, regions below layers previously classified as opaque are now scanned for the presence of atmospheric features. This leads to an increase in the number of aerosol layers reported near the surface.

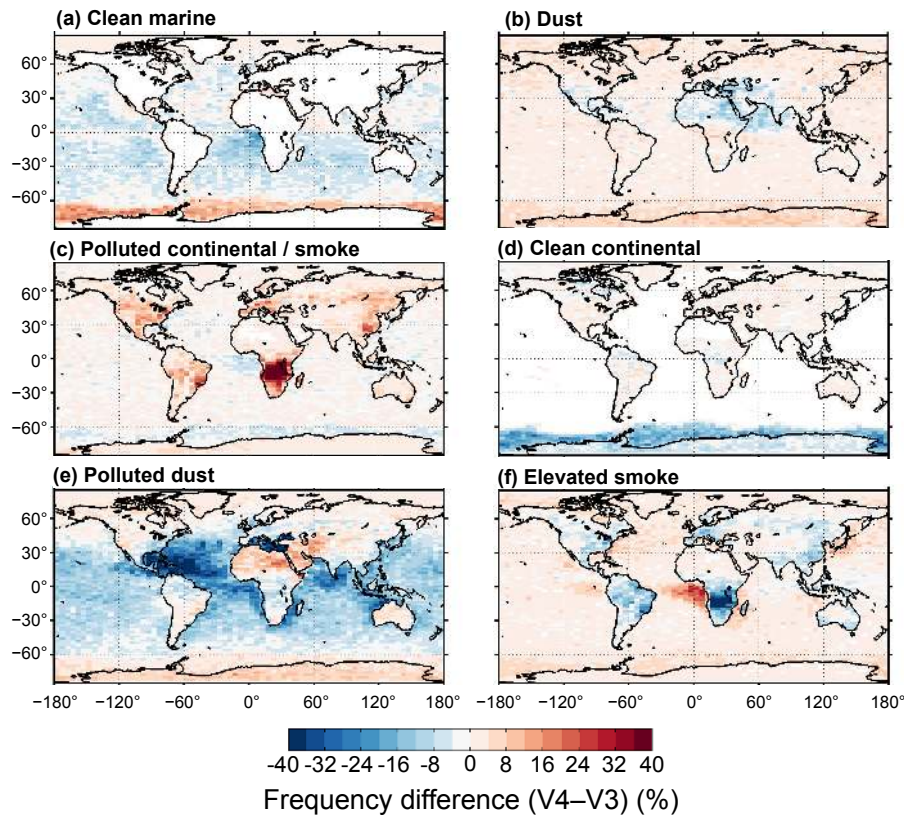


Figure 11. Differences in frequency of occurrence of indicated aerosol subtype from V3 to V4 ($f_{V4} - f_{V3}$) for aerosol subtypes common to both versions, JJA 2007 day and night. Frequencies are computed from level 2 aerosol profile products and the number of aerosol samples, with the indicated aerosol type divided by the total number of aerosol samples.

3.2 Aerosol subtype changes

The spatial distribution and frequency of occurrence of aerosols has changed from V3 to V4 for reasons described in Sect. 3.1. Similarly, enhancements to the aerosol subtyping algorithm described in Sect. 2 are responsible for changes in the spatial distributions and occurrence frequencies of the different aerosol subtypes. The net effect of these changes is demonstrated by Fig. 11, which shows the difference in aerosol subtype detection frequencies for JJA 2007, day and night combined. For context, Fig. 12 shows the number of aerosol samples detected during the same time period. The frequency of clean marine aerosol is slightly reduced in V4 except for in the oceans around Antarctica (Fig. 11a), with most changed layers becoming dusty marine. Table 4 shows that 3.9 % of V3 clean marine aerosol is reclassified as dusty marine in V4. The increase in clean marine aerosol in V4 over the Antarctic Ocean mainly comes from clean continental and polluted continental aerosols due to the changes in aerosol subtyping algorithm over the polar regions (Fig. 1). Approximately 4.1 % of clean marine aerosol off the southwest African coast became elevated smoke in 2007–2009 (Table 4).

The revised definition for elevated smoke (Sect. 2.1.3) and the implementation of SCAARF (Sect. 2.3) are responsible for correcting the frequency of elevated smoke classifications in this region in V4 (Fig. 11f). Additionally, the revised elevated smoke definition is responsible for the changes in polluted continental/smoke and elevated smoke classifications over southern Africa in Fig. 11c and f, respectively. During JJA, smoke from biomass burning is ubiquitous in this region, so a smoke aerosol subtype classification is expected most often. Because the top altitudes of smoke layers within this region are often below 2.5 km above the ground level, many layers do not meet the V4 elevated definition, causing an increase in the frequency of polluted continental/smoke classifications and a reduction in the frequency of elevated smoke classifications compared to V3.

As expected and intended, the introduction of the new dusty marine aerosol type (Sect. 2.1.2) has improved the aerosol subtyping over oceans in regions where mixtures of dust and urban pollution are not expected (e.g., the mid-Atlantic and mid-Pacific oceans). This is shown by a decreased frequency of polluted dust aerosol layers in V4 (Fig. 11e). Over the north African–Arabian dust region, the frequency of polluted dust has increased while the frequency

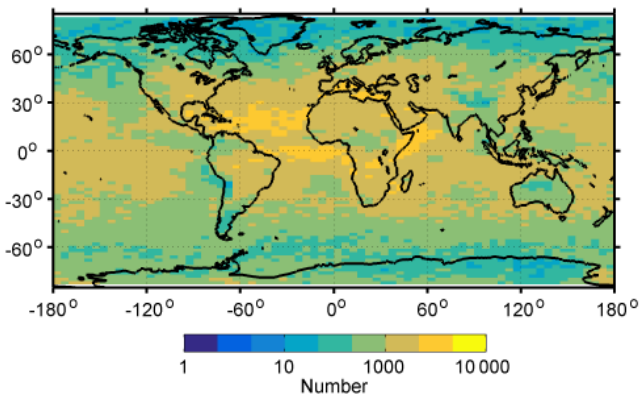


Figure 12. Number of aerosol samples detected in V4 for JJA day and night combined, computed from the CALIOP level 2 aerosol profile product.

of dust has decreased (Fig. 11b), in part due to correcting the overestimate of δ_p^{est} that existed in V3. This correction in δ_p^{est} also caused about 4.9 % of V3 dust to become dusty marine in V4 (Table 4). Though the fraction of aerosol classified as dust has changed by a small amount, the number of dust layers at high altitudes has increased due to changes in CAD, which shows an improved ability to correctly classify lofted dust layers as aerosols rather than cirrus clouds (Liu et al., 2018).

The frequency of clean continental aerosol has decreased over regions characterized by snow, ice, and tundra (Fig. 11d) because all aerosol type classifications are allowed in V4 over these surface types (Sect. 2.1.1). Clean continental aerosols have mainly changed to clean marine (11.6 %), polluted dust (11.3 %), elevated smoke (10.2 %), and polluted continental/smoke (9.7 %). The increase in dust and polluted dust classifications over the Antarctic reflect CAD misclassifications of tenuous ice clouds and blowing snow. Only 8.8 % of clean continental aerosol layers are unchanged in V4 (Table 4).

As a global summary, Fig. 13 shows frequency distributions of aerosol subtypes for daytime and nighttime in V3 and V4, normalized by the total number of bins (day and night together for each version) that were classified as aerosol according to the AVD data from the level 2 aerosol profile products. More aerosol layers are detected at night for both V3 and V4 (Liu et al., 2018). This is expected since a higher SNR at night means the CALIOP layer detection algorithm detects more weakly scattering features during nighttime (Vaughan et al., 2009). Clean continental is only rarely identified in V4. Clean continental was common in the polar regions, especially over the Antarctic in V3. Because V4 allows all aerosol types in the poles, the dominance of clean continental is significantly reduced, as shown in Fig. 11d. The frequency of polluted dust is reduced for both day and night. While part of this reduction is due to the layer attenuation corrections men-

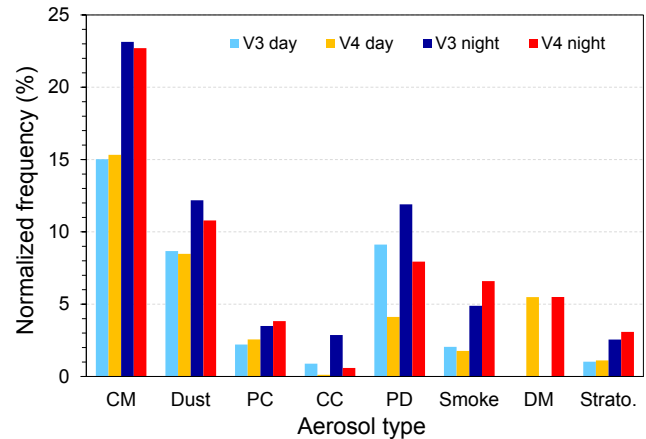


Figure 13. Normalized frequencies of aerosol subtypes in V3 and V4 for daytime and nighttime. Note that “strato.” represents stratospheric features for V3 but stratospheric aerosols for V4. CM: clean marine; PC: polluted continental; CC: clean continental; PD: polluted dust; DM: dusty marine.

tioned in Sect. 2.1.1, the predominant reason is because layers previously classified as polluted dust are now more realistically classified as dusty marine in V4. Since the frequency of occurrence of polluted dust aerosols is larger for daytime compared to nighttime over ocean in V3, as shown in Fig. 3b, the change from polluted dust to dusty marine is relatively more frequent for daytime than nighttime. In fact, 59 % of the daytime dusty marine in V4 is polluted dust in V3, but only 42 % of the nighttime dusty marine is polluted dust in V3. The generic stratospheric features previously identified in V3 are now classified as clouds or aerosol in V4. During the daytime, these V3 stratospheric features are more frequently identified as clouds, rather than aerosols. At night the situation is reversed: nighttime V3 stratospheric features are most often classified as aerosols.

3.3 AOD changes

In order to compute the change in AOD from V3 to V4, CALIOP level 2 aerosol extinction profiles are vertically integrated and compared profile to profile between the two versions. Only profiles in which either V3 or V4 contained aerosol are included in the average. In cases in which only one version reports aerosol, the other version is assumed to have AOD = 0. Furthermore, only aerosol bins with the extinction quality control (QC) flags of 0, 1, 16, and 18 are used (excluding 6 % of aerosol samples), which represent unconstrained retrievals that do not change the lidar ratio (0), constrained retrievals that derive an optimized lidar ratio (1), opaque layers for which the lidar ratio was not changed (16), and opaque layers in which the lidar ratio was reduced to prevent the retrieval from diverging (18), respectively (Tackett et al., 2018). For 2007 to 2009, the total change in mean nighttime (daytime) CALIOP level 2 column AOD has in-

Table 5. Mean column AODs (\pm standard deviation) for CALIOP V3 and V4, computed from aerosol extinction profiles, for all-sky conditions from 2007 to 2009. Profiles in which either V3 or V4 contained aerosol layers are included in the average.

	Night	Day
V3	0.084 ± 0.162	0.090 ± 0.150
V4	0.128 ± 0.242	0.126 ± 0.202

creased from 0.084 (0.090) in V3 to 0.128 (0.126) in V4 (Table 5). Day and night AOD become more comparable in V4, whereas daytime AOD is larger than nighttime AOD in V3. Note that the mean AOD computed here is not meant to represent global conditions but instead examines AOD changes only where AOD is detected by CALIOP.

The AOD increase from V3 to V4 is due to various factors. Using the feature types and aerosol subtypes reported in the level 2 AVD, AOD changes attributed to layer detection, CAD, totally attenuated layers, surface detection, stratospheric aerosol classification, aerosol type, and lidar ratio are identified using the procedure diagrammed in Fig. 14. This strategy isolates changes in AOD due to each of these factors using CALIOP level 2 products from 2007 to 2009. All range bins whose feature type is determined as aerosol by either V3 or V4 are selected for the analyses. If a bin is identified as aerosol in one of V3 or V4 and the other is clear, the corresponding AOD change is regarded as changing due to the difference of layer detection in the two versions (pathway 1 in Fig. 14). Similarly, an aerosol bin that changed from/to cloud, totally attenuated layer, surface, and stratospheric feature is counted in the AOD changes due to the updates of CAD, totally attenuated signals, surface detection, and stratospheric aerosol in V4, respectively (pathways 2–5). When feature types in both V3 and V4 are aerosol, AOD differences can be due to aerosol subtype changes (pathway 6) or lidar ratio adjustments without changing subtype (pathway 7). If aerosol subtype is identified as polluted continental, polluted dust, or smoke in both V3 and V4, there are no changes in the aerosol subtyping (pathway 8). However, the AOD can be different between V3 and V4 even when there are “no changes” in their subtype and lidar ratio. The most likely source of these differences is changes in the magnitude of β' , either due to level 1 calibration improvements (Kar et al., 2018; Getzewich et al., 2018) or to changes in the two-way transmittances estimated for overlying cloud and/or aerosol layers (Young et al., 2018).

Table 6 quantifies the AOD changes from V3 to V4 for all-sky conditions for the different factors categorized in Fig. 14, i.e., layer detection, CAD, surface detection, stratospheric aerosol, aerosol subtype, lidar ratio, and no change. Here, the all-sky analysis includes all profiles that contain identified aerosol regardless of the presence of clouds. All of the factors listed above contribute to the increase in AOD in V4,

and the magnitudes of the AOD changes are strongly related to their occurrence frequencies (Table 6).

Global maps of AOD changes for each factor are shown in Fig. 15. CALIOP AOD has increased by 0.007 and 0.005 for nighttime and daytime, respectively, because of changes in layer detection (Table 6 and Fig. 15b). This implies that the CALIOP V4 layer detection algorithm finds tenuous layers that were not found in V3. Note that no significant changes were made to the CALIOP layer detection algorithm in V4. The increased detection of faint layers is attributed primarily to changes in the 532 nm calibration coefficients that generally increase β' . The CAD algorithm classifies most of these new layers as aerosols.

Figure 15c shows that AOD changes due to CAD have a day and night difference. The mean daytime AOD increase is twice the nighttime AOD increase (Table 6). The daytime AOD increase is due primarily to a net increase in the number of V4 aerosols. The number of new aerosols in V4 (i.e., layers that were classified as clouds in V3) is much larger (~ 3.4 times) than the converse (i.e., the aerosols in V3 that were classified as clouds in V4) at daytime. Among these new aerosols, the subtypes dust and polluted dust account for more than 50%. The V4 CAD PDFs were deliberately tuned to be more sensitive to aerosol presence in the upper troposphere and lower stratosphere, resulting in improved performance in distinguishing high-altitude Asian dust plumes from cirrus (Liu et al., 2018). However, as a side effect, some fraction of the cirrus fringes detected along the edges and lower boundaries of cirrus clouds that were classified as clouds in V3 are now classified as aerosols in V4. Most of these misclassified fringes are subsequently identified as dust or polluted dust by the aerosol subtyping algorithm. These increases in misclassified dust and polluted dust at high altitudes contribute the most to the daytime AOD increase due to CAD. Although the misclassification of cirrus fringes as aerosols also occurs in the V4 nighttime aerosol products, the gain and loss in the total aerosol number due to CAD are about the same and hence the change in nighttime aerosols cannot fully explain the increase in the nighttime mean AOD increase in Table 6. It appears that the change in V4 level 1 data calibration also plays an important role. As discussed below for Fig. 15i, changes in the V4 level 1 data calibration alone can cause a nighttime AOD increase of 0.003, as shown in Table 6, about half the nighttime AOD change of 0.007 due to CAD. However, the net change for each aerosol subtype varies largely and may play an important role in the regional AOD changes as seen in the left panel of Fig. 15c.

If a bin is previously identified as totally attenuated in V3 and becomes aerosol in V4, the most likely cause is difference in surface detection. The V4 surface detection algorithm (Vaughan et al., 2018b) is considerably more effective than the V3 algorithm in detecting the Earth’s surface after penetrating atmospheric layers of substantial optical depth (e.g., cirrus clouds with optical depths of 2.5 or larger). As a result, many regions where the signal was considered totally attenu-

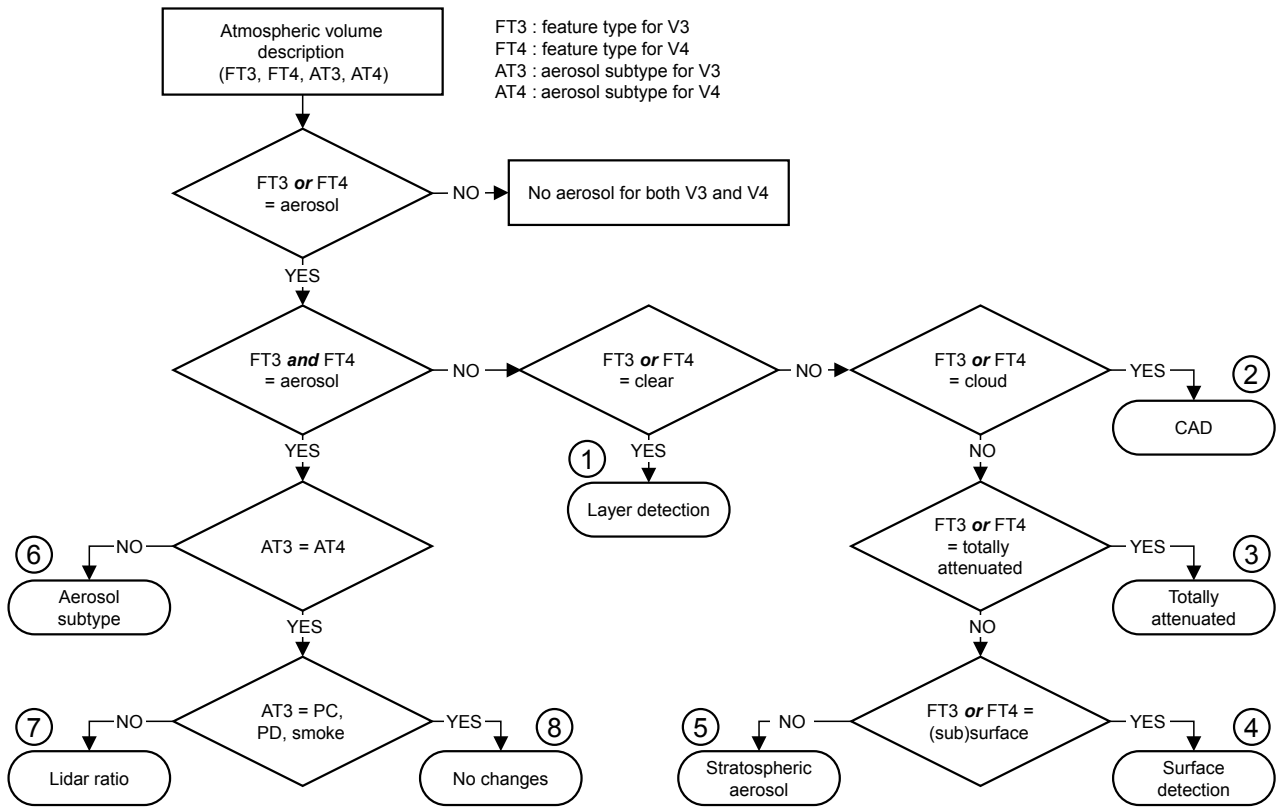


Figure 14. Flowchart to categorize factors that impact the AOD change between V3 and V4. Note that changes between polluted continental and smoke are treated as no changes because the lidar ratios at 532 nm for those aerosols are the same (70 sr). FT3 and FT4 represent the feature types assigned in V3 and V4, respectively. Similarly, AT3 and AT4 designate version-specific aerosol subtypes.

Table 6. Mean column AOD changes (\pm standard deviation) from CALIOP V3 to V4 (defined as $V4 - V3$) and their bin frequencies for different reasons described in Fig. 5 for all-sky conditions from 2007 to 2009.

	Frequency (%)		AOD change	
	Night	Day	Night	Day
Layer detection	20.9	17.5	0.007 ± 0.050	0.005 ± 0.061
CAD	11.7	12.2	0.007 ± 0.159	0.014 ± 0.121
Total attenuated	1.7	1.3	0.008 ± 0.075	0.003 ± 0.047
Surface detection	1.5	1.5	0.001 ± 0.025	0.002 ± 0.015
Stratospheric aerosol	5.5	4.0	0.001 ± 0.020	0.002 ± 0.017
Aerosol subtype	16.5	18.7	0.003 ± 0.081	-0.004 ± 0.068
Lidar ratio	31.5	36.8	0.013 ± 0.067	0.012 ± 0.060
No change	10.7	8.0	0.003 ± 0.040	0.003 ± 0.032
Total (number of samples)	100 (868, 893, 575)	100 (492, 266, 349)	0.044 ± 0.225	0.036 ± 0.183

ated in V3 are now searched for the presence of features, and the aerosol layers detected in these regions contribute to an increase in AOD in V4 (Fig. 15d).

Changes in the surface detection and the newly introduced stratospheric aerosol types also contribute to AOD increases in V4, but not significantly. Figure 15e shows that some surface signals misclassified as aerosols in V3 are now classified

as surface in V4. This leads to a decrease in AOD especially in the southern Asian continent. Since the surface returns are much stronger than backscatter signals for aerosols, AOD changes appear relatively large. AOD increases due to newly introduced stratospheric aerosols in V4 are found mainly in the Arctic and Antarctic regions where the STS PSCs are

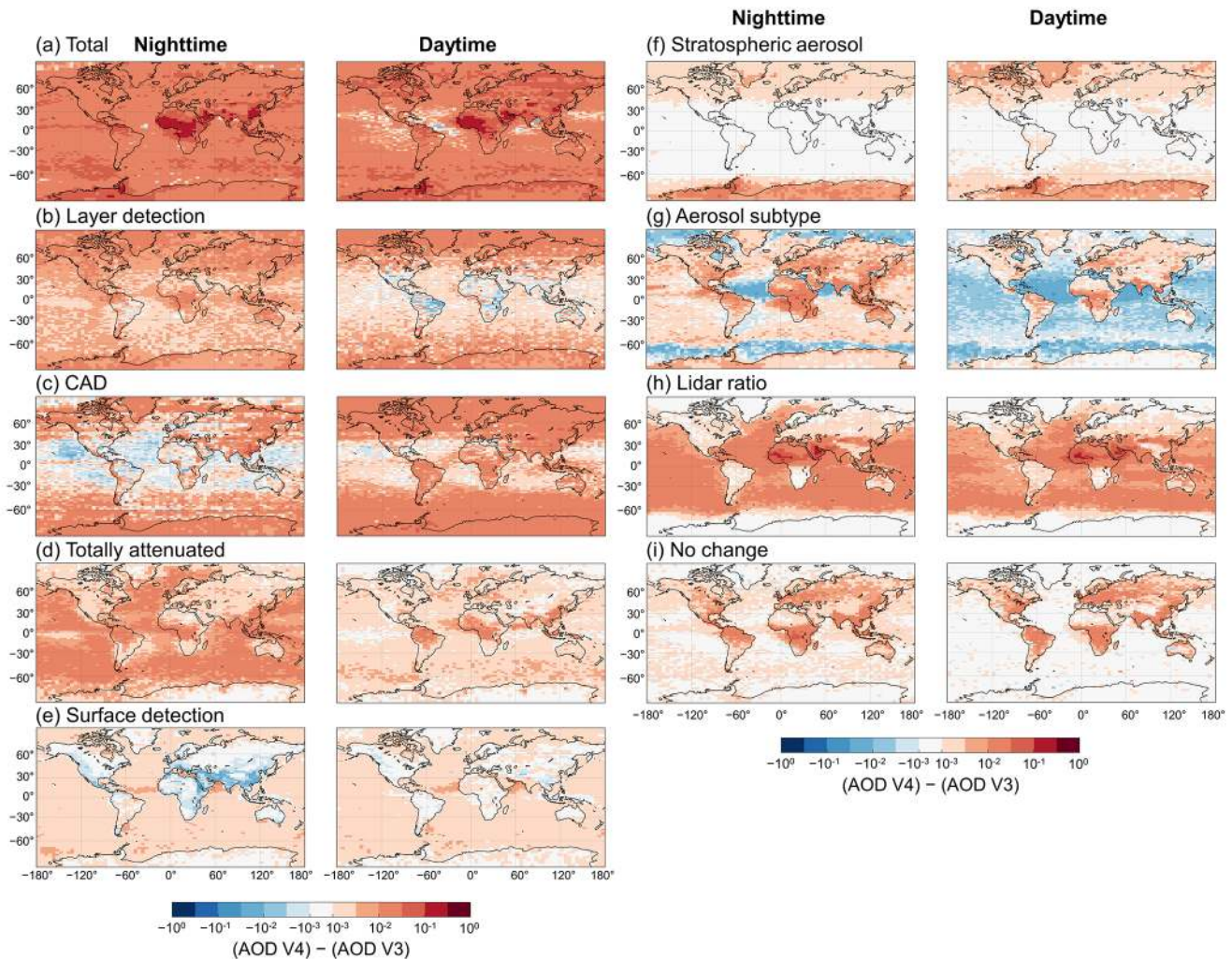


Figure 15. Global maps of mean AOD differences between V3 and V4 for each factor categorized in Fig. 14 from 2007 to 2009: (a) total, (b) layer detection, (c) CAD, (d) totally attenuated, (e) surface detection, (f) stratospheric aerosol, (g) aerosol subtype, (h) lidar ratio, and (i) no changes. Left and right columns are for nighttime and daytime, respectively.

ubiquitous in the polar winter and are most often classified as stratospheric aerosol in V4 (Fig. 15f).

There is a decrease in the mean AOD due to aerosol subtype changes for daytime, but an increase for nighttime (Table 6). Figure 15g shows that AOD changes due to the aerosol type changes generally have opposite signs at day and night over oceans. The dominant aerosol type over oceans is clean marine, which has the smallest lidar ratio among the CALIOP aerosol models. Therefore, any changes from clean marine to other types of aerosol can lead to an AOD increase in V4. This is the dominant type change over ocean for the nighttime. For the daytime, however, a type change from polluted dust to dusty marine occurs more frequently, as explained earlier (Sect. 3.2). The reduction in lidar ratio from polluted dust (55 sr) to dusty marine (37 sr) leads to a decrease in the mean daytime AOD. AODs decrease for

both day and night over the mid-Atlantic and Indian oceans as well as over the Arctic and Antarctic oceans, as shown in Fig. 15g. Dust is frequently transported to the Atlantic and Indian oceans from the Saharan and Arabian deserts. Aerosol type changes from dust or polluted dust to dusty marine dominate in these regions and lead to the AOD decreases in these regions. The AOD decreases over the Arctic and Antarctic oceans are because the V4 aerosol subtyping algorithm now allows all aerosol types over these regions rather than solely the clean continental and polluted continental subtypes (Sect. 2.1.1).

Updates in lidar ratio led to an AOD increase of 0.013 and 0.012 for nighttime and daytime, respectively. The 532 nm lidar ratios for three aerosol subtypes were changed in V4: clean marine, dust, and clean continental. Since the lidar ratios for these subtypes were all increased, AOD increased

Table 7. Same as Table 6 but for cloud-free sky.

	Frequency (%)		AOD change	
	Night	Day	Night	Day
Layer detection	17.3	13.2	0.006 ± 0.030	0.003 ± 0.042
CAD	–	–	–	–
Total attenuated	0.1	0.2	0.000 ± 0.014	0.001 ± 0.022
Surface detection	2.2	2.1	0.001 ± 0.029	0.003 ± 0.014
Stratospheric aerosol	2.9	1.6	0.001 ± 0.009	0.001 ± 0.008
Aerosol subtype	18.2	22.8	0.000 ± 0.076	-0.008 ± 0.071
Lidar ratio	46.1	50.6	0.016 ± 0.056	0.013 ± 0.057
No change	13.2	9.7	0.003 ± 0.030	0.002 ± 0.028
Total (number of samples)	100 (362, 664, 890)	100 (249, 431, 801)	0.027 ± 0.113	0.015 ± 0.115

correspondingly. Figure 15h shows the AOD increases due to the lidar ratio updates. The AOD increase over oceans was due to the lidar ratio change for clean marine. The most significant AOD increase is seen over North Africa and the Arabian Peninsula where pure dust is a dominant aerosol type. The change was caused by the lidar ratio update for dust from 40 to 44 sr. Due to the nonlinear behavior of the AOD retrieval, this 10 % increase in lidar ratio yields an increase of up to 20 % in AOD for dust layers as shown by AOD retrieval above opaque water clouds (Liu et al., 2015). Some of the AOD increases are even larger over North Africa and the Arabian Peninsula, where the dust is generally denser than that over the East Atlantic, thus further amplifying the nonlinear response of AOD to lidar ratio.

Figure 15i shows AOD changes even if there are no changes in aerosol subtype and lidar ratio. AOD is slightly increased, especially over land. These changes are due to differences in calibration and two-way transmittance estimates for upper layers between V3 and V4.

AOD changes between V3 and V4 for cloud-free conditions are typically smaller than in the all-sky cases discussed above. Cloud-free cases are restricted to those profiles in which no clouds were detected for both V3 and V4 from the level 2 5 km profile product. Table 7 shows occurrence frequencies and AOD changes for cloud-free conditions. The frequencies for layer detection are substantially reduced compared to all-sky conditions. This implies that, when compared to V3, the V4 aerosol detection frequency is higher in cloudy skies but relatively unchanged for clear skies. This behavior is not unexpected and can be at least partially explained by the improved surface detection in V4 that identifies more transparent air columns compared with V3. This behavior can also be attributed partially to the presence of more misclassified cirrus fringes in V4 (Liu et al., 2018). Comparing Tables 6 and 7, a larger fraction of aerosols maintain their subtype in the cloud-free conditions than in the all-sky conditions (i.e., the lidar ratio category in Table 7 is 45.9 % night and 50.7 % day vs. 30.2 % night and 35.9 % day in Table 6). Due to the largely increased frequencies, AOD

increases by the lidar ratio updates in V4 overwhelm all the other factors for cloud-free skies compared to cloudy skies.

4 Preliminary validation with AERONET and MODIS

A low bias of the V3 CALIOP AOD estimates relative to both MODIS and AERONET has been established in a number of previous publications (Kacenelenbogen et al., 2011; Oo and Holz, 2011; Redemann et al., 2012; Schuster et al., 2012; Kim et al., 2013; Omar et al., 2013). In this study, CALIOP AODs for both V3 and V4 are compared with AERONET and MODIS using collocation methods similar to Omar et al. (2013) and Kim et al. (2013). The collocation criteria adopted for CALIOP and AERONET (level 2) require data acquisition times within ± 30 min and spatial matching of the CALIOP footprint to within a 40 km radius of the AERONET site. Enforcing these criteria yields 736 data pairs from 176 sites over the globe from 2007 to 2009. MODIS level 2 AOD and CALIOP level 2 column-integrated AODs whose distance from the center of the MODIS grid is less than 10 km are selected as collocated data pairs for the same period. CALIOP level 2 data with extinction QC flags of 0, 1, and 16 are used for both V3 and V4. MODIS collection 6 Dark-Target AODs (Levy et al., 2013), “Effective_Optical_Depth_Average_Ocean” over ocean and “Corrected_Optical_Depth_Land” over land at 550 nm, with “Quality_Assurance_Ocean” of 1 (marginal) or higher and “Quality_Assurance_Land” of 3 (very good) are used for comparison. To remove cloud contamination, data pairs with CALIOP cloud column optical depths greater than 0 or MODIS cloud fractions greater than 0 % are rejected.

Global maps of AOD differences between CALIOP and AERONET–MODIS (CALIOP – AERONET–MODIS) are shown in Fig. 16. The color-coded maps show AOD differences relative to MODIS, while differences relative to AERONET are shown as individual filled circles on the map. The AOD differences between CALIOP and AERONET are generally similar between the two versions. Likewise, re-

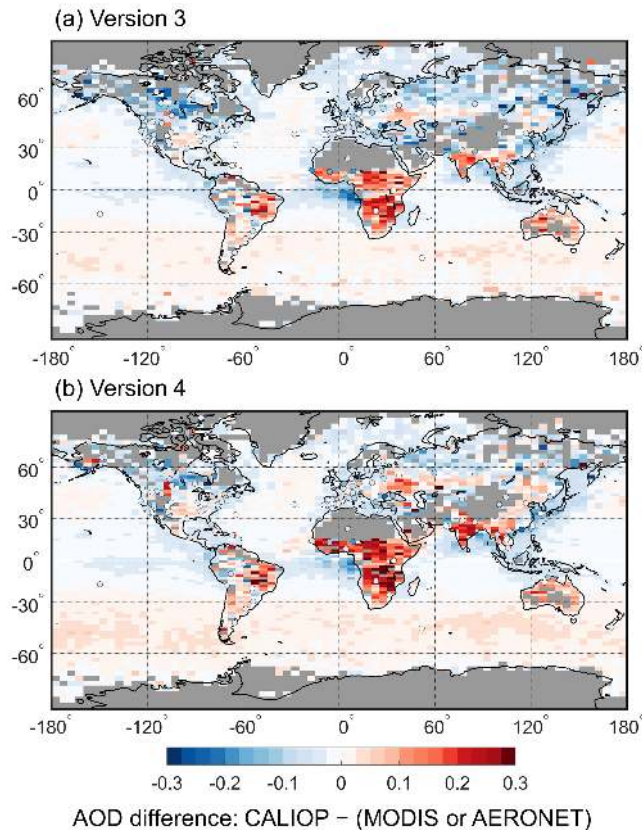


Figure 16. Global maps of mean AOD difference between CALIOP and MODIS. CALIOP data for (a) V3 and (b) V4 and MODIS collection 6 from 2007 to 2009. Mean AOD difference between CALIOP and AERONET is shown in circles.

gional CALIOP – MODIS AOD differences over oceans are generally similar for V3 and V4, except for the southern oceans ($<30^{\circ}$ S), where the V4 AOD differences are slightly larger. Another noticeable difference between the two versions is that the AOD difference is reduced in V4 off the southwest African coast. This is mostly related to aerosol type changes from correcting the classifications of elevated smoke plumes previously misclassified as clean marine over this region in V3 (Sect. 2.3). Over land, AOD differences relative to MODIS typically increase in V4 compared to V3. The increases over tropical and southern Africa are, in part, due to corrections in δ_p^{est} , which were overestimated in V3 (Sect. 2.1.2). These corrections tend to change aerosol subtype classifications to aerosol subtypes with higher lidar ratios (e.g., dust to polluted dust). Differences between CALIOP and MODIS are most noticeable in Africa and South Asia, whereas agreement with AERONET in these regions tends to be much better.

Resolution of the inconsistency between the comparisons with AERONET and MODIS points to the need for further validation studies, especially over land. Since the MODIS over-ocean algorithm is generally more accurate than the over-land algorithm (Levy et al., 2013), AOD differences between CALIOP and MODIS over land are excluded from further consideration in our analyses. Global mean and median AOD differences between CALIOP and AERONET–MODIS for V3 and V4 are shown in Table 8. Both V3 and V4 show that the mean CALIOP AODs are smaller than AERONET and MODIS (ocean), but the mean (median) discrepancies are reduced from -0.064 (-0.052) to -0.051 (-0.045) for AERONET and from -0.010 (-0.012) to -0.006 (-0.008) for MODIS over ocean. The absolute difference in AOD over global oceans between CALIPSO V3 and MODIS collection 6 is smaller compared to previous studies (e.g., Oo and Holz, 2011; Redemann et al., 2012; Kim et al., 2013). These earlier studies used MODIS collection 5, and global AOD for MODIS collection 6 has decreased by 0.02 over ocean compared to collection 5 (Levy et al., 2013).

Figure 17 compares the V3 and V4 CALIOP AOD differences with respect to MODIS over ocean from 2007 to 2009. Points on the black one-to-one line correspond to no AOD change between V3 and V4. Points closer to the x axis ($y = 0$) represent AOD biases that are smaller in V4 compared to V3, while points closer to the y axis ($x = 0$) represent AOD biases that are larger in V4. The linear trend line has a slope of less than 1, which means that the overall AOD bias is reduced in V4 (perfect agreement between V4 and MODIS would yield a slope of zero). AOD biases with respect to MODIS for V3 and V4 have a distribution close to the one-to-one line. The slope of the linear trend is 0.82, indicating a small reduction in the AOD bias from V3 to V4.

5 Summary

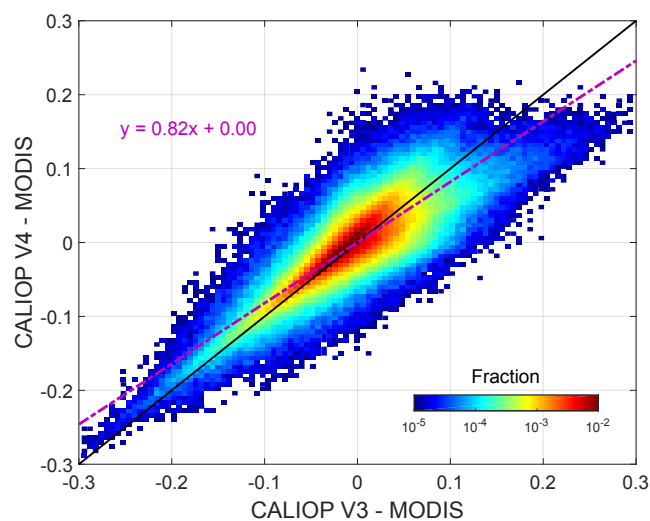
The CALIPSO version 4.10 (V4) lidar level 2 data products were released in November 2016. V4 is the first wholly new set of data products since the initial release of the version 3 (V3) series of products in May 2010. Algorithm updates and data product changes for V4 aerosol subtyping algorithms are discussed in this study. The most significant algorithm updates in V4 are as follows.

All aerosol subtypes are now allowed over snow, ice, and tundra surfaces, whereas only clean continental and polluted continental aerosols were allowed in previous versions.

A new aerosol subtype, dusty marine, has been introduced. The widespread occurrence of layers misclassified as polluted dust over the ocean in previous versions has been rectified, and these layers are now realistically classified as dusty marine.

Table 8. Mean (\pm standard deviation) and median (\pm median absolute deviation) of AOD difference between CALIOP and AERONET–MODIS (defined as CALIOP – AERONET–MODIS) for V3 and V4 from 2007 to 2009.

	CALIOP V3		CALIOP V4		Number of data pairs
	Mean	Median	Mean	Median	
AERONET	-0.064 ± 0.087	-0.052 ± 0.028	-0.051 ± 0.085	-0.045 ± 0.025	736
MODIS (ocean)	-0.010 ± 0.070	-0.012 ± 0.025	-0.006 ± 0.068	-0.008 ± 0.025	911 376
MODIS (land)	0.069 ± 0.195	0.062 ± 0.091	0.121 ± 0.225	0.090 ± 0.098	38 142

**Figure 17.** Distribution of V3 CALIOP AOD differences from MODIS versus the V4 CALIOP AOD differences for data acquired over ocean from 2007 to 2009. The dashed purple line shows the linear regression, with coefficients given in the equation.

The polluted continental and smoke aerosol types in previous versions have been renamed in V4 as “polluted continental/smoke” and “elevated smoke”, respectively.

A new scheme, the Subtype Coalescence Algorithm for AeRosol Fringes (SCAARF), is applied to re-evaluate the aerosol subtype of aerosol layers detected at coarse spatial averaging resolutions below overlying horizontally adjacent layers.

Stratospheric aerosol subtypes have been introduced for ash, sulfate/other, smoke, and polar stratospheric aerosol.

Aerosol lidar ratios have been updated for clean marine, dust, clean continental, and elevated smoke to represent the current state of knowledge for these types.

Feature type and aerosol subtype changes between V3 and V4 are investigated. Tropospheric aerosol occurrence frequency has increased by 18 % in V4 compared to V3, which implies that the V4 algorithm detects more weakly scattering layers that are subsequently classified as aerosols. Moreover, including stratospheric aerosols in V4, aerosol occurrence frequency increases by 31 % relative to V3. As a consequence, the occurrence frequency of most aerosol subtypes

also increases. The sole exceptions are polluted dust and clean continental. Layers previously classified as polluted dust that have base altitudes of less than 2.5 km are now classified as dusty marine in V4. Similarly, the clean continental aerosols that were ubiquitous in the polar regions in the V3 and earlier datasets are now classified as other subtypes in V4.

The CALIOP level 2 mean column-integrated AOD at 532 nm has increased by 0.044 for nighttime and 0.036 for daytime for all-sky conditions in V4 from 2007 to 2009. The most significant reasons for the AOD increase in V4 are changes in lidar ratio, CAD, and layer detection. For cloud-free skies, however, the contribution of CAD and aerosol layer detection is not as pronounced. Initial comparisons of AERONET and MODIS with both versions of CALIOP show that mean AOD differences with AERONET and MODIS (ocean) are reduced in V4 compared to V3. However, the CALIOP AOD estimates remain low relative to MODIS, and this disparity will not be reconciled based solely on future modifications to the CALIOP aerosol typing and lidar ratio selection algorithms. MODIS makes multi-spectral total column measurements from which AOD estimates can be derived but cannot provide height-resolved estimates of extinction. In principal, CALIOP has the capacity to deliver these height-resolved estimates of aerosol extinction coefficients on a global scale. But, to date, CALIOP has limited the retrieval of aerosol optical properties to those regions where the layer detection algorithm and cloud–aerosol discrimination algorithm have positively identified the presence of aerosol in the atmosphere. No attempt is currently being made to retrieve aerosol optical properties in those regions where the aerosol loading lies below the CALIOP detection limits, and hence many of the differences seen between the CALIOP and MODIS estimates of AOD should be expected. Should the CALIOP retrieval strategy change in future data releases, comparisons with MODIS will need to be thoroughly and rigorously re-examined.

Data availability. The following CALIPSO standard data products were used in this study: the CALIPSO 5 km aerosol profile product (Vaughan et al., 2018c; NASA Langley Research Center Atmospheric Science Data Center; https://doi.org/10.5067/CALIPSO/CALIPSO/LID_L2_05kmAPro-Standard-V4-10; last ac-

cess: 26 September 2018); the CALIPSO 5 km aerosol profile product (Vaughan et al., 2018c; NASA Langley Research Center Atmospheric Science Data Center; https://doi.org/10.5067/CALIPSO/CALIPSO/LID_L2_05kmALay-Standard-V4-10; last access: 26 September 2018); and the CALIPSO vertical feature mask product (Vaughan et al., 2018c; NASA Langley Research Center Atmospheric Science Data Center; https://doi.org/10.5067/CALIPSO/CALIPSO/LID_L2_VFM-Standard-V4-10; last access: 26 September 2018). We also used the MODIS Atmosphere L2 Aerosol Product (Levy et al., 2015; NASA MODIS Adaptive Processing System, Goddard Space Flight Center, USA; http://dx.doi.org/10.5067/MODIS/MOD04_L2.006; last access: 26 September 2018).

Competing interests. The authors declare that they have no conflicts of interest. Coauthor Charles R. Trepte is a one of the guest editors for the “CALIPSO version 4 algorithms and data products” special issue in *Atmospheric Measurement Techniques* but did not participate in any aspects of the editorial review of this paper.

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