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THE DESIGN OF AXIAL COMPRESSOR AIRF L3
USING ARBITRARY CHAMBER LINES

George R. Frost, et al

Aerospace Research Laboratories
Wright-Patterson Air Force Base, Ohio

July 1973

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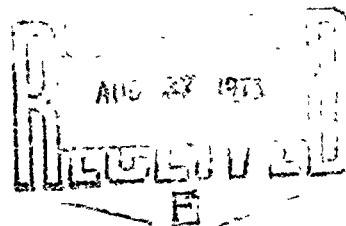
THE DESIGN OF AXIAL COMPRESSOR AIRFOILS USING ARBITRARY CAMBER LINES

GEORGE R. FROST, CAPTAIN, USAF

ARTHUR J. WENNERSTROM

FLUID DYNAMICS FACILITIES RESEARCH LABORATORY

PROJECT 7065



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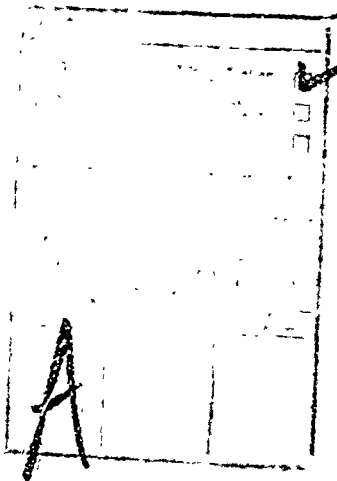
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1. ORIGINATING ACTIVITY (Corporate number) Fluid Dynamics Facilities Research Laboratory Aerospace Research Laboratories (AFSC) Wright-Patterson AFB, Ohio 45433		2a. REPORT SECURITY CLASSIFICATION Unclassified	
		2b. GROUP	
3. REPORT TITLE THE DESIGN OF AXIAL COMPRESSOR AIRFOILS USING ARBITRARY CAMBER LINES			
4. DESCRIPTIVE NOTES (Type of report and inclusive dates) Scientific Final			
5. AUTHOR(S) (First name, middle initial, last name) George R. Frost, Captain USAF Arthur J. Wennerstrom			
6. REPORT DATE July 1973		7a. TOTAL NO. OF PAGES 301 105	7b. NO. OF REFS 2
8a. CONTRACT OR GRANT NO. In-house Research		8b. ORIGINATOR'S REPORT NUMBER(S) ARL 73-0107	
8c. PROJECT NO. 7065-04-09		8d. OTHER REPORT NO. (Any other numbers that may be assigned this report)	
8c.			
10. DISTRIBUTION STATEMENT Approved for public release; distribution unlimited.			
11. SUPPLEMENTARY NOTES TECH OTHER		12. SPONSORING MILITARY ACTIVITY Aerospace Research Laboratories/LF Air Force Systems Command Wright-Patterson AFB, Ohio 45433	
13. ABSTRACT This report describes a technique which has been developed for use in the design of axial compressor airfoils with camber lines of arbitrary shape. The slope of the camber line at several points on a streamsurface is determined from the air angles at these points as well as the incidence and deviation angle distributions for the blade. A camber line is produced by fitting a smooth curve segment through each pair of points from the leading to the trailing edge. A thickness distribution is applied to this camber line to produce the blade element. A computer program which uses this technique to produce blade elements, stack them, and then determine coordinates for plane surfaces through the resultant blade is also described.			

DD FORM 1473
1 NOV 60

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UNCLASSIFIED
Security Classification

IC	KEY WORDS	LINK A		LINK B		LINK C	
		ROLE	WT	ROLE	WT	ROLE	WT
	axial compressor						
	compressor blade						
	airfoil geometry						
	turbine engines						
	turbomachinery						
	gas turbines						

il

ARL 73-0107

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USING ARBITRARY CAMBER LINES**

GEORGE R. FROST, CAPTAIN, USAF

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FLUID DYNAMICS FACILITIES RESEARCH LABORATORY

JULY 1973

PROJECT 7055

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AEROSPACE RESEARCH LABORATORIES
AIR FORCE SYSTEMS COMMAND
UNITED STATES AIR FORCE
WRIGHT-PATTERSON AIR FORCE BASE, OHIO

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FOREWORD

This report was prepared by Captain George R. Frost and Dr. Arthur J. Wennerstrom of the Fluid Dynamics Facilities Research Laboratory, Aerospace Research Laboratories, Wright-Patterson Air Force Base, Ohio.

The report presents results from a portion of the effort of the Fluid Machinery Research Group supervised by Dr. Arthur J. Wennerstrom and was conducted under Work Unit 09 of Project 7065, "Aerospace Simulation Techniques Research" under the overall direction of Mr. Elmer G. Johnson.

ABSTRACT

This report describes a technique which has been developed for use in the design of axial compressor airfoils with camber lines of arbitrary shape. The slope of the camber line at several points on a streamsurface is determined from the air angles at these points as well as the incidence and deviation angle distributions for the blade. A camber line is produced by fitting a smooth curve segment through each pair of points from the leading to the trailing edge. A thickness distribution is applied to this camber line to produce the blade element. A computer program which uses this technique to produce blade elements, stack them, and then determine coordinates for plane surfaces through the resultant blade is also described.

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SECTION I

INTRODUCTION

The traditional approach to the selection of blades for axial-flow compressors has been to choose a specific type of airfoil, subsequently to adjust the parameters defining that airfoil to suit prevailing aerodynamic conditions. Many successful designs have been accomplished in this manner using such blades as NACA 65-series, double circular arc, multiple circular arc, etc. This approach has the virtue of employing airfoil sections about which something is usually known with respect to losses, deviation angle, and operating limits. Reference 1, an earlier publication of this laboratory, is representative of this approach.

A typical contemporary design will be accomplished using a streamline curvature or matrix through-flow analysis incorporating computing stations internal to blade rows as well as at blade edges and in free spaces. Some criterion for optimization of blade shape must be chosen. (The authors of this report choose to achieve a particular shape of static pressure distribution along streamlines.) The spanwise distributions of inlet and outlet relative flow angles, loss coefficients, etc. will have been determined through some preliminary design procedure. A rule for determining deviation angle and distributing it along streamlines will have been selected. Subsequently, the aerodynamic blade design procedure consists of assuming a blade geometry, performing an aerodynamic analysis using specified relative flow angles as input data, and then repeating this procedure as many times as necessary, varying the parameters describing the airfoil sections, until the result of the aerodynamic analysis adequately satisfies the chosen optimization criterion.

There are three principal disadvantages to employing this procedure for the design of transonic and supersonic blade rows. First, the iteration required is time consuming and, to some degree, laborious. Many adjustments to the geometry specified may be required before optimization objectives are met. Although the bulk of the calculations are performed by computer, the designer generally must still examine and evaluate the aerodynamic result and decide what to change, and how much, for the next attempt. Second, when airfoil shape is restricted to any particular class of airfoil, it will rarely be possible to achieve the optimization objectives as closely as might be desired, everywhere along the span. Some compromise will nearly always be necessary. Third, streamline curvature and matrix through-flow analyses sometimes experience difficulty in finding solutions for certain combinations of high relative Mach number and high absolute Mach number near choking when relative flow

angle is specified as input data within blade rows. This is a numerical problem related to the construction of these computer programs and can vary considerably from one program to another.

A design method which eliminates or appreciably reduces these problems consists of specifying total temperature (in rotors) or the product of radius and whirl velocity (in stators) as input data to the aerodynamic analysis program and then fitting airfoils of arbitrary shape to the resulting relative flow angles. In so doing, one loses the data base which might be associated with a particular class of airfoil, but the value of such a geometrically-related data base is questionable for transonic and supersonic sections. Following this approach, the aerodynamic analysis can be optimized with considerably fewer iterations than are usually required with specified geometry. In most cases, optimization objectives can be achieved on nearly every streamsurface. Some interaction is required between the blade design program and the aerodynamic analysis to insure that the blade lean angles and blockages are kept up-to-date. However, the over-all effort required to achieve a satisfactory design using this method has been found to be substantially less.

The principal difficulty in developing a procedure to define arbitrary airfoils consists of arriving at a method which produces aerodynamically attractive shapes which are in addition practical from a structural and manufacturing viewpoint. This report describes one such method developed at the Aerospace Research Laboratories. The method has been incorporated into a computer program which is an extension of the work reported in Reference 1. In addition, to determining the shape of the airfoils on aerodynamic surfaces, section properties are computed, the blade is stacked, and Cartesian coordinates are determined for manufacturing purposes.

The overall design technique is described in Section II. The mathematical details of implementing the technique in a calculation procedure are described in Sections III and IV. A method of producing the optimal camber line on a streamsurface is treated in Section III; the calculations related to other aspects of the blade design procedure are discussed briefly in Section IV. Sections V, VI, and VII present the details of and use of a computer program which incorporates this design technique, currently used at the Aerospace Research Laboratories in the design of axial compressor airfoils.

SECTION II

DESCRIPTION OF THE TECHNIQUE

1. TECHNIQUE OVERVIEW

The technique described in this report uses an iterative procedure to produce an "optimal" camber line on each stream-surface. A thickness distribution is applied to each camber line, and the resulting blade elements are stacked to produce the desired airfoil. The technique requires the designer to specify the incidence distribution radially at the blade leading edge, the location of the stack axis and the stacking offsets of each streamsurface section centroid therefrom, the parameters of the thickness distribution, and the chordwise distribution of deviation angle along the span.

The optimization criterion which has been selected for the section camber line is to maximize the absolute value of the minimum radius of curvature on the camber line. The "optimal" camber line is chosen from a set of camber lines containing the minimum number of inflection points. This original set of camber lines is generated by varying the second derivative at the leading edge.

The starting point of the design technique is output data from an aerodynamic analysis of a particular blade row which has been generated by specifying a parameter other than blade geometry, such as those suggested in the Introduction, across the blade row. This data is in the form of the meridional coordinates of the streamsurfaces and the chordwise distribution of the relative air angles on each streamsurface. The essential steps of the technique itself are described in a qualitative sense in the remainder of this section.

2. DETAILS OF THE TECHNIQUE

The first step of the overall procedure is to determine the optimal blade section on each streamsurface. This in itself is a multiple-step process which incorporates an iteration with solidity to establish a camber line for each of a range of values of the second derivative at the leading edge, a search procedure to choose the "optimal" camber line, and the application of a thickness distribution to this camber line.

The procedure begins with an initial estimate of solidity on the streamsurface. This estimate is made by applying the stagger angle, assumed equal to the average of the inlet and outlet relative air angles, to the meridional chord length, obtained by integrating along each streamline from the assumed

leading to trailing edge, to get a first estimate of the true chord. The solidity is then computed from this estimate, the mean streamsurface radius, and the number of blades in the blade row.

The total deviation angle is computed from this estimate in some fashion, such as the modified Carter's Rule with appropriate constants. The deviation angle at each internal point is next determined as a designer-specified fraction of the total deviation. The required section angle at each internal point and at the trailing edge is then the difference between the relative air angle and the deviation angle, while the section angle at the leading edge is the difference between the relative air angle and the incidence angle.

Each section camber line is determined by fitting a segment of a smooth curve, such as a cubic, between each pair of points from the leading to the trailing edge of the section. The slope at the endpoint of each segment matches the specified section angle there. The true chord length and the associated value of solidity can then be determined. If the solidity differs by more than a prescribed tolerance from the previous estimate, the steps subsequent to and including the total deviation determination are repeated for the revised values of solidity until the desired tolerance is achieved.

The entire procedure described thus far is repeated for a range of values of the second derivative at the leading edge. The resultant set of camber lines are inspected first to focus only on those which contain the minimum number of inflection points, and from these to choose the camber line which is "optimal" in the sense previously described.

A thickness distribution is then applied to this camber line, and the procedure is repeated for each streamsurface. The blade sections are stacked, and the Cartesian coordinates of the resulting blade determined. In addition, the blade blockage and lean angle are computed at each appropriate stream-surface-computing station intersection point.

As a final step, the designer inspects the resulting blockages, Cartesian centroid offsets, blade lean angles, and coincidence of the blade edges with the designated computing stations. If necessary, appropriate changes are made in the inputs to the aerodynamic analysis, and the entire procedure recycled until adequate overall coincidence between the blade design and the aerodynamic analysis is achieved.

SECTION III

THE SECTION CAMBER LINE

The first item required in the application of the technique described in the preceding section is the meridional chord length of the blade element, obtained by integrating along the streamline between the assumed leading and trailing edges. This is accomplished by passing a spline curve through the meridional coordinates (x, r) of the streamsurface. The slope of the streamsurface is calculated (as the slope of the spline-curve) at 100 points distributed uniformly on the x -axis (axially) between the edges of the blade section. The chord length, C_m , is obtained from the equation

$$C_m = \sum_{n=2}^{100} (x_n - x_{n-1}) \sqrt{1 + \left[\left(\frac{dr}{dx_n} + \frac{dr}{dx_{n-1}} \right) / 2 \right]^2} \quad (1)$$

An estimate of true chord is obtained by applying the stagger angle, assumed equal to the average of the inlet and outlet relative air angles, to the meridional chord so that the true chord estimate, C_e , is

$$C_e = \frac{C_m}{\cos\left(\frac{\beta_{le} + \beta_{te}}{2}\right)} \quad (2)$$

The first estimate of solidity may be computed from the equation

$$\sigma = \frac{NC_e}{2\pi\left(\frac{r_{le} + r_{te}}{2}\right)} \quad (3)$$

where N is the number of blades and r_{le} , r_{te} are the radii of the streamsurface at the leading and trailing edges, respectively.

The calculation of the deviation angle, δ , follows the NASA method (Reference 2, Equations 269 and 271) with an additional term, γ .

$$\delta = \delta_{0_{10}} K_{\delta_s} K_{\delta_t} + \frac{m}{\sigma^b} (\beta_{\ell e} - i - \beta_{te} + \delta) + \gamma \quad (4)$$

where $\delta_{0_{10}}$ is the variation from the reference deviation for a 10 percent-thick NACA 65-series thickness distribution

K_{δ_s} is a correction factor for a blade shape with a thickness distribution different from a 65-series blade

K_{δ_t} is a correction factor for a maximum thickness other than 10 percent

m is the slope of the deviation angle variation from reference deviation with camber

b is the solidity exponent (variable with air inlet angle)

β_{xe} is the relative air angle at the particular edge

i is the incidence angle

γ is the arbitrary extra deviation

Solving Eq (4) for δ yields

$$\delta = \frac{\delta_{0_{10}} K_{\delta_s} K_{\delta_t} + \frac{m}{\sigma^b} (\beta_{\ell e} - i - \beta_{te}) + \gamma}{(1 - \frac{m}{\sigma^b})} \quad (5)$$

For use in the calculation procedure, K_{δ_s} , i , and γ are specified by the designer. Several of the other quantities are obtained from known quantities and figures of Reference 2: $\delta_{0_{10}}$ from Figure 161; K_{δ_t} , Figure 172; m , Figure 166; and b , Figure 164.

The blade angle, α , is established at several points across the blade element from the relative air angle, β , modified by the proper consideration of incidence or deviation. At the leading edge,

$$\alpha_{le} = \beta_{le} - i \quad (6)$$

and at the trailing edge,

$$\alpha_{te} = \beta_{te} - \delta \quad (7)$$

At the other points, the blade angles are determined by subtracting a fraction f of the trailing-edge deviation from the relative air angle. At each internal point j ,

$$\alpha_j = \beta_j - f_j \delta \quad (8)$$

The fraction f_j is determined by radial interpolation from the deviation distributions specified by the designer.

The camber line is constructed by fitting a third order polynomial (cubic) through each pair of points from the leading to the trailing edge of the section. Thus, each segment of the camber line is defined by equations of the form

$$y = ax^3 + bx^2 + cx + d \quad (9)$$

$$y' = 3ax^2 + 2bx + c \quad (10)$$

$$y'' = 6ax + 2b \quad (11)$$

As a result, each segment has at most one inflection point ($y'' = 0$) in its useful range, and in most instances has none.

The constants a, b, c, and d for any particular segment can be expressed in terms of the endpoints (denoted by subscripts 1 and 2) of that segment as

$$a = \frac{(y_2' - y_1') - y_1''(x_2 - x_1)}{3[(x_2^2 - x_1^2) - 2x_1(x_2 - x_1)]} \quad (12)$$

$$b = \frac{y_1'' - 6ax_1}{2} \quad (13)$$

$$c = y_1' - 3ax_1^2 - 2bx_1 \quad (14)$$

$$d = y_1 - ax_1^3 - bx_1^2 - cx_1 \quad (15)$$

For simplicity, the leading edge of the camber line is placed at the origin of the coordinate system, resulting in the following boundary conditions for the first segment:

$$\begin{aligned} \text{At } x = 0, y &= 0 \\ y' &= \tan \alpha_{le} \\ y'' &= y_0'' \end{aligned} \quad (16)$$

$$\text{At } x = x_1, y' = \tan \alpha_1 \quad (17)$$

With these boundary conditions, the appropriate values of a, b, c, and d for this segment are completely determined.

The boundary conditions for the second and subsequent segments are specified at one endpoint by equating the first and second derivatives to the values for the preceding segment at the point of juncture; for example, for the second segment,

$$\begin{aligned} \text{At } x = x_1, y &= y_1 \text{ (first segment)} \\ y' &= \tan \alpha_1 \\ y'' &= y_1'' \text{ (first segment)} \end{aligned} \quad (18)$$

and at the other endpoint,

$$\text{At } x = x_2, y' = \tan \alpha_2 \quad (19)$$

From these conditions, a distinct set of constants (a, b, c, d) are computed for the second segment. This same procedure is applied to each pair of points to produce a camber line with continuous first and second derivatives all along its length.

Note that the first segment of the camber line requires the specification of the second derivative y_0'' at the leading edge. This boundary condition affects the constants of the first segment and thus the nature of this entire segment, including the conditions (y_1, y_1'') at the other endpoint. Since the constants for the second segment are established from these conditions, and so on for the rest of the segments, the nature of the entire camber line depends on the value of y_0'' specified at the leading edge.

It has been found convenient to specify y_0'' in terms of a non-dimensional parameter S/R_0 , the ratio of blade spacing, S , to the radius of curvature, R_0 , at the leading edge. R_0 is given by the equation

$$R_0 = \frac{[1 + \tan^2 \alpha_{le}]^{3/2}}{y_0''} \quad (20)$$

and S is obtained from

$$S = \frac{2\pi r_{le}}{N} \quad (21)$$

From Equations (20) and (21),

$$\frac{S}{R_0} = \frac{2\pi r_{le} y_0''}{N [1 + \tan^2 \alpha_{le}]^{3/2}} \quad (22)$$

Solving for y_0'' gives

$$y_0'' = \frac{R \left[1 + \tan^2 \alpha_{le} \right]^{3/2}}{2\pi r_{le}} \cdot \frac{S}{R_0} \quad (23)$$

which indicates that y_0'' is the parameter S/R_0 multiplied by a constant.

For a particular value of S/R_0 , the true chord length of the resulting camber lines may be determined from the endpoint of the final segment as

$$C = \sqrt{(x_{te})^2 + (y_{te})^2} \quad (24)$$

This value is used to compute a revised value of solidity, which is compared to the original estimate. If satisfactory coincidence has not been achieved, a corrected deviation angle is computed from the revised solidity, and the camber line reconstructed. This iteration is repeated until adequate coincidence has been obtained.

It is difficult if not impossible to have an intuitive notion of a "good" value of y_0'' (hence, S/R_0). For some ranges of S/R_0 , each camber line segment may contain an inflection point, while for other ranges, few if any segments may contain such a point. The authors of this report have assumed that, for aerodynamic as well as mechanical reasons, the most desirable airfoil among several matching the same flow angle at each computing station will be one having the minimum number of inflection points between leading and trailing edge. This is accomplished by calculating the camber line for a broad range of values of S/R_0 and isolating the range in which the minimum total number of inflection points occurs. This range is examined with finer S/R_0 increments to generate a new set of camber lines on which the minimum absolute radius of curvature is identified. The value of S/R_0 which produces the largest such radius is then made the mid-value of S/R_0 for the final search pass, using still finer S/R_0 increments. The camber line which possesses the largest value of the minimum radius of curvature at the conclusion of this search procedure is chosen as opt'

SECTION IV

OTHER ASPECTS OF THE CALCULATION PROCEDURE

Various other aspects of the calculation procedure are discussed briefly in this section. For greater detail on these topics, the reader's attention is directed to Reference 1, where these items are treated at some length as elements of the calculation procedure of which the subject procedure is a modification.

1. THE SECTION THICKNESS DISTRIBUTION

The thickness distribution which is applied to the camber line herein described is that referred to as the "Standard Thickness Distribution" in Reference 1. The distribution is defined by two third-order polynomials, one from the leading edge to the point of maximum thickness, and another from there to the trailing edge. At the point of juncture, the thickness and the first and second derivatives of thickness are equated. In order to prevent a reflex curvature from occurring in the thickness distribution near the leading edge, the second derivative of thickness is set equal to zero at the leading edge. The thickness of the leading and trailing edges is independently specified so that it need not be the same at both edges. At the leading edge, the blade surface is completed with a circular arc. At the trailing edge, the blade surface is truncated by connecting the two endpoints with a straight line.

2. CARTESIAN COORDINATES FOR THE BLADE

The preceding material has described the methods used to design individual blade sections. When located as desired relative to the blade stacking axis, the section coordinates are the coordinates of the streamsurface blade section. A series of sections on all streamsurfaces specifies the envelope of the blade, but the surface coordinates are not in a form convenient for manufacturing purposes. The calculation procedure uses a spline-curve to interpolate (or extrapolate) the coordinates of the blade surfaces for manufacturing purposes.

3. SECTION PROPERTIES

The stacking axis of the blade is passed through each streamsurface section either at one of the edges or at a point specified relative to the centroid of the section. Because the streamsurface sections are in general non-planar, the centroids of the manufacturing sections will not generally lie precisely

on the stacking axis when the streamsurface sections are stacked on their centroids. By determining the locations of the centroids of the manufacturing sections so obtained, it is possible to estimate the offsets that must be applied when restacking the streamsurface sections to locate the manufacturing centroids as desired relative to the stacking axis.

To assist further in the mechanical analysis of the blade, the areas, second moments of area, principal axes, and principal second moments of area for both the streamsurface and manufacturing sections are also determined in the calculation procedure.

4. BLADE CHARACTERISTICS

A calculation of the volume enclosed by the blade between the innermost and outermost streamsurfaces is made. In addition, quantities which describe the blade on cylindrical surfaces and which may be required in an aerodynamic analysis of the blade are computed as an option. The calculations are presented here because a typographical error undetected during editing of Reference 1 has impaired their usefulness in that Reference.

First, the angular position of the camber line with respect to the stack axis at a streamsurface-computing station intersection is specified in terms of Φ , defined in Figure 1.

The physical passage blockage (B) due to the presence of the blades is determined as a percentage of the passage circumference in terms of the number of blades in the blade row and τ , the angle subtended on the cylindrical surface by each blade:

$$B = \frac{N\tau}{2\pi} \quad (25)$$

The blade lean angle, ϵ , with respect to the radial direction at a given point is obtained from the slope of a spline-curve fit through the y-z Cartesian coordinates of the streamsurface section camber lines at the particular axial location.

Thus

$$\epsilon = \Phi - \text{Arctan} \left(\frac{dy}{dz} \right) \quad (26)$$

Two other quantities are needed to produce the proper mean-camber line angle on the cylindrical surface: The local computing station inclination, μ , obtained from the specified station description; and the local streamsurface inclination, γ , obtained from the specified x-r streamsurface description. Together with the camber line angle on the streamsurface, α_* , these quantities are employed in the following equation to calculate the proper cylindrical-surface section angle, α_*^o :

$$\tan \alpha_*^o = \frac{\tan \gamma \tan \epsilon + \tan \alpha_*/\cos \gamma}{1 - \tan \mu \tan \gamma} \quad (27)$$

SECTION V
USE OF THE PROGRAM

Basic information required by the user to run the ARL computer program which incorporates the calculation procedure described in this report is given in this section. The various input data items are defined first, and the input data format is then specified. A description of the output data that may be expected is given. (Implementation of the program on a computing system is not discussed here, but in the section entitled "Computer Program Details".)

1. DEFINITION OF INPUT DATA ITEMS

- TITLE An alphanumeric title of 72 characters that may be used to identify a run.
- NLINES The number of streamsurfaces which are defined and on which blade sections will be designed. Must satisfy $2 \leq \text{NLINES} \leq 15$.
- NSTNS The number of computing stations at which the streamsurface radii are specified. Must satisfy $3 \leq \text{NSTNS} \leq 10$.
- NZ The number of constant-z planes on which manufacturing (Cartesian) coordinates for the blade are required. Must satisfy $3 \leq \text{NZ} \leq 15$.
- NSPEC The number of radially-disposed points at which the parameters of the blade sections are specified. Must satisfy $1 \leq \text{NSPEC} \leq 15$.
- ISEGPT The number of points to be used to define each segment of the camber line. $2 \leq \text{ISEGPT} \leq \text{Integer} \left(\frac{80}{|\text{IRTE} - \text{IRLE}|} \right)$
- NBLADE The number of blades in the blade row.
- ISTAK If ISTAK = 0, the blade will be stacked at the leading edge.
- If ISTAK = 1, the blade will be stacked at the trailing edge.
- If ISTAK = 2, the blade will be stacked at, or offset from, the section centroid.

IPUNCH If IPUNCH = 0, the quantities necessary for aerodynamic analysis of the resulting blade are not produced on punched cards.

If IPUNCH = 1, these quantities are produced on punched cards.

IFPLOT Where CALCOMP software is incorporated into the computing system, IFPLOT specifies the creation of precision plots. (Further information regarding the requirements for this are given in the section entitled "Computer Program Details.")

If IFPLOT = 0, no plots will be produced.

If IFPLOT = 1, a plot of the streamsurface sections will be produced. All NLINEs sections are shown superimposed. The origin for each section plot is offset from the centroid of the section by distances specified by DELX and DFLY. If IFPLOT = 2, a plot of the manufacturing sections will be produced. The origin is the blade stacking axis, and all NZ sections are shown superimposed.

If IFPLOT = 3, both of the plots described for IFPLOT = 1 and 2 will be produced.

If IFPLOT = 4, individual plots of each of the manufacturing sections will be produced. The axes are rotated clockwise by the section stagger angle for each plot.

IPRINT The input data is always listed by the program. Details of the streamsurface and manufacturing sections are printed as prescribed by IPRINT.

If IPRINT = 0, details of streamsurface and manufacturing sections are printed.

If IPRINT = 1, details of streamsurface sections are printed.

If IPRINT = 2, details of the manufacturing sections are printed.

**ZINNER,
ZOUTER** The NZ manufacturing sections are equispaced between z equals ZINNER and ZOUTER.

SCALE When precision plots are produced, SCALE is the scale factor employed.

STACKX The axial coordinate of the stacking axis for the blade, relative to the same origin as used for the station locations, XSTA.

PLTSSZ The size (inches) of the plotter to be used in the creation of precision plots.

IRLE The number of the computing station designated as the blade leading edge.

IRTE The number of the computing station designated as the blade trailing edge.

NRADEV The number of radii at which the non-dimensional deviation distribution is specified. $1 \leq \text{NRADEV} \leq 5$.

NINC The number of points which describe the incidence angle distribution. $1 \leq \text{NINC} \leq 15$.

NSIGN An integer which specifies the sign convention of the particular blade. Conventionally positive rotors and stators have NSIGN values of -1 and +1, respectively.

IFCA If IFCA = 1, the factor m in the deviation angle rule is that of the NACA-65-series mean line (Figure 195, Reference 2).
If IFCA = 2, the factor m in the deviation angle rule is that of the circular-arc mean line.

IPASS The number of initial values of S/R_0 which are to be used in the procedure to find the optimal camber line. $20 \leq \text{IPASS} \leq 50$.

XKSHPE The shape factor (K_{δ_s}) in the deviation equation.

SOLTOL The solidity tolerance used in the iterative procedure to produce a consistent camber line.

NPTS The number of points defining a particular chord-wise deviation distribution. $1 \leq \text{NPTS} \leq 10$.

RADEV Radius at which a particular deviation distribution applies.

SM An array of NPTS meridional chord fractions which, together with DEVCRV, specify a particular deviation distribution.

DEVCRV An array of NPTS normalized deviation fractions which, together with SM, specify a particular deviation distribution.

RINC An array of NINC radii which, together with XINC, specify the incidence distribution at the leading edge.

XINC An array of NINC incidence angles which, together with RINC, specify the incidence distribution. Input positive for conventionally positive rotors and stators (see NSIGN).

DELDEV An array of NINC angles which, together with RINC, specify the distribution of the "arbitrary extra deviation" term in the deviation determination. Input positive for conventionally positive rotors and stators (see NSIGN).

KPTS The number of points provided to specify the shape of a computing station.

 If KPTS = 1, the computing station is upright and linear.

 If KPTS = 2, the computing station is linear and either upright or inclined.

 If KPTS > 2, a spline curve is fitted through the points provided to specify the shape of the station.

IFANGS If IFANGS = 0, the calculations of the quantities required for aerodynamic analysis will be omitted at a particular computing station.

 If IFANGS = 1, these calculations will be performed at that station.

XSTA An array of KPTS axial coordinates (relative to an arbitrary origin) which, together with RSTA, specify the shape of a particular computing station.

RSTA An array of KPTS radii which, together with XSTA, specify the shape of a particular computing station.

R The streamsurface radii at N LINES locations at each of the NSTNS stations.

AIRANG The relative air angles at N LINES locations at each of the NSTNS stations.

ZR The variation of properties of the streamsurface blade sections is specified as a function of streamsurface number. The various quantities are then interpolated (or extrapolated) at each streamsurface. The streamsurfaces are numbered consecutively from the innermost outward, starting with 1.0. ZR must increase monotonically, there being NSPEC values in all.

YA The fraction of meridional chord used as the leading edge in the calculation of the section chord for the solidity iteration on a particular streamsurface. If $YA = 0.$, the true chord length is calculated. $0.0 \leq YA \leq 1.0.$

YB The increment in S/R_0 which, with SDIVR and IPASS, establishes the initial range of S/R_0 which is inspected in the determination of the optimal camber line on a particular streamsurface. May be positive or negative.

YC If $YC = 0.$, the radius of curvature at the leading edge of each camber line will be considered in the procedure to identify the camber line which maximizes the minimum radius of curvature.

If $YC = 1.0$, the radius of curvature at the leading edge will not be considered in this procedure.

YE The maximum number of inflection points expected on a particular camber line. If the calculated minimum number is greater than YE, an informational diagnostic is printed.

RLE The ratio of section leading edge radius to chord.

TC The ratio of section maximum thickness to chord.

TE The ratio of section trailing edge half-thickness to chord.

Z The location of the section maximum thickness, as a fraction of camber line length.

SDIVR The initial value of S/R_0 .

DELX,
DELY The stacking axis passes through the streamsurface blade sections, offset from the centroid, leading, or trailing edge by DELX and DELY in the x and y directions, respectively.

2. INPUT DATA FORMAT

Data input is by punched card, and three formats are used. The first card only is alphanumeric, using the first 72 columns of the card. Integers are placed in three-column fields, which start with Column 1. No decimal points are used, and the integer should be right-justified. Real numbers are placed in 12-column fields, which also start with Column 1. Decimal points should be included, and the numbers may be placed anywhere in the field.

In the following chart, one line corresponds to one card.

TITLE

NLINES NSTNS NZ NSPEC ISEGPT NBLADE ISTAK IPUNCH IFPLOT IPRINT

ZINNER ZOUTER SCALE STACKX PLTSZE

IRLE IRTE NRADEV NINC NSIGN IFCA IPASS

XKSHPE SOLTOL

NPTS

RADEV

SM DEVCRV } repeated NPTS times

} repeated NRADEV times

RINC XINC DELDEV } repeated NINC times

KPTS IFANGS

XSTA RSTA } repeated KPTS times

} repeated NSTNS times

R AIRANG } repeated NLINES times

ZR YA YB YC YE RLE

TC TE Z SDIVR DELX DELY

} repeated NSPEC times

Listing of a sample input data deck is included under "Example of Use of the Program."

3. OUTPUT DATA

Printed output from the program may be considered to consist of four sections: a printout of the input data, details of the camber line and blade section on each streamsurface, a

listing of quantities required for aerodynamic analysis, and details of the manufacturing sections determined on the constant-z planes. These are briefly described below.

The input data printout includes all quantities read in, and is self-explanatory.

Details of the streamsurface blade sections are printed if IPRINT = 0 or 1. Listed first are the results of the investigations of the S/R_0 parameter. The initial table presents the results of the first iteration which is used to identify the range of S/R_0 in which the minimum number of inflection points occur on the camber line. This range is in turn investigated with finer increments of S/R_0 to determine the maximum value of the minimum radius of curvature. Then follow the details of the optimal camber line which has been identified by a third investigation of S/R_0 with still finer parameter increments. These details include the deviation and solidity which have been calculated for this optimal S/R_0 , and a description of the camber line in terms of coordinates, first and second derivatives, and the radii of curvature. Listed next are the parameters defining the blade section, some of which are computed and some of which are interpolated at the stream-surface from the tables read in. Then follow details of the blade section in "normalized" form. The blade section geometry is given for the particular section, except that the meridional projection of the chord is unity. For this section of the output, the coordinate origin is the blade leading edge. The following quantities are given: blade chord, stagger angle, camber angle, section area, location of centroid of the section, second moments of area of the section about the centroid, orientation of the principal axes, and the principal second moments of area of the section about the centroid. Then are listed the coordinates of the camber line, the camber line angle, the section thickness, and the coordinates of the blade surfaces. A line-printer plot of the normalized section follows. The scales for the plot are arranged so that the section just fills the page. Thus, the scales will generally differ from one plot to another. "Dimensional" details of the blade section are given next. The normalized data given previously is scaled to give the proper blade section. For this section of the output, the coordinates are with respect to the blade stacking axis. The following quantities are given: blade chord, radius and location of center of the leading edge, section area, the second moments of area of the section about the centroid, and the principal second moments of area of the section about the centroid. The coordinates of points on the blade surfaces are then listed, followed by the coordinates of 31 points distributed at six degree intervals around the leading edge. Finally, the coordinates of the blade surfaces and points around the leading edge are shown in Cartesian form.

The quantities required for aerodynamic analysis are printed at all computing stations specified by the IFANGS parameter. The radius, section angle, blade lean angle, blade blockage, and relative angular location of the camber line are printed at each streamsurface intersection with the particular computing station.

Details of the manufacturing sections are printed if IPRINT = 0 or 2. At each value of z specified by ZINNER, ZOUTER and NZ, section properties and coordinates are given. The origin for the coordinates is the blade stacking axis. The following quantities are given: section area, the location of the centroid of the section, the second moments of area of the section about the centroid, the principal second moments of area of the section about the centroid, the orientation of the principal axes, and the section torsional constant. Then the coordinates of points on the blade section surfaces are listed, followed by 31 points around the leading edge.

Precision plots are produced if IFPLOT = 1, 2, 3 or 4 as described under the definition of IFPLOT given previously.

If IPUNCH = 1, the program punches the quantities required for aerodynamic analysis, together with identifying indices denoting station number and streamsurface number, on cards in the following format: 5 fields each of 12 locations for the quantities themselves, followed by 2 fields each of 3 locations for the indices.

SECTION VI

EXAMPLE OF USE OF THE PROGRAM

This section shows the use of the program to generate a compressor rotor with an inlet hub-to-tip ratio of 0.31, a rather steep hub ramp angle (32.5°), and a constant outer radius. The blade is defined by six computing stations, one at either edge and four internal. This results in a camber line composed of five segments. Six streamlines have been used to define the flow and hence the blade by means of the streamsurface blade sections. The computing-stations and streamsurfaces which define the blade are depicted in a stack-axis projection in Figure 2.

1. INPUT DATA

The input data deck used for this example is listed below. Some points of interest are noted in the order in which they occur in the input.

As mentioned above, six streamsurface blade sections are used to define the blade. The streamsurface radii are specified at eight computing stations, the first and last of which are outside of the rotor. This ensures that the boundary conditions imposed on the spline-curve (zero curvature at the endpoints) have little influence on the shape of the curve representing the streamsurface within the blade. The useful relative air angles are specified at the six computing stations defining the blade. The computing stations within the blade are curved in an attempt to make the meridional projections of the camber line segments approximately equal. The parameters which define the streamsurface blade sections are given at six locations; that is, at every streamsurface. Twelve points are used to define each segment, which results in a camber line defined by a total of fifty-six points. (This number serves the purposes of this example well, but it would be advantageous to use more points if the precision-plot output is to be incorporated directly in the manufacturing procedure.) There are twenty blades in the particular blade row, stacked approximately on their stream-surface centroids. No punched output is requested. All optional sections of the printed output are to be printed, and superimposed section plots are to be produced on a plotter (with an 11-inch useful range) at two and one-half times full size.

Stations 2 and 7 are the leading and trailing edges of the blade, respectively. The deviation distribution is the same at all radii, since it is specified only at one radius. The incidence angles and the arbitrary extra deviation are specified

at six points for this rotor blade. The factor n in the deviation calculation is to be that of a circular-arc camber line. Thirty camber lines will initially be investigated in the effort to identify the optimal camber line, representing a broad range of the S/R_0 parameter. The shape factor in the deviation calculation is unity, and the tolerance on solidity in the iteration for each camber line is 0.005.

The streamsurface radii and relative air angles have been determined from an aerodynamic analysis of the flow through the blade row. The leading edge of the blade has been established as the point from which the chord length, and thus the solidity, will be computed.

The increment in the S/R_0 parameter has been initially set equal to + 0.04 in the investigation to find the optimal camber line. This increment will automatically be reduced twice subsequently as the most favorable range of S/R_0 is more closely scrutinized. It is anticipated that no inflection points will be required near the hub, while a single inflection point will probably be required in the mid and tip regions of the blade. The blade thickness distribution is determined by aerodynamic and mechanical factors. The leading edge radius and trailing edge half-thickness are set to approximately 0.005 inch, probably a practical minimum. Maximum thickness/chord ratios vary from 6 percent at the hub to 2.5 percent at the casing. The maximum thickness is placed in the rearward portion of the camber line, which helps to maintain a small leading edge wedge angle.

EXAMPLE - LCH HUE/TIF RATIO COMPRESSOR RCTCR DESIGN

6	8	7	6	12	20	2	0	3	0		
2.5				8.50				2.5		-7.05	11.0
2	7	1	6	-1	2	30					
1.				.005							
6											
3.3											
0.				.1							
0.2				.11							
0.4				.15							
.6				.22							
.8				.36							
1.				1.00							
2.68				6.37				2.			
3.84				5.57				2.			
5.09				4.85				2.			
6.42				4.2				2.			
7.79				3.92				2.			
8.5				3.69				2.			
1	0										
-9.				2.35							
2.35											
3.6454											
4.9893											
6.3817											
7.7723											
8.5											
5	0										
-8.51				2.6514							
-8.5926				5.0683							
-8.531				6.3989							
-8.3115				7.7861							
-8.161				8.5							
				2.6514				-40.9695			
				3.8041				-47.2370			
				5.0786				-50.8039			
				6.4109				-53.6378			
				7.7902				-57.2964			
				8.5000				-59.7859			
4	1										
-7.905				3.0363							
-8.000				5.07							
-7.96				6.48							
-7.725				8.5							
				3.0383				-30.0198			
				4.0696				-37.2906			
				5.2456				-44.5116			
				6.4975				-51.0404			
				7.8091				-57.8178			
				8.5000				-61.3719			

4 1		
-7.35	3.3893	
-7.395	5.385	
-7.415	6.565	
-7.511	8.5	
	3.3893	-20.0393
	4.3344	-28.9282
	5.4154	-38.6681
	6.5824	-47.7054
	7.8307	-56.2706
	8.5000	-60.2293

4 1		
-6.801	3.7385	
-6.801	5.49	
-6.87	6.65	
-6.94	8.5	
	3.7385	-12.2698
	4.5798	-21.2618
	5.5662	-33.3334
	6.6591	-44.2126
	7.8459	-54.0832
	8.5000	-58.9884

4 1		
-6.251	4.0884	
-6.18	5.7	
-6.3	6.725	
-6.56	8.5	
	4.0884	-5.4451
	4.8259	-13.8107
	5.7147	-27.6798
	6.7242	-40.6566
	7.8575	-51.6465
	8.5000	-57.5196

5 1		
-5.665	4.4612	
-5.5846	5.896	
-5.7208	6.7945	
-5.9516	7.8661	
-6.134	8.5	
	4.4612	11.5881
	5.0795	-7.0980
	5.8623	-25.6222
	6.7858	-40.0751
	7.8716	-51.3351
	8.5000	-56.5798

4 0		
-5.52	4.5534	
-5.35	5.2	
-5.3	5.80	
-5.7	8.5	

4.5534
 5.1806
 5.9412
 6.8278
 7.8877
 8.5

1.0	0.	0.04	0.	0.	.00155
.66	.00155	.56	-0.2	.01	
2.0	0.	.04	0.	0.	.00149
.0525	.00149	.59	-0.15	-.018	
3.0	0.	.04	0.	1.	.00143
.0423	.00143	.62	-0.3	.035	
4.	0.0	.64	0.0	1.0	.00137
.6325	.00137	.65	-1.3	.02	
5.0	0.0	.04	0.	1.0	.00131
.0265	.00131	.68	-2.0	.01	
6.	0.	0.04	0.	1.0	.00125
.025	.00125	.70	-2.3	-.001	

2. OUTPUT DATA

The input data specified all optional output data, and a sample of each segment of the output is presented in this section. A brief description of some aspects of the output is presented below.

Shown first is the printout of the input data. This is followed by details of the first streamsurface blade section. The tables presenting the results of the S/R_0 investigations are followed by a description of the camber line which has been selected. Then appear the details of, and a line-printer plot of, the normalized blade section, followed by the specifications of the section scaled to the proper dimensions. Printed first are the 56 points specified for each blade surface. Next appear the 31 points describing the leading edge radius. The final data for the streamsurface section are the equivalent Cartesian coordinates for these same points.

The format is repeated for each of the remaining streamsurface blade sections, but these results are not reproduced here. Subsequent to the streamsurface data are printed the quantities required for aerodynamic analysis at those stations where requested by the IFANGS parameter.

Details for the seven manufacturing sections defining the blade follow. Reproduced below is the output relating to the first (innermost) section. Properties of the section are followed by coordinates of 56 points on each surface and 31 points around the leading edge. It will be noted that the section centroid is not calculated to be exactly on the stacking axis. If it were desired to have the centroids of the manufacturing sections lie more nearly precisely on the stacking axis, the program would be rerun with either DELX and DELY offsets specified so that they would counteract the mislocation of the centroids previously determined, or with a slightly shifted location of the stack axis. However, the user must bear in mind that the final step in the design procedure is to obtain satisfactory coincidence of the blade with the stations defining its leading and trailing edges in the meridional plane. It is possible that a blade which had all manufacturing sections stacked precisely on their centroids at a particular stacking-axis location would have quite an undesirable meridional profile. There are tradeoffs, then, between the stacking preciseness and the coincidence of the calculated blade's edges with its assumed profile on the one hand, and the number of iterations it would require to find the truly optimal stack location and centroid offsets, on the other.

The input data specified superimposed precision plots of both the streamsurface sections and the manufacturing sections. These plots are reproduced (at reduced size) as Figures 3 and 4,

respectively. It is of interest to refer also to Figure 2. The innermost manufacturing plane is well below the lowest point on the hub streamsurface section in the plane of the stacking axis. The Cartesian coordinates of this streamsurface section show that the lowest point on the section (the 14th point on the leading edge) is at $Z = 2.57224$. The streamsurface radius at this point is 2.6514, and the innermost manufacturing plane is at $Z = 2.5$. Thus, at the leading edge, the extrapolation required to define the manufacturing section is somewhat smaller than might first appear. At the trailing edge, extrapolation is required for the first three manufacturing sections. The streamsurface radius at the casing and the Z-coordinate for the outermost manufacturing plane both equal 8.5; however, the Z-coordinates of the blade section are all actually below 8.5. Thus, the outermost section too is defined completely by extrapolation. Of course, portions of the blade that are defined by extrapolation do not appear on the final blade, but facilitate manufacture.

USAF -- ARL(LE) ARBITRARY CAMBER LINE PROGRAM

EXAMPLE -- LOW HUB/TIP RATIO COMPRESSOR ROTOR DESIGN

TITLE =
 NUMBER OF STREAMSURFACES = 6
 NUMBER OF STATIONS = 8
 NUMBER OF CONSTANT-Z PLANES = 7
 NUMBER OF BLADE DATA POINTS = 6
 NUMBER OF PCINTS PER SEGMENT = 12
 NUMBER OF BLADES IN BLADE ROW = 20
 ISTAK = 2
 IPUNCH = 0
 IFPLOT = 3
 IPRINT = 0
 ZINNER = 2.5000
 ZOUTER = 8.5000
 SCALE = 2.5000
 STACKX = -7.0500
 PLTSE = 11.0000

LEADING EDGE STATION NUMBER = 2
 TRAILING EDGE STATION NUMBER = 7
 RADII SPECIFYING DEVIATION = 1
 RADII SPECIFYING INCIDENCE = 6
 SENSE OF ROTATION INDICATOR = -1
 DEVIATION CALCULATION INDEX = 2
 NUMBER OF INITIAL S/R TRIALS = 30

SHAPE FACTOR = 1.0000
 SOLICITY TOLERANCE = .0050

DEVIATION CURVE 1 NUMBER OF POINTS = 6 RADIUS = 3.3000

POINT	NCRMALIZED MERIODIONAL CHCRC	NORMALIZED DEVIATION DISTRIBUTION
1	0.0000	.1000
2	.2000	.1100
3	.4000	.1500
4	.6000	.2200
5	.8000	.3000
6	1.0000	1.0000

INCIDENCE AND EXTRA DEVIATION DISTRIBUTION

INLET RADIUS	INCIDENCE	EXTRA DEVIATION
2.6800	6.370	2.000
3.8400	5.570	2.000
5.0900	4.850	2.000
6.4200	4.200	2.000
7.7900	3.920	2.000
8.5000	3.690	2.000

STREAMSURFACE GEOMETRY SPECIFICATION

COMPUTING STATION 1 NUMBER OF DESCRIBING POINTS= 2 IFANGS(1)= 0

DESCRIPTION X	R	STREAMLINE NUMBER	RADII	AIR ANGLE
-9.0900	2.3500	1	2.3500	-0.0000
-9.0900	3.3500	2	3.6454	-0.0000
		3	4.9893	-0.0000
		4	6.3617	-0.0000
		5	7.7723	-0.0000
		6	8.5100	-0.0000

COMPUTING STATION 2 NUMBER OF DESCRIBING POINTS= 5 IFANGS(2)= 0

DESCRIPTION X	R	STREAMLINE NUMBER	RADII	AIR ANGLE
-8.5100	2.6514	1	2.6514	-40.9855
-0.5926	5.0663	2	3.8041	-47.2370
-8.5310	6.3989	3	5.0706	-50.8039
-8.3115	7.7861	4	6.4109	-53.6370
-8.1610	8.5000	5	7.7502	-57.2964
		6	8.5000	-59.7859

COMPUTING STATION 3 NUMBER OF DESCRIBING POINTS= 4 IFANGS(3)= 1

DESCRIPTION X	R	STREAMLINE NUMBER	RADII	AIR ANGLE
-7.9050	3.0363	1	3.0363	-30.0198
-8.0000	5.0700	2	4.0696	-37.2906
-7.9600	6.4800	3	5.2456	-44.5116
-7.7250	8.5000	4	6.4575	-51.0404
		5	7.8091	-57.8178
		6	8.5000	-61.3719

COMPUTING STATION 4 NUMBER OF DESCRIBING POINTS= 4 IFANGS(4)= 1

DESCRIPTION X	R	STREAMLINE NUMBER	RADII	AIR ANGLE
-7.3500	3.3893	1	3.3893	-20.0393
-7.3950	5.3850	2	4.3244	-28.9282
-7.4150	6.5650	3	5.4154	-38.6681
-7.3110	8.5000	4	6.5824	-47.7054
		5	7.8207	-56.2706
		6	8.5100	-60.2253

COMPUTING STATION 5 NUMBER OF DESCRIBING POINTS= 4 IFANGS (5) = 1

DESCRIPTION X	R	STREAMLINE NUMBER	RADII	AIR ANGLE
-6.0910	3.7385	1	3.7385	-12.2650
-6.8010	5.4900	2	4.5798	-21.2618
-6.8700	6.6500	3	5.5662	-33.3334
-6.9400	8.5000	4	6.6591	-44.2126
		5	7.8459	-54.0832
		6	8.5100	-56.5884

COMPUTING STATION 6 NUMBER OF DESCRIBING POINTS= 4 IFANGS (6) = 1

DESCRIPTION X	R	STREAMLINE NUMBER	RADII	AIR ANGLE
-6.2510	4.0884	1	4.0884	-5.4451
-6.1800	5.7000	2	4.8259	-13.8107
-6.3000	6.7250	3	5.7147	-27.6750
-6.5600	8.5000	4	6.7242	-40.6966
		5	7.8275	-51.6465
		6	8.5100	-57.5156

COMPUTING STATION 7 NUMBER OF DESCRIBING POINTS= 5 IFANGS (7) = 1

DESCRIPTION X	R	STREAMLINE NUMBER	RADII	AIR ANGLE
-5.6650	4.4612	1	4.4612	11.5881
-5.5846	5.0560	2	5.0795	-7.0960
-5.7208	6.7945	3	5.8623	-25.6222
-5.9516	7.8661	4	6.7250	-40.0751
-6.1340	8.5000	5	7.8216	-51.3351
		6	8.5100	-56.5750

COMPUTING STATION 8 NUMBER OF DESCRIBING POINTS= 4 IFANGS (8) = 0

DESCRIPTION X	R	STREAMLINE NUMBER	RADII	AIR ANGLE
-5.5200	4.5534	1	4.5534	-0.0000
-5.3500	5.2000	2	5.1806	-0.0000
-5.3000	5.8000	3	5.9412	-0.0000
-5.7000	8.5000	4	6.8378	-0.0000
		5	7.8677	-0.0000
		6	8.5000	-0.0000

SECTION GEOMETRY SPECIFICATION

STREAMLINE NUMBER	SLD CL FT	INCEL S/R	CONSID LL MC CRV	NC.ALC INFL. FTS	LE RADIUS /CHCRC	MAX THICK /CHCRC	TE THICK /2*CHCRC	PCINT CF START VAL OF SVR	X STACK CFFSET	Y STACK CFFSET
1.00	0.000	.040	0.000	0.000	.00151	.06000	.00155	-.2000	.01000	-0.000000
2.00	0.000	.040	0.000	0.000	.00149	.05250	.00149	-.1500	-.01000	-0.000000
3.00	0.000	.040	0.000	1.000	.00142	.04230	.00143	-.3000	.035000	-0.000000
4.00	0.000	.040	0.000	1.000	.00137	.03250	.00137	-1.3000	.020000	-0.000000
5.00	0.000	.040	0.000	1.000	.00131	.02650	.00131	-2.0000	.010000	-0.000000
6.00	0.000	.040	0.000	1.000	.00125	.02500	.00125	-2.3000	-.001000	-0.000000

STREAMSURFACE 1
 ITERATION 1

INITIAL S/R = -.2000

INCREMENTAL S/R = .0400

PASS NC.	NC. OF INFLECTION PTS	MIN. RADIUS OF CURVATURE
1	1	.340
2	1	.348
3	1	.357
4	1	.367
5	1	.376
6	1	.387
7	0	.398
8	0	.409
9	0	.421
10	0	.434
11	0	.448
12	0	.463
13	0	.477
14	2	.492
15	2	.505
16	2	.517
17	2	.522
18	2	.521
19	2	.511
20	2	.492
21	4	.472
22	4	.454
23	4	.437
24	4	.421
25	4	.406
26	4	.393
27	4	.380
28	4	.368
29	4	.357
30	4	.346

STREAMSURFACE 1
 ITERATION 2

INITIAL S/R = 0.0000 INCREMENTAL S/R = .0110
 PASS NO. NO. OF INFLECTION PTS MIN. RADIUS OF CURVATURE

1	1	.387
2	0	.350
3	0	.393
4	0	.396
5	0	.399
6	0	.402
7	0	.405
8	0	.408
9	0	.412
10	0	.415
11	0	.418
12	0	.422
13	0	.425
14	0	.429
15	0	.433
16	0	.436
17	0	.440
18	0	.444
19	0	.448
20	0	.452
21	0	.456
22	0	.460
23	0	.464
24	0	.468
25	0	.472
26	0	.476
27	0	.480
28	0	.484
29	2	.488
30	2	.492

THE MAXIMUM VALUE OF THE MINIMUM RADIUS OF CURVATURE OCCURS AT AN END POINT OF THE PRESENT S/R RANGE

OPTIPAL SECTION

FINAL S/R = .3025

ITERATIONS ON SOLIDITY

ITERATION 1
ITERATION 2

DEVIATION = 8.666 SOLICITY = 3.1200
DEVIATION = 8.666 SOLICITY = 3.1211

PCINT	NORMALIZED MERIDIONAL COORDINATE	TANGENTIAL COORDINATE	CAMBER LINE SLOPE	SECOND DERIVATIVE	RADIAL CURVATURE
1	0.0000	0.0000	-.6953	.6506	2.754
2	.0193	-.0132	-.6768	.6466	2.723
3	.0387	-.0262	-.6643	.6427	2.692
4	.0580	-.0389	-.6518	.6388	2.663
5	.0773	-.0514	-.6393	.6349	2.633
6	.0967	-.0636	-.6274	.6309	2.607
7	.1160	-.0756	-.6152	.6270	2.581
8	.1353	-.0874	-.6031	.6231	2.556
9	.1547	-.0990	-.5911	.6192	2.532
10	.1740	-.1103	-.5792	.6152	2.508
11	.1933	-.1213	-.5673	.6113	2.486
12	.2127	-.1322	-.5556	.6074	2.465
13	.2304	-.1420	-.5440	.6039	2.445
14	.2481	-.1515	-.5328	.6009	2.426
15	.2659	-.1608	-.5219	.6021	2.408
16	.2836	-.1698	-.5113	.6036	2.391
17	.3013	-.1785	-.5010	.6052	2.375
18	.3191	-.1868	-.4910	.6068	2.360
19	.3368	-.1948	-.4814	.6084	2.345
20	.3545	-.2025	-.4714	.6100	2.331
21	.3723	-.2096	-.4617	.6116	2.317
22	.3900	-.2164	-.4523	.6132	2.304
23	.4077	-.2226	-.4431	.6148	2.291
24	.4253	-.2283	-.4341	.6164	2.279
25	.4428	-.2336	-.4254	.6180	2.267
26	.4604	-.2384	-.4170	.6196	2.255
27	.4779	-.2429	-.4088	.6212	2.244
28	.4954	-.2471	-.4009	.6228	2.233
29	.5130	-.2510	-.3933	.6244	2.222
30	.5305	-.2546	-.3860	.6260	2.211
31	.5481	-.2581	-.3790	.6276	2.200
32	.5656	-.2615	-.3722	.6292	2.190
33	.5832	-.2647	-.3656	.6308	2.180
34	.6007	-.2680	-.3592	.6324	2.170
35	.6183	-.2712	-.3530	.6340	2.160
36	.6358	-.2743	-.3470	.6356	2.150
37	.6534	-.2774	-.3412	.6372	2.140
38	.6710	-.2804	-.3356	.6388	2.130
39	.6886	-.2832	-.3302	.6404	2.120
40	.7061	-.2857	-.3250	.6420	2.110
41	.7237	-.2881	-.3200	.6436	2.100
42	.7413	-.2901	-.3152	.6452	2.090
43	.7589	-.2918	-.3106	.6468	2.080
44	.7764	-.2931	-.3062	.6484	2.070
45	.7940	-.2940	-.3020	.6500	2.060
46	.8127	-.2945	-.2980	.6516	2.050
47	.8315	-.2944	-.2942	.6532	2.040
48	.8502	-.2938	-.2907	.6548	2.030

49
50
51
52
53
54
55
56

.8689
.8876
.9064
.9251
.9438
.9625
.9813
1.0000

--.2925
--.2906
--.2880
--.2846
--.2806
--.2757
--.2701
--.2636

.0854
.1208
.1579
.1967
.2373
.2795
.3234
.3690

1.8460
1.9368
2.0275
2.1183
2.2091
2.2998
2.3906
2.4814

.548
.528
.512
.500
.491
.487
.486
.480

STREAMSURFACE GEOMETRY ON STREAMLINE NUMBER 1

BETA1 = -34.579 (BLADE INLET ANGLE.)
 BETA2 = 20.254 (BLADE OUTLET ANGLE.)
 YZERO = .00155 (BLADE LEADING EDGE RADIUS AS A FRACTION OF CHORD.)
 T = .06000 (BLADE MAXIMUM THICKNESS AS A FRACTION OF CHORD.)
 YCHE = .00155 (BLADE TRAILING EDGE HALF-THICKNESS AS A FRACTION OF CHORD.)
 Z = .5600 (LOCATION OF MAXIMUM THICKNESS AS A FRACTION OF MEAN LINE.)
 GCRC = 3.3719 (MERIDIONAL CHORD OF SECTION.)

NORMALISED RESULTS - ALL THE FOLLOWING REFER TO ABLADE HAVING A MERIDIONAL CHORD PROJECTION OF UNITY

BLADE CHORD = 1.0335
 STAGGER ANGLE = -14.745
 CAMBER ANGLE = -54.633
 SECTION AREA = .04394

LOCATION OF CENTROID RELATIVE TO LEADING EDGE

XBAR = .50573
 YBAR = -.22597

SECOND MOMENTS OF AREA ABOUT CENTROID

IX = .00021
 IY = .00233
 IXY = -.00063

ANGLE OF INCLINATION OF (CNE) PRINCIPAL AXIS TO 'X' AXIS = -15.355

PRINCIPAL SECOND MOMENTS OF AREA ABOUT CENTROID

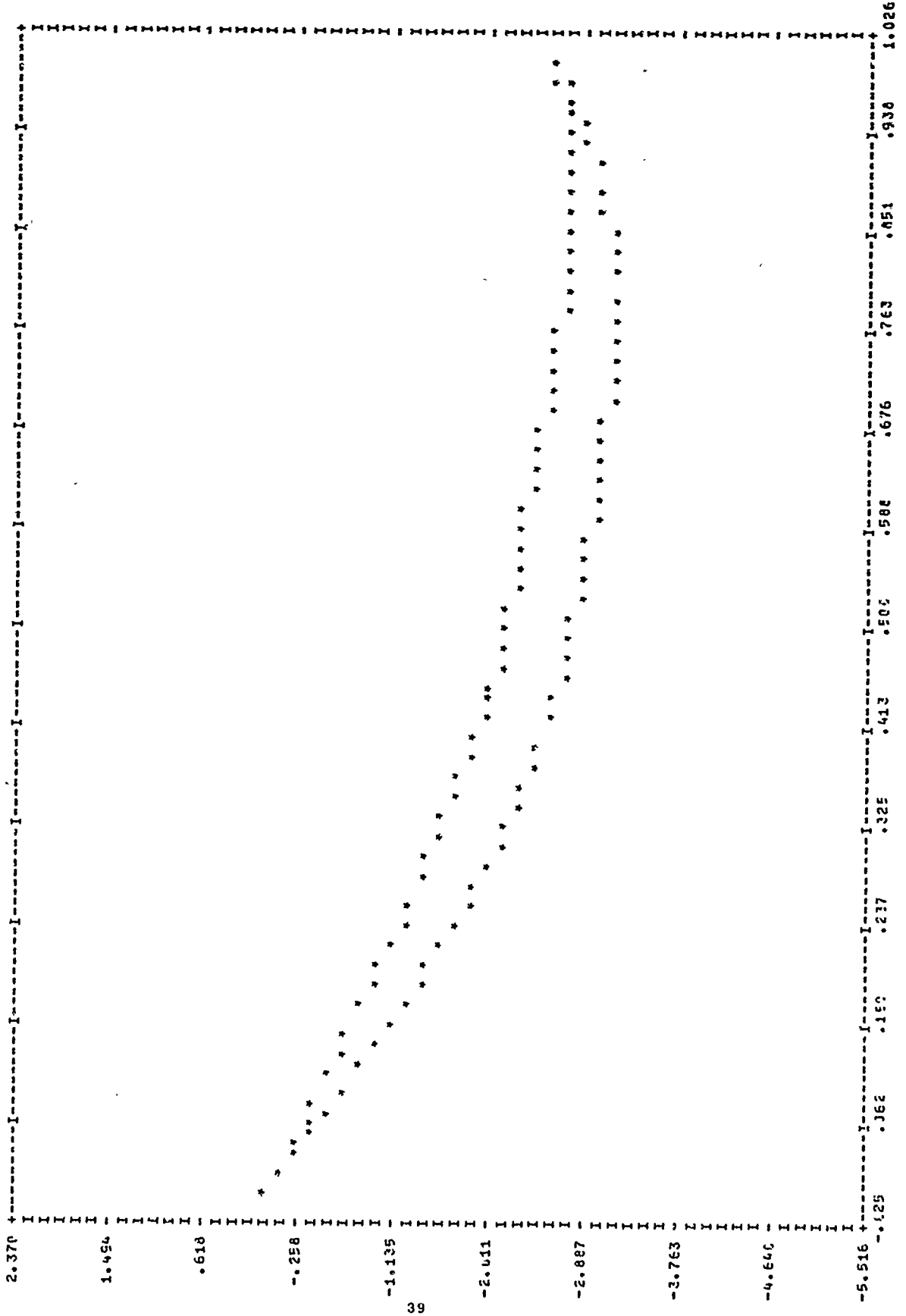
IPX = .00004 (AT -15.355 WITH 'X' AXIS)
 IPY = .00250 (AT -15.355 WITH 'Y' AXIS)

POINT NUMBER	H E A N L I N E D A T A		A N G L E T H I C K N E S S		S U R F A C E C O O R D I N A T E D A T A			
	X	Y	ANGLE	THICKNESS	XS	YS	XP	YP
1	.00160	0.00000	-34.579	.00320	.00251	.00132	.00069	-.00132
2	.02069	-.01318	-34.089	.00665	.02276	-.01042	.01903	-.01593
3	.04018	-.02611	-33.596	.01007	.04297	-.02192	.03740	-.03030
4	.05948	-.03881	-33.101	.01345	.06315	-.03310	.05580	-.04444
5	.07877	-.05126	-32.603	.01677	.08328	-.04420	.07425	-.05833
6	.09806	-.06349	-32.103	.02004	.10330	-.05500	.09273	-.07197
7	.11735	-.07547	-31.600	.02324	.12344	-.06557	.11126	-.08527
8	.13664	-.08722	-31.095	.02637	.14345	-.07593	.12983	-.09891
9	.15593	-.09874	-30.588	.02941	.16341	-.08608	.14845	-.11140
10	.17522	-.11003	-30.079	.03236	.18333	-.09603	.16711	-.12403
11	.19451	-.12109	-29.568	.03522	.20320	-.10577	.18582	-.13640
12	.21360	-.13192	-29.055	.03796	.22302	-.11533	.20459	-.14851
13	.23150	-.14165	-28.545	.04038	.24115	-.12391	.22105	-.15938

POINT NUMBER	H E A N L I N E D A T A			SURFACE COORDINATE DATA			
	X	Y	ANGLE THICKNESS	XS	YS	XP	YP
14	.24919	-.15116	-27.950	.04265	.25920	-.13231	.23919
15	.26689	-.16042	-27.291	.04489	.27718	-.14048	.25660
16	.28459	-.16941	-26.541	.04698	.29500	-.14839	.27409
17	.30228	-.17809	-25.706	.04895	.31290	-.15604	.29166
18	.31998	-.18644	-24.783	.05079	.33062	-.16330	.30933
19	.33767	-.19442	-23.768	.05250	.34825	-.17040	.32705
20	.35537	-.20201	-22.657	.05408	.36573	-.17706	.34495
21	.37306	-.20919	-21.448	.05553	.38321	-.18334	.36291
22	.39076	-.21551	-20.136	.05683	.40054	-.18923	.38098
23	.40845	-.22215	-18.718	.05795	.41776	-.19469	.39915
24	.42595	-.22784	-17.317	.05900	.43474	-.19968	.41718
25	.44346	-.23308	-16.031	.05986	.45173	-.20432	.43520
26	.46097	-.23792	-14.866	.06058	.46874	-.20864	.45319
27	.47847	-.24239	-13.826	.06116	.48574	-.21270	.47116
28	.49598	-.24655	-12.918	.06159	.50286	-.21653	.48909
29	.51348	-.25043	-12.144	.06187	.51999	-.22019	.50697
30	.53098	-.25410	-11.506	.06200	.53717	-.22372	.52480
31	.54848	-.25758	-11.000	.06198	.55441	-.22716	.54257
32	.56599	-.26092	-10.651	.06179	.57170	-.23056	.56026
33	.58350	-.26418	-10.435	.06145	.58906	-.23396	.57793
34	.60100	-.26738	-10.361	.06094	.60648	-.23741	.59552
35	.61854	-.27058	-10.294	.06028	.62392	-.24093	.61315
36	.63608	-.27374	-10.094	.05544	.64128	-.24448	.63087
37	.65361	-.27681	-9.763	.05845	.65857	-.24801	.64866
38	.67115	-.27976	-9.300	.05729	.67578	-.25149	.66652
39	.68869	-.28254	-8.703	.05596	.69292	-.25488	.68445
40	.70622	-.28512	-7.970	.05447	.71000	-.25814	.70245
41	.72376	-.28744	-7.102	.05282	.72703	-.26123	.72050
42	.74130	-.28947	-6.097	.05100	.74401	-.26412	.73859
43	.75884	-.29117	-4.953	.04901	.76095	-.26676	.75672
44	.77637	-.29250	-3.671	.04685	.77787	-.26912	.77487
45	.79391	-.29341	-2.249	.04453	.79478	-.27116	.79304
46	.81250	-.29388	-.611	.04187	.81282	-.27295	.81237
47	.83128	-.29380	1.126	.03501	.83090	-.27430	.83166
48	.84997	-.29313	2.958	.03595	.84904	-.27518	.85069
49	.86865	-.29185	4.881	.03268	.86726	-.27557	.87004
50	.88734	-.28993	6.889	.02520	.88558	-.27544	.88909
51	.90602	-.28733	8.974	.02550	.90403	-.27474	.90801
52	.92471	-.28402	11.130	.02156	.92262	-.27344	.92679
53	.94339	-.27997	13.347	.01738	.94130	-.27151	.94540
54	.96200	-.27514	15.614	.01294	.96033	-.26891	.96382
55	.98076	-.26951	17.921	.00822	.97950	-.26560	.98202
56	.99945	-.26305	20.254	.00320	.99889	-.26154	1.00000

NORMALISED PLOT OF SECTION NUMBER 1

SCALES - 'X' IS SPCNN TIMES 10 TO THE POWER OF -C 'Y' IS SPCNN TIMES 10 TO THE POWER OF 1



DIAPHRAGM RESULTS - ALL RESULTS REFER TO A BLADE OF SPECIFIED CHORD

BLADE CHORD = 3.48493E+00
 L.E.RADIUS = 5.40164E-03
 SECTION AREA = 4.99538E-01
 CENTEREC AT X = -1.70988E+00 Y = 7.61934E-01

SECTION MOMENTS OF AREA ABOUT CENTROID
 IX = 2.68937E-02
 IY = 3.00714E-01
 IXY = -8.13213E-02

PRINCIPAL SECOND MOMENTS OF AREA ABOUT CENTROID

IFX = 4.56332E-03 (AT-15.395 WITH 'X' AXIS)
 IFY = 3.23044E-01 (AT-15.395 WITH 'Y' AXIS)

PT AC	SUCTIION-----SURFACE X	Y	PRESSURE-----SURFACE X	Y	FT AC	SUCTIION-----SURFACE X	Y	PRESSURE-----SURFACE X	Y
1	-1.70688E+00	7.66381E-01	-1.71293E+00	7.57486E-01	2	-1.63853E+00	7.26791E-01	-1.65110E+00	7.08316E-01
2	-1.57038E+00	6.88028E-01	-1.58516E+00	6.59750E-01	4	-1.50234E+00	6.50070E-01	-1.52710E+00	6.12092E-01
3	-1.43444E+00	6.12899E-01	-1.46491E+00	5.65255E-01	6	-1.36667E+00	5.76494E-01	-1.40299E+00	5.19247E-01
5	-1.29905E+00	5.40286E-01	-1.34012E+00	4.74080E-01	8	-1.23757E+00	5.09305E-01	-1.27750E+00	4.29763E-01
7	-1.16455E+00	4.71682E-01	-1.21472E+00	3.86304E-01	10	-1.09101E+00	4.38148E-01	-1.15179E+00	3.43715E-01
9	-1.03018E+00	4.05282E-01	-1.08869E+00	3.02002E-01	12	-9.62269E-01	3.73069E-01	-1.02443E+00	2.61170E-01
11	-9.02155E-01	3.44116E-01	-9.67211E-01	2.24516E-01	14	-8.41275E-01	3.15814E-01	-9.08750E-01	1.88670E-01
13	-7.80647E-01	2.88271E-01	-8.50053E-01	1.53745E-01	16	-7.20289E-01	2.61570E-01	-7.21079E-01	1.19843E-01
15	-6.60220E-01	2.35786E-01	-7.31814E-01	8.70755E-02	18	-6.00855E-01	2.11038E-01	-6.72246E-01	5.55459E-02
17	-5.41095E-01	1.87384E-01	-6.12384E-01	2.33608E-02	20	-4.81893E-01	1.64919E-01	-5.52143E-01	-3.37266E-03
19	-4.23125E-01	1.43722E-01	-4.91581E-01	-3.05387E-02	22	-3.64704E-01	1.23376E-01	-4.30666E-01	-5.60231E-02
21	-3.06645E-01	1.05462E-01	-3.69392E-01	-7.67227E-02	24	-2.49390E-01	8.86345E-02	-3.08603E-01	-1.01272E-01
23	-1.92164E-01	7.30086E-02	-2.47844E-01	-1.20985E-01	26	-1.34748E-01	5.84325E-02	-1.07156E-01	-1.39017E-01
25	-7.72876E-02	4.47566E-02	-1.26572E-01	-1.55495E-01	28	-1.96336E-02	3.18229E-02	-6.61219E-02	-1.70663E-01
27	3.80587E-02	1.54856E-02	-5.82585E-03	-1.64478E-01	30	9.55866E-02	7.59163E-03	5.42846E-02	-1.97214E-01
29	1.54111E-01	-4.01143E-02	1.14207E-01	-2.39705E-01	32	2.12335E-01	-1.54738E-02	1.73327E-01	-2.20236E-01
31	2.70966E-01	-2.69447E-02	2.33408E-01	-2.50416E-01	34	3.25705E-01	-3.85153E-02	2.92746E-01	-2.40714E-01
33	3.88517E-01	-5.04464E-02	3.52199E-01	-2.68555E-01	36	4.47056E-01	-6.24097E-02	4.11925E-01	-2.59744E-01
35	5.45334E-01	-7.43260E-02	4.71513E-01	-2.85636E-01	38	5.63355E-01	-8.60544E-02	5.32140E-01	-2.76657E-01
37	6.21155E-01	-9.74940E-02	5.92613E-01	-2.84025E-01	40	6.78757E-01	-1.08485E-01	6.53837E-01	-2.90286E-01
39	7.36165E-01	-1.18908E-01	7.14145E-01	-2.95636E-01	42	7.93415E-01	-1.28835E-01	7.75156E-01	-2.99615E-01
41	8.50555E-01	-1.37573E-01	8.36286E-01	-3.02173E-01	44	9.07810E-01	-1.45500E-01	8.97466E-01	-3.03157E-01
43	9.64632E-01	-1.52383E-01	9.58740E-01	-3.02444E-01	46	1.02544E+00	-1.50400E-01	1.02354E+00	-2.99851E-01
45	1.08646E+00	-1.62955E-01	1.08899E+00	-2.94445E-01	48	1.14754E+00	-1.65937E-01	1.15332E+00	-2.86931E-01
47	1.20981E+00	-1.67259E-01	1.21839E+00	-2.77057E-01	50	1.27808E+00	-1.56796E-01	1.20661E+00	-2.64517E-01
49	1.33360E+00	-1.64439E-01	1.34641E+00	-2.49366E-01	52	1.35569E+00	-1.60470E-01	1.40973E+00	-2.31461E-01
51	1.45895E+00	-1.53566E-01	1.47288E+00	-2.10580E-01	54	1.52284E+00	-1.44789E-01	1.53129E+00	-1.86819E-01
53	1.58745E+00	-1.33609E-01	1.55588E+00	-1.60004E-01	56	1.65885E+00	-1.19951E-01	1.65859E+00	-1.20086E-01

PCINTS DESCRIBING LEADING EDGE RADIUS

PCINT NC.	X	Y
1	-1.71293E+00	7.57486E-01
2	-1.71336E+00	7.57631E-01
3	-1.71378E+00	7.58221E-01
4	-1.71415E+00	7.58651E-01
5	-1.71447E+00	7.59118E-01
6	-1.71474E+00	7.59615E-01
7	-1.71498E+00	7.60138E-01
8	-1.71512E+00	7.60660E-01
9	-1.71522E+00	7.61236E-01
10	-1.71526E+00	7.61808E-01
11	-1.71525E+00	7.62365E-01
12	-1.71517E+00	7.62926E-01
13	-1.71504E+00	7.63475E-01
14	-1.71485E+00	7.64008E-01
15	-1.71461E+00	7.64518E-01
16	-1.71431E+00	7.64999E-01
17	-1.71396E+00	7.65448E-01
18	-1.71357E+00	7.65857E-01
19	-1.71314E+00	7.66224E-01
20	-1.71268E+00	7.66543E-01
21	-1.71218E+00	7.66812E-01
22	-1.71166E+00	7.67028E-01
23	-1.71112E+00	7.67188E-01
24	-1.71056E+00	7.67290E-01
25	-1.71000E+00	7.67334E-01
26	-1.70943E+00	7.67318E-01
27	-1.70887E+00	7.67244E-01
28	-1.70832E+00	7.67111E-01
29	-1.70779E+00	7.66921E-01
30	-1.70728E+00	7.66677E-01
31	-1.70680E+00	7.66361E-01

CARTESIAN COORDINATES ON STREAMSURFACE 1

PCINT AC	ZS	XS	YS	ZP	XP	YP
1	2.57578E+00	-1.44008E+00	6.793391E-01	2.57488E+00	-1.444527E+00	6.69902E-01
2	2.62081E+00	-1.38231E+00	6.49769E-01	2.61872E+00	-1.39294E+00	6.30192E-01
3	2.66533E+00	-1.32471E+00	6.20279E-01	2.66178E+00	-1.34058E+00	5.90458E-01
4	2.70929E+00	-1.26724E+00	5.90880E-01	2.70411E+00	-1.28816E+00	5.51002E-01
5	2.75268E+00	-1.20996E+00	5.61579E-01	2.74574E+00	-1.23567E+00	5.11703E-01
6	2.79558E+00	-1.15281E+00	5.32384E-01	2.78670E+00	-1.18309E+00	4.72643E-01
7	2.83795E+00	-1.09581E+00	5.13202E-01	2.82702E+00	-1.13042E+00	4.33856E-01
8	2.87980E+00	-1.03892E+00	4.74340E-01	2.86671E+00	-1.07765E+00	3.95294E-01
9	2.92113E+00	-9.82233E-01	4.45030E-01	2.90581E+00	-1.02475E+00	3.57260E-01
10	2.96194E+00	-9.25647E-01	4.16797E-01	2.94435E+00	-9.71731E-01	3.19507E-01
11	3.00224E+00	-8.69188E-01	3.88229E-01	2.98234E+00	-9.18567E-01	2.82142E-01
12	3.04201E+00	-8.12852E-01	3.59100E-01	3.01981E+00	-8.65253E-01	2.45204E-01
13	3.07802E+00	-7.56131E-01	3.39040E-01	3.05376E+00	-8.116176E-01	2.08735E-01
14	3.11357E+00	-7.09968E-01	3.18275E-01	3.08736E+00	-7.56887E-01	1.78735E-01
15	3.14865E+00	-6.58812E-01	2.83033E-01	3.12065E+00	-7.017373E-01	1.46309E-01
16	3.18328E+00	-6.07888E-01	2.50203E-01	3.15367E+00	-6.467620E-01	1.14560E-01
17	3.21746E+00	-5.57193E-01	2.23400E-01	3.18646E+00	-5.917614E-01	8.36502E-02

PCINT	NC	ZSEMI	XSEMI	YSEMI	ZP	XP	YF
18	2	5.25119E+00	-5.06751E-01	2.10564E-01	3.21908E+00	-5.67343E-01	5.37112E-02
19	3	5.56573E+00	-4.56573E-01	1.87520E-01	3.25152E+00	-5.16799E-01	2.40061E-02
20	3	1.1739E+00	-4.06673E-01	1.6147E-01	3.28390E+00	-4.65971E-01	-2.93534E-03
21	3	4.9063E+00	-3.47064E-01	1.45434E-01	3.21622E+00	-4.14051E-01	-2.53572E-02
22	3	3.8203E+00	-3.07756E-01	1.25500E-01	3.34857E+00	-3.63432E-01	-5.42682E-02
23	3	4.1381E+00	-2.58754E-01	1.07566E-01	3.38095E+00	-3.11713E-01	-7.76772E-02
24	3	4.4503E+00	-2.10435E-01	9.15955E-02	3.41202E+00	-2.60406E-01	-5.51429E-02
25	3	4.7615E+00	-1.62093E-01	7.47768E-02	3.44495E+00	-2.05131E-01	-1.16943E-01
26	3	5.0722E+00	-1.13655E-01	5.8300E-02	3.47695E+00	-1.57917E-01	-1.37239E-01
27	3	5.3927E+00	-6.65210E-02	4.56245E-02	3.50873E+00	-1.06796E-01	-1.54107E-01
28	3	5.6934E+00	-1.66159E-02	3.20936E-02	3.54045E+00	-5.57895E-02	-1.69744E-01
29	3	6.0043E+00	8.65955E-02	2.50465E-02	3.57217E+00	-4.91876E-01	-1.84259E-01
30	3	6.3158E+00	1.30235E-01	6.31236E-03	3.60377E+00	4.58005E-02	-1.57856E-01
31	3	6.6278E+00	1.79230E-01	-6.22831E-01	3.63565E+00	9.63565E-02	-2.10575E-01
32	3	6.9405E+00	2.28612E-01	-2.32768E-02	3.66797E+00	1.46741E-01	-2.22632E-01
33	3	7.2535E+00	2.79165E-01	-4.41188E-02	3.69979E+00	1.96951E-01	-2.34168E-01
34	3	7.5665E+00	3.27789E-01	-5.41188E-02	3.72516E+00	2.46927E-01	-2.46214E-01
35	3	7.8820E+00	3.77182E-01	-7.16083E-02	3.75042E+00	2.97144E-01	-2.56238E-01
36	3	8.1940E+00	4.26351E-01	-6.59795E-02	3.79182E+00	3.47540E-01	-2.66650E-01
37	3	8.5042E+00	4.75313E-01	-5.72590E-02	3.82332E+00	3.98153E-01	-2.77138E-01
38	3	8.8127E+00	5.24082E-01	-1.12665E-01	3.85508E+00	4.48975E-01	-2.86755E-01
39	3	9.1196E+00	5.72675E-01	-1.22881E-01	3.88695E+00	4.95952E-01	-2.95709E-01
40	3	9.4251E+00	6.21112E-01	-1.35037E-01	3.91900E+00	5.51189E-01	-3.03773E-01
41	3	9.7294E+00	6.69420E-01	-1.46546E-01	3.95124E+00	6.02533E-01	-3.10827E-01
42	3	1.00328E+00	7.17627E-01	-1.56534E-01	3.98360E+00	6.54011E-01	-3.16625E-01
43	3	1.03357E+00	7.65767E-01	-1.57192E-01	4.01616E+00	7.05569E-01	-3.21038E-01
44	3	1.06383E+00	8.13878E-01	-1.57575E-01	4.04898E+00	7.57233E-01	-3.23599E-01
45	3	1.09409E+00	8.6183E-01	-1.57371E-01	4.08176E+00	8.08906E-01	-3.25300E-01
46	3	1.12428E+00	9.09614E-01	-1.57288E-01	4.11652E+00	8.62914E-01	-3.24608E-01
47	3	1.15448E+00	9.56614E-01	-1.57088E-01	4.15218E+00	9.16785E-01	-3.21628E-01
48	3	1.18467E+00	1.00222E-01	-1.57189E-01	4.18750E+00	9.73500E-01	-3.16241E-01
49	3	1.21486E+00	1.04806E+00	-1.57042E-01	4.22284E+00	1.02757E+00	-3.08315E-01
50	3	1.24505E+00	1.09215E+00	-1.56973E-01	4.25815E+00	1.08216E+00	-2.97855E-01
51	3	1.27524E+00	1.13467E+00	-1.56967E-01	4.29338E+00	1.13599E+00	-2.84696E-01
52	3	1.30543E+00	1.17575E+00	-1.57042E-01	4.32845E+00	1.18441E+00	-2.68643E-01
53	3	1.33562E+00	1.21494E+00	-1.56257E-01	4.36335E+00	1.24235E+00	-2.45565E-01
54	3	1.36581E+00	1.25485E+00	-1.55063E-01	4.39795E+00	1.29476E+00	-2.27355E-01
55	3	1.39600E+00	1.29337E+00	-1.53321E-01	4.43216E+00	1.34656E+00	-2.01053E-01
56	3	1.42619E+00	1.33155E+00	-1.5162632E-01	4.46559E+00	1.39777E+00	-1.72988E-01

PCINT	NC	ZSEMI	XSEMI	YSEMI
1	2	5.7488E+00	-1.44527E+00	6.65983E-01
2	2	5.7456E+00	-1.44565E+00	6.70258E-01
3	2	5.7425E+00	-1.44602E+00	6.70581E-01
4	2	5.7393E+00	-1.44639E+00	6.70945E-01
5	2	5.7362E+00	-1.44676E+00	6.71358E-01
6	2	5.7331E+00	-1.44713E+00	6.71804E-01
7	2	5.7300E+00	-1.44750E+00	6.72281E-01
8	2	5.7269E+00	-1.44787E+00	6.72784E-01
9	2	5.7238E+00	-1.44824E+00	6.73309E-01
10	2	5.7207E+00	-1.44861E+00	6.73848E-01
11	2	5.7176E+00	-1.44898E+00	6.74397E-01
12	2	5.7145E+00	-1.44935E+00	6.74945E-01
13	2	5.7114E+00	-1.44972E+00	6.75498E-01
14	2	5.7083E+00	-1.45009E+00	6.76053E-01
15	2	5.7052E+00	-1.45046E+00	6.76614E-01
16	2	5.7021E+00	-1.45083E+00	6.77186E-01

PCINT NC	ZSEMI	XSEMI	YSEMI
17	2.57233E+00	-1.44615E+00	6.77548E-01
18	2.57243E+00	-1.44582E+00	6.77596E-01
19	2.57255E+00	-1.44545E+00	6.78407E-01
20	2.57271E+00	-1.44506E+00	6.78777E-01
21	2.57290E+00	-1.44464E+00	6.79103E-01
22	2.57311E+00	-1.44420E+00	6.79380E-01
23	2.57335E+00	-1.44374E+00	6.79606E-01
24	2.57361E+00	-1.44327E+00	6.79778E-01
25	2.57389E+00	-1.44279E+00	6.79894E-01
26	2.57418E+00	-1.44231E+00	6.79953E-01
27	2.57449E+00	-1.44184E+00	6.79954E-01
28	2.57481E+00	-1.44137E+00	6.79892E-01
29	2.57513E+00	-1.44092E+00	6.79784E-01
30	2.57545E+00	-1.44049E+00	6.79615E-01
31	2.57578E+00	-1.44008E+00	6.79391E-01

BLADE CALCULATIONS FOR AERODYNAMIC ANALYSIS

STATION 3		NUMBER OF FACII= 6		THETA
RADIUS	SECTION ANGLE	LEAN ANGLE	BLADE BLOCKAGE	
2.9363	-34.5568	-5.7373	.1506	.1030
4.0656	-35.5746	-2.4342	.1002	.1238
5.2456	-45.2380	-2.5753	.0763	.1326
6.4975	-51.2117	-1.0540	.0541	.1424
7.8091	-57.5491	2.4370	.0415	.1388
8.5000	-60.9548	2.7736	.0373	.1350

STATION 4		NUMBER OF FACII= 6		THETA
RADIUS	SECTION ANGLE	LEAN ANGLE	BLADE BLOCKAGE	
3.3897	-25.0291	-5.4105	.1531	.0062
4.3344	-31.0055	-2.1185	.1407	.0223
5.4154	-38.8175	-3.6777	.1072	.0305
6.5824	-47.5182	-3.3044	.0795	.0462
7.8307	-55.7777	.4414	.0341	.0450
8.5000	-59.8318	.6624	.0595	.0482

STATION 5		NUMBER OF FACII= 6		THETA
RADIUS	SECTION ANGLE	LEAN ANGLE	BLADE BLOCKAGE	
3.7385	-12.8574	-4.602	.1783	-.0379
4.5758	-20.6393	1.8574	.1366	.0403
5.5662	-32.2241	-5.642	.1076	-.0453
6.6591	-43.3122	-3.2075	.0847	-.0369
7.8459	-53.2632	-3.0393	.0707	-.0290
8.5000	-58.3035	-4.1035	.0674	-.0240

STATION 6		NUMBER OF FACII= 6		THETA
RADIUS	SECTION ANGLE	LEAN ANGLE	BLADE BLOCKAGE	
4.0284	-.6510	3.8432	.1186	-.0610
4.8259	-8.6767	9.3017	.0958	-.0832
5.7147	-23.7341	5.1020	.0751	-.1078
6.7242	-38.5832	-1.5136	.0668	-.1115
7.8675	-50.1564	-4.9335	.0602	-.1033
8.5000	-56.4261	-7.4341	.0613	-.0948

RADIUS	SECTION ANGLE	LEAN ANGLE	BLADE BLOCKAGE	THETA
4.4612	38.0404	21.8805	.0108	-.0386
5.0795	11.3631	23.1255	.0143	-.0924
5.8623	-14.4548	17.0305	.0034	-.1486
6.7858	-33.9363	5.1628	.0059	-.1758
7.8716	-47.4131	-5.0787	.0046	-.1770
8.5000	-53.4651	-11.9278	.0076	-.1656

PLATE SURFACE GEOMETRY IN CARTESIAN COORDINATES AT SPECIFIED VALUES OF 'Z'

SECTION NUMBER 1 'Z' = 2.5000

SECTION PROPERTIES

SECTION AREA = 4.3539E-01
 LOCATION OF CENTROID
 RELATIVE TO STACK AXIS XEAR = -6.1846E-02
 YEAR = 8.9764E-02
 SECCO MMENTS OF AREA ABOUT CENTROID
 IX = 1.3782E-02
 IY = 1.5176E-01
 IXY = -8.5456E-03
 PRINCIPAL SECCO MMENTS OF AREA ABOUT CENTROID
 IFX = 1.3294E-02 (AT -3.69 DEGREES TO 'X' AXIS)
 IFY = 1.5234E-01 (AT -3.69 DEGREES TO 'Y' AXIS)
 TORSIONAL CONSTANT = 5.2463E-03

SECTION COORDINATES

FCINT NO	XS	YS	XF	YP
1	-1.4401E+00	6.6206E-01	-1.4451E+00	6.5277E-01
2	-1.3822E+00	6.2333E-01	-1.3926E+00	6.0377E-01
3	-1.3245E+00	5.8567E-01	-1.3409E+00	5.5575E-01
4	-1.2670E+00	5.4904E-01	-1.2873E+00	5.0866E-01
5	-1.2096E+00	5.1347E-01	-1.2344E+00	4.6249E-01
6	-1.1523E+00	4.7881E-01	-1.1814E+00	4.1724E-01
7	-1.0951E+00	4.4507E-01	-1.1281E+00	3.7292E-01
8	-1.0380E+00	4.1220E-01	-1.0747E+00	3.2954E-01
9	-9.8197E-01	3.8015E-01	-1.0211E+00	2.8704E-01
10	-9.2400E-01	3.4885E-01	-9.6724E-01	2.4538E-01
11	-8.6712E-01	3.1824E-01	-9.1317E-01	2.0456E-01
12	-8.1130E-01	2.8925E-01	-8.5896E-01	1.6456E-01
13	-7.6113E-01	2.6314E-01	-8.1144E-01	1.3067E-01
14	-7.1253E-01	2.3881E-01	-7.6406E-01	9.7691E-02
15	-6.6452E-01	2.1535E-01	-7.1873E-01	6.9579E-02
16	-6.1715E-01	1.9287E-01	-6.6943E-01	3.4782E-02
17	-5.7047E-01	1.7162E-01	-6.2219E-01	5.2116E-03
18	-5.2450E-01	1.5185E-01	-5.7486E-01	-2.2864E-02
19	-4.7930E-01	1.3357E-01	-5.2756E-01	-4.9410E-02
20	-4.3491E-01	1.1686E-01	-4.8023E-01	-7.4121E-02
21	-3.9135E-01	1.0211E-01	-4.3287E-01	-9.6726E-02
22	-3.4870E-01	8.9602E-02	-3.8544E-01	-1.1688E-01
23	-3.0699E-01	7.9437E-02	-3.3757E-01	-1.3448E-01
24	-2.6488E-01	7.0952E-02	-2.8969E-01	-1.4995E-01
25	-2.2302E-01	6.4764E-02	-2.4183E-01	-1.6252E-01
26	-1.8138E-01	6.0442E-02	-1.9409E-01	-1.7209E-01
27	-1.3989E-01	5.7800E-02	-1.4774E-01	-1.7902E-01
28	-9.8522E-02	5.6980E-02	-1.0167E-01	-1.8363E-01
29	-5.7226E-02	5.7292E-02	-5.6368E-02	-1.8617E-01
30	-1.5991E-02	5.8570E-02	-1.1898E-02	-1.8661E-01
31	2.5215E-02	6.0662E-02	3.1669E-02	-1.8533E-01
32	6.6100E-02	6.3293E-02	7.4271E-02	-1.8272E-01
33	1.0756E-01	6.5907E-02	1.1665E-01	-1.7919E-01
34	1.4672E-01	6.8309E-02	1.5963E-01	-1.7494E-01

FCINT NO	XS	YS	XP	YP
35	1.87827E-01	7.07226E-02	1.94538E-01	-1.69955E-01
36	2.29936E-01	7.29277E-02	2.32328E-01	-1.64692E-01
37	2.62042E-01	7.50131E-02	2.69747E-01	-1.58903E-01
38	2.95151E-01	7.73488E-02	3.06779E-01	-1.52265E-01
39	3.34271E-01	8.03610E-02	3.43413E-01	-1.44451E-01
40	3.64222E-01	8.43596E-02	3.75642E-01	-1.35235E-01
41	4.01631E-01	8.92597E-02	4.15544E-01	-1.24240E-01
42	4.33945E-01	9.57912E-02	4.50406E-01	-1.10735E-01
43	4.65422E-01	1.04638E-01	4.85701E-01	-9.43730E-02
44	4.96101E-01	1.15936E-01	5.20122E-01	-7.52074E-02
45	5.26081E-01	1.29543E-01	5.54018E-01	-5.25993E-02
46	5.65661E-01	1.47128E-01	5.98442E-01	-2.30496E-02
47	6.05137E-01	1.69887E-01	6.42467E-01	1.30288E-02
48	6.44567E-01	1.98633E-01	6.85914E-01	5.62132E-02
49	6.84044E-01	2.33723E-01	7.28558E-01	1.07248E-01
50	7.23622E-01	2.75563E-01	7.70158E-01	1.66419E-01
51	7.62492E-01	3.25882E-01	8.10429E-01	2.34813E-01
52	8.03664E-01	3.86627E-01	8.49057E-01	3.14310E-01
53	8.47294E-01	4.58989E-01	8.85717E-01	4.05505E-01
54	8.85492E-01	5.44508E-01	9.20050E-01	5.09385E-01
55	9.27413E-01	6.45143E-01	9.51715E-01	6.27039E-01
56	9.70161E-01	7.63431E-01	9.80319E-01	7.59971E-01

FCINT NO	XSEMI	YSEMI
1	-1.44511E+00	6.52778E-01
2	-1.44549E+00	6.53122E-01
3	-1.44584E+00	6.53514E-01
4	-1.44616E+00	6.53940E-01
5	-1.44643E+00	6.54420E-01
6	-1.44666E+00	6.54925E-01
7	-1.44685E+00	6.55458E-01
8	-1.44699E+00	6.56012E-01
9	-1.44708E+00	6.56581E-01
10	-1.44712E+00	6.57160E-01
11	-1.44711E+00	6.57742E-01
12	-1.44705E+00	6.58320E-01
13	-1.44695E+00	6.58888E-01
14	-1.44679E+00	6.59440E-01
15	-1.44659E+00	6.59971E-01
16	-1.44634E+00	6.60473E-01
17	-1.44606E+00	6.60942E-01
18	-1.44573E+00	6.61372E-01
19	-1.44537E+00	6.61759E-01
20	-1.44498E+00	6.62099E-01
21	-1.44456E+00	6.62387E-01
22	-1.44412E+00	6.62621E-01
23	-1.44366E+00	6.62798E-01
24	-1.44319E+00	6.62916E-01
25	-1.44272E+00	6.62973E-01
26	-1.44224E+00	6.62978E-01
27	-1.44177E+00	6.62906E-01
28	-1.44131E+00	6.62782E-01
29	-1.44085E+00	6.62599E-01
30	-1.44042E+00	6.62360E-01
31	-1.44001E+00	6.62066E-01

SECTION VII

COMPUTER PROGRAM DETAILS

1. IMPLEMENTATION OF THE COMPUTER PROGRAM

The program is written in FORTRAN IV and was developed on a CDC 6000 Series System, incorporating the version 3.3 SCOPE Operating System. When loaded into core, the program (and resident system) occupies about 32K of storage, so that the program will probably not be usable without modification on a relatively small computer. Apart from this limitation, the program should be compatible with the majority of modern computing systems. The program consists of a main program, and Subroutines BQ, CQ, D1, EQ, and FQ. The six decks have been given the identifiers A, B, C, D, E, and F, respectively. Listings of the decks are shown below, and the deck set-up required for the CDC 6000 Series System is also presented.

The program uses three numerical system units for its input and output routines. Input is drawn from the card unit via READ statements referring to Unit LOG 1; output is sent to the line printer by WRITE statements referring to Unit LOG 2; and punched output is produced via WRITE statements referenced to Unit LOG 3. Units LOG 1, LOG 2, and LOG 3 are set equal to 5, 6, and 7, respectively, on cards A130-140 in the FORTRAN programming. On the CDC 6000 Series System, the "PROGRAM" card must also establish the input and output linkages. On other computing systems, the "PROGRAM" card may not be required, and the input-output files may be established via control cards.

The program as presented herein utilizes an on-line precision plotting capability available at the program development site. Calls to four subroutines not included in the deck are included in the program. These calls are executed only if precision plots are specified in the input data, and the entry points expressed are part of standard CALCOMP software normally supplied to users of CALCOMP precision plotting equipment. The various call statements used in the program are explained below, to facilitate modification should the need arise.

CALL PLOT (XPLOT, YPLOT, N)

The majority of plotting is done using this form of call. The parameters XPLOT and YPLOT are the "x" and "y" coordinates (in inches) on the paper to which the pen is being directed. The parameter N indicates pen up or down, $|N| = 3$ or $|N| = 2$, respectively, and will cause XPLOT or YPLOT to be assigned as the origin for further coordinates if N is negative.

CALL SYMBOL (X, Y, H, TEXT, THETA, N)

This call is used to title the plots. The parameters X and Y are the coordinates (in inches) of the lower left hand corner of the first character, H is the character height (in inches), TEXT is the character to be printed, THETA is the angle of the lettering with respect to the "x" axis and N is the total number of characters to be printed.

CALL NUMBER (X, Y, H, F, THETA, N)

This call causes the printing of the number F. The parameters X, Y, H, and THETA are used as for CALL SYMBOL. The parameter N indicates the number of digits following the decimal point if positive, or truncation to an integer if equal to -1.

CALL PLOTE

This call terminates the tape.

In the event the program is used on a computing system which does not include CALCOMP software, and the operating system will not execute a program with unsatisfied external references, dummy entry points may be supplied by adding to the deck a subroutine such as the following:

SUBROUTINE PLOT

A = A

ENTRY SYMBOL

ENTRY NUMBER

ENTRY PLOTE

RETURN

END

2. DECK SETUP FOR CDC 6000 SERIES SYSTEM

The deck setup required to run the program on a CDC 6000 Series System incorporating the SCOPE 3.3 Operating System is shown below. Production runs of the program would usually employ relocatable binary forms of the routines produced from the source decks to avoid having to compile the FORTRAN for each run and the waste of associated computer resources.

JOB

Identification, etc.

FTN.

LGO.

7/8/9 End of Record

SOURCE DECK A

SOURCE DECK B

SOURCE DECK C

SOURCE DECK D

SOURCE DECK E

SOURCE DECK F

7/8/9 End of Record

DATA DECK

6/7/8/9 End of Job

3. FORTRAN PROGRAM LISTING

A listing of the FORTRAN program appears on the following pages with each subroutine started on a new page.

```

PROGRAM ARBITR(INPUT,OUTPUT,PUNCH,PLOT,TAFES=INPUT,TAPE6=OUTPUT,
1TAPE7=PUNCH)
DIMENSION AIRANG(10,15), YPFME(81), SL(82), YU(81), BETMET(10), SM
1(10,5), DEVCRV(10,5), RADEV(5), RINC(15), XINC(15), EXB(15), S1(10
2), DEVRAD(10), LL(10), CELDEV(15), F137E(8), F137S(5), F161C(8,5),
3 F195M(8,2), F164XB(8), F172K(7), F142TC(7), NPTS(15), YMPRME(81),
4 YA(15), YB(15), YC(15), YE(15), NOINF(51), SORARR(51), ROMIN(51)
COMMON EPZ(100,3), R(10,15), ZOUT(15), SS(100), X(100), YFRIME(100), YS(
115,81), YP(15,81), XP(15,81), XS(15,81), YSEMI(15,31), XSEMI(15,31), ZS(
215,81), ZP(15,81), ZSEMI(15,31), TITLE(8), XHERE(10), XTEMP(100), RAD(10
30), TEMP1(15), TEMP2(15), TEMP3(15), TEMP4(15), ZR(15), ZZ(15), RLE(15), T
4C(15), YE(15), SOIVR(15), DELX(15), DELY(15), XSTA(15,10), RSTA(15,10), K
5PTS(15), SIGHA(100), TANFHI(10,15), ZCAMB(15,10), YCAMB(15,10), IFANGS(
610), THETA(15,10), ALFHA(15,10)
REAL IX,IY,IXY,IPX,IPY,IXN,IYN,IXO,IYO
DATA F137B/0.0,10.0,20.0,30.0,40.0,50.0,60.0,70.0/
DATA F137S/0.4,0.8,1.2,1.6,2.0/
DATA F142TC/0.0,0.02,0.04,0.06,0.08,0.10,0.12/
DATA F161D/0.0,0.009,0.017,0.029,0.042,0.059,0.079,1.05,0.0,0.12,0.30,0
1.51,0.75,1.05,1.47,2.07,0.0,0.16,0.33,0.61,0.95,1.42,2.12,3.07,0.0
2,0.17,0.40,0.72,1.11,1.71,2.62,3.95,0.0,0.2,0.44,0.78,1.21,1.90,3.
301,4.75/
DATA F195M/0.17,0.173,0.179,0.189,0.206,0.232,0.269,0.310,0.25,0.2
155,0.261,0.268,0.278,0.292,0.312,0.342/
DATA F164XB/0.965,0.945,0.921,0.890,0.850,0.782,0.679,0.550/
DATA F172K/0.0,0.166,0.331,0.521,0.74,1.0,1.300/
LOG1=5
LOG2=6
LOG3=7
PI=3.1415926536
C1=180.0/PI
READ (LCG1,5) TITLE
FORMAT (7A10,A2)
WRITE (LOG2,10) TITLE
5 FORMAT (1H1,38X,44HUSAF - ARL(LF) ARBITRARY CAMBER LINE PROGRAM,/)
10 139X,44(1H*),//,10X,5HTITLE,25X,1H=,7A10,A2)
READ (LCG1,15) NLINES,NSTNS,NZ,NSPEC,ISEGFT,NBLADE,ISTAK,IPUNCH,IF
1PLOY,IPRINT
15 FORMAT (12I3)
WRITE (LOG2,20) NLINES,NSTNS,NZ,NSPEC,ISEGPT,NBLADE,ISTAK,IPUNCH,I
1FFLCT,IFRINT

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20  FORMAT (10X,24HNUMBER OF STREAMSURFACES,6X,1H=,I3,/,10X,18HNUMBER
    10F STATIONS,12X,1H=,I3,/,10X,27HNUMBER OF CCNSTANT-Z PLANES,3X,1H=
    2, I3,/,10X,27HNUMBER OF BLADE DATA PCINTS,3X,1H=,I3,/,10X,31HNUMBER
    3 OF PCINTS PER SEGMENT =,I3,/,10X,29HNUMBER OF BLADES IN BLADE RO
    4W,1X,1H=,I3,/,10X,5HISTAK,25X,1H=,I3,/,10X,6HIPUNCH,24X,1H=,I3,/,1
    50X,6HIPLOT,24X,1H=,I3,/,10X,6HIPRINT,24X,1H=,I3)
    READ (LCG1,25) ZINNER,ZOUTER,SCALE,STACKX,PLTSZ
    WRITE (LOG2,30) ZINNER,ZOUTER,SCALE,STACKX,PLTSZ
    FORMAT (5F12.0)
25  FORMAT (/,10X,6HZINNER,24X,1H=,F8.4,/,10X,6HZCUTER,24X,1H=,F8.4,/,
30  110X,5HSCALE,25X,1H=,F8.4,/,10X,6HSTACKX,24X,1H=,F8.4,/,10X,6HPLTSZ
    2E,24X,1H=,F8.4,/,/,2CX)
    READ (LCG1,15) IRLE,IRTE,NRADEV,NINC,NSIGN,IFCA,IPASS
    WRITE (LCG2,35) IRLE,IRTE,NRADEV,NINC,NSIGN,IFCA,IPASS
35  FORMAT (10X,27HLEADING EDGE STATION NUMBER,3X,1H=,I3,/,10X,28HTRAI
    1LING EDGE STATION NUMBER,2X,1H=,I3,/,10X,26HRADII SPECIFYING DEVI
    2TION,4X,1H=,I3,/,10X,26HRADII SPECIFYING INCIDENCE,4X,1H=,I3,/,10X,2
    37HSENSE CF ROTATION INDICATOR,3X,1H=,I3,/,10X,27HDEVIATION CALCULA
    4TION INDEX,3X,1H=,I3,/,10X,28HNUMBER CF INITIAL S/R TRIALS,2X,1H=,
    5I3,/,2X)
    READ (LCG1,25) XKSHFE,SCLTOL
    WRITE (LCG2,40) XKSHFE,SCLTOL
40  FORMAT (10X,12HSHAPE FACTOR,18X,1H=,F8.4,/,10X,18HSOLIDITY TOLERAN
    1CE,12X,1H=,F8.4,/,/,2X)
    DO 55 K=1,NRADEV
    READ (LOG1,15) NPTS(K)
    READ (LOG1,25) RADEV(K)
    WRITE (LCG2,45) K,NPTS(K),RADEV(K)
45  FORMAT (5X,16HDEVIATION CURVE ,I2,5X,18HNUMBER OF PCINTS =,I2,5X,8
    1HRADIUS =,F8.4,/,2X)
    NPT=NPTS(K)
    READ (LCG1,50) (SM(J,K),DEVCRV(J,K),J=1,NPT)
    FORMAT (2F12.0)
50  WRITE (LOG2,60) (J,SM(J,K),DEVCRV(J,K),J=1,NPT)
55  FORMAT (10X,5HPCINT,5X,22HNCORMALIZED MERICDIONAL,5X,20HNCORMALIZED
60  1DEVIATION,/,28X,5HCFORD,18X,12H01STRIEUTICN,/(11X,I2,14X,F6.4,20X
    2,F6.4)
    READ (LCG1,65) (RINC(J),XINC(J),DELDEV(J),J=1,NING)
    FORMAT (3F12.0)
65  WRITE (LCG2,70) (RINC(J),XINC(J),DELDEV(J),J=1,NING)

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70  FORMAT (2X,/,5X,42HINCIDENCE AND EXTRA DEVIATION DISTRIBUTION,/,
110X,12HINLET RADIUS,4X,9HINCIDENCE,4X,15HEXTRA DEVIATION,/(F19.4,
2F14.3,F15.3)
LNCT=3
WRITE (LOG2,75)
75  FCRMAT (1H1,/,20X,36HSTREAMSURFACE GEOMETRY SPECIFICATION)
DO 120 I=1,NSTNS
READ (LCG1,15) KPTS(I),IFANGS(I),LOG8
IF (LOG8.EQ.0) LOG8=5
KPT=KPTS(I)
READ (LCG1,50) (XSTA(K,I),RSTA(K,I),K=1,KFT)
IF (KPTS(I).GE.2) GO TO 80
KPTS(I)=2
XSTA(2,I)=XSTA(1,I)
RSTA(2,I)=RSTA(1,I)+1.0
80  READ (LCG8,50) (R(I,J),AIRANG(I,J),J=1,NLINES)
IDUM=KPTS(I)
IF (NLINES.GT.IDUM) IDUM=NLINES
IF (LNCT.LE.54-NLINES) GO TO 90
WRITE (LOG2,85)
95  FCRMAT (1H1)
LNCT=1
LNCT=LNCT+IDUM+6
WRITE (LCG2,95) I,KPTS(I),I,IFANGS(I)
95  FORMAT (2X,/,10X,17HCOMPUTING STATION,I3,5X,28HNUMBER OF DESCRIBIN
1G PCINYS=,I3,6X,7HIFANGS(,I2,2H)=,I3,/,6X,11HDESCRIPTION,9X,10HSTR
2EAMLINE,5X,5HRADII,11X,5HAIR ANGLE,/,6X,11X,9X,1HR,11X,6HNUMBER,/,
3,2X)
DO 100 K=1,IDUM
IF (K.LE.KPTS(I).AND.K.LE.NLINES) WRITE (LOG2,105) XSTA(K,I),RSTA(
1K,I),K,R(I,K),AIRANG(I,K)
IF (K.LE.KPTS(I).AND.K.GT.NLINES) WRITE (LOG2,110) XSTA(K,I),RSTA(
1K,I)
IF (K.GT.KPTS(I).AND.K.LE.NLINES) WRITE (LOG2,115) K,R(I,K),AIRANG
1(I,K)
CONTINUE
100
105  FORMAT (3X,F8.4,2X,F8.4,8X,I2,9X,F8.4,9X,F8.4)
110  FORMAT (3X,F8.4,2X,F8.4)
115  FORMAT (29X,I2,9X,F8.4,5X,F8.4)
CONTINUE
120

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125 IF (LNCT.LE.54-NSPEC) GO TO 125
    WRITE (LOG2,85)
    LNCT=1
    LNCT=LNCT+NSPEC+6
130 READ (LCG1,130) (ZR(J),YA(J),YB(J),YC(J),YE(J),RLE(J),TC(J),TE(J),
    1ZZ(J),SDIVR(J),DELX(J),DELY(J),J=1,NSPEC)
    FORMAT (6F12.0)
    WRITE (LCG2,135) (ZF(J),YA(J),YB(J),YC(J),YE(J),RLE(J),TC(J),TE(J),
    1ZZ(J),SDIVR(J),DELX(J),DELY(J),J=1,NSPEC)
135 FORMAT (2X,/,20X,30#SECTION GEOMETRY SPECIFICATION,/,10X,10#STREA
    1MLINE,2X,5#SLD ,5X,6#IN.CEL,4X,6#CONSIG,4X,6#NO.ALD,3X,4#HLE RADI
    2US MAX THICK TE THICK FOINT OF START VAL,3X,7#X STACK,3X,7#Y STAC
    3K,/,11X,6#NUMBER,5X,5#CL FT,5X,5# S/R,0,3X,1#HLE RD CRV INFL. PTS,3
    4X,6#H/CHORD,4X,6#H/CHCRD,3X,8#H/2*CHORD,2X,18#MAX THICK OF S/R ,4X,6
    5#OFFSET,4X,6#CFFSET,/, (10X,F7.2,3X,F8.3,F10.3,2F10.4,3F10.5,2F10.
    64,F11.6,F10.6))
    IF (IFPLOT.EQ.4) CALL PLOT (0.0,-PLTSE,-3)
    IF (IFPLOT.EQ.0.OR.IFPLCT.EQ.4) GO TO 140
    IKDUM=0
    IF ((AIRANG(IRLE,1)-AIRANG(IRTE,1)).LT.0.) IKDUM=1
    IF (IFPLOT.EQ.1.OR.IFPLCT.EQ.3) CALL FQ (ISTAK,PLTSE,1,TITLE,IKDU
    1M,IFPLOT)
140 DO 465 J=1,NLINES
    DO 145 I=IRLE,IRTE
    KPT=KPTS(I)
145 CALL D1 (RSTA(1,I),XSTA(1,I),KPT,R(I),XHERE(I),1,0)
    X(1)=XHERE(IRLE)
    X(10)=XHERE(IRTE)
    AX=(X(10)-X(1))/99.0
    DO 150 I=2,99
150 X(I)=X(I-1)+AX
    ICORIT=IRTE-IRLE+1
    CALL CQ (XHERE(IRLE),R(IRLE,J),ICORIT,X,XGUM,YPRIME,100,1)
    SS(1)=0.0
    DO 155 I=2,100
155 SS(I)=SS(I-1)+AX*SQRT(1.0+((YPRIME(I)-YPRIME(I-1))/2.0)**2)
    XJ=J
    CALL D1 (ZR,RLE,NSPEC,XJ,YZERO,1,0)
    CALL D1 (ZR,TC,NSPEC,XJ,T,1,0)
    CALL D1 (ZR,TE,NSPEC,XJ,YCNE,1,0)

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A 990
A 995
A 1000

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CALL D1 (ZR,DELX,NSFEC,XJ,XDEL,1,0)
CALL D1 (ZR,DELY,NSFEC,XJ,YDEL,1,0)
CALL D1 (ZR,ZZ,NSPEC,XJ,Z,1,0)
CALL D1 (ZR,YA,NSPEC,XJ,SSOLID,1,0)
CALL D1 (ZR,SDIVR,NSPEC,XJ,SDR,1,0)
CALL D1 (ZR,YB,NSPEC,XJ,DELSDR,1,0)
CALL D1 (ZR,YC,NSPEC,XJ,RELEMN,1,0)
CALL D1 (ZR,YE,NSPEC,XJ,ACCIFF,1,0)
IJ=IFPASS-1
LMN=0
IJK=-1
PRNT=0.
XSIGN=NSIGN
STAGER=(AIRANG(IRLE,J)+AIRANG(IRTE,J))/2.
RINSCL=(R(IRLE,J)+R(IRTE,J))/2.
SOR1=SOR
CHORC=SS(100)/COS(STAGER/C1)
IF (IPRINT.NE.0.AND.IPRINT.NE.1) GO TC 170
IF (IJK.EQ.3) WRITE (LOG2,165) SOR
FORMAT (1H1,9X,15HOFTIMAL SECTION,/,1CX,15(1H*),/,10X,11HFINAL S/
1R =,F8.4,/,10X,23HITERATIONS ON SOLICITY )
SOLID=CHORO/RINSOL/2./PI*FLCAT(NBLADE)
CALL D1 (RING,XINC,AINC,R(IRLE,J),TEMP2,1,0)
CALL D1 (RING,DELDEV,NINC,R(IRLE,J),TEMP3,1,0)
BETMET(1)=AIRANG(IRLE,J)-XSIGN*TEMP2(1)
BETS=AIRANG(IRLE,J)*XSIGN
DO 175 K=1,5
CALL D1 (F137B,F161[(1,K),8,BETS,EXB(K),1,0)
CALL D1 (F137E,F195P(1,IFCA),8,BETS,XPS,1,0)
CALL D1 (F137B,F161[7B,8,BETS,XTEMP,1,0)
CALL D1 (ZR,TC,NSPEC,XJ,X1,1,0)
CALL D1 (F142TC,F172K,7,X1,XKOT,1,0)
BETS=8BETMET(1)*XSIGN
NN=0
NN=NN+1
IF (NN.GT.20) GO TO 700
CALL C1 (F137S,EXB,5,SCLIC,CO,1,1)
XMM=XMS/SOLID+XTEMP(1)
DEV={CO*XKOT*XKSHPE+XMM*(BETS-XSIGN*AIRANG(IRTE,J))+TEMP3(1)}*1.0/
1(1.-XMM)

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185 IF (IJK.EQ.3.AND.IPRINT.NE.2) WRITE (LOG2,185) NN,DEV,SCLIC
    FORMAT (33X,10HITERATION ,I2,3X,11HDEVIATION =,F7.3,3X,10HSOLIORITY
1    =,F7.4)
    HN=IRTE-IRLE+1
    BETMET(MN)=AIRANG(IFTE,J)-DEV*XSIGN
    S1(1)=0.
190 DO 205 I=1,NSTNS
    IF (I-IRLE) 205,205,190
195 IF (IRTE-I) 205,205,195
    L=I-IRLE+1
    CALL D1 (X,SS,100,XFERE(I),S1(L),1,1)
    S1(L)=S1(L)/SS(100)
    DO 200 K=1,NRADEV
200 CALL D1 (SH(1,K),DEVCRV(1,K),NPIS(K),S1(L),DEVVRAD(K),1,0)
    CALL D1 (RADEV,DEVVRAD,NRADEV,R(IRTE,J),DEVPCT,1,0)
    BETMET(L)=AIRANG(I,J)-DEV*DEVPCT*XSIGN
    CONTINUE
205 S1(MN)=1.
    YP1=TAN(BETMET(1)/C1)
    YMPRME(1)=YP1
    YU(1)=0.
    IPOINT=1
    SU(1)=0.
    Y1=0.
    YPP1=SDR/2./PI/R(IRLE,J)*FLOAT(NBLADE)*(1.+YP1*YP1)**(1.5)
    YPPME(1)=YPP1
    IF (YPP1.NE.0.) GO TO 210
    YPRIME(1)=1000.
    GC TC 215
210 CONTINUE
    YPRIME(1)=(1.+YMPRME(1)*YMPRME(1))**(1.5)/YPPME(1)
215 CONTINUE
    S11=0.
    S12=0.
    LL(1)=0
    DO 230 K=2,MN
    YP2=TAN(BETMET(K)/C1)
    LL(K)=0
    S2=S1(K)
    S22=S2*S2

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A1005
A1010
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A1170
A1175
A1180
A1185
A1190
A1195
A1200

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A1205 A=(YF2-YP1-YPP1*(S2-S11))/3./(S22-S12-2.*S11*(S2-S11))
A1210 B=(YPP1-6.*A*S11)/2.
A1215 C=Y1-3.*A*S12-2.*B*S11
A1220 D=Y1-A*S12*S11-B*S12-C*S11
A1225 SDIFF=(S2-S11)/FLOAT(ISEGFT-1)
A1230 KL=IFPOINT+1
A1235 KJ=IFPOINT+ISEGFT-1
A1240 DO 225 L=KL,KJ
A1245 SU(L)=SU(L-1)+SDIFF
A1250 YU(L)=D+SU(L)*(C+SU(L))*(B+A*SU(L))
A1255 YMPRME(L)=C+SU(L)*(E*2.+A*3.*SU(L))
A1260 YPPME(L)=6.*A*SU(L)+2.*E
A1265 IF (YPPME(L).EQ.0.) YPRIME(L)=1000.
A1270 IF (YFPME(L).EQ.0.) GO TO 225
A1275 YPRIME(L)=(1.+YMPRME(L)*YMPRME(L))*(.1.5)/YFPME(L)
A1280 SLPE=ABS(YFPME(L)-YFPME(L-1))
A1285 IF (SLPE.GE.ABS(YPPME(L)).AND.SLPE.GE.ABS(YFPME(L-1))) GO TO 220
A1290 GO TO 225
A1295 LL(K)=L
A1300 CONTINUE
A1305 IPOINT=KJ
A1310 Y1=YU(IPOINT)
A1315 YP1=YPPME(KJ)
A1320 S11=S2
A1325 S12=S22
A1330 YF1=YF2
A1335 IS=0
A1340 DO 235 K=1,MN
A1345 IF (LL(K).NE.0) IS=IS+1
A1350 CONTINUE
A1355 CHORD1=SQRT(YU(IPOINT)**2+1.)*SS(100)
A1360 CALL D1 (SU,YU,IPOINT,SSOLID,YSOLID,1,1)
A1365 CHORC=SQRT((SU(IPOINT)-SSCLID)**2+(YU(IPOINT)-YSOLID)**2)*SS(100)
A1370 SOLIC1=CHORD/RINSOL/2./PI*FLOAT(NBLADE)
A1375 DIFF=SCLID-SOLIE1
A1380 IF (ABS(DIFF).LT.SOLTOL*SCLID) GO TO 240
A1385 SOLIC=SOLID1
A1390 GO TO 180
A1395 IF (IJK.EQ.3.AND.IPFRINT.NE.2) WRITE (LOG2,185) NN,DEV,SCLID1
A1400 IF (IJK.EQ.3) GC TO 305

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A1595
A1600

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LMN=LMN+1
NOINF(LMN)=IS
SDRARR(LMN)=SDR
SOR=SDR+DELSDR
RDMIN(LMN)=1000.
DO 245 L=1,IPCINT
IF (L.EQ.1.AND.RDLE.N.EQ.1.0) GO TO 245
IF (ABS(YPRIME(L)).LT.RCHIN(LMN)) RDMIN(LMN)=ABS(YPRIME(L))
CONTINUE
245 IF (LMN.LE.IJ.AND.IJK.LE.0) GO TO 160
IF (LMN.GT.IJ.AND.IJK.LE.0) GO TO 250
IF (LMN.GT.19) GO TC 250
GO TO 160
IF (LMN.EQ.20.OR.LMN.EQ.IPASS) IJK=IJK+1
IF (IJK.EQ.20.OR.IJK.EQ.3) GC TO 290
NMNINF=20
DO 255 LMN=1,IPASS
IF (NOINF(LMN).LT.NMNINF) IFIRST=LMN
IF (NCINF(LMN).LT.NMNINF) NMNINF=NOINF(LMN)
CONTINUE
IF (IPRINT.NE.0.AND.IPRINT.NE.1) GO TC 275
WRITE (LOG2,85)
IF (FLOAT(NMNINF).GE.(ACDIFF+1)).AND.IPRINT.NE.2) WRITE (LOG2,260)
1
260 FORMAT (74H NOTE THAT THE MINIMUM NUMBER OF INFLECTION POINTS IS G
1 GREATER THAN DESIRED,/2X)
INDEX=IJK+1
WRITE (LOG2,265) J,INDEX,SDR1,DELSDR
265 FORMAT (5X,14HSTREA*SURFACE ,I2,/10X,10HITERATION ,I2,/ ,10X,12(1H*
1),/,10X,14HINITIAL S/R = ,F8.4,10X,17HINCREMENTAL S/R =,F8.4,/,/,1
25X,8HPASS RC.,5X,21HNO. OF INFLECTION PTS,5X,24HMIN. RADIUS CF CUR
3VATURE,/,2X)
WRITE (LOG2,270) (L,N,NCINF(LMN),RDMIN(LMN),LMN=1,IPASS)
270 FORMAT (18X,I2,18X,I2,22X,F8.3)
ILAST=0
DO 280 LMN=IFIRST,IPASS
IF (NCINF(LMN).GT.NMNINF) ILAST=LMN
IF (NCINF(LMN).GT.NMNINF) GC TO 285
CONTINUE
280 ILAST=IPASS

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285 IF (IJK.EQ.0) IFIRST=IFIRST-1
    IF (IFIRST.EQ.0) IFIRST=1
    IF (IFIRST.EQ.IPASS) IFIRST=IJ
    IF (IJK.EQ.1.ANC.NCINF(IPASS).GT.NMNINF) ILAST=ILAST-1
    IF (ILAST.EQ.IFIRST) ILAST=ILAST+1
    IF (ILAST.EQ.(IPASS+1).CR.ILAST.EQ.0) ILAST=IFASS
    IF (IJK.EQ.0) LJ=IPASS-1
    IF (IJK.EQ.1) LJ=19
DELSR=(SDRARR(ILAST)-SCRARR(IFIRST))/FLOAT(LJ)
SDR=SDRARR(IFIRST)
SDR1=SDR
LMN=0
GO TC 160
RADMX=0.
DO 295 L=1,20
    IF (RDMIN(L).GT.RADMX.AND.NCINF(L).EQ.NMNINF) LMN=L
    IF (RDMIN(L).GT.RADMX.AND.NCINF(L).EQ.NMNINF) RADMX=RDMIN(L)
295 CONTINUE
    IF (LMN.EQ.1.ANC.IPRINT.NE.2) WRITE (LOG2,300)
    IF (LMN.EQ.20.AND.IPRINT.NE.2) WRITE (LOG2,300)
    FORMAT (//101H THE MAXIMUM VALUE OF THE MINIMUM RADIUS OF CURVATUR
300 1E OCCURS AT AN END POINT OF THE PRESENT S/R RANGE)
    IF (IJK.EQ.3) SDR=SCRARR(LMN)
    IF (IJK.EQ.3) PRNT=1.
    IF (IJK.EQ.3) GC TO 160
SDR=SDRARR(LMN)-3.0*DELSDR
DELSR=6.*DELSDR/20.
LMN=C
GO TC 160
305 IF (IPRINT.NE.0.AND.IPRINT.NE.1) GO TC 320
    WRITE (LOG2,310)
310 FORMAT (/10X,5HPOINT,5X,22HNORMALIZED MERIDIONAL,5X,10HTANGENTIAL
    1,5X,11HCAMBER LINE,7X,6HSECND,7X,9HRADIUS OF,/,26X,10HCOORDINATE,
    211X,10HCOORDINATE,8X,5HSLCPE,8X,10HDERIVATIVE,5X,9HCURVATURE,/,2X)
    IP=IFPOINT
    IF (IPOINT.GE.49) IF=48
    WRITE (LOG2,315) (L,SU(L),YU(L),YMPRME(L),YFFME(L),YFRIME(L),L=1,I
    1P)
    IF (IPOINT.GE.49) WRITE (LOG2,85)
    IF (IPCINT.GE.49) WRITE (LOG2,315) (L,SU(L),YU(L),YMPRME(L),YPPME(

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315 1L), YPRIME(L), L=49, IFOINT)
320  FORMAT (12X, I2, 14X, F6.4, 14X, F7.4, 6X, F8.4, 5X, F8.4, 7X, F8.3)
      NPOINT=IPGINT
      XNORMC=CHORC1/SS(10C)
      AXIALC=SS(100)
      DO 325 I=1, NSTNS
      KFT=KPTS(I)
325  CALL D1 (RSTA(1,I), XSTA(1,I), KPT,R(I,J), XHERE(I), 1, 0)
      X(1)=XHERE(1)
      X(10C)=XHERE(NSTNS)
      AX=(X(100)-X(1))/99.0
      DO 330 I=2, 99
330  X(I)=X(I-1)+AX
      CALL CQ (XHERE, R(1,J), NSTNS, X, XDUM, YPRIME, 100, 1)
      CALL CQ (XHERE, R(1,J), NSTNS, XHERE, XDUM, TANFI(1,J), NSTNS, 1)
      CS(1)=0.0
      DO 335 I=2, 100
335  SS(I)=SS(I-1)+AX*SQRT(1.0+((YPRIME(I)+YPRIME(I-1))/2.0)**2)
      CALL D1 (X, SS, 100, STACKX, EX, 1, 1)
      CALL 8Q (J, YS, YP, XS, XP, YSEMI, XSEMI, LOG2, IFOINT, IPRINT, BETMET(1), BE
1TRET(M,N), YZERC, T, YCNE, XCEL, YDEL, Z, XNORMC, LNCT, XTEMP, YPRIME, RAD, SIG
2NA, EPZ, XHERE, X, SS, NSTNS, R, BX, SU, YU, YMFRME, AXIALC, ISTAK)
      CALL D1 (X, SS, 100, STACKX, EX, 1, 1)
      DO 340 I=1, 100
      X(I)=X(I)-STACKX
340  SS(I)=SS(I)-BX
      DO 345 I=1, NSTNS
345  XHERE(I)=XHERE(I)-STACKX
      IF (IFPLCT.EQ.0.OR.IFPLCT.EQ.2.OR.IFPLCT.EQ.4) GO TO 365
      XPLOT=XS(J,1)*SCALE
      YPLOT=YS(J,1)*SCALE
      CALL FLCT (XPLOT, YPLOT, 3)
      DO 350 I=2, NPOINT
      XPLOT=XS(J,I)*SCALE
      YPLOT=YS(J,I)*SCALE
350  CALL FLCT (XPLOT, YPLOT, 2)
      DO 355 II=1, NPOINT
      I=NPCINT-II+1
      XPLOT=XP(J,I)*SCALE
      YPLOT=YP(J,I)*SCALE

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355 CALL FLCT (XPLOT,YPLOT,2)
DO 360 I=2,30
XPLOT=XSEMI(J,I)*SCALE
YPLOT=YSEMI(J,I)*SCALE
360 CALL FLCT (XPLOT,YPLOT,2)
XPLOT=XS(J,1)*SCALE
YPLOT=YS(J,1)*SCALE
365 CALL FLCT (XPLOT,YPLOT,2)
IJDUM=0
DO 370 I=1,NSTNS
IF (IFANGS(I).EQ.1) IJDUM=1
370 CONTINUE
IF (IJDUM.EQ.0) GO TO 380
CALL D1 (SS,X,100,XTEMP,XTEMP,100,1)
DO 375 I=1,NSTNS
CALL D1 (XTEMP,SIGMA,100,XHERE(I),THETA(J,I),1,1)
CALL D1 (XTEMP,YPRIME,100,XHERE(I),ALPHA(J,I),1,1)
ZCAME(J,I)=R(I,J)*CCS(THETA(J,I))
YCAME(J,I)=R(I,J)*SIN(THETA(J,I))
375 DO 385 I=1,NPOINT
XTEMP(I)=XS(J,I)
380 CALL C1 (SS,X,100,XTEMP,XTEMP,NPOINT,1)
385 CALL D1 (XHERE,R(1,J),NSTNS,XTEMP,RAD,NPOINT,0)
K=1
DO 390 I=1,NPCINT
EPS=EPZ(I,K)
ZS(J,I)=RAD(I)*COS(EPS)
YS(J,I)=RAD(I)*SIN(EPS)
390 XS(J,I)=XTEMP(I)
DO 395 I=1,NPCINT
XTEMP(I)=XP(J,I)
395 CALL D1 (SS,X,100,XTEMP,XTEMP,NPOINT,1)
CALL D1 (XHERE,R(1,J),NSTNS,XTEMP,RAD,NPOINT,0)
K=2
DO 400 I=1,NPCINT
EPS=EPZ(I,K)
ZP(J,I)=RAD(I)*COS(EPS)
YP(J,I)=RAD(I)*SIN(EPS)
400 XP(J,I)=XTEMP(I)
DO 405 I=1,31

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405 XTEMP(I)=XSEMI(J,I)
CALL O1 (SS,X,100,XTEMP,XTEMP,31,1)
CALL O1 (XHERE,R(1,J),NSTNS,XTEMP,RAD,31,0)
K=3
DO 410 I=1,31
EPS=EPZ(I,K)
ZSEMI(J,I)=RAD(I)*CCS(EFS)
YSEMI(J,I)=RAD(I)*SIN(EFS)
XSEMI(J,I)=XTEMP(I)
IF (IPRINT.EQ.2) GO TO 465
IF (LNCT.LE.50) GO TO 415
WRITE (LOG2,85)
LNCT=1
415 LNCT=LNCT+5
WRITE (LOG2,420) J
420 FORMAT (2X,/,10X,38FCARTESIAN COORDINATES ON STREAMSURFACE,I3,/,1
10X,8HPOINT NO,5X,2HZS,12X,2HXS,12X,2HZP,12X,2HXP,12X,2HYP
2,/,2X)
I=1
425 WRITE (LOG2,430) I,ZS(J,I),XS(J,I),YS(J,I),ZP(J,I),XF(J,I),YF(J,I)
430 FORMAT (10X,I5,3X,1F3E14.5,4X,1P3E14.5)
I=I+1
LNCT=LNCT+1
IF (I.GT.NFCINT) GO TO 440
IF (LNCT.LE.59) GO TO 425
WRITE (LOG2,435)
435 FORMAT (1H1,9X,8HPOINT NO,5X,2HZS,12X,2HXS,12X,2HYS,16X,2HZP,12X,2
1HXP,12X,2HYP,/,2X)
LNCT=2
GO TO 425
440 IF (LNCT.LE.50) GO TO 445
WRITE (LOG2,85)
LNCT=1
445 LNCT=LNCT+3
WRITE (LOG2,450)
450 FORMAT (2X,/,10X,8HPOINT NO,4X,5HZSEMI,9X,5HXSEMI,9X,5IYSEMI,/,2X)
I=1
455 WRITE (LOG2,460) I,ZSEMI(J,I),XSEMI(J,I),YSEMI(J,I)
460 FORMAT (10X,I5,3X,1F3E14.5)
I=I+1

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LNCT=LNCT+1
IF (I.GT.31) GO TO 465
IF (LNCT.LE.59) GO TO 455
WRITE (LOG2,85)
WRITE (LOG2,450)
LNCT=4
GO TO 455
465 CONTINUE
IF (IPRINT.EQ.1) GO TO 530
VOL=0.0
DO 470 J=2,NLINES
VOL=VOL+((XS(J,1)-XP(J,1))**2+(YS(J,1)-YF(J,1))**2)+(XS(J-1,1)-X
1P(J-1,1))**2+(YS(J-1,1)-YF(J-1,1))**2)*(ZS(J,1)+ZP(J,1)-ZS(J-1,1)
2-ZP(J-1,1))*PI/32.0
DO 470 I=2,NPCINT
VOL=VOL+((SQRT((XS(J,I)-XF(J,I))**2+(YS(J,I)-YF(J,I))**2)+SQRT((XS
1(J,I-1)-XP(J,I-1))**2+(YS(J,I-1)-YP(J,I-1))**2))*(SQRT((XS(J,I-1)-
2XS(J,I))**2+(YS(J,I-1)-YS(J,I))**2)+SQRT((XP(J,I-1)-XP(J,I))**2+(Y
3P(J,I-1)-YP(J,I))**2)+(SQRT((XS(J-1,I)-XF(J-1,I))**2+(YS(J-1,I)-Y
4P(J-1,I))**2)+SQRT((XS(J-1,I-1)-XF(J-1,I-1))**2+(YS(J-1,I-1)-YP(J-
5I,I-1))**2))*(SQRT((XS(J-1,I-1)-XP(J-1,I))**2+(YS(J-1,I-1)-YS(J-1,
6I))**2)+SQRT((XP(J-1,I-1)-XF(J-1,I))**2+(YP(J-1,I-1)-YP(J-1,I))**2
7)))*(ZS(J,I)+ZS(J,I-1)+ZP(J,I)+ZP(J,I-1)-ZS(J-1,I)-ZS(J-1,I-1)-ZP(
8J-1,I)-ZP(J-1,I-1))/32.0
IF (LNCT.LE.56) GO TO 475
LNCT=1
WRITE (LOG2,85)
LNCT=LNCT+4
475 WRITE (LOG2,480) VOL
480 FORMAT (2X,/,2X,/,4CX,25HVOLUME OF BLADE SECTION =,1FE11.4,/,40X,3
16(1H*))
IF (IJDUM.EQ.0) GO TO 530
WRITE (LOG2,85)
WRITE (LOG2,485)
FORMAT (43X,43HBLADE CALCULATIONS FOR AERODYNAMIC ANALYSIS,/,43X,4
13(1H*))
IDUM=7
LNCT=3
DO 525 I=1,NSTNS
485 IF (IFANGS(I).EQ.0) GO TO 525

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DO 495 J=1,NLINES
CALL D1 (RSTA(1,I),XSTA(1,I),KPTS(I),R(I,J),XDUM,1,0)
CALL C0 (RSTA(1,I),XSTA(1,I),KPTS(I),R(I,J),XDUM,ZR(J),1,1)
DO 490 K=1,NPOINT
SS(K)=XS(J,K)
RAD(K)=YS(J,K)
XTEMP(K)=XP(J,K)
X(K)=YP(J,K)
XDUM=XDUM-STACKX
CALL D1 (SS,RAD,NPOINT,XDUM,YY1,1,1)
CALL D1 (XTEMP,X,NPCINT,XCUM,YY2,1,1)
W1=YY1/R(I,J)
W2=YY2/R(I,J)
TC(J)=ABS(ATAN(W1/SCRT(1.-W1**2))-ATAN(W2/SCRT(1.-W2**2)))/(2.*PI)
1*FLOAT(NBLADE)
CONTINUE
CALL C0 (ZCAMB(1,I),YCAMP(1,I),NLINES,ZCAMP(1,I),XDUM,RLE,NLINES,1)
1)
IF (LNCT+IDUM+NLINES.LE.59) GO TO 500
WRITE (LOG2,85)
LNCT=2
LNCT=LNCT+IDUM+NLINES
WRITE (LOG2,505) I,NLINES
FORMAT (//,48X,8HSTATION,I2,5X,17HNUMBER OF RADII=,I2,/,36X,6H
1RADIUS,5X,7HSECTION,6X,4HLEAN,9X,5HBLADE,7X,5H-THETA,/,48X,5HANGLE,
26X,5HANGLE,7X,8HBLOCKAGE,/,2X)
DO 510 J=1,NLINES
EPS=(THETA(J,I)-ATAN(RLE(J)))*C1
ALPH5=ALPHA(J,I)
ALP=(ATAN((TANPHI(I,J)*TAN(EPS/C1)+ALPH5*SCRT(1.+TANPHI(I,J)**2)))/
1(1.-TANPHI(I,J)*ZR(J)))*C1
WRITE (LOG2,515) R(I,J),ALP,EPS,TC(J),THETA(J,I)
IF (IFUNCH.EQ.0) GO TO 510
WRITE (LOG3,520) R(I,J),ALP,EPS,TC(J),THETA(J,I),I,J
CONTINUE
510
515
520
525
530
FORMAT (30X,5F12.4)
FORMAT (5F12.7,2I3)
CONTINUE
IF (IFPLCT.LT.2.0R. IFPLCT.EG.4) GC TO 535
CALL FQ (ISTAK,PLTSSZ,2,TITLE,IKDUM,IFPLOT)

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535 IF (IPRINT.EQ.1) GO TO 545
    LNCT=2
    WRITE (LOG2,540)
540 FORMAT (1H1,27X,74HBLADE SURFACE GEOMETRY IN CARTESIAN COORDINATES
1 AT SPECIFIED VALUES OF 'Z',/,28X,74H*****
2*****
545 IF (IPRINT.EQ.1.AND.IFPLOT.LE.1) GO TC 695
    XZ=NZ-1
    OZ=(ZOUTER-ZINNER)/XZ
    ZOUT(1)=ZINNER
    DO 550 J=3,NZ
    ZOUT(J-1)=ZOUT(J-2)+OZ
    ZOUT(NZ)=ZCUTER
    DO 555 I=1,NPOINT
    CALL O1 (ZS(1,I),XS(1,I),NLINES,ZOUT,TEMP1,NZ,0)
    CALL C1 (ZS(1,I),YS(1,I),NLINES,ZCUT,TEMP2,NZ,0)
    CALL D1 (ZP(1,I),XP(1,I),NLINES,ZCUT,TEMP3,NZ,0)
    CALL O1 (ZP(1,I),YP(1,I),NLINES,ZOUT,TEMP4,NZ,0)
    DO 555 J=1,NZ
    XS(J,I)=TEMP1(J)
    YS(J,I)=TEMP2(J)
    XP(J,I)=TEMP3(J)
    YP(J,I)=TEMP4(J)
    DO 560 I=1,31
    CALL C1 (ZSEMI(1,I),XSEMI(1,I),NLINES,ZCUT,TEMP1,NZ,0)
    CALL O1 (ZSEMI(1,I),YSEMI(1,I),NLINES,ZCUT,TEMP2,NZ,0)
    DO 560 J=1,NZ
    XSEMI(J,I)=TEMP1(J)
    YSEMI(J,I)=TEMP2(J)
    DO 650 J=1,NZ
    RD=SGRT((XS(J,1)-XP(J,1))**2+(YS(J,1)-YP(J,1))**2)/2.0
    AREA=PI*RD**2/2.0
    BETA1=ATAN((YS(J,2)+YP(J,1)-YS(J,1)-YP(J,1))/(XS(J,2)+XF(J,2)-XS(J,1,1)-XP(J,1)))
    XINT=AREA*((XP(J,1)+XS(J,1))/2.0-COS(BETA1))*4.0/(3.0*PI)*RD)
    YINT=AREA*((YP(J,1)+YS(J,1))/2.0-SIN(BETA1))*4.0/(3.0*PI)*RC)
    DO 565 I=2,NPOINT
    DELA=(SQRT((XS(J,I)-XP(J,I))**2+(YS(J,I)-YP(J,I))**2)+SQRT((XS(J,I,1-1)-XF(J,I-1))**2+(YS(J,I-1)-YP(J,I-1))**2)+SQRT((XF(J,I-1)-XP(J,I))**2+(YP(J,2,I)-YF(J,I-1))**2))

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3 I-1) -YP(J,I))**2)/4.0
AREA=AREA+DELA
XINT=XINT+DELA*(XS(J,I)+XS(J,I-1)+XP(J,I)+XP(J,I-1))/4.0
YINT=YINT+DELA*(YS(J,I)+YS(J,I-1)+YP(J,I)+YP(J,I-1))/4.0
YINT=YINT/AREA
XINT=XINT/AREA
X1=(XS(J,1)+XP(J,1))/2.
Y1=(YS(J,1)+YP(J,1))/2.
T1=SGRT((XS(J,1)-XP(J,1))**2+(YS(J,1)-YP(J,1))**2)
F=0.
U=0.
DO 570 I=2,NPCINT
T2=SGRT((XS(J,I)-XP(J,I))**2+(YS(J,I)-YP(J,I))**2)
X2=(XS(J,I)+XP(J,I))/2.
Y2=(YS(J,I)+YP(J,I))/2.
DELU=SGRT((X2-X1)**2+(Y2-Y1)**2)
U=U+CELU
TAV3=(T1**3+T2**3)/2.
F=F+TAV3*DELU

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565

570

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TORCCN=((1./3.)**F)/(1.+(4./3.))*F/AREA/U**2)
IX=0.0
IY=0.0
IXY=0.0
DO 575 I=2,NPCINT
XD=(SGRT((XS(J,I-1)-XP(J,I-1))**2+(YS(J,I-1)-YP(J,I-1))**2)+SGRT((
1 XS(J,I)-XP(J,I))**2+(YS(J,I)-YP(J,I))**2))/2.0
YD=(SGRT((XS(J,I)-XP(J,I))**2+(YS(J,I)-YP(J,I))**2)+SGRT((XP(J
1,I)-XP(J,I-1))**2+(YP(J,I)-YP(J,I-1))**2))/2.0
IXD=YD*YD*YD/XD/12.0
IYD=XD*XD*XD/YD/12.0
ANG=ATAN((YS(J,I)+YP(J,I)-YS(J,I-1)-YP(J,I-1))/(XP(J,I)+XS(J,I))-XP
1 (J,I-1)-XS(J,I-1))
COSANG=COS(2.0*ANG)
IXN=(IXD+IYD+(IXD-IYD)*COSANG)/2.0
IYN=(IXD-IYD-(IXD-IYD)*COSANG)/2.0
IXYN=0.0
IF (ANG.NE.0.0) IXYN=((IXN-IYN)*COSANG-IXC+IYD)/(2.0*SIN(2.0*ANG))

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A3205 DELA=XC*YD
A3210 YMN=(YS(J,I)+YS(J,I-1)+YP(J,I)+YP(J,I-1))/4.0-YINT
A3215 XMN=(XS(J,I)+XS(J,I-1)+XP(J,I)+XP(J,I-1))/4.0-XINT
A3220 IX=IX+IXN+DELA*YMN*YMN
A3225 IY=IY+IYN+DELA*XMN*XMN
A3230 IXY=IXY+IXYN+DELA*Y*YMN*XMN
A3235 ANG=ATAN(2.0*IXY/(IY-IX))
A3240 IPX=(IX+IY)/2.0+(IX-IY)/2.0*COS(ANG)-IXY*SIN(ANG)
A3245 IPY=(IX+IY)/2.0-(IX-IY)/2.0*COS(ANG)+IXY*SIN(ANG)
A3250 ANG=ANG/2.0*C1
A3255 IF (LPRINT.EQ.1) GO TO 64C
A3260 IF (LNCT.LE.45) GO TO 580
A3265 WRITE (LOG2,85)
A3270 LNCT=1
A3275 LNCT=LNCT+16
A3280 WRITE (LOG2,585) J,ZOUT(J),AREA,XINT,YINT,IX,IY,IPX,ANG,IPY,AN
A3285 16
A3290 1*****2X,/,50X,14*SECTICN NUMEER,I3,3X,5H,Z',=,F9.4,/,50X,34H***
A3295 22HSECTION AREA,26X,1H=,1PE12.4,/,45X,20HLOCATION OF CENTRIC,11X,1
A3300 34HXBAR,3X,1H=,E12.4,/,45X,22HRELATIVE TO STACK AXIS,9X,4HYBAR,3X,1
A3305 4H=,E12.4,/,45X,22HSECOND MOMENTS OF AREA,9X,2HIX,5X,1H=,E12.4,/,4
A3310 55X,14HABOUT CENTROID,17X,2HIY,5X,1H=,E12.4,/,76X,3HIXY,4X,1H=,E12.
A3315 64,/,45X,24HPRINCIPAL SECCNC MOMENTS,7X,3HIFX,4X,1H=,E12.4,4H(AT,
A3320 70PF7.2,21H DEGREES TO 'X' AXIS),/,45X,22HCF AREA ABOUT CENTROID,9X
A3325 8,3HIFY,4X,1H=,1FE12.4,4H(AT,0PF7.2,21H DEGREES TO 'Y' AXIS))
A3330 WRITE (LOG2,590) TORCON
A3335 FORMAT (/,45X,18HTORSIONAL CONSTANT,20X,1F=,1PE12.4,/,2X)
A3340 LNCT=LNCT+3
A3345 IF (LNCT.LE.50) GO TO 595
A3350 WRITE (LOG2,85)
A3355 LNCT=1
A3360 LNCT=LNCT+5
A3365 WRITE (LOG2,600)
A3370 FORMAT (2X,/,20X,19*SECTION COORDINATES,/,2X)
A3375 WRITE (LOG2,605)
A3380 FORMAT (31X,8HPCINT NO,5X,2FXS,12X,2HYS,1EX,2FXF,12X,2HYF,/,2X)
A3385 DO 610 I=1,NPOINT
A3390 LNCT=LNCT+1
A3395 IF (LNCT.LE.60) GO TO 610
A3400

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A3405
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A3590
A3595
A3600

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LNCT=4
WRITE (LOG2,85)
WRITE (LOG2,605)
WRITE (LOG2,615) I,XS(J,I),YS(J,I),XP(J,I),YP(J,I)
FORMAT (31X,I5,3X,1F2E14.5,4X,2E14.5)
IF (LNCT.LE.55) GO TO 620
LNCT=1
WRITE (LOG2,85)
LNCT=LNCT+3
WRITE (LOG2,625)
FORMAT (2X,/,31X,8HFPOINT NO,5X,5HXSEMI,9X,5+YSEMI,/,2X)
CO 630 I=1,31
LNCT=LNCT+1
IF (LNCT.LE.60) GO TO 630
WRITE (LOG2,85)
WRITE (LOG2,625)
LNCT=4
WRITE (LOG2,635) I,XSEMI(J,I),YSEMI(J,I)
FORMAT (31X,I5,3X,1F2E14.5)
IF (IFPLCT.LT.2) GO TO 690
IF (IFPLCT.EQ.4) GO TO 660
XPLOT=XS(J,1)*SCALE
YPLOT=YS(J,1)*SCALE
CALL PLOT (XPLOT,YPLOT,3)
DO 645 I=2,NPCINT
XPLOT=XS(J,I)*SCALE
YPLOT=YS(J,I)*SCALE
CALL PLCT (XPLOT,YPLOT,2)
DO 650 II=1,NPOINT
I=NPCINT+1-II
XPLOT=XP(J,II)*SCALE
YPLOT=YF(J,II)*SCALE
CALL PLOT (XPLOT,YPLOT,2)
DO 655 I=2,30
XPLOT=XSEMI(J,II)*SCALE
YPLOT=YSEMI(J,II)*SCALE
CALL FLCT (XPLOT,YPLOT,2)
XPLOT=XS(J,1)*SCALE
YPLOT=YS(J,1)*SCALE
CALL FLCT (XPLOT,YPLOT,2)

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A3605
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A3770
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A3795
A3800

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660 GO TC 690
CALL SYMBOL (19.9,2.0,.175,22HCARTESIAN SECTION NO. ,0.0,22)
XJ=J
CALL NUMBER (23.75,2.,.175,XJ,0.0,-1)
CALL SYMBOL (20.6,1.0,.175,10HSTAGGER = ,0.0,10)
STAGER=ATAN((YS(J,NFOINT)+YF(J,NPOINT))-YS(J,1))-YP(J,1))/(XS(J,NPOI
1NT)+XP(J,NFCINT))-XS(J,1))-XP(J,1))*C1
CALL NUMBER (22.35,1.,.175,STAGER,0.0,3)
CALL FLCT (22.0,5.25,-3)
SINSTG=SIN(STAGER/C1)
CCSSTG=CCS(STAGER/C1)
YPL0T=4.75
XPL0T=4.75*SINSTG/CCSSTG
IF (ABS(XPL0T).LE.22.0) GO TO 665
XPL0T=22.0
YPL0T=-22.0/SINSTG*CCSSTG
CALL FLCT (XPL0T,YPL0T,3)
XPL0T=-XPLCT
YPL0T=-YPLCT
CALL FLCT (XPL0T,YPL0T,2)
XPL0T=22.0
YPL0T=-22.0*SINSTG/COSSTG
IF (ABS(YPL0T).LE.4.75) GC TO 670
YPL0T=-4.75
XPL0T=4.75/SINSTG*CCSSTG
CALL FLCT (XPL0T,YPL0T,3)
XPL0T=-XPLCT
YPL0T=-YPLCT
CALL FLCT (XPL0T,YPL0T,2)
XPL0T=SCALE*(XS(J,1))*CCSSTG+YS(J,1)*SINSTG)
YPL0T=SCALE*(YS(J,1))*COSSTG-XS(J,1)*SINSTG)
CALL FLCT (XPL0T,YPL0T,3)
DO 675 I=2,NPCINT
XPL0T=SCALE*(XS(J,I))*COSSTG+YS(J,I)*SINSTG)
YPL0T=SCALE*(YS(J,I))*COSSTG-XS(J,I)*SINSTG)
CALL FLCT (XPL0T,YPL0T,2)
DO 660 II=1,NFOINT
I=NPCINT+1-II
XPL0T=SCALE*(XP(J,I))*CCSSTG+YP(J,I)*SINSTG)
YPL0T=SCALE*(YP(J,I))*COSSTG-XP(J,I)*SINSTG)

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680 CALL PLCT (XPLOT,YPLOT,2)
DO 685 I=2,30
XPLOT=SCALE*(XSEMI(J,I))*CCSSTG+YSEMI(J,I)*SINSTG)
YPLOT=SCALE*(YSEMI(J,I))*CCSSTG-XSEMI(J,I)*SINSTG)
CALL PLCT (XPLOT,YPLOT,2)
XPLOT=SCALE*(XS(J,1))*COSSSTG+YS(J,1)*SINSTG)
YPLOT=SCALE*(YS(J,1))*COSSSTG-XS(J,1)*SINSTG)
CALL PLCT (XPLOT,YPLOT,2)
CALL PLOT (23.0,-5.25,-3)
CONTINUE
IF (IFPLOT.NE.0) CALL PLOTE
GO TO 710
WRITE (LOG2,705) J
705 FORMAT (10X,8HFAILEC ,I2)
710 CONTINUE
STOP
END

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A3885-

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SUBROUTINE BQ (IBL,YS,YF,XS,XP,YSEMI,XSEMI,LOG2,N,IFPRINT,BETA1,BET
1A2,YZERO,T,YONE,XDEL,YDEL,Z,XNORMC,LNCT,DX,Y,CY,SIGMA,SS1,XHERE,X,
2SS,NSINS,R,BX,XM,YM,AM,AXIALC,ISTAK)
REAL IX,IY,IXY,IPX,IPY,IXC,IYD,IXN,IYN,IXYI
DIMENSION YS(15,81), YF(15,81), XS(15,81), XP(15,61), YSEMI(15,31)
1, XSEMI(15,31), S(81), Y(100), THICK2(81), XM(82), YM(81), AM(81),
2 XHERE(100), X(100), SS(100), R(10,15), DX(100), CY(100), SS1(100,
33), SIGMA(100)
5   FORMAT (1H1)
   PI=3.1415926535
   C1=180.0/PI
   IF (IFPRINT.EQ.2) GO TO 15
10  WRITE (LCG2,10) IBL,BETA1,BETA2,YZERO,T,YCNE,Z,AXIALC
   FORMAT (1H1,44X,43HSTREAMSURFACE GEOMETRY ON STREAMLINE NUMBER,13,
1/45X,46(1H*),/,/20X,5HBETA1,11X,1H=,F7.3,6X,20H(BLADE INLET ANGLE.
2),/,/20X,5HBETA2,11X,1H=,F7.3,6X,21H(BLADE OUTLET ANGLE.),/20X,5HY
3ZERO,11X,1H=,F8.5,5X,51H(BLADE LEADING EDGE RADIUS AS A FRACTION O
4F CHORD.),/20X,1HT,15X,1H=,F8.5,5X,49H(BLADE MAXIMUM THICKNESS AS
5 A FRACTION OF CHORD.),/20X,4HYONE,12X,1H=,F8.5,5X,60H(BLADE TRAI
6LING EDGE HALF-THICKNESS AS A FRACTION CF CHORD.),/20X,1HZ,15X,1H
7=,F7.4,6X,59H(LOCATION CF MAXIMUM THICKNESS AS A FRACTICN CF MEAN
8LINE.),/20X,4HCORD,12X,1H=,F7.4,6X,36H(MERIDICNAL CHORD OF SECTIO
9N.)
15  CHORD=XNORMC/(1.0-YZERO+XNORMC*(YZERO+ABS(YONE*SIN(BETA2/C1))))
   FCSLMN=1.0-CHORD*(YZERO+ABS(YONE*SIN(BETA2/C1)))
   AX=1./99.
   DX(1)=0.
   DO 20 IK=2,100
   DX(IK)=DX(IK-1)+AX
20  CALL D1 (XM,YM,N,DX,DY,100,1)
   SIGMA(1)=0.
   DO 25 K=2,100
   SIGMA(K)=SIGMA(K-1)+SQRT((DX(K)-DX(K-1))**2+(DY(K)-DY(K-1))**2)
25  CALL D1 (DX,SIGMA,100,XP,S,N,1)
   YZERO=YZERC*CHORD/FCSLMN
   YONE=YONE*CHORD/FCSLMN
   T=T*CHORD/FCSLMN
   S(1)=0.0
   AT=(YZERC-T/2.0)/(2.0+Z**2)
   CT=(1/2.0-YZERO)*3.0/(2.0+Z)

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DT=YZERO
ET=(YONE-T/2.0)/(1.0-Z)**3-1.5*(YZERO-T/2.0)/(Z**2*(1.0-Z))
FT=1.5*(YZERO-T/2.0)/Z**2
HT=T/2.0
DO 40 J=1,N
SN=S(J)/S(N)
IF (SN.GT.Z) GO TO 30
THICK2(J)=(AT*SN**2+CT)*SN+DT
GO TO 35
30 SN=SN-Z
THICK2(J)=(ET*SN+FT)*SN**2+FT
FYPR=1./SQRT(1.+AM(J)**2)
YPRIME=AM(J)
XS(1BL,J)=(XM(J)-THICK2(J)*YPRIME*FYPR+YZERO)*FCSLMN
YS(1BL,J)=(YM(J)+THICK2(J)*FYPR)*FCSLMN
XP(1BL,J)=(XM(J)+THICK2(J)*YPRIME*FYPR+YZERO)*FCSLMN
YP(1BL,J)=(YM(J)-THICK2(J)*FYPR)*FCSLMN
AM(J)=ATAN(AM(J))*C1
XM(J)=(XM(J)+YZERO)*FCSLMN
YM(J)=YM(J)*FCSLMN
THICK2(J)=THICK2(J)*FCSLMN
S(J)=S(J)*FCSLMN
YZERC=YZERC*FCSLMN
AREA=PI/2.0*YZERO**2
XINT=YZERO*(1.0-COS(BETA1/C1)*4.0/(3.0*PI))*AREA
YINT=-4.0/(3.0*PI)*YZERO*AREA*SIN(BETA1/C1)
DO 45 J=2,N
DELA=(THICK2(J)+THICK2(J-1))*(S(J)-S(J-1))
AREA=AREA+DELA
XINT=XINT+DELA*(XM(J)+XM(J-1))/2.0
YINT=YINT+DELA*(YM(J)+YP(J-1))/2.0
XBAR=XINT/AREA
YBAR=YINT/AREA
XBARB=XBAR
YBARB=YBAR
YBAR=YBAR+YDEL/AXIALC
XBAR=XBAR+XDEL/AXIALC
CALL D1 (XM,AM,N,DX,SS1(1,1),100,1)
DO 50 IK=1,100
SS1(IK,1)=TAN(SS1(IK,1)/C1)
  
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50      Y(IK)=DY(IK)*FCSLMN
      SIGMA(IK)=DX(IK)*FCSLMN+YZERO
      CALL D1 (SIGMA,Y,100,DX,DY,100,1)
      CALL D1 (SIGMA,SS1(1,1),100,DX,Y,100,1)
      CALL D1 (DX,DY,100,XBAR,XAB,1,1)
      CALL C1 (DX,Y,100,XEAR,XBC,1,1)
      XBAR=XBARB
      YBAR=YBARB
      IX=0.0
      IY=0.0
      IXY=0.0
      CO 55 J=2,N
      DELA=(THICK2(J)+THICK2(J-1))*S(J)-S(J-1)
      IXD=(THICK2(J)+THICK2(J-1))*3*(S(J)-S(J-1))/12.0
      IYD=(THICK2(J)+THICK2(J-1))*S(J)-S(J-1))*3/12.0
      CCSANG=CCS((AM(J)+AM(J-1))/C1)
      IXN=(IXD+IYD+(IXD-IYD)*COSANG)/2.0
      IYN=(IXD+IYD-(IXD-IYD)*COSANG)/2.0
      IXYN=0.0
      IF ((AM(J)+AM(J-1)).NE.C()) IXYN=((IXN-IYN)*CCSANG-IXD+IYD)/(2.0*S
1 IN((AM(J)+AM(J-1))/C1)
      IX=IX+IXN+CELA*((YM(J)+YM(J-1))/2.0-VEAR)**2
      IY=IY+IYN+CELA*((XM(J)+XM(J-1))/2.0-XEAR)**2
      IXY=IXY+IXYN+DELA*(YBAR-(YM(J)+YM(J-1))/2.0)*(XBAR-(XM(J)+XM(J-1)
1/2.0)
      ANG=ATAN(2.0*IXY/(IY-IX))
      IPX=(IX+IY)/2.0+(IX-IY)/2.0*CCS(ANG)-IXY*SIN(ANG)
      IPY=(IX+IY)/2.0-(IX-IY)/2.0*COS(ANG)+IXY*SIN(ANG)
      ANG=ANG/2.0*C1
      STAGER=ATAN(YM(N)/XP(N))*C1
      XNL=XM(N)
      YML=YM(N)
      CAMBER=BETA1-BETA2
      IF (IPRINT.EQ.2) GO TO 95
      LNCI=47
      WRITE (LCG2,60) CHORD, STAGER, CAMBER, AFEA, XBAR, YBAR, IX, IY, IXY, ANG, I
1PX, ANG, IPY, ANG
60      FORMAT (/,16X,100HNCRMALISED RESULTS - ALL THE FOLLOING REFER TO
1ABLACE HAVING A MERIDICNAL CHORC PR3JECTION OF UNITY,/,16X,100(1H*
2),//20X,11HELADE CHCRD,4X,1P=,F7.4,/,//,20X,16HSTAGGER ANGLE =,F7.3

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3, //, 20X, 16HCAMBER ANGLE =, F7.3, //, 20X, 16HSECTION AREA =, F7.5, /
4, //, 20X, 45HLOCATION OF CENTROID RELATIVE TO LEADING EDGE, //, 30X, 6HXB
5AR =, F8.5, //, 30X, 6HYBAR =, F8.5, //, 20X, 37HSECOND MOMENTS CF AREA ABO
6UT CENTROID, //, 30X, 6HIX =, F8.5, //, 30X, 6HIY =, F8.5, //, 30X, 6HIXY
7 =, F8.5, //, 20X, 58HANGLE CF INCLINATION OF (ONE) PRINCIPAL AXIS TO ,
8X, AXIS =, F7.3, //, 20X, 47HPRINCIPAL SECOND MOMENTS OF AREA ABOUT CE
9NTROID, //, 30X, 6HIPX =, F7.5, 6X, 3H(AT, F7.3, 15H WITH 'X' AXIS), //, 30X
$, 6HIY =, F7.5, 6X, 3H(AT, F7.3, 15H WITH 'Y' AXIS), //)
FORMAT (27X, 5HPCINT, 8X, 24HE A N L I N E C A T A, 13X, 23HSURFACE
1COORCINATE DATA, //, 27X, 6HNUMBER, 5X, 1HX, 7X, 1HY, 5X, 15HANGLE THICKNESS
2, 9X, 2HXS, 6X, 2HYS, 6X, 2HXP, 6X, 2HYP, //)
WRITE (LOG2, 65)
DO 75 J=1, N
IF (LNCT.NE.60) GO TO 70
WRITE (LOG2, 5)
WRITE (LOG2, 65)
LNCT=4
LNCT=LNCT+1
TM=THICK2(J)*2.0
70 WRITE (LOG2, 80) J, XM(J), YM(J), AM(J), TM, XS( IBL, J), YS( IBL, J), XF( IBL,
1J), YF( IBL, J)
FORMAT (27X, I3, F13.5, F8.5, F7.3, F8.5, F16.5, 3F8.5)
DO 85 J=1, N
XM(J)=XS( IBL, J)
YM(J)=YS( IBL, J)
AM(J)=XF( IBL, J)
THICK2(J)=YP( IBL, J)
85 WRITE (LOG2, 90) IBL
FORMAT (1H1, 45X, 33HNORMALISED PLOT OF SECTION NUMBER, I3, //, 2X)
90 CALL EQ (N, LOG2, XM, YM, AM, THICK2)
A2=AXIALC**2
A4=A2**2
IX=IX+A4
IY=IY+A4
IXY=IXY+A4
IPX=IPX+A4
IPY=IPY+A4
IF ( ISTAT.GT.1) GO TO 100
XBAR=ISTAK
IF ( ISTAT.EQ.0) YBAR=0.
95

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100 IF (ISTAK.EQ.1) YBAR=YML
    RLE=YZERO*AXIALC
    CHORD=CHORD*AXIALC
    AREA=AREA*A2
    XC=RLE-XBAR*AXIALC-XOEL
    YC=-YBAR*AXIALC-YOEL
    IF (IPRINT.EQ.2) GO TO 120
    WRITE (LOG2,105) CHCRD,RLE,XC,YC,AREA,IX,IY,IFX,ANG,IPY,ANG
    FORMAT (1H1,31X,69HCIMENSIONAL RESULTS - ALL RESULTS REFER TO A BL
105 1ADE CF SPECIFIED CHCRD,/,32X,69H*****
2 *****
3PE12.5,/,20X,10HL.E.RADIUS,/,20X,11HBLADE CHORD,4X,1H=,1
4E13.5,3H Y=,1PE13.5,/,20X,16HSECTION AREA =,1PE12.5,/,20X,37HS
5ECONC MMENTS OF AREA ABOUT CENTROID,/,30X,6HIX =,1PE12.5,/,30X
6,6HIY =,1PE12.5,/,30X,6FIXY =,1PE12.5,/,20X,47HPRINCIPAL SECON
70 MOMENTS OF AREA ABOUT CENTROID,/,30X,6HIPX =,1PE12.5,5H (AT,0
8PF7.3,15H WITH 'X' AXIS),/,30X,6HIPY =.1PE12.5,5H (AT,0PF7.3,15H
9 WITH 'Y' AXIS),/)
    WRITE (LOG2,110)
    WRITE (LOG2,115)
110 FORMAT (124H PT SUCTION-----SURFACE PRESSURE-----SUR
    1RFACE FT SUCTICN-----SURFACE
2FACE)
115 FORMAT (4X,2HNO,8X,1HX,13X,1HY,12X,2HNO,8X,1HX13X,
    1HY,13X,1HX,13X,1HY,/)
    LNCT=24
120 00 135 J=1,N
    XS(1EL,J)=(XS(1BL,J)-XBAR)*AXIALC-XOEL
    YS(1BL,J)=(YS(1BL,J)-YBAR)*AXIALC-YOEL
    XP(1EL,J)=(XP(1BL,J)-XBAR)*AXIALC-XOEL
    YP(1BL,J)=(YP(1BL,J)-YBAR)*AXIALC-YOEL
    IF (IPRINT.EQ.2) GO TO 135
    IF ((J/2)*2.NE.J) GC TO 135
    IF (LNCT.NE.60) GO TO 125
    LNCT=4
    WRITE (LOG2,5)
    WRITE (LOG2,110)
    WRITE (LOG2,115)
125 LNCT=LNCT+1
    JM1=J-1

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```

130 WRITE (LOG2,130) JM1,XS( IBL, JM1),YS( IEL, JM1),XP( IBL, JM1),YP( IBL, JM
135 11),J,XS( IBL,J),YS( IBL,J),XP( IBL,J),YP( IBL,J)
    FORMAT (3X,I3,4(2X,1PE12.5),6X,I3,4(2X,1PE12.5))
    CONTINUE
140 IF (IPRINT.EQ.2) GO TO 150
    IF (LNCT.GT.24) WRITE (LOG2,140)
    FORMAT (1H1)
    IF (LNCT.GT.24) LNCT=2
    LNCT=LNCT+5
145 WRITE (LOG2,145)
    FCRMAT (2X,/,48X,37+POINTS DESCRIBING LEACING EDGE RADIUS,/,48X,9
    1HPPOINT NO.,6X,1HX,13X,1HY,/,2X)
    EPS=BETA1+180.0
    DO 160 J=1,31
150 XSEMI( IBL,J)=XC-RLE*SIN(EFS/C1)
    YSEMI( IBL,J)=YC+RLE*COS(EFS/C1)
    EPS=EPS-6.0
    IF (IPRINT.EQ.2) GO TO 160
    WRITE (LOG2,155) J,XSEMI( IBL,J),YSEMI( IBL,J)
    LNCT=LNCT+1
    FCRMAT (48X,I5,1PE17.5,1PE14.5)
155 CONTINUE
160 SSURF=AXIALC
    SS2=EX-AXIALC*XBAR-XDEL
    SBAR=SS2+AXIALC*XBAR*XB+XDEL
    DO 165 IK=1,100
    SS( IK)=SS( IK)-SBAR
165 CALL D1 (SS,X,100,0.,SBAR,1,1)
    CALL D1 (XHERE,R(1, IBL),NSTNS,SBAR,RXEAR,1,0)
    XBARC=XBAR
    YBARC=YBAR
    XBAR=XBARB+XDEL/AXIALC
    YBAR=YBARB+YDEL/AXIALC
    SS1(1,1)=SS(1)
    S23=AXIALC/99.
    SS(1)=SS(1)+S23
    DO 170 IK=2,100
    SS1( IK,1)=SS( IK)
    SS( IK)=SS( IK-1)+S23
170 SIGMAC=(XAB-YBAR)/RXBAR+AXIALC

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175 00 175 IK=2,100
    IF (XBAR.EQ.OX(IK)) GO TO 185
    IF (XBAR.GT.OX(IK-1).AND.XBAR.LT.OX(IK)) GC TO 190
    CONTINUE
180  WRITE (LOG2,180)
185  FORMAT (1H1,23H XBAR CANNOT BE LOCATED)
    SIGMA(IK)=SIGMAC
    KL=IK+1
    GO TC 195
190  KL=IK
    SIGMA(IK-1)=SIGMAO
195  SSDUM=SS(KL-1)
    SS(KL-1)=0.
    YP1=XBC
    RX1=RXBAR
    DO 200 IK=KL,100
    XSURF=SS2+OX(IK)*SSURF+SS1(1,1)
    CALL D1 (SS1(1,1),X,100,XSURF,XDUM,1,1)
    CALL D1 (SS1(1,1),X,130,XSURF,XDUM,1,1)
    CALL C1 (SS1(1,1),X,100,XSURF,XDUM,1,1)
    CALL D1 (XHERE,R(1,IBL),NSTNS,XDUM,RX2,1,0)
    SIGMA(IK)=SIGMA(IK-1)+(Y(IK)/RX2+YP1/RX1)/2.*(SS(IK)-SS(IK-1))
    YP1=Y(IK)
200  RX1=RX2
    SS(KL-1)=SSDUM
    SSDUM=SS(KL)
    SIGDUM=SIGMA(KL)
    SIGMA(KL)=SIGMAC
    SS(KL)=0.
    RX1=RXEAR
    YP1=XBC
    KM=KL-1
    CO 205 IK=1,KM
    KJ=KL-1K
    XSURF=SS2+OX(KJ)*SSURF+SS1(1,1)
    CALL D1 (SS1(1,1),X,100,XSURF,XDUM,1,1)
    CALL C1 (XPERE,R(1,IBL),NSTNS,XDUM,RX2,1,0)
    SIGMA(KJ)=SIGMA(KJ+1)-(Y(KJ)/RX2+YP1/RX1)/2.*(SS(KJ+1)-SS(KJ))
    YP1=Y(KJ)
205  RX1=RX2
  
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    SIGMA(KL)=SIGDUM
    SS(KL)=SSDUM
    DO 210 IK=1,100
    SS(IK)=SS1(IK,1)
    XBAR=XBARC
    YBAR=YBARC
    DO 215 IK=1,N
    SS1(IK,1)=SS2+((XS( IBL,IK)+XDEL)/AXIALC+XBAR)*SSURF+SS(1)
    SS1(IK,2)=SS2+((XP( IBL,IK)+XDEL)/AXIALC+XEAR)*SSURF+SS(1)
    DO 220 IK=1,31
    SS1(IK,3)=SS2+((XSEMI( IBL,IK)+XDEL)/AXIALC+XBAR)*SSURF+SS(1)
    CALL G1 (SS,X,100,SS1(1,1),SS1(1,1),N,1)
    CALL G1 (SS,X,100,SS1(1,2),SS1(1,2),N,1)
    CALL G1 (SS,X,100,SS1(1,3),SS1(1,3),31,1)
    IF (ISTAK.GT.1) GO TO 230
    IF (ISTAK.EQ.1) SIGMA0=SIGMA(100)
    IF (ISTAK.EQ.0) SIGMA0=SIGMA(1)
    DO 225 IK=1,100
    SIGMA(IK)=SIGMA(IK)-SIGMAC
    225
    DO 235 IK=1,100
    DX(IK)=(OX(IK)-XBAR)*AXIALC-XDEL
    DY(IK)=(OY(IK)-YBAR)*AXIALC-YDEL
    DO 245 MK=1,3
    IF (MK.EQ.3) NNN=31
    IF (MK.EQ.1.OR.MK.EG.2) NFN=N
    DO 240 IK=1,NNN
    IF (MK.EG.1) YP1=YS( IBL,IK)
    IF (MK.EG.2) YP1=YP( IBL,IK)
    IF (MK.EQ.3) YP1=YSEMI( IBL,IK)
    IF (MK.EQ.1) RX1=XS( IBL,IK)
    IF (MK.EQ.2) RX1=XP( IBL,IK)
    IF (MK.EQ.3) RX1=XSEMI( IBL,IK)
    CALL G1 (DX,DY,100,RX1,RXEAR,1,1)
    DELLY=YP1-RXBAR
    CALL G1 (XHERE,R(1, IBL),NSTNS,SS1(IK,MK),FAB,1,0)
    DELSIG=CELLY/RAB
    CALL G1 (DX,SIGMA,100,RX1,XAB,1,1)
    SS1(IK,MK)=XAB+DELSIG
    240
    245
    CONTINUE
    RETURN
    END
  
```



```

SUBRCUTINE CQ (XDATA, YDATA, NDATA, XIN, YOUT, YPRIME, NXY, NNOT)
REAL M
DIMENSION A(65), B(65), D(65), H(65), XDATA(1), YDATA(1), XIN(1),
1 YOUT(1), YPRIME(1)
IF (NDATA-2) 120, 5, 35
IF (NNOT-1) 10, 20, 10
DO 15 I=1, NXY
YOUT(I) = ((YDATA(2) - YDATA(1)) / (XDATA(2) - XDATA(1))) * (XIN(I) - XDATA(1)
1) + YDATA(1)
IF (NNOT) 120, 120, 25
OC 30 I=1, NXY
YPRIME(I) = (YDATA(2) - YDATA(1)) / (XDATA(2) - XDATA(1))
GO TC 120
CONTINUE
E1=1.0
E2=1.0
A(1)=1.0
B(1)=-E1
D(1)=0.0
N=NDATA-1
DC 40 I=2, N
A(I) = (XDATA(I+1) - XDATA(I-1)) / 3.0 - (XDATA(I) - XDATA(I-1)) * B(I-1) / (6.0
1 * A(I-1))
B(I) = (XDATA(I+1) - XDATA(I)) / 6.0
D(I) = (YDATA(I+1) - YDATA(I)) / (XDATA(I+1) - XDATA(I)) - (YDATA(I) - YDATA(I
1-1)) / (XDATA(I) - XDATA(I-1)) * G(I-1) / 6.0 / A(I-1)
A(NDATA) = -E2
B(NDATA) = 1.0
D(NDATA) = 0.0
M(NDATA) = A(NDATA) * D(N) / (A(NDATA) * B(N) - A(N) * B(NDATA))
OC 45 II=2, NDATA
I=NDATA+1-II
M(I) = (D(I) - B(I) * M(I+1)) / A(I)
J=1
I=1
IF (XIN(I) - XDATA(1)) 95, 95, 55
IF (XIN(I) - XDATA(J+1)) 70, 70, 60
IF (J+1 - NDATA) 65, 70, 70
J=J+1
GO TC 55

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C 5
C 10
C 15
C 20
C 25
C 30
C 35
C 40
C 45
C 50
C 55
C 60
C 65
C 70
C 75
C 80
C 85
C 90
C 95
C 100
C 105
C 110
C 115
C 120
C 125
C 130
C 135
C 140
C 145
C 150
C 155
C 160
C 165
C 170
C 175
C 180
C 185
C 190
C 195
C 200

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70 IF (XIN(I)-XDATA(NDATA)) 75,110,110
75 CX=XDATA(J+1)-XDATA(J)
80 IF (NWCT-1) 80,85,8C
85 YOUT(I)=M(J)/(6.0*DX)*XDATA(J+1)-XIN(I))*3+M(J+1)/(6.0*DX)*(XIN(
1I)-XDATA(J))*3+(XDATA(J+1)-XIN(I))*(YDATA(J)/DX-M(J)/6.0*DX)+(XIN
2(I)-XDATA(J))*(YDATA(J+1)/DX-M(J+1)/6.0*DX)
90 IF (NWOT) 85,90,85
95 YPRIME(I)=(-M(J))*(XDATA(J+1)-XIN(I))*2/2.0+M(J+1)*(XIN(I)-XDATA(J
1))*2/2.0+YDATA(J+1)-YDATA(J)/DX-(M(J+1)-M(J))/6.0*DX
I=I+1
95 IF (I-NXY) 50,50,12C
YDASH=(YDATA(2)-YDATA(1))/(XDATA(2)-XDATA(1))- (M(1)/3.0+M(2)/6.0)*
1(XDATA(2)-XDATA(1))
100 IF (NWCT-1) 100,105,100
YOUT(I)=YDATA(1)-YDASH*(XDATA(1)-XIN(I))
105 IF (NWOT) 105,90,105
YPRIME(I)=YDASH
60 TC 90
110 YDASH=(YDATA(NDATA)-YDATA(N))/(XDATA(NDATA)-XDATA(N))+ (M(NDATA)/3.
10+M(N)/6.0)*(XDATA(NDATA)-XDATA(N))
115 IF (NWCT-1) 115,105,115
YOUT(I)=YDATA(NDATA)+YDASH*(XIN(I)-XDATA(NDATA))
120 IF (NWOT) 105,90,105
RETURN
END

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C 205
C 210
C 215
C 220
C 225
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C 235
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C 245
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C 310
C 315
C 320
C 325-

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SUBRCUTINE G1 (XDATA,YDATA,NDATA,XIN,YOUT,NXY,NTYPE)
REAL M
DIMENSION A(15), B(15), C(15), XDATA(1), YDATA(1), XIN(1),
1YOUT(1)
IF (NDATA-1) 5,5,15
DO 10 I=1,NXY
YOUT(I)=YDATA(1)
RETURN
IF (NDATA-2) 25,25,20
IF (NTYPE) 90,90,25
J=1
I=1
IF (XIN(I)-XDATA(2)) 65,65,35
IF (XIN(I)-XDATA(NDATA-1)) 40,70,70
IF (XIN(I)-XDATA(J)) 50,60,45
IF (XIN(I)-XDATA(J+1)) 60,60,50
J=J+1
IF (J-NDATA) 40,55,55
J=1
GO TC 40
YOUT(I)=YDATA(J)+(YDATA(J+1)-YDATA(J))/(XEATA(J+1)-XDATA(J))*(XIN(
1I)-XCATA(J))
GO TC 75
YOUT(I)=YDATA(1)+(YEATA(2)-YDATA(1))/(XDATA(2)-XDATA(1))*(XIN(I)-X
1DATA(1))
GO TC 75
YOUT(I)=YDATA(NDATA-1)+(YDATA(NDATA)-YDATA(NDATA-1))/(XCATA(NDATA)
1-XDATA(NDATA-1))*(XIN(I)-XDATA(NDATA-1))
IF (I-NXY) 80,85,85
I=I+1
GO TC 30
RETURN
A(1)=1.0
B(1)=0.0
D(1)=0.0
N=NDATA-1
DC 95 I=2,N
A(I)=(XDATA(I+1)-XDATA(I-1))/3.0-(XDATA(I)-XDATA(I-1))*E(I-1)/(6.0
1*A(I-1))
B(I)=(XDATA(I+1)-XDATA(I))/6.0
  
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95      D(I)=(YDATA(I+1)-YDATA(I))/(XD*(YDATA(I+1)-YDATA(I))-XDATA(I))-YDATA(I)-YDATA(I
1-1))/(XDATA(I)-XDATA(I-1))-(XDATA(I)-XDATA(I-1))/6.0/A(I-1)
      M(NDATA)=0.0
      DO 100 II=2,N
      I=NDATA+1-II
      M(I)=(D(I)-B(I)*M(I+1))/A(I)
      N(I)=0.0
      J=1
      I=1
      IF (XIN(I)-XDATA(1)) 115,130,110
      IF (XIN(I)-XDATA(NDATA)) 140,135,120
      JP=1
      KP=2
      GO TC 125
      JP=NCATA
      KP=NCATA-1
      YPRIME=(YDATA(KF)-YDATA(JF))/(XDATA(KF)-XDATA(JP))-M(KP)/6.0*(XDATA
1A(KP)-XDATA(JP))
      YOUT(I)=YDATA(JP)+(XIN(I)-XDATA(JP))*YPRIME
      GO TC 175
      YOUT(I)=YDATA(1)
      GO TC 175
      YCUT(I)=YDATA(NCATA)
      GO TC 175
      IF (XIN(I)-XDATA(J)) 150,160,145
      IF (XIN(I)-XDATA(J+1)) 170,165,150
      J=J+1
      IF (J-NCATA) 140,155,155
      J=1
      GO TC 140
      YOUT(I)=YDATA(J)
      GO TC 175
      YOUT(I)=YDATA(J+1)
      GO TC 175
      DX=XDATA(J+1)-XDATA(J)
      YOUT(I)=M(J)/(6.0*DX)*(XDATA(J+1)-XIN(I))*3+M(J+1)/(6.0*DX)*(XIN(
1I)-XDATA(J))*3+(XDATA(J+1)-XIN(I))*(YDATA(J)/DX-M(J)/6.0*DX)+(XIN
2(I)-XDATA(J))*(YDATA(J+1)/DX-M(J+1)/6.0*DX)
      IF (I-NXY) 180,185,185
      I=I+1
      GO TC 105
      RETURN
      END
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SUBRCUTINE EQ (IX,LCG1,X1,Y1,X2,Y2)
REAL LINE
DIMENSION X1(1), Y1(1), X2(1), Y2(1), LINE(121), XNUM(13)
DATA SYMBOL/1H+/,DASH/1H-/,CROSS/1H+/,BLANK/1H /,XI/1HI/
YMIN=Y1(1)
XMIN=X1(1)
YMAX=YMIN
XMAX=XMIN
DO 5 I=1,IX
  IF (Y2(I).LT.YMIN) YMIN=Y2(I)
  IF (Y2(I).GT.YMAX) YMAX=Y2(I)
  IF (X2(I).LT.XMIN) XMIN=X2(I)
  IF (X2(I).GT.XMAX) XMAX=X2(I)
  IF (Y1(I).GT.YMAX) YMAX=Y1(I)
  IF (X1(I).GT.XMAX) XMAX=X1(I)
CONTINUE
IF (XMAX.EQ.XMIN.OR.YMIN.EQ.YMAX) GO TO 85
YH=YMAX+(YMAX-YMIN)/25.0
YL=YMIN-(YMAX-YMIN)/25.0
XH=XMAX+(XMAX-XMIN)/38.3333
XL=XMIN-(XMAX-XMIN)/38.3333
IF ((YH-YL)/(XH-XL).GT.0.75) XH=1.3333*(YH-YL)+XL
IF ((YH-YL)/(XH-XL).LT.0.75) YH=0.75*(XH-XL)+YL
XMAX=(XMIN+XMAX-XH+XL)/2.0
XH=XH-XL+XMAX
XL=XMAX
XMAX=(YMIN+YMAX-YH+YL)/2.0
YH=YH-YL+XMAX
YL=XMAX
XMAX=ABS(XH)
XMIN=ABS(XL)
YMIN=ABS(YL)
YMAX=ABS(YH)
IF (XMIN.GT.XMAX) XMAX=XMIN
IF (YMIN.GT.YMAX) YMAX=YMIN
XMAX=ALCG10(XMAX)
YMAX=ALCG10(YMAX)
IF (XMAX.LT.0.0) XMAX=XMAX-1.0
IF (YMAX.LT.0.0) YMAX=YMAX-1.0
MX=-XMAX

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10 MY=-YMAX
   WRITE (LOG1,10) MX,MY
   FORMAT (20X,46HSCALES - 'X' IS SHOWN TIMES 10 TC THE POWER OF,I3,4
10H 'Y' IS SHOWN TIMES 10 TO THE POWER OF,I3,/)
   YINC=(YH-YL)/54.0
   YINC2=YINC/2.0
   X RANGE=XH-XL
   DO 70 KLINE=1,55
   IF (KLINE.EQ.1.OR.KLINE.EG.55) GO TC 25
   DO 15 L=2,120
   LINE(L)=BLANK
   IF (KLINE.EQ.7.OR.KLINE.EQ.13.OR.KLINE.EQ.19.OR.KLINE.EQ.25.OR.KLI
15 NE.EG.31.OR.KLINE.EG.37.OR.KLINE.EQ.43.CR.KLINE.EQ.49) GC TO 20
   LINE(1)=XI
   LINE(121)=XI
   GO TC 40
   LINE(1)=DASH
   LINE(121)=DASH
   GO TC 40
20 DO 30 L=2,120
   LINE(L)=DASH
30 LINE(1)=CRCSS
   LINE(121)=CROSS
   DO 35 L=11,111,10
   LINE(L)=XI
   GO TC 60
40 GO 50 I=1,IX
   IF (Y2(I).GT.YH+YINC2.OR.Y2(I).LE.YH-YINC2) GC TO 45
   L=(X2(I)-XL)/X RANGE*120.0+1.5
   LINE(L)=SYMBOL
45 IF (Y1(I).GT.YH+YINC2.OR.Y1(I).LE.YH-YINC2) GC TO 50
   L=(X1(I)-XL)/X RANGE*120.0+1.5
   LINE(L)=SYMBOL
50 CONTINUE
   IF (KLINE.EQ.1.CR.KLINE.EG.7.OR.KLINE.EG.13.OR.KLINE.EG.19.OR.KLIM
1E.EQ.25.OR.KLINE.EQ.31.CR.KLINE.EQ.37.OR.KLINE.EQ.43.OR.KLINE.EQ.4
29.OR.KLINE.EQ.55) GC TC 60
   WRITE (LOG1,55) LINE
   FORMAT (8X,121A1)
55 GO TC 70

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60 YNUM=YH*10.0**MY
   WRITE (LOG1,65) YNUM,LINE
65 FORMAT (1X,F6.3,1X,121A1)
70 YH=YH-YINC
   XNUM(1)=XL*10.0**MX
   XINC=((XH-XL)/12.0)*10.0**MX
   DO 75 I=2,13
75 XNUM(I)=XNUM(I-1)+XINC
   WRITE (LOG1,80) XNUM
80 FORMAT (6X,12(F6.3,4X),F6.3)
   RETURN
85 WRITE (LOG1,90)
90 FORMAT (//,35X,54HNC PLCT HAS BEEN MADE BECAUSE *X* CR *Y* RANGE I
1S ZERO)
   RETURN
   END

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E 405
E 410
E 415
E 420
E 425
E 430
E 435
E 440
E 445
E 450
E 455
E 460
E 465
E 470
E 475
E 480-

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SUBROUTINE FQ (ISTAK,PLTSZ,ITRIG,TITLE,IKDUM,IFPLOT)
DIMENSION TITL(8)
IF (ITRIG.EQ.2.AND.IFPLCT.NE.2) CALL FLCT (PLTSZ,0.,-3)
PLTTIT=PLTSZ*.1
IF (ISTAK.LT.2) GO TO 5
BAL=.35*PLTSZ
XLEN1=.3*PLTSZ
XLEN2=XLEN1
YLEN1=.25*PLTSZ
YLEN2=-1.*YLEN1
XBACK1=-1.9
XBACK2=-6.2
GO TC 25
5  IF (ISTAK.EQ.0) GO TO 10
    XLEN1=.70*PLTSZ
    XLEN2=.15*PLTSZ
    XBACK1=-1.9-.20*PLTSZ
    XBACK2=-6.2-.20*PLTSZ
    IF (IKDUM.EQ.1) GO TO 15
    GO TO 20
10  CONTINUE
    XLEN1=.15*PLTSZ
    XLEN2=.70*PLTSZ
    XBACK1=-1.9+.20*PLTSZ
    XBACK2=-6.2+.20*PLTSZ
    IF (IKDUM.EQ.1) GO TO 20
15  BAL=.25*PLTSZ
    YLEN1=.50*PLTSZ
    YLEN2=-.15*PLTSZ
    GO TO 25
20  BAL=.50*PLTSZ
    YLEN1=.15*PLTSZ
    YLEN2=-.50*PLTSZ
25  CONTINUE
    YBACK1=-(.35+BAL)
    YBACK2=YBACK1-.01*PLTSZ-.175
    CALL FLOT (0.0,-PLTSZ,-3)
    CALL FLCT (7.0,PLTTIT,-3)
    CALL PLCT (0.0,BAL,3)
    CALL FLCT (XLEN1,BAL,-2)

```

F
5 10 15 20 25 30 35 40 45 50 55 60 65 70 75 80 85 90 95 100 105 110 115 120 125 130 135 140 145 150 155 160 165 170 175 180 185 190 195 200


```

30 CALL FLCT (XLEN2,0.0,2)
   CALL PLCT (0.0,YLEN1,3)
   CALL FLCT (0.0,YLEN2,2)
   GO TO (30,35), IIRIG
35 CALL SYMBOL (XBACK1,YBACK1,.175,2HSTREAMSURFACE SECTIONS,0.0,22)
   GO TC 40
   XBACK1=XBACK1+0.35
40 CALL SYMBOL (XBACK1,YBACK1,.175,10HCARTESIAN SECTIONS,0.0,18)
   CALL SYMBOL (XBACK2,YBACK2,.175,TITLE,0.0,72)
   RETURN
   END

```

```

F 205
F 210
F 215
F 220
F 225
F 230
F 235
F 240
F 245
F 250
F 255-

```

4. PROGRAM LOGIC

The calculation procedure which has been described in this report is performed primarily in the main program and Subroutine BQ. The calculations regarding the construction of the camber line, the stacking of the streamsurface blade sections, and the determination of manufacturing sections are performed in the main program. Subroutine BQ applies the thickness distribution to the camber line and determines quantities necessary to obtain the Cartesian coordinates of the section from the streamsurface coordinates. Subroutine D1 is the curve-fitting routine, and CQ is used to determine slopes of various spline curves at particular points. EQ produces the line-printer section plot in the printed portion of the output, and FQ produces axes on the section plots for IFPLOT = 1, 2, or 3.

A description of the calculation procedure employed in the main program and in Subroutine BQ is described below. Each step is keyed to its location in the program by the parenthetical deck serialization.

1. The input data is read and printed. (A155-A680)
2. If precision plotting is specified, the plot is initialized, and axes produced if IFPLOT = 1 or 3. (A695-A710)
3. A loop which creates a section on each streamsurface is commenced. (A715)
4. The axial locations of the intersections of a particular streamsurface with the computing stations describing the blade are determined. The meridional streamsurface length is obtained as described in Equation (1). (A720-A780)
5. The parameters relating to the streamsurface blade section are interpolated (or extrapolated) from the input tables. If NSPEC = 1, they are taken to be radially uniform. If NSPEC = 2, linear interpolation is used; if NSPEC = 3, spline-curve interpolation is employed. (A785-A840)
6. The loop to determine the optimal camber line is initiated. (A855)
7. The first estimate of true chord is calculated per Equation (2), and the solidity as in Equation (3). (A870-A910)
8. The incidence angle and extra deviation applicable to the particular section are obtained by interpolation of the radius at the leading edge of the streamsurface in the input tables. (A915-A920)

9. The section angle at the leading edge is determined as in Equation (6). (A925)
10. The quantities required for the deviation angle calculation are obtained by interpolation from various figures of Reference 2. (A935-A960)
11. The deviation angle is calculated using Equation (5). (A995-A1000)
12. The section angle at the trailing edge is calculated using Equation (7), and at internal points using Equation (8), with fractions of deviation obtained by radial interpolation from the input distributions based on the streamsurface radius at the trailing edge of the blade. (A1020-A1085)
13. A camber line is constructed of cubic segments following the analysis of Equations (9) - (15) for the initial value of S/R_0 . The number of inflection points is determined. (A1090-A1350)
14. The iteration on solidity is performed until the tolerance is within the prescribed limit. (A1355-A1395)
15. Steps 13 and 14 are repeated for IPASS-1 values of the S/R_0 parameter. (A1406-A1450)
16. The range of S/R_0 with the minimum number of inflection points is established. (A1480-A1600)
17. Steps 13, 14 and 15 are repeated for finer increments of the S/R_0 parameter in the range determined in 16. The maximum value of the minimum radius of curvature in this range is determined. (A1645-A1690)
18. Still finer increments of S/R_0 on either side of the S/R_0 value which produced the maximum value of the minimum radius of curvature in 17 are examined to find the optimal S/R_0 value. (A1730-A1745)
19. The details of the optimal camber line are printed if IPRINT = 0 or 1. (A1755-A1810)
20. The normalized chord length of the optimal camber line is computed. (A1820)
21. The total streamsurface length is calculated. (A1830-A1890)
22. If IPRINT = 0 or 1, the parameters defining the section are printed. (B65-B115)

23. The coefficients of the two thickness equations are computed. (B175-B220)
24. At each point of the camber line, the corresponding coordinates on each blade surface are obtained from the coordinates and slope of the camber line, and the appropriate thickness, scaled for an overall section meridional chord of unity. (B225-B310)
25. The section area and centroid location are determined. (B315-B365)
26. The camber line is redefined in terms of 100 points to assure sufficient points for accurate linear interpolation in the determination of ϕ (Figure 1), needed for the eventual Cartesian coordinate determination. (B380-B440)
27. The various streamsurface section properties are determined. (B445-B560)
28. If IPRINT = 0 or 1, details of the normalized blade section and a line-printer plot are produced. (B575-B750)
29. Sectional properties are scaled to produce the "dimensional" results. (B755-B830)
30. If IPRINT = 0 or 1, the section information is printed. (B840-B1095)
31. The coordinates of 31 points describing the leading edge are determined. (B1070-B1080)
32. The origin of the coordinate system is shifted to the stack axis, and the relative ϕ values for the blade surfaces are determined. (B1120-B1595)
33. If IFPLOT = 1 or 3, the streamsurface section plot is produced. (A1950-A2040)
34. If the calculations for aerodynamic analysis are required, various items related to the camber line are stored. (A2045-A2095)
35. The Cartesian coordinates for each point on the section surface are computed, and printed if IPRINT = 0 or 1. (A2100-A2435)
36. The loop initiated in 3 is repeated for each streamsurface. (A2440)
37. Unless IPRINT = 1, the volume of the blade is computed and printed. (A2445-A2555)

38. If specified, the calculations for aerodynamic analysis are performed and printed, and punched if IPUNCH = 1. (A2560-A2790)
39. If IFPLOT = 2 or 3, the axes are drawn and titled for the superimposed plot of the manufacturing sections. (A2800)
40. If no output relating to manufacturing sections is specified by either IFPLOT or IPRINT, the remainder of the program is bypassed. Alternatively, if printed details of the manufacturing sections are specified, a heading is printed. (A2805-A2835)
41. The location of each of the manufacturing planes is determined. (A2840-A2865)
42. The (Cartesian) coordinates of each point on the blade surface are obtained by spline-curve interpolation at each of the manufacturing sections. (A2870-A2945)
43. A loop that is performed for each manufacturing section is initiated. This loop contains the determination of section properties and the output of results for the section. If IPRINT = 0 or 2, section properties and coordinates are printed. (A2950-A3495)
44. If IFPLOT = 2 or 3, a plot of the manufacturing sections is produced. (A3510-A3605)
45. If IFPLOT = 4, an individual plot of the manufacturing sections is made. The axes are rotated clockwise until the chord line is horizontal. The angle of rotation is indicated as the stagger angle. (A3610-A3845)
46. The loop initiated in Step 43 for each manufacturing section is terminated. (A3850)
47. If precision plots have been made, the plotting is terminated. (A3855)

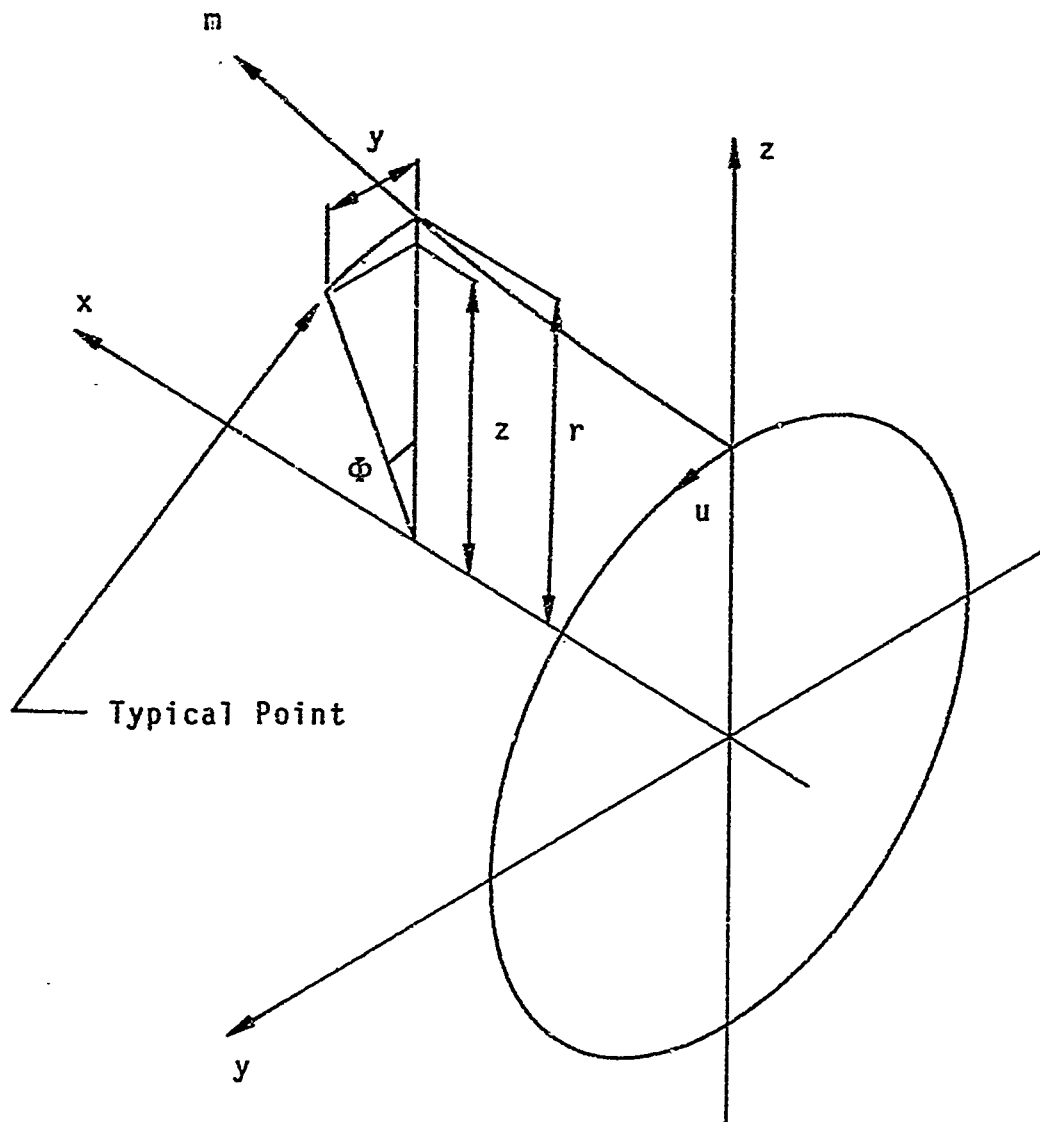


Figure 1. Cartesian and Streamsurface Coordinates of a Point

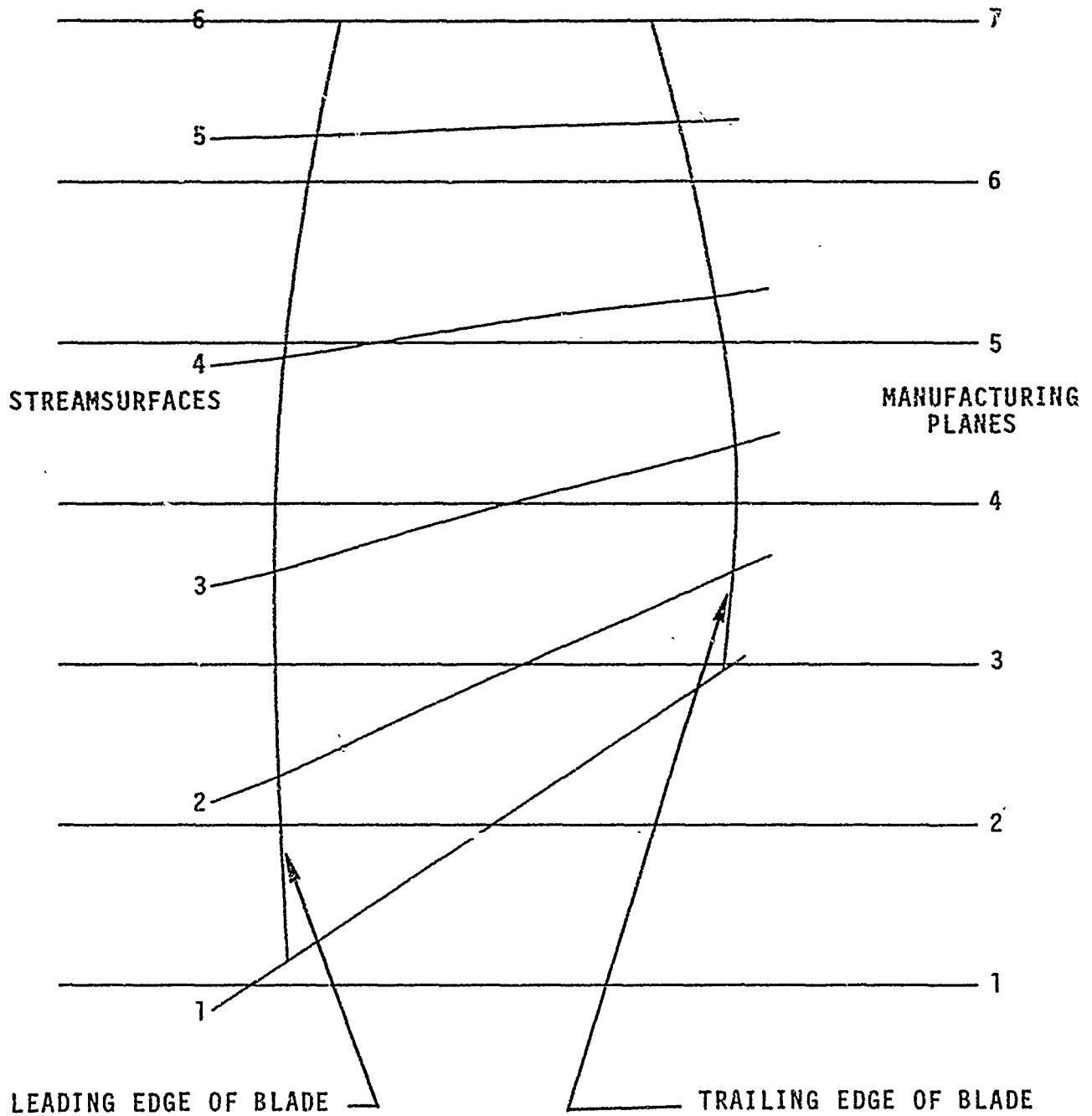


Figure 2. Locations of Streamsurfaces and Manufacturing Planes for Example Blade Design

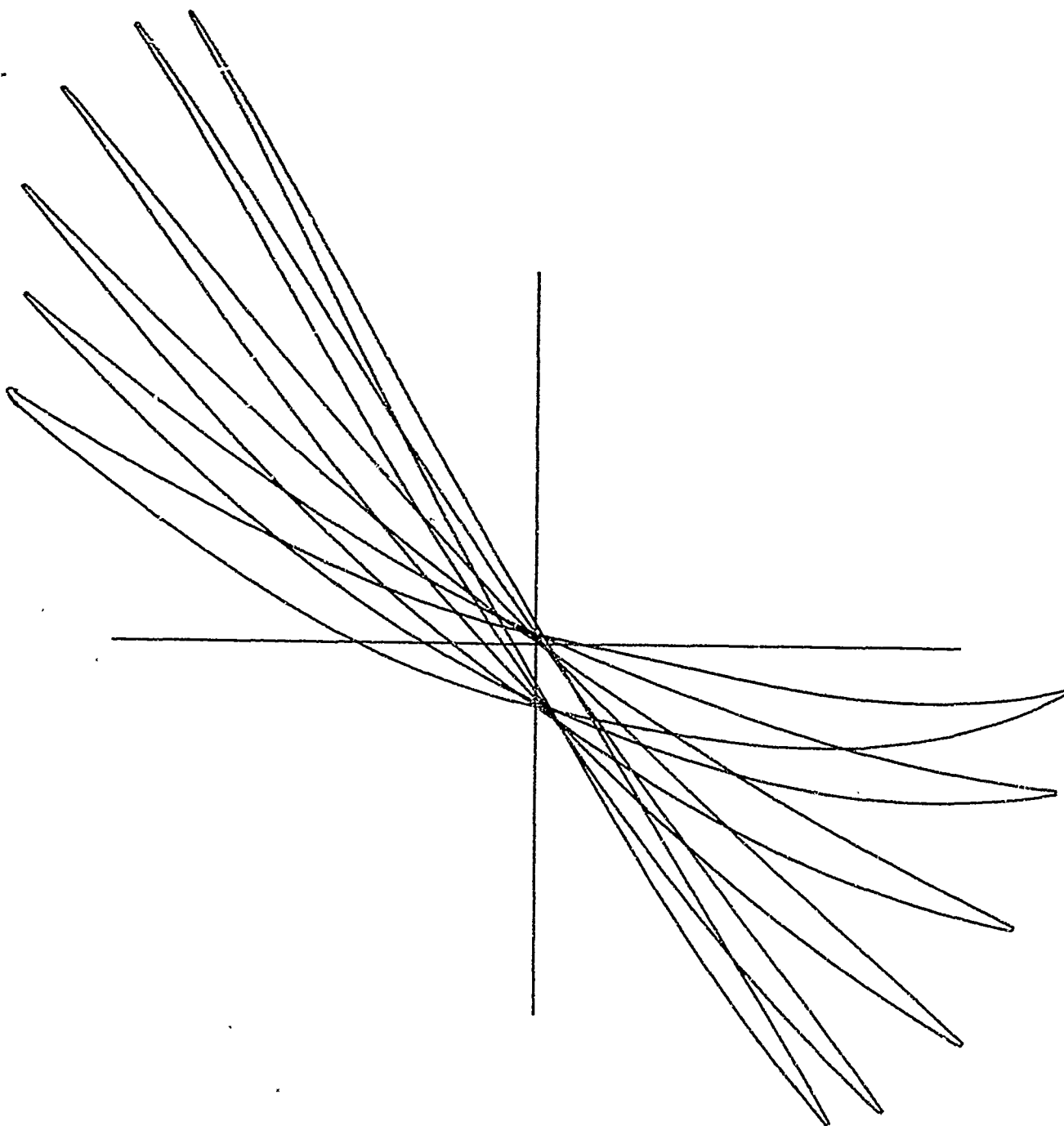


Figure 3, Example Blade Design:
Streamsurface Sections

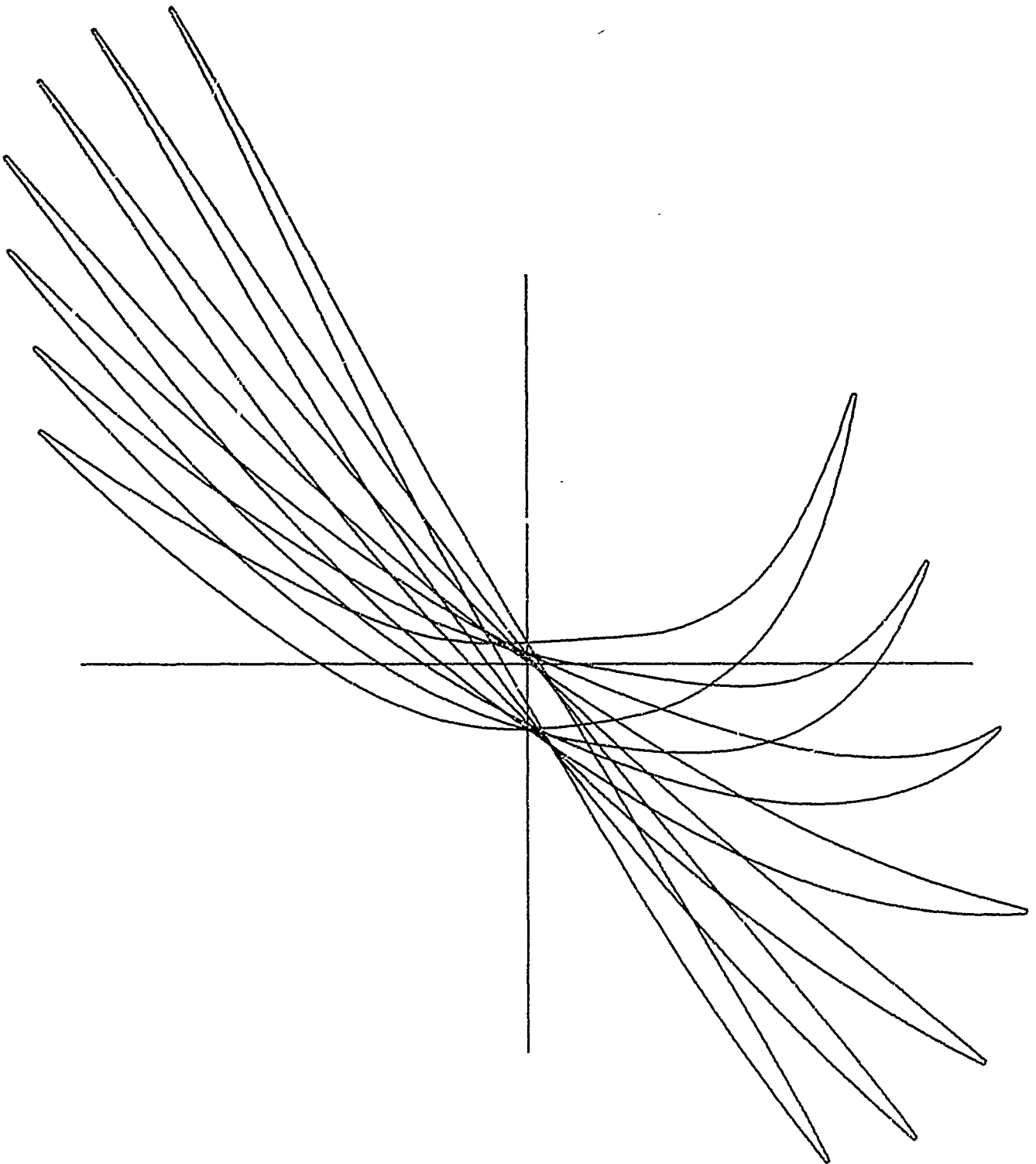


Figure 4. Example Blade Design:
Cartesian Sections

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1. Frost, G.R., Hearsey, R.M., and Wennerstrom, A.J., "A Computer Program for the Specification of Axial Compressor Airfoils," Aerospace Research Laboratories, Wright-Patterson AFB, Ohio, ARL 72-0171, AD 756879, December 1972.
2. Johnsen, I.A., Bullock, R.O., et al, "Aerodynamic Design of Axial Flow Compressors," Lewis Research Center, Cleveland, Ohio, NASA SP-36, 1965.