# The distortion problem 

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## 1. Introduction

An infinite dimensional Banach space $X$ is distortable if there exists an equivalent norm $|\cdot|$ on $X$ and $\lambda>1$ such that for all infinite dimensional subspaces $Y$ of $X$,

$$
\begin{equation*}
\sup \{|y| /|z|: y, z \in S(Y ;\|\cdot\|)\}>\lambda \tag{1.1}
\end{equation*}
$$

where $S(Y ;\|\cdot\|)$ is the unit sphere of $Y$. R. C. James [11] proved that $l_{1}$ and $c_{0}$ are not distortable. In this paper we prove that $l_{2}$ is distortable. In fact we shall prove that $l_{2}$ is arbitrarily distortable (for every $\lambda>1$ there exists an equivalent norm on $l_{2}$ satisfying (1.1)).

The distortion problem is related to stability problems for a wider class of functions than the class of equivalent norms. A function $f: S(X) \rightarrow \mathbf{R}$ is oscillation stable on $X$ if for all subspaces $Y$ of $X$ and for all $\varepsilon>0$ there exists a subspace $Z$ of $Y$ with

$$
\begin{equation*}
\sup \{|f(y)-f(z)|: y, z \in S(Z)\}<\varepsilon \tag{1.2}
\end{equation*}
$$

(By subspace we shall mean a closed infinite dimensional linear subspace unless otherwise specified.) It was proved by V. Milman (see e.g., [28, p. 6] or [26], [27] that every Lipschitz (or even uniformly continuous) function $f: S(X) \rightarrow \mathbf{R}$ is finitely oscillation stable (a subspace $Z$ of arbitrary finite dimension can be found satisfying (1.2)). V. Milman also proved in his fundamental papers [26], [27] that if all Lipschitz functions on every unit sphere of every Banach space were oscillation stable, then every $X$ would isomorphically contain $c_{0}$ or $l_{p}$ for some $1 \leqslant p<\infty$. Of course Tsirelson's famous example [38] dashed such hopes and caused Milman's paper to be overlooked. However Milman's work contains the result that if $X$ does not contain $c_{0}$ or $l_{p}(1 \leqslant p<\infty)$ then some subspace of $X$

[^0]admits a distorted norm. Thus the general distortion problem (does a given $X$ contain a distortable subspace?) reduces to the case $X=l_{p}(1<p<\infty)$.

For a given space $X$, every Lipschitz function $f: S(X) \rightarrow \mathbf{R}$ is oscillation stable if and only if every uniformly continuous $g: S(X) \rightarrow \mathbf{R}$ is oscillation stable. Indeed if such a $g$ were not oscillation stable then there exist a subspace $Y$ of $X$ and reals $a<b$ such that

$$
C=\{y \in S(Y): g(y)<a\} \quad \text { and } \quad D=\{y \in S(Y): g(y)>b\}
$$

are both asymptotic for $Y$ ( $C$ is asymptotic for $Y$ if $C_{\varepsilon} \cap S(Z) \neq \varnothing$ for all subspaces $Z$ of $Y$ and all $\varepsilon>0$ where $\left.C_{\varepsilon}=\{x: d(C, x)<\varepsilon\}\right)$. Since $g$ is uniformly continuous, $d(C, D) \equiv$ $\inf \{\|c-d\|: c \in C, d \in D\}>0$ and so $f(x) \equiv d(C, x)$ is a Lipschitz function on $S(X)$ that does not stabilize in $Y$.

If $C$ and $D$ are asymptotic sets for a uniformly convex space $X$ with $d(C, D)>0$ then $X$ contains a distortable subspace. For example, the norm $|\cdot|$ on $X$ whose unit ball is the closed convex hull of $(A \cup-A \cup \delta \operatorname{Ba} X)$ is a distortion of a subspace for sufficiently small $\delta$ and any choice $A \in\{C, D\}$. If $X=c_{0}$ or $l_{p}(1 \leqslant p<\infty)$, then by the minimality of $X$ one obtains that every uniformly continuous $f: S(X) \rightarrow \mathbf{R}$ is oscillation stable if and only if $S(X)$ does not contain two asymptotic sets a positive distance apart. If $X=l_{p}$ $(1<p<\infty)$ then this is, in turn, equivalent to $X$ is not distortable.
T. Gowers [8] proved that every uniformly continuous function $f: S\left(c_{0}\right) \rightarrow \mathbf{R}$ is oscillation stable. Every uniformly continuous $f: S\left(l_{1}\right) \rightarrow \mathbf{R}$ is oscillation stable if and only if $l_{2}$ (equivalently $l_{p}, 1<p<\infty$ ) is not distortable. This is seen by considering the Mazur map [25] $M: S\left(l_{1}\right) \rightarrow S\left(l_{2}\right)$ given by $M\left(x_{i}\right)_{i=1}^{\infty}=\left(\left(\operatorname{sign} x_{i}\right) \sqrt{\left|x_{i}\right|}\right)_{i=1}^{\infty} . M$ is a uniform homeomorphism between the two unit spheres (see e.g., [32, Lemma 1]). Moreover, since $M$ preserves subspaces spanned by block bases of the respective unit vector bases of $l_{1}$ and $l_{2}, C$ is an asymptotic set for $l_{1}$ if and only if $M(C)$ is an asymptotic set for $l_{2}$.

Gowers theorem combined with our main result and that of Milman's yields
Theorem 1.1. Let $X$ be an infinite dimensional Banach space. Then every Lipschitz function $f: S(X) \rightarrow \mathbf{R}$ is oscillation stable if and only if $X$ is $c_{0}$-saturated.
( $X$ is $c_{0}$-saturated if every subspace of $X$ contains an isomorph of $c_{0}$.)
In $\S 2$ we consider a generalization of the Mazur map. The Mazur map satisfies for $h=\left(h_{i}\right) \in S\left(l_{1}\right)^{+}$with $h$ finitely supported, $M(h)=x$ where $x \in S\left(l_{2}\right)^{+}$maximizes $E(h, y) \equiv$ $\sum_{i} h_{i} \log y_{i}$ over $S\left(l_{2}\right)^{+}$. Furthermore in this case $h=x^{*}$ o $x$ where $x^{*}$ is the unique support functional of $x$ and $\circ$ denotes pointwise multiplication of the sequences $x$ and $x^{*}$. These facts are well known. We give a proof in Proposition 2.5.

The generalization is given as follows. Let $X$ have a 1 -unconditional normalized basis $\left(e_{i}\right)$. This just means that $\||x|\|=\|x\|$ for all $x=\sum a_{i} e_{i} \in X$ where $|x|=\sum\left|a_{i}\right| e_{i}$.

We regard $X$ as a discrete lattice. $c_{00}$ denotes the linear space of finitely supported sequences on $\mathbf{N}$. Thus $X \cap c_{00}=\{x \in X: \operatorname{supp} x$ is finite $\}$ where $\operatorname{supp}\left(\sum a_{i} e_{i}\right)=\left\{i: a_{i} \neq 0\right\}$. For $B \subseteq \mathbf{N}$ and $x=\sum x_{i} e_{i} \in X$ we set $B x=\sum_{i \in B} x_{i} e_{i}$. We often write $x=\left(x_{i}\right) . l_{1}$ is a particular instance of such an $X$ and we use the same notational conventions for $l_{1}$.

The generalization $F_{X}$ of the Mazur map is defined in terms of an auxilliary map, the entropy function $E:\left(l_{1} \cap c_{00}\right) \times X \rightarrow[-\infty, \infty)$ given by $E(h, x) \equiv E(|h|,|x|) \equiv \sum_{i}\left|h_{i}\right| \log \left|x_{i}\right|$ where $h=\left(h_{i}\right) \in l_{1} \cap c_{00}$ and $x=\left(x_{i}\right) \in X$ under the convention $0 \log 0 \equiv 0$. Fix $h \in l_{1} \cap c_{00}$ and $B=\operatorname{supp} h$. Then there exists a unique $x=\left(x_{i}\right) \in S(X)$ satisfying
(i) $E(h, x) \geqslant E(h, y)$ for all $y \in S(X)$,
(ii) $\operatorname{supp} h=\operatorname{supp} x=B$,
(iii) $\operatorname{sign} x_{i}=\operatorname{sign} h_{i}$ for $i \in B$.

This unique $x$ we denote by $F_{X}(h)$ and we set

$$
E_{X}(h)=E\left(h, F_{X}(h)\right)=\max \{E(h, y): y \in S(X)\}
$$

Indeed the function $E(h, \cdot):\left\{x \in S(X)^{+}: \operatorname{supp} x \subseteq B\right\} \rightarrow[-\infty, 0]$ is continuous taking real values on those $x$ 's with supp $x=B$ and taking the value $-\infty$ otherwise. Thus there exists $x \in S(X)^{+}$satisfying (ii) and $E(h, x) \geqslant E(h, y)$ if $y \in S(X)^{+}$, supp $y \subseteq B$. Since $\left(e_{i}\right)$ is 1-unconditional and $E(h, y)=E(h, B y)$ for all $y \in X$, we obtain (i). (iii) is then achieved by changing the signs of $x_{i}$ as needed. The uniqueness of $x$ follows from the strict concavity of the $\log$ function. If $\operatorname{supp} x=\operatorname{supp} y=B$ and $x \neq y$ then $E\left(h, \frac{1}{2}(|x|+|y|)\right)>$ $\frac{1}{2} E(h,|x|)+\frac{1}{2} E(h,|y|)$.

We discovered the map $E$ in a paper of Gillespie [7] and we thank L. Weis for bringing that paper to our attention. A similar map is considered in [37]. As noted there other authors have also worked with this map in various contexts ([20], [21], [13], [30], [36], [14]). The central objective of some of these earlier papers was to show that elements of $S\left(l_{1}\right)$ could be written as $x^{*} \circ x$ with $\left\|x^{*}\right\|=\|x\|=1$. Our additional focal point is the map $F_{X}$ itself. For certain $X, F_{X}$ is uniformly continuous. In general $F_{X}$ is not uniformly continuous, but retains enough structure (Proposition 2.3) to be extremely useful in $\S 3$. In addition it is known (e.g., [37, Lemma 39.3]) that whenever $x=F_{X}(h)$ there exists $x^{*} \in S\left(X^{*}\right)$ with $x^{*} \circ x=h$.

We prove (Theorem 2.1) that if $X$ has an unconditional basis and if $X$ does not contain $l_{\infty}^{n}$ uniformly in $n$, then there exists a uniform homeomorphism $F: S\left(l_{1}\right) \rightarrow S(X)$. We prove this by reducing the problem, this follows easily from the work of [6] and [23], to the case where $X$ has a 1 -unconditional basis and is $q$-concave with constant 1 for some $q<\infty$. $X$ is $q$-concave with constant $M_{q}(X)$ if

$$
\begin{equation*}
\left(\sum_{i=1}^{n}\left\|x^{i}\right\|^{q}\right)^{1 / q} \leqslant M_{q}(X)\left\|\left(\sum_{i=1}^{n}\left|x^{i}\right|^{q}\right)^{1 / q}\right\| \tag{1.3}
\end{equation*}
$$

whenever $\left(x^{i}\right)_{i=1}^{n} \subseteq X$. The vector on the right side of (1.3) is computed coordinatewise with respect to $\left(e_{j}\right)$. In this particular case the uniform homeomorphism $F$ is the map $F_{X}$ described above (see the remark before Proposition 2.9).

One way to attack the distortion problem is to find a distortable space $X$ with a 1-unconditional basis and having say $M_{2}(X)=1$ and possessing a describable pair of separated asymptotic sets. Then use the map $F_{X}$ to pull these sets back to a separated pair (easy) of asymptotic sets (not easy) in $S\left(l_{1}\right)$. Our original proof that $l_{2}$ is distortable was a variation of this idea using $X=T_{2}^{*}$, the dual of convexified Tsirelson space. However much more is possible as was shown to us by B. Maurey. Maurey's elegant argument is given in $\S 3$ (Theorem 3.4). We thank him for permitting us to include it in this paper.

In $\S 3$ we use the map $F_{X}$ for $X=S^{*}$, the dual space of the arbitrarily distortable space constructed in [34] (see also [35]). As shown in [10] and implicitly in [34], [35] this space contains a sequence of nearly biorthogonal sets: $A_{k} \subseteq S(S), A_{k}^{*} \subseteq \mathrm{Ba}\left(S^{*}\right)$ with $A_{k}$ asymptotic in $S$ for all $k$. By "nearly biorthogonal" we mean that for some sequence $\varepsilon_{i} \downarrow 0$, $\left|x_{k}^{*}\left(x_{j}\right)\right|<\varepsilon_{\min (k, j)}$ if $k \neq j, x_{k}^{*} \in A_{k}^{*}, x_{j} \in A_{j}$, and $A_{k}^{*}\left(1-\varepsilon_{k}\right)$-norms $A_{k}$. The latter means that for all $x_{k} \in A_{k}$ there exists $x_{k}^{*} \in A_{k}^{*}$ with $x_{k}^{*}\left(x_{k}\right)>1-\varepsilon_{k}$. The particular description of these sets is used along with the mapping $F_{S}$. to show that the sets

$$
\begin{aligned}
C_{k} \equiv\left\{x \in l_{2}:|x|\right. & =\left(\left|x_{k}^{*} \circ x_{k}\right| /\left\|x_{k}^{*} \circ x_{k}\right\|_{1}\right)^{1 / 2} \text { for some } \\
& \left.x_{k}^{*} \in A_{k}^{*}, x_{k} \in A_{k} \text { with }\left\|x_{k}^{*} \circ x_{k}\right\|_{1} \geqslant 1-\varepsilon_{k}\right\}
\end{aligned}
$$

are nearly biorthogonal in $l_{2}$ (easy) and that $C_{k}$ is asymptotic in $l_{2}$. By $x^{*} \circ x$ we mean again the element of $l_{1}$ given by the operation of pointwise multiplication. Thus if $x^{*}=\sum a_{i} e_{i}^{*}$ and $x=\sum b_{i} e_{i}, x^{*} \circ x=\left(a_{i} b_{i}\right)_{i=1}^{\infty} .\|\cdot\|_{1}$ is the $l_{1}$-norm.

The sets $C_{k}$ easily lead to an arbitrary distortion of $l_{2}$. In fact using an argument of [10] one can prove the following (see also Theorem 3.1).

Theorem 1.2. For all $1<p<\infty, \varepsilon>0$ and $n \in \mathbf{N}$ there exists an equivalent norm $|\cdot|$ on $l_{p}$ such that for any block basis ( $y_{i}$ ) of the unit vector basis of $l_{p}$ there exists a finite block basis $\left(z_{i}\right)_{i=1}^{n}$ of $\left(y_{i}\right)$ which is $(1+\varepsilon)$-equivalent to the first $n$ terms of the summing basis, $\left(s_{i}\right)_{i=1}^{n}$.

The summing basis norm is

$$
\left\|\sum_{i=1}^{n} a_{i} s_{i}\right\|=\sup \left\{\left|\sum_{i=1}^{l} a_{i}\right|: l \leqslant n\right\} .
$$

Thus for all $\lambda>1$ there exists an equivalent norm $|\cdot|$ on $l_{p}$ such that no basic sequence in $l_{p}$ is $\lambda$-unconditional in the $|\cdot|$ norm. The sets $C_{k}$, in addition to being nearly biorthogonal,
are unconditional and spreading (defined in $\S 3$ just before the statement of Theorem 3.4) and seem likely to prove useful elsewhere.
T. Gowers [9] proved the conditional theorem that if every equivalent norm on $l_{2}$ admits an almost symmetric subspace, then $l_{2}$ is not distortable. Theorem 1.2 shows that one cannot even obtain an almost 1-unconditional subspace in general.

The paper by Lindenstrauss and Pełczyński [17] also contains some nice results on distortion. They consider a restricted form of distortion in which the subspace $Y$ of (1.1) is isomorphic to $X$.

Our notation is standard Banach space terminology as may be found in the books [18] and [19]. In §2 we use a number of results in [6] although we cite the corresponding statements in [19].

Thanks are due to numerous people, especially B. Maurey and N. Tomczak-Jaegermann. As we noted, Maurey gave us the elegant argument of $\S 3$. The idea of exploiting the ramifications of being able to write elements of $S\left(l_{2}\right)$ as $\sqrt{x^{*} \circ x}$ with $x$ in the sphere of a Tsirelson-type space $X$ and $x^{*} \in S\left(X^{*}\right)$ in attacking the distortion problem is due to Tomczak-Jaegermann.

## 2. Uniform homeomorphisms between unit spheres

The main result of this section is
Theorem 2.1. Let $X$ be a Banach space with an unconditional basis. Then $S(X)$ and $S\left(l_{1}\right)$ are uniformly homeomorphic if and only if $X$ does not contain $l_{\infty}^{n}$ uniformly in $n$.

A uniform homeomorphism between two metric spaces is an invertible map such that both the map and its inverse are uniformly continuous. Many results are known concerning uniform homeomorphisms between Banach spaces (see [1] for a nice survey of these results). Our focus however is on the unit spheres of Banach spaces. The prototype of such maps is the Mazur map discussed in the introduction.

Before proceeding we set some notation. Unless stated otherwise $X$ shall be a Banach space with a normalized 1-unconditional basis $\left(e_{i}\right)$. We regard $X$ as a discrete lattice. $x=\left(x_{i}\right) \in X$ means that $x=\sum x_{i} e_{i},|x|=\left(\left|x_{i}\right|\right)$, and $\mathrm{Ba}(X)^{+}=\{x \in \mathrm{Ba}(X): x=|x|\} . \mathrm{Ba}(X)$ is the closed unit ball of $X$. For $1 \leqslant p<\infty, X$ is $p$-convex with $p$-convexity constant $M^{p}(X)$ if for all $\left(x^{i}\right)_{i=1}^{n} \subseteq X$,

$$
\left\|\left(\sum_{i=1}^{n}\left|x^{i}\right|^{p}\right)^{1 / p}\right\| \leqslant M^{p}(X)\left(\sum_{i=1}^{n}\left\|x^{i}\right\|^{p}\right)^{1 / p}
$$

where $M^{p}(X)$ is the smallest constant satisfying the inequality. The $p$-convexification of $X$ is the Banach space given by

$$
X^{(p)}=\left\{\left(x_{i}\right):\left\|\left(x_{i}\right)\right\|_{(p)} \equiv\left\|\sum_{i}\left|x_{i}\right|^{p} e_{i}\right\|^{1 / p}<\infty\right\}
$$

The unit vector basis of $X^{(p)}$, which we still denote by $\left(e_{i}\right)$, is a 1 -unconditional basis for $X^{(p)}$ and $M^{p}\left(X^{(p)}\right)=1$. These facts may be found in [19, $\left.\S 1 . \mathrm{d}\right]$.

Let $F_{X}: l_{1} \cap c_{00} \rightarrow S(X)$ be as defined in the introduction. As we shall see in Proposition 2.5, $F_{X}$ generalizes the Mazur map. If $X=l_{p}(1<p<\infty)$ and $h \in S\left(l_{1}\right)^{+} \cap c_{00}$ then $F_{X}(h)=\left(h_{i}^{1 / p}\right)$. Even in this nice setting however we cannot use our definitions directly on infinitely supported elements. Indeed one can find $h \in S\left(l_{1}\right)$ with $E_{l_{2}}(h)=-\infty$. The map $F_{l_{2}}$ is uniformly continuous on $S\left(l_{1}\right) \cap c_{00}$, though, and thus extends to a map on $S\left(l_{1}\right) . E_{X}$ is not uniformly continuous on $S\left(l_{1}\right) \cap c_{00}$ but has some positive features as the next proposition reveals. Some of our arguments could be shortened by referring to the papers [20], [21], [13], [37] and [7] but we choose to present complete proofs.

First we define a function $\psi(\varepsilon)$ that appears in Proposition 2.3. Note that there exists a function $\eta:(0,1) \rightarrow(0,1)$ so that

$$
\begin{equation*}
\log \frac{1}{2}\left(\sqrt{a}+\frac{1}{\sqrt{a}}\right)>\eta(\varepsilon) \quad \text { if }|a-1|>\varepsilon \text { with } a>0 . \tag{2.1}
\end{equation*}
$$

Indeed, let $g(a)=\log \frac{1}{2}(a+1 / a)$ for $a>0 . g$ is continuous on ( $0, \infty$ ), strictly decreasing on $(0,1)$ and strictly increasing on $(1, \infty)$. The minimum value of $g$ is $g(1)=0$. Thus there exists $\eta:(0,1) \rightarrow(0,1)$ so that $|a-1|>\varepsilon$ implies $g(\sqrt{a})>\eta(\varepsilon)$.

Definition 2.2. $\psi(\varepsilon)=\varepsilon \eta(\varepsilon)$ for $\varepsilon \in(0,1)$.
Proposition 2.3. Let $X$ have a 1-unconditional basis.
(A) Let $h \in S\left(l_{1}\right)^{+} \cap c_{00}$, let $\varepsilon>0$ and $v \in \mathrm{Ba}(X)^{+}$be such that $E(h, v) \geqslant E_{X}(h)-\psi(\varepsilon)$. Then if $u=F_{X}(h)$ there exists $A \subseteq \operatorname{supp} h$ satisfying $\|A h\|>1-\varepsilon$ and $(1-\varepsilon) A u \leqslant A v \leqslant$ $(1+\varepsilon) A u$ (the latter inequalities being pointwise in the lattice sense).
(B) Let $h_{1}, h_{2} \in S\left(l_{1}\right)^{+} \cap c_{00}$ with $\left\|h_{1}-h_{2}\right\| \leqslant 1$. Let $x_{i}=F_{X}\left(h_{i}\right)$ for $i=1,2$. Then

$$
\left\|\frac{1}{2}\left(x_{1}+x_{2}\right)\right\| \geqslant 1-\sqrt{\left\|h_{1}-h_{2}\right\|} .
$$

Proof. (A) Let $u=\left(u_{i}\right)$ and $v=\left(v_{i}\right)$ be as in the statement of (A). We may assume that $\operatorname{supp} u=\operatorname{supp} v=B \equiv \operatorname{supp} h . E(h, v) \geqslant E_{X}(h)-\psi(\varepsilon)$ yields

$$
\begin{equation*}
\psi(\varepsilon) \geqslant \sum_{i \in B} h_{i}\left(\log u_{i}-\log v_{i}\right) \tag{2.2}
\end{equation*}
$$

Since $\frac{1}{2}(u+v) \in \operatorname{Ba}(X)^{+}$and $u=F_{X}(h)$ we obtain from (2.2)

$$
\begin{aligned}
\psi(\varepsilon) & \geqslant \sum_{i \in B} h_{i}\left[\log \frac{1}{2}\left(u_{i}+v_{i}\right)-\log v_{i}\right] \\
& =\sum_{i \in B} h_{i}\left[\frac{1}{2} \log u_{i}+\frac{1}{2} \log v_{i}+\log \frac{1}{2}\left(u_{i}+v_{i}\right)-\log \sqrt{u_{i} v_{i}}-\log v_{i}\right] \\
& =\frac{1}{2} \sum_{i \in B} h_{i}\left(\log u_{i}-\log v_{i}\right)+\sum_{i \in B} h_{i} \log \frac{1}{2}\left(\sqrt{\frac{v_{i}}{u_{i}}}+\sqrt{\frac{u_{i}}{v_{i}}}\right) .
\end{aligned}
$$

The first term in the last expression is nonnegative so

$$
\begin{equation*}
\psi(\varepsilon) \geqslant \sum_{i \in B} h_{i} \log \frac{1}{2}\left(\sqrt{\frac{v_{i}}{u_{i}}}+\sqrt{\frac{u_{i}}{v_{i}}}\right) . \tag{2.3}
\end{equation*}
$$

Now $\left|v_{i} / u_{i}-1\right| \leqslant \varepsilon$ if and only if $(1-\varepsilon) u_{i} \leqslant v_{i} \leqslant(1+\varepsilon) u_{i}$. Let $I=\left\{i \in B:\left|v_{i} / u_{i}-1\right|>\varepsilon\right\}$. For $i \in I$,

$$
\begin{equation*}
\log \frac{1}{2}\left(\sqrt{\frac{u_{i}}{v_{i}}}+\sqrt{\frac{v_{i}}{u_{i}}}\right)>\eta(\varepsilon) \quad(\text { by }(2.1)) \tag{2.4}
\end{equation*}
$$

Let $J=\left\{i \in B: \log \frac{1}{2}\left(\sqrt{u_{i} / v_{i}}+\sqrt{v_{i} / u_{i}}\right)>\eta(\varepsilon)\right\}$. Thus $I \subseteq J$ by (2.4) and from (2.3),

$$
\sum_{i \in I} h_{i} \leqslant \sum_{i \in J} h_{i} \leqslant \frac{1}{\eta(\varepsilon)} \sum_{i \in J} h_{i} \log \frac{1}{2}\left(\sqrt{\frac{u_{i}}{v_{i}}}+\sqrt{\frac{v_{i}}{u_{i}}}\right) \leqslant \frac{\psi(\varepsilon)}{\eta(\varepsilon)}=\varepsilon
$$

Thus (A) follows with $A=B \backslash I$.
(B) Let $\left\|\frac{1}{2}\left(x_{1}+x_{2}\right)\right\| \equiv 1-2 \varepsilon$. Set $\tilde{x}_{1}=x_{1}+\varepsilon x_{2}$ and $\tilde{x}_{2}=x_{2}+\varepsilon x_{1}$. Thus supp $\tilde{x}_{1}=$ $\operatorname{supp} \tilde{x}_{2}=\operatorname{supp} h_{1} \cup \operatorname{supp} h_{2}$ and $\left\|\frac{1}{2}\left(\tilde{x}_{1}+\tilde{x}_{2}\right)\right\| \leqslant 1-\varepsilon$. We may assume $\varepsilon>0$. For $j \in \operatorname{supp} \tilde{x}_{1}$, $\left|\log \tilde{x}_{1, j}-\log \tilde{x}_{2, j}\right| \leqslant|\log \varepsilon|$ where $\tilde{x}_{i}=\left(\tilde{x}_{i, j}\right)$ for $i=1,2$.

From this and $\tilde{x}_{1} \geqslant x_{1}$ we obtain

$$
\begin{aligned}
E\left(h_{1}, \tilde{x}_{1}\right) & \geqslant E\left(h_{1}, x_{1}\right) \geqslant E\left(h_{1}, \frac{\tilde{x}_{1}+\tilde{x}_{2}}{2(1-\varepsilon)}\right) \\
& =E\left(h_{1}, \frac{1}{2}\left(\tilde{x}_{1}+\tilde{x}_{2}\right)\right)+|\log (1-\varepsilon)| \\
& \geqslant \frac{1}{2} E\left(h_{1}, \tilde{x}_{1}\right)+\frac{1}{2} E\left(h_{1}, \tilde{x}_{2}\right)+|\log (1-\varepsilon)| .
\end{aligned}
$$

Thus

$$
|\log (1-\varepsilon)| \leqslant \frac{1}{2}\left(E\left(h_{1}, \tilde{x}_{1}\right)-E\left(h_{1}, \tilde{x}_{2}\right)\right)
$$

Similarly,

$$
|\log (1-\varepsilon)| \leqslant \frac{1}{2}\left(E\left(h_{2}, \tilde{x}_{2}\right)-E\left(h_{2}, \tilde{x}_{1}\right)\right)
$$

Averaging the two inequalities yields

$$
\begin{aligned}
\varepsilon & \leqslant|\log (1-\varepsilon)| \leqslant \frac{1}{4}\left(E\left(h_{1}, \tilde{x}_{1}\right)-E\left(h_{1}, \tilde{x}_{2}\right)-E\left(h_{2}, \tilde{x}_{1}\right)+E\left(h_{2}, \tilde{x}_{2}\right)\right) \\
& =\frac{1}{4} \sum_{j \in B}\left(h_{1, j}-h_{2, j}\right)\left(\log \tilde{x}_{1, j}-\log \tilde{x}_{2, j}\right) \\
& \leqslant \frac{1}{4}\left\|h_{1}-h_{2}\right\| \cdot|\log \varepsilon| \leqslant \frac{1}{4}\left\|h_{1}-h_{2}\right\| \varepsilon^{-1}
\end{aligned}
$$

Thus $\varepsilon \leqslant \frac{1}{2}\left\|h_{1}-h_{2}\right\|^{1 / 2}$. Hence $\left\|\frac{1}{2}\left(x_{1}+x_{2}\right)\right\|=1-2 \varepsilon \geqslant 1-\left\|h_{1}-h_{2}\right\|^{1 / 2}$.
Proposition 2.4. Let $X$ be a uniformly convex Banach space with a 1-unconditional basis. The map $F_{X}: S\left(l_{1}\right) \cap c_{00} \rightarrow S(X)$ is uniformly continuous. Moreover the modulus of continuity of $F_{X}$ depends solely on the modulus of uniform convexity of $X$.

Proof. The uniform continuity of $F_{X}$ on $S\left(l_{1}\right)^{+} \cap c_{00}$ follows immediately from Proposition 2.3 (B).

Precisely, there is a function $g(\varepsilon)$, depending solely upon the modulus of uniform convexity of $X$, which is continuous at 0 with $g(0)=0$ and satisfies

$$
\left\|F_{X}\left(h_{1}\right)-F_{X}\left(h_{2}\right)\right\| \leqslant g\left(\left\|h_{1}-h_{2}\right\|\right)
$$

for $h_{1}, h_{2} \in S\left(l_{1}\right)^{+} \cap c_{00}$. A consequence of this is that if $h \in S\left(l_{1}\right)^{+} \cap c_{00}, x=F_{X}(h)$ and $I \subseteq \mathbf{N}$ is such that $\|I h\|<\varepsilon$ then $\|I x\|<g(2 \varepsilon)$. Indeed if $J=\mathbf{N} \backslash I$,

$$
\left\|h-\frac{J h}{\|J h\|}\right\|=\|I h\|+\left\|J h-\frac{J h}{\|J h\|}\right\|<2 \varepsilon .
$$

Thus since $I x=I\left(F_{X}(h)-F_{X}(J h /\|J h\|)\right)$,

$$
\|I x\| \leqslant\left\|F_{X}(h)-F_{X}\left(\frac{J h}{\|J h\|}\right)\right\|<g(2 \varepsilon)
$$

For the general case let $h_{1}, h_{2} \in S\left(l_{1}\right) \cap c_{00}$ with $\left\|h_{1}-h_{2}\right\|=\varepsilon$. Let $F_{X}\left(\left|h_{i}\right|\right)=\left|x_{i}\right|$ for $i=1,2$. Then $x_{i} \equiv \operatorname{sign} h_{i} \circ\left|x_{i}\right|$, 。 denoting pointwise multiplication, satisfies $x_{i}=F_{X}\left(h_{i}\right)$ for $i=1,2$. Also $\left\|\left|h_{1}\right|-\left|h_{2}\right|\right\| \leqslant\left\|h_{1}-h_{2}\right\|$. Thus if $I=\left\{j: \operatorname{sign} x_{1, j} \neq \operatorname{sign} x_{2, j}\right\}$,

$$
\begin{aligned}
\left\|x_{1}-x_{2}\right\| & \leqslant\left\|\left|x_{1}\right|-\left|x_{2}\right|\right\|+\left\|\sum_{j \in I}\left(\left|x_{1, j}\right|+\left|x_{2, j}\right|\right) e_{j}\right\| \\
& \leqslant g\left(\left\|\left|h_{1}\right|-\left|h_{2}\right|\right\|\right)+\left\|I\left|x_{1}\right|\right\|+\left\|I\left|x_{2}\right|\right\| \\
& \leqslant g(\varepsilon)+g(2 \varepsilon)+g(2 \varepsilon)
\end{aligned}
$$

Here is a fact we promised earlier.

Proposition 2.5. Let $X=l_{p}, 1<p<\infty$. Then $F_{X}$ is the Mazur map, i.e., if $h \in$ $S\left(l_{1}\right)^{+} \cap c_{00}$ then $F_{X}(h)=\left(h_{i}^{1 / p}\right)$.

Proof. Let $h \in S\left(l_{1}\right)^{+} \cap c_{00}, B=\operatorname{supp} h$ and $F_{X}(h)=x$. Then $\operatorname{supp} x=B$ and the vector $\left(x_{i}\right)_{i \in B}$ maximizes the function $\mathbf{R}_{+}^{B} \ni\left(y_{i}\right) \mapsto \sum_{i \in B} h_{i} \log y_{i}$ under the restriction $\sum_{i \in B} y_{i}^{p}=1$. By the method of Lagrange multipliers this implies that there is a number $c \neq 0$ so that $h_{i} / x_{i}=c p x_{i}^{p-1}$ for $i \in B$. Thus $x_{i}=(c p)^{-1 / p} h_{i}^{1 / p}$. Since $\|x\|_{p}=1$,

$$
c=p^{-1} \quad \text { and } \quad x_{i}=h_{i}^{1 / p} \text { for } i \in B .
$$

If $X$ is uniformly convex, by Proposition 2.4 the map $F_{X}$ extends uniquely to a uniformly continuous map, which we still denote by $F_{X}$, from $S\left(l_{1}\right) \rightarrow S(X)$.

Proposition 2.6. Let $X$ be a uniformly convex uniformly smooth Banach space with a 1 -unconditional basis. Then $F_{X}: S\left(l_{1}\right) \rightarrow S(X)$ is invertible and $\left(F_{X}\right)^{-1}$ is uniformly continuous, with modulus of continuity depending only on the modulus of uniform smoothness of $X$. For $x \in S(X), F_{X}^{-1}(x)=\operatorname{sign}(x) \circ x^{*} \circ x=\left|x^{*}\right| \circ x$ where $x^{*}$ is the unique support functional of $x$.

Proof. For $x \in S(X)$ there exists a unique element $x^{*} \in S\left(X^{*}\right)$ such that $x^{*}(x)=1$. The biorthogonal functionals ( $e_{i}^{*}$ ) are a 1 -unconditional basis for $X^{*}$ and thus we can express $x^{*}=\sum x_{i}^{*} e_{i}^{*}$ and write $x^{*}=\left(x_{i}^{*}\right)$. The element $x^{*} \circ x \in S\left(l_{1}\right)^{+}$and $\operatorname{sign} x^{*}=\operatorname{sign} x$. Let $G(x)=\left|x^{*}\right| \circ x . G$ is uniformly continuous. Indeed the map $S(X) \ni x \mapsto x^{*}$, the supporting functional, is uniformly continuous since $X$ is uniformly smooth. The modulus of continuity of this map depends solely on the modulus of uniform smoothness of $X$ (see e.g., [4, p. 36]). Let $G\left(x_{i}\right)=h_{i}=\left|x_{i}^{*}\right| \circ x_{i}$ for $i=1,2$. Then

$$
\begin{aligned}
\left\|h_{1}-h_{2}\right\| & =\left\|\left|x_{1}^{*}\right| \circ x_{1}-\left|x_{2}^{*}\right| \circ x_{2}\right\| \leqslant\left\|\left|x_{1}^{*}\right| \circ\left(x_{1}-x_{2}\right)\right\|+\left\|\left(\left|x_{1}^{*}\right|-\left|x_{2}^{*}\right|\right) \circ x_{2}\right\| \\
& \leqslant\left\|x_{1}^{*}\right\| \cdot\left\|x_{1}-x_{2}\right\|+\left\|\left|\left|x_{1}^{*}\right|-\left|x_{2}^{*}\right|\|\cdot\| x_{2}\|\leqslant\| x_{1}-x_{2}\|+\| x_{1}^{*}-x_{2}^{*} \|\right.\right.
\end{aligned}
$$

which proves that $G$ is uniformly continuous.
It remains only to show that $G=F_{X}^{-1}$. Since $G(x)=\operatorname{sign} x \circ G(|x|)$ we need only show that $G(F(h))=h$ for $h \in S\left(l_{1}\right)^{+} \cap c_{00}$ and $F(G(x))=x$ for $x \in S(X)^{+} \cap c_{00}$.

If $h \in S\left(l_{1}^{+}\right) \cap c_{00}$ and $x=F_{X}(h)$ then, as in the proof of Proposition 2.5, the method of Lagrange multipliers yields that $\vec{\nabla} E(h, x)=\left(h_{i} / x_{i}\right)_{i \in \text { supp } h}$ equals a multiple of $\left(x_{i}^{*}\right)_{i \in \text { supp } h}$ where $x^{*}$ is the support functional of $x$. This multiple must be 1 and $h_{i}=x_{i}^{*} \circ x_{i}$ or $G(F(h))=h$.

That $F(G(x))=x$ follows once we observe that if $h=x^{*} \circ x=y^{*} \circ y$, all norm 1 elements, then $x=y$. Assume for simplicity supp $h=\{1,2, \ldots, n\}$. Define $f(z)=\|z\|-E(h, z)$ for $z \in U$, a convex open subset of the positive cone $\mathrm{Ba}\left(\left(e_{i}\right\rangle_{i=1}^{n}\right)^{+}$which contains both $x$ and
$y$ and is bounded away from the boundary of the cone. $f(z)$ is strictly convex so $\vec{\nabla} f(z)=\overrightarrow{0}$ for at most one point. But $\vec{\nabla} f(z)=\overrightarrow{0}$ if and only if $h=z^{*} \circ z$.

Corollary 2.7 [37, Lemma 39.3]. Let $X$ have a 1-unconditional basis and let $h \in S\left(l_{1}^{+}\right) \cap c_{00}$ with $x \in F_{X}(h)$. Then there exists $x^{*} \in S\left(X^{*}\right)$ with $x^{*} \circ x=h$.

Proof. We may restrict our attention to $X=\left\langle e_{i}\right\rangle_{i \in \text { supp } h}$. The result follows if $X$ is smooth from the proof of Proposition 2.6. Let $\|\cdot\|_{n}$ be a sequence of smooth norms on $X$ with $\|\cdot\|_{n} \rightarrow\|\cdot\|$ and such that $x /\|x\|_{n} \in F_{X_{n}}(h)$. Then use a compactness argument.

Before proving Theorem 2.1 we need one more proposition. Recall that $X^{(p)}$ is the $p$-convexification of $X$. The map $G_{p}$ below is another generalization of the Mazur map.

Proposition 2.8. Let $1<p<\infty$ and let $X$ be a Banach space with a 1-unconditional basis. The map $G_{p}: S\left(X^{(p)}\right) \rightarrow S(X)$ given by $G_{p}(x)=\operatorname{sign}(x) \circ|x|^{p}=\left(\left(\operatorname{sign} x_{i}\right)\left|x_{i}\right|^{p}\right)$ for $x=\left(x_{i}\right)$ is a uniform homeomorphism. Moreover the modulus of continuity of $G_{p}$ and $G_{p}^{-1}$ are functions solely of $p$.

Proof. As usual ( $e_{i}$ ) denotes the normalized 1-unconditional basis of both $X$ and $X^{(p)}$. Let $x, y \in S\left(X^{(p)}\right)$ with $\delta \equiv\|x-y\|_{(p)}$. We shall show that

$$
2^{1-p} \delta^{p} \leqslant\left\|G_{p}(x)-G_{p}(y)\right\| \leqslant \delta^{p}+\delta^{p / 2}+2\left(1-(1-\sqrt{\delta})^{p}\right)
$$

which will complete the proof.
Let $x=\sum x_{i} e_{i}$ and $y=\sum y_{i} e_{i}$.

$$
\begin{aligned}
\left\|G_{p}(x)-G_{p}(y)\right\| & =\left\|\sum_{i=1}^{\infty}\left(\operatorname{sign}\left(x_{i}\right)\left|x_{i}\right|^{p}-\operatorname{sign}\left(y_{i}\right)\left|y_{i}\right|^{p}\right) e_{i}\right\| \\
& =\left\|\sum_{i \in I_{+}}\left(\left|x_{i}\right|^{p}-\left|y_{i}\right|^{p}\right) e_{i}+\sum_{i \in I_{-}}\left(\left|x_{i}\right|^{p}+\left|y_{i}\right|^{p}\right) e_{i}\right\|
\end{aligned}
$$

where

$$
I_{+}=\left\{i: \operatorname{sign}\left(x_{i}\right)=\operatorname{sign}\left(y_{i}\right)\right\} \quad \text { and } \quad I_{-}=\left\{i: \operatorname{sign}\left(x_{i}\right) \neq \operatorname{sign}\left(y_{i}\right)\right\} .
$$

We denote the two terms in the last norm expression as $d_{+}$and $d_{-}$, respectively.
Since $a^{p}-b^{p} \geqslant(a-b)^{p}$ and $a^{p}+b^{p} \geqslant 2^{1-p}(a+b)^{p}$ for $a \geqslant b \geqslant 0$ we deduce from the 1unconditionality of $\left(e_{i}\right)$ that

$$
\begin{aligned}
&\left\|d_{+}+d_{-}\right\| \geqslant\left\|\sum_{i \in I_{+}}| | x_{i}\left|-\left|y_{i}\right|\right|^{p} e_{i}+2^{1-p} \sum_{i \in I_{-}}\left(\left|x_{i}\right|+\left|y_{i}\right|\right)^{p} e_{i}\right\| \\
& \geqslant 2^{1-p}\left\|\sum\left|x_{i}-y_{i}\right|^{p} e_{i}\right\|=2^{1-p}\|x-y\|_{(p)^{\cdot}}^{p} .
\end{aligned}
$$

To prove the upper estimate we begin by noting that

$$
\left\|d_{-}\right\| \leqslant\left\|\sum_{i \in I_{-}}\left|x_{i}-y_{i}\right|^{p} e_{i}\right\| \leqslant\|x-y\|_{(p)}^{p}=\delta^{p}
$$

Set $q=1-\sqrt{\delta}$ and $c=(1-q)^{-p}=\delta^{-p / 2}$. For $a, b \geqslant 0$ with $0 \leqslant b \leqslant q a$ we have

$$
\begin{equation*}
c(a-b)^{p}-\left(a^{p}-b^{p}\right) \geqslant c(1-q)^{p} a^{p}-a^{p}=a^{p}\left(c(1-q)^{p}-1\right)=0 . \tag{2.5}
\end{equation*}
$$

Let $I_{+}^{\prime}=\left\{i \in I_{+}:\left|y_{i}\right|<q\left|x_{i}\right|\right.$ or $\left.\left|x_{i}\right|<q\left|y_{i}\right|\right\}$ and $I_{+}^{\prime \prime}=I_{+} \backslash I_{+}^{\prime}$. Write $d_{+}=d_{+}^{\prime}+d_{+}^{\prime \prime}$ where $d_{+}^{\prime}=$ $\sum_{i \in I_{+}^{\prime}}\left(\left|x_{i}\right|^{p}-\left|y_{i}\right|^{p}\right) e_{i}$ and $d_{+}^{\prime \prime}=d_{+}-d_{+}^{\prime}$. Thus (2.5) yields that

$$
\left\|d_{+}^{\prime}\right\| \leqslant c\left\|\sum_{i \in I_{+}^{\prime}}\right\| x_{i}\left|-\left|y_{i}\right|\right|^{p} e_{i}\left\|\leqslant \delta^{-p / 2}\right\| x-y \|_{(p)}^{p}=\delta^{p / 2}
$$

Furthermore,

$$
\left\|d_{+}^{\prime \prime}\right\| \leqslant\left(1-q^{p}\right)\left\|\sum_{i \in I_{+}^{\prime \prime}}\left(\left|x_{i}\right|^{p}+\left|y_{i}\right|^{p}\right) e_{i}\right\| \leqslant 2\left(1-q^{p}\right) \leqslant 2\left(1-(1-\sqrt{\delta})^{p}\right)
$$

Proof of Theorem 2.1. It follows quickly from work of Enflo that if $X$ contains $l_{\infty}^{n}$ uniformly in $n$ then $S(X)$ is not uniformly homeomorphic to a subset of $S\left(l_{1}\right)$. Indeed Enflo [5] proved that a certain family of finite subsets of $\mathrm{Ba}\left(l_{\infty}^{n}\right), n \in \mathbb{N}$, cannot be uniformly embedded into $\mathrm{Ba}\left(l_{2}\right)$ and hence neither into $\mathrm{Ba}\left(l_{1}\right)$. But $B\left(l_{\infty}^{n}\right)$ embeds isometrically into $S\left(l_{\infty}^{n+1}\right)$ and hence these finite subsets embed uniformly into $S(X)$.

For the converse assume that $X$ does not contain $l_{\infty}^{n}$ uniformly in $n$. We may suppose that $X$ has a 1 -unconditional basis $\left(e_{i}\right)$. Indeed if $\left(e_{i}\right)$ is a normalized basis for $X$, $|x| \equiv\left\|\sum\left|x_{i}\right| e_{i}\right\|$ is an equivalent 1 -unconditional norm. Furthermore the map $x \mapsto x /\|x\|$ is easily seen to be a uniform homeomorphism between $S(X,|\cdot|)$ and $S(X,\|\cdot\|)$.

By a theorem of Maurey and Pisier [23], $X$ has cotype $q^{\prime}$ for some $q^{\prime}<\infty$. This implies that $X$ is $q$-concave for all $q>q^{\prime}([19$, p. 88$])$. Fix $q>q^{\prime}$. There exists an equivalent norm on $X$ for which $\left(e_{i}\right)$ is still 1-unconditional and for which $M_{q}(X)=1$ ( $[19$, p. 54]). The 2-convexification of $X$ in this norm, $X^{(2)}$, satisfies $M_{2 q}\left(X^{(2)}\right)=1=M^{2}\left(X^{(2)}\right)$ ([19, p. 54]). In particular $X^{(2)}$ is uniformly convex and uniformly smooth ([19, p. 80]) and so $F_{X^{(2)}}: S\left(l_{1}\right) \rightarrow S\left(X^{(2)}\right)$ is a uniform homeomorphism by Proposition 2.6. Thus $G_{2} \circ F_{X^{(2)}}: S\left(l_{1}\right) \rightarrow S(X)$ is a uniform homeomorphism by Proposition 2.8.

Remark. If $X$ has a 1 -unconditional basis and $M_{q}(X)=1$ for some $q<\infty$, the map $G_{2} \circ F_{X^{(2)}}=F_{X}$. Furthermore the modulus of continuity of $F_{X}$ and $F_{X}^{-1}$ are functions solely of $q$.

The uniform homeomorphism theorem extends to unit balls by the following simple proposition.

Proposition 2.9. Let $X$ and $Y$ be Banach spaces and let $F: S(X) \rightarrow S(Y)$ be a uniform homeomorphism. For $x \in \operatorname{Ba}(X)$ let $\bar{F}(x)=\|x\| F(x /\|x\|)$ if $x \neq 0$ and $\bar{F}(0)=0$. Then $\widetilde{F}$ is a uniform homeomorphism between $\mathrm{Ba}(X)$ and $\mathrm{Ba}(Y)$.

Proof. Clearly $\bar{F}$ is a bijection. Since $\bar{F}^{-1}(y)=\|y\| F^{-1}(y /\|y\|)$ for $y \neq 0$, it suffices to show that $\bar{F}$ is uniformly continuous. Let $f$ be the modulus of continuity of $F$, i.e., $\left\|F\left(x_{1}\right)-F\left(x_{2}\right)\right\| \leqslant f\left(\left\|x_{1}-x_{2}\right\|\right)$.

Let $x_{1}, x_{2} \in \mathrm{Ba}(X)$ with $\left\|x_{1}-x_{2}\right\|=\delta, \lambda_{1}=\left\|x_{1}\right\|, \lambda_{2}=\left\|x_{2}\right\|$ and $\lambda_{1} \geqslant \lambda_{2}$.

$$
\begin{aligned}
\left\|\bar{F}\left(x_{1}\right)-\bar{F}\left(x_{2}\right)\right\| & =\left\|\lambda_{1} F\left(\frac{x_{1}}{\lambda_{1}}\right)-\lambda_{2} F\left(\frac{x_{2}}{\lambda_{2}}\right)\right\| \\
& \leqslant\left(\lambda_{1}-\lambda_{2}\right)+\lambda_{2}\left\|F\left(\frac{x_{1}}{\lambda_{1}}\right)-F\left(\frac{x_{2}}{\lambda_{2}}\right)\right\| .
\end{aligned}
$$

If $\lambda_{2}<\delta^{1 / 4}$ this is less than $\delta+2 \delta^{1 / 4}$. Otherwise

$$
\begin{aligned}
\left\|\frac{x_{1}}{\lambda_{1}}-\frac{x_{2}}{\lambda_{2}}\right\| & =\frac{1}{\lambda_{1} \lambda_{2}}\left\|\lambda_{2} x_{1}-\lambda_{1} x_{2}\right\| \\
& \leqslant \frac{1}{\lambda_{1} \lambda_{2}}\left[\lambda_{1}\left\|x_{1}-x_{2}\right\|+\lambda_{1}-\lambda_{2}\right] \leqslant \frac{\delta}{\lambda_{2}}+\frac{\delta}{\lambda_{1} \lambda_{2}} \\
& \leqslant \frac{2 \delta}{\lambda_{1} \lambda_{2}} \leqslant \frac{2 \delta}{\sqrt{\delta}}=2 \sqrt{\delta} .
\end{aligned}
$$

Thus

$$
\left\|\bar{F}\left(x_{1}\right)-\bar{F}\left(x_{2}\right)\right\| \leqslant \max \left(\delta+f(2 \sqrt{\delta}), \delta+2 \delta^{1 / 4}\right) .
$$

Remark. It is not possible, in general, to replace "uniformly homeomorphic" by "Lipschitz equivalent" in Theorem 2.1. Indeed if $S(X)$ and $S(Y)$ are Lipschitz equivalent, then an argument much like that of Proposition 2.9, yields that $X$ and $Y$ are Lipschitz equivalent which need not be true (see [1]).

There exist separable infinite dimensional Banach spaces $X$ not containing $l_{\infty}^{n}$ 's uniformly such that $\mathrm{Ba}(X)$ does not embed uniformly into $l_{2}$. For example the James' nonoctohedral space [12] has this property. Indeed, Y. Raynaud [31] proved that if $X$ is not reflexive and $\mathrm{Ba}(X)$ embeds uniformly into $l_{2}$, then $X$ admits an $l_{1}$-spreading model.

Fouad Chaatit [2] has extended Theorem 2.1. He showed one can replace the hypothesis that $X$ has an unconditional basis with the more general assumption that $X$ is a separable infinite dimensional Banach lattice. N. J. Kalton [15] and M. Daher [3] have subsequently discovered proofs of this result using complex interpolation theory.

## 3. $l_{\mathbf{2}}$ is arbitrarily distortable

Let $X$ be a Banach space with a basis $\left(e_{i}\right)$. A block subspace of $X$ is any subspace spanned by a block basis of $\left(e_{i}\right) . X$ is sequentially arbitrarily distortable if there exist a sequence of equivalent norms $\|\cdot\|_{i}$ on $X$ and $\varepsilon_{i} \downarrow 0$ such that:
$\|\cdot\|_{i} \leqslant\|\cdot\|$ for all $i$ and for all subspaces $Y$ of $X$, and for all $i_{0} \in \mathbf{N}$ there exists $y \in S\left(Y,\|\cdot\|_{i_{0}}\right)$ with $\|y\|_{i} \leqslant \varepsilon_{\min \left(i, i_{0}\right)}$ for $i \neq i_{0}$.

We note that if $X$ contains an asymptotic biorthogonal system with vanishing constant (see [10]), then $X$ is sequentially arbitrarily distortable.

If $X$ is sequentially arbitrarily distortable then $X$ is arbitrarily distortable. Indeed fix $i>1$ and let $Y$ be a subspace of $X$. Choose $x \in Y$ with $\|x\|_{i}=1$ and $\|x\|_{1} \leqslant \varepsilon_{1}$. Let $\|\cdot\|_{1} \leqslant$ $\|\cdot\| \leqslant C_{1}\|\cdot\|_{1}$ and $\tilde{x}=x /\|x\|$. Then $\|\tilde{x}\|_{i}=1 /\|x\| \geqslant 1 / C_{1} \varepsilon_{1}$. Choose $y \in Y$ with $\|y\|_{i+1}=1$ and $\|y\|_{i} \leqslant \varepsilon_{i}$. Then for $\tilde{y}=y /\|y\|_{,}\|\tilde{y}\|_{i} \leqslant \varepsilon_{i} /\|y\| \leqslant \varepsilon_{i}$. Thus $\|\tilde{x}\|_{i} /\|\tilde{y}\|_{i} \geqslant 1 / C_{1} \varepsilon_{1} \varepsilon_{i}$. Furthermore we have

Theorem 3.1. Let $X$ be a sequentially arbitrarily distortable Banach space with a basis $\left(e_{i}\right)$. For all $n \in \mathbf{N}$ and $\varepsilon>0$ there exists an equivalent norm $|\cdot|$ on $X$ with the following property. Let $\left(y_{i}\right)_{i=1}^{n}$ be a normalized monotone basis for an n-dimensional Banach space. Then every block basis of $\left(e_{i}\right)$ admits a further finite block basis $\left(x_{i}\right)_{i=1}^{n}$ which is $(1+\varepsilon)$-equivalent to $\left(y_{i}\right)_{i=1}^{n}$.

The space $S$ of [34] was shown in [10] to be sequentially arbitrarily distortable. The argument used to prove Theorem 3.1 is a slight variation of an argument which appears in [10] which, in turn, has its origins in [24].

Proof of Theorem 3.1. Choose for $n \in \mathbf{N}$ and $\varepsilon>0,\left(B_{i}\right)_{i=1}^{k(n)}$ a finite sequence of $n$ dimensional Banach spaces, each having a normalized monotone basis, such that every normalized monotone basis of length $n$ is $(1+\varepsilon)$-equivalent to the basis of some $B_{i}^{n}$. Let $\left(w_{i}\right)_{i=1}^{\infty}$ be a normalized monotone basis for $W \equiv\left(\sum_{n, i} B_{i}^{n}\right)_{l_{2}}$ such that the monotone basis of each $B_{i}^{n}$ is 1-equivalent to $\left(w_{i}\right)_{i \in A_{i}^{n}}$ for some segment $A_{i}^{n} \subseteq \mathbf{N}$. Let ( $w_{i}^{*}$ ) be the biorthogonal functionals of $\left(w_{i}\right)$.

It suffices to prove that for all $n \in \mathbf{N}$ there exists an equivalent norm $|\cdot|$ on $X$ such that every block basis of $\left(e_{i}\right)$ admits a further block basis $\left(x_{i}\right)_{i=1}^{n}$ which is $(1+8 / n)$ equivalent to $\left(w_{i}\right)_{i=1}^{n}$.

Let $n \in \mathbf{N}, \varepsilon_{i} \downarrow 0$ and let $\|\cdot\|_{i}$ be a sequence of equivalent norms on $X$ satisfying the definition of sequentially arbitrarily distortable. Let $\varepsilon>0$ with $n^{5} \varepsilon<1$. We may assume that $\max _{i} \varepsilon_{i}<\frac{1}{4} \varepsilon$.

Let $X_{i}=\left(X,\|\cdot\|_{i}\right)$. Let $\left(z_{i}^{*}\right)_{i=2}^{\infty}$ be an enumeration of all elements of the linear span
of $\left(e_{i}^{*}\right)$ which have rational coordinates. Set

$$
\begin{aligned}
\Gamma=\left\{z^{*}=\right. & \sum_{i=1}^{n} b_{i} \sum_{j=(i-1) n+1}^{i n} z_{k_{j}}^{*}: k_{1}<\ldots<k_{n^{2}},\left(z_{k_{i}}^{*}\right)_{i=1}^{n^{2}} \text { is a finite } \\
& \text { block basis of }\left(e_{i}^{*}\right) \text { with } z_{k_{1}}^{*} \in 3 \mathrm{Ba}\left(X_{1}^{*}\right), \\
& \left.z_{k_{i+1}}^{*} \in 3 \mathrm{Ba}\left(X_{k_{i}}^{*}\right) \text { for } 1 \leqslant i \leqslant n^{2}-1 \text { and } \sum_{i=1}^{n} b_{i} w_{i}^{*} \in \mathrm{Ba}\left(W^{*}\right)\right\} .
\end{aligned}
$$

Define $|\cdot|$ on $X$ by

$$
|x|=\sup \left\{\left|z^{*}(x)\right|: z^{*} \in \Gamma\right\} .
$$

Then $3\|x\|_{1} \leqslant|x| \leqslant 6 n^{2}\|x\|$ for all $x \in X$ and so $|\cdot|$ is an equivalent norm on $X$.
Let $Z$ be any block subspace of $X$. Since $X$ being distortable cannot contain $l_{1}$ [11], we may assume by [33] that $Z$ is spanned by a normalized weakly null block basis of $\left(e_{i}\right)$, denoted $\left(z_{i}\right)$. Using the argument that a subsequence of $\left(z_{i}\right)$ is nearly monotone for any given norm $|\cdot|_{i}$ and a diagonal argument we may suppose that for all $i,\left\|P_{A}\right\|_{i}<2.5$ whenever $A \subseteq \mathbf{N}$ is a segment of $\mathbf{N}$ with $i \leqslant \min A$. (Here $P_{A}$ is the projection $P_{A}\left(\sum a_{i} z_{i}\right)=$ $\sum_{i \in A} a_{i} z_{i}$.)

From our hypotheses we can then choose block bases $\left(\bar{x}_{i}\right)_{i=1}^{n^{2}}$ of $\left(z_{i}\right)$, and $\left(z_{k_{i}}^{*}\right)_{i=1}^{n^{2}}$ of ( $e_{i}^{*}$ ) satisfying $k_{1}<k_{2}<\ldots<k_{n^{2}}$ and
(i) $z_{k_{1}}^{*} \in 3 \mathrm{Ba}\left(X_{1}^{*}\right)$ and $z_{k_{i+1}}^{*} \in 3 \mathrm{Ba}\left(X_{k_{i}}^{*}\right)$ for $1 \leqslant i<n^{2}$,
(ii) $z_{k_{i}}^{*}\left(\bar{x}_{j}\right)=\delta_{i j}$ for $1 \leqslant i, j \leqslant n^{2}$,
(iii) $\left\|\bar{x}_{i}\right\|_{j}<\frac{1}{3} \varepsilon$ if $j \neq k_{i-1}$ and $\left\|\bar{x}_{i}\right\|_{k_{i-1}} \leqslant 1$.

Let $x_{i}=(1 / n) \sum_{j=(i-1) n+1}^{i n} \bar{x}_{j}$ for $1 \leqslant i \leqslant n$, and let $\left\|\sum_{1}^{n} a_{i} w_{i}\right\|=1=\sum_{1}^{n} a_{i} b_{i}$ where $\left\|\sum_{1}^{n} b_{i} w_{i}^{*}\right\|=1$. Let

$$
z^{*}=\sum_{i=1}^{n} b_{i} \sum_{j=(i-1) n+1}^{i n} z_{k_{j}}^{*}
$$

and note that $z^{*} \in \Gamma$. Thus

$$
\left|\sum_{1}^{n} a_{i} x_{i}\right| \geqslant z^{*}\left(\sum_{1}^{n} a_{i} x_{i}\right)=\sum_{1}^{n} a_{i} b_{i}=1 .
$$

For the reverse inequality, let $\bar{z}^{*}=\sum_{i=1}^{n} c_{i} \sum_{j=(i-1) n+1}^{i n} z_{m_{j}}^{*} \in \Gamma$ with $z_{m_{1}}^{*} \in 3 \mathrm{Ba}\left(X_{1}^{*}\right)$, $z_{m_{i+1}}^{*} \in 3 \mathrm{Ba}\left(X_{m_{i}}^{*}\right)$ for $i<n^{2}$ and $\left\|\sum_{1}^{n} c_{i} w_{i}^{*}\right\| \leqslant 1$. Let $j_{0}$ be the smallest integer such that $m_{j_{0}} \neq k_{j_{0}}$. We first deduce from the definition of $\Gamma$ and the choice of $\left(\bar{x}_{i}\right)$ that $\left|z_{m_{i}}^{*}\left(\bar{x}_{j}\right)\right|<\varepsilon$ and $\left|z_{m_{j}}^{*}\left(\tilde{x}_{i}\right)\right|<\varepsilon$ if $i<j_{0}, j \leqslant n^{2}$ and $i \neq j$. Secondly we claim that

$$
\left\{m_{j_{0}}, m_{j_{0}+1}, \ldots, m_{n^{2}}\right\} \cap\left\{k_{j_{0}}, k_{j_{0+1}}, \ldots, k_{n^{2}}\right\}=\varnothing
$$

Indeed, if not, let $j \geqslant j_{0}$ be the smallest integer such that $m_{j}=k_{i}$ for some $i \geqslant j_{0}$. If $j=j_{0}$ then $i>j_{0}$. But then (letting $\left.k_{0} \equiv 1\right) z_{m_{j}}^{*} \in 3 \mathrm{Ba}\left(X_{k_{j_{0}-1}}^{*}\right)$ and $\left\|\bar{x}_{i}\right\|_{k_{j_{0}-1}}<\frac{1}{3} \varepsilon$ which contradicts $z_{k_{i}}^{*}\left(\bar{x}_{i}\right)=1$. If $j>j_{0}$ then $z_{m_{j}}^{*} \in 3 \mathrm{Ba}\left(X_{m_{j-1}}^{*}\right)$ and $\left\|\bar{x}_{i}\right\|_{m_{j-1}}<\frac{1}{3} \varepsilon$ since $m_{j-1} \neq$ $k_{i-1}$, yielding again a contradiction to $z_{k_{i}}^{*}\left(\bar{x}_{i}\right)=1$.

It follows that $\left|z_{m_{j_{0}}}^{*}\left(\bar{x}_{i}\right)\right|<\varepsilon$ if $i \neq j_{0}$ and $\left|z_{m_{j}}^{*}\left(\bar{x}_{i}\right)\right|<\varepsilon$ if $j>j_{0}$ and $i \leqslant n^{2}$. Let $j_{0}=$ $i_{0} n+s_{0}$ with $0 \leqslant i_{0}<n, 1 \leqslant s_{0} \leqslant n$. Then

$$
\begin{aligned}
\left|\bar{z}^{*}\left(\sum_{i=1}^{n} a_{i} x_{i}\right)\right| & =\left|\left(\sum_{i=1}^{n} c_{i} \sum_{j=(i-1) n+1}^{i n} z_{m_{j}}^{*}\right)\left(\sum_{i=1}^{n} a_{i} \frac{1}{n} \sum_{j=(i-1) n+1}^{i n} \bar{x}_{j}\right)\right| \\
& \leqslant\left|\sum_{i=1}^{i_{0}} c_{i} a_{i}+\frac{s_{0}-1}{n} c_{i_{0}+1} a_{i_{0}+1}\right|+3\left|\frac{c_{i_{0}+1} a_{i_{0}+1}}{n}\right|+n^{4} \varepsilon \max _{i}\left|a_{i} c_{i}\right| \\
& \leqslant\left\|\sum_{1}^{n} a_{i} w_{i}\right\|\left[1+\frac{6}{n}+\frac{2}{n}\right] .
\end{aligned}
$$

We used that from monotonicity the first term in the next to last inequality does not exceed

$$
\max \left(\left|\sum_{i=1}^{i_{0}} c_{i} a_{i}\right|,\left|\sum_{i=1}^{i_{0}+1} c_{i} a_{i}\right|\right) \leqslant\left\|\sum_{1}^{n} a_{i} w_{i}\right\|
$$

and $\left|c_{i} a_{i}\right| \leqslant 2$ for all $i$.
Remark. The proof of Theorem 3.1 requires only the following condition. For all $\varepsilon>0$ there exists a sequence of equivalent norms $\|\cdot\|_{i} \leqslant\|\cdot\|$ on $X$ such that for all subspaces $Z$ of $X$ and all $i_{0} \in \mathbf{N}$ there exists $y \in S\left(Z,\|\cdot\|_{i_{0}}\right)$ with $\|y\|_{i}<\varepsilon$ if $i \neq i_{0}$. Theorem 1.2 is a special case of Theorem 3.1.

Theorem 1.2 yields that a sequentially arbitrarily distortable Banach space can be renormed to not contain an almost bimonotone basic sequence. Since $\left\|s_{1}-2 s_{2}\right\|=1$, the best constant that can be achieved for the norm of the tail projections of a basic sequence is 2 .

Other curious norms can be put on sequentially arbitrarily distortable spaces $X$. For example let $\left(w_{i}\right)_{i=1}^{n}$ be a normalized 1-unconditional 1 -subsymmetric finite basic sequence and let $\varepsilon>0$. One can find a norm on $X$ such that every block basis contains a further block basis $\left(z_{i}\right)$ with $\left(z_{k_{i}}\right)_{i=1}^{n} \stackrel{1+\varepsilon}{\sim}\left(w_{i}\right)_{i=1}^{n}$ whenever $k_{1}<\ldots<k_{n}$. This is accomplished by taking (using the terminology of the proof of Theorem 3.1)

$$
\begin{aligned}
\Gamma=\left\{z^{*}=\right. & \sum_{i=1}^{n} b_{i} \sum_{j=\left(k_{i}-1\right) n+1}^{k_{i} n} z_{m_{j}}^{*}:\left(z_{m_{j}}^{*}\right)_{j=1}^{\infty} \text { is a block basis of }\left(e_{i}^{*}\right) \\
& \text { with } z_{m_{1}}^{*} \in 3 \mathrm{Ba}\left(X_{1}^{*}\right), z_{m_{j_{+1}}}^{*} \in 3 \mathrm{Ba}\left(X_{m_{j}}^{*}\right) \text { for } j \in \mathbf{N}, \\
& \left.k_{1}<k_{2}<\ldots<k_{n} \text { and }\left\|\sum_{1}^{n} b_{i} w_{i}^{*}\right\| \leqslant 1\right\} .
\end{aligned}
$$

Theorem 3.2. For $1<p<\infty, l_{p}$ is sequentially arbitrarily distortable.
In order to prove Theorem 3.2 we will make use of the Banach space $S$ introduced in [34].

The space $S$ has a 1-unconditional 1-subsymmetric normalized basis ( $e_{i}$ ) whose norm satisfies the following implicit equation

$$
\|x\|=\max \left\{\|x\|_{c_{0}}, \sup _{\substack{l \geqslant 2 \\ E_{1}<E_{2}<\ldots<E_{l}}} \frac{1}{\phi(l)} \sum_{i=1}^{l}\left\|E_{i} x\right\|\right\}
$$

where $\phi(l)=\log _{2}(1+l)$.
The fact that $S$ is arbitrarily distortable [34] and complementably minimal [35] hinges heavily on two types of vectors which live in all block subspaces: $l_{1}^{n}+$ averages and averages of rapidly increasing $l_{1}^{n_{i}}+$ averages or RIS vectors. Precisely, following the terminology of [10], we call $x \in S$ an $l_{1}^{n}+$ average with constant $C$ if $\|x\|=1$ and $x=\sum_{i=1}^{n} x_{i}$ for some block basis $\left(x_{i}\right)_{i=1}^{n}$ of $\left(e_{i}\right)$ where $\left\|x_{i}\right\| \leqslant C n^{-1}$ for all $i$.

Let $M_{\phi}(x)=\phi^{-1}\left(36 x^{2}\right)$ for $x \in \mathbf{R}$. A block basis $\left(x_{i}\right)_{i=1}^{N}$ is an RIS of length $N$ with constant $C \equiv 1+\varepsilon<2$ if each $x_{k}$ is an $l_{1}^{n_{k}}+$ average with constant $C$,

$$
n_{1} \geqslant 2 C M_{\phi}(N / \varepsilon) / 2 \varepsilon \ln 2
$$

and

$$
\frac{1}{2} \varepsilon \phi\left(n_{k}\right)^{1 / 2} \geqslant\left|\operatorname{supp}\left(x_{k-1}\right)\right| \quad \text { for } k=2, \ldots, N
$$

The vector $x=\left(\sum_{i=1}^{N} x_{i}\right) /\left\|\sum_{i=1}^{N} x_{i}\right\|$ is called an RIS vector of length $N$ and constant $C$ and we say that the RIS sequence $\left(x_{i}\right)_{i=1}^{N}$ generates $x$.

Lemma 3.3 [10]. Let $\varepsilon_{i} \downarrow 0$. There exist integers $p_{k} \uparrow \infty$ and reals $\delta_{k} \downarrow 0$ with

$$
\left(1+2 \delta_{k}\right)^{-1}>1-\varepsilon_{k}
$$

so that if

$$
A_{k}=\left\{x \in S: x \text { is an RIS vector of length } p_{k} \text { with constant } 1+\delta_{k}\right\}
$$

and

$$
A_{k}^{*}=\left\{x^{*} \in S^{*}: x^{*}=\frac{1}{\phi\left(p_{k}\right)} \sum_{1}^{p_{k}} x_{i}^{*} \text { where }\left(x_{i}^{*}\right)_{1}^{p_{k}} \text { is a block sequence in } \mathrm{Ba}\left(S^{*}\right)\right\}
$$

then:
(a) $\left|x_{k}^{*}\left(x_{l}\right)\right|<\varepsilon_{\min (k, l)}$ if $k \neq l, x_{k}^{*} \in A_{k}^{*}$ and $x_{l} \in A_{l}$.
(b) For all $k \in \mathbf{N}$ and $x \in A_{k}$ there exists $x^{*} \in A_{k}^{*}$ with $x^{*}(x)>1-\varepsilon_{k}$. This follows from the fact if $x$ is generated by $\left(x_{i}\right)_{i=1}^{p_{k}}$, then $\left\|\sum_{1}^{p_{k}} x_{i}\right\| \leqslant\left(1+2 \delta_{k}\right) p_{k} / \phi\left(p_{k}\right)$.

Moreover $A_{k}$ is asymptotic in $S$ for all $k \in \mathbf{N}$.

Using the sets $A_{k}$ and $A_{k}^{*}$ we can define the following subsets of $l_{1}$

$$
B_{k}=\left\{x_{k}^{*} \circ x_{k} /\left|x_{k}^{*}\right|\left(\left|x_{k}\right|\right): x_{k}^{*} \in A_{k}^{*}, x_{k} \in A_{k} \text { and }\left|x_{k}^{*}\right|\left(\left|x_{k}\right|\right)=\left\|x_{k}^{*} \circ x_{k}\right\|_{1} \geqslant 1-\varepsilon_{k}\right\} .
$$

A set of sequences $B$ is unconditional if $x=\left(x_{i}\right) \in B$ implies that $\left( \pm x_{i}\right) \in B$ for all choices of signs and $B$ is spreading if $x=\left(x_{i}\right) \in B$ implies $\sum_{i} x_{i} e_{n_{i}} \in B$ for all increasing sequences $\left(n_{i}\right)$. Note that $A_{k}^{*} \subseteq \mathrm{Ba}\left(S^{*}\right)$ and the sets $A_{k}$ and $A_{k}^{*}$ are unconditional and spreading. Thus the sets $B_{k} \subseteq S\left(l_{1}\right)$ are also spreading and unconditional.

Theorem 3.4. The sets $B_{k} \subseteq S\left(l_{1}\right), k \in \mathbf{N}$, are unconditional, spreading and asymptotic.

We postpone the proof of Theorem 3.4.
Proof of Theorem 3.2. We first give the argument for $p=2$. Let $C_{k}=\left\{v \in S\left(l_{2}\right)\right.$ : $\left.|v|^{2} \in B_{k}\right\} . C_{k}$ is just the image of $B_{k}$ in $S\left(l_{2}\right)$ under the Mazur map. Since the Mazur map preserves block subspaces and is a uniform homeomorphism, $C_{k}$ is asymptotic in $l_{2}$ for all $k$. Moreover the $C_{k}$ 's are nearly biorthogonal. Indeed if $v_{k} \in C_{k}, v_{l} \in C_{l}$ with $k \neq l$ let $\left|v_{k}\right|^{2}=\left(x_{k}^{*} \circ x_{k}\right) /\left|x_{k}^{*}\right|\left(\left|x_{k}\right|\right)$ and $\left|v_{l}\right|^{2}=\left(x_{l}^{*} \circ x_{l}\right) /\left|x_{l}^{*}\right|\left(\left|x_{l}\right|\right)$ be as in the definition of $B_{k}$ and $B_{l}$. Then letting $\lambda=\left(1-\varepsilon_{1}\right)^{-1}$

$$
\begin{aligned}
\langle | v_{k}\left|,\left|v_{l}\right|\right\rangle & \leqslant \lambda \sum_{j}\left|x_{k}^{*}(j) x_{k}(j) x_{l}^{*}(j) x_{l}(j)\right|^{1 / 2} \\
& \leqslant \lambda\left(\sum_{j}\left|x_{k}^{*}(j) x_{l}(j)\right|\right)^{1 / 2}\left(\sum_{j}\left|x_{l}^{*}(j) x_{k}(j)\right|\right)^{1 / 2} \quad \text { (by Cauchy-Schwarz) } \\
& =\lambda\left(\left|x_{k}^{*}\right|,\left|x_{l}\right|\right\rangle^{1 / 2}\left(\left|x_{l}^{*}\right|,\left|x_{k}\right|\right\rangle^{1 / 2} \leqslant \lambda \varepsilon_{\min (k, l)} \quad \text { (by Lemma 3.3). }
\end{aligned}
$$

Define $\|x\|_{k}=\sup \left\{|\langle x, v\rangle|: v \in C_{k} \cup \varepsilon_{k} \mathrm{Ba}\left(l_{2}\right)\right\}$.
If $p \neq 2$ we use a similar argument. Let $C_{k}=\left\{v \in S\left(l_{p}\right):|v|^{p} \in B_{k}\right\}$ and $D_{k}=\left\{v \in S\left(l_{q}\right)\right.$ : $\left.|v|^{q} \in B_{k}\right\}$ where $1 / p+1 / q=1$. Define $\|\cdot\|_{k}$ on $l_{p}$ by

$$
\|x\|_{k}=\sup \left\{|\langle x, v\rangle|: v \in D_{k} \cup \varepsilon_{k} \operatorname{Ba}\left(l_{q}\right)\right\} .
$$

Again, via the Mazur map, $C_{k}$ is asymptotic in $l_{p}$.
Let $v_{k} \in C_{k}$ and $v_{l} \in D_{l}$ with $k \neq l$. Let $\left|v_{k}\right|^{p}=\left(x_{k}^{*} \circ x_{k}\right) /\left|x_{k}^{*}\right|\left(\left|x_{k}\right|\right)$ and $\left|v_{l}\right|^{q}=\left(x_{l}^{*} \circ x_{l}\right) /$ $\left|x_{l}^{*}\right|\left(\left|x_{l}\right|\right)$ be as in the definition of $B_{k}$ and $B_{l}$. Assume $p>2$. Then

$$
\begin{aligned}
\left.\left|\langle | v_{k}\right|,\left|v_{l}\right|\right\rangle \mid & \leqslant \lambda \sum_{j}\left|x_{k}^{*}(j) x_{k}(j)\right|^{1 / p}\left|x_{l}^{*}(j) x_{l}(j)\right|^{1 / q} \\
& =\lambda \sum_{j}\left|x_{k}^{*}(j) x_{k}(j) x_{l}^{*}(j) x_{l}(j)\right|^{1 / p}\left|x_{l}^{*}(j) x_{l}(j)\right|^{1 / q-1 / p} .
\end{aligned}
$$

Using Hölder's inequality with exponents $\frac{1}{2} p$ and $p /(p-2)$ and the fact that $1 / q-1 / p=$ $(p-2) / p$ we obtain that the last expression is

$$
\leqslant \lambda\left(\sum_{j}\left|x_{k}^{*}(j) x_{k}(j) x_{l}^{*}(j) x_{l}(j)\right|^{1 / 2}\right)^{2 / p}\left(\sum_{j}\left|x_{l}^{*}(j) x_{l}(j)\right|\right)^{(p-2) / p} \leqslant \lambda \varepsilon_{\min (k, l)}^{2 / p}
$$

from the first part of the proof. The same estimates prevail if $p<2$.
Remark. The proof yields that for $1<p<\infty, 1 / p+1 / q=1$ there exist sequences $C_{k} \subseteq$ $S\left(l_{p}\right)$ and $D_{k} \subseteq S\left(l_{q}\right)$ of nearly biorthogonal asymptotic unconditional spreading sets.

It remains only to prove Theorem 3.4 which entails only showing that each $B_{k}$ is asymptotic. This will follow from the following

Lemma 3.5. Let $Y$ be a block subspace of $l_{1}$ and let $\varepsilon>0, m \in \mathbf{N}$. There exists a vector $u \in S$ which is an $l_{1}^{m}+$ average with constant $1+\varepsilon$ and $u^{*} \in \mathrm{Ba}\left(S^{*}\right)$ with $d\left(u^{*} \circ u, S(Y)\right)<\varepsilon$.

Indeed assume that the lemma is proved and let $k \in \mathbf{N}$ and $\varepsilon>0$ with

$$
(1+\varepsilon)^{-1}\left(1+2 \delta_{k}\right)^{-1}>1-\varepsilon_{k} .
$$

From the lemma we can find finite block sequences $\left(u_{i}\right)_{i=1}^{p_{k}} \subseteq S(S)$ and $\left(u_{i}^{*}\right)_{i=1}^{p_{k}} \subseteq \operatorname{Ba}\left(S^{*}\right)$ along with a normalized block sequence $\left(y_{i}\right)_{i=1}^{p_{k}} \subseteq S(Y)$ and $1 \leqslant \lambda_{i}<1+\varepsilon$ for $i \leqslant p_{k}$ such that
(1) $u=\left(\sum_{i=1}^{p_{k}} u_{i}\right) /\left\|\sum_{i=1}^{p_{k}} u_{i}\right\|$ is an RIS vector of length $p_{k}$ and constant $\left(1+\delta_{k}\right)$ generated by the RIS $\left(u_{i}\right)_{i=1}^{p_{k}}$,
(2) $\left\|u_{i}^{*} \circ u_{i}-y_{i}\right\|_{1}<\varepsilon$ for $i \leqslant p_{k}$,
(3) $u_{i}^{*} \circ u_{j}=0$ if $i \neq j$ and $\left\|\lambda_{i} u_{i}^{*} \circ u_{i}\right\|_{1}=1$ for $i \leqslant p_{k}$.

Let $u^{*}=\left(1 /(1+\varepsilon) \phi\left(p_{k}\right)\right) \sum_{1}^{p_{k}} \lambda_{i} u_{i}^{*}$. Then $u^{*} \in A_{k}^{*}$ and from Lemma 3.3 (b)

$$
\left\|u^{*} \circ u\right\|_{1}=\frac{1}{(1+\varepsilon) \phi\left(p_{k}\right)} \cdot \frac{p_{k}}{\left\|\sum_{1}^{p_{k}} u_{i}\right\|} \geqslant \frac{1}{(1+\varepsilon)\left(1+2 \delta_{k}\right)}>1-\varepsilon_{k} .
$$

Thus $\left(u^{*} \circ u\right) /\left\|u^{*} \circ u\right\|_{1} \in B_{k}$. Now $\left(u^{*} \circ u\right) /\left\|u^{*} \circ u\right\|_{1}=\left(1 / p_{k}\right) \sum_{1}^{p_{k}} \lambda_{i} u_{i}^{*} \circ u_{i}$ and so using (2)

$$
\left\|\frac{u^{*} \circ u}{\left\|u^{*} \circ u\right\|_{1}}-\frac{1}{p_{k}} \sum_{1}^{p_{k}} y_{i}\right\| \leqslant \frac{1}{p_{k}} \sum_{1}^{p_{k}}\left\|\lambda_{i} u_{i}^{*} \circ u_{i}-y_{i}\right\|_{1}<2 \varepsilon .
$$

This proves that $B_{k}$ is asymptotic in $l_{1}$.
In order to prove Lemma 3.5 we first need a sublemma. We denote the maps $E_{S^{*}}(h)$ and $F_{S^{*}}(h)$ by $E_{*}(h)$ and $F_{*}(h)$, respectively.

Sublemma 3.6. Let $m, K$ be integers and let $0<\tau<1$ be such that $\log \phi\left(m^{K}\right)<\tau K$. Let $\left(h_{i}\right)_{i=1}^{m^{K}}$ be a normalized block sequence in $l_{1}^{+}$. Then there exist in $l_{1}^{+}$a normalized block basis $\left(b_{i}\right)_{i=1}^{m}$ of $\left(h_{i}\right)_{1}^{m^{K}}$ such that

$$
\begin{equation*}
\sum_{j=1}^{m} E_{*}\left(b_{j}\right)-E_{*}\left(\sum_{j=1}^{m} b_{j}\right) \leqslant r m . \tag{3.1}
\end{equation*}
$$

Proof. For each $i \leqslant m^{K}$, let $v_{i}=F_{*}\left(h_{i}\right)$. Now $\left(1 / \phi\left(m^{K}\right)\right) \sum_{1}^{m^{K}} v_{i} \in \operatorname{Ba}\left(S^{*}\right)$ and so

$$
\begin{align*}
E_{*}\left(\sum_{1}^{m^{K}} h_{i}\right) & \geqslant E\left(\sum_{1}^{m^{K}} h_{i}, \frac{1}{\phi\left(m^{K}\right)} \sum_{1}^{m^{K}} v_{i}\right) \\
& =\sum_{1}^{m^{K}} E\left(h_{i}, v_{i}\right)-m^{K} \log \phi\left(m^{K}\right)  \tag{3.2}\\
& =\sum_{1}^{m^{K}} E_{*}\left(h_{i}\right)-m^{K} \log \phi\left(m^{K}\right) .
\end{align*}
$$

Let $\sum_{i=1}^{m^{K}} h_{i}=\sum_{j=1}^{m} d_{j}^{1}$ where $\left(d_{j}^{1}\right)_{j=1}^{m}$ is a block basis of $\left(h_{i}\right)$, each $d_{j}^{1}$ consisting of the sum of $m^{K-1}$ of the $h_{i}$ 's. Break each $d_{j}^{1}$ into $m$ successive pieces, each containing $m^{K-2}$ of the $h_{i}$ 's to obtain $d_{j}^{1}=\sum_{l=1}^{m} d_{j, l}^{2}$ and continue to define $d_{\alpha, j}^{l}$ for $l \leqslant k$ and $\alpha \in\{1, \ldots, m\}^{l-1}$ in this fashion. Consider the telescoping sum

$$
\begin{aligned}
\sum_{i=1}^{m^{K}} E_{*}\left(h_{i}\right)-E_{*}\left(\sum_{i=1}^{m^{K}} h_{i}\right)= & \sum_{j=1}^{m} E_{*}\left(d_{j}^{1}\right)-E_{*}\left(\sum_{j=1}^{m} d_{j}^{1}\right) \\
& +\sum_{j=1}^{m}\left[\sum_{l=1}^{m} E_{*}\left(d_{j, l}^{2}\right)-E_{*}\left(\sum_{l=1}^{m} d_{j, l}^{2}\right)\right]+\ldots
\end{aligned}
$$

For $1 \leqslant s \leqslant K$, the $s$ th level of this decomposition is the sum of $m^{s-1}$ nonnegative terms of the form (for $\alpha \in\{1, \ldots, m\}^{s-1}$ )

$$
\begin{equation*}
\sum_{l=1}^{m} E_{*}\left(d_{\alpha, l}^{s}\right)-E_{*}\left(\sum_{l=1}^{m} d_{\alpha, l}^{s}\right) \tag{3.3}
\end{equation*}
$$

If each of these terms is greater than $\tau m^{K-s+1}$ then the sum of all terms on the $s$ th level is greater than $\tau m^{K}$ and so the sum over all $K$ levels yields

$$
\sum_{i=1}^{m^{K}} E_{*}\left(h_{i}\right)-E_{*}\left(\sum_{1}^{m^{K}} h_{i}\right)>K \tau m^{K}
$$

which contradicts (3.2).
Thus the number (3.3) does not exceed the value $\tau m^{K-s+1}$ for some $s$ and multiindex $\alpha$. Let $b_{l}=d_{\alpha, l}^{s} /\left\|d_{\alpha, l}^{s}\right\|$. Using $E_{*}(a h)=a E_{*}(h)$ for $a>0$ and $\left\|d_{\alpha, l}^{s}\right\|=m^{K-s}$ we obtain

$$
\sum_{l=1}^{m} E_{*}\left(b_{l}\right)-E_{*}\left(\sum_{l=1}^{m} b_{l}\right) \leqslant \frac{\tau m^{K-s+1}}{m^{K-s}}=\tau m .
$$

Proof of Lemma 3.5. Let $\varepsilon>0, m \in \mathbf{N}$ and let $Y$ be a block subspace of $l_{1}$ with block basis $\left(h_{i}\right)$. By unconditionality in $S$ it suffices to consider only the case where $\left(h_{i}\right) \subseteq S\left(l_{1}\right)^{+}$. Let $0<\tau<\psi(\varepsilon) / m$ (see Definition 2.2) and choose $K \in \mathbf{N}$ such that $\tau K>$ $\log \left(\phi\left(m^{K}\right)\right)$. By Sublemma 3.6 choose a block basis $\left(b_{i}\right)_{1}^{m}$ of $\left(h_{i}\right)_{i=1}^{m^{K}},\left(b_{i}\right)_{1}^{m} \subseteq S\left(l_{1}^{+}\right)$with

$$
\begin{equation*}
\sum_{1}^{m} E_{*}\left(b_{j}\right)-E_{*}\left(\sum_{j=1}^{m} b_{j}\right)<\tau m . \tag{3.4}
\end{equation*}
$$

Choose $x^{*}=F_{*}\left(\sum_{j=1}^{m} b_{j}\right)$ and write $x^{*}=\sum_{j=1}^{m} x_{j}^{*}$ with $\operatorname{supp} x_{j}^{*}=\operatorname{supp} b_{j}$. For $j \leqslant m$ let $w_{j}^{*}=F_{*}\left(b_{j}\right)$. As we noted in $\S 2$, for each $j$ there exists $w_{j} \in S(S)^{+}$with $b_{j}=w_{j}^{*} \circ w_{j}$ and $\operatorname{supp} w_{j}=\operatorname{supp} b_{j}$. By (3.4) we have

$$
\sum_{j=1}^{m} E\left(b_{j}, w_{j}^{*}\right)-E\left(\sum_{j=1}^{m} b_{j}, x^{*}\right)=\sum_{j=1}^{m}\left[E\left(b_{j}, w_{j}^{*}\right)-E\left(b_{j}, x_{j}^{*}\right)\right]<\tau m<\psi(\varepsilon) .
$$

Since each term in the middle expression is nonnegative we obtain

$$
E\left(b_{j}, x_{j}^{*}\right)>E\left(b_{j}, w_{j}^{*}\right)-\psi(\varepsilon) \quad \text { for } j \leqslant m
$$

By Proposition $2.3(\mathrm{~A})$ there exists sets $H_{j} \subseteq \operatorname{supp} b_{j}$ such that $\left\|H_{j} b_{j}\right\|_{1}>1-\varepsilon$ and $(1-\varepsilon) H_{j} w_{j}^{*} \leqslant H_{j} x_{j}^{*} \leqslant(1+\varepsilon) H_{j} w_{j}^{*}$ pointwise for all $1 \leqslant j \leqslant m$.
$H_{j} b_{j}=H_{j} w_{j}^{*} \circ w_{j}$ and $\left\|H_{j} x_{j}^{*}-H_{j} w_{j}^{*}\right\| \leqslant \varepsilon$ so $\left\|H_{j} b_{j}-H_{j} x_{j}^{*} \circ w_{j}\right\|_{1} \leqslant \varepsilon$. Thus

$$
\begin{equation*}
\left\|b_{j}-H_{j} x_{j}^{*} \circ w_{j}\right\|_{1} \leqslant 2 \varepsilon \quad \text { for } 1 \leqslant j \leqslant m . \tag{3.5}
\end{equation*}
$$

From this we first note that $H_{j} x_{j}^{*}\left(w_{j}\right) \geqslant 1-2 \varepsilon$ and so for $a_{i}$ 's nonnegative,

$$
\left\|\sum_{1}^{m} a_{j} w_{j}\right\| \geqslant x^{*}\left(\sum_{1}^{m} a_{j} w_{j}\right) \geqslant \sum_{j=1}^{m} a_{j} H_{j} x_{j}^{*}\left(w_{j}\right) \geqslant\left(\sum_{j=1}^{m} a_{j}\right)(1-2 \varepsilon) .
$$

By unconditionality $\left(w_{j}\right)_{j=1}^{m}$ is an $l_{1}^{m}$ sequence with constant $(1-2 \varepsilon)^{-1}$.
Secondly, set

$$
\bar{w}=\frac{1}{m} \sum_{j=1}^{m} w_{j} \quad \text { and } \quad w=\frac{1}{\left\|\sum_{j=1}^{m} w_{j}\right\|} \sum_{j=1}^{m} w_{j} .
$$

$w$ is an $l_{1}^{m}$ average with constant $(1-2 \varepsilon)^{-1}$. Furthermore

$$
\begin{aligned}
\left\|\frac{1}{m} \sum_{j=1}^{m} b_{j}-\left(\bigcup_{j=1}^{m} H_{j}\right) x^{*} \circ w\right\|_{1} & \leqslant\left\|\frac{1}{m} \sum_{j=1}^{m} b_{j}-\left(\bigcup_{j=1}^{n} H_{j}\right) x^{*} \circ \bar{w}\right\|_{1}+\|w-\bar{w}\| \\
& \leqslant \frac{1}{m} \sum_{j=1}^{m}\left\|b_{j}-H_{j} x^{*} \circ w_{j}\right\|_{1}+\|w-\bar{w}\| .
\end{aligned}
$$

The first term is $<2 \varepsilon$ by (3.5). Since $\left\|\sum_{j=1}^{m} w_{j}\right\| \geqslant m(1-2 \varepsilon),\|w-\bar{w}\| \leqslant 2 \varepsilon /(1-2 \varepsilon)$. Thus

$$
d\left(\left(\bigcup_{j=1}^{m} H_{j}\right) x^{*} \circ w, S(Y)\right)<2 \varepsilon+\frac{2 \varepsilon}{1-2 \varepsilon}
$$

which proves Lemma 3.5.
Remark 3.7. Our proof of Theorem 3.2 actually shows that $l_{p}$ admits an asymptotic biorthogonal system with vanishing constant (see [10]). B. Maurey [22] has recently extended the results above. He has proven that if $X$ has an unconditional basis and does not contain $l_{1}^{n}$ uniformly, then $X$ contains an arbitrarily distortable subspace. B. Maurey and the second named author have independently shown that one can construct the sets $B_{k}$ to be symmetric $\left(\left(x_{i}\right) \in B_{k} \Rightarrow\left(x_{\pi(i)}\right) \in B_{k}\right.$ if $\pi$ is a permutation of $\left.\mathbf{N}\right)$.
N. Tomczak-Jaegermann and V. Milman [29] have proven that if $X$ has bounded distortion, then $X$ contains an "asymptotic $l_{p}$ or $c_{0}$ ". $X$ has bounded distortion if for some $\lambda<\infty$, no subspace of $X$ is $\lambda$-distortable. A space with a basis $\left(e_{i}\right)$ is an asymptotic $l_{p}$ if for some $C<\infty$ for all $n$ whenever

$$
e_{n}<x_{1}<\ldots<x_{n}, \quad\left\|x_{i}\right\|=1 \quad(i=1, \ldots, n)
$$

then $\left(x_{i}\right)_{1}^{n}$ is $C$-equivalent to the unit vector basis of $l_{p}^{n}$.

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