



# The effect of processing parameters on the mechanical characteristics of PLA produced by a 3D FFF printer

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## Abstract

3D printing by fused filament fabrication (FFF) provides an innovative manufacturing method for complex geometry components. Since FFF is a layered manufacturing process, effects of process parameters are of concern when plastic materials such as polylactic acid (PLA), polystyrene and nylon are used. This study explores how the process parameters, e.g. build orientation and infill pattern/density, affect the mechanical response of PLA samples produced using FFF. Digital image correlation (DIC) was employed to get full-field surface-strain measurements. The results show the influence of build orientation and infill density is significant. For on-edge orientation, the tensile strength and Young's modulus were 55 MPa and 3.5 GPa respectively, which were about 91% and 40% less for the upright orientation, demonstrating a significant anisotropy. The tensile strength and Young's modulus increased with increasing infill density. In contrast, different infill patterns have no significant effect. Considering the influence of build orientation, based on the experimental results, a constitutive model derived from the laminate plate theory was employed. The material parameters were determined by tensile tests. Results demonstrated a reasonable agreement between the experimental data and the predictive model. Similar anisotropy to tension was observed in shear tests; shear modulus and shear strength for 45° flat orientation were about 1.55 GPa and 36 MPa, whereas for upright specimens they were about 0.95 GPa and 18 MPa, respectively. The findings provide a framework for systematic mechanical characterisation of 3D-printed polymers and potential ways of choosing process parameters to maximise performance for a given design.

**Keywords** 3D printing · Rapid prototyping · Fused deposition modelling · Digital image correlation · Mechanical characteristics

## 1 Introduction

In comparison with traditional manufacturing methods, 3D printing is a rapid prototyping technology that offers advantages such as reduction of the production cost and material waste, ability to manufacture complex geometries and being less labour-intensive finding new applications in many areas of aerospace [1, 2], construction and civil engineering [3–6] biomedical engineering [7–10] and robotics [11, 12].

Among the different techniques for producing polymeric 3D printing parts, fused filament fabrication (FFF) is one of the most developed additive manufacturing processes involving extrusion of a polymeric filament material through a heated nozzle to deposit semi-molten material in a layer by layer

fashion on a substrate until the desired object geometry is produced. In FFF, based on a computer-aided design (CAD) model of the component, a computer programme is used to slice the model into single layers with defined thickness that build up the full geometry of the object. The slice geometry and other machine parameters are the converted into G-code which can be read by the printer to generate the object.

Generally in 3D-printed FFF parts, the existence of filament gaps (voids) between deposited layers, the variation in the layer to layer adhesion quality and the shrinkage during the cooling can all affect the mechanical properties and cause anisotropy [13–15]. It has been also shown that several parameters such as build orientation, layer thickness, raster width and orientation/extruded fibre layout, infill pattern/density, temperature and feed rate can influence this and have significant impact on the quality of FFF parts in terms of mechanical properties [14, 16–25]. Therefore, a number of input conditions and process variables need to be optimised in order to generate high-quality components. This necessitates a better understanding of the process-properties relationship of 3D FFF parts.

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Limited knowledge about the inherently heterogeneous mechanical behaviour of 3D FFF-fabricated materials and lack of suitable design tools is a major barrier of using this technology for producing functional parts. Mechanical properties of FFF-fabricated parts are a key measure of their quality and performance. For example, the orthotropic elastic constants and strength parameters are required in the design process of highly stressed 3D-printed structures. Therefore, to drive further application of 3D printing technology and address the issues related to the anisotropy of the mechanical properties of these parts (structural integrity), much research has been done in order to establish an experimental relationship between process variables and mechanical properties of 3D FFF-fabricated parts. To date, no complete and comprehensive study exists for any material but considerable information is available for some aspects.

The effects of build orientation on mechanical behaviour of FFF parts have been studied [14, 20, 21, 26–28] and it has been found that the highest mechanical properties are obtained when the filament deposition direction coincides with the tensile load direction, however, a wide range of build orientations with respect to the tensile direction have not been investigated previously. In addition, the effect of layer height and raster orientation on the tensile properties of 3D-printed polylactic acid (PLA) and acrylonitrile butadiene styrene (ABS) parts have been investigated by a number of workers [17, 29–32], and it has been found that increasing raster angle towards 90° reduces the tensile strength, while a lower value of layer height results in higher tensile strength. To account for the effect of layer thickness and air gap, it has been found that negative air gap and minimum layer thickness can improve the mechanical properties of ABS-printed parts [21, 31, 33]. Also, the effect of build orientation, layer thickness and feed rate on the mechanical properties of PLA parts have been investigated by [34], and it has been shown that the best mechanical properties are obtained for samples printed on edge or flat orientations with the lowest value of layer thickness. In terms of analytical study, classical laminate theory (CLT) has been used to estimate the effect of raster angle on tensile properties of 3D-printed samples [20]. In this work, the values of longitudinal and transverse modulus, the shear modulus and Poisson's ratio required to calculate the stiffness matrix have been determined experimentally from the horizontally built specimens. The present study shows that using the experimentally calculated parameters of elastic constants of the upright 3D-printed samples in the stiffness matrix, the CLT can also be used to predict the effect of build orientation on the tensile properties. In addition to the use of CLT, the use of numerical homogenisation technique based on Finite Element (FE) modelling of Representative Volume Element (RVE) has been found useful to predict the mechanical behaviour of 3D-printed parts as a function of both build and raster orientation; however, the results of this study is not comparable with

experiment as the bonding between the adjacent filaments was assumed to be perfect in the FE model of RVE, whereas it is not the case in printed samples [35].

While the printing orientation and infill density can alter tensile, flexural and compressive properties [36–38], many of these studies has only been done with ABS, and only relatively recently PLA has been the topic of such investigations. Due to the advantages of PLA (biocompatibility and environmentally friendly material) and the fact that many desktop printers nowadays use PLA as it is easier to print without curling, this paper focuses on the effect of FFF process parameters on PLA parts. Although some mechanical properties of PLA have been investigated recently, there is little information about the evaluation of shear properties. In addition, the majority of the previous research is focused on the study of raster angle and build orientation on the tensile properties of 3D-printed parts, with less attention on the effect of infill pattern and infill density. Given the importance of orthotropic elastic constants (which are obtained from standard tension and shear tests) in the design process of load-bearing 3D-printed structures, it is necessary to understand the effect of infill density, infill pattern and build orientation on the tensile and shear properties of 3D-printed PLA parts.

Although, many studies have sought to improve the load bearing capacity of parts manufactured using FFF by optimising various printing parameters [39–43], the lack of standard method to assess the failure progression and to measure the components of engineering strains during mechanical deformation has resulted in inconsistent results indicating that the influence of printing conditions on mechanical properties still needs to be further investigated. In fact, most studies on the mechanical response of 3D FFF parts are based on using conventional strain gauges and extensometer to build the stress-strain curve and extract the main parameters such as Young's modulus, failure strain and ultimate/yield strength while lacking other properties such as Poisson's ratio and longitudinal, transverse and shear data which are essential for fully characterising their mechanical performance. In addition, in FFF parts, the irregularity of the geometric features associated with filament-scale structure can change the local behaviour of the printed parts under the deformation leading to non-uniform distribution of strain; this is why a unique technique to map the strain distribution is also required.

Due to the anisotropy effect of 3D-printed parts, using conventional strain gauges does not reveal actual information about strain localisation and the gradient of strain fields. An ideal technique for measuring strain and tracking the failure progression in 3D FFF-fabricated parts is a non-contact strain measurement method such as digital image correlation (DIC). Using DIC, restrictions regarding specimen dimensions to obtain a uniform displacement distribution can be eliminated. Full-field measurement digital image processing techniques, such as DIC, were introduced in the field of 3D-printed

materials to map the strain fields and to measure components of strains and Poisson’s ratio [23, 24, 44, 45]. However, to date, the determination of mesoscopic deformation of heterogeneous 3D FFF parts and the influence of material structure heterogeneity on both tensile and shear strain have not been widely investigated by this technique.

In order to bring the FFF technology into volume production for producing functional parts, the optimising of 3D printing parameters to produce suitable mechanical properties needs to be investigated thoroughly. This study aims to look at the effect of parameters such as build orientation and infill density/pattern on the tensile and shear properties of 3D-printed parts with the aid of a DIC system. DIC is also used to assess the difference observed in the strain/deformation fields of these materials under tensile and shear loads for the same process parameters. Moreover, full-field DIC strain maps are used to show the areas on the specimen surface where damage occurs. A better understanding of mechanical performance, surface-strain fields and failure progression of 3D FFF parts under deformation will make the use of these parts more reliable and increase the design safety of engineering parts manufactured by them.

## 2 Orthotropic constitutive model

In the FFF process, the materials are manufactured by stacking layers deposited from the filament by a rastering process (see in Fig. 1). As a result, each layer can be considered as a lamina (ply). In this study an orthotropic model which is well-known in the composite field is used to evaluate the effect of build orientation on mechanical behaviour of 3D FFF tension test coupons, and a comparison between analytical and experimental solutions can be made to validate the results.

Given the plane stress condition (thickness dimension is much smaller than the length and width dimensions [46]), in 3D FFF tension specimens, only the values of in-plane engineering constants (longitudinal modulus, in-plane transverse modulus, in-plane shear modulus, major and minor Poisson’s ratio) are required to define the orthotropic nature of the lamina. These values are calculated experimentally from tensile tests in the longitudinal (0° on-edge sample) and transverse

(upright sample) directions (Fig. 6) as well as the Iosipescu shear test (Table 7). Therefore, the equations used in the stress analysis of tensile samples are applied to the plane stress condition and the constitutive equation which relates the stress to strain is defined as follows:

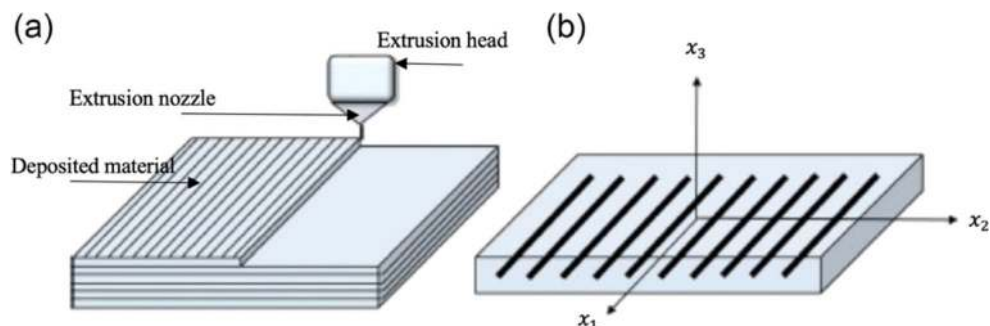
$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_{12} \end{bmatrix} = [Q_{ij}] \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix} \text{ where } [Q_{ij}] = \begin{bmatrix} Q_{11} = \frac{E_1}{1-\nu_{12}\nu_{21}} & Q_{12} = \frac{\nu_{21}E_1}{1-\nu_{12}\nu_{21}} & Q_{16} = 0 \\ Q_{21} = \frac{\nu_{21}E_1}{1-\nu_{12}\nu_{21}} & Q_{22} = \frac{E_2}{1-\nu_{12}\nu_{21}} & Q_{26} = 0 \\ Q_{61} = 0 & Q_{62} = 0 & Q_{66} = G_{12} \end{bmatrix} \quad (1)$$

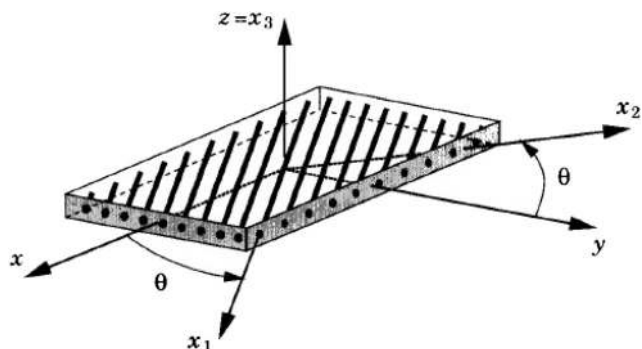
where  $\sigma_1$ ,  $\sigma_2$  and  $\sigma_{12}$  are the longitudinal (parallel to the filament), in-plane transverse (perpendicular to the filament) and in-plane shear stresses respectively. Correspondingly,  $\varepsilon_1$ ,  $\varepsilon_2$  and  $\gamma_{12}$  represent the in-plane engineering strains.  $E_1$  is the elastic modulus of the 0° on-edge sample,  $E_2$  is the elastic modulus of the upright sample,  $G_{12}$  is the in-plane shear modulus of the 0° on-edge sample, and  $\nu_{12}$  and  $\nu_{21}$  denote the major and minor Poisson’s ratios respectively. In this study, analytical solutions developed for tension testing of 3D FFF parts are then validated with experimentally generated data. For laminated 3D FFF parts subjected to a pure uniaxial tension load of  $P$  [46], the in-plane stresses for each layer:

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_{12} \end{bmatrix} = [Q_{ij}] [A_{ij}]^{-1} \begin{bmatrix} P/b \\ 0 \\ 0 \end{bmatrix} \text{ where } [A_{ij}] = \sum_{k=1}^n [Q_{ij}] \quad (2)$$

where  $P$  is the tension load,  $t$  is the thickness,  $n$  is the number of layers through the thickness direction of the laminate,  $b$  is the width of specimen and the matrix  $[A_{ij}]^{-1}$  is the inverted extensional stiffness matrix  $[A_{ij}]$  showing the relationship between components of stress and strain [46]. It must be noted that in the above equations, the loading direction is either parallel or perpendicular to the filament direction; when the loading direction does not correspond to the principal material directions (given the relation between the principal and material coordinate system (Fig. 2) where coupling between extension and shear occurs), the stiffness matrix ( $[Q_{ij}]$ ) is calculated using free-body diagrams. Full descriptions of the equations are detailed in [46].

Fig. 1 a FFF-processed materials. b Lamina structure with the material coordinate system ( $x_1, x_2, x_3$ )





**Fig. 2** A lamina with material  $(x_1, x_2, x_3)$  and principal  $(x, y, z)$  coordinate system

### 3 Methods

#### 3.1 Sample preparation

All specimens were produced using a low cost fused filament fabrication (FFF) 3D printer (Crealty Ender-3, Shenzhen, China). A polylactic acid (PLA) filament from the same manufacturer was used to obtain the 3D-printed specimens. The main advantage of PLA is that it is easy to use, provides dependable design, adheres well and does not suffer from any substantial distortion during printing. The Ultimaker Cura 4.0 edition was used as the slicer to generate the machine code for the 3D FFF printer from the 3D model file. Simple 3D-printed test sample designs based on ASTM standards were used in all cases. The PLA filament's initial diameter was 1.75 mm with a nozzle of diameter 0.4 mm. The extrusion and bed temperatures were maintained at 200 °C and 60 °C respectively. Once the first layer is deposited on the heated bed, the head lifts and proceeds to deposit the following layers with fan cooling; this approach promotes adhesion. The process parameters like raster width, raster starting angle and temperature were software default values for the printer. Tensile and shear test specimens were manufactured with dog-bone and Iosipescu specimen geometry respectively (Table 1 and 2).

The specimens were prepared with four infill densities of different percentages (25%, 50%, 75% and 100%), eight different build orientations (0°, 15°, 30°, 45°, 60°, 75°, 90°, flat 0° and upright (see Fig. 3b, c) and four different infill patterns (square, triangle, concentric and gyroid) to evaluate the effect on mechanical properties. The manufacturing parameters for tensile and shear test samples are presented in Table 3.

For all upright and on-edge samples, a raft of PLA was deposited prior to sample manufacture to ensure adhesion. For the upright samples between 15° and 75° and the on-edge samples, a support was used to ensure the geometry was maintained. The raft and support parameters were set by the CURA software as the default for the chosen printer.

The measured density of the PLA filament was  $1.22 \pm 0.02 \text{ g/cm}^3$  in line with the expected literature value and the manufacturer's data sheet. The average sample density varied between 56 and 99% of this value as infill density increased. The sample structure has a relatively dense shell surrounding the region of reduced infill density—thus, the average density of the sample will depend on sample size, shape and shell thickness as well as build orientation. In this study, about 42% of the sample volume was shell and the rest infill.

#### 3.2 Mechanical testing

The tensile and shear testing of 3D-printed specimens and the tensile testing on of PLA filament were carried out using a Tinius Olsen Universal testing machine fitted with a 10 kN load cell with  $\pm 0.5\%$  accuracy. These mechanical tests were conducted in conjunction with digital image correlation (Fig. 4). Before any 3D FFF printing, tensile testing on the PLA filament was carried out to provide baseline data. PLA specimens of 1.72 mm in diameter (nominally 1.75 mm) and 200 mm in length were clamped inside the load frame on the Tinius Olsen Universal machine using capstan grips. The geometry of specimens for subsequent tension and shear tests were set according to ASTM D638 [47] and ASTM D5379 respectively [48, 49]. A schematic view of the geometry of specimens is illustrated in Fig. 3d, e. The specifications of all specimens are mentioned in Table 3.

Before testing, the specimens were air dried at a temperature of 50 °C. The tensile tests were performed using type IV dog-bone-shaped specimens with a thickness of 2 mm and a width of 6 mm (Table 1), and shear tests were performed using the Iosipescu specimen (Table 2). The test speed was 2 mm/min. All tests were conducted under ambient conditions (about 22 °C and 60% humidity). At least five specimens of each condition were tested. During the mechanical tests, the DIC system was used for full-field strain measurement.

**Table 1** Geometry of the tensile test specimen

Type	Gauge length	Width at gauge length	Thickness	Distance between grips	Width at grips	Length
Tension (dog bone)	35 mm	6 mm	2 mm	70 mm	20 mm	115 mm

**Table 2** Geometry of the shear test specimen

Type	Distance between notches	Depth of notches	Radius of end notches	Thickness	Width	Length
Iosipescu	11.4 mm	3.8 mm	1.3 mm	5 mm	19 mm	76 mm

### 3.3 Digital image correlation (DIC) testing

Full-field deformation measurements were carried out using the DIC technique. DIC is based on the comparison between two images acquired before and after the deformation. A CCD camera was used for image acquisition; these images are digitised and analysed to create strain maps [50, 51]. Before measurement, specimens were sprayed alternately using black and white paint to create a speckle pattern with sufficient greyscale contrast for analysis. The camera features a spatial resolution of 5.5  $\mu\text{m}/\text{pixel}$  and is equipped with lenses of 0.193 magnification at the working distance of about 300 mm. An external cold light source was used to illuminate the whole sample uniformly for minimum errors introduced by variable lightning conditions; this is essential for strain mapping. Image acquisition was synchronised with the beginning of each mechanical test. Digital image correlation (DIC) allows a full-field strain measurement of the surface using a speckle pattern distribution [50]. The images were recorded during the tensile test using the Imetrum video-gauge software at a rate of 5 Hz, and the images obtained were then processed with the VIC-2D software from Correlated Solutions, Inc. The software was used to interpolate the points and give the full-field strain maps and stress-strain curves for the 3D-printed specimens.

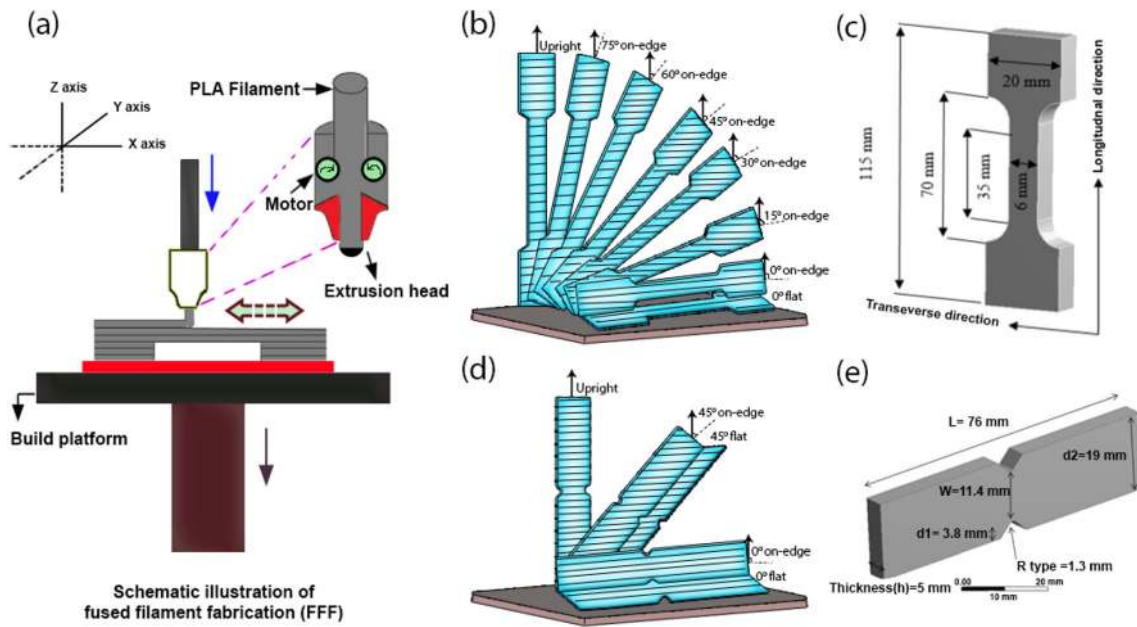
## 4 Results and discussion

### 4.1 Tensile tests

All of the investigations in this study were performed using an amorphous polylactic acid (PLA) filament, which is extensively used in 3D FFF technology, as PLA has low a melting point and is environmentally greener [52]. The average elastic modulus, tensile strength and the failure strain of the PLA filament were found to be about  $3.5 \pm 0.1\text{GPa}$ ,  $51 \pm 1\text{MPa}$  and  $6 \pm 0.5\%$ , respectively. Similar properties for PLA filament have been reported in the literature [53]. The 3D FFF printer instrument controls both the direction of the layer orientation as well as the extruded fibre raster pattern. Past research was primarily concerned with the variation of mechanical properties with build orientation, while infill pattern and infill density have rarely been assessed. To give better insight into the mechanical response of the material, a systematic study of factors affecting performance has been undertaken here.

#### 4.1.1 Effect of build orientation on mechanical properties

Tensile tests were conducted on 3D-printed samples with different build orientation. Following the recommendation of ASTM standard D-638, for each building orientation, 5



**Fig. 3** a Schematic view of 3D FFF printer, where the model is built layer by layer. b Schematic of the orientations of the specimens used in this investigation for tension, c the orientations of the specimens used in this investigation for shear, d tensile specimen, and e Iosipescu shear specimen

**Table 3** Process parameter of 3D-printed parts used for tensile and shear tests

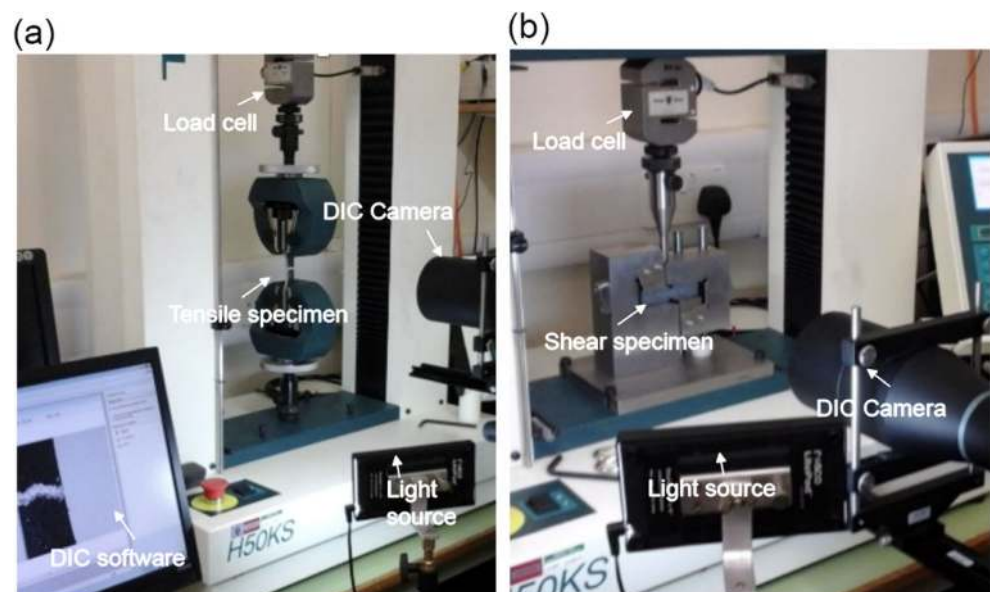
Parameter	Method	Description							
Infill density (%)	Tension	25	50	75	100				
	Shear	–							
Manufacturing orientation	Tension	0°	15°	30°	45°	60°	75°	0° flat	Upright
	Shear	0° on-edge	45°	0° flat		Upright			
Infill pattern	Tension	square	triangle	concentric		gyroid			
	Shear	square							
Layer height (mm)	Tension	0.15							
	Shear								
Shell thickness (mm)	Tension	1.20							
	Shear								
Nozzle size (mm)	Tension	0.4							
	Shear								
extrusion temperature (°C)	Tension	220							
	Shear								
Bed temperature (°C)	Tension	60							
	Shear								
Deposition speed (mm/s)	Tension	60							
	Shear								

specimens were tested. In terms of failure location and depending on the failure modes (i.e. inter-layer and intra-layer fracture), for each building orientation, the majority of specimens failed within the gauge length; however, occasionally, some samples failed outside the gauge length. In these cases, the test specimens were 3D-printed again and tensile test was repeated until a successful result was produced.

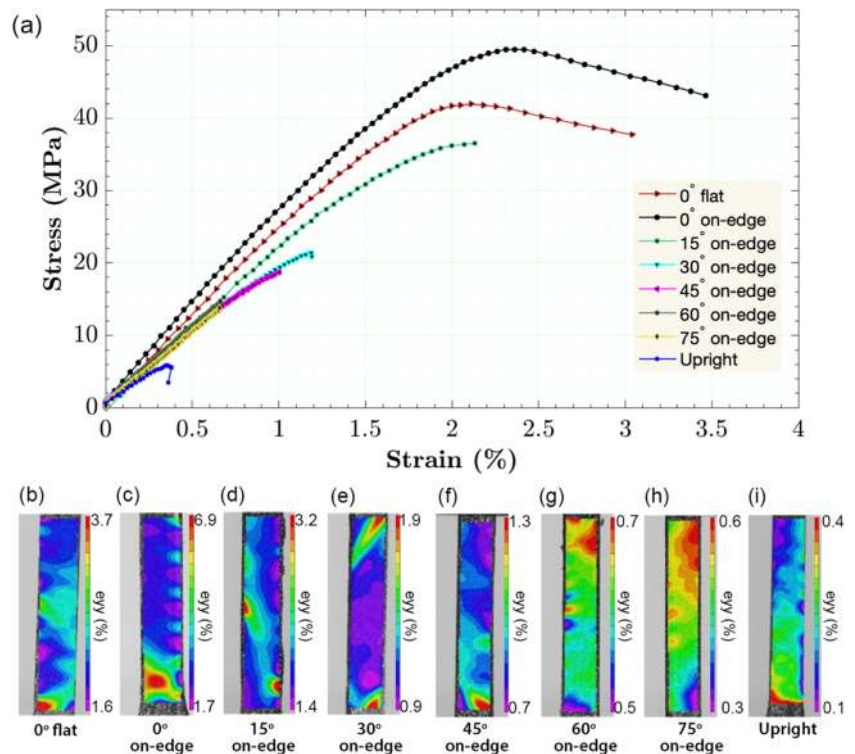
Figure 5 illustrates stress-strain curves for all the build orientations, as described in the schematic Fig. 3b. There appears to be significant variation in tensile strength, elastic modulus, Poisson's ratio and elongation as a function of build orientation; Fig. 6 summarises the mechanical test results revealing

that the PLA exhibits remarkable variation with build orientation.

The on-edge build orientation shows highest values of ultimate tensile strength and elastic modulus, which were about  $\sigma_{UTS} = 55$  MPa and  $E_y = 3.5$  GPa respectively. The upright orientation resulted in the lowest values measured here; the tensile strength and elastic modulus were about  $\sigma_{UTS} = 5$  MPa and  $E_y = 2$  GPa respectively. The on-edge orientation showed the highest value for the elongation and Poisson's ratio with an average of about  $\epsilon_{max} = 5\%$  and  $\nu_m = 0.35$ , respectively, higher than the flat ( $\epsilon_{max} = 2.5\%$  and  $\nu_m = 0.32$ ) and upright ( $\epsilon_{max} = 0.45\%$  and  $\nu_m = 0.2$ ) orientations. This indicates that

**Fig. 4** Experimental set up for DIC testing **a** under tensile loading and **b** under shear loading

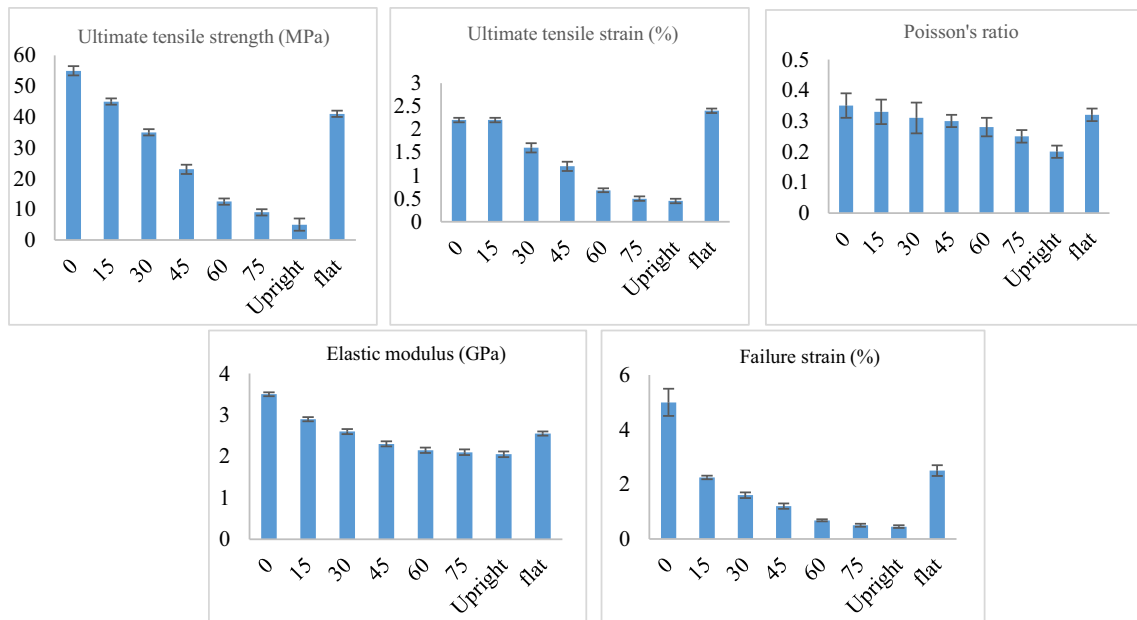
**Fig. 5 a** Tensile stress-strain curves for different build orientation of 3D FFF-printed PLA measured by DIC method. An infill pattern of parallel fibres in the long dimension of the sample with an infill density of 100% has been used for 3D printing of these samples. DIC strain distribution map in terms of longitudinal strains prior to the fracture point for different build orientation of 3D FFF-printed tensile specimen of **b** 0° flat, **c** 0° on edge, **d** 15° on edge, **e** 30° on edge, **f** 45°, **g** 60° on edge, **h** 75° on edge and **i** upright orientation



the on-edge orientation has a significant improvement in mechanical properties compared to the other build orientations. When the angle of the on-edge orientation increased from 15° to 75°, the tensile strength, elastic modulus, Poisson’s ratio and elongation decreased (Fig. 6). These results have confirmed observations in previous studies [24, 33].

Figure 5 b–i show DIC results in terms of engineering strain plots  $\epsilon_{yy}$  (loading direction) just prior to failure (about

95% of failure strain) for the eight different build orientations. All specimens failed within the gauge length. In almost all the cases, the results show a very high localised strain at the edge near to the grip. For the flat build orientation, the high strain concentration occurred at the edge and splitting at the surface was observed. From the DIC images, it can be seen that the highest localised  $\epsilon_{yy}$  strain is aligned perpendicular to the layer direction, with high strain values recorded ( $\epsilon_{yy} = 3.7\%$ ). For



**Fig. 6** Tensile properties of 3D FFF-printed PLA as a function of build orientation

**Table 4** Comparison between the yield strength of 3D-printed tension test coupons obtained by experimental and analytical solution

Method of measurement	15° edge	30° edge	45° edge	60° edge	75° edge
Experimental (MPa)	45 ± 1	35 ± 2	23 ± 2	12.5 ± 0.5	9 ± 1
Analytical (MPa)	44	35	22	12	9
Difference (%)	2.3	0.5	4	4	1

the on-edge orientation, a similar high strain concentration occurred at the edge of the sample. In this case, localised  $\varepsilon_{yy}$  strain runs perpendicular to the layer direction, with slightly higher strain values ( $\varepsilon_{yy} = 6.9\%$ ) than for the flat orientation. In contrast, for the upright orientation, the highest strain concentration occurred at the edge, and the localised  $\varepsilon_{yy}$  strain runs along the layer direction, with relatively low strain values ( $\varepsilon_{yy} = 0.4\%$ ); through-layer failure would be expected at this strain level. The  $\varepsilon_{yy}$  values with build orientation at 0° on-edge ( $\varepsilon_{yy} = 6.9\%$ ) is considerably higher than build orientation at 75° on-edge ( $\varepsilon_{yy} = 0.6\%$ ), and the noticeably high strain concentration is rotated in conjunction with the build orientation angles further demonstrating the anisotropic behaviour of 3D FFF parts.

The difference in failure mode can be attributed to two main factors during the 3D FFF manufacturing process: inter-layer and trans-layer failures [17, 21, 33, 54, 55]. In the case of the upright orientation, the specimens were pulled parallel to the layer deposition plane and load was applied perpendicular to the filament deposition direction, resulting in inter-layer bond failure known as brittle delamination [21, 33]. Due to the limited extent of fusion and hence weak adhesion, a lower tensile strength than that of the individual layer is expected [17, 21, 33, 54, 55]. In contrast, for the on-edge and flat orientations, the layers' deposition direction was perpendicular to the specimen long dimension and the load was applied parallel to the layers, resulting in through-thickness failure for each layer pulled along the longitudinal axis [17, 21, 33, 54, 55]. This leads to higher tensile strength of the on-edge and flat orientations when compared to the upright orientation. The stress-strain curve for the upright orientation indicates brittle behaviour, whereas the on-edge and flat orientations show more ductile behaviour with significant plastic deformation, especially in the case of the on-edge orientation. The on-edge sample with 0° orientation shows the maximum value of yield stress and tensile strength at failure. This is

because of the mechanism described earlier where more layers are loaded longitudinally. Additionally, it is observed that for the build orientation at different angles (15°, 30°, 45°, 60° and 75°), the deformation shows a similar ductile behaviour and plastic deformation, with a considerable anisotropy effect; as the build orientation decreases, the maximum tensile strength also decreases. The main objective of changing the angle of build orientation was to examine the variation of stress/strain behaviour and if it could be further explained using a simple constitutive model.

The yield strength of 3D-printed tension samples was calculated using Eq. 2 (based on the tension load at the yield point) and compared with experimental results in Table 4 indicating that the constitutive model can approximately predict the effect of manufacturing orientation on the yield strength of 3D-printed tension samples. In fact, the measured values are usually about 5% less than the predicted values regardless of orientation due to the defects introduced into the material during the additive layer manufacturing process.

#### 4.1.2 Effect of infill density on mechanical properties

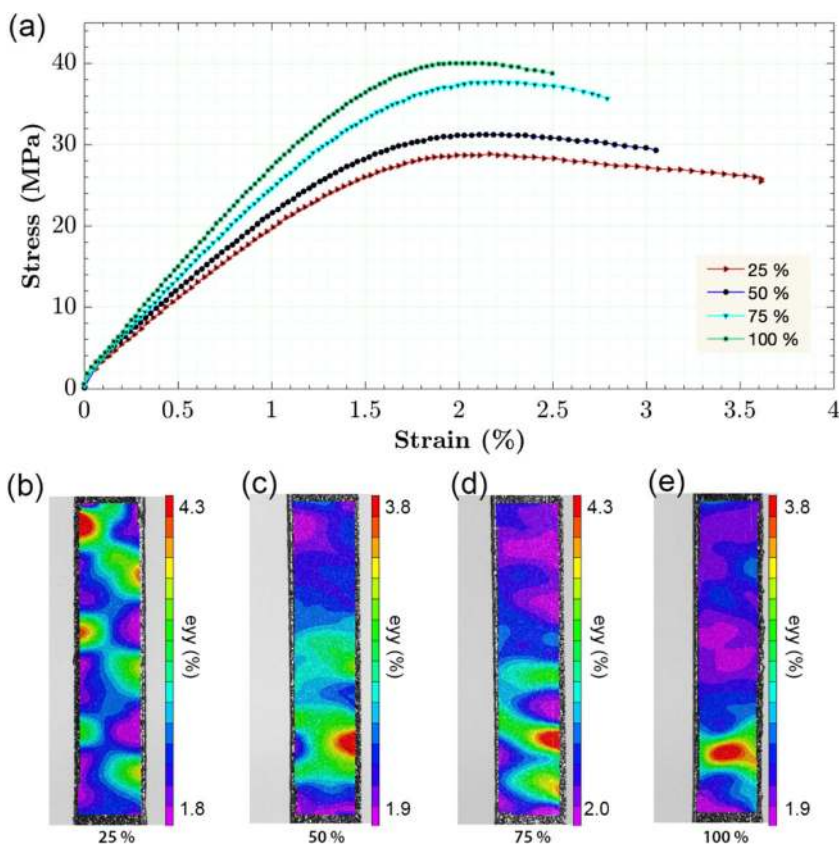
Figure 7 illustrates stress-strain curves for four different infill densities (25%, 50%, 75% and 100%) with build orientation of 0° flat. The tensile properties of these samples are provided in Table 5; it can be seen that infill density has a considerable effect on mechanical properties. The tensile strength and Young's modulus increase with infill density (Fig. 8). This observation is consistent with previous studies [56–58]. The justification is that with the increase of the fill density, the volume of air gaps decreases (i.e. an increase in the polymer content of the material) and the number of filament junctions increases which improves the inter-layer bonding strength of the FFF-printed material. Thus, the 3D-printed part can support a higher load. According to Gibson and Ashby [59], relative Young's modulus of a porous material compared to

**Table 5** Tensile properties of 3D FFF-printed PLA as a function of infill density

Infill density	Ultimate tensile strength (MPa)	Difference to filament (%)	Ultimate tensile strain (%)	Poisson's ratio	Elastic modulus (GPa)	Failure strain (%)
25%	29±1	-43	2.15±0.04	0.31±0.03	2.05±0.05	3.4±0.2
50%	30±2	-41	2.15±0.04	0.32±0.02	2.15±0.05	2.75±0.25
75%	36±0.5	-29	2.5±0.05	0.32±0.02	2.5±0.05	2.85±0.15
100%	38±3	-25	2.6±0.05	0.33±0.01	2.75±0.05	2.25±0.025



**Fig. 7** **a** Tensile stress-strain curves for different infill density of 3D FFF-printed PLA (grid infill pattern with  $\pm 45^\circ$  wall orientation to the longitudinal axis) measured by the DIC method. DIC strain distribution map along the tensile specimens of different infill density of **b** 25%, **c** 50%, **d** 75% and **e** 100%

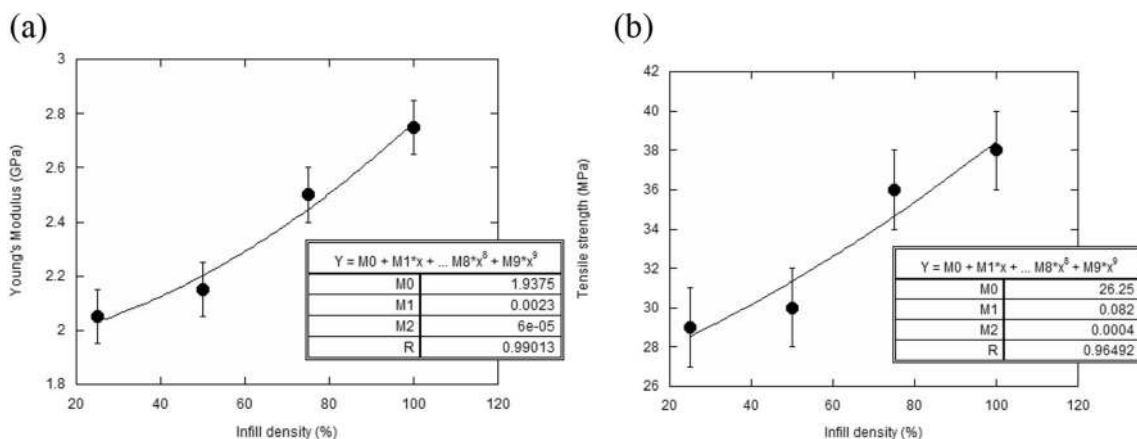


its fully dense counterpart should vary as the relative density squared so a power law fit with order 2 might be expected to give the best fit. However, the samples prepared here have a relatively dense shell surrounding the region of lower infill density so this is modified to the quadratic variation which shows the excellent fit in Fig. 8a.

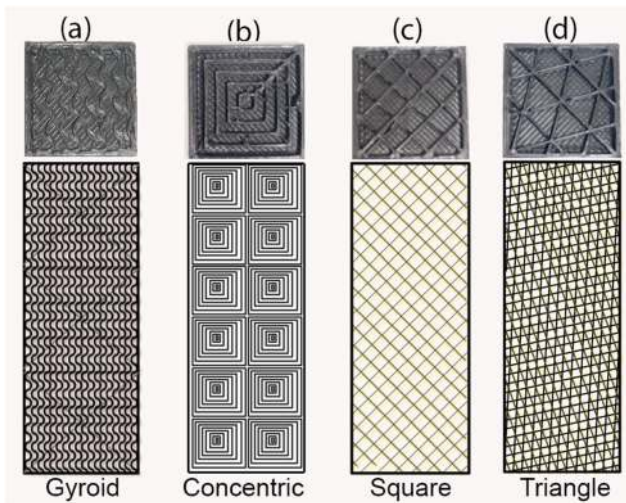
Poisson’s ratio also increases very slightly with infill density ( $\nu_m = 0.31$  for 25% and  $\nu_m = 0.33$  for 100%). The specimens with 25% infill density have lowest performance, with reduction of 23.6% tensile strength and 25.45% Young’s modulus, compared with 100% infill density. In short, it is

best to select the highest infill density 3D FFF parts for optimum mechanical response but this can increase build time and cost so a compromise may be necessary. The effect of infill density on ductility is less significant but it is worth noting that the ductility decreases as the infill density increases. The tensile strain at fracture for 25% infill density was  $\sim \epsilon_f = 3.4\%$  and it decreased to  $\epsilon_f \sim 2.25\%$  at 100% density.

The strain field obtained by the DIC technique under tensile loading at four different infill densities is illustrated in Fig. 7. Figure 7 b–e show DIC results in terms of longitudinal strain field plots  $\epsilon_{yy}$  (in the loading direction) near to the final



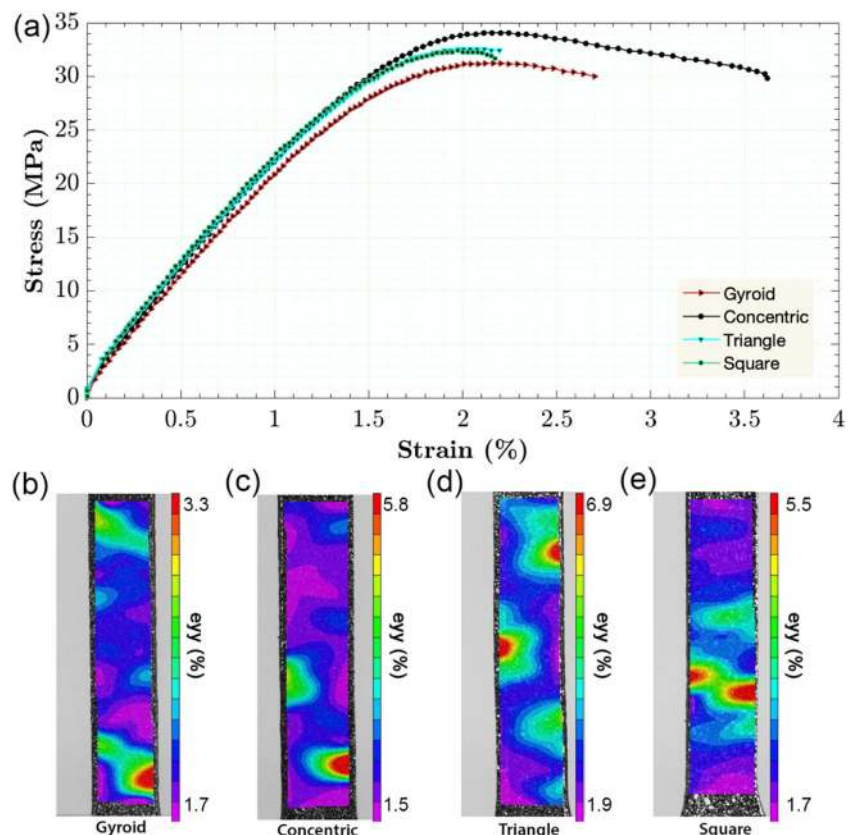
**Fig. 8** Variation of **a** Young’s modulus and **b** tensile strength with infill density



**Fig. 9** Schematic of different 3D printing infill patterns **a** gyroid, **b** concentric, **c** square grid and **d** triangle

failure (about 95% of failure load). All specimens failed within the gauge length as shown in Fig. 7. In almost all infill densities, the results show very high localised strain at the edge of the sample. For 25% infill density, lots of regions of high strain concentration were observed at the edge of the sample ultimately leading to fracture. A very high local strain value ( $\varepsilon_{yy} = 4.3\%$ ) was observed in one of these locations

**Fig. 10 a** Tensile stress-strain curves for different infill pattern of 3D FFF-printed PLA measured by the DIC method (the infill density of 50%); the DIC strain distribution map along the tensile specimens of different patterns of **b** gyroid, **c** concentric, **d** triangle and **e** square grid



(Fig. 7b). In case of 50% infill density, there were a smaller number of localised strain concentrations and these penetrated deeper into the middle of the sample. A similar pattern was observed in the case of the 75% infill density. At 100% infill density, the single large region of localised strain concentration was in the middle of the sample. The comparison shows that reducing the number of localised strain concentrations markedly lowers strain at failure when the infill densities increase which confirms the substantial effect of infill densities on mechanical properties of 3D FFF parts.

#### 4.1.3 Effect of infill pattern on mechanical properties

The prior research on the 3D FFF parts has mainly focused on a linear infill pattern, with the main object to find the effect of infill material types and orientations, not on different build patterns [52, 59]. In this study, we compared four different patterns (i.e. gyroid, concentric, triangle and square (Fig. 9)) printed at 50% infill density. Figure 10 illustrates stress-strain curves for these four patterns and their tensile properties are provided in Table 6.

The stress-strain curves illustrated in Fig. 10 show that the different patterns have a minor effect on mechanical properties of the sample in comparison to build orientation and infill density. For the gyroid, the tensile strength and elastic modu-

**Table 6** Tensile properties of 3D FFF-printed PLA as a function of infill pattern

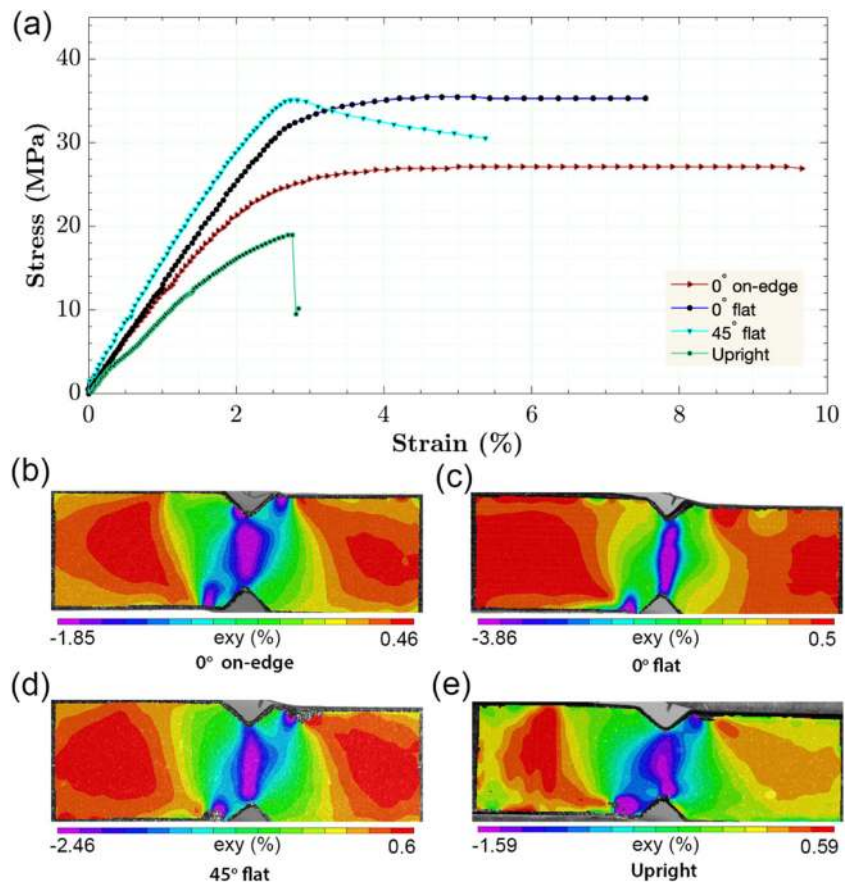
Infill pattern	Ultimate tensile strength (MPa)	Difference to filament	Ultimate tensile strain (%)	Poisson’s ratio	Elastic modulus (GPa)	Failure strain (%)
50% concentric	31±1	− 39	2.15 ± 0.05	0.32 ± 0.01	2.2 ± 0.05	3.5 ± 0.1
50% gyroid	30±1	− 41	2.12 ± 0.03	0.31 ± 0.01	2.2 ± 0.05	2.75 ± 0.3
50% square	31±1	− 39	2.1 ± 0.05	0.32 ± 0.01	2.28 ± 0.04	2.35 ± 0.15
50% triangle	31±1	− 39	2 ± 0.05	0.32 ± 0.02	2.15 ± 0.05	2.33 ± 0.05

lus were lowest, while the tensile strength and elastic modulus were almost identical for concentric, triangle and square patterns (Table 6). In terms of Poisson’s ratio, the variation in values was negligible for all four different infill pattern cases. The tensile strain at fracture in the case of concentric pattern was 27% and 48.9% larger in comparison to gyroid and square infill patterns respectively. Thus, the variation in tensile properties with respect to infill pattern choice was small; however, the concentric pattern had a slightly better mechanical response in all measurements here.

The strain fields obtained by the DIC technique for the four different infill patterns under tensile loading are illustrated in Fig. 10. Figure 10b–e shows DIC results obtained in terms of longitudinal strain field plots  $\epsilon_{yy}$  (loading direction) near to

failure (about 95% of failure) load. All specimens failed within the gauge length. All infill patterns show a very high localised strain at the edge of the sample. For the square pattern, a high strain concentration was observed at the edge just near the grip and led to fracture; the localised strain value at this point was  $\epsilon_{yy} = 3.3\%$  (Fig. 10e). For the triangle pattern, a single high local strain concentration was also observed at the edge just near to the grip and this caused fracture the same as for the square pattern; a higher localised strain value ( $\epsilon_{yy} = 5.8\%$ ) was observed (Fig. 10d). In case of concentric and gyroid patterns, very high localised strains occurred at several positions only one of which led to fracture; the peak strains in these cases were 6–7% suggesting that these infill designs can accommodate more strain in the material.

**Fig. 11 a** Shear stress-strain curves for different build orientation of 3D FFF-printed PLA measured by the DIC method (parallel fibres with the infill density of 100%); the DIC strain distribution map along the shear specimens of **b** 0° on-edge orientation, **c** 0° flat orientation, **d** 45° flat orientation and **e** 50% upright orientation



**Table 7** Shear properties of 3D FFF-printed PLA as a function of build orientation

Specimen	Shear strength (MPa)	Yield strength (MPa)	Shear modulus (GPa)	Failure shear strain (%)
0° on-edge	27 ± 0.6	23 ± 0.6	1.21 ± 0.03	9.6 ± 0.3
0° flat	35 ± 0.5	30 ± 0.5	1.27 ± 0.05	7.5 ± 0.2
45° flat	36 ± 0.3	33 ± 0.3	1.55 ± 0.08	5.5 ± 0.4
Upright	18 ± 0.5	17.5 ± 0.5	0.95 ± 0.06	2.1 ± 0.3

## 4.2 Shear tests

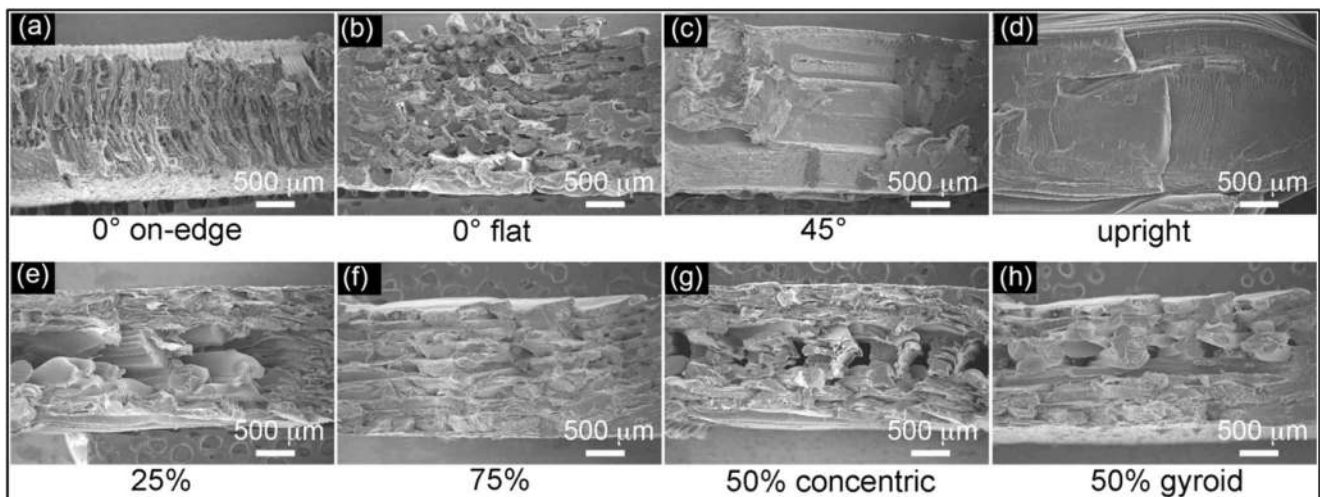
Figure 11 illustrates shear stress-strain curves for different build orientations of 0° on-edge, 0° flat, 45° flat and upright. There are significant variations in shear strength and shear modulus as a function of build orientation as presented in Table 7. The shear stress-strain curves reveal the same trends as seen in tensile results in that the PLA exhibits remarkable anisotropy.

The 45° flat orientation shows the highest values for maximum shear strength and shear modulus which were about  $\tau = 36$  MPa and  $G_{yx} = 1.55$  GPa respectively, while the upright orientation resulted in the lowest values. The shear strength and shear modulus were about  $\tau = 18$  MPa and  $G_{yx} = 0.95$  GPa respectively for the upright orientation, which is about 50% and 38.7% less than the 45° flat orientation. The 0° on-edge orientation depicted lower shear strength and shear modulus ( $\tau = 27$  MPa and  $G_{yx} = 1.21$  GPa respectively) as compared to the 45° flat orientation. In the case of the 0° flat, the shear strength and shear modulus were about  $\tau = 35$  MPa and  $G_{yx} = 1.27$  GPa respectively. The shear modulus appears isotropic as a function of build orientation, unlike the results seen in tensile testing. However, the upright specimens featured the lowest values (Table 7), which indicates weak adhesion between the deposited layers of PLA. These results have confirmed the results of previous studies [22].

The strain fields obtained by DIC under shear loading at four different build orientations are illustrated in Fig. 11. Figure 11 b–e show DIC results in terms of the shear strain,  $\gamma_{xy}$ , distribution just before failure (at about 95% of failure load) for the four different build orientations. It is seen that all specimens failed within the gauge length. In all the four cases, the DIC results show the specimens appeared to delaminate along the notched area and very high localised strains occur near to the notches in the Iosipescu specimen as expected. Noticeably, the build orientations appeared to have less effect on shear modulus as only the upright specimen was significantly different from the other orientations. For the 0° on-edge specimen, the localised shear strain maximum was  $\sim \gamma_{xy} = 0.4\%$ , whereas  $\gamma_{xy} = 0.5\%$  for the 0° flat specimen. Comparing the 45° flat and upright specimens, the maximum localised shear strain was almost identical. The results show a good agreement with tensile testing. Thus, it is reasonable to conclude that the 3D FFF part on-edge specimens showed the optimal mechanical performance in terms of strength, modulus and ductility in both tensile and shear testing.

## 4.3 Fractography analysis of tensile failure

The breakage occurred within the gauge length for all the specimens tested. Figure 12 shows SEM images of the fractured surface of tensile specimens of 0° on-edge, 0° flat, 45°, 25% infill density, 75% infill density, 50% concentric pattern and 50% gyroid pattern.



**Fig. 12** SEM images illustrating details of the fracture surfaces of **a** 0° on-edge orientation, **b** 0° flat orientation, **c** 45° orientation, **d** upright orientation, **e** 25% infill density, **f** 75% infill density, **g** 50% concentric pattern and **h** 50% gyroid pattern

upright, 25% infill density, 75% infill density, 50% concentric pattern and 50% gyroid pattern. Comparison of the fracture morphology shows the failure mode changes as a function of build orientation. Failure from on-edge to upright orientation changes from ductile to brittle; the transition in behaviour from ductile to brittle fracture is mainly due to the layer deposition direction. In 0° on-edge orientation, the layer deposition direction was perpendicular to the specimen axis and the load was applied parallel to the layers, which is mainly associated with trans-layer failure and therefore shows ductile fracture with significant plastic deformation (see stress-strain curve, illustrated in Fig. 5). As the build angle increases, the specimens display an intermediate brittle-ductile fracture behaviour. Noticeably, when the build orientation angles increase ( $\geq 45^\circ$ ), the specimen demonstrates the transition to brittle failure, with little plastic deformation. The upright orientation fails by brittle fracture due to inter-layer fusion bond failure as the load is applied perpendicular to their layers; the stress-strain curve exhibits linear behaviour followed by sudden failure.

Figure 12 e, f show the SEM images of the tensile fracture surface for 25% and 75% infill densities, whereas Fig. 12 g, h show the 50% concentric and 50% gyroid pattern fracture surfaces respectively. The 50% infill density displays a mixed brittle-ductile behaviour. For the 25% infill density, the empty space between the layer interfaces is greater as compared to 75% infill density, and there is more plastic deformation in the solid regions at lower infill density. Changing the infill pattern does not significantly change the plastic response as seen in the stress-strain curve.

## 5 Conclusions

In this work, the effect of build orientation, infill density and infill pattern on the mechanical properties of 3D-printed polylactic acid (PLA) specimens was investigated with the aid of digital image correlation (DIC). Samples according to the ASTM standard D-638 for tensile (type IV) and D-5379 for shear geometry were created using fused filament fabrication (FFF) 3D printing. Digital image correlation (DIC) was employed to get full-field surface-strain measurements. The mechanical response was shown to significantly vary as a function of process parameters, especially the build orientation. Anisotropy was found when comparing the on-edge, flat and upright orientations of 3D FFF-printed PLA specimens. For on-edge samples typical values, the tensile strength and Young's modulus were found to be 55 MPa and 3.5 GPa, and for the upright orientation, they were 5 MPa and 2 GPa respectively. Similar anisotropy was observed in shear tests. With increasing infill density, the tensile strength and Young's modulus increase in a quadratic fashion. When the filament deposition direction aligns with loading direction, the

mechanical properties of the test pieces are almost identical to those of the individual filaments. When the loading axis is at an angle to the filament deposition direction, lower strength and stiffness values were produced; the fusion between deposited filaments is not perfect leading to defects between them which affect mechanical properties. This is true for both build orientation and raster direction. The experimental results were compared to an analytical constitutive model based on laminate theory predictions. Identical trends were observed with the predictions greater than the measured results due to the defects introduced in the printing process and tensile loading on the interface between deposited filament lines. For different infill patterns, the mechanical response did not vary significantly.

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