THE GEOMETRICAL LANGUAGE OF CONTINUUM MECHANICS

This book presents the fundamental concepts of modern Differential Geometry within the framework of Continuum Mechanics. It is divided into three parts of roughly equal length. The book opens with a motivational chapter to impress upon the reader that Differential Geometry is indeed the natural language of Continuum Mechanics or, better still, that the latter is a prime example of the application and materialization of the former. In the second part, the fundamental notions of Differential Geometry are presented with rigor using a writing style that is as informal as possible. Differentiable manifolds, tangent bundles, exterior derivatives, Lie derivatives, and Lie groups are illustrated in terms of their mechanical interpretations. The third part includes the theory of fibre bundles, G-structures, and groupoids, which are applicable to bodies with internal structure and to the description of material inhomogeneity. The abstract notions of Differential Geometry are thus illuminated by practical and intuitively meaningful engineering applications.

Marcelo Epstein is currently a Professor of Mechanical Engineering at the University of Calgary, Canada. His main research revolves around the various aspects of modern Continuum Mechanics and its applications. A secondary related area of interest is biomechanics. He is a Fellow of the American Academy of Mechanics, recipient of the Cancam prize, and University Professor of Rational Mechanics. He is also adjunct Professor in the Faculties of Humanities and Kinesiology at the University of Calgary.

The Geometrical Language of Continuum Mechanics

Marcelo Epstein University of Calgary



CAMBRIDGE UNIVERSITY PRESS

University Printing House, Cambridge CB2 8BS, United Kingdom

One Liberty Plaza, 20th Floor, New York, NY 10006, USA

477 Williamstown Road, Port Melbourne, VIC 3207, Australia

314-321, 3rd Floor, Plot 3, Splendor Forum, Jasola District Centre, New Delhi - 110025, India

103 Penang Road, #05-06/07, Visioncrest Commercial, Singapore 238467

Cambridge University Press is part of the University of Cambridge.

It furthers the University's mission by disseminating knowledge in the pursuit of education, learning and research at the highest international levels of excellence.

www.cambridge.org Information on this title: www.cambridge.org/9780521198554

© Marcelo Epstein 2010

This publication is in copyright. Subject to statutory exception and to the provisions of relevant collective licensing agreements, no reproduction of any part may take place without the written permission of Cambridge University Press.

First published 2010 First paperback edition 2013

A catalogue record for this publication is available from the British Library

Library of Congress Cataloging in Publication data Epstein, M. (Marcelo) The geometrical language of continuum mechanics / Marcelo Epstein. p. cm. ISBN 978-0-521-19855-4 (hardback) 1. Continuum mechanics. I. Title. QA808.2.E67 2010 531-dc22 2010019217

ISBN 978-0-521-19855-4 Hardback ISBN 978-1-107-61703-2 Paperback

Cambridge University Press has no responsibility for the persistence or accuracy of URLs for external or third-party internet websites referred to in this publication, and does not guarantee that any content on such websites is, or will remain, accurate or appropriate.

> To Silvio's memory "Heu ... frater adempte mihi!"

Contents

Preface	·	xi
PAF	RT 1 MOTIVATION AND BACKGROUND	1
1	The Case for Differential Geometry	3
1.1	Classical Space-Time and Fibre Bundles	4
1.2	Configuration Manifolds and Their Tangent and Cotangent Spaces	10
1.3	The Infinite-dimensional Case	13
1.4	Elasticity	22
1.5	Material or Configurational Forces	23
2	Vector and Affine Spaces	24
2.1	Vector Spaces: Definition and Examples	24
2.2	Linear Independence and Dimension	26
2.3	Change of Basis and the Summation Convention	30
2.4	The Dual Space	31
2.5	Linear Operators and the Tensor Product	34
2.6	Isomorphisms and Iterated Dual	36
2.7	Inner-product Spaces	41
2.8	Affine Spaces	46
2.9	Banach Spaces	52
3	Tensor Algebras and Multivectors	57
3.1	The Algebra of Tensors on a Vector Space	57
3.2	The Contravariant and Covariant Subalgebras	60
3.3	Exterior Algebra	62
3.4	Multivectors and Oriented Affine Simplexes	69
3.5	The Faces of an Oriented Affine Simplex	71
3.6	Multicovectors or <i>r</i> -Forms	72
3.7	The Physical Meaning of <i>r</i> -Forms	75
3.8	Some Useful Isomorphisms	76

viii Contents

PAR	T 2 DIFFERENTIAL GEOMETRY	79
4	Differentiable Manifolds	81
4.1	Introduction	81
4.2	Some Topological Notions	83
4.3	Topological Manifolds	85
4.4	Differentiable Manifolds	86
4.5	Differentiability	87
4.6	Tangent Vectors	89
4.7	The Tangent Bundle	94
4.8	The Lie Bracket	96
4.9	The Differential of a Map	101
4.10	Immersions, Embeddings, Submanifolds	105
4.11	The Cotangent Bundle	109
4.12	Tensor Bundles	110
4.13	Pull-backs	112
4.14	Exterior Differentiation of Differential Forms	114
4.15	Some Properties of the Exterior Derivative	117
4.16	Riemannian Manifolds	118
4.17	Manifolds with Boundary	119
4.18	Differential Spaces and Generalized Bodies	120
5	Lie Derivatives, Lie Groups, Lie Algebras	126
5 5.1	Lie Derivatives, Lie Groups, Lie Algebras	126 126
5.1	Introduction	126
5.1 5.2	Introduction The Fundamental Theorem of the Theory of ODEs	126 127
5.1 5.2 5.3	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field	126 127
5.1 5.2 5.3	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations	126 127 128
5.1 5.2 5.3 5.4	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows	126 127 128 129
5.1 5.2 5.3 5.4 5.5	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields	126 127 128 129 130
 5.1 5.2 5.3 5.4 5.5 5.6 	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative	126 127 128 129 130 131
5.1 5.2 5.3 5.4 5.5 5.6 5.7	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative Invariant Tensor Fields	126 127 128 129 130 131 135
5.1 5.2 5.3 5.4 5.5 5.6 5.7 5.8	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative Invariant Tensor Fields Lie Groups	126 127 128 129 130 131 135 138
5.1 5.2 5.3 5.4 5.5 5.6 5.7 5.8 5.9 5.10 5.11	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative Invariant Tensor Fields Lie Groups Group Actions One-Parameter Subgroups Left- and Right-Invariant Vector Fields on a Lie Group	126 127 128 129 130 131 135 138 140 142 143
5.1 5.2 5.3 5.4 5.5 5.6 5.7 5.8 5.9 5.10 5.11 5.12	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative Invariant Tensor Fields Lie Groups Group Actions One-Parameter Subgroups Left- and Right-Invariant Vector Fields on a Lie Group The Lie Algebra of a Lie Group	126 127 128 129 130 131 135 138 140 142 143 145
5.1 5.2 5.3 5.4 5.5 5.6 5.7 5.8 5.9 5.10 5.11 5.12 5.13	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative Invariant Tensor Fields Lie Groups Group Actions One-Parameter Subgroups Left- and Right-Invariant Vector Fields on a Lie Group The Lie Algebra of a Lie Group Down-to-Earth Considerations	126 127 128 129 130 131 135 138 140 142 143 145 149
5.1 5.2 5.3 5.4 5.5 5.6 5.7 5.8 5.9 5.10 5.11 5.12	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative Invariant Tensor Fields Lie Groups Group Actions One-Parameter Subgroups Left- and Right-Invariant Vector Fields on a Lie Group The Lie Algebra of a Lie Group	126 127 128 129 130 131 135 138 140 142 143 145
5.1 5.2 5.3 5.4 5.5 5.6 5.7 5.8 5.9 5.10 5.11 5.12 5.13	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative Invariant Tensor Fields Lie Groups Group Actions One-Parameter Subgroups Left- and Right-Invariant Vector Fields on a Lie Group The Lie Algebra of a Lie Group Down-to-Earth Considerations	126 127 128 129 130 131 135 138 140 142 143 145 149
5.1 5.2 5.3 5.4 5.5 5.6 5.7 5.8 5.9 5.10 5.11 5.12 5.13 5.14	Introduction The Fundamental Theorem of the Theory of ODEs The Flow of a Vector Field One-parameter Groups of Transformations Generated by Flows Time-Dependent Vector Fields The Lie Derivative Invariant Tensor Fields Lie Groups Group Actions One-Parameter Subgroups Left- and Right-Invariant Vector Fields on a Lie Group The Lie Algebra of a Lie Group Down-to-Earth Considerations The Adjoint Representation	126 127 128 129 130 131 135 138 140 142 143 145 149 153

	Con	tents
6.3	Integration of Forms on Oriented Manifolds	166
6.4	Fluxes in Continuum Physics	169
6.5	General Bodies and Whitney's Geometric Integration Theory	174
PAR	T 3 FURTHER TOPICS	189
7	Fibre Bundles	191
7.1	Product Bundles	191
7.2	Trivial Bundles	193
7.3	General Fibre Bundles	196
7.4	The Fundamental Existence Theorem	198
7.5	The Tangent and Cotangent Bundles	199
7.6	The Bundle of Linear Frames	201
7.7	Principal Bundles	203
7.8	Associated Bundles	206
7.9	Fibre-Bundle Morphisms	209
7.10	Cross Sections	212
7.11	Iterated Fibre Bundles	214
8	Inhomogeneity Theory	220
8.1	Material Uniformity	220
8.2	The Material Lie groupoid	233
8.3	The Material Principal Bundle	237
8.4	Flatness and Homogeneity	239
8.5	Distributions and the Theorem of Frobenius	240
8.6	Jet Bundles and Differential Equations	242
9	Connection, Curvature, Torsion	245
9.1	Ehresmann Connection	245
9.1 9.2	Connections in Principal Bundles	243 248
9.2 9.3	Linear Connections	240
9.4	G-Connections	252 258
9. 4 9.5	Riemannian Connections	258 264
9.6	Material Homogeneity	264 265
9.0 9.7	Homogeneity Criteria	203 270
		_,,
Арр	endix A A Primer in Continuum Mechanics	274
A.1	Bodies and Configurations	274
A.2	Observers and Frames	275
A.3	Strain	276
A.4	Volume and Area	280
A.5	The Material Time Derivative	281

ix

x Contents

A.6	Change of Reference	282
A.7	Transport Theorems	284
A.8	The General Balance Equation	285
A.9	The Fundamental Balance Equations of Continuum Mechanics	289
A.10	A Modicum of Constitutive Theory	295
Index		306

Preface

Il naufragar m'è dolce in questo mare. GIACOMO LEOPARDI

In mathematics and the sciences, just as in the arts, there is no substitute for the masterpieces. Fortunately, both in Differential Geometry and in Continuum Mechanics, we possess a veritable treasure trove of fundamental masterpieces, classical as well as modern. Reading them may elicit a pleasure, even an emotion, comparable to that aroused by playing a Mozart piano sonata, the same sensation of perfection and beauty, the sweetness of drowning in such an ocean. This comparison is fair also in a different sense, namely, that for common mortals to achieve these spiritual heights requires a considerable amount of study and work, without which we must resign ourselves to the intuitive feelings evoked by the senses and to the assurances of the critics or the arbiters of taste. The aim of this book is to provide some familiarity with the basic ideas of Differential Geometry as they become actualized in the context of Continuum Mechanics so that the reader can feel more at home with the masters.

Differential Geometry is a rather sophisticated blend of Algebra, Topology, and Analysis. My selection of topics as a nonmathematician is rather haphazard and the depth and rigor of the treatment vary from topic to topic. As befits human nature, I am understandably forgiving of myself for this lack of consistency, but the reader may not be so kind, in which case I will not take it as a personal offence. One way or the other, there is no escape from the fact that the subject matter is extremely difficult and requires dedication and patience, particularly for the various interconnected levels of generalization and abstraction. In this respect, the presence of Continuum Mechanics as a materialization of many of the important geometric notions is of invaluable help. Learning can be regarded as a helical process, whereby each turn elevates us to the next storey of a building with an infinite number of floors. On each floor the same ideas dwell as on all others, but the perspective is wider. The speed of ascent is strongly dependent on the natural abilities and background of the visitor. Ideally, a good book should help to accelerate this process, regardless of

CAMBRIDGE

Cambridge University Press & Assessment 978-0-521-19855-4 — The Geometrical Language of Continuum Mechanics Marcelo Epstein Frontmatter More Information

xii Preface

the particular floor of departure. In some cases, a good book may help the visitor to abandon the building altogether in justifiable alarm and despair.

The plan and structure of the book emerge quite clearly from a cursory glance at the Contents, which probably reflects my own predilections and priorities. Having been trained initially in Civil Engineering, my own ascent to modern Differential Geometry was rather tortuous and slow: from beams and shells to classical geometry of curves and surfaces, from Linear Elasticity to Continuum Mechanics, General Relativity, continuous distributions of dislocations, and beyond. Along the way, I was privileged to have the help of Jędrzej Śniatycki (Calgary), Reuven Segev (Beer Sheva), Marek Elżanowski (Portland), and Manuel de León (Madrid) – to each of whom I owe more than I can express. These notes are in part the result of two graduate courses in engineering, the first at the invitation of Carlos Corona at the Universidad Politécnica de Madrid in the spring of 2006 and the second at the invitation of Ben Nadler at the University of Alberta in the spring of 2009. Both courses were helpful in providing a sounding board for the presentation and, in the second case, getting assistance from the students in spotting errors in the manuscript and providing valuable suggestions.

Calgary, July 2009