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The holographic fluid dual to vacuum Einstein gravity

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Science Park 904, 1090 GL Amsterdam, the Netherlands. ^bInstitute for Theoretical Physics, Science Park 904, 1090 GL Amsterdam, the Netherlands. ^cGravitation and Astro-Particle Physics Amsterdam, Science Park 904, 1090 GL Amsterdam, the Netherlands. E-mail: gcompere@uva.nl, p.l.mcfadden@uva.nl, k.skenderis@uva.nl, m.taylor@uva.nl ABSTRACT: We present an algorithm for systematically reconstructing a solution of the (d+ 2)-dimensional vacuum Einstein equations from a (d + 1)-dimensional fluid, extending the non-relativistic hydrodynamic expansion of Bredberg et al. in arXiv:1101.2451 to arbitrary order. The fluid satisfies equations of motion which are the incompressible Navier-Stokes equations, corrected by specific higher-derivative terms. The uniqueness and regularity of this solution is established to all orders and explicit results are given for the bulk metric and the stress tensor of the dual fluid through fifth order in the hydrodynamic expansion. We

establish the validity of a relativistic hydrodynamic description for the dual fluid, which has the unusual property of having a vanishing equilibrium energy density. The gravitational results are used to identify transport coefficients of the dual fluid, which also obeys an interesting and exact constraint on its stress tensor. We propose novel Lagrangian models which realise key properties of the holographic fluid.

KEYWORDS: Gauge-gravity correspondence, Classical Theories of Gravity

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Contents

1	Introduction and summary of results	1
2	Equilibrium configurations	5
3	Seed metric for near-equilibrium configurations	7
4	Constructing the solution to all orders	8
5	Gauge choices for the fluid	12
	5.1 Fixing $F_i^{(n)}(\tau, \vec{x})$	13
	5.2 Fixing $F_{\tau}^{(n)}(\tau, \vec{x})$	14
6	Results to $O(\epsilon^6)$	14
	6.1 Corrections to Navier-Stokes and incompressibility	14
	6.2 Metric at higher orders	15
	6.3 Stress tensor at higher orders	16
7	Characterising the dual fluid	17
	7.1 Relativistic hydrodynamics for vanishing equilibrium energy density	18
	7.2 Determination of transport coefficients	19
8	Models for the dual fluid	20
9	Discussion	23
\mathbf{A}	Choice of radial gauge	25
в	Infinitesimal diffeomorphisms preserving equilibrium	25
С	A basis for second-order relativistic hydrodynamics	27

1 Introduction and summary of results

Black hole physics suggests that gravitational theories are holographic and indeed over the last 15 years we have witnessed remarkable progress in uncovering holographic relations, mainly between (d+2)-dimensional gravitational theories with negative cosmological constant and (d+1)-dimensional local quantum field theories. The case of asymptotically flat spacetimes remains elusive and indeed the structure of the asymptotic solutions [1–3] and the divergences of the on-shell action suggest [4] that if there is a dual theory it is nonlocal, see also [5].

In a recent paper [6] (see [7–14] for earlier relevant work), a remarkable relation between incompressible non-relativistic fluids in (d + 1) dimensions satisfying the Navier-Stokes equation and (d + 2)-dimensional Ricci flat metrics was found. The construction of [6] starts from considering the portion of Minkowski spacetime between a flat hypersurface Σ_c , given by the equation $X^2 - T^2 = 4r_c$, and its future horizon \mathcal{H}^+ , the null surface X = T. Then the effects of finite perturbations of the extrinsic curvature of Σ_c , with the intrinsic metric γ_{ab} kept fixed, were studied and it was found that a regular Ricci flat metric exists provided that the Brown-York stress tensor on Σ_c is that of an incompressible Navier-Stokes fluid. More precisely, they work in a hydrodynamic non-relativistic limit and construct the bulk metric up to third order in the hydrodynamic expansion. Apart from its intrinsic value, this relationship provides a potential example of a holographic duality involving a flat spacetime and as such it should be further explored.

The aim of this paper is two-fold. Firstly, we would like to provide a systematic construction of the bulk solution to all orders in the hydrodynamic expansion and secondly we would like to extract the physical properties of the dual fluid in order to obtain clues about the nature of the dual theory.

Let us summarise our results. First recall that in the hydrodynamic limit essentially any (d + 1)-dimensional fluid is governed by the incompressible Navier-Stokes equation

$$E_i \equiv \partial_\tau v_i + v^j \partial_j v_i - \eta \partial^2 v_i + \partial_i P = 0, \qquad E \equiv \partial_i v^i = 0, \quad (i = 1, \dots, d), \tag{1.1}$$

where v^i is the velocity field, P is a pressure fluctuation about the background value and η is the kinematic viscosity. This equation has a scaling symmetry and admits a one-parameter family of solutions

$$v_i^{(\epsilon)}(\tau, \vec{x}) = \epsilon v_i(\epsilon^2 \tau, \epsilon \vec{x}), \qquad P^{(\epsilon)}(\tau, \vec{x}) = \epsilon^2 P(\epsilon^2 \tau, \epsilon \vec{x}). \tag{1.2}$$

If one considers now higher-derivative corrections to E_i and E, these are naturally organised according to their scaling with ϵ .

Our first main result is an algorithmic construction of a regular Ricci-flat metric corresponding to a fluid satisfying (1.1) with specific higher-derivative corrections. We begin with the observation that the metric up to order ϵ^2 with constant velocity and pressure fields is actually flat space in disguise: it can be obtained from the Rindler metric by a linear coordinate transformation combining a boost which introduces a constant velocity field v^i with a simple shift and rescaling of the radial and time coordinates that introduces a constant pressure function P. In fact, these transformations are the most general infinitesimal diffeomorphisms that preserve the induced metric at $r = r_c$ and lead to a Brown-York stress tensor which is of the form of a fluid in equilibrium. (Recall that the Brown-York stress tensor for Rindler spacetime is of that form).

To extend the solution to next order in the hydrodynamic expansion, we follow [15] and promote the velocity field and the pressure function to be spacetime dependent quantities, subject to the requirement that the Einstein equations hold up to order ϵ^3 . To satisfy this requirement one needs to introduce new terms of order ϵ^3 in the metric and we find that (1.1) holds. This reproduces the metric given in [6] (up to a choice of gauge for the dual fluid). Next we prove inductively that Einstein equations can in fact be satisfied to arbitrarily high order in ϵ , by adding appropriate terms to the metric and modifying the Navier-Stokes equation and the incompressibility condition by specific higher derivative corrections. In particular, the incompressibility condition E is modified at even powers of ϵ while the Navier-Stokes equation E_i is modified at odd powers of ϵ . We carried out this procedure explicitly to order ϵ^5 and obtained the resultant metric through to order ϵ^5 , given in (6.5)– (6.6)–(6.8)–(6.9) as well as the leading order corrections to E and E_i , given in (6.1) and (6.3), respectively.

The dual fluid has a number of interesting and unconventional features. Firstly, in equilibrium it has zero energy density and positive nonzero pressure. In the hydrodynamic regime, the stress tensor receives dissipative corrections, the explicit form of which is given to order ϵ^5 in (6.10), (6.11) and (6.12). As a consequence of the (bulk) Hamiltonian constraint, the fluid stress tensor satisfies the quadratic constraint,

$$dT_{ab}T^{ab} = T^2. aga{1.3}$$

This is an interesting constraint on the dual theory which will be discussed further below.

Since the bulk solution is constructed using a non-relativistic hydrodynamic expansion in ϵ , the fluid stress tensor appears to be non-relativistic. In turns out however that the complete answer, including dissipative terms, can be obtained from a relativistic hydrodynamic stress tensor upon using the non-relativistic expansion in ϵ . The rather complicated expressions obtained by direct computation actually originate from a much simpler relativistic stress tensor. The information encoded in the stress tensor can then be expressed in terms of a few transport coefficients. These considerations indicate also that the underlying holographic dual theory should be relativistic.

Recall that a relativistic fluid stress tensor takes the general form

$$T_{ab} = \rho u_a u_b + p h_{ab} + \Pi_{ab}^{\perp}, \qquad u^a \Pi_{ab}^{\perp} = 0,$$
 (1.4)

where ρ and p are the energy density and pressure of the fluid in the local rest frame, u^a is the relativistic fluid velocity (normalised such that $u_a u^a = -1$), and $h_{ab} = \gamma_{ab} + u_a u_b$ is the induced metric on surfaces orthogonal to the fluid velocity. The term Π_{ab}^{\perp} encodes dissipative corrections and may be expanded in gradients of the fluid velocity. When the equilibrium energy density is nonzero, one may show that the Landau-Lifshitz prescription [16] implies that the energy density ρ does not receive any gradient corrections. This is in stark contrast to the case in hand where the equilibrium fluid has zero energy density and the energy density becomes nonzero and negative due to gradient terms. In fact the quadratic constraint (1.3) uniquely determines ρ in terms of the dissipative terms. The leading order result for ρ is given in (7.1).

From the dissipative terms, Π_{ab}^{\perp} , one can read off the transport coefficients. The relativistic corrections are organised according to the number of derivatives they contain. Each of these terms can then be expanded in the non-relativistic hydrodynamic expansion. The ϵ expansion may increase the number of derivatives but it never decreases them. This means that one can unambiguously extract all transport coefficients but one will have to

work to sufficiently high order in ϵ in order to obtain all transport coefficients. At first order in derivatives, there is only one possible term¹ and from this the kinematic shear viscosity is obtained. If we identify the entropy density of the fluid using the entropy of the Rindler horizon, the ratio η/s takes the universal value,

$$\eta/s = 1/(4\pi).$$
 (1.5)

At second order, there are six transport coefficients (for a fluid in a flat background) and our computation to order ϵ^5 determines four of them, see (7.5) and (7.12). The products of these coefficients with the (background) pressure are pure numbers and one gets the following relations

$$2c_1p = c_2p = c_3p = c_4p = -4. (1.6)$$

These results encode all the information contained in the dissipative parts of the stress tensor, up to this order.

Let us now move to the non-dissipative part,

$$T_{ab}^{\rm non-dissipative} = ph_{ab}.$$
 (1.7)

Note that this satisfies by itself the quadratic constraint. One may ask whether there is a Lagrangian model that leads to this stress tensor. It turns out that such a model indeed exists and is given by²

$$S = \int \mathrm{d}^{d+1}x \sqrt{-\gamma} \sqrt{-(\partial\phi)^2}.$$
 (1.8)

This describes an ideal fluid with $u_a = \partial_a \phi / \sqrt{-(\partial \phi)^2}$ and stress tensor given by (1.7) with $p = \sqrt{-(\partial \phi)^2}$. The equilibrium configuration corresponds to the solution $\phi = \tau$ and near-equilibrium configurations are obtained by looking at small fluctuations around this solution. The background solution breaks the relativistic invariance and the expansion around this solution leads to a non-relativistic nonlocal action (since it contains an infinite number of derivatives). Thus, this simple scalar theory (and its generalisations, see (8.13)) reproduces the non-dissipative part of the stress tensor and incorporates many of the features ones expects from the holographic dual theory.

The plan of the paper is as follows. In section 2, we discuss a general class of flat metrics admitting a Rindler horizon for which the Brown-York stress tensor on the constant-radius slice Σ_c outside the horizon is that of a perfect fluid with zero energy density. These equilibrium backgrounds are used in section 3 as seed metrics to construct corresponding near-equilibrium configurations. In section 4, we give the algorithm for systematically constructing the bulk solution to arbitrary order in the hydrodynamic expansion, while in section 5, we explain the gauge-fixing conditions imposed on the fluid. In section 6, we give explicit results for the metric and stress tensor up to order ϵ^5 , and in section 7, these results are interpreted in terms of transport coefficients for the dual fluid. Section 8 proposes a simple dual Lagrangian which captures key properties of the fluid, and in

¹For relativistic fluids in general there would also be a bulk viscosity term. For fluids with zero equilibrium energy density, this term vanishes as a consequence of the equations of motion (see section 7).

^{2}Interestingly, this action has also been investigated in the context of dark energy, see [17, 18].

section 9, we discuss our results. Finally, in the three appendices we present some of the technical results used in the main text. In appendix A, we discuss the choice of radial gauge; in appendix B, we derive the class of infinitesimal diffeomorphisms preserving the equilibrium form of the Brown-York stress tensor; and in appendix C, we derive the general form of the hydrodynamic expansion to second order in gradients for a relativistic fluid with vanishing equilibrium energy density.

2 Equilibrium configurations

Let us first construct a class of Riemann-flat metrics which have the following properties: (i) they admit a co-dimension one hypersurface Σ_c of flat induced metric

$$\gamma_{ab} \mathrm{d}x^a \mathrm{d}x^b = -r_c \mathrm{d}\tau^2 + \mathrm{d}x_i \mathrm{d}x^i, \qquad (2.1)$$

where the speed of light $\sqrt{r_c}$ is arbitrary, $x^{\mu} = (r, x^a)$ and $x^a = (\tau, x^i)$ with $i = 1, \ldots, d$ (unless otherwise noted, Latin indices are raised with γ^{ab} and Greek indices with $g^{\mu\nu}$); (ii) the Brown-York stress tensor [19] on Σ_c , given by³

$$T_{ab} = \frac{1}{8\pi G} (K\gamma_{ab} - K_{ab}),$$
(2.2)

where K_{ab} is the extrinsic curvature of Σ_c , takes the form of a perfect fluid stress tensor,

$$T_{ab} = \rho u_a u_b + p h_{ab}, \tag{2.3}$$

and finally; (iii) they are stationary with respect to ∂_{τ} and homogeneous in the x^i directions.

One such metric with these properties is

$$ds^{2} = \bar{g}_{\mu\nu} dx^{\mu} dx^{\nu} = -r d\tau^{2} + 2d\tau dr + dx_{i} dx^{i}, \qquad (2.4)$$

which describes flat space in ingoing Rindler coordinates. (Upon setting $\tau = 2 \ln(X + T)$ and $4r = X^2 - T^2$, we recover $ds^2 = -dT^2 + dX^2$). The induced metric γ_{ab} on the surface Σ_c defined by $r = r_c$ then has the form (2.1), while the Brown-York stress tensor on Σ_c has the form (2.3), where $u_{\tau} = -r_c^{1/2}$, $u_i = 0$, $\rho = 0$ and $p = r_c^{-1/2}$. The Rindler horizon is at r = 0.

We may now obtain further metrics satisfying conditions (i), (ii) and (iii) by considering the action of diffeomorphisms on (2.4). Since we wish to obtain a connected thermodynamical state space, it is sufficient to consider only diffeomorphisms that are continuously connected to the identity, i.e., those obtained by exponentiating infinitesimal diffeomorphisms. In appendix B, we show that there are only two infinitesimal diffeomorphisms yielding metrics satisfying conditions (i), (ii) and (iii), after fixing the radial gauge as described in appendix A. Exponentiating these, we obtain the following two finite diffeomorphisms.

³From here onwards we will set $16\pi G = 1$. We also assume the validity of classical gravity, i.e., higherorder curvature and quantum corrections are suppressed.

The first is a constant boost β_i , given by

$$\sqrt{r_c}\tau \to \gamma\sqrt{r_c}\tau - \gamma\beta_i x^i, \qquad x^i \to x^i - \gamma\beta^i\sqrt{r_c}\tau + (\gamma - 1)\frac{\beta^i\beta_j}{\beta^2}x^j,$$
 (2.5)

where $\gamma = (1 - \beta^2)^{-1/2}$ and $\beta_i \equiv r_c^{-1/2} v_i$. The second is a constant linear shift of r and associated re-scaling of τ ,

$$r \to r - r_h, \qquad \tau \to (1 - r_h/r_c)^{-1/2} \tau.$$
 (2.6)

Note that this latter transformation shifts the position of the horizon to $r = r_h$; as we are only interested in the case where Σ_c is outside the horizon we will restrict $r_h < r_c$.

Since these transformations are both linear in the coordinates, one can apply them in either order on Rindler spacetime. One obtains

$$ds^{2} = \frac{d\tau^{2}}{1 - v^{2}/r_{c}} \left(v^{2} - \frac{r - r_{h}}{1 - r_{h}/r_{c}} \right) + \frac{2\gamma}{\sqrt{1 - r_{h}/r_{c}}} d\tau dr - \frac{2\gamma v_{i}}{r_{c}\sqrt{1 - r_{h}/r_{c}}} dx^{i} dr + \frac{2v_{i}}{1 - v^{2}/r_{c}} \left(\frac{r - r_{c}}{r_{c} - r_{h}} \right) dx^{i} d\tau + \left(\delta_{ij} - \frac{v_{i}v_{j}}{r_{c}^{2}(1 - v^{2}/r_{c})} \left(\frac{r - r_{c}}{1 - r_{h}/r_{c}} \right) \right) dx^{i} dx^{j}.$$
(2.7)

While this metric appears complicated, it is in reality simply flat space written in a complicated coordinate system. Nevertheless, the Brown-York stress tensor on Σ_c has the desired form (2.3), where the energy density, pressure and relativistic fluid velocity are given by

$$\rho = 0, \qquad p = \frac{1}{\sqrt{r_c - r_h}}, \qquad u^a = \frac{1}{\sqrt{r_c - v^2}}(1, v_i).$$
(2.8)

In particular, the energy density ρ vanishes. We stress that there is no flat solution continuously connected to Rindler spacetime which generates a nonzero equilibrium energy density while at the same time preserving the form of the induced metric on Σ_c , as shown in appendix B. In connection with this, note that the inherent ambiguity in the definition of the Brown-York stress tensor [19], which gives the freedom to send $T_{ab} \to T_{ab} + C\gamma_{ab}$ for some constant C, produces only a trivial constant shift in the background energy density and pressure given by $\rho \to \rho - C$ and $p \to p + C$. This ambiguity has no dynamical consequences, however, and so we will suppress it in the remainder of this paper by setting C = 0. Furthermore, since the induced metric γ_{ab} is flat, there are no additional ambiguities involving the intrinsic curvature of Σ_c .

Finally, let us consider the thermodynamic properties of the metric (2.7). First, the Rindler horizon is a Killing horizon and has a constant Unruh temperature given by

$$T = \frac{\kappa}{2\pi} = \frac{1}{4\pi\sqrt{r_c - r_h}},\tag{2.9}$$

where the surface gravity κ is defined as $\xi^{\nu} \nabla_{\nu} \xi^{\mu} = \kappa \xi^{\mu}$, where $\xi = \frac{1}{\sqrt{r_c - v^2}} (\partial_{\tau} + v_i \partial_i)$ is normalised so that $\xi_a \xi^a = -1$ on Σ_c . If we then introduce an entropy density associated with the Rindler horizon identical to the black hole entropy density s = 1/4G, we note the thermodynamic relation⁴

$$sT = p. (2.10)$$

This further implies that two neighbouring equilibrium configurations are related by the Gibbs-Duhem relation

$$s\delta T = \delta p \,. \tag{2.11}$$

As a final point of interest, we note that the region $r_h \leq r \leq r_h + (1 - r_h/r_c)v^2$ is an ergoregion with respect to the τ -translations, which may lead to effects analogous to superradiance.

3 Seed metric for near-equilibrium configurations

Let us now change gears and discuss how to construct near-equilibrium configurations. We would like to obtain a solution of the vacuum Einstein equations parameterised by a velocity field v_i and a pressure field p which are local slowly varying functions of the coordinates x^a , while preserving the form of the induced metric on Σ_c . Working perturbatively in ϵ , in the present section we show how to construct this solution up to order ϵ^2 . In the following section, we then show how to extend this 'seed' solution through to all orders in ϵ .

Clearly, if we promote v_i and p to depend arbitrarily on the coordinates x^a , the metric (2.7) is no longer an exact solution of the vacuum Einstein equations. However, treating $v_i = v_i^{(\epsilon)}(\tau, \vec{x})$ and $p = r_c^{-1/2} + r_c^{-3/2}P^{(\epsilon)}(\tau, \vec{x})$ as small fluctuations around the background $v_i = 0$, $p = r_c^{-1/2}$ in the hydrodynamic limit

$$v_i^{(\epsilon)}(\tau, \vec{x}) = \epsilon v_i(\epsilon^2 \tau, \epsilon \vec{x}), \qquad P^{(\epsilon)}(\tau, \vec{x}) = \epsilon^2 P(\epsilon^2 \tau, \epsilon \vec{x}), \tag{3.1}$$

upon expanding (2.7) (noting that $r_h = 2P^{(\epsilon)} + O(\epsilon^4)$) we obtain

$$ds^{2} = -rd\tau^{2} + 2d\tau dr + dx_{i}dx^{i}$$

$$-2\left(1 - \frac{r}{r_{c}}\right)v_{i}dx^{i}d\tau - \frac{2v_{i}}{r_{c}}dx^{i}dr$$

$$+\left(1 - \frac{r}{r_{c}}\right)\left[(v^{2} + 2P)d\tau^{2} + \frac{v_{i}v_{j}}{r_{c}}dx^{i}dx^{j}\right] + \left(\frac{v^{2}}{r_{c}} + \frac{2P}{r_{c}}\right)d\tau dr + O(\epsilon^{3}), \quad (3.2)$$

where each successive line is of one order higher in the ϵ expansion. (Here, and in the following, we drop the superscripts on $P^{(\epsilon)}$ and $v_i^{(\epsilon)}$ for simplicity). This metric by construction preserves the induced metric γ_{ab} on Σ_c . Moreover, it solves Einstein's equations to $O(\epsilon^3)$, provided one additionally imposes incompressibility, i.e., $\partial_i v^i = O(\epsilon^3)$. The metric (3.2) reproduces the solution found in [6] through to ϵ^2 order.

⁴The relation (2.10) may also be derived by evaluating Komar integrals both at the horizon Σ_h and at Σ_c . Since the solution is stationary, homogeneous in x^i and Ricci flat, the Komar integrals do not depend on the radius of evaluation and one can relate sT defined at the horizon to p defined on Σ_c using standard manipulations, see e.g., [20, 21].

As shown in [6], the Brown-York stress tensor on Σ_c for the seed solution (3.2) is

$$T_{ab} dx^{a} dx^{b} = \frac{d\vec{x}^{2}}{\sqrt{r_{c}}} - \frac{2v_{i}}{\sqrt{r_{c}}} dx^{i} d\tau + \frac{v^{2}}{\sqrt{r_{c}}} d\tau^{2} + r_{c}^{-3/2} \Big[P\delta_{ij} + v_{i}v_{j} - 2r_{c}\partial_{i}v_{j} \Big] dx^{i} dx^{j} + O(\epsilon^{3}) \,.$$
(3.3)

It is interesting to compare this result with the hydrodynamic stress tensor for a relativistic fluid with vanishing equilibrium energy density. Up to first order in fluid gradients, this takes the form⁵

$$T_{ab} = \rho u_a u_b + p h_{ab} - 2\eta \mathcal{K}_{ab} + O(\partial^2), \qquad (3.4)$$

where $\mathcal{K}_{ab} = h_a^c h_b^d \partial_{(c} u_{d)}$ is the extrinsic curvature of surfaces orthogonal to the fluid velocity⁶ and plays the role of the fluid shear. Expanding this hydrodynamic stress tensor in ϵ to order ϵ^2 , one finds that one can indeed reproduce (3.3) upon setting

$$\rho = 0 + O(\epsilon^3), \qquad p = \frac{1}{\sqrt{r_c}} + \frac{P}{r_c^{3/2}} + O(\epsilon^3), \qquad \eta = 1.$$
(3.5)

In the following section, we will now describe the algorithm to extend our seed solution (3.2) to arbitrarily high order in ϵ , with the pressure and velocity perturbations obeying the incompressible Navier-Stokes equations with higher order corrections. Note that, if desired, spacetimes describing fluctuations around a background with nonzero velocity and with a Rindler horizon located at arbitrary $r = r_h$ may then be found by applying the finite diffeomorphisms (2.5) and (2.6) to the resulting solution.

4 Constructing the solution to all orders

Let us begin by assuming we know the bulk metric through order ϵ^{n-1} . The first nonvanishing components of the Ricci tensor appear therefore at order ϵ^n . We now wish to add a new term $g_{\mu\nu}^{(n)}$ to the metric at order ϵ^n so as to extend our solution to order $O(\epsilon^{n+1})$. In addition to adding a new term to the metric, we must also consider the effect of gauge transformations $\xi^{(n)\mu}$ and field redefinitions $\delta v_i^{(n)}$ and $\delta P^{(n)}$ also at order ϵ^n .

Noting that

$$\partial_r \sim \epsilon^0, \qquad \partial_i \sim \epsilon^1, \qquad \partial_\tau \sim \epsilon^2,$$

$$(4.1)$$

adding a new term $g_{\mu\nu}^{(n)}$ at order ϵ^n to the bulk metric produces a change in bulk Ricci tensor at the same order given by

$$\delta R_{rr}^{(n)} = -\frac{1}{2} \partial_r^2 g_{ii}^{(n)},$$

$$\delta R_{ij}^{(n)} = -\frac{1}{2} \partial_r (r \partial_r g_{ij}^{(n)}),$$

$$\delta R_{\tau i}^{(n)} = -r \delta R_{ri}^{(n)} = -\frac{r}{2} \partial_r^2 g_{\tau i}^{(n)},$$

$$\delta R_{\tau \tau}^{(n)} = -r \delta R_{r\tau}^{(n)} = -\frac{r}{4} \left(\partial_r (r g_{rr}^{(n)}) + 2 \partial_r g_{r\tau}^{(n)} - \partial_r g_{ii}^{(n)} + 2 \partial_r^2 g_{\tau \tau}^{(n)} \right),$$
(4.2)

where we write $g_{ii}^{(n)} \equiv \delta^{ij} g_{ij}^{(n)}$ and $\delta R_{ii}^{(n)} \equiv \delta^{ij} \delta R_{ij}^{(n)}$.

⁵As noted previously, and as we will discuss in section 7, for a fluid with vanishing equilibrium energy density the relativistic divergence $\mathcal{K} = \partial_a u^a$ vanishes at first order in gradients and so the usual bulk viscosity term is absent.

⁶We reserve the symbol K_{ab} for the extrinsic curvature of Σ_c itself.

Our goal then is to find a $g_{\mu\nu}^{(n)}$ which cancels out the part of the Ricci tensor at order ϵ^n arising from the pre-existing metric up to order ϵ^{n-1} . (In fact, as we will see shortly, the boundary conditions are such that this requirement leads, after gauge-fixing, to a unique solution for $g_{\mu\nu}^{(n)}$). The full Ricci tensor at order ϵ^n must therefore satisfy

$$R^{(n)}_{\mu\nu} = \delta R^{(n)}_{\mu\nu} + \hat{R}^{(n)}_{\mu\nu} = 0, \qquad (4.3)$$

where $\hat{R}^{(n)}_{\mu\nu}$ denotes the part of the Ricci tensor at order ϵ^n arising from the metric up to order ϵ^{n-1} . Inspecting the equations for $\delta R^{(n)}_{\mu\nu}$ above, we see that such a cancellation will only be possible provided the following integrability conditions are satisfied:

$$0 = \partial_r (\hat{R}_{ii}^{(n)} - r\hat{R}_{rr}^{(n)}) - \hat{R}_{rr}^{(n)}, \qquad 0 = \hat{R}_{\tau a}^{(n)} + r\hat{R}_{ra}^{(n)}.$$
(4.4)

To verify that these conditions are indeed satisfied, we evaluate the Bianchi identity at order ϵ^n yielding⁷

$$0 = \partial_r (\hat{R}_{ii}^{(n)} - r\hat{R}_{rr}^{(n)}) - \hat{R}_{rr}^{(n)},$$

$$0 = \partial_r (\hat{R}_{\tau a}^{(n)} + r\hat{R}_{ra}^{(n)}) \implies \hat{R}_{\tau a}^{(n)} + r\hat{R}_{ra}^{(n)} = f_a^{(n)}(\tau, \vec{x}).$$
(4.5)

The integrability conditions are therefore satisfied provided the arbitrary function $f_a^{(n)}(\tau, \vec{x})$ vanishes.

Evaluating the Gauss-Codazzi identity on Σ_c at order ϵ^n , we find

$$\nabla^{b}T_{ab}|_{\Sigma_{c}}^{(n)} = \left[2\nabla^{b}(K\gamma_{ab} - K_{ab})\right]^{(n)} = \left[-2R_{a\mu}N^{\mu}\right]^{(n)} = -\frac{2}{\sqrt{r_{c}}}(\hat{R}_{\tau a}^{(n)} + r_{c}\hat{R}_{ra}^{(n)}) = -\frac{2}{\sqrt{r_{c}}}f_{a}^{(n)}(\tau,\vec{x}).$$
(4.6)

Thus, imposing the conservation of the Brown-York stress tensor on Σ_c at order ϵ^n enforces the vanishing of $f_a^{(n)}(\tau, \vec{x})$, ensuring the validity of the integrability conditions (4.4). From the perspective of the dual fluid, at order ϵ^3 (i.e., the first order beyond the seed solution), this constraint reduces to the exact Navier-Stokes equation. At subsequent even orders in ϵ , this step amounts to adding corrections to the incompressibility condition, while at higher odd orders it amounts to adding corrections to the Navier-Stokes equation.

It is interesting to note that evaluating the Hamiltonian constraint on Σ_c yields an exact and nontrivial constraint on the Brown-York stress tensor of the dual fluid, namely

$$dT_{ab}T^{ab} = T^2. (4.7)$$

Applying this constraint alone to equilibrium fluid configurations, one finds that either the equilibrium energy density vanishes $\rho_{\text{eqm}} = 0$ (as is the case here) or else is given by $\rho_{\text{eqm}} = (-2d/(d-1)) p$, where p is the equilibrium pressure. It would be interesting to see if this latter solution branch could be obtained through a modification of the present scenario. We will discuss further the implications of the constraint (4.7) for the dual hydrodynamics in section 7.

⁷Note that the Ricci tensor $R_{\mu\nu}$ is itself of order ϵ^n (as we have already solved the vacuum Einstein equations at order ϵ^{n-1}), so all the remaining covariant derivatives, metrics and inverse metrics appearing in the Bianchi identity are those of the background Rindler metric.

We may now proceed to use (4.2) to identify a particular solution $\tilde{g}_{\mu\nu}^{(n)}$ that satisfies the Einstein equation (4.3) at order ϵ^n . One such particular solution is

$$\begin{split} \tilde{g}_{r\mu}^{(n)} &= 0, \\ \tilde{g}_{\tau\tau}^{(n)} &= \beta_1^{(n)}(\tau, \vec{x}) + (1 - r/r_c)\beta_2^{(n)}(\tau, \vec{x}) + \int_r^{r_c} \mathrm{d}r' \int_{r'}^{r_c} \mathrm{d}r''(\hat{R}_{ii}^{(n)} - r\hat{R}_{rr}^{(n)} - 2\hat{R}_{r\tau}^{(n)}), \\ \tilde{g}_{\tau i}^{(n)} &= \beta_{3i}^{(n)}(\tau, \vec{x}) + (1 - r/r_c)\beta_{4i}^{(n)}(\tau, \vec{x}) - 2\int_r^{r_c} \mathrm{d}r' \int_{r'}^{r_c} \mathrm{d}r''\hat{R}_{ri}^{(n)}, \\ \tilde{g}_{ij}^{(n)} &= \beta_{5ij}^{(n)}(\tau, \vec{x}) + \ln(r/r_c)\beta_{6ij}^{(n)}(\tau, \vec{x}) - 2\int_r^{r_c} \mathrm{d}r' \frac{1}{r'} \int_{r_*}^{r'} \mathrm{d}r''\hat{R}_{ij}^{(n)}. \end{split}$$
(4.8)

Here, we have chosen limits so that the integrals vanish for $r = r_c$, facilitating the evaluation of boundary conditions to follow shortly. We will leave the lower limit r_* appearing in the inner integral for $\tilde{g}_{ij}^{(n)}$ arbitrary for now. Note however that the rr Einstein equation, in combination with the Bianchi identity (4.5), fixes the trace $\beta_{6ii}^{(n)} = \delta^{ij}\beta_{6ij}^{(n)}$ to be

$$\beta_{6ii}^{(n)}(\tau, \vec{x}) = 2r_* (\hat{R}_{ii}^{(n)} - r_* \hat{R}_{rr}^{(n)}) \big|_{r=r_*}.$$
(4.9)

Allowing now for gauge transformations $\xi^{(n)\mu}(r,\tau,\vec{x})$ at order ϵ^n , as well as field redefinitions $\delta v_i^{(n)}(\tau,\vec{x})$ and $\delta P^{(n)}(\tau,\vec{x})$ also at this order, the above solution generalises to

$$\begin{split} g_{rr}^{(n)} &= 2\partial_r \xi^{(n)\tau}, \\ g_{r\tau}^{(n)} &= -r\partial_r \xi^{(n)\tau} + \partial_r \xi^{(n)r} + \frac{1}{r_c} \delta P^{(n)}, \\ g_{ri}^{(n)} &= \partial_r \xi_i^{(n)} - \frac{1}{r_c} \delta v_i^{(n)}, \\ g_{\tau\tau}^{(n)} &= \tilde{g}_{\tau\tau}^{(n)} - \xi^{(n)r} + (1 - r/r_c) 2\delta P^{(n)}, \\ g_{\tau i}^{(n)} &= \tilde{g}_{\tau i}^{(n)} - 2(1 - r/r_c) \delta v_i^{(n)}, \\ g_{ij}^{(n)} &= \tilde{g}_{ij}^{(n)}. \end{split}$$
(4.10)

Here, to obtain the terms involving $\delta v_i^{(n)}$ and $\delta P^{(n)}$ it is sufficient to look at how v_i and P appear linearly in the seed solution (3.2), since $\delta v_i^{(n)} \sim \delta P^{(n)} \sim \epsilon^n$. Note that the $g_{\mu\nu}^{(n)}$ above is still a solution of Einstein's equations, since the additional terms coming from field redefinitions and gauge transformations do not contribute to $\delta R_{\mu\nu}^{(n)}$, as we see from (4.2).

To fix the gauge, we will impose $g_{r\mu}^{(n)} = 0$, for all n > 2. This choice is convenient since we do not have boundary conditions at Σ_c for these metric components, unlike for the $g_{ab}^{(n)}$. The $g_{r\mu}$ components of the full metric are then simply those of the seed solution, i.e., to all orders in ϵ ,

$$g_{rr} = 0, \qquad g_{r\tau} = 1 + \frac{v^2}{2r_c} + \frac{P}{r_c}, \qquad g_{ri} = -\frac{v_i}{r_c}.$$
 (4.11)

Note this gauge choice is fully consistent with our considerations in appendix A (cf. equation (A.2)). To impose this gauge choice then, we must fix

$$\xi^{(n)r} = (1 - r/r_c)\delta P^{(n)} + \tilde{\xi}^{(n)r}(\tau, \vec{x}), \qquad \xi^{(n)\tau} = \tilde{\xi}^{(n)\tau}(\tau, \vec{x}),$$

$$\xi_i^{(n)} = -(1 - r/r_c)\delta v_i^{(n)} + \tilde{\xi}_i^{(n)}(\tau, \vec{x}), \qquad (4.12)$$

where the $\tilde{\xi}^{(n)\mu}(\tau, \vec{x})$ parameterise the residual gauge freedom. Substituting this back into (4.10), we find

$$g_{r\mu}^{(n)} = 0,$$

$$g_{\tau\tau}^{(n)} = \beta_1^{(n)} - \tilde{\xi}^{(n)r} + (1 - r/r_c)(\beta_2^{(n)} + \delta P^{(n)}) + \int_r^{r_c} dr' \int_{r'}^{r_c} dr''(\hat{R}_{ii}^{(n)} - r\hat{R}_{rr}^{(n)} - 2\hat{R}_{r\tau}^{(n)}),$$

$$g_{\tau i}^{(n)} = \beta_{3i}^{(n)} + (1 - r/r_c)(\beta_{4i}^{(n)} - 2\delta v_i^{(n)}) - 2\int_r^{r_c} dr' \int_{r'}^{r_c} dr''\hat{R}_{ri}^{(n)},$$

$$g_{ij}^{(n)} = \beta_{5ij}^{(n)} + \ln(r/r_c)\beta_{6ij}^{(n)} - 2\int_r^{r_c} dr' \frac{1}{r'} \int_{r_*}^{r'} dr''\hat{R}_{ij}^{(n)}.$$
(4.13)

Imposing the boundary condition $g_{ab}^{(n)} = 0$ on Σ_c (so that the induced metric γ_{ab} remains fixed) then fixes

$$\beta_1^{(n)}(\tau, \vec{x}) = \tilde{\xi}^{(n)r}(\tau, \vec{x}), \qquad \beta_{3i}^{(n)}(\tau, \vec{x}) = 0, \qquad \beta_{5ij}^{(n)}(\tau, \vec{x}) = 0.$$
(4.14)

To fix the trace-free part of $\beta_{6ij}^{(n)}$, we require that the metric must be regular at the future horizon r = 0, or equivalently analytic, at each order ϵ^n . To achieve this, it is useful to choose the lower limit r_* in the inner integral for $g_{ij}^{(n)}$ in (4.13) to be zero. Since $\hat{R}_{ij}^{(n)}$ will turn out to be a polynomial in r, by setting $r_* = 0$ we ensure that the outer integral does not generate any additional logarithmic terms beyond those associated with the $\beta_{6ij}^{(n)}$. (Moreover, the trace part of $\beta_{6ij}^{(n)}$ is set to zero through (4.9)). Regularity on the future horizon at order ϵ^n then requires⁸ that these remaining logarithmic terms vanish:

$$\beta_{6ij}^{(n)}(\tau, \vec{x}) = 0. \tag{4.15}$$

In conclusion then, with these boundary conditions, the new part of the bulk metric at order ϵ^n is therefore

$$\begin{split} g_{r\mu}^{(n)} &= 0, \\ g_{\tau\tau}^{(n)} &= (1 - r/r_c) F_{\tau}^{(n)}(\tau, \vec{x}) + \int_{r}^{r_c} \mathrm{d}r' \int_{r'}^{r_c} \mathrm{d}r''(\hat{R}_{ii}^{(n)} - r\hat{R}_{rr}^{(n)} - 2\hat{R}_{r\tau}^{(n)}), \\ g_{\tau i}^{(n)} &= (1 - r/r_c) F_i^{(n)}(\tau, \vec{x}) - 2 \int_{r}^{r_c} \mathrm{d}r' \int_{r'}^{r_c} \mathrm{d}r'' \hat{R}_{ri}^{(n)}, \\ g_{ij}^{(n)} &= -2 \int_{r}^{r_c} \mathrm{d}r' \frac{1}{r'} \int_{0}^{r'} \mathrm{d}r'' \hat{R}_{ij}^{(n)}, \end{split}$$
(4.16)

where the arbitrary functions are

$$F_{\tau}^{(n)}(\tau, \vec{x}) = \beta_2^{(n)}(\tau, \vec{x}) + \delta P^{(n)}(\tau, \vec{x}), \qquad F_i^{(n)}(\tau, \vec{x}) = \beta_{4i}^{(n)}(\tau, \vec{x}) - 2\delta v_i^{(n)}(\tau, \vec{x}). \tag{4.17}$$

We will discuss gauge choices to fix these arbitrary functions in the following section.

⁸A possible caveat here is that we impose order by order regularity but the logarithmic terms could yield a finite value on the future horizon when resummed to all orders in ϵ . We thank Bob Wald for discussion on this point.

As emphasized above, at each order ϵ^n this integration scheme generates a solution that is regular on the future horizon r = 0. If $\hat{R}_{\mu\nu}^{(n)}$ is a polynomial in r that is regular at r = 0, then $g_{\mu\nu}^{(n)}$ will itself be regular at r = 0. This in turn implies that at the next order $\hat{R}_{\mu\nu}^{(n+1)}$ will be regular as well. Since for the seed solution $\hat{R}_{\mu\nu}^{(3)}$ is regular, this argument ensures regularity of $g_{\mu\nu}^{(n)}$ at r = 0 for each n.

An additional interesting feature of the hydrodynamic expansion is fact that any vector constructed from v_i , P and their derivatives is necessarily of odd order in ϵ , while any scalar or rank-two tensor constructed from these variables must necessarily be of even order in ϵ . This means that at orders ϵ^n , where n is odd, the Ricci tensor components $\hat{R}_{rr}^{(n)}$, $\hat{R}_{\tau\tau}^{(n)}$ and $\hat{R}_{ij}^{(n)}$ and the arbitrary function $F_{\tau}^{(n)}(\tau, \vec{x})$ all vanish identically, and so the only nonzero metric component generated by the integration scheme (4.16) is $g_{\tau i}^{(n)}$. Correspondingly, at orders ϵ^n where n is now even, $\hat{R}_{\tau i}^{(n)}$ and $F_i^{(n)}(\tau, \vec{x})$ are zero, and so and so the only nonzero metric components generated by the integration scheme are $g_{\tau\tau}^{(n)}$ and $g_{ij}^{(n)}$.

5 Gauge choices for the fluid

In this section we discuss the gauge choice for the fluid so as fix the arbitrary functions $F_a^{(n)}(\tau, \vec{x})$ appearing in the integration scheme (4.16). In preparation, let us begin by evaluating the contribution $\delta T_{ab}^{(n)}$ to the Brown-York stress tensor arising from the new term $g_{\mu\nu}^{(n)}$ added to the metric at order ϵ^n .

The variation in the extrinsic curvature of Σ_c at order ϵ^n due to $g^{(n)}_{\mu\nu}$ is

$$\delta K_{ab}^{(n)} = \frac{1}{2} \pounds_N g_{ab}^{(n)} = \frac{1}{2} N^r \partial_r g_{ab}^{(n)} = \frac{1}{2} \sqrt{r_c} \partial_r g_{ab}^{(n)} \big|_{\Sigma_c},$$
(5.1)

where, since $g_{\mu\nu}^{(n)}$ is already of order ϵ^n , only derivatives with respect to r survive, and the normal is that associated with the background Rindler spacetime. Thus, we have

$$\delta K_{\tau\tau}^{(n)} = -\frac{F_{\tau}^{(n)}(\tau, \vec{x})}{2\sqrt{r_c}}, \qquad \delta K_{\tau i}^{(n)} = -\frac{F_i^{(n)}(\tau, \vec{x})}{2\sqrt{r_c}}, \qquad \delta K_{ij}^{(n)} = +\frac{1}{\sqrt{r_c}} \int_0^{r_c} \mathrm{d}r' \hat{R}_{ij}^{(n)}. \tag{5.2}$$

The new term due to $g_{\mu\nu}^{(n)}$ in the Brown-York stress tensor on Σ_c at order ϵ^n is then

$$\delta T_{ab}^{(n)} = 2(\gamma_{ab}\delta K^{(n)} - \delta K_{ab}^{(n)}), \tag{5.3}$$

which evaluates to

$$\delta T_{\tau\tau}^{(n)} = -2\sqrt{r_c} \int_0^{r_c} \mathrm{d}r' \hat{R}_{ij}^{(n)}, \qquad \delta T_{\tau i}^{(n)} = \frac{F_i^{(n)}(\tau, \vec{x})}{\sqrt{r_c}},$$

$$\delta T_{ij}^{(n)} = \frac{F_{\tau}^{(n)}(\tau, \vec{x})}{r_c^{3/2}} \,\delta_{ij} + \frac{2}{\sqrt{r_c}} \int_0^{r_c} \mathrm{d}r' (\delta_{ij} \hat{R}_{kk}^{(n)} - \hat{R}_{ij}^{(n)}). \tag{5.4}$$

The complete Brown-York stress tensor on Σ_c at order ϵ^n is then

$$T_{ab}^{(n)} = \delta T_{ab}^{(n)} + \hat{T}_{ab}^{(n)}, \tag{5.5}$$

where $\hat{T}_{ab}^{(n)}$ represents the contribution at order ϵ^n due to the metric up to order ϵ^{n-1} .

5.1 Fixing $F_i^{(n)}(\tau, \vec{x})$

From (4.17), we see that the arbitrary vector function $F_i^{(n)}(\tau, \vec{x})$ appearing at odd orders in ϵ is related to redefinitions of the fluid velocity. To fix this ambiguity, we define the fluid velocity as the boost from the lab frame to the local rest frame of the fluid, in which the momentum density vanishes (i.e., $T_{\tau i} = 0$ in the local rest frame where the fluid velocity is purely timelike). In an arbitrary frame where the fluid velocity $u^a = \gamma(1, v_i)$, this Landau gauge condition [16] then reads

$$0 = h_a^b T_{bc} u^c, \qquad h_b^a = \delta_b^a + u^a u_b.$$
(5.6)

At odd orders in ϵ , the τ component of this equation vanishes identically, since there are no scalars at odd order. The remaining vector component reads

$$0 = T_{i\tau}^{(n)} + T_{ij}^{(n-1)} v_j + \rho^{(n-1)} v_i,$$
(5.7)

where $\rho = T_{ab}u^a u^b$ is the energy density in the local rest frame.⁹ Hence at order ϵ^n (for odd *n*), we find $F_i^{(n)}(\tau, \vec{x})$ is fixed in terms of known quantities according to

$$0 = \frac{F_i^{(n)}(\tau, \vec{x})}{\sqrt{r_c}} + \hat{T}_{i\tau}^{(n)} + T_{ij}^{(n-1)}v_j + \rho^{(n-1)}v_i,$$
(5.8)

where $T_{ij}^{(n-1)}$ and $\rho^{(n-1)}$ denote respectively the full stress tensor and the energy density evaluated at order ϵ^{n-1} , both of which are known quantities.

If we now move to order ϵ^{n+1} (where n+1 is even), we find the vector component of (5.6) vanishes identically (as there are no vectors at even orders), but the τ component is nontrivial and reads

$$0 = T_{\tau\tau}^{(n+1)} + T_{\tau i}^{(n)} v_i - r_c \rho^{(n+1)}.$$
(5.9)

Noting that $\rho = \gamma^2 (T_{\tau\tau} + 2T_{\tau i}v_i + T_{ij}v_iv_j)$ and that $1 - r_c\gamma^2 = -v^2\gamma^2$, one can show that (5.9) is equivalent to

$$0 = v^{2} (T_{\tau\tau}^{(n-1)} + T_{\tau i}^{(n-2)} v_{i}) + r_{c} (T_{\tau i}^{(n)} + T_{ij}^{(n-1)} v_{j}) v_{i}.$$
(5.10)

Then, assuming (5.7) is satisfied at order ϵ^n , (5.9) reduces to

$$0 = v^2 (T_{\tau\tau}^{(n-1)} + T_{\tau i}^{(n-2)} v_i - r_c \rho^{(n-1)}).$$
(5.11)

Thus, (5.9) is satisfied at order ϵ^{n+1} provided that it is satisfied at the preceding even order ϵ^{n-1} . Since the seed solution (3.2) explicitly satisfies (5.9) at order ϵ^2 , we see that the gauge condition (5.6) can indeed be consistently imposed at all orders by choosing $F_i^{(n)}(\tau, \vec{x})$ according to (5.8).

It is quite nontrivial that we can consistently impose the *relativistic* gauge choice (5.6) on the dual fluid, since the latter is constructed according to a non-relativistic expansion scheme in which time and spatial derivatives have different order in ϵ . We will return to this topic in section 7.

⁹While this quantity vanishes for the background solution, it is nonzero at higher order in fluid gradients.

5.2 Fixing $F_{\tau}^{(n)}(\tau, \vec{x})$

From (4.17), we see that $F_{\tau}^{(n)}(\tau, \vec{x})$, the arbitrary scalar function appearing at all even orders in ϵ greater than two, is related to redefinitions of the pressure fluctuation P. To remove this ambiguity, we propose defining the pressure fluctuation P so that the isotropic part of T_{ij} is fixed to be

$$T_{ij}^{\text{isotropic}} = \left(\frac{1}{\sqrt{r_c}} + \frac{P}{r_c^{3/2}}\right)\delta_{ij}$$
(5.12)

to all orders. From (5.4), it is clear that we can always choose $F_{\tau}^{(n)}(\tau, \vec{x})$ at every even order greater than two so as to ensure that T_{ij} receives no higher order corrections that are proportional to δ_{ij} .

While other gauge choices to define the pressure fluctuation P are possible (see footnote 12), the present choice is especially simple from an operational point of view.

6 Results to $O(\epsilon^6)$

In this section we now apply the integration scheme developed in the preceding sections to compute the bulk metric and the ensuing fluid stress tensor at orders up to and including ϵ^5 in four and five bulk spacetime dimensions. We have checked explicitly at the end of the procedure that our solution satisfies the bulk Einstein equations to $O(\epsilon^6)$ for four and five dimensions.

Since neither the seed metric, nor the algorithm to construct the solution at each step, depends on the dimension; and moreover scalars, vectors and rank-two tensors formed from v_i , P have no special properties in three spatial dimensions (unlike in two spatial dimensions¹⁰), we expect that the following results are valid in *any* bulk dimension greater than five as well. We have not, however, explicitly checked that the equations of motion hold to $O(\epsilon^6)$ for bulk dimensions greater than five.

6.1 Corrections to Navier-Stokes and incompressibility

As noted in [6], imposing conservation of the Brown-York stress tensor at order ϵ^2 yields the incompressibility condition, while at order ϵ^3 we recover the Navier-Stokes equation. In section 4, we saw explicitly how conservation of the Brown-York stress tensor at order ϵ^n is required in order to construct the bulk metric at that same order.

Applying the integration scheme described in section 4, at order ϵ^4 we obtain the following corrections to the incompressibility equation:

$$\partial_i v_i = \frac{1}{r_c} v_i \partial_i P - v_i \partial^2 v_i + \frac{1}{2} \sigma_{ij} \sigma_{ij} + O(\epsilon^6), \qquad (6.1)$$

where the fluid shear σ_{ij} and vorticity ω_{ij} are given by

$$\sigma_{ij} = 2\partial_{(i}v_{j)} \equiv \partial_i v_j + \partial_j v_i, \qquad \omega_{ij} = 2\partial_{[i}v_{j]} \equiv \partial_i v_j - \partial_j v_i.$$
(6.2)

¹⁰In two spatial dimensions (i.e., d = 2), v_i has two components and dimension dependent identities for rank 2 tensors exist at order ϵ^4 . Notably, $\sigma_{ik}\sigma_{kj} = 1/2\delta_{ij}\sigma_{kl}\sigma_{kl}$ and $\omega_{ik}\omega_{kj} = 1/2\delta_{ij}\omega_{kl}\omega_{lk}$, where σ_{ij} and ω_{ij} are as defined in (6.2).

As (6.1) is a scalar equation, there are no corrections at odd orders, and so the next corrections appear at order ϵ^6 .

As expected, the Navier-Stokes equations are modified at order ϵ^5 :

$$\partial_{\tau}v_{i}+v_{j}\partial_{j}v_{i}-r_{c}\partial^{2}v_{i}+\partial_{i}P = -\frac{3r_{c}^{2}}{2}\partial^{4}v_{i}+2r_{c}v_{k}\partial^{2}\partial_{k}v_{i}+r_{c}\sigma_{ik}\partial_{l}\sigma_{kl}-\frac{5r_{c}}{2}\omega_{ik}\partial_{l}\sigma_{kl}$$
$$-\frac{3r_{c}}{4}\partial_{i}(\sigma_{kl}\sigma_{kl})-\frac{5r_{c}}{8}\partial_{i}(\omega_{kl}\omega_{lk})+r_{c}\sigma_{kl}\partial_{k}\sigma_{li}-2v_{k}\partial_{k}\partial_{i}P$$
$$-2(\partial_{k}v_{i})\partial_{k}P-P\partial^{2}v_{i}-\frac{1}{2}v^{2}\partial^{2}v_{i}-\frac{1}{2}(\partial_{k}\sigma_{il})v_{k}v_{l}+\frac{1}{2}(\partial_{k}\omega_{il})v_{k}v_{l}$$
$$+2(\partial_{k}v_{i})\omega_{kl}v_{l}+\frac{1}{r_{c}}(P+v^{2})\partial_{i}P-\frac{1}{r_{c}}v_{i}\partial_{\tau}P+O(\epsilon^{7}).$$
(6.3)

Since this is a vector equation, there are no corrections at even orders, hence the next corrections will be at order ϵ^7 .

In writing the form of these correction terms, we eliminated $\partial^2 P$ terms using the relationship

$$\partial^2 P + (\partial_i v_j)(\partial_j v_i) = O(\epsilon^6), \tag{6.4}$$

which follows from taking the divergence of Navier-Stokes equation and using incompressibility.

6.2 Metric at higher orders

The initial seed metric up to ϵ^2 is given in (3.2). Applying our solution algorithm for the bulk geometry, at order ϵ^3 the only nonvanishing components of the metric are

$$g_{\tau i}^{(3)} = \frac{(r - r_c)}{2r_c} \Big[(v^2 + 2P) \frac{2v_i}{r_c} + 4\partial_i P - (r + r_c)\partial^2 v_i \Big].$$
(6.5)

Note that only the last of these terms was found in [6]; the first two terms are required in order to impose the fluid gauge condition (5.7) at order ϵ^3 .

At ϵ^4 , the only nonvanishing components of the metric are

$$g_{\tau\tau}^{(4)} = -\frac{(r-r_c)^3}{8r_c^2}(\omega_{kl}\omega_{lk}) + \frac{(r-r_c)^2}{8r_c}(8v_k\partial^2 v_k + \sigma_{kl}\sigma_{kl}) - \frac{(r-r_c)}{r_c}F_{\tau}^{(4)}, \quad (6.6)$$

where

$$F_{\tau}^{(4)} = \frac{9}{8r_c}v^4 + \frac{5}{2r_c}Pv^2 + \frac{P^2}{r_c} - 2r_cv_i\partial^2 v_i - \frac{r_c}{2}\sigma_{kl}\sigma_{kl} - 2\partial_{\tau}P + 2v_k\partial_kP, \qquad (6.7)$$

is fixed by the gauge condition. Also,

$$g_{ij}^{(4)} = \left(1 - \frac{r}{r_c}\right) \left[\frac{1}{r_c^2} v_i v_j (v^2 + 2P) + \frac{2}{r_c} v_{(i} \partial_{j)} P - 4 \partial_i \partial_j P - \frac{1}{2} \sigma_{ik} \sigma_{kj} + \frac{r - 5r_c}{4r_c} \omega_{ik} \omega_{kj} + \sigma_{k(i} \omega_{j)k} - \frac{r + r_c}{r_c} v_{(i} \partial^2 v_{j)} + \frac{r + 5r_c}{4} \partial^2 \sigma_{ij} - \frac{1}{r_c} v_{(i} \partial_{j)} v^2 - \frac{1}{2r_c} \sigma_{ij} (v^2 + 2P)\right].$$
(6.8)

At next order we find that the only nonvanishing components of the metric are

$$\begin{split} g_{\tau i}^{(5)} &= (1 - \frac{r}{r_c}) \bigg[- \frac{(r + 2r_c)(r + 5r_c)}{12} \partial^4 v_i + \frac{r - 3r_c}{4} v_k \partial^2 \sigma_{ik} - \frac{1}{2} (r + r_c) v_k \partial^2 \omega_{ik} + r_c \sigma_{ik} \partial_l \sigma_{kl} \\ &- \frac{(r + r_c)(r + 4r_c)}{4r_c} \omega_{ik} \partial_l \sigma_{kl} - \frac{5r + r_c}{8} \partial_i (\sigma_{kl} \sigma_{kl}) + \frac{r^2 - 7r_c r - 4r_c^2}{16r_c} \partial_i (\omega_{kl} \omega_{lk}) \\ &+ \frac{r + r_c}{2} \sigma_{kl} \partial_k \sigma_{li} - \frac{r - 3r_c}{r_c} v_k \partial_k \partial_i P - \sigma_{ik} \partial_k P + \frac{r}{r_c} \omega_{ik} \partial_k P + \frac{r - 2r_c}{r_c} \partial^2 v_i P \\ &+ \frac{r}{2r_c} v^2 \partial^2 v_i + \frac{r}{r_c} v_i v_l \partial_k \sigma_{kl} - \frac{r + r_c}{4r_c} \partial_k \sigma_{il} v_k v_l + \frac{r + r_c}{4r_c} \partial_k \omega_{ik} v_k v_l + \frac{1}{2} \sigma_{ik} \sigma_{kl} v_l \\ &+ \frac{r + 2r_c}{2r_c} \sigma_{ik} \omega_{kl} v_l - \frac{1}{2} \omega_{ik} \sigma_{kl} v_l - \frac{3r - 3r_c}{4r_c} \omega_{ik} \omega_{kl} v_l + \frac{r + 3r_c}{8r_c} \sigma_{kl} \sigma_{kl} v_i \\ &- \frac{(r - r_c)^2}{8r_c^2} \omega_{kl} \omega_{lk} v_i - \frac{1}{r_c^2} P^2 v_i - \frac{5}{2r_c^2} P v_i v^2 - \frac{9}{8r_c^2} v_i (v^2)^2 + \frac{1}{r_c} P \partial_i P \\ &+ \frac{r - r_c}{r_c^2} \partial_i v^2 P - \frac{1}{r_c} v_k \partial_k P v_i - \frac{r - 2r_c}{r_c^2} v_k \sigma_{ki} P - \frac{1}{r_c} \partial_\tau P v_i + \frac{1}{r_c} \sigma_{ik} v_k v^2 \\ &+ \frac{r}{2r_c^2} \omega_{ik} v_k v^2 + \frac{1}{2r_c} v_l \sigma_{kl} v_l v_l \bigg] . \end{split}$$

Inspecting these results, we see that the bulk metric takes the form of a polynomial in r, and as such we would expect it to have only a finite radius of convergence centered about $r = r_c$. Note however that this location is arbitrary: by applying the scaling $(r, \tau, x_i, v_i, P) \rightarrow (\lambda^2 r, \tau, \lambda x_i, \lambda v_i, \lambda^2 P)$ we may set r_c to any chosen value. Let us also mention that, while we verified that the d = 4 solution is Petrov II up to order ϵ^{12} , as noted in [6], the metric fails to be of Petrov II type at order ϵ^{14} .

Finally, let us comment on the location of the Rindler horizon for the full solution. This can be worked out perturbatively in the non-relativistic expansion, as in the analogous computation in [22]. Let $r = R(\tau, x_i)$ be this position, where R is constructed from v_i , P and their derivatives. The terms without any derivatives follow from the equilibrium solution, which yields $R_{eqm} = r_c [1 - (1 + P/r_c)^{-2}]$. The remaining gradient terms may then be determined by imposing at each order in ϵ that the hypersurface be null: $0 = g^{\mu\nu}\partial_{\mu}(r-R)\partial_{\nu}(r-R)$. To $O(\epsilon^4)$, there are no gradient terms that can be constructed, hence $R = 2P + O(\epsilon^4)$. To obtain the non-trivial gradient terms appearing at ϵ^4 order, however, would require knowing g^{rr} to ϵ^6 order.

6.3 Stress tensor at higher orders

The stress tensor of the seed metric was given in (3.3). At order ϵ^3 , this stress tensor gets corrected by the following expression

$$T_{ab}^{(3)} dx^a dx^b = 2r_c^{-3/2} \Big[r_c \sigma_{ik} v_k - (v^2 + P) v_i \Big] dx^i d\tau \,.$$
(6.10)

At order ϵ^4 , the only nonvanishing components of the stress tensor that receive a correction are the scalar $T_{\tau\tau}^{(4)}$ and tensor parts $T_{ii}^{(4)}$ as follows,

$$T_{ab}^{(4)} dx^{a} dx^{b} = r_{c}^{-3/2} \Big[v^{2} (v^{2} + P) - \frac{r_{c}^{2}}{2} \sigma_{ij} \sigma_{ij} - r_{c} \sigma_{ij} v_{i} v_{j} \Big] d\tau^{2} + r_{c}^{-5/2} \Big[v_{i} v_{j} (v^{2} + P) + 2r_{c} v_{(i} \partial_{j)} P - 4r_{c}^{2} \partial_{i} \partial_{j} P - \frac{r_{c}^{2}}{2} \sigma_{ik} \sigma_{kj} - r_{c}^{2} \omega_{ik} \omega_{kj} + r_{c}^{2} \sigma_{k(i} \omega_{j)k} - 2r_{c}^{2} v_{(i} \partial^{2} v_{j)} + \frac{3r_{c}^{3}}{2} \partial^{2} \sigma_{ij} - r_{c} v_{(i} \partial_{j)} v^{2} - \frac{r_{c}}{2} \sigma_{ij} v^{2} \Big] dx^{i} dx^{j}.$$

$$(6.11)$$

At order ϵ^5 , we obtain

$$T_{ab}^{(5)} dx^{a} dx^{b} = 2r_{c}^{-5/2} \left[-\frac{3r_{c}^{3}}{2} v_{k} \partial^{2} \sigma_{ik} + 4r_{c}^{2} v_{k} \partial_{k} \partial_{i} P + r_{c}^{2} v^{2} \partial^{2} v_{i} + r_{c}^{2} v_{i} v_{l} \partial_{k} \sigma_{kl} + \frac{r_{c}^{2}}{2} \sigma_{ik} \partial_{k} v^{2} - \frac{r_{c}^{2}}{2} \omega_{ik} \sigma_{kl} v_{l} + r_{c}^{2} \omega_{ik} \omega_{kl} v_{l} + \frac{r_{c}^{2}}{2} \sigma_{kl} \sigma_{kl} v_{i} - v_{i} v^{2} (P + v^{2}) - r_{c} v^{2} \partial_{i} P - r_{c} v_{i} v_{k} \partial_{k} P + r_{c} \sigma_{ik} v_{k} v^{2} + \frac{r_{c}}{2} \omega_{ik} v_{k} v^{2} + \frac{r_{c}}{2} v_{k} \sigma_{kl} v_{l} v_{l} \right] d\tau dx^{i} .$$
(6.12)

To simplify the form of these expressions, we have made use of the constraint equations (6.1) and (6.3) below in such a manner that all τ derivatives of v_i do not appear in the final form of the expressions, as well as equations deriving from these such as (6.4) in such a manner that $\partial^2 P$ does not appear in the final form of the expressions.

7 Characterising the dual fluid

Earlier, we noted how the Brown-York stress tensor of the seed metric could be obtained from the ϵ -expansion of the hydrodynamic stress tensor for a relativistic fluid. Moreover, when constructing the bulk solution, we found one can consistently choose a gauge such that $u^a T_{ab} h_c^c = 0$ to all orders in ϵ . Taken together, these observations suggest that it might in fact be possible to recover our full gravitational results for the Brown-York stress tensor from the ϵ -expansion of some appropriately chosen relativistic hydrodynamic stress tensor.

Examining the results of the previous section more closely, we find that the energy density in the local rest frame is given by

$$\rho = T_{ab}u^a u^b = -\frac{1}{2\sqrt{r_c}}\sigma_{ij}\sigma_{ij} + O(\epsilon^6).$$
(7.1)

In particular, we see that the energy density vanishes for equilibrium configurations in which the fluid velocity is everywhere constant. In the following section, we discuss the theory of relativistic hydrodynamics at second order in fluid gradients, paying special attention to the modifications necessitated by the vanishing equilibrium energy density. We will then proceed to match our proposed relativistic hydrodynamic stress tensor with the Brown-York stress tensor derived from our gravitational calculations above, permitting the identification of second-order transport coefficients.

7.1 Relativistic hydrodynamics for vanishing equilibrium energy density

Defining the relativistic fluid velocity u^a as in (5.6), so that the momentum density in the local rest frame vanishes, the fluid stress tensor takes the general form

$$T_{ab} = \rho u_a u_b + p h_{ab} + \Pi_{ab}^{\perp}, \qquad u^a \Pi_{ab}^{\perp} = 0.$$
 (7.2)

Here, $h_{ab} = \gamma_{ab} + u_a u_b$ is the induced metric on surfaces orthogonal to the fluid velocity, and p represents the pressure of the fluid in the local rest frame. The term Π_{ab}^{\perp} encodes dissipative corrections and may be expanded in gradients of the fluid velocity. Since in the present case the equilibrium energy density vanishes, we must also expand the energy density ρ in terms of gradients of the fluid velocity. Inserting (7.2) into the constraint (4.7) deriving from the bulk Hamiltonian constraint, we find

$$0 = \rho \left((d-1)\rho + 2dp + 2\Pi^{\perp} \right) + d\Pi_{ab}^{\perp} \Pi^{\perp ab} - (\Pi^{\perp})^2,$$
(7.3)

where $\Pi^{\perp} = h^{ab} \Pi_{ab}^{\perp}$. This relation then fully determines the energy density ρ in terms of p and Π_{ab}^{\perp} (remembering that we must select the solution branch corresponding to a zero equilibrium energy density). Equation (7.3) therefore plays a role somewhat analogous to that of the equation of state for a conventional fluid.

To write down the gradient expansions for ρ and Π_{ab}^{\perp} precisely, it is useful to first consider the equations of motion at lowest order in fluid gradients: noting that ρ has no component at zeroth order in gradients, these are

$$0 = u^a \partial^b T_{ab} = -p \partial_a u^a + O(\partial^2), \qquad 0 = h^b_a \partial^c T_{bc} \quad \Rightarrow \quad D u_a = -D^\perp_a \ln p + O(\partial^2), \quad (7.4)$$

where we have omitted terms of second and higher order in fluid gradients, and we have defined $D_a^{\perp} \equiv h_a^b \partial_b$ and $D \equiv u^a \partial_a$. We may use these equations to simplify the form of the possible coefficients that appear at a given order in the gradient expansion: for example, we see that the only possible first order term in the gradient expansion for ρ , namely $\partial_a u^a$, in fact vanishes at this order. The expansion for ρ therefore starts at second order.

As shown in appendix C, making use of the relations (7.4) we may write down the following complete basis for Π_{ab}^{\perp} up to second order in gradients,

$$\Pi_{ab}^{\perp} = -2\eta \mathcal{K}_{ab} + c_1 \mathcal{K}_a^c \mathcal{K}_{cb} + c_2 \mathcal{K}_{(a}^c \Omega_{|c|b)} + c_3 \Omega_a^{\ c} \Omega_{cb} + c_4 h_a^c h_b^d \partial_c \partial_d \ln p + c_5 \mathcal{K}_{ab} D \ln p + c_6 D_a^{\perp} \ln p D_b^{\perp} \ln p + O(\partial^3),$$
(7.5)

where η is the relativistic kinematic viscosity and the c_1 , c_2 , etc., are the corresponding transport coefficients at second order. Here, we are restricting to flat space,¹¹ and we have defined the relativistic shear and vorticity according to

$$\mathcal{K}_{ab} = h_a^c h_b^d \partial_{(c} u_{d)}, \qquad \Omega_{ab} = h_a^c h_b^d \partial_{[c} u_{d]}, \tag{7.6}$$

where symmetrisation and anti-symmetrisation are defined as in (6.2).

¹¹For curved backgrounds additional terms involving the Riemann tensor appear, see e.g., [23].

Note also we have not included any terms in (7.5) proportional to some secondorder scalar times h_{ab} itself: this is because our definition of the pressure fluctuation Pin (5.12) forbids all such terms,¹² as may be seen by going to the rest frame in which h_{ij} reduces to δ_{ij} .

To determine the energy density ρ in the local rest frame, we now simply insert the expansion (7.5) into the constraint (7.3). Expanding to second order in fluid gradients, we find

$$\rho = -\frac{2\eta^2}{p} \mathcal{K}_{ab} \mathcal{K}^{ab} + O(\partial^3). \tag{7.7}$$

7.2 Determination of transport coefficients

To test the proposed relativistic hydrodynamic expansion given by (7.2), and to identify the transport coefficients appearing in (7.5), we now perform a second expansion of (7.5) in ϵ up to $O(\epsilon^6)$. We will then backsubstitute into (7.2), and compare with our results for the Brown-York stress tensor in (6.10), (6.11) and (6.12).

In comparing the two expansions, it is useful to note that the terms associated with the coefficients c_5 and c_6 both vanish to $O(\epsilon^6)$, and so are not constrained by the gravitational analysis above. Nevertheless, if required, these transport coefficients may be straightforwardly evaluated by extending the gravitational analysis to the appropriate order.

In the following analysis, we expect to be able to recover all of the terms in the Brown-York stress tensor containing up to two gradients, commensurate with the second-order accuracy of our corresponding hydrodynamic expansion. Note, however, that the number of gradients in a given relativistic term may increase after expanding in ϵ , since we make free use of the incompressibility and Navier-Stokes equations to simplify our expressions. Crucially though, the order in gradients can never decrease as we go from the relativistic expansion to the ϵ -expansion.

Examining the terms up to ϵ^2 order, as noted earlier we find

$$p = \frac{1}{\sqrt{r_c}} + \frac{P}{r_c^{3/2}},\tag{7.8}$$

i.e., the pressure p of the dual fluid consists of an equilibrium part $r_c^{-1/2}$ (as expected from the result for Rindler space) and a fluctuation $r_c^{-3/2}P$ at order ϵ^2 . The nature of our gauge choice (5.12) is such that this relation is exact and receives no corrections at higher orders. The full hydrodynamical stress tensor (7.2) expanded to ϵ^2 order is then

$$T_{ab}^{\text{hydro}} dx^a dx^b = \frac{d\vec{x}^2}{\sqrt{r_c}} - \frac{2v_i}{\sqrt{r_c}} dx^i d\tau + \frac{v^2}{\sqrt{r_c}} d\tau^2 + r_c^{-3/2} \Big[P\delta_{ij} + v_i v_j - 2\eta r_c \partial_i v_j \Big] dx^i dx^j + O(\epsilon^3),$$
(7.9)

from which we immediately note $\eta = 1$, although we will leave η explicit in the following formulae.

¹²Alternative gauge choices for P are however possible. In particular, one may send $P \to P - r_c^{3/2} \Pi^{\perp}/d$, which would render the dissipative part Π_{ab}^{\perp} transverse traceless. This would correspond to the gauge choice $h^{ab}T_{ab} = d(r_c^{-1/2} + r_c^{-3/2}P)$.

Evaluating now the terms at ϵ^3 order, we find

$$T_{ab}^{(3)\,\text{hydro}} \mathrm{d}x^a \mathrm{d}x^b = 2r_c^{-3/2} \Big[\eta r_c \sigma_{ik} v_k - (v^2 + P) v_i \Big] \mathrm{d}x^i \mathrm{d}\tau, \tag{7.10}$$

which is straightforwardly consistent with (6.10) above.

At ϵ^4 order, we obtain

$$T_{ab}^{(4) \text{ hydro}} dx^{a} dx^{b} = r_{c}^{-3/2} \left[v^{2} (v^{2} + P) - \eta r_{c} \sigma_{ij} v_{i} v_{j} - \frac{r_{c}^{2}}{2} \sigma_{ij} \sigma_{ij} \right] d\tau^{2} + r_{c}^{-5/2} \left[v_{i} v_{j} (v^{2} + P) + 2 \eta r_{c} v_{(i} \partial_{j)} P + c_{4} r_{c}^{3/2} \partial_{i} \partial_{j} P + \frac{c_{1}}{4} r_{c}^{3/2} \sigma_{ik} \sigma_{kj} + \frac{c_{3}}{4} r_{c}^{3/2} \omega_{ik} \omega_{kj} - \frac{c_{2}}{4} r_{c}^{3/2} \sigma_{k(i} \omega_{j)k} - 2 \eta r_{c}^{2} v_{(i} \partial^{2} v_{j)} - \eta r_{c} v_{(i} \partial_{j)} v^{2} - \frac{r_{c}}{2} \eta \sigma_{ij} v^{2} \right] dx^{i} dx^{j} .$$
(7.11)

Comparing with Brown-York stress tensor (6.11), we find exact agreement upon setting

 $c_1 = -2\sqrt{r_c}, \quad c_2 = c_3 = c_4 = -4\sqrt{r_c}.$ (7.12)

In fact, the only term in (6.11) not captured by the hydrodynamic expansion (7.11) is the term proportional to $\partial^2 \sigma_{ij}$: as this term is of third order in fluid gradients, however, we do not expect to be able to reproduce it from our second-order hydrodynamic expansion.

Finally, at order ϵ^5 , we obtain

$$T_{ab}^{(5) \text{ hydro}} dx^{a} dx^{b} = 2r_{c}^{-5/2} \Big[-c_{4}r_{c}^{3/2}v_{k}\partial_{k}\partial_{i}P + \eta r_{c}^{2}v^{2}\partial^{2}v_{i} + \eta r_{c}^{2}v_{i}v_{l}\partial_{k}\sigma_{kl} - \frac{c_{2}}{8}r_{c}^{3/2}\sigma_{ik}\partial_{k}v^{2} \\ + \frac{1}{8}(c_{2} - 2c_{1})r_{c}^{3/2}\sigma_{ij}\sigma_{jk}v_{k} + \frac{c_{2}}{8}r_{c}^{3/2}\omega_{ik}\sigma_{kl}v_{l} - \frac{c_{3}}{4}r_{c}^{3/2}\omega_{ik}\omega_{kl}v_{l} \\ + \frac{r_{c}^{2}}{2}\sigma_{kl}\sigma_{kl}v_{i} - v_{i}v^{2}(P + v^{2}) - \eta r_{c}v^{2}\partial_{i}P \\ - \eta r_{c}v_{i}v_{k}\partial_{k}P + \eta r_{c}\sigma_{ik}v_{k}v^{2} + \frac{r_{c}}{2}\eta\omega_{ik}v_{k}v^{2} + \frac{r_{c}}{2}\eta v_{k}\sigma_{kl}v_{l}v_{l}\Big] d\tau dx^{i}.$$
(7.13)

Checking this result against (6.12), we find that we can indeed reproduce all terms (again, apart from the single third-order term proportional to $v_k \partial^2 \sigma_{ik}$) with the assignments (7.12).

In conclusion then, we have seen how our seemingly complicated results (6.10), (6.11) and (6.12) for the Brown-York stress tensor may be recovered from the ϵ -expansion of the simple relativistic hydrodynamic stress tensor (7.2), where the relevant transport coefficients in (7.5) are given by (7.12).

8 Models for the dual fluid

In this section, we present a simple Lagrangian model for the dual fluid. Since in general one would not expect to be able to reproduce the dissipative part of the stress tensor from such a model (without first coupling to a heat bath), we focus on reproducing the non-dissipative piece of the stress tensor, namely

$$T_{ab} = ph_{ab}.\tag{8.1}$$

This corresponds to a fluid with nonzero pressure but a vanishing energy density in the local rest frame, $\rho = T_{ab}u^a u^b = 0$. Note that this stress tensor also satisfies the 'equation of state' following from the Hamiltonian constraint, $dT_{ab}T^{ab} = T^2$. The equations of motion follow from the conservation of T_{ab} , and are then those in (7.4) but with no higher-derivative corrections, i.e.,

$$\partial^a u_a = 0, \qquad D u_a = -D_a^{\perp} \ln p, \tag{8.2}$$

where $D_a^{\perp} \equiv h_a^b \partial_b$ and $D \equiv u^a \partial_a$.

In the previous section, we showed that the stress tensor of the dual fluid (including dissipative terms) may be obtained from a non-relativistic limit of the stress tensor for a relativistic fluid. The fluid velocity spontaneously breaks relativistic invariance, however, and so we are led to consider a relativistic Lagrangian in which the relativistic symmetry is spontaneously broken by a background value for the field. The following scalar field action satisfies all requirements,

$$S = \int \mathrm{d}^{d+1}x \sqrt{-\gamma} \sqrt{-(\partial\phi)^2}.$$
(8.3)

The field equations are given by

$$\nabla^a u_a = 0, \qquad u_a = \frac{\partial_a \phi}{\sqrt{X}},\tag{8.4}$$

where $X = -(\partial \phi)^2$. Note that u_a satisfies,

$$u^a u_a = -1. \tag{8.5}$$

The stress tensor is given by

$$T_{ab} = \sqrt{X}\gamma_{ab} + \frac{1}{\sqrt{X}}\partial_a\phi\partial_b\phi = \sqrt{X}h_{ab},$$
(8.6)

This is precisely of the form (8.1) with $p = \sqrt{X}$ and consequently T_{ab} indeed satisfies the zero energy density condition, $\rho = T_{ab}u^a u^b = 0$, and the quadratic constraint $dT_{ab}T^{ab} = T^2$. By construction, the stress tensor is conserved and the equations in (8.2) are therefore reproduced.

Note that (8.4) precisely defines the fluid velocity in terms of a potential (i.e., the fluid motion corresponds to potential flow). We also note that taking a generic Lagrangian density $\mathcal{L}(X, \phi)$ and then imposing

$$0 = T_{ab}u^{a}u^{b} = \left(-2\frac{\delta\mathcal{L}}{\delta\gamma^{ab}} + \gamma_{ab}\mathcal{L}\right)\frac{\partial^{a}\phi\partial^{b}\phi}{X} = 2X\frac{\delta\mathcal{L}}{\delta X} - \mathcal{L}$$
(8.7)

uniquely picks out the square root action (8.3), up an integration constant which can be absorbed into a field redefinition.

The equilibrium configuration with pressure $p = r_c^{-1/2}$ in the rest frame¹³ corresponds to the solution,

$$\phi = \tau. \tag{8.8}$$

¹³The background solution corresponding to the equilibrium configuration in an arbitrary frame is obtained by Lorentz transforming the rhs of (8.8). Note that in such a case $T_{\tau\tau} \neq 0$ even though the energy density is zero.

(Recall that the background metric is given by $\gamma_{ab} dx^a dx^b = -r_c d\tau^2 + dx_i dx^i$.) This solution spontaneously breaks Lorentz invariance, as required.

To model a fluid in its rest frame with small pressure fluctuations about a constant equilibrium value of $r_c^{-1/2}$, we must set

$$\phi = \tau + \delta \phi(\tau, \vec{x}), \tag{8.9}$$

The pressure is then given by

$$p = \sqrt{X} = \frac{1}{\sqrt{r_c}} (1 + 2\delta\dot{\phi} + \delta\dot{\phi}^2 - r_c\delta\phi_{,i}\delta\phi_{,i})^{1/2} = \frac{1}{\sqrt{r_c}} + \frac{P}{r_c^{3/2}},$$
(8.10)

where the last equation serves to define the pressure fluctuation P in terms of the field fluctuation $\delta\phi$, in accordance with (7.8). Similarly, from the components of the relativistic fluid velocity $u_{\tau} = -r_c\gamma = (1 + \delta\dot{\phi})/\sqrt{X}$ and $u_i = \gamma v_i = \delta\phi_{,i}/\sqrt{X}$, we may solve for the fluid boost velocity v_i in terms of $\delta\phi$, yielding

$$v_i = -\frac{r_c \delta \phi_{,i}}{(1+\delta \dot{\phi})}.$$
(8.11)

In summary then, we have shown that the non-dissipative part of the fluid stress tensor (8.1), describing a fluid with vanishing energy density in the local rest frame, leads naturally to the square-root action (8.3). This action is nonlocal in the sense that the expansion around the background solution involves an infinite number of derivatives.

The square root action has various interesting features. The action is real for any timelike $(\partial \phi)$ and the Hamiltonian is positive semi-definite since

$$\mathcal{H} = X^{-1}(\partial_i \phi)(\partial^i \phi), \tag{8.12}$$

so there is no obvious unitarity problem, despite the unconventional nature of the action. One can generate a wide variety of field theories by adding extra matter to this scalar field model, provided that one expands about zero background values of these fields. For example, consider a generic action

$$S = \int d^{d+1}x \sqrt{-\gamma} [f[\psi, A_a, \Phi] \sqrt{-(\partial \phi)^2 + g[\psi, A_a, \Phi]} + h[\psi, A_a, \Phi]],$$
(8.13)

with ψ denoting fermions, A_a denoting gauge fields and Φ denoting scalars. Here the functions $f[\psi, A_a, \Phi]$, $g[\psi, A_a, \Phi]$ and $h[\psi, A_a, \Phi]$ are only constrained by the requirement that g vanishes with f finite and h either finite or zero when $\psi = A_a = \Phi = 0$. Choosing a background in which $\phi = \tau$ with all other fields vanishing will always give a zero energy density fluid, as above, for any matter content and choice of functions. Reinstating the $1/16\pi G$ in the bulk will introduce a corresponding prefactor in the action above; as usual, a holographic correspondence involving classical gravity would be expected to correspond to a dual field theory with a large number of degrees of freedom.

The appearance of the square root in (8.3) might at first sight suggest a connection with a brane action. Suppose for example that one considers a (d + 1)-dimensional brane embedded into a (d+2)-dimensional Minkowski target space. The brane embedding would be described by an action

$$S = -T \int d^{d+1}\xi \sqrt{-\sigma},\tag{8.14}$$

where T is the brane tension, ξ are the worldvolume coordinates and $\sigma_{ab} = \partial_a Y^{\mu} \partial_b Y^{\nu} \eta_{\mu\nu}$ is the pulled back metric, with Y^{μ} the target space coordinates. Fixing static gauge for the coordinates (τ, \vec{x}) leads to

$$S = -T \int d^{d+1}x \sqrt{1 + (\partial Y)^2},$$
(8.15)

where $Y \equiv Y^{d+2}$ is the transverse coordinate to the brane. One can take a tensionless limit of this action in which $T \to 0$ with $\varphi = \sqrt{T}Y$ held fixed to eliminate the constant term in the square root

$$S = -\int d^{d+1}x \sqrt{(\partial\varphi)^2},\tag{8.16}$$

but this differs from (8.3) by the absence of the minus term inside the square root. It follows that the tensionless limit gives rise to a real action only when $(\partial \varphi)^2 > 0$ while the background solution of interest in (8.3) has $(\partial \phi)^2$ timelike, in which case the onshell brane action would be imaginary. One possibility would be to embed the brane into a flat target space of signature (d, 2) so that $Y \to iY$ and $\varphi \to i\varphi \equiv \phi$, reproducing (8.3) in the tensionless limit.

9 Discussion

In this paper we established a direct relation between (d + 2)-dimensional Ricci-flat metrics and (d + 1)-dimensional fluids satisfying the incompressible Navier-Stokes equations, corrected by specific higher-derivative terms. Our results raise many interesting questions and there are diverse directions one may wish to further pursue.

Perhaps the most interesting question is whether the correspondence extends beyond the hydrodynamic regime (on the field theory side) and/or the classical gravitational description (on the bulk side). Is there a string embedding of this correspondence? Even without a string embedding, one may ask how this correspondence changes if one adds, for example, a bulk stress tensor or considers higher-derivative corrections to Einstein gravity. Will such changes modify the properties of the dual fluid?

The dual fluid has many unconventional features. In particular, it has zero energy density in equilibrium but nonzero pressure. What theories have such properties? One of our most tantalising observations is that there exists a simple scalar field model that has these properties and at the same time has no obvious problems with unitarity, etc. This provides then a candidate model for the dual to flat spacetime. Can one obtain this model from branes? Are there any other theories which at and near equilibrium are described by such a fluid?

This paper has focused on the gravity/fluid correspondence, computing transport coefficients of the dual fluid holographically, but it is very exciting to ask how far flat space holography can be developed. Defining the holographic theory on Σ_c , is there a holographic dictionary relating bulk computations to quantities computable in the dual field theory model?

Here, the construction of the bulk metric was achieved using a non-relativistic hydrodynamic expansion. We have seen, however, that there is an underlying relativistic description. Can one find a manifestly relativistic construction of the bulk metric?

The metric perturbations are by construction regular at the horizon and throughout the region $r_h < r < r_c$, but, in general, one would expect that the series expansion only converges in a finite neighbourhood of the surface Σ_c . What is the dependence of the radius of convergence on the defining data on Σ_c , and what is the range of validity of the gauge choice for the radial foliation off the surface Σ_c ? Can one resum the series to obtain a closed-form expression for the metric?

It is important to note here that the hydrodynamic expansion can be made around a surface of *arbitrary* radius r_c , which in particular can be far from the horizon. (As $r_c \to \infty$, the pressure and temperature of the equilibrium fluid tends to zero; the stress tensor of the fluid is then zero in this limit). The expansion is therefore in general physically distinct from a near-horizon expansion, although it would certainly be useful to understand in more detail the limit in which r_c is taken to be close to the horizon, following [7].

In this paper, we have used flat space in Rindler coordinates as a seed solution about which the hydrodynamic expansion is made. As the present construction uses neither the existence of an event horizon, nor the detailed asymptotic structure of flat space, there is no reason why it should be applicable only to asymptotically flat or black hole spacetimes. In fact, by the equivalence principle, the construction should hold locally in any small neighbourhood. Can one patch such a 'local' holographic description of neighbourhoods to obtain a global holographic description of general spacetimes?

Another generalisation would be to start from a different seed solution. This should admit at least one Killing vector for the solution to support equilibrium configurations, but the dual fluid need not live on a flat spacetime; it could live instead, for example, on a background such as $R_{\tau} \times S^d$. Note that this would be the geometry of constant-radius slices of Schwarzschild spacetime.

This work also raises many interesting questions from a general relativity viewpoint. We have shown explicitly that the data defined on Σ_c , together with regularity at the horizon, suffices to define the solution uniquely as a series expansion in the region between Σ_c and the horizon. Do these solutions exist globally?¹⁴ A priori it would seem far from obvious that this radial initial value problem is well-posed and admits a unique solution: it would be instructive to understand better these issues.

All in all, this correspondence provides an interesting arena to explore holography for general spacetimes and raises many interesting questions that we hope to return to in the future.

¹⁴Note that the same question applies also to the standard AdS/fluid correspondence. In exact parallel, it was shown in [15] that the derivative expansion defines the solution uniquely as a series expansion in the region between the conformal boundary and the future horizon. It is a non-trivial question whether this provides a global solution. We thank Bob Wald for discussions regarding this point.

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A Choice of radial gauge

The boundary conditions imposed on the surface Σ_c defined by $r = r_c$ do not constrain the radial coordinate away from the surface Σ_c . In the main text, we adopt coordinates such that lines of constant x^a form a null geodesic congruence around Σ_c . Moreover, along each null geodesic, we will choose the transverse coordinate r to be an affine parameter.

These geometrical conditions can be translated into conditions on the metric components as follows. Firstly, the tangent to lines of constant x^a is $n = f(x^a, r)\partial_r$. Here, n is a null vector if and only if $g_{rr} = 0$. One then has

$$n^{\nu}\nabla_{\nu}n^{\mu} = n^{\mu}\partial_{r}f + f^{2}g^{\mu a}\partial_{r}g_{ra}.$$
(A.1)

Hence, vectors n are tangent to geodesics with affine parameter r if and only if $\partial_r g_{ra} = 0$ and $f(x^a, r) = f(x^a)$. In summary, we impose the conditions

$$g_{rr} = 0, \qquad \partial_r g_{ra} = 0. \tag{A.2}$$

These conditions are similar to those used in the conformal fluid/anti-de Sitter gravity correspondence (see e.g., [15, 24]). Note that there is in general no guarantee that these coordinates may be extended far away from Σ_c . Rather, these coordinates might break down at some finite radius outside Σ_c if the null congruence has caustics.

B Infinitesimal diffeomorphisms preserving equilibrium

Let us consider a general infinitesimal diffeomorphism around Rindler spacetime. From the boundary condition $g_{ab} = \gamma_{ab}$ at $r = r_c$, we find that on the surface $r = r_c$ the following conditions hold

$$\partial_{(i}\xi_{j)} = 0, \tag{B.1}$$

$$\partial_i \xi^r - r_c \partial_i \xi^\tau + \partial_\tau \xi^i = 0, \tag{B.2}$$

$$-\xi^r + 2\partial_\tau (\xi^r - r_c \xi^\tau) = 0. \tag{B.3}$$

The first of these equations amounts to Killing's equation on *d*-dimensional Euclidean space and is solved by

$$\xi_i = a_i(r,\tau) + b_{[ij]}(r,\tau)x^j.$$
(B.4)

In particular, we obtain $\partial_i \xi_i = 0$ and $\partial_j \partial_j \xi_i = 0$. Acting on (B.3) with ∂_i and using (B.2), we obtain

$$\partial_i \xi^r = -2\partial_\tau^2 \xi^i. \tag{B.5}$$

These equations are integrable for ξ^r only if $\partial_{\tau}^2 b_{[ij]} = 0$. We then find

$$b_{[ij]}(r,\tau) = \tau d_{[ij]}(r) + e_{[ij]}(r)$$
(B.6)

$$\xi^r = -2\partial_\tau^2 a_i(r,\tau)x^i + c(r,\tau).$$
(B.7)

The equation (B.2) is integrable only if $d_{[ij]} = 0$. The equations (B.2)–(B.3) are then solved by

$$\xi^{\tau} = \left(-\frac{2}{r_c}\partial_{\tau}^2 a_i + \frac{1}{r_c}\partial_{\tau} a_i\right)x^i + \frac{c(r,\tau)}{r_c} - \frac{1}{2r_c}\int d\tau c(r,\tau).$$
 (B.8)

Finally, the diffeomorphisms preserving the induced metric on Σ_c are given by

$$\begin{aligned} \xi^{r} &= -2\partial_{\tau}^{2}a_{i}(r,\tau)x^{i} + c(r,\tau), \\ \xi^{\tau} &= \left(-\frac{2}{r_{c}}\partial_{\tau}^{2}a_{i}(r,\tau) + \frac{1}{r_{c}}\partial_{\tau}a_{i}(r,\tau)\right)x^{i} + \frac{c(r,\tau)}{r_{c}} - \frac{1}{2r_{c}}\int d\tau c(r,\tau) + t(r), \\ \xi_{i} &= a_{i}(r,\tau) + e_{[ij]}(r)x^{j}. \end{aligned}$$
(B.9)

One then computes the Brown-York stress tensor on Σ_c for the metric $g_{\mu\nu} = \bar{g}_{\mu\nu} + \mathcal{L}_{\xi}\bar{g}_{\mu\nu}$. The resulting stress tensor has the form of a relativistic perfect fluid $T_{ab} = \rho u_a u_b + p(\gamma_{ab} + u_a u_b)$, where

$$\rho = 0
p = \frac{1}{\sqrt{r_c}} + \frac{1}{2r_c^{3/2}} (-c + 4\partial_\tau^2 c - 2x^i \partial_\tau v_i)|_{r=r_c}
v_i = -\partial_\tau a_i + 4\partial_\tau^3 a_i|_{r=r_c}.$$
(B.10)

We have therefore shown that a nonzero energy density cannot be generated from an infinitesimal diffeomorphism acting on Rindler spacetime. Note that we did not need to use the gauge condition (A.2) for this argument.

Let us now require that the fluid is in equilibrium with a uniform velocity profile v_i and pressure p on Σ_c . For convenience, let us define r_h via $p = r_c^{-1/2}(1 + r_h/2r_c)$. The set of allowed diffeomorphisms then reduces to

$$a_i(r,\tau) = A_i(r) - v_i(r)\tau + e^{\tau/2}B_i(r) + e^{-\tau/2}C_i(r),$$

$$c(r,\tau) = -R(r) + e^{\tau/2}D(r) + e^{-\tau/2}E(r),$$
(B.11)

where $v_i(r_c) = v_i$ and $R(r_c) = r_h$. We now fix the gauge freedom associated with redefining the surfaces of constant r by imposing the conditions (A.2). Stationarity and homogeneity then further restrict $\partial_b g_{ra}(r, x^c) = 0$. The vectors obeying these conditions reduce simply to a linear combination of a finite set of transformations,

$$\begin{aligned} \xi^{r} &= -r_{h} + e^{\tau/2} \xi^{v}_{(0)} - \frac{1}{2} e^{\tau/2} B^{i} x_{i} \,, \\ \xi^{\tau} &= \xi^{\tau}_{(0)} + \frac{r_{h}}{2r_{c}} \tau - \frac{v_{i} x^{i}}{r_{c}} \,, \\ \xi^{i} &= \xi^{i}_{(0)} + \omega_{[ij]} x^{j} - v_{i} \tau + f^{i} r + e^{\tau/2} B^{i} \,. \end{aligned}$$
(B.12)

Recall that Rindler spacetime can be rewritten in null coordinates $u = e^{\tau/2}$, $v = 4re^{-\tau/2}$. One then recognises τ -translations or alternatively boosts in the (u, v) plane (associated with $\xi_{(0)}^{\tau}$), spatial translations (associated with $\xi_{(0)}^{i}$), rotations (associated with $\omega_{[ij]}$), v-translations (associated with $\xi_{(0)}^{v}$) and boosts (associated with B^{i}), all of which are Killing symmetries and do not lead to any perturbation $\mathcal{L}_{\xi}\bar{g}_{\mu\nu}$. The *r*-dependent translation (associated with f^{i}) amounts solely to shifting g_{ri} by f^{i} . If we restrict the gauge choice further so that $g_{ri} = -v_i/r_c$ (as in (4.11)), this then fixes $f^{i} = 0$.

Finally, the nontrivial perturbations are (i) a shift of r combined with a linearised dilatation of time (associated with r_h); (ii) a linearised boost in the *i* direction (associated with v_i). These two transformations are the linearisation of the two finite transformations (2.5)–(2.6) considered in the main text. The pressure $p = r_c^{-1/2}(1 + r_h/2r_c)$ is the linearisation of the pressure (2.8) in the main text.

C A basis for second-order relativistic hydrodynamics

In this appendix we show how to construct a general basis for the scalars and transverse tensors that appear at second order in the gradient expansion of relativistic hydrodynamics, for the special case in which the equilibrium energy density vanishes. We restrict to the case in which the dual fluid is in a flat background.

We begin by writing down all possible symmetric transverse tensors constructed from two gradients of the fluid pressure p and velocity u^a . These take the form $X_{ab}^{\perp} = h_{(a}^c h_{b)}^d X_{cd}$ where the transverse projector $h_b^a = \delta_b^a + u^a u_b$, and the possible independent choices for X_{cd} are

$$\partial_c \ln p \,\partial_d \ln p, \qquad \partial_c \partial_d \ln p, \qquad u^e \partial_e \ln p \,\partial_c u_d, \qquad u^e \partial_e u_c \partial_d \ln p, u^e \partial_e \partial_c u_d, \qquad \partial_e u^e \partial_c u_d, \qquad \partial_e u_c \partial^e u_d, \qquad \partial_e u_c \partial_d u^e, \qquad \partial_c u_e \partial_d u^e$$
(C.1)

(Note that the term $u^e \partial_c \partial_d u_e = -\partial_c u^e \partial_d u_e$ and so is not independent). We have not considered terms consisting of the induced metric h_{ab} multiplied by a scalar function of second order in gradients since our choice of gauge (5.12) effectively absorbs all such corrections into the zeroth order ph_{ab} term in (7.2).

We may now reduce this list to just six independent choices by applying the fluid equations of motion evaluated to leading order in gradients, given in equation (7.4). In particular, these tell us that the fluid divergence $\mathcal{K} = \partial_a u^a$ vanishes at first order in the gradient expansion, meaning the term $\partial_e u^e \partial_c u_d$ in the list above vanishes at second order and may be dropped. Using the identity

$$\partial_a u_b = \mathcal{K}_{ab} + \Omega_{ab} - u_a D u_b, \tag{C.2}$$

where the transverse tensors \mathcal{K}_{ab} and Ω_{ab} are defined in (7.6) and the fluid derivatives $D \equiv u^a \partial_a$ and $D_a^{\perp} \equiv h_a^b \partial_b$, the six remaining independent choices for X_{ab}^{\perp} may be written as

$$\mathcal{K}_{a}^{c}\mathcal{K}_{cb}, \qquad \mathcal{K}_{(a}^{c}\Omega_{|c|b)}, \qquad \Omega_{a}^{\ c}\Omega_{cb}, \qquad h_{a}^{c}h_{b}^{d}\partial_{c}\partial_{d}\ln p, \qquad D_{a}^{\perp}\ln p D_{b}^{\perp}\ln p, \qquad \mathcal{K}_{ab} D\ln p.$$
(C.3)

For example, the term $h_{(a}^{c}h_{b)}^{d}u^{e}\partial_{e}\partial_{c}u_{d}$ reduces to a linear combination of the last three terms in the list above, by reversing the order of the derivatives, then pushing the u^{e} inside the ∂_{c} and applying (7.4).

Although in the present case the energy density ρ in the local rest frame is fixed by the constraint (7.3), as a matter of general interest one might wish to construct a complete basis for second-order scalar quantities, in a fashion analogous to that done above for symmetric transverse tensors.

One way to construct such a basis is to contract the tensors appearing in (C.1), and then apply the leading order equations of motion (7.4) along with the identity (C.2). After eliminating all dependencies, we find the following complete set of independent terms:

$$\mathcal{K}_{ab}\mathcal{K}^{ab}, \qquad \Omega_{ab}\Omega^{ab}, \qquad D_a^{\perp}\ln p \, D^{\perp a}\ln p, \qquad D\ln p \, D\ln p, \qquad D^2\ln p.$$
(C.4)

Note that taking the divergence of the leading order equations of motion (7.4) yields the result

$$h^{ab}\partial_a\partial_b\ln p = D^{\perp a}\ln p D_a^{\perp}\ln p - K_{ab}K^{ab} + \Omega_{ab}\Omega^{ab} + O(\partial^3),$$
(C.5)

which, upon expanding in ϵ , reduces to our earlier result (6.4).

Using this list of terms, for a general hydrodynamic theory with vanishing equilibrium energy density, one could then write

$$\rho = b_1 \mathcal{K}_{ab} \mathcal{K}^{ab} + b_2 \Omega_{ab} \Omega^{ab} + b_3 D \ln p D \ln p + b_4 D^2 \ln p + b_5 D_a^{\perp} \ln p D^{\perp a} \ln p + O(\partial^3),$$
(C.6)

where b_1 , b_2 , etc., define additional second-order transport coefficients.

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