

The impact of mergers on relaxed X-ray clusters – I. Dynamical evolution and emergent transient structures

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ABSTRACT

We report on the analysis of a suite of smoothed particle hydrodynamics simulations (incorporating cooling and star formation) of mergers involving idealized X-ray clusters whose initial conditions resemble relaxed clusters with cool compact cores observed by *Chandra* and *XMM*. The simulations sample the most-interesting, theoretically plausible, range of impact parameters and progenitor mass ratios. We find that all mergers evolve via a common progression. We illustrate this progression in the projected gas density, X-ray surface brightness, Sunyaev–Zel’dovich, temperature, and gas-entropy maps. Several different classes of transient ‘cold front’ like features can arise over the course of a merger. Each class is distinguished by a distinct morphological signature and physical cause. We find that all these classes are present in *Chandra* and *XMM* observations of merging systems and propose a naming scheme for these features: ‘comet-like’ tails, bridges, plumes, streams and edges. In none of the cases considered do the initial cool compact cores of the primary and the secondary get destroyed during the course of the mergers. Instead, the two remnant cores eventually combine to form a new core that, depending on the final mass of the remnant, can have a greater cooling efficiency than either of its progenitors. We quantify the evolving morphology of our mergers using centroid variance, power ratios and offset between the X-ray and the projected mass maps. We find that the centroid variance best captures the dynamical state of the cluster. It also provides an excellent indicator of how far the system is from virial and hydrostatic equilibrium. Placing the system at $z = 0.1$, we find that all easily identified observable traces of the secondary disappear from a simulated 50-ks *Chandra* image following the second pericentric passage. The system, however, takes an additional ~ 2 Gyr to relax and virialize. Observationally, the only reliable indicator of a system in this state is the smoothness of its X-ray surface brightness isophotes, not temperature fluctuations. Temperature fluctuations at the level of $\Delta T/T \sim 20$ per cent, can persist in the final systems well past the point of virialization, suggesting that the existence of temperature fluctuations, in and of themselves, does not necessarily indicate a disturbed or unrelaxed system.

Key words: galaxies: clusters: general – intergalactic medium – cosmology: theory – X-rays: general.

1 INTRODUCTION

The utility of galaxy clusters as tools for studying cosmology and the history of structure formation is well established. Furthermore, siz-

able samples of clusters extending to high redshift will soon be available from wide-field X-ray and Sunyaev–Zel’dovich (SZ) surveys, greatly expanding their importance and ensuring that they will feature prominently in these pursuits throughout the foreseeable future.

Often implicit in such studies is the assumption that clusters are in equilibrium. However, galaxy clusters are dynamically young systems and are thus prone to regular disruptions by mergers (Cohn

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& White 2005). Recent *Chandra* and *XMM* observations support this. High-resolution spectroscopic imaging has provided dramatic evidence of ongoing mergers in several systems. As a result, we now know that the intracluster medium (ICM) of merging clusters can express a variety of complicated transient features including cold fronts (Markevitch et al. 2000), shock fronts (Markevitch & Vikhlinin 2001) and the ‘sloshing’ of cool cores in their dark matter potentials (Markevitch, Vikhlinin & Mazzotta 2001; Dupke & White 2003).

Such observations have stimulated several theoretical and computational studies devoted to understanding the impact of mergers on clusters. Bialek, Evrard & Mohr (2002), for instance, have shown that cold fronts can be produced through the disruption of cold cores during mergers while Motl et al. (2004) have shown that a significant fraction of a merging cold core can avoid shock heating, contributing to the assembly of the remnant’s cold core. Furthermore, Rowley, Thomas & Kay (2004) have shown that smooth accretion and mergers lead to different evolutions in a system’s X-ray luminosity and temperature. Combined with the results of O’Hara et al. (2006) who suggested that all clusters may exhibit departures from equilibrium due to the lingering effects of their past merger activity, it becomes clear that we must understand the impact of merging to account for the observed properties of clusters, even the seemingly relaxed ones.

Determining the detailed effects of a single merger on a cluster evolving in a cosmological environment can be greatly complicated by the presence of extant substructure, subsequent mergers and smooth accretion. Simulations of idealized two-body cluster mergers provide an alternative approach and, given the fact that most clusters obtain much of their mass through significant mergers (Cohn & White 2005), are not a significant departure from cosmological simulations. They allow control of the initial structure and orbits of the interacting systems and facilitate the investigation of not only the obvious short-term effects of the event, but also the more subtle long-term effects. They also simplify the interpretation of specific merger observations which typically involve only two dominant components.

Several authors have explored cluster mergers in this way (see Roettiger, Burns & Loken 1993; Schindler & Mueller 1993; Pearce, Thomas & Couchman 1994; Roettiger, Loken & Burns 1997, for pioneering studies). Among recent studies, Gomez et al. (2002) have constructed a suite of idealized merging systems of 4:1 and 16:1 mass ratios to study the effects of mergers on the stability of central cool cores. The initial conditions for their clusters were chosen to have gas core radii of $r_c \sim 250$ kpc and the dark matter in their simulations was distributed according to a King model. Ricker & Sarazin (2001, hereafter RS01) have studied mergers between idealized systems with cuspy dark matter profiles. Since the focus of their study was on the luminosity and temperature ‘boosts’ which a merger system experiences on impact of the cluster cores, they did not include the effects of cooling in their simulations. Lastly, Ritchie & Thomas (2002) have analysed a set of simulations incorporating cooling and star formation for idealized merging systems constructed with cuspy dark matter profiles. Their initial conditions primarily examine systems with long cooling times and core radii of $r_c \sim 100$ kpc, although three cases represent systems with short cooling times and small core radii ($r_c \sim 50$ kpc).

However, it is now known that clusters have cuspy dark matter profiles and that 70–90 per cent of observed systems possess compact cores ($r_c \sim 50$ kpc, Peres et al. 1998; Edge, Stewart & Fabian 1992) with cooling times short enough to be of significant importance to their structure. Hence, a comprehensive study of cluster mergers utilizing initial conditions faithful to our contemporary

understanding of a typical cluster’s structure while including the important effects of cooling has not been performed. Given the wide-ranging applications of cluster studies, the importance of mergers to understand the structure of the ICM, and the wealth of detailed cluster merger observations requiring interpretation, a thorough revisit of the issues introduced by cluster mergers would be of great utility.

In this paper and the series to follow, we will present an analysis of a suite of smoothed particle hydrodynamics (SPH) simulations of isolated two-body mergers between idealized clusters constructed to possess realistic compact cool cores. With this study, we seek to provide a conceptual foundation for subsequent studies to be conducted in a full cosmological context. Our approach utilizes insights provided by recent high-resolution observations of clusters to motivate the initial conditions for a set of nine hydrodynamic simulations (incorporating the effects of cooling and star formation) involving a representative range of mass ratios and impact parameters. In this paper, we explain our approach to construct idealized merger simulations and present their general dynamical progression, eventual relaxation and transient phenomena which manifest during the event. Since many of the phenomena we study have low surface brightnesses, we utilize synthetic observations to delineate realistically observable phenomena from those which are not. In subsequent papers, we will examine in detail several specific issues which we can only touch on in this work.

In Section 2, we describe our methods for initializing merging systems and placing them on realistic orbits as well as the details of our numerical methods. In Section 3 we qualitatively describe the evolution of our cluster mergers through a generic sequence of states and introduce the transient structures formed in the process. In Section 4, we examine the evolution of several measures of our mergers’ apparent degree of disruption to determine when our systems would appear undisturbed under reasonable observational circumstances. In Section 5, we assess the degree to which our apparently relaxed merger remnants are formally so. In Section 6, we examine in further detail the different transient structures which form during a merger, describing their properties and the processes which drive their creation. Finally, we summarize our study in Section 7.

In all cases, our assumed cosmology will be $(\Omega_M, \Omega_\Lambda) = (0.3, 0.7)$ with $H_0 = 75 \text{ km s}^{-1} \text{ Mpc}^{-1}$ and $\Omega_b = 0.02 h^{-2}$.

2 SIMULATIONS

We run our simulations with GASOLINE (Wadsley, Stadel & Quinn 2004), a versatile parallel SPH tree code with multi-stepping. We include the effects of radiative cooling, star formation and minimal feedback from supernovae in our simulations but the effects of feedback from active galactic nuclei (AGN) are omitted. It is important to note that we do not include the effects of magnetic fields, pressure generated from cosmic rays or conduction, and that our choice of algorithm is not well suited to modelling the effects of turbulence. The relevance of each of these processes is not well established (theoretically or observationally) and we can only provide the caveat that some of our results are susceptible to change once we have the resources to properly model them (although see Markevitch et al. 2003; Fabian et al. 2003, for references suggesting that neither conduction nor turbulence is relevant in cluster cores).

In this section, we describe how our clusters are initialized, how we set up pairs of clusters to form a merging system, the numerical methods and code parameters of our runs.

2.1 Cluster initial conditions

The structure of a merger remnant is likely to depend sensitively on the initial structure of the interacting systems (Gomez et al. 2002) making it important to implement realistic initial conditions for the gas and dark matter properties of our clusters. We follow the analytic prescription of Babul et al. (2002) and McCarthy et al. (2004) to produce systems which conform with recent theoretical and observational insights into cluster structure.

The dark matter density profiles of our systems follow an Navarro–Frenk–White (NFW)-like form (Navarro, Frenk & White 1996; Moore et al. 1998) given by

$$\rho_{\text{DM}}(r) = \frac{\rho_s}{(r/r_s)^\beta [1 + (r/r_s)]^{3-\beta}}, \quad (1)$$

with the central asymptotic logarithmic slope chosen to be $\beta = 1.4$ and r_s selected to yield a concentration $c = R_{200}/r_s = 2.6$ (we will use R_Δ throughout to indicate the radius within which the mean density of the system is Δ times the critical density, $\rho_c = 3H_0^2/8\pi G$). This dark matter distribution would yield $c = 4.5$ if fitted by equation (1) with $\beta = 1$ and is consistent with results from cosmological N -body simulations (Eke, Navarro & Steinmetz 2001).

The initial density and temperature profiles of the clusters are set by requiring that (1) the gas be in hydrostatic equilibrium within the halo, (2) the ratio of gas mass to dark matter mass within the virial radius be $\Omega_b/(\Omega_m - \Omega_b)$, and (3) the initial gas entropy¹ scales as $S(r) \propto r^{1.1}$ over the bulk of the cluster body.

Our choice for the initial gas distribution is motivated by the fact that we are interested in studying ‘typical’ systems which correspond to the most likely pre-interaction configuration for merging clusters. Estimates in the literature suggest that the majority of observed clusters (70–90 per cent) possess dense, cool, compact cores with short cooling times (Peres et al. 1998). Recent *Chandra* observations reveal that these systems exhibit power-law entropy profiles of the form $S(r) \propto r^{1.0-1.3}$, beyond the central 10 kpc, over a wide range of mass scales (Donahue et al. 2006). We note that our choice for the form of the initial density profile conforms not only with these observations but also with the results of high-resolution cluster simulations (Lewis et al. 2000; Voit et al. 2003).

We normalize the entropy profiles such that the temperature of the ICM at R_{vir} is half the virial temperature. This also approximately matches cosmological simulations (Lewis et al. 2000; Loken et al. 2002) and observations (De Grandi & Molendi 2002). Finally, for practical purposes, we start our systems with small, constant, low-entropy (10 keV cm²) cores. The cores, however, evolve to equilibrium power-law distributions quickly (~ 0.5 Gyr) and well before the clusters begin interacting significantly.

Particle realizations are initialized using the ZENO package of J. Barnes. Gas particles are distributed spherically and assigned temperatures according to the model described above. The dark matter velocity distribution is taken to be isotropic and the distribution function of particle energies calculated by solving the Abel integral equation (Binney & Tremaine 1987; Kazantzidis, Magorrian & Moore 2004). Previous cluster merger studies have been initialized with Gaussian distributions resulting in systems which subsequently evolve significantly from their initial conditions (RS01).

¹ We use the standard proxy for entropy given by $S \equiv kT/n_e^{2/3}$, with n_e and T representing the electron density and temperature of the gas, respectively.

Our approach initializes the system very close to equilibrium, ensuring that our interacting systems accurately maintain our desired initial conditions until they collide.

Negative values for the dark matter energy distribution function are avoided by truncating our clusters (dark matter and gas) smoothly beyond the virial radius (R_{vir}) with the function $\rho(r) \propto (r/R_{\text{vir}})^\gamma \exp[-(r - R_{\text{vir}})/R_{\text{sm}}]^3$, where γ is set to ensure a continuous first derivative for $\rho(r)$. Beyond the point where the gas pressure reaches that of the intergalactic medium (IGM) [we choose $P_{\text{IGM}} = (\Omega_b \rho_c k T_{\text{IGM}})/(\mu m_{\text{H}})$ with $T_{\text{IGM}} = 3 \times 10^5$ K], we surround our systems with a dynamically negligible uniform gaseous medium of pressure P_{IGM} . This is done mainly to confine small numbers of high-velocity gas particles occasionally produced during our simulations. Without this external medium, these particles would adiabatically expand to unrealistically low densities and temperatures and pose numerical difficulties for the code.

In this study, we examine mergers between systems set to have mass ratios of 1:1, 3:1 and 10:1. In what follows, we will distinguish the two interacting clusters by identifying the most-massive $10^{15} M_\odot$ system as the primary system (with mass M_p) and the smaller incident system (with mass M_s) as the secondary. For our equal-mass mergers, we arbitrarily choose one system as the primary with no effect on our results due to the symmetry in such cases. All positions and velocities are measured relative to the centre of mass of the primary system.

The virial mass of primary system is set to $10^{15} M_\odot$ in all cases and the secondary systems have virial masses of 10^{15} , $10^{14.5}$ and $10^{14} M_\odot$. These values are larger than M_{200} , which takes the values 7.5×10^{14} , 2.4×10^{14} and $7.8 \times 10^{13} M_\odot$ for the three systems. We will, however, refer to the systems by their virial mass rather than M_{200} . The circular velocities of the haloes at R_{200} (V_{200}) are 1340, 920 and 630 km s⁻¹, respectively.

2.2 Initial kinematics

The problem of initializing the kinematics of idealized merging clusters has been faced by several authors (RS01; Ritchie & Thomas 2002). Whereas previous studies have initialized orbits based on analytic arguments, our initial conditions are motivated by analysis of the orbital properties of substructure in high-resolution cosmological dark matter simulations.

We construct orbits for these systems which produce specified radial and tangential velocities for the secondary system (v_r and v_t , respectively) when its centre of mass reaches the virial radius of the primary (R_{vir}). For each of the three mass ratios we study, we examine three orbits selected to produce a typical value of $v_r(R_{\text{vir}})$ and to cover a significant range of the transverse velocity $v_t(R_{\text{vir}})$ giving rise to mergers found in cosmological dark matter simulations.

In an N -body study of haloes merging on to rich clusters, Tormen (1997) found that the average velocity of an accreting secondary system is $v(R_{\text{vir}}) = (1.1 \pm 0.1)V_c(R_{\text{vir}})$, where V_c is the primary system’s circular velocity. In another study, Vitvitska et al. (2002) (see also Benson 2005) examined the distribution of secondary subhalo velocities moving within the virial radius of massive haloes. They found that the total velocities of accreting systems (i.e. those with negative radial velocities in the range $r = 0.8-1.2R_{\text{vir}}$) relative to the primary are distributed normally. They reported mean infall velocities of $\langle v \rangle \approx V_c$ (independent of mass), consistent with Tormen (1997). They also found that tangential two-dimensional rms velocities decrease with the secondary mass, ranging from $\sigma_\perp \approx 0.4 V_c$ for 1:1 mergers to $\sigma_\perp \approx 0.67 V_c$ for 10:1 mergers. It is

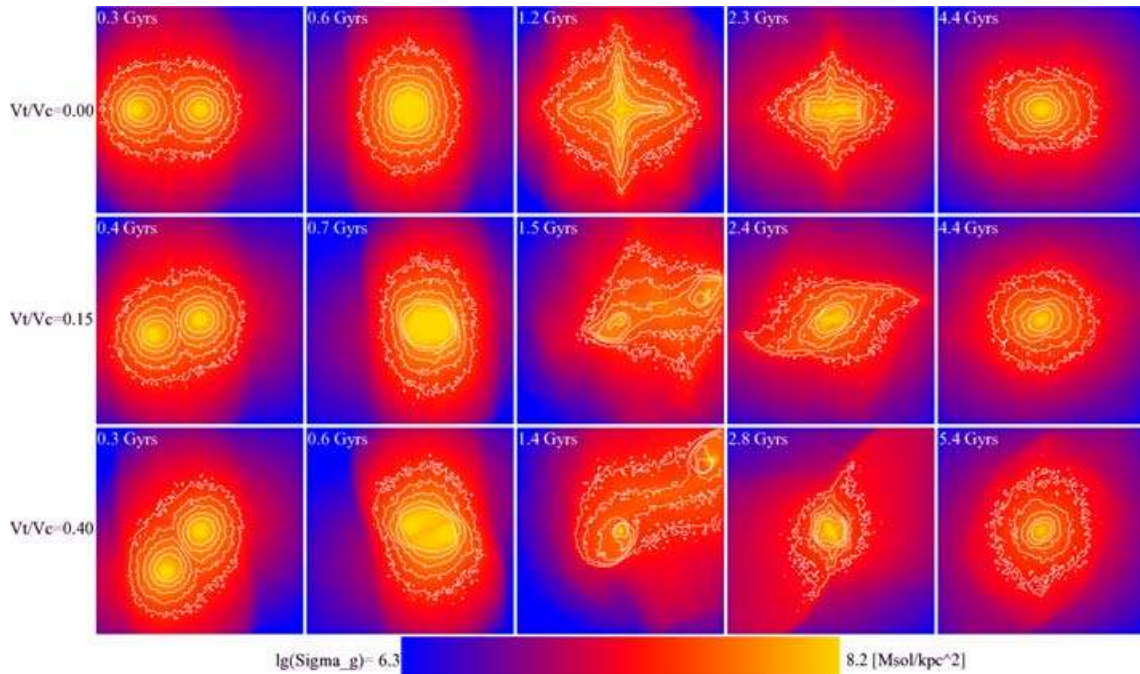


Figure 1. Grey-scale maps of the gas surface density for our 1:1 simulations, projected along an axis normal to the plane of the orbit (3 Mpc on a side). The white contours are X-ray surface brightness isophotes from simulated 50-ks $z = 0.1$ *Chandra* observations (3–48 times the background stepping by factors of 2). Times depicted are $t_{\text{closest}} - 200$ Myr (where t_{closest} is the time of first pericentric passage), $t_{\text{closest}} + 100$ Myr, t_{apo} (where t_{apo} is the time of first apocentric passage), $t_{\text{accrete}} + 100$ Myr (where t_{accrete} is the time of the second and usually the final pericentric passage), and t_{relax} , the time when system appears relaxed. All times are measured relative to t_0 (the time when the secondary’s centre of mass first crosses R_{200} of the primary). (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

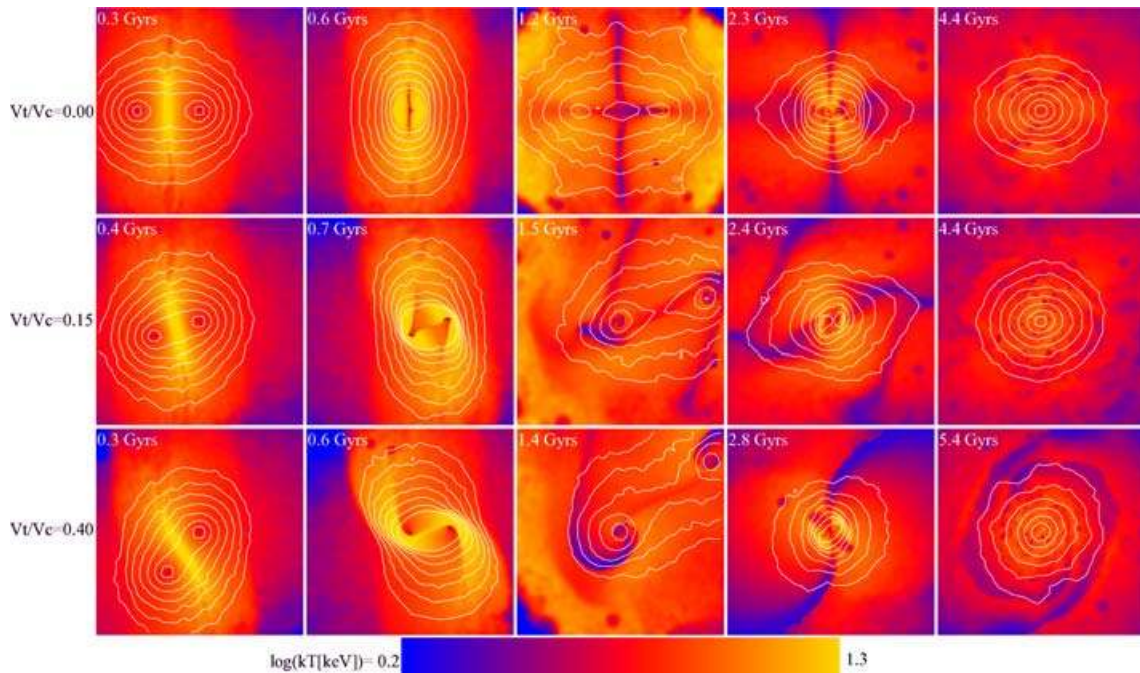


Figure 2. Grey-scale maps of the projected ‘spectroscopic-like’ temperature (Mazzotta et al. 2004) maps for a 0.5-Mpc-thick slice (3 Mpc on a side) passing through the centre of our 1:1 simulations. The Contours depict the SZ effect (for the entire simulation volume along the line of sight) and represent $\log(y) = -5.5$ to -4 in increments of 0.25. The times represented are the same as Fig. 1. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

Table 1. Initial separations (r), radial and transverse velocities (v_r and v_t , respectively) for our simulation orbits and measures of the final remnant’s global structure (the spin parameter λ_{200} and triaxial ratios q_{200} and s_{200} , all measured within R_{200}). At the start of our simulations, $t = 0$; when the secondary’s centre of mass passes the virial radii R_{100} or R_{200} of the primary, $t = t'_o$ or t_o , respectively.

$M_p:M_s$	$v_t(t'_o)/v_c(t'_o)$	$t_o(\text{Gyr})$	$r(0)$ (Mpc)	$v_t(0)$ (km s^{-1})	$v_r(0)$ (km s^{-1})	r_{\min} (kpc)	λ_{200}	q_{200}	s_{200}
1:1	0.00	3.4	6.54	0	−721	5	0.0	0.67	0.62
1:1	0.15	3.4	6.54	−111	−708	110	0.021	0.70	0.65
1:1	0.40	3.2	6.54	−315	−925	390	0.059	0.68	0.65
3:1	0.00	3.4	5.53	0	−574	12	0.0	0.76	0.73
3:1	0.15	3.4	5.53	−87	−587	103	0.014	0.80	0.75
3:1	0.40	2.6	5.53	−271	−908	360	0.042	0.78	0.76
10:1	0.00	2.2	4.81	0	−905	10	0.0	0.96	0.94
10:1	0.15	2.4	4.81	−106	−872	130	0.007	0.96	0.92
10:1	0.40	2.2	4.81	−284	−950	419	0.018	0.97	0.93

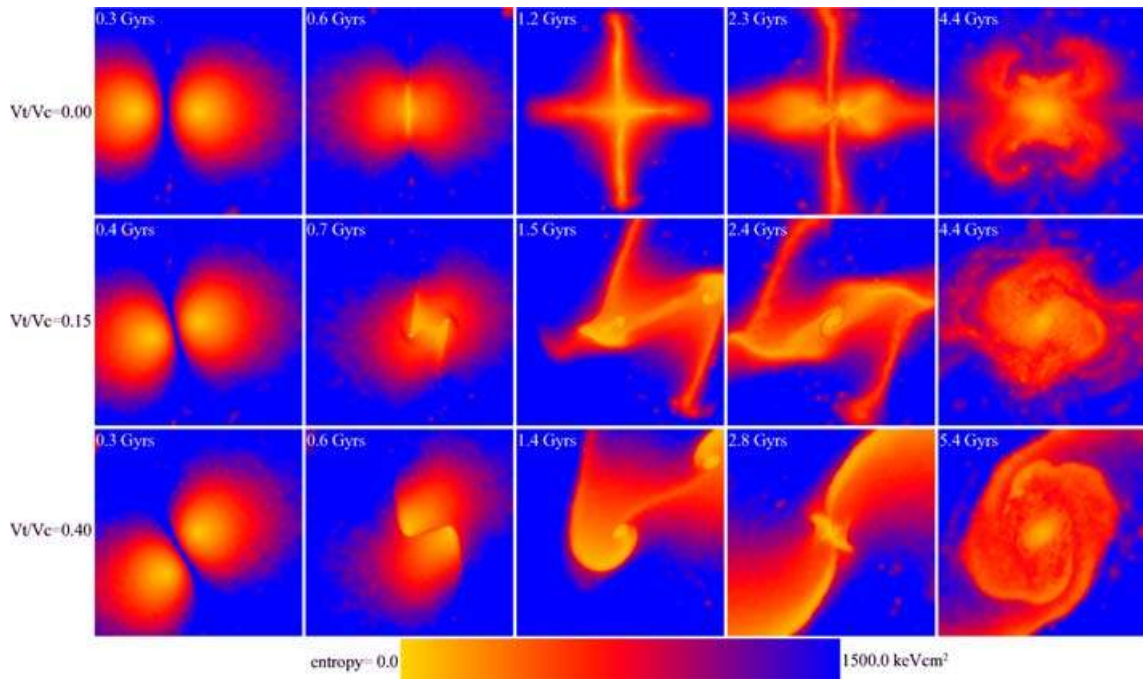


Figure 3. Grey-scale entropy maps for a 0.5-Mpc-thick slice (3 Mpc on a side) through the centres of our 1:1 simulations. The times represented are the same as Fig. 1. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

important to note that these statistics likely include systems making secondary or tertiary encounters with their primary. The orbits of such systems have likely been rendered more isotropic, making these tangential dispersions upper limits for substructure accreting for the first time. To produce systems which will merge fully within a reasonable amount of time, we have chosen to examine three values of v_t/V_c which roughly span the lower half of the Vitvitska et al. (2002) distribution. Specifically, we construct orbits to produce $v_t(R_{\text{vir}}) = 1.2V_c(R_{\text{vir}})$ (slightly higher but consistent with the mean velocities cited above) and $v_t/V_c = 0, 0.15$, and 0.4 . Unlike in the rest of our study, we define the virial radius here by an overdensity $\Delta = 100$, corresponding to the threshold used by Vitvitska et al. (2002). Doing this for mass ratios of 1:1, 3:1 and 10:1 produces nine simulations which constitute the basis of the analysis we present in this study.

Throughout our analysis, we will refer to three coordinate axes; x and y will denote directions in the plane of the initial orbit, and z the direction orthogonal to this plane. To properly capture the initial

effects of the encounter as the outermost envelopes of the systems make contact and the interaction shocks begin to form, we initialize our clusters separated along the x -axis so that their smoothly truncated envelopes barely touch (i.e. separated by slightly more than the sum of their virial radii). As a result, the initial conditions we have outlined above must be imposed at a time part way through the run when the centre of mass of the secondary system crosses the virial radius of the primary. To determine the initial velocities which yield these conditions, we first approximate the systems as point masses and analytically determine the initial conditions which yield the desired constraints. To account for the extended, tidally deforming mass distributions, we then iteratively refine these orbits with low-resolution dark-matter-only simulations.

Table 1 lists the parameters relevant to the initial conditions of our runs including the centre-of-mass separation of the secondary from the primary (r), initial tangential and radial centre-of-mass velocities of the secondary relative to the primary (v_t and v_r), the time of virial crossing (t_o , using the virial radius R_{200}), and the

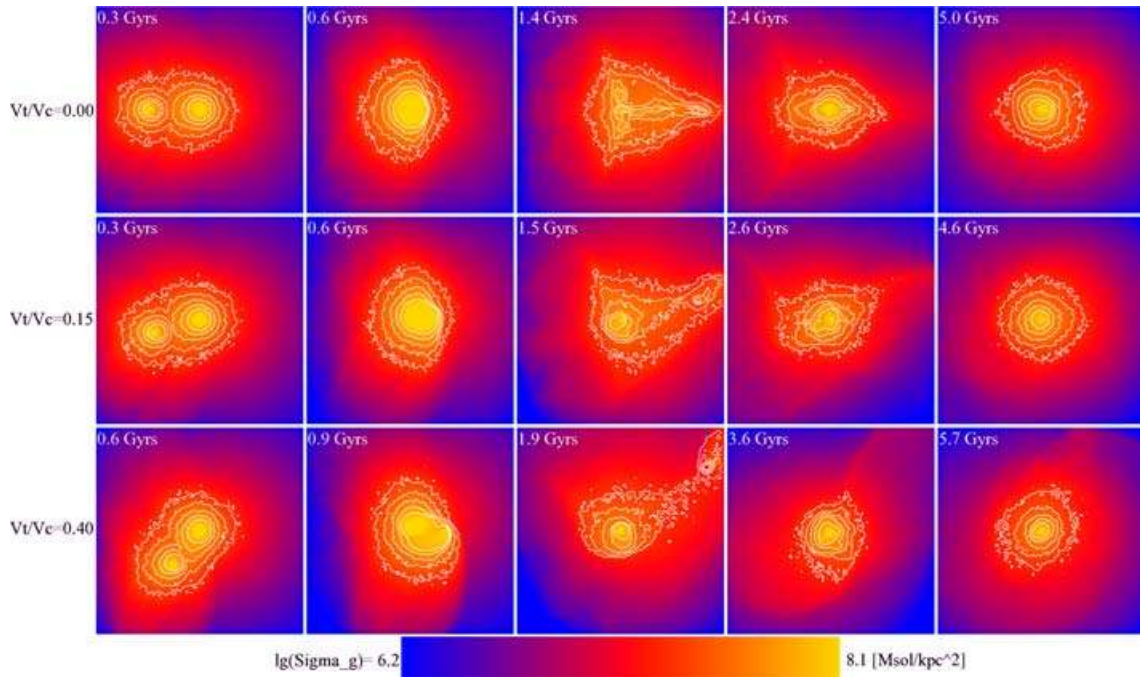


Figure 4. Grey-scale maps of the gas surface density for our 3:1 simulations, projected along an axis normal to the plane of the orbit (3 Mpc on a side). The white contours are X-ray surface brightness isophotes from simulated 50 ks $z = 0.1$ *Chandra* observations (3–48 times the background stepping by factors of 2). The times depicted are $t_{\text{closest}} - 200$ Myr, $t_{\text{closest}} + 100$ Myr, t_{apo} , $t_{\text{accrete}} + 100$ Myr and t_{relax} . See the caption for Fig. 1 or Table 2 for a brief definition of the time-scales. All times are measured relative to the t_0 when the secondary’s centre of mass crosses the virial radius of the primary for the first time. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

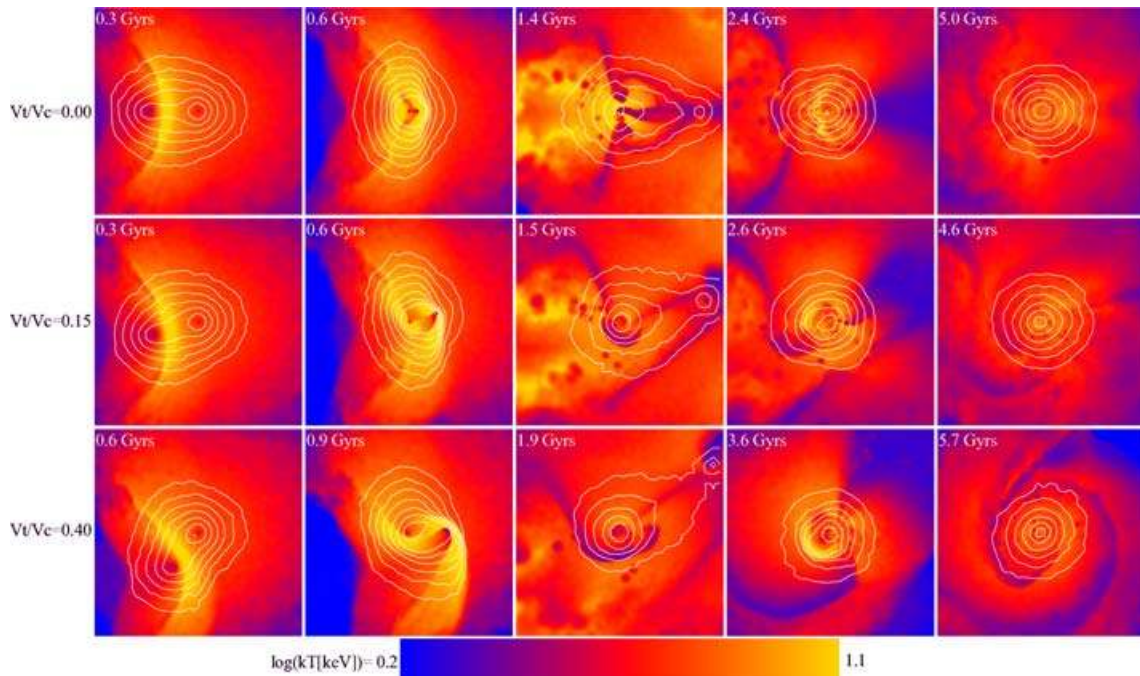


Figure 5. Grey-scale maps of the projected ‘spectroscopic-like’ temperature (Mazzotta et al. 2004) maps for a 0.5-Mpc-thick slice (3 Mpc on a side) passing through the centre of our 3:1 simulations. The contours depict the SZ effect (for the entire simulation volume along the line of sight) and represent $\log(y) = -5.5$ to -4 in increments of 0.25. The times represented are the same as in Fig. 4. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

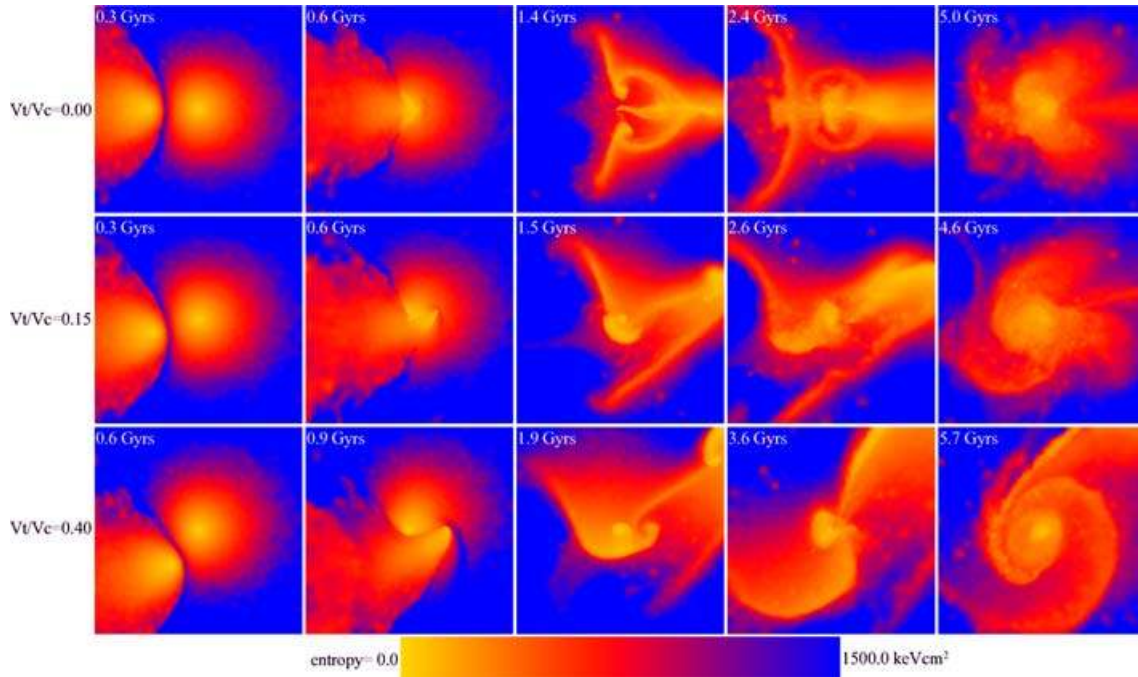


Figure 6. Grey-scale entropy maps for a 0.5-Mpc-thick slice (3 Mpc on a side) through the centres of our 3:1 simulations. The times represented are the same as in Fig. 4. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

centre-of-mass distances of closest approach (r_{\min}). As a test of the validity of our orbits, we have compiled the spin parameter and dark matter triaxial shapes for our final combined systems. We compute the spin parameter from $\lambda = J|E|^{1/2}/GM^{5/2}$ with J being the total angular momentum, E the total energy and M the total mass of the remnant, all integrated within R_{200} . We compute the triaxial ratios at R_{200} (denoted q_{200} and s_{200}), following the approach of Dubinski & Carlberg (1991). All are in reasonable agreement with accepted distributions from cosmological simulations (Barnes & Efstathiou 1987; Jing & Suto 2002).

2.3 Numerical methods

To compute the hydrodynamic forces between gas particles, we use *GASOLINE* in its default configuration (Wadsley et al. 2004): we use the Benz arithmetic-asymmetric implementation of the SPH momentum and energy equations. The gas quantities are smoothed over 32 particles, the Courant time-step parameter is set to $\eta_c = 0.4$, and the viscosity uses the standard Monaghan formulation of viscosity with $\alpha = 1$ and $\beta = 2$.

The gravitational forces are calculated with a tree that uses an opening angle $\theta = 0.8$. Each particle trajectory is integrated on its own time-step Δt_i , which is related to the particle’s acceleration a_i by the criterion $\Delta t_i < \eta (\epsilon/a_i)^{1/2}$ with tolerance parameter $\eta = 0.2$. The gravitational softening uses spline kernel interpolation, and the spline softening length is set to a constant value of $\epsilon = 10$ kpc for all cluster particles. This ensures that gravitational forces in the core are well resolved.

Radiative cooling allows for the formation of resilient dense gaseous cores. In some cases, it can also dissipate significant amounts of the thermal energy deposited in the centres of merger remnants, further stabilizing them. Since we are acutely interested in the evolution of these regions for this series of papers, the inclusion of cooling in our simulations is necessary.

We focus our analysis on radii $r > 40$ kpc $\sim 0.03R_{500}$ and have sought to ensure that we accurately model the behaviour of the system in that range. This is because the precise nature of very central regions of the observed compact cool cores is still not well understood. The temperature floors observed at their centres (Peterson et al. 2003) indicate the presence of a source of heating whose nature is still highly uncertain with several candidate mechanisms presently being considered (e.g. heating from AGN, conduction and turbulent mixing to name only a few). There is also evidence of other complex phenomena occurring in the central 40 kpc, such as multiphase cooling and ongoing star formation (Jaffe, Bremer & Baker 2005; Egami et al. 2006). These processes cannot be realistically captured with SPH simulations such as ours. In light of these issues, we will compute ‘central’ quantities at 40 kpc and will exclude the central 30 kpc $\sim 0.025R_{500}$ of the system from integrated quantities such as globally averaged temperatures.

For our simulations, we use a cooling function appropriate to a primordial gas. However, typical clusters have metallicities of $Z \sim 0.3Z_{\odot}$ and by omitting heavy-element line emission, we are underestimating the cooling rate of material with temperatures $T = 10^5$ – 10^7 K. A very small fraction (< 1 per cent) of the gas mass in our systems exists at these temperatures; most of the mass has $T = 10^7$ – 10^8 K. Additionally, this discrepancy has a negligible effect on the dynamics of our simulations. All subsequent analyses (e.g. producing X-ray surface brightness maps) are computed assuming a more realistic Raymond–Smith model (Raymond & Smith 1977) compiled for a metallicity of $Z \sim 0.3Z_{\odot}$.

We include star formation in our simulations using an algorithm which turns cold and dense gas into collisionless star particles, using a recipe similar to that of Katz, Weinberg & Hernquist (1996) and Stinson et al. (2006). We first select gas particles which are capable of forming stars based on four eligibility criteria: the gas must be dense ($n_H > 0.1 \text{ cm}^{-3}$); it must be either cool ($T < 3 \times 10^4$ K) or cooling ($dT/dt < 0$); its flow must be converging ($\nabla \cdot \mathbf{v} < 0$); and

the particle must be Jeans unstable. Once selected, star formation produces star particles with a probability $p = 1.0 - \exp(-c_* \Delta T / t_{\text{form}})$, where the star formation efficiency is taken to be $c_* = 0.1$. We set t_{form} to the maximum of the cooling time and the dynamical time, unless the particle is already cool ($T < 3 \times 10^4$ K) in which case we always set it to the dynamical time. If the particle is chosen to form stars, a new star particle is created with one-third of the mass of a full-sized gas particle.

Star formation and supernova explosions go hand in hand. The energy released by the supernovae is injected into the surrounding ICM as follows. At every time-step, we consider each star particle in the simulation, and based on its age, determine the associated supernova rate. The total energy released by the supernovae over the course of the time-step is then injected at a steady rate to the surrounding gas particles over the time-step. The star formation and feedback recipe we use is similar to that described in Stinson et al. (2006), except that we do not disable radiative cooling during feedback, and stellar winds which release mass from intermediate-mass stars are not included. This is a ‘minimal’ feedback scheme, since the energy is quickly radiated away and the feedback does not impact the evolution of the ICM in any meaningful fashion.

Finally, we note that our chosen mass-resolution models the initial conditions of a $10^{15} M_{\odot}$ system with 217 441 dark matter and 211 914 gas particles, where about 70 per cent of the particles in each species are within R_{200} . The dark matter particle mass is $4.4 \times 10^9 M_{\odot}$ and the initial gas particle mass is $5.9 \times 10^8 M_{\odot}$. In test runs, we have found that the cooling rates of isolated clusters are not robust, until there are ~ 100 particles within the ‘cooling radius’ (i.e. the radius within which $t_{\text{cool}} < t_{\text{Hubble}}$; $R_c \sim 150$ kpc for our simulations). With our initial conditions, the central core ($r_c \sim 50$ kpc) of a $10^{15} M_{\odot}$ system is initially resolved by ~ 240 particles, and its cooling radius by ~ 6300 particles.

2.4 Simulated observations

In Section 4, we will examine possible discrepancies between the relaxed appearance of systems and the degree to which they are formally so. For this reason as well as to determine the observability of features in the projected mass, temperature and entropy maps presented in Figs 1–9, we have created mock *Chandra* observations of our simulations. To create these we generate 325 projected X-ray maps ranging from 0.5 to 7.0 keV in 20-eV intervals using the Theoretical Image Processing System (TIPSY). This package takes the SPH outputs from our GASOLINE simulations and produces smoothed projected X-ray surface brightness maps with the appropriate variable SPH kernel applied individually to the flux represented by each particle. To these we add a three-component X-ray background (following the prescription of the QUICKSIM *XMM* simulation package) consisting of an extragalactic power-law component (Chen, Fabian & Gendreau 1997) and two thermal components of 10^6 and $10^{6.6}$ K modelled with a Raymond–Smith plasma (Raymond & Smith 1977). Generally, each image would then be multiplied by an energy-dependent radially varying effective area. However, we are interested in the detectability of extended features at $z = 0.1$ and our merging systems rarely fit within the *Chandra* field of view (FOV) at such a redshift. For this reason, we simulate a ‘mosaic’ mode for our simulated observations using constant but energy dependent effective areas, area averaged over the *Chandra* FOV. An unvignetted and spectrally flat particle background is then added with normalization 3.5×10^{-2} counts arcmin $^{-2}$ s $^{-1}$ keV $^{-1}$. The resulting images are convolved with an azimuthally symmet-

ric energy-dependent point spread function (PSF) taken from the on-axis PSFs specified by version 2.23 of the *Chandra* CALDB. The result is converted to a photon flux at a redshift of $z = 0.1$, quantized with a Poisson distribution, and co-added. For this paper, we use an integration time of 50 ks.

3 QUALITATIVE EVOLUTION

In what follows we present a qualitative account of common elements in the dynamical evolution of typical cluster mergers. A series of stages which mergers generically progress through will be identified, and the evolution of the system’s physical and observable properties will be described. In the process, several classes of transient structures will be introduced. This discussion is kept brief and is intended to provide a context for the discussion of the observability of substructure and relaxation which follows in Sections 4 and 5.² For those seeking a more detailed description, a specific discussion of each class of transient structure can be found afterwards in Section 6. All quoted times are measured from t_{o} , the moment at which the secondary system traverses R_{200} of the primary.

3.1 Evolutionary stages

All the simulations we have studied proceed through a similar evolutionary sequence involving five distinct stages: a pre-interaction phase, first core–core interaction, apocentric passage, secondary core accretion, and relaxation. Several important times during this progression which we will refer to throughout our analysis are listed in Table 2.

Initially, our systems are constructed to possess small core radii ($r_c \sim 50$ kpc, measured from β -model fits), low central entropies ($S = 10$ keV cm 2 at 10 kpc) and strong central positive temperature gradients. The low-density outer atmosphere of each system becomes distorted during pre-interaction through tidal forces and compression, adiabatically raising the temperature of material between and producing a short-lived bridge in surface brightness joining them. As the cores continue to accelerate upon approach, a pair of shock fronts materialise and are driven towards each core, heating and compressing them briefly. The effects of this interaction reaches its maximum strength at $t_{\text{closest}} = 0.5\text{--}0.8$ Gyr when the cores reach their closest approach. The system’s temperature and luminosity increase sharply for ~ 400 Myr at this point. Cooling of gas to a cold ($T < 2.5 \times 10^4$ K) state or to stars is subsequently quenched for 2–3 Gyr in most cases but is merely suppressed in the off-axis 10:1 interactions. Meanwhile, the primary system’s projected central positive temperature gradient is strongly reduced and its core radius increased. A detailed analysis of these phenomena is presented in the second and third papers of this series (Poole et al. (2006a), in preparation; Poole et al. (2006b), in preparation) in which the effects of mergers on the global properties of merging systems and the structure and appearance of compact cool cores will be studied.

In every case (including the head-on collisions) some part of the secondary’s cool core survives its first encounter with the primary core, forming a single clump and large cool stream of stripped material in off-axis cases and strings of one or more clumps in head-on cases.

² Readers are invited to peruse relevant digital movies detailing the evolution of various system properties over the course of the simulations at [http://astro.phys.uvic.ca/~babul/Merger_Paper I](http://astro.phys.uvic.ca/~babul/Merger_Paper_I).

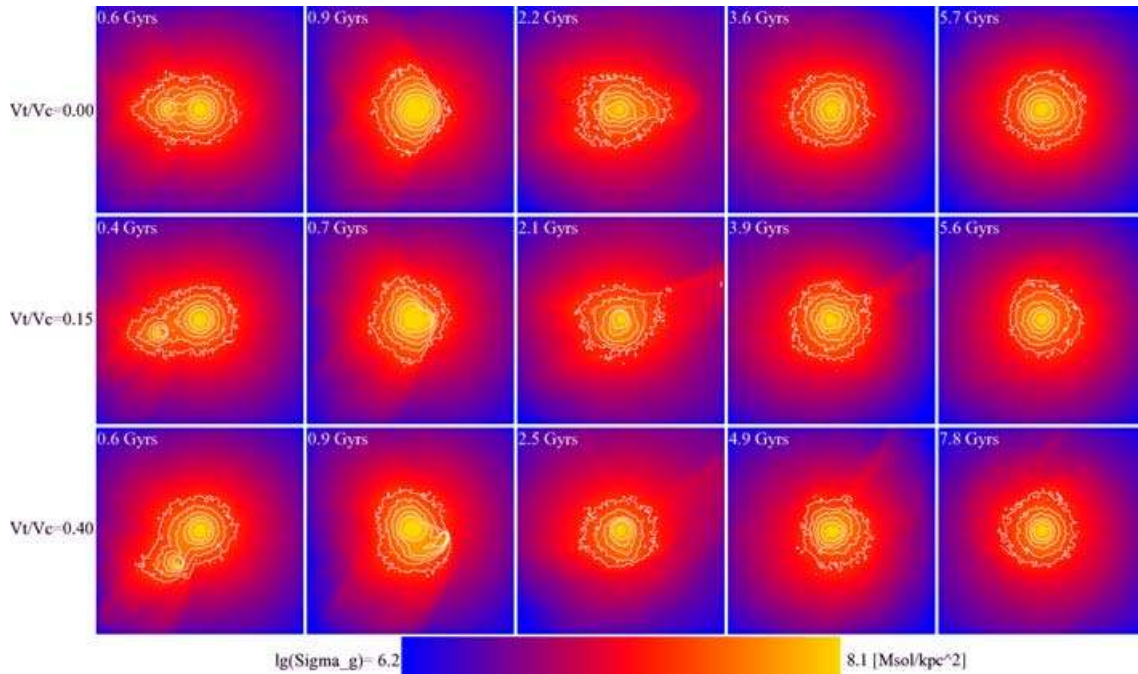


Figure 7. Grey-scale maps of the gas surface density for our 10:1 simulations, projected along an axis normal to the plane of the orbit (3 Mpc on a side). The white contours are X-ray surface brightness isophotes from simulated 50-ks $z = 0.1$ *Chandra* observations (3–48 times the background stepping by factors of 2). The times depicted are $t_{\text{closest}} - 200$ Myr, $t_{\text{closest}} + 100$ Myr, t_{apo} , $t_{\text{accrete}} + 100$ Myr and t_{relax} . See the caption for Fig. 1 or Table 2 for a brief definition of the time-scales. All times are measured relative to the t_0 when the secondary’s centre of mass crosses the R_{200} radius of the primary for the first time. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

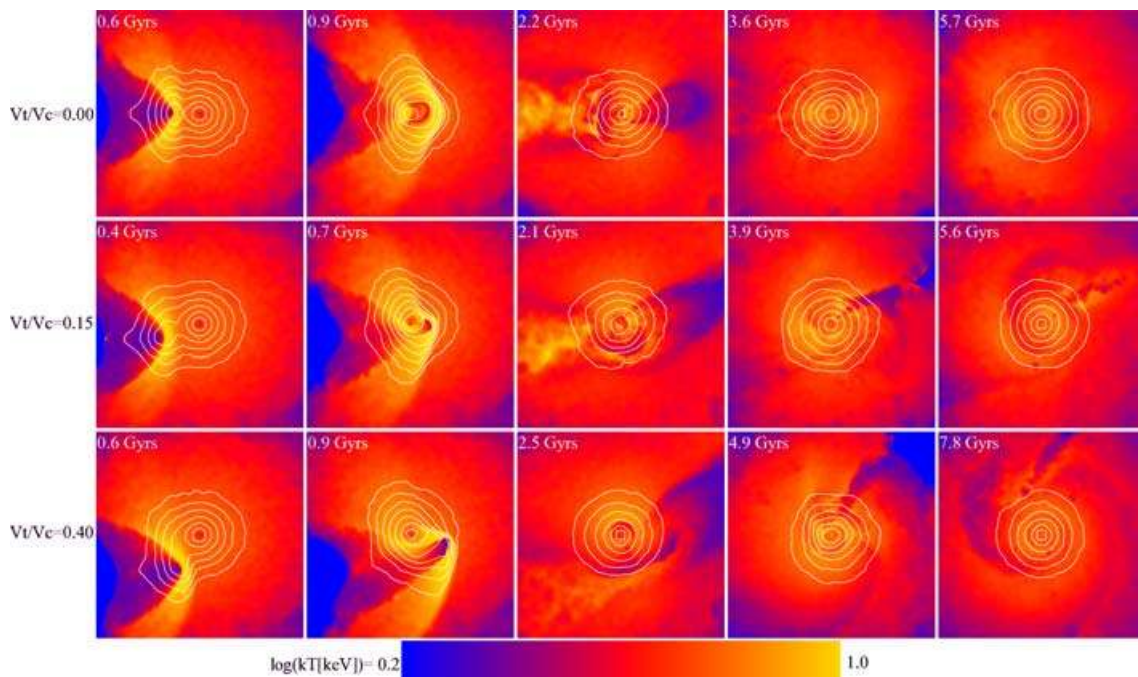


Figure 8. Grey-scale maps of the projected ‘spectroscopic-like’ temperature (Mazzotta et al. 2004) maps for a 0.5-Mpc-thick slice (3 Mpc on a side) passing through the centre of our 10:1 simulations. The contours depict the SZ effect (for the entire simulation volume along the line of sight) and represent $\log(y) = -5.5$ to -4 in increments of 0.25. The times represented are the same as in Fig. 7. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

At $t_{\text{apo}} = 1.2$ – 2.5 Gyr the disturbed secondary core reaches a maximum separation of 1.2–1.7 Mpc from the primary core. The surviving portion then returns for another encounter with the primary, reaching a second pericenter at $t_{\text{accrete}} = 2.2$ – 4.8 Gyr. In Table 2, we

see that the time elapsed until either of these stages generally correlates with the mass ratio and impact parameter of the interaction, presumably due to the declining efficiency of dynamical friction. Second pericentric passage marks the beginning of an extended

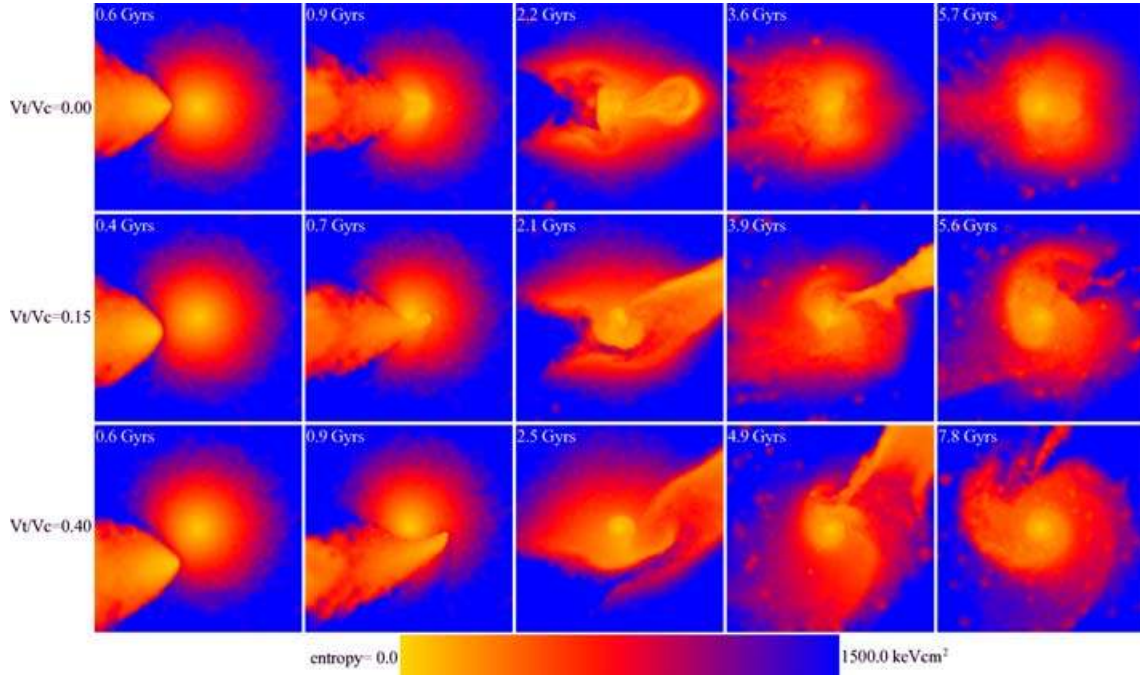


Figure 9. Grey-scale entropy maps for a 0.5-Mpc-thick slice (3 Mpc on a side) through the centres of our 10:1 simulations. The times represented are the same as in Fig. 7. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

Table 2. Times of important stages in the dynamical evolution of our simulations measured relative to t_0 , the time when the secondary’s centre of mass crosses the primary’s R_{200} radius. These are as follows: t_{closest} is the time of first pericentric passage; t_{apo} is the time of the first apocentric passage; t_{accrete} is the time of the second pericentric passage typically during which the secondary’s gas core merges with that of the primary and it also marks the beginning of stream accretion; t_{relax} is the time at which the total system visually appears relaxed in simulated 50-ks *Chandra* observations at $z = 0.1$; t_{virial} is time at which the system’s dark matter is assessed to be virialized within R_{500} ; and t_{hydro} is the time at which the system returns to hydrostatic equilibrium (to within 10 per cent) at R_{500} . Quantities in brackets indicate the redshift at which the secondary core would have to cross R_{200} of the primary for the system to be observed in the given state at $z = 0.1$ and 0.5, respectively. Additional parameters in the table are: the mass ratio of the primary to the secondary (column 1) and the secondary’s transverse velocity at when its centre of mass crosses the virial radius of the primary, in units of the primary’s circular velocity (column 2).

$M_p:M_s$	v_t/v_c	t_{closest}	t_{apo}	t_{accrete}	t_{relax}	t_{virial}	t_{hydro}
1:1	0.00	0.5 (0.14, 0.58)	1.2 (0.21, 0.70)	2.2 (0.33, 0.92)	4.4 (0.65, 1.73)	4.4 (0.65, 1.73)	7.9 (1.73, >10)
1:1	0.15	0.6 (0.15, 0.60)	1.5 (0.25, 0.77)	2.3 (0.34, 0.95)	4.4 (0.65, 1.73)	4.4 (0.65, 1.73)	–
1:1	0.40	0.5 (0.14, 0.58)	1.4 (0.24, 0.75)	2.7 (0.39, 1.06)	5.4 (0.85, 2.44)	3.8 (0.55, 1.44)	3.3 (0.47, 1.25)
3:1	0.00	0.5 (0.14, 0.58)	1.4 (0.24, 0.75)	2.3 (0.34, 0.95)	5.0 (0.77, 2.10)	3.4 (0.49, 1.28)	4.3 (0.63, 1.67)
3:1	0.15	0.5 (0.14, 0.58)	1.5 (0.25, 0.77)	2.5 (0.26, 1.00)	4.6 (0.69, 1.84)	3.4 (0.49, 1.28)	4.3 (0.63, 1.67)
3:1	0.40	0.8 (0.18, 0.63)	1.9 (0.29, 0.85)	3.5 (0.50, 1.32)	5.7 (0.92, 2.75)	4.3 (0.63, 1.67)	3.6 (0.52, 1.36)
10:1	0.00	0.8 (0.18, 0.63)	2.2 (0.33, 0.92)	3.5 (0.50, 1.32)	4.8 (0.73, 1.96)	4.6 (0.69, 1.84)	5.2 (0.81, 2.26)
10:1	0.15	0.6 (0.15, 0.60)	2.1 (0.32, 0.90)	3.8 (0.55, 1.44)	5.6 (0.90, 2.65)	4.5 (0.67, 1.78)	5.1 (0.79, 2.18)
10:1	0.40	0.8 (0.18, 0.63)	2.5 (0.26, 1.00)	4.8 (0.73, 1.96)	7.8 (1.68, >10)	5.6 (0.90, 2.65)	5.8 (0.95, 2.88)

period of several Gyr during which material dispersed from the secondary core accumulates on to the core of the primary system. Although a small portion of the secondary core can survive the resulting disruption and experience tertiary encounters with the primary, there are no realistically observable traces of it following t_{accrete} in any of the cases we have studied.³ For this reason, our systems are considered to be evolving as a single merger remnant from t_{accrete} onwards.

In a study of the orbital parameters of cluster substructure in a cosmological context (including gas but not cooling), Tormen,

³ Higher-impact parameters than those probed by our simulations, although atypical, could result in longer-lived distinct secondary cores.

Moscardini & Yoshida (2004) similarly found that the gaseous component of secondary systems becomes disrupted shortly after second pericentric passage. They also presented simple analytic models for predicting the time and distance of first pericentric and apocentric passages. Our simulations compare well to their model predictions, supporting the consistency of our initial conditions with the orbital properties of substructure in cosmological simulations.

Following the accretion of the secondary core, the resulting remnant proceeds through a period of relaxation. It appears undisturbed under reasonable observational circumstances in simulated *Chandra* observations by $t_{\text{relax}} = 4.4\text{--}7.8$ Gyr but past this time, continues to evolve until the end of our simulations: recovery of the core’s central temperature decrement is still proceeding (see Poole et al., in preparation for more details) as well as accretion of both dark matter and

gas dispersed beyond the R_{200} radius during the merger. The system sustains a virialized state within R_{500} after t_{virial} and hydrostatic equilibrium at R_{500} after t_{hydro} (see Section 5).

Following t_{closest} , short-lived structures in the system's distribution of X-ray surface brightness, SZ signature, temperature and entropy arise. In Figs 1–9, we present projected gas surface density/X-ray brightness, temperature/SZ and entropy maps of each of our simulations near several of the times discussed above. In what follows, we will use these figures to present the progression of these structures (both physical and observable) as they arise and dissolve.

Readers may find it useful to refer to movies of our simulations² while reading the following sections.

3.2 Evolution of head-on mergers

Our head-on mergers evolve in a distinctly different way from our off-axis mergers, with even their qualitative evolutions exhibiting strong dependencies on the mass ratio of the systems. We thus isolate the account of their evolution from that of the off-axis cases.

3.2.1 Physical state

In our equal-mass head-on merger, two near-planar shocks are produced shortly before t_{closest} and are driven into and through each core (in good agreement with RS01). They subsequently exit the system as two symmetric hemispherical fronts. Due to the confining geometry of this situation, material initially in the cores of the merging systems remains in relatively high-density structures during the impact. From t_{closest} to approximately t_{apo} , much of this material occupies an expanding disc oriented normally to the axis of the merging systems' motion and a filament of dense clumps strung between the remnants of the two cores, both of which are clearly visible in Fig. 1. In Figs 2 and 3, we see that this material is cold ($T \sim 1.0$ keV) and has low entropy ($S \sim 10$ keV cm²). At approximately t_{accrete} , it re-accretes on to the remnant core having radiated most of the thermal energy generated by the impact. As a result, the system's core returns to a state of cooling twice as efficient at converting the hot ICM into stars and condensed gas ($T < 2.5 \times 10^5$ K) as the primary prior to the merger. Although equal-mass head-on mergers are predicted to be rare in cold dark matter models of structure formation,⁴ this supports the findings of Motl et al. (2004) who found that mergers can act as a means of constructing actively cooling cores. We will study this in more detail in Poole et al. (in preparation).

Comparing Figs 1–4, we can see that reducing the mass of the secondary to a third of the primary's dramatically changes even the qualitative behaviour of a head-on collision. Although two shocks are still produced, the one leading the secondary's motion is much more significant to the system's evolution. As Figs 5 and 6 show, the bow-shaped geometry of this shock (again, in good agreement with RS01) displaces the material of the primary core forward and laterally. The result is a conical shell of cool ($T \sim 3$ keV) moderate-entropy ($S \sim 150$ keV cm²) gas, entrained by the remainder of the secondary core at its apex. This structure surrounds a bubble of hot ($T \sim 10$ keV) high-entropy ($S \sim 550$ keV cm²) gas. These figures also illustrate how the low-pressure region created in the wake of the secondary's

motion is quickly and convectively filled by this displaced material. Material displaced most laterally re-accretes first, flowing in through the back of the secondary's wake. Material initially displaced more forwardly is dragged in behind afterwards. Upon returning to the core, this material experiences additional shocking, resulting, for example, in the high-temperature ($T \sim 9.5$ keV) region seen to the left-hand side of the core shortly after t_{accrete} in Fig. 5.

In the 10:1 case, the secondary core penetrates the primary core and deposits nearly all the kinetic energy of its gaseous component into the core of the primary. The result is a large (~ 500 kpc) bubble with an expanding shell of cool ($T \sim 3.5$ keV) low-entropy ($S \sim 70$ keV cm²) material filled with hot ($T \sim 7$ keV) moderate-entropy ($S \sim 180$ keV cm²) gas. In Fig. 8, the initial formation of the bubble after t_{closest} is illustrated. This bubble lasts for ~ 1.5 Gyr and is carried forward to a radius of ~ 750 kpc by the momentum of the collision. Its final extent can be seen in Figs 8 and 9. Shortly before t_{apo} it stops moving and expanding, collapses into a low-entropy stream and accretes back to the core by t_{accrete} .

3.2.2 Observable state

Following the procedure detailed in Section 2.4, we have produced simulated *Chandra* observations and overlaid their contours on to the projected gas surface density maps presented in Figs 1, 4 and 7. This allows us to determine which distributed features have sufficiently high surface brightnesses to be detected under reasonable observational circumstances. We have also generated SZ maps and overlaid their contours on the temperature maps presented in Figs 2, 5 and 8. Since these maps do not include the effects of instrumentation, we cannot comment in detail on the detectability of low surface brightness features through SZ observations. We place our faintest contours at a level of $\log y = -5.5$ ($\delta T = -17$ μ K at 30 GHz, McCarthy et al. 2003) to approximate the depth to which the next generation of SZ imaging instruments will reach (e.g. -10 μ K for Sunyaev–Zeldovich Array at 30 GHz, Knox, Holder & Church 2004). The resulting SZ limit is a good match to the system extent realistically observable by *Chandra*.

In the 1:1 case, we can see in Figs 1 and 2 that both the expanding disc and the filament of disturbed core material created in the impact and discussed above are reasonably observable through X-ray observations. Comparing these figures, we can see that the remnant's X-ray isophotes are extremely boxy, whereas the SZ contours are significantly more regular and much less elliptical (this is a trend that we observe in all our simulations). Complicated temperature and entropy variations are seen throughout the duration of the merger, with small ~ 100 kpc scale variations ($\Delta T/T \sim 15$ per cent) remaining at t_{relax} .

In the 3:1 head-on case, Figs 4 and 5 illustrate that the extended features generated in this merger following t_{closest} are similarly observable as in the 1:1 case. However, we can see that at t_{accrete} there are large extended low surface brightness features that escape detection by *Chandra*. Complicated temperature and entropy variations, distinctly different from those observed in the 1:1 case, emerge after t_{accrete} and persist until the end of the simulation. The temperature fluctuations present at t_{relax} are more significant ($\Delta T/T \sim 20$ per cent) and spatially irregular than those in the 1:1 case.

Lastly, Figs 7 and 8 illustrate the observability of extended structures formed in our 10:1 head-on merger. We can see from these that the large expanding bubble formed from the collision is not detectable when it reaches its largest extent at t_{apo} . Furthermore, the system looks quite regular in both X-ray and SZ at t_{accrete} , although

⁴ However, they are not without observational precedence; RXC J0532.9–3701 (Finoguenov, Böhringer & Zhang 2005) has boxy isophotes and a cloverleaf morphology in entropy, much like our relaxing equal-mass head-on merger.

small but significant irregularities in the central X-ray isophotes persist for ~ 2 Gyr afterwards. Temperature and entropy fluctuations are present throughout the merger with the bubble formed from the core material dominating the temperature and entropy distributions after t_{closest} . Significant fluctuations in temperature ($\Delta T/T \sim 20$ per cent) are present at t_{relax} , with little change occurring between t_{accrete} and t_{relax} .

3.3 Evolution of off-axis mergers

In all the off-axis simulations we have studied, several distinct classes of transient structure are formed when the secondary (and sometimes the primary) system's core becomes disturbed. Interestingly, the qualitative evolution of these structures is remarkably independent of impact parameter and mass ratio over the ranges we have studied. Furthermore, their properties are consistent with those of 'cold fronts' observed in many *Chandra* and *XMM* observations (Markevitch et al. 2000). Cold fronts are contact discontinuities between regions of bright, dense, cold gas and faint, hot, rarefied gas. These regions are observed to be in near pressure equilibrium with the surrounding ICM and the jumps in temperature across their interface imply mildly sonic or subsonic velocities.

Several authors have studied simulations of merging clusters illustrating that the ram-pressure disruption of cold low-entropy cores during mergers can account for these features (Bialek et al. 2002; Heinz et al. 2003; Mathis et al. 2005). Once removed from the dark matter potential confining it, stripped gas lags behind its dark matter and galactic components, adiabatically expanding and cooling until it establishes pressure equilibrium within the resulting merger remnant.

Our simulations confirm these results. In what follows, we will give a qualitative account of our off-axis mergers' evolution through a series of transient structures and discuss their observable properties. We will find that there are many points when several classes of structures resembling cold fronts can be created. Additional details can be found in Section 6 where each of these classes will be studied in detail and new mechanisms involved in the production and evolution of cold fronts will be presented.

3.3.1 Physical state

In all our 1:1 and 3:1 off-axis mergers, ram-pressure stripping causes both the primary and secondary cores to develop 'comet-like' head-tail morphologies in gas surface density, X-ray surface brightness, temperature and entropy during their first pericentric passage. In the 10:1 cases, this is true only for the secondary core. In all cases, this morphology starts ~ 100 Myr before t_{closest} and ends shortly before t_{apo} with a typical duration of ~ 0.5 Gyr.

On reaching apocentric passage, several extended structures in the system's distribution of temperature, entropy and gas density have evolved. In Figs 1 and 4, we see that a bridge connecting the surviving portions of the primary and secondary cores has formed in the 1:1 and 3:1 cases (see Section 6.1). Several long and roughly radial outwardly moving plumes of cool ($T \sim 3$ keV) low-entropy ($S \sim 60$ keV cm²) material have also formed (see Section 6.2). These features are not obvious in the system's gas density or surface brightness maps, but are evident in the temperature and entropy maps presented in Figs 2, 3, 5 and 6. All these structures are essentially absent in our off-axis 10:1 mergers.

Following t_{apo} , material displaced as plumes from the primary and secondary cores stops expanding away from the system and begins

returning towards the remnant core. At t_{accrete} , the secondary core returns for its second (and last) pericentric passage of the system. After this, plume material begins accreting to the remnant core as collimated high-velocity (~ 1000 km s⁻¹) streams of material (see Section 6.4). At this point, evidence of a secondary core has been destroyed and these features are not associated with an apparent merging system. Stream material is generally shock-heated as it accretes on to the remnant core. These streams occur even in our 10:1 cases and are visible in the temperature and entropy maps presented in Figs 2, 3, 5, 6, 8 and 9 as narrow and radially oriented cold low-entropy structures following t_{accrete} . When they accrete directly to the remnant core, these streams lead to multiple discontinuities, or 'edges' in the system's central surface brightness distribution (see Section 6.5).

3.3.2 Observable state

Elongated and curved disturbed cores have been observed in several systems (e.g. A85, A1758 and A2256) and are frequently attributed to the disruption of accreting systems due to ram-pressure stripping. We observe this for only a short duration ($\lesssim 0.5$ Gyr) following t_{closest} in all our off-axis mergers. Prior to t_{closest} , this morphology does not manifest. At t_{apo} , longer lived elongated tails are created but the ejection mechanism is not ram-pressure stripping (see Section 6.5).

In Fig. 1, we see that the bridge formed after t_{closest} in our off-axis 1:1 mergers remains visible in our simulated *Chandra* observations until destroyed at t_{accrete} . The material forming this structure is not stripped from the central core but from the region just outside the initial cooling radius. Hence, it is of intermediate entropy (300–500 keV cm²) and temperature (~ 6.5 keV). No strong pressure gradients arise across it, as shown in the SZ maps in Fig. 2.

The bridges formed in our off-axis 3:1 mergers remain detectable for only 1.0 Gyr following t_{closest} , or roughly until t_{apo} . As in the 1:1 cases, the entropy of the bridge material is of intermediate entropy (200–400 keV cm²) and temperature (~ 4.5 keV) and exhibits no strong pressure gradients.

In Figs 1 and 4, we also see that the plumes generated from the disturbance of the primary and secondary cores are observable in the 1:1 cases, but only marginally so in the 3:1 cases. Fig. 7 shows that in the 10:1 cases, although the system appears disturbed after t_{closest} , no extended features exist with sufficient surface brightness to be detected.

At t_{accrete} , very significant temperature fluctuations ($\Delta T/T \sim 20$ per cent) are present in all cases and persist until well after t_{relax} . Because the accreting streams retain angular momentum from the merger and do not readily mix with the remnant, they produce spiral structures in the remnant's temperature and entropy distribution which are visible in our temperature and entropy maps at t_{relax} .

Because the SZ signature is proportional to gas density (ρ_g) rather than the ρ_g^2 dependence of the X-ray surface brightness, extended low-density features tend to be washed-out in the SZ maps. Despite this, we can see that our SZ maps indicate that the bridges formed in the 1:1 and 3:1 mergers remain above our nominal SZ threshold. At t_{relax} , when accreting streams leave the X-ray surface brightness elongated in these cases, the SZ maps look significantly more regular with only the 1:1 $v_t/V_c = 0.15$ case looking comparably disturbed to its X-ray surface brightness.

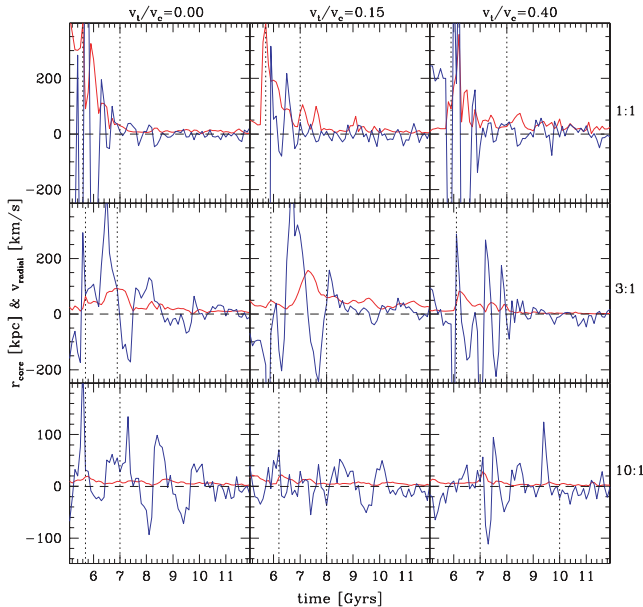


Figure 10. Displacement of the centre of mass of gas within the central 150 kpc from its dark matter centre of mass (smoother, lower-amplitude red curve) and the mass-averaged velocity of the same material in the direction of that displacement (the more erratic blue curve) for the late stages of each of our simulations. The vertical dashed lines correspond to t_{accrete} and t_{relax} . The increased activity between these two time-scales is primarily the result of the gas core being disturbed by the secondary’s gas core during the second and typically the final pericentric passage, and by the ensuing cold stream. The values across the top panel indicate the transverse velocity at t_0 depicted by each column, whereas the text on the right-hand panel indicates the mass ratio depicted by each row. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

3.4 Core oscillations

In several of the cases we have studied, we find that the central ($r \lesssim 0.5R_{500}$) ICM of our merger remnants oscillates with respect to their dark matter distributions. In the discussion of the evolution of disturbed morphology and relaxation which follows, there will be several instances when these oscillations will be relevant. Such oscillations have been discussed by several authors in attempts to account for ‘edges’ observed in the central surface brightness of some clusters (see Section 6.5 for more details and references).

In Fig. 10, we present the displacement of the centre of mass of the densest central 150 kpc of our remnant gaseous cores relative to the centre of mass of the densest central 150 kpc of dark matter. To differentiate oscillating modes from the influence of substructure passing through the core in this calculation, we also present the mass-averaged velocity of the gas in the direction of this displacement’s vector. Displacement due to coherent oscillations will be accompanied by positive velocities until peak displacement when the velocity turns around and becomes negative, returning to zero when the displacement does. The displacement of the core due to the arrival of substructure is revealed by increases in the displacement at times of small or negative radial velocity. There are several instances of significant core oscillations following t_{accrete} stimulated by the second pericentric passage of the secondary core. They generally last until t_{relax} .

We have performed this calculation for material within 50 kpc as well. On these scales, we observe no oscillations larger than the softening length (10 kpc) at times when oscillations are present on

150-kpc scales. Hence, gas in the central regions of our remnant cores (where cooling is most rapidly taking place) remains tightly coupled to the dark matter potential with the surrounding material constituting the oscillation seen on 150-kpc scales. It has been hypothesized that energy from bulk oscillations in the potential of the core due to displacements of the gas from the dark matter could act as a source of heating for compact cool cores (Markevitch et al. 2001). Our analysis suggests that although oscillations may occur on 150-kpc scales, the actively cooling gas on 50-kpc scales can remain strongly coupled to the dark matter. In such cases, oscillations in the potential may not be affecting cooling. Further study is required to determine if this is the case for oscillations stimulated through close encounters by secondary systems with mass ratios of only a few percent, such as those studied by Tittley & Henriksen (2005).

All these calculations determine the motion of the gaseous core relative to the dark matter core. We have checked to see how the dark matter core is itself moving within its halo. For our 1:1 cases, we find that on both the 150-kpc and the 50-kpc scales the dark matter cores remain stationary relative to the centre of mass of the system, following t_{accrete} . However, the dark matter cores of our 3:1 and 10:1 mergers experience significant motions about the system’s centre of mass until well after t_{relax} . The oscillations we observe between the gas and dark matter on 150-kpc scales are thus a result of the dark matter core orbiting the centre of mass of the system. As the gravitationally dominant dark matter core moves, the gaseous component is dragged behind it but with a lag due to the extra pressure it experiences. The result is an oscillation between the two components as the dark matter core moves in its orbit. On 50-kpc scales, baryonic material dominates the potential of most of the gas and the dark matter can follow it since it is not subject to pressure. As a result, oscillations between the gas and dark matter do not occur on these scales.

Following t_{accrete} , the gaseous and dark matter cores of our 1:1 merger remnants rapidly become concentric by t_{relax} . A few displacements of the core position with respect to the dark matter are apparent but these are generally accompanied by negative radial velocities indicating that they are a product of the accretion of substructure on to the core.

The cores of our 3:1 merger remnants all experience bulk oscillations between their gaseous and dark matter components, following t_{accrete} . In the head-on and $v_t/V_c = 0.15$ cases, the amplitude of these motions are 100 and 150 kpc, respectively, with velocities reaching 400 km s^{-1} . These motions last for ~ 1 Gyr and end immediately before t_{relax} . In the $v_t/V_c = 0.4$ case, a series of four core oscillations occur beginning at t_{accrete} with amplitudes as large as 50 kpc and velocities of $175\text{--}250 \text{ km s}^{-1}$. They are of much shorter duration (~ 0.5 Gyr) and are finished by t_{relax} .

Some part of the dark matter cores of the secondary systems in our 10:1 mergers remain intact in near-circular orbits within 50 kpc of the remnant’s centre until the end of our simulations. This is not surprising since the sinking time-scale due to dynamical friction is the longest. As a result, we measure small-amplitude (< 20 kpc) oscillations in our 10:1 merger remnants. These motions are most coherent in the head-on case and involve bulk velocities of $< 100 \text{ km s}^{-1}$.

4 EVOLUTION OF DISTURBED MORPHOLOGY

With the general evolution of merging systems accounted for, we now discuss the time-scales by which evidence of the merger event disappears. A determination of the degree to which a cluster is

disturbed has generally taken three approaches in observational studies: visual inspection, measurement of displacements of the X-ray peak from the X-ray or mass centroid of the system, and power-ratio analyses of the system's X-ray surface brightness. In this section, we will apply each of these approaches in turn to establish when our simulated merger remnants would return to apparently undisturbed states. In the section which follows, we will compare these time-scales to more formal and physical measures of the system's dynamical state.

4.1 Simulated observations

In evaluating the effectiveness of quantitative measures of our remnants' dynamical state, we will use as a fiducial the time when our systems appear relaxed under reasonable observational circumstances. We determine this time by visual judgement of our simulated *Chandra* observations and of the uniformity of their isophotes; a process we facilitate by generating unsharp masked images with smoothing kernel sizes of 1.5 and 15 arcsec (Chatzikos, Sarazin & Kempner 2006). This is all done in projections normal to the plane of the orbit. A substructure is likely to be most identifiable in this projection and, thus, this measure represents a conservative upper limit on the time when the system would look disturbed. We have studied how our results change if evaluation is performed in x - and y -projections and find that the systems can look undisturbed as much as 2 Gyr earlier.

Generally speaking, evidence of substructure disappears first from the simulated images, then from the unsharp masked images and finally in the structure of the X-ray isophotes. The delay between the dissolving of a substructure in the images and the regularization of their isophotes can take several Gyr and varies significantly from case to case. Since the isophotes are the most-sensitive measure, the system will be said to appear relaxed at t_{relax} when all isophotes brighter than six times the background level (i.e. all but the faintest in Figs 1, 4 and 7) appear regular by a visual inspection. These times are tabulated in Table 2.

In one case (1:1 head-on), minor complications arose during this procedure. Although the simulated observations appear regular and relaxed by $t \sim 3.8$ Gyr, their isophotes remain significantly boxy until $t \sim 4.4$ Gyr. Some evidence of this boxy morphology lingers until the end of the simulation making a clear determination of t_{relax} difficult.

4.2 Centroid shifts

The apparent displacement of a system's core from the centre of the system has been used as a measure of dynamical disequilibrium by several authors and has been implemented in several different ways. For instance, Mohr, Fabricant & Geller (1993) quantified X-ray centroid shifts (w_x) using the offset of a system's X-ray surface brightness peak from its surface brightness centroid (integrated within a projected radius r_p). They argued that systems for which w_x is dependent on r_p are dynamically young. For a sample of 46 *Einstein* observed clusters, they obtained an average value $\langle w_x \rangle = 62$ kpc with 71 per cent of systems having $w_x > 0$ at a 3σ or greater significance. These results generally conform with more recent results of Kolokotronis et al. (2001) who found $\langle w_x \rangle = 83$ kpc for a sample of 22 *ROSAT*-observed systems.

We have chosen to quantify the centroid variance of our systems using the method employed by O'Hara et al. (2006). This approach determines the offset between the X-ray peak and centroid as a function of $r_p \lesssim R_{500}$ and assigns to w_x the rms of the resulting

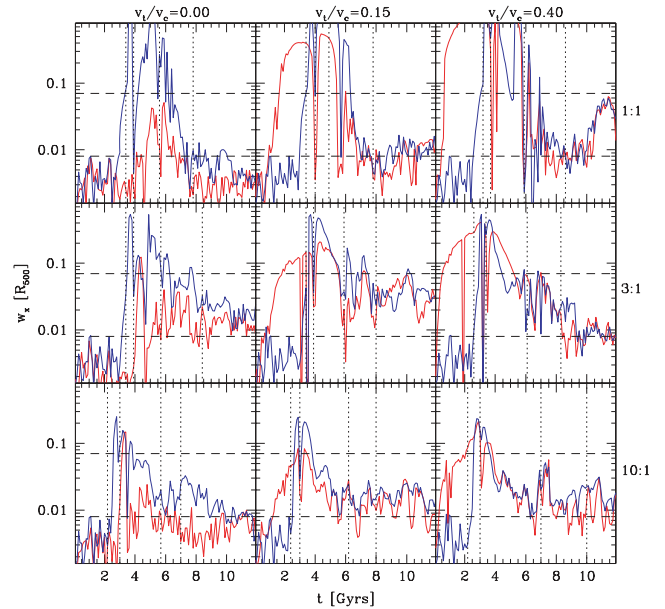


Figure 11. Evolution of the centroid variance computed from the X-ray surface brightness maps in the x (line of sight) and z (orthogonal) projections (thin red lines and thick blue lines respectively). The horizontal dashed lines indicate the range of centroid shifts observed by O'Hara et al. (2006), whereas the vertical dotted lines indicate (from left- to right-hand panel) t_0 , t_{closest} , t_{accrete} and t_{relax} . Centroids are computed within 1.2 Mpc (roughly the initial R_{500} of the primary). The centroid statistic traces the qualitative evolution of the merging system very well. The statistic takes on its maximum values when the system is in its most disturbed state and typically, it falls off between t_{accrete} and t_{relax} as the system recovers. Over the course of the merger, the statistic spans the entire range of values found by O'Hara et al. (2006) in an analysis of 45 clusters. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_Paper1.)

profile. We determine this profile by computing the centroid within a circular aperture of size $r_p = R_{500}$ and then reducing its size by 5 per cent until it reaches $r_p \leq 0.05 R_{500}$. We have experimented with various details of this procedure and find that it is essential to exclude the bright central core if the statistic is to detect subtle distortions. Hence, we excise the central $r_p = 30$ kpc when computing centroids (but retain it when we compute the position of the peak).

In Fig. 11, we plot the time dependence of w_x measured in this way for each of our simulations in x - and z -projections. The evolution of this quantity in y -projections is very similar to its evolution in the z -projection and is omitted to clarify the plot. We also indicate the range of typical values observed by O'Hara et al. (2006) in their study of 45 *ROSAT*-observed clusters ($w_x = 0.008\text{--}0.07 R_{500}$, with five extreme points excluded) as well as the times of several important stages in each system's evolution.

As a product of our idealized initial conditions, all our systems start with values of w_x less than the lower bound of the observations. In off-axis cases, it immediately begins to increase in x -projections as the cores slowly move apart in projection. This effect grows more significant with increasing v_t/V_c as we would expect. In z -projections, no increase occurs until $\sim t_0$ when the body of the secondary enters the $R_{500} \sim 1.2$ Mpc aperture used for our calculations. In the off-axis cases, the statistic for the x - and z -projections are virtually indistinguishable following t_{closest} . In the head-on cases, the signal is much lower when the merger proceeds along the line of sight. Typically, the statistic drops sharply when the primary and the secondary are close together, as in the line-of-sight/head-on

case and more generally at t_{closest} and t_{accrete} . This is due to the fact that the centroid shift in all the apertures is nearly the same. In detecting disturbances, the centroid variance method depends on the displacement varying as the aperture is reduced, and successively more distant surface brightness fluctuations are excluded from consideration.

Our 1:1 mergers evolve to values of w_x much larger than those observed for a duration of ~ 4 Gyr. During this time, the system is a distinct binary and is not representative of any of the systems present in the O’Hara et al. (2006) catalogue. Following t_{accrete} , w_x declines rapidly and reaches a roughly constant level near the minimum observed value ~ 1 Gyr before t_{relax} . In our $v_t/V_c = 0.4$ case, there is a subsequent rise at late times due to a late accretion of material. It is likely that the strength of this rise would not be as significant in a system hosting realistic substructure where the effect of late-accreting material from multiple mergers would tend to cancel their individual effects. For this reason, we will consider the system to have relaxed according to this measure ~ 1 Gyr prior to t_{relax} in this case but acknowledge that more study is required to understand clearly the role long-lasting substructure has on w_x in realistic environments.

In the 3:1 cases, we see a similar rise after t_0 to values greater than the maximum observed but lasting for a much shorter duration (~ 2 Gyr). Following t_{accrete} , w_x oscillates erratically amongst the highest values observed by O’Hara et al. (2006). It slowly declines to the minimum observed value by the end of the simulations in the head-on and $v_t/V_c = 0.4$ cases but remains high in the $v_t/V_c = 0.15$ case. The cause of this slowed or absent decline in w_x following t_{accrete} is a sustained shift of the centroid in the central $0.5R_{500}$. This is due to oscillations in the remnant’s central dark matter distribution.

Lastly, our 10:1 cases are disturbed to high levels of w_x for ~ 4 Gyr following t_0 and for ~ 1 Gyr following t_{accrete} in the $v_t/V_c = 0.4$ case (due to the reduced disruption of the core). They oscillate just above the minimum observed value, otherwise.

Thus, our systems appear exceptionally disturbed to our centroid variance measure for ~ 4 Gyr between t_{closest} and t_{accrete} when they generally appear as two distinct clusters. Immediately following t_{accrete} for our major/moderate (1:1 and 3:1) mergers and ~ 2 Gyr after t_{closest} for our 10:1 mergers (when the systems appear as single remnants), our simulations all exhibit values of w_x similar to the maximum observed by O’Hara et al. (2006) (with the natural exception of the head-on cases in x -projections). In 3:1 cases, w_x remains high until well past t_{relax} . Our equal-mass and 10:1 mergers quickly relax to levels comparable to the minimum values observed by O’Hara et al. (2006). Referring to Table 2, we can see that for a cluster observed at $z = 0.1$, most 10:1 mergers occurring before $z \sim 0.5$ would have evolved past t_{accrete} and will thus yield $w_x \sim 0.01R_{500}$. This fact combined with the expectation that most clusters should have experienced such an event naturally explains the observed minimum of this statistic.

We have also computed this statistic for SZ maps (w_{SZ}) of our systems. We find that the evolution of w_{SZ} is nearly identical to that of w_x , with both producing very similar maximum shifts and periods during which w_x is significantly higher than $0.1R_{500}$.

Another approach to measuring centroid shifts has been implemented by Smith et al. (2005) who measured the shift between the peak in the X-ray surface brightness and the centre of projected mass of the system (Δr), as determined from weak-lensing maps. For a sample of 10 clusters, they found $\langle \Delta r \rangle = 55$ kpc ($\sim 0.045R_{500}$ for our systems) with 70 per cent of their systems having $\Delta r > 0$ at a 3σ or greater significance. In Fig. 12, we present the evolution of this

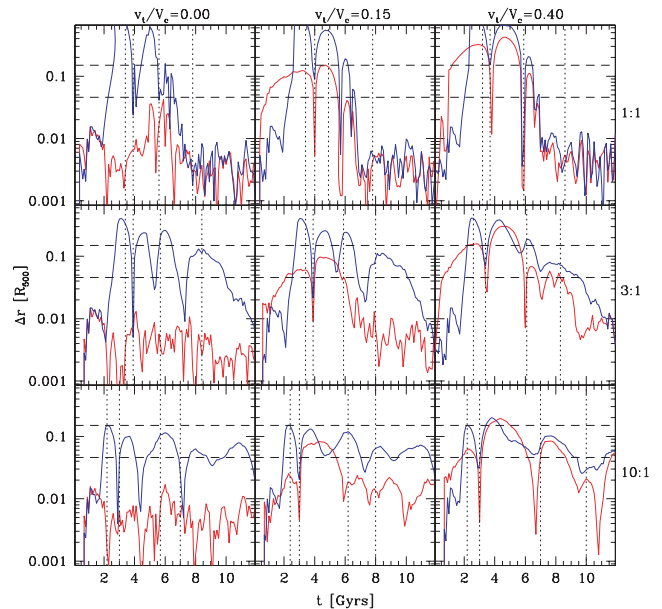


Figure 12. The time-evolution of the displacement between the X-ray peak and the centroid of the projected mass maps in the x (line of sight) and z (orthogonal) projections (thin red lines and thick blue lines, respectively). The horizontal dashed lines indicate the mean and maximum centroid shifts measured by Smith et al. (2005) (normalized by R_{500} of our system), whereas the vertical dotted lines indicate (from left- to right-hand panel) t_0 , t_{closest} , t_{accrete} and t_{relax} . In the case of massive (1:1) mergers, the statistic behaves like w_x and tracks the morphological evolution of the system over the course of the merger. For moderate and minor mergers, the statistic remains high well past t_{relax} although the system is close to being virialized for $t > t_{\text{relax}}$. This signal is entirely due to low-mass remnant dark matter substructure that keeps jiggling the mass centroid. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_Paper1.)

statistic for our simulations. Again, we plot only x and z -projections due to the similarity of results in y - and z -projections.

Examining Fig. 12, we see that for the 1:1 mergers, this statistic drops precipitously after t_{accrete} (similarly to w_x) and sustains similar values after t_{relax} . For the 3:1 mergers, however, there is a long-lived late-time shift in z -projections which does not reach maximum amplitude until t_{relax} and does not reduce to $\Delta r \sim 0.01R_{500}$ until shortly before the end of our simulations. A similar but even longer-lived shift persists in our 10:1 mergers which fail to sustain $\Delta r \lesssim 0.01R_{500}$ for more than 0.5 Gyr in any projection for any case. These sustained shifts are due to central dark matter oscillations (see Section 3.4).

Given the relatively high frequency of 10:1 mergers and the long duration of their impact on Δr , we expect that a few systems should exhibit $\Delta r < 0.045R_{500}$ (the mean value for our 10:1 $v_t/V_c = 0.15$ merger after t_{relax}) and, therefore, it is surprising that Smith et al. (2005) found any systems consistent with $\Delta r = 0$. However, if projection effects are considered, it may be that some or all the three systems to which they assigned relaxed morphologies using this statistic are being seen with their X-ray peak merely in projection against their centre of mass. Alternatively, long-lived substructure from multiple past minor mergers may compete against each other in their influence on the centre of mass, reducing its overall offset from the X-ray peak. Further study of this statistic and its efficacy as an indicator of disturbed systems in a full cosmological context is clearly necessary.

4.3 Power ratio morphology

The use of surface brightness moment decomposition for quantifying the degree to which systems appear relaxed was first introduced by Buote & Tsai (1995) and has since been utilized in several observational (Buote & Tsai 1996; Jeltema et al. 2005) and theoretical studies (Thomas et al. 1998; O'Hara et al. 2006). This method uses power ratios (P_m/P_0) computed from moments of the system's surface brightness distribution; $\Sigma(x')$, where $x' = (R, \phi)$ is in polar coordinates. Following the procedure of (Jeltema et al. 2005, hereafter J05), we have applied this procedure to our simulations computing power ratios from

$$P_0(R) = [a_0 \ln(R)]^2, \quad (2)$$

$$P_m(R) = \frac{1}{2m^2 R^{2m}} (a_m^2 + b_m^2), \quad (3)$$

where a_m and b_m are moments of the distribution given by

$$a_m(R) = \int_{R' \leq R} \Sigma(x')(R')^m \cos m\phi' d^2x' \quad (4)$$

and

$$b_m(R) = \int_{R' \leq R} \Sigma(x')(R')^m \sin m\phi' d^2x', \quad (5)$$

respectively. These statistics are usually normalized by P_0 (i.e. expressed as P_m/P_0), a measure of the total luminosity of the system.

We have studied the effects of removing the central cores of our simulated clusters when computing these statistics. We find this to be particularly necessary when the system is only subtly disturbed. At such times, the contribution of any persisting structure in $\Sigma(x')$ to equations (4) and (5) becomes overwhelmed by the bright and centrally concentrated cores of the merging systems. When we exclude the central cores from our calculations of P_m we find a significant increase in amplitude and scatter. For the discussion which follows, we have computed power ratios with the central 30 kpc $\sim 0.025R_{500}$ excised. We have confirmed that there is little effect on our conclusions if this radius is reduced to 15 kpc or increased to 50 kpc.

In Fig. 13, we plot the time evolution of P_2/P_0 , P_3/P_0 and P_4/P_0 in a 0.5-Mpc z -projected aperture for each of our mergers. Buote & Tsai (1995) found that model systems with power ratios identically equal to zero can be assigned significant values (a few times 10^{-7} for P_3/P_0 , for instance) when realistic noise is added to simulated X-ray images. Based on their analysis of an observed sample of clusters, J05 found that median noise contributions resulted in values for P_2/P_0 , P_3/P_0 and P_4/P_0 of 7.5×10^{-8} , 1.9×10^{-8} and 9.4×10^{-9} , respectively. We indicate these levels in the plot. The plot illustrates that in the absence of noise, the values of the power ratios for the mergers are typically well below the median noise levels, except when the systems are in their most disturbed state. In practice, the values assigned to a relatively relaxed-looking cluster will be highly dependent on the quality of the individual observations. In fact, the lowest values of P_N/P_0 quoted by J05 are a factor of ~ 10 below the median noise levels. In what follows, we will loosely refer to the median noise levels reported by J05 as the 'observable levels' of each statistic. We will treat these levels as a reasonable fiducial when determining the point at which our systems would be judged as undisturbed by this approach.

The evolution of P_3/P_0 and P_4/P_0 is very similar; the latter behaves more or less like a scaled version of the former. In the approach to the first pericentric passage at t_{closest} , both power ratios experience a brief sharp spike which exceeds observable levels in

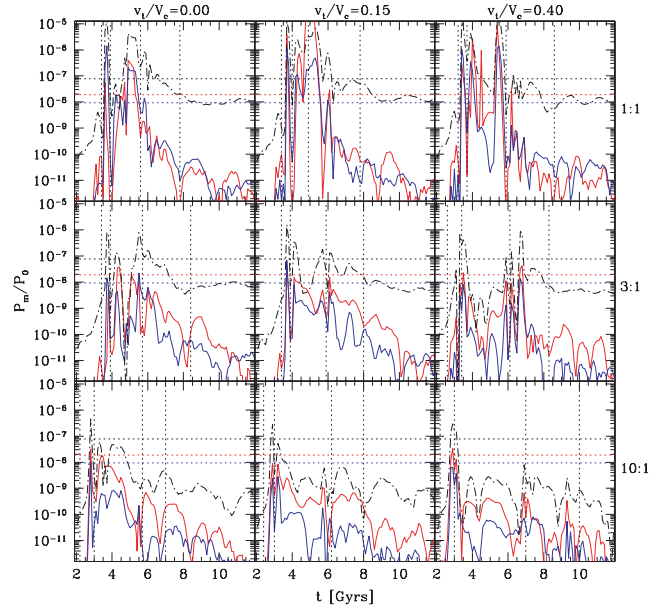


Figure 13. The time-evolution of the X-ray surface brightness power ratios computed within a 0.5-Mpc aperture in the z -projection, the projection in which the merger-induced disturbances are the most apparent. The dotted horizontal lines depict the median noise levels for the observational sample analysed by J05 for (in descending order) P_2/P_0 , P_3/P_0 and P_4/P_0 . The dash-dotted black, thick red and blue lines correspond to P_2/P_0 , P_3/P_0 and P_4/P_0 , respectively. Vertical dotted lines represent (from left-hand to right-hand panel) t_0 , t_{closest} , t_{accrete} and t_{relax} . The power ratios can easily pick out the very short-duration highly-disturbed states but for the most part the amplitudes tend to be comparable to or less than the median noise levels for the J05 sample of clusters. See also Fig. 14. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_Paper1.)

all cases, though just barely in the 3:1 and 10:1 mergers. This is followed by a climb to a plateau or a broad peak, during which time the signal remains at or below the observable levels except in the 1:1 case, and a fall-off at $\sim t_{\text{accrete}} \pm 1$ Gyr. The amplitudes of the initial spike and of the plateau/broad peak are correlated with the secondary's mass, with the most-massive merger generating the greatest signal. There do not appear to be any clearly discernible correlations with impact parameter. Once the signal falls below observable levels after the second drop, it remains so for the duration of the simulation under all conditions.

The evolution of P_2/P_0 is different from that of P_3/P_0 and P_4/P_0 . Like the latter two, the signal briefly spikes above the noise level at t_{closest} but rapidly drops below. It exceeds the noise level again at t_{accrete} for $\lesssim 2$ Gyr and then generally only for the mergers with mass ratios greater than 3:1. (At 3:1, the second spike just exceeds the observable level). Afterwards, it stabilizes at values far below observable levels, changing very little after t_{relax} . For the major/moderate (1:1 and 3:1) mergers, P_2/P_0 settles at $\sim 10^{-8}$, whereas for our 10:1 mergers, the power ratio hovers at values of about $\sim 10^{-9}$.

In their study of the redshift evolution of power ratios, J05 found that between $z = 0.5$ and 0.9 (their high- z sample) and $z < 0.5$ (their low- z sample), the P_3/P_0 and P_4/P_0 ratios show statistically significant declines, whereas the P_2/P_0 ratio shows no significant change. Furthermore, observed values of P_2/P_0 are confined to a range more narrow than P_3/P_0 or P_4/P_0 . Our simulations reproduce these trends but with a much lower normalization. Further study is required to understand if this discrepancy is a product of

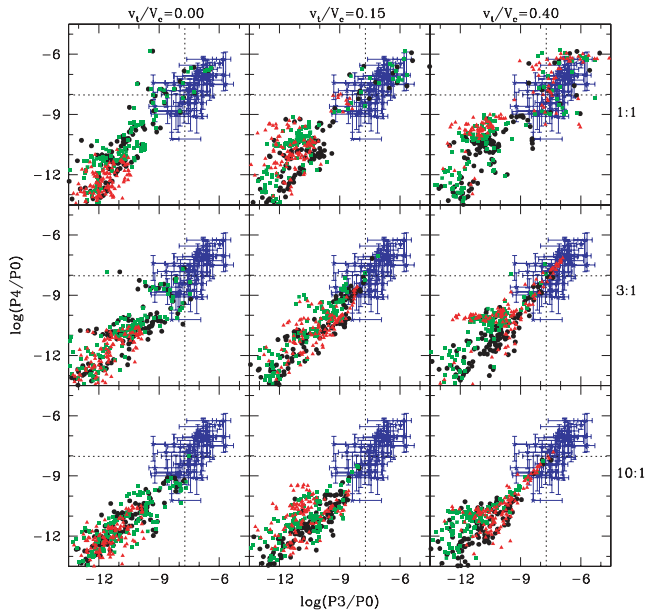


Figure 14. Plot of P_4/P_0 versus P_3/P_0 for our simulations measured at different time snapshots over the course of the merger, within an aperture of 0.5 Mpc. The data of J05 are plotted in blue with our simulations plotted as the red triangles, green squares and black circles for x -, y - and z -projections, respectively. This combination of power ratios yields a signal above the median noise level of J05 sample (shown as the horizontal and vertical lines) only when system is caught in the short-lived highly disturbed state. It is most sensitive to disturbances induced by highly off-axis mergers and least sensitive to line-of-sight mergers. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

noise effects or our idealized initial conditions and lack of cosmological substructure. Since P_2/P_0 is the power ratio most sensitive to the large-scale ellipticity of the system, it would be interesting to determine if more realistic triaxial initial conditions would produce a similar narrow range of near-constant final P_2/P_0 but with a higher normalization comparable to that observed. As it stands, our results suggest that the power ratios are most sensitive to gross disturbances such as those that arise early in the merging process.

Correlations between different power ratios have generally been used to identify disturbed systems and to study the evolution of cluster substructure. Here, we focus our attention on the P_4/P_0 – P_3/P_0 plane. In Fig. 14, we present a comparison in this plane between the observations of J05 and our simulations computed within apertures of 0.5 Mpc. Results computed in x -, y - and z -projections are presented with the red triangles, green squares and black circles, respectively. In Fig. 14, we can see that the observed trends in normalization, maximum amplitude and scatter are well reproduced, though our measurements cluster at values of P_3/P_0 and P_4/P_0 well below the observations. These two power ratios return values above the observable levels only during the highly disturbed phases of the merger, and during the initial stages of the off-axis mergers.

We have also examined the distribution of points in the P_4/P_0 – P_3/P_0 plane, where the power ratios are computed within a larger aperture of radius $R_{500} \sim 1.2$ Mpc. With the exception of some reduction in the scatter, the results are very similar to those presented in Fig. 14

Finally, we also applied the power ratio analysis to total projected mass and SZ maps to examine the efficacy of this approach to

measuring substructure through weak-lensing and microwave observations. The results were indistinguishable from the X-ray results, with amplitudes of the P_3/P_0 and P_4/P_0 for the projected mass maps being lower.

4.4 Comparison of disturbed morphology measures

We have examined several methods of determining the dynamical state of galaxy clusters. In Figs 11–13, we present the time evolution of w_x , Δr and P_m/P_0 . In each case, we indicate the moment when the isophotes of our simulated 50-ks $z = 0.1$ *Chandra* observations appear undisturbed as a fiducial reference for the sensitivity of each approach.

We find that while the centroid shift and power ratio approaches are both capable of identifying either highly disturbed systems or systems with significant, well-defined substructures, the w_x is more sensitive to subtler disturbances and its time evolution tracks the visual appearance as well as the dynamical state of the merging system quite well. The amplitude of the power ratios is relatively low when the system is not highly perturbed (for example, the analysis barely registers 10:1 mergers) and appears to be highly susceptible to noise in the X-ray images. More study is required to understand in exactly what way realistic noise affects the sensitivity of the P_m/P_0 statistics.

Our experiments with the Δr statistic introduced by Smith et al. (2005) suggest that it is very sensitive to long lived substructures and oscillating modes in the dark matter haloes of merger remnants. The statistic yields a signal even when, dynamically, the system is within 2 per cent of being relaxed as defined by our virial indicator (see Section 5 and Fig. 15). However, it is likely that our idealized mergers are exaggerating this sensitivity. More

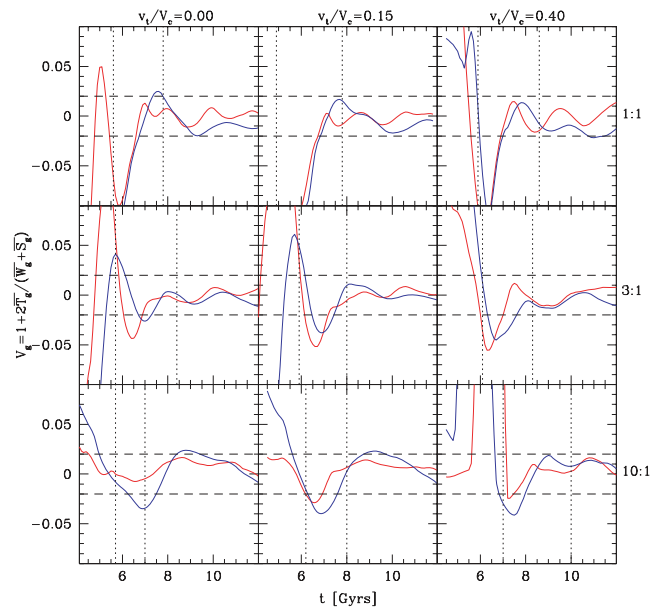


Figure 15. The time-evolution of the virial parameter computed over a volume of radius R_{500} (thick red) and R_{200} (blue) for the gaseous component of our simulations. The evolution of the *gas* virial parameters for these two volumes is very similar. The horizontal dashed lines indicate our 2 per cent virialization criteria. The vertical dotted lines indicate t_{accrete} and t_{relax} for each case. If we define the system to be relaxed when the virial parameter drops to and remains at $|V| < 0.02$, then the gas component typically relaxes halfway between t_{accrete} and t_{relax} . (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

study with cosmological simulations which include a proper account of halo substructure should be conducted to determine exactly how effective Δr is relative to centroid shift and power ratio measures.

In summary, for clusters at $z = 0.1$, the eye is remarkably adept at identifying disturbed morphologies in deep *Chandra* images but, quantitatively, we find that the centroid variance, w_x , is the most effective measure of a system's dynamical state.

5 RELAXATION

Is a system which appears undisturbed actually in a relaxed state? This is commonly assumed to be the case in studies which have selected compact cool core systems with regular and symmetric isophotes to represent equilibrium systems. However, all clusters are a product of mergers and even though their dynamical time-scales are short (~ 1.5 Gyr at R_{200}), the time-scales by which bound substructures become disrupted and dissolve into the accreting halo can be much longer, as illustrated in the preceding sections. As a result, a merger remnant can take significant lengths of time to reach a proper equilibrium state, perhaps even longer than the typical interval separating merger events.

In practical terms, the point at which a system appears undisturbed depends on the state of the system's baryonic component whose signatures of disturbance can be diluted by observational limitations. Furthermore, the gaseous component is subject to disruptive gas dynamical forces which do not act on the dynamically dominant dark matter component, perhaps erasing evidence of substructure faster than it loses dynamical relevance. Hence, it is natural to suspect a discrepancy between when a system appears relaxed and when it is formally so.

In this section, we will quantify the relaxation of our merger remnants by studying their recovery towards a virialized and hydrostatic state of equilibrium. We will compare the time-scales by which they do this to the point at which the system would look relaxed under typical observational circumstances. We will find that our systems typically achieve a virialized state approximately when they appear relaxed but continue to exhibit deviations from hydrostatic equilibrium at the level of 10–20 per cent until the end of our simulations.

5.1 Virialization

To study the virialization of our systems, we employ the scalar virial theorem (see Collins 1978; Spitzer 1978; Binney & Tremaine 1987, for good reviews) which states that

$$\frac{1}{2} \frac{d^2 I}{dt^2} = 2T + W + S \quad (6)$$

where $T = K + U$ is the sum of the system's kinetic (K) and thermal (U) energies, $W = \sum_{i=1}^N \mathbf{F}_i \cdot \mathbf{r}_i$ is the 'virial', and I is the system's moment of inertia, all computed within a specified volume. The term denoted by $S = S_g + S_d$ is a surface pressure term integrated over the bounding surface of the volume, with contributions S_g and S_d due to the gaseous and collisionless (dark matter and stellar) components given by

$$S_g = - \oint P r dA \quad (7)$$

and

$$S_d = - \oint \rho_d \sigma_d^2 dA, \quad (8)$$

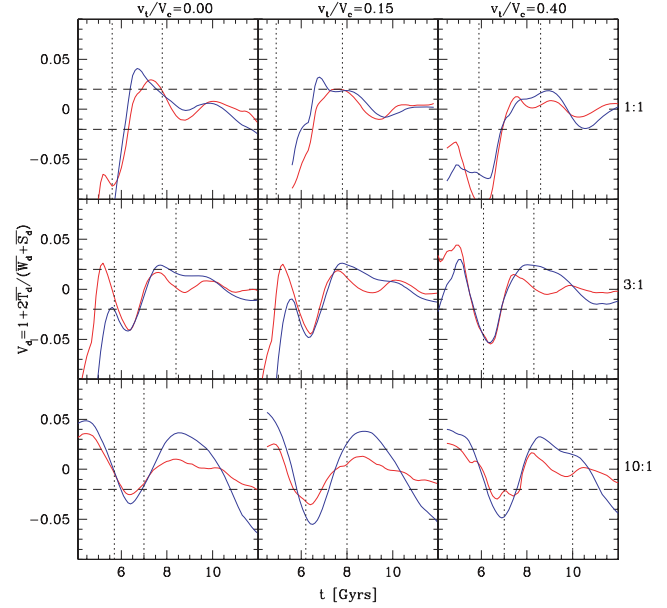


Figure 16. Same as in Fig. 15 but depicting the virialization of the dark matter component of our simulations. The dark matter component typically relaxes slightly later than the gas component and the oscillations in V damp out more slowly. Also, the central regions of the systems relax faster than the full cluster. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

respectively, where $P = nkT$ is the pressure of the gas with a number density n and temperature T , and σ_d and ρ_d denote the velocity dispersion normal to the surface and mass density of the collisionless component, respectively.

Averaged over an interval in which the system is periodic (or instantaneously for a steady-state system), the left-hand side of equation (6) vanishes. Furthermore, when integrated over the entirety of an isolated system, S becomes zero and equation (6) takes its popular form

$$2T + W = 0. \quad (9)$$

It is commonly taken for granted that W represents the gravitational binding energy of the system but it must be emphasized that this is strictly true only when computed over the totality of an isolated system. In general, W is not equivalent to the gravitational binding energy within r .

In Figs 15 and 16, we present the temporal dependence of the virial disequilibrium parameter (Ricker 1998) for the gaseous and dark matter components of our evolving merger remnants following t_{accrete} (when the system can be considered to be a single remnant). (Although the baryonic component's contribution to the virial parameter of the total system is negligible, it is interesting to see if the observable gaseous component virializes on the same time-scales as the dark matter component.) This virial parameter is defined as follows:

$$V = 1 + \frac{2\bar{T}}{\bar{W} + \bar{S}}, \quad (10)$$

where \bar{T} , \bar{W} and \bar{S} are time-averages computed to account for the fact that the canonical form of the virial theorem presented in equation (9) holds only when the quantities in equation (6) are averaged over an interval in which the system is periodic. This is done using a dynamical time $t_{\text{dyn}} = \sqrt{3\pi/16G\Delta\rho_c}$ (where Δ is the overdensity being considered) for quantities involving the collisionless

component and the local isothermal sound crossing time $t_{sc} = r \sqrt{\mu m_p / kT}$ for quantities involving the gaseous component. Although the system may not be strictly periodic over these timescales, we have confirmed that the term involving I in equation (6) contributes negligibly during the period we present in Figs 15 and 16. Following RS01, we select the moment of virialization to be when the system sustains a value of $|V| < 0.02$.

Overall, we find that the virial parameters for the gas and the dark matter track each other's general trends although the oscillations in the gas virial parameter tend to be of slightly lower amplitude and damp more quickly. As a result, the gas component typically relaxes (i.e. the gas virial parameter drops to and remains at $|V| < 0.02$) earlier than the dark matter component. There is not much difference in the relaxation time of gas within R_{500} and R_{200} . On the other hand, the dark matter distribution within R_{500} relaxes earlier than the full cluster.

In more detail, our 1:1 mergers all virialize by t_{relax} . The gaseous component generally virializes ~ 0.5 Gyr before the dark matter component which virializes almost exactly at t_{relax} in all cases. Thus, the system is virialized approximately 4.5–5.5 Gyr (or three to four dynamical times) after the secondary initially crosses R_{200} of the primary (in good agreement with the findings of previous studies, e.g. Roettiger et al. 1997). The virialization of our 3:1 mergers proceeds similarly to our 1:1 mergers for the dark matter. In the 10:1 case, the gaseous component within R_{500} achieves virialization at or well before our 1:1 and 3:1 mergers: immediately after $t_{accrete}$ in the off-axis cases and well before in the head-on case. Within R_{200} , however, our 10:1 gaseous components reach virialization much later (~ 2 Gyr) than our 1:1 and 3:1 cases. The dark matter behaves similarly. Within R_{500} , the system is virialized at or before t_{relax} , whereas within R_{200} , the system never reaches our virialization criteria. In these cases, the system sustains a state where V_d oscillates with an amplitude of ~ 5 per cent until the end of our simulations. The retarded onset or absence of virialization within R_{200} for our 10:1 mergers is a result of late infall of material dispersed beyond R_{200} during the merger.

5.2 Hydrostatic equilibrium

Another independent measure of the equilibrium status of our merger remnants is the dynamical criterion of hydrostatic equilibrium. For a pressure-supported medium in a gravitational potential, hydrostatic equilibrium implies

$$\rho^{-1} \frac{dP}{dr} = \frac{GM(<r)}{r^2}. \quad (11)$$

Given that X-ray-derived mass determinations of clusters assume that this condition holds, its validity following mergers is of significant importance. Recent studies have found evidence suggesting that clusters for which hydrostatic equilibrium can be accurately assumed are rare but no consideration has yet been given to whether systems can fail to be in hydrostatic equilibrium while appearing undisturbed. In Fig. 17, we plot the evolving hydrostatic disequilibrium parameter of our merger remnants following $t_{accrete}$ given by

$$H = 1 + \frac{\rho^{-1} (dP/dr)}{r^{-2} GM(<r)}. \quad (12)$$

The evolution of hydrostatic disequilibrium for all our systems follows the same qualitative pattern. Shortly before $t_{accrete}$, at both R_{500} and R_{200} , they experience significant positive excursions in H as the secondary core accretes on to the remnant core. Following

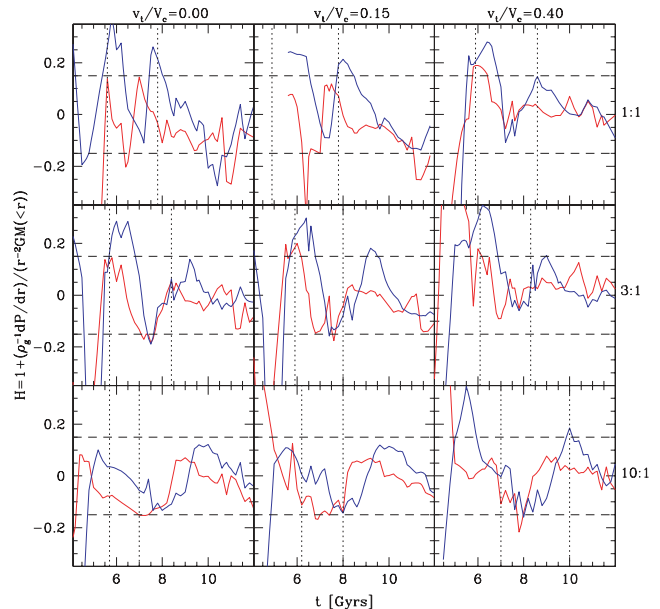


Figure 17. Hydrostatic disequilibrium parameter measured at R_{500} (thick red) and R_{200} (blue). The horizontal dashed lines indicate 15 per cent equilibrium (the criteria used for t_{hydro} in Table 2). The vertical dotted lines indicate $t_{accrete}$ and t_{relax} for each case. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_Paper1.)

this, H is seen to oscillate with damped amplitude in each case with the oscillations at R_{200} lagging in phase behind those at R_{500} by ~ 0.5 Gyr. The phase of these oscillations is generally such that at R_{200} , a period of positive H lasting ~ 2 Gyr with an amplitude of 10–20 per cent, occurs at or shortly after $t_{accrete}$. At R_{500} , slightly lower-amplitude (typically ~ 10 –20 per cent) and less-coherent oscillations persist until the end of our simulations.

Regular disruptions of hydrostatic equilibrium such as those depicted in Fig. 17 could translate into discrepancies in X-ray mass measurements obtained from methods which assume the validity of equation (11). We will examine this issue in more detail in Poole et al. (in preparation) where we will discuss the effects of mergers on global cluster observables and scaling relations.

5.3 Comparison of apparent and formal states of relaxation

In Section 4, we found that our merger remnants generally appear relaxed through centroid (our preferred method) and power ratio measures, once the isophotes of our simulated $z = 0.1$ *Chandra* observations appear undisturbed at t_{relax} .

In Table 2, we list the times at which our systems are formally virialized (t_{virial} ; measured for the dark matter) or in hydrostatic equilibrium (t_{hydro} ; taken to be when the system sustains $|H| < 0.15$) at R_{500} . Our systems are generally virialized (both the gas and the dark matter) within R_{500} at or near t_{relax} , whereas late accretion of material renders the system somewhat less virialized (5 per cent versus our 2 per cent virialization criterion) at R_{200} in our 10:1 mergers at t_{relax} . We also list the redshifts at which the secondary would have to cross R_{200} of the primary in order to be seen in each phase at redshifts of $z = 0.1$ and 0.5. We can see from this how unlikely virialized or hydrostatic clusters should be at $z = 0.5$.

We thus find that our merger remnants are generally virialized at or shortly ($\lesssim 2$ Gyr) after appearing relaxed to a visual inspection. However, even at this time merger remnants are adiabatically

oscillating, exchanging energy between thermal and kinetic components. They are in hydrostatic equilibrium only at the 10–20 per cent level at this time and sustain this level of hydrostatic disequilibrium with little change after appearing relaxed.

6 TRANSIENT STRUCTURES

Our simulations reveal that the phenomena generally referred to as ‘cold fronts’ consist of several classes of transient structures formed by the disruption of compact cool cores in off-axis mergers. Previous theoretical studies of cold-front production have focused primarily on the disruption of the secondary’s core but our analysis reveals that both cores can be involved. Several other transient phenomena, such as core surface brightness discontinuities and oscillations, are naturally formed in the process as well. In this section, we will discuss in more detail the processes driving the formation of these structures, noting where possible the occurrence of each in presently published observations of cluster mergers.

6.1 Bridges

At two points during a cluster merger, luminous bridges connecting the interacting systems can be formed. In the first, the outer atmospheres of the merging clusters become compressed on the incident side of the collision during pre-interaction. The resulting increase in gas density and temperature between the systems leads to enhanced surface brightness between the two systems and the formation of a luminous bridge. This effect is short lived (~ 0.5 Gyr in the 1:1 cases, less in others) but has been observed in several systems including A399/401 (Sakellou & Ponman 2004) and A1750 (Belsole et al. 2005).

As discussed in Section 3.3, material stripped by ram pressure from the interacting clusters becomes dispersed, forming comet-like tails which trail their surviving cores following t_{closest} . Due to the density gradients of the systems they are passing through and the scaling of ram pressure with the density of the flowing material, this process is more efficient on the side of each core incident to the collision. As a result, overlapping enhancements of stripped material form behind each core, producing a luminous bridge which joins the two systems.

Following t_{closest} , material from these regions moving in the plane of the orbit is driven together. It becomes particularly concentrated in a curved planar feature oriented normal to the plane of the orbit. As a result, the surface brightness of this bridge is most bright and concentrated in z -projections. In x -projections, it is not discernible and in y -projections it is significantly wider and more diffuse. The cores of both clusters appear disturbed at these times, distinguishing this process from the one acting during pre-interaction.

The dependence of the brightness and shape of the bridge could be used as a useful cue when interpreting the orientations of observed merging systems. In A1758 (David & Kempner 2004), for instance, we see an excellent example of a system apparently exhibiting a post-interaction bridge. The two merging systems in this case (A1758N and A1758S) both have disturbed cores and there is an obvious bridge connecting them. The width of the bridge is more than 1.2 Mpc, suggesting that the system may be significantly inclined to the plane of the sky. Other systems exhibiting similar morphologies include A1644 (Reiprich et al. 2004), A754 (Henry, Finoguenov & Briel 2004) and A115 (Gutierrez & Krawczynski 2005).

6.2 Plumes

In Section 3.3, we noted that in all the off-axis cases we have studied, outwardly propagating collimated plumes of primary and secondary core materials are produced between t_{closest} and t_{apo} . Several mechanisms are involved in the production of these structures; a few of which have been discussed previously in the literature. Mathis et al. (2005) provided a good summary of theoretical research involving the disruption of cold cores. Their work supports the claims of Heinz et al. (2003) who illustrated the important influence of ram-pressure stripping during the disruption of merging cluster cores. However, they emphasized that other processes are likely essential to the formation of cold fronts.

Our study confirms and expands on this claim. Although ram pressure is certainly important for the disruption of both clusters, it is primarily only responsible for the stripping of material roughly beyond $R_{2500} \sim 500$ kpc (moderately high-entropy material). It does not lead to the prominent low-entropy radial plumes produced in our simulations. In our simulated *Chandra* images, the period during which ram-pressure-stripped material is bright enough to produce an observable ‘comet-like’ surface brightness feature is brief (~ 0.5 Gyr) and occurs only at or shortly after t_{closest} . A disturbed merging system spends most of its time at or near apocentric passage. In our simulations, material stripped by ram pressure has dispersed and is no longer apparent in surface brightness by that point. Bright features of displaced core material are produced primarily by other mechanisms during this longer lived phase.

In Fig. 18, we illustrate the production of three low-entropy plumes generated from the cores of the primary (Fig. 18a) and secondary (Fig. 18b) with a series of entropy maps covering the evolution of our 3:1 $v_i/V_c = 0.15$ simulation during first pericentric passage (Fig. 18a) and apocentric passage (Fig. 18b). In these figures, the secondary enters from the bottom left-hand side and passes underneath and near to the core of the primary.

In Fig. 18(a), we see that two plume-like structures (labelled ‘A’ and ‘B’) are produced from the primary core. The one labelled ‘A’ is produced on the side roughly opposite to the point of closest contact with the secondary core at t_{closest} . This feature is generated from material which has become confined in a narrow structure by the convergence of the shock as it passes the primary core. This behaviour is produced by refraction of the shock due to the decline in the primary core’s sound speed into the centre.

The other two plumes (‘B’ and ‘C’ in Fig. 18) are produced through distinctly different means. In the off-axis simulations we have studied, short-lived but strong negative radial pressure gradients can be generated near the cores of the interacting clusters, leading to the ejection of low-entropy material into the outer regions of the merger remnant. Since these gradients are often very localized, the ejection tends to be highly directional leading to the formation of large outwardly flowing collimated plumes. Since the process is adiabatic, the ejected material retains its low entropy and eventually re-accretes on to the core of the remnant. This occurs as low-entropy streams of high-velocity material over an extended period lasting well after t_{accrete} (see Section 6.4).

Two mechanisms generally conspire to make this happen: the sudden release of compressive forces due to changes in the relative radial motion of the systems and the presence of low-pressure regions in the direction towards which material is dispersed as a result. After pericentric passage, the primary’s core is rapidly compressed and the wake of the secondary’s motion creates a large low-pressure region on the incident side of the collision. Low-entropy material from

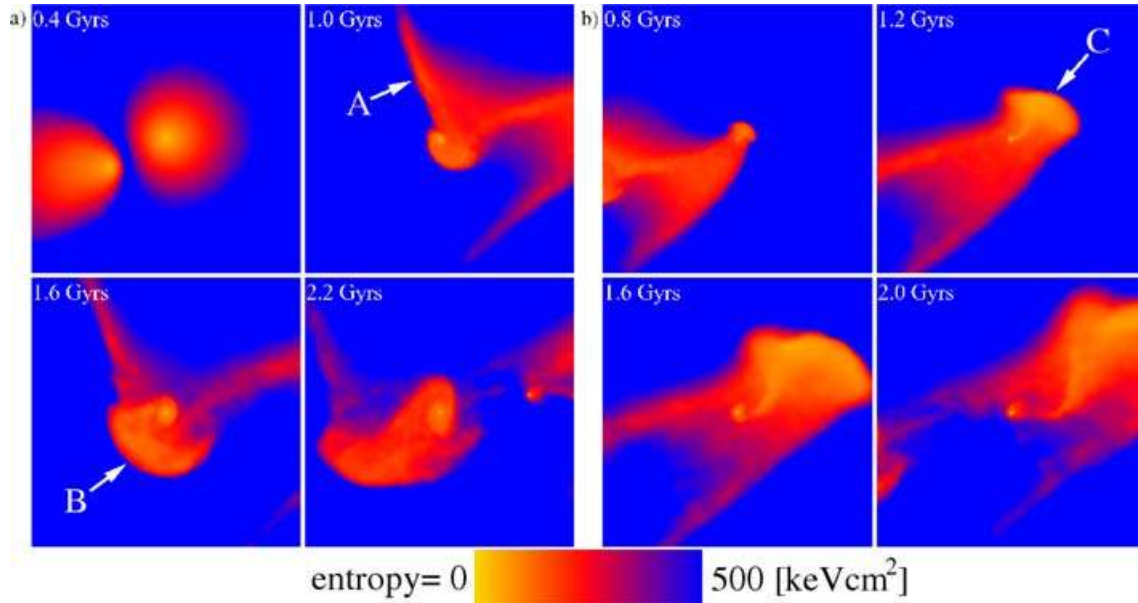


Figure 18. The left-hand panel of four plots shows entropy maps for our 3:1 $v_t/V_c = 0.15$ simulation illustrating the ejection of two distinct ‘plumes’ (labelled A and B) of low-entropy material from the primary core in response to the pericentric passage of the secondary. The first is triggered by the shocks that precede the secondary, and the second by negative pressure gradients in the wake behind the secondary. The right-hand panel of plots illustrates the ejection of a plume (labelled C) from the secondary at apocentre in the same simulation. The plumes eventually evolve into streams and most of the ejected low-entropy material flows along the streams into the primary core. Each frame above is 1.5 Mpc on a side and is a z -projection of a 0.5-Mpc-thick slice. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

the primary’s core becomes ejected back along the secondary’s path as a result, forming plume ‘B’ which reaches a radius of ~ 800 kpc in this case.

The secondary core is subject to these mechanisms at t_{apo} when it turns around and returns to the primary core. The decline of ram pressure at that time results in the release of compressive forces, and the strong negative pressure gradient of the primary at large radii provides a low-pressure region for the secondary core’s material to disperse towards. These mechanisms are assisted by a gravitational ‘sling-shot’ effect resulting from the lag of the secondary’s gas core behind its dark matter halo, as noted by Bialek et al. (2002). This lag is due to the additional pressure experienced by the gas but not the dark matter. The net result of these processes is the displacement of a significant portion of the surviving secondary core’s material outwards to its tidal radius. This material is then efficiently stripped away by tidal effects forming plume ‘C’ depicted in Fig. 18(b). As a result, the plume formed from the secondary after apocentric passage assumes the morphology of a trailing tidal tail (Toomre & Toomre 1972). More specifically, it has a shape which is curved in the same sense (from tail to core) as the orbit (see Fig. 18b). As the system passes apocentre, this structure precesses until it is oriented radially with the primary core. Plumes ejected from primary cores at t_{closest} are confined by the pressure gradients of the secondary’s wake and do not share this shape nor evolution.

The symmetry of our 1:1 off-axis mergers means that all the processes discussed above act on both cores equally to create a pair of symmetric plumes. They connect at t_{accrete} forming an ‘integral’ shaped structure. Its curvature is much more pronounced in the $v_t/V_c = 0.4$ case. Comparing Figs 3–6, we can see that the plumes formed from the secondary cores are quite similar between the 1:1 and 3:1 cases. However, in the 3:1 cases the plumes formed from the primary core reach much smaller radii.

The compressive forces generated in our 10:1 simulations are far less significant than those in the 1:1 or 3:1 cases resulting in a much less significant plume of primary core material following t_{closest} . Furthermore, the resulting pressure gradients are far less localized and result in a broader and less-collimated displacement of material. By t_{apo} , all the material of the secondary beyond 300 kpc has been completely stripped and dispersed into the outer regions of the system. Part of the core survives until t_{accrete} though, generating a small but undetectable plume after t_{apo} .

Several examples of observed systems exhibiting these morphologies exist including A1758 (David & Kempner 2004) and A2744 (Kempner & David 2004a). These systems possess disturbed accreting cores with curved shapes. In both cases, the authors suggest that they are products of ram-pressure stripping but this interpretation is not consistent with our simulations in either case: their large projected separations from their primary cores and their shape suggest that they have ejected plumes similar to plume ‘C’. A1758N appears to have passed in front of A1758S from east to west, transited apocentric passage and is ejecting a plume of material as it returns back towards A1758S. The A1758N plume is curved in the sense expected from such an orbit. A plume from the core of A1758S is apparent but lacks the same curved appearance. This may mean that A1758S is the more massive of the systems and has a plume such as plume ‘B’ depicted in Fig. 18(a), or that projection effects are distorting its appearance.

A more secure example of a plume being ejected from a massive primary system such as plume ‘B’ can be seen in A1644 (Reiprich et al. 2004). As noted above, this system has a significant bridge joining the interacting systems. It appears to be at or near apocentric passage, and the bridge’s lack of curvature, the absence of curved plumes and the thickness of the bridge suggest that the system’s orbit is highly inclined. Although the temperature map is cut off near the main system to the south-west, there is a strong suggestion of an

elongated cold region similar to plume ‘B’ seen in a y -projection. As we would expect from such an orientation, this feature is nearly collinear with the bridge.

Another good example of a system which appears to have had a plume of primary core material ejected by a merger is A2744. Kempner & David (2004a) suggested that this system is a 4:1 merger and should compare well to our 3:1 off-axis cases. We conclude from the structure of the bridge joining the interacting systems and the shape of the secondary’s plume that this system is near apocentric passage and significantly inclined. The left-handed orientation of the secondary plume’s curvature suggests that it has passed behind the primary in a north-western direction and is now travelling towards us near apocentric passage. Consistent with this interpretation, we find a cold region to the south-east of the primary, where the secondary would have entered the system, ejecting a plume from the primary’s core.

6.3 Induced core rotation

Due to the initial gas density gradients of the systems, the ram pressure acting on the cores as they pass each other is differential in off-axis cases. This induces torques on the gaseous components of each system causing them to rotate. Generally, the result is two co-rotating cores lasting from t_{closest} to the second pericentric passage at t_{accrete} when the coherence of this motion is disturbed. Remarkably, the release of the pressure gradients which lead to plume ‘B’ in Fig. 18(a) applies enough torque on the primary core in our 3:1 $v_t/V_c = 0.15$ case to cause the core to counter-rotate. This is the only instance in which we witness such counter-rotation and more exploration of orbital and mass ratio parameter space is needed to understand how often this occurs.

As a result of its induced rotation prior to apocentric passage, our secondary cores have prograde rotations when they eject the material which form the tidal tail plumes discussed above. This enhances the efficiency of the process.

6.4 Streams

The plumes of material removed from the cores of merging clusters discussed in Section 6.2 collect into large collimated structures. Because of the reduced entropy of this material, its buoyancy is low and it ultimately accretes on to the remnant core after the remainder of the secondary core does so at t_{accrete} . As a result, long-lived (~ 2 Gyr) high-velocity ($v \sim 1000 \text{ km s}^{-1}$) structures form in the cores of the remnant before the system relaxes. We distinguish these structures from plumes because they are inwardly propagating high-velocity structures of low (generally undetectable) surface brightness and are not associated with an apparent merging core (the secondary having been accreted and its observable presence destroyed at t_{accrete}).

In Fig. 19, we present a series of radial velocity maps for our 3:1 $v_t/V_c = 0.15$ simulation illustrating the interaction of two low-entropy streams (labelled ‘A’ and ‘B’) with the remnant core. The secondary core accretes from the top right-hand side at $t_{\text{accrete}} = 2.5$ Gyr in this case and the stream formed from its disruption (labelled ‘B’) follows it from the same direction. Another inwardly radial (but unapparent in surface brightness) feature (labelled ‘A’) can be seen on the opposite side of the system in these frames. It is a long-lasting stream formed from plume ‘A’ identified in Fig. 18(a).

Large-scale bulk motions with velocities similar to these streams were observed in the cores of merger remnants in the cosmological Adaptive Mesh Refinement simulations of Motl et al. (2004). These authors raised concerns that such motions preclude the existence of

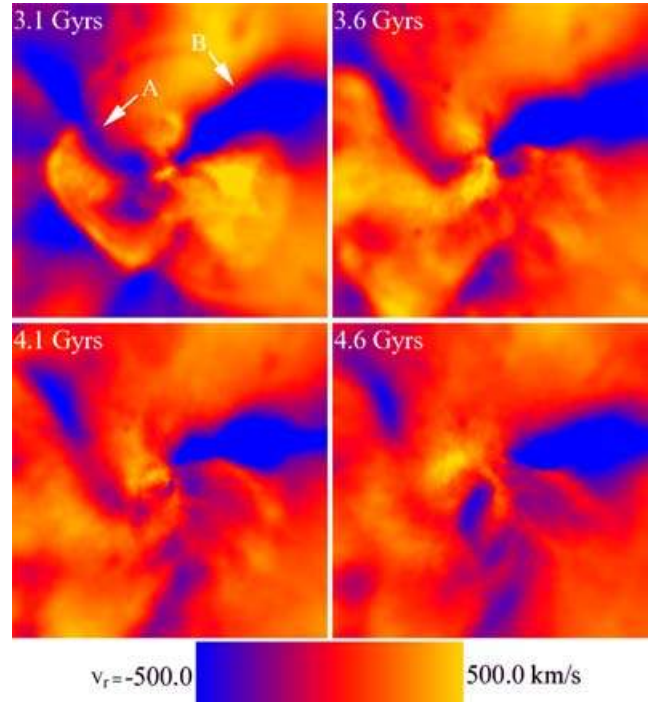


Figure 19. Different time snapshots of the radial velocity maps (mass weighted) for the gaseous component in the 3:1 $v_t/V_c = 0.15$ simulation showing the collision of a high-velocity stream (labelled B) with the remnant core. In this specific case, the primary and the secondary cores merged at $t_{\text{accrete}} = 2.5$ Gyr. Stream B consists of low-entropy material that was originally part of the secondary core but shorn off during the course of the merger. Also shown is a stream feature (labelled A) that is not readily apparent in the surface brightness map but which corresponds to a stream associated with returning material originally ejected from the primary core during the creation of plume ‘A’ (see Fig. 18a). Each frame here is 3.0 Mpc on a side and is a z -projection of a 0.5-Mpc-thick slice. (For colour plots, please see the electronic version or <http://astro.phys.uvic.ca/~babul/Merger.Paper1.>)

actively cooling cores. In our simulations, high-velocity structures in the core remain highly collimated and completely disrupt cooling of the core in only one case (3:1 $v_t/V_c = 0.15$). Even in this extreme case, cooling resumes on rapid (~ 300 Myr) time-scales once the stream finishes its accretion. This takes ~ 2 Gyr. In all other 1:1 and 3:1 off-axis cases we have studied, the high-velocity streams possess enough angular momentum when they accrete to miss the region of active cooling. In the 10:1 cases, the stream does not significantly disrupt cooling even when it does interact directly with the remnant core. In Poole et al. (in preparation), we will examine in more detail the effect these streams can have on the final structure of a merger remnant.

The low-entropy streams formed in the 1:1 off-axis cases are highly collimated and accrete quickly soon after t_{accrete} . In all cases, some portions of the streams are visible until t_{accrete} when their appearance becomes disrupted by the second interaction of the cores. In the $v_t/V_c = 0.4$ case, the accreting streams form a large low-entropy spiral which evolves into a ring roughly 1 Mpc in diameter by t_{relax} (see Fig. 2). This structure then slowly dissolves, disappearing ~ 2 Gyr after forming.

The secondary cores in our 3:1 mergers become more significantly disrupted after t_{closest} than in the 1:1 cases. As a result, material stripped from the secondary core becomes dispersed over a larger volume. Furthermore, it accretes slightly later than t_{accrete} and over

a longer period. The streams are barely observable in our simulated *Chandra* observations for only a ~ 300 Myr following t_{accrete} .

Streams such as these have low surface brightness and are best observed in the temperature structure of clusters. They should manifest as cold fronts oriented radially to the primary core with no obvious secondary core being present. There are several examples of observed systems like this. In A576, for instance, Kempner & David (2004b) noted a ‘finger’ of cool gas which extends to the north-west of the system from its core. In A2255 (Sakelliou & Ponman 2006), there is a distinct cool region to the south-east of the cluster core which is not associated with an obvious peak in X-ray brightness. Finally, in A2034 (Kempner, Sarazin & Markevitch 2003) there is a large diffuse tail of relatively cool gas extending towards the south of the cluster centre with no obvious X-ray peak associated with it.

6.5 Edges

The enhanced spatial resolution of *Chandra* has revealed that the central regions of several clusters exhibit ‘edges’ in their surface brightness as a result of large and localized gas density gradients. Among these are RX J1720.1+2638 (Mazzotta et al. 2001), A496 (Dupke & White 2003) and A1795 (Markevitch et al. 2001). Systems with several of these features have also been found including A576 (Kempner & David 2004b) which has at least two within 50 kpc, and ZW3146 (Forman et al. 2002) which has three at $r \sim 20, 45$ and 170 kpc. Attempts to account for these features have generally invoked bulk motions of cold core material with respect to its surrounding ICM. Explored mechanisms capable of driving such motions include the activity of jets from central AGN (Fabian et al. 2005) or gravitationally induced motions due to small passing substructure (Markevitch et al. 2001; Tittley & Henriksen 2005).

Occasionally, when the streams discussed in Section 6.4 accrete on to the centre of the remnant, an interface forms between it and the stationary core. Significant and abrupt jumps in density, temperature and pressure can result accompanied by a jump in surface brightness reminiscent of observed edges.

In Fig. 20, we show the evolution of two such edges following t_{accrete} for our 3:1 $v_t/V_c = 0.15$ simulation. As the secondary core accretes on to the primary core in this case, it does so on the top right-hand side. This leads to an expanding edge (labelled ‘A’) which starts at a radius of 120 kpc and disappears 0.3 Gyr later at a radius of 210 kpc. The stream which follows the accreting secondary core gets deflected towards the bottom of the core by this structure, forming a more significant edge (labelled ‘B’) at a radius of 40 kpc which lasts for 0.5 Gyr.

In Section 6.4, we noted several systems which show evidence of streams of radially collimated material. In two of these, A576 and A2034, there are obvious edge features present. In the case of A576, these edges are aligned properly with the orientation of the stream to be produced by it. In the case of A2034, the edges are apparently on the opposite side from the stream. In our simulations, multiple streams are typically produced by a single merger. It may be that an unseen stream (possibly produced by the same event which generated the observed stream) is responsible for the observed edge in this case. It may also be that the observed stream is passing in front of or behind the core before making contact with it.

No obvious edges are produced in our simulations by core oscillations. Edges produced through the accretion of streams are distinct, long lived (~ 500 Myr) and can yield multiple edges (such as those seen in A576) simultaneously. The last of these properties is difficult to account for through core oscillations but naturally explained as a product of accreting streams.

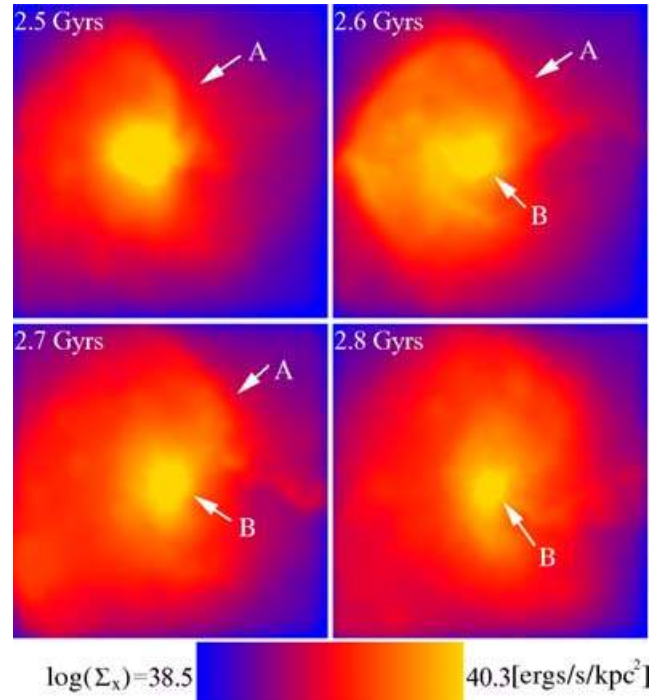


Figure 20. Surface brightness maps of our 3:1 $v_t/V_c = 0.15$ simulation showing the formation of two ‘edges’ associated with the accretion of the secondary (labelled A) and the stream of low-entropy material that follows the secondary (labelled B). The first ‘edge’ is a weak feature that moves outwards in radius and disappears soon after t_{accrete} . The second ‘edge’ is more well-defined and remains stationary during the accretion of the stream material, a process that can last for ~ 0.5 Gyr. Neither we see any examples of ‘edges’ produced by core oscillations, nor we find evidence for significant core oscillations in our simulations. Each frame shown is a z-projection 0.5 Mpc on a side. (For colour plots, please see the electronic version or http://astro.phys.uvic.ca/~babul/Merger_PaperI.)

7 SUMMARY AND CONCLUSIONS

(i) This paper is the first in a series aimed at elucidating the impact of mergers on relaxed X-ray clusters. For this study, we have carried out and analysed a suite of nine SPH simulations (incorporating the effects of cooling as well as star formation and associated supernova feedback) of two-body mergers between idealized clusters covering interesting and cosmologically relevant range of mass ratios and orbital properties. Our merging clusters are initialized with realistic initial dark matter and gas distributions, the latter resembling those seen in relaxed clusters with cool compact cores observed by *Chandra* and *XMM*.

(ii) Following a detailed qualitative analysis, we have identified a generic progression for typical cluster mergers. The stages of this progression are: (i) pre-interaction, (ii) initial closest approach, (iii) apocentric passage, (iv) accretion and disruption of the secondary core, and (v) relaxation. To facilitate comparison and interpretation of observations, we describe in detail the interactions associated with the gas components of the two merging systems during each of the stages and quantify the times at which these stages arise relative to the beginning of the merger. We also show gas density, X-ray surface brightness, gas temperature, SZ and gas-entropy maps at different points during the mergers.

(iii) Moderate and massive mergers tend to run for 4.5–5.5 Gyr, while minor mergers last for up to ~ 2 Gyr longer (in good agreement with the trend identified by Tormen et al. 2004). This duration is the

elapsed time from the point when the secondary’s centre of mass crosses R_{200} of the primary (the beginning) to the time when the gas distribution in the final system has relaxed and nearly returned to virial/hydrostatic equilibrium (the end). Typically, off-axis mergers run longer than head-on mergers.

(iv) In simulated 50-ks *Chandra* observations (assuming $z = 0.1$), all easily identifiable substructures generated by our merger events disappear during the secondary’s second pericentric passage of the primary core. However, the system takes an additional ~ 2 Gyr for its isophots to appear relaxed. Temperature fluctuations are not necessarily a reliable indicator of the system’s dynamical state.

(v) We find that following the merger, the resultant system settles into virial equilibrium sooner than into hydrostatic equilibrium. In many cases, the final cluster exhibits oscillations that result in instantaneous deviations from hydrostatic equilibrium by as much as 15 per cent for as long as 7 Gyr after the beginning of the merger. We also find that generically complex patterns of entropy and temperature fluctuations, at the level of $\Delta T/T \sim 20$ per cent, can persist in the final systems well past the point when the systems appear relaxed. Based on our findings, we suggest that temperature fluctuations of this order, without any other corroborating signatures of ongoing merger, should not be interpreted as evidence of a highly disturbed system.

(vi) We find that in none of the cases considered are the initial cool compact cores of the primary and the secondary destroyed during the course of the mergers. Instead, the two remnant cores eventually combine to form a new core that, depending on the final mass of the remnant, can have a greater cooling efficiency than either of its progenitors. We will discuss this behaviour in more detail in a forthcoming paper.

(vii) While the large-scale coherent displacements between the dark matter and gas components in the merging system are not uncommon, they do not trigger any obvious surface brightness discontinuities. Within the central 50 kpc, the gas and the dark matter remain tightly coupled to each other. We do not see any evidence of core oscillations or of any associated heating.

(viii) We investigated the efficacy of three measures used to quantify the degree to which observed clusters are disturbed. These are (i) centroid variance, (ii) power ratios, and (iii) X-ray surface brightness/projected mass displacement. We find that the centroid variance is the best of the three. It best reflects the state of the cluster as determined by a visual examination. It also provides an excellent indicator of how far the system is from virial and hydrostatic equilibrium. The power ratios are very sensitive to noise and once this is factored in, they provide an unambiguous signal only when the system is highly disturbed. The X-ray/mass displacements are extremely sensitive to weak but long-lived perturbations in the dark matter distribution caused by low-mass mergers.

(ix) During the course of the merger, we find a variety of transient features arising and disappearing in the projected temperature, entropy and surface brightness maps, most of which resemble ‘cold fronts’ observed in recent *Chandra* and *XMM* observations. While ‘cold fronts’ are generally associated with the disruption of the secondary’s core, we find that they can be caused by several different mechanisms. The resulting features can potentially be distinguished based on their morphological properties. Interested readers are referred to Section 6 for examples of clusters whose recently published X-ray images show examples of the different types of transient structures. We propose the following classification scheme based on their origin and appearance.

(i) *‘Comet-like’ tails.* Ram pressure strips the outer atmospheres of secondary systems forming very brief (~ 0.5 Gyr) comet-like morphologies for both cluster cores (except the primary in 10:1 mergers). This morphology is observable only between first pericentric and apocentric passages.

(ii) *Bridges.* Ram pressure disperses core material from both cluster cores in 1:1 and 3:1 cases. A luminous moderate-entropy bridge resulting from the convergence of the two resulting regions of dispersed material is produced. This structure remains observable in 50-ks *Chandra* exposures at $z = 0.1$ until secondary core accretion in our 1:1 mergers and until apocentric passage in our 3:1 mergers. The morphology of this structure could be useful as a cue for determining the inclination of observed merger systems.

(iii) *Plumes.* Pressure gradients produced by the secondary’s motion at t_{closest} and t_{apo} can lead to the ejection of significant amounts of the primary and secondary cores’ gas. This material forms large collimated plumes of low-entropy material. At apocentric passage, material ejected in this way from the secondary’s core becomes tidally stripped and adopts the morphology of a trailing tidal tail. The majority of observed disturbed merging cores likely owe their appearance to this process, rather than ram-pressure stripping.

(iv) *Streams.* Low-entropy streams form from these plumes and accrete on to the centre of the remnant following the second pericentric passage and disruption of the secondary core at t_{accrete} . This material remains collimated and typically has enough angular momentum to avoid a direct impact with the remnant core. This mitigates the concerns of Motl et al. (2004) who suggested that high-velocity structures formed in mergers may prevent the formation of compact cool cores. These streams may also play an important role in fuelling the activity of central AGN in clusters.

(v) *Induced core rotation.* Off-axis mergers subject the gaseous cores of both merging clusters to torques which induce rotation. In one simulation (our 3:1 $v_i/V_c = 0.15$ case), the resulting rotation of the primary’s core is retrograde to the secondary’s orbit. In all cases, the coherence of this rotation is completely disrupted by the disruption of the cores during second pericentric passage.

(vi) *Edges.* Streams can accrete directly on to the core of the remnant, generating strong ‘edges’ in surface brightness and gradients in temperature and density. The resulting features are similar to several cold front systems whose morphology had previously been attributed to AGN activity or motion of the gaseous core within its dark matter potential.

We would like to reiterate that our simulations do not incorporate the physical processes associated with magnetic fields, pressure from cosmic rays or thermal conduction nor do we adequately model the effects of turbulence. The influence of these processes on clusters remains a contentious issue and we cannot make any confident predictions at this point regarding their effects on our results.

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