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# THE LIFESPAN OF SMALL DATA SOLUTIONS IN TWO DIMENSIONAL CAPILLARY WATER WAVES 

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#### Abstract

This article is concerned with the incompressible, irrotational infinite depth water wave equation in two space dimensions, without gravity but with surface tension. We consider this problem expressed in position-velocity potential holomorphic coordinates, and prove that small data solutions have at least cubic lifespan while small localized data leads to global solutions.


## 1. Introduction

We consider the incompressible, infinite depth water wave equation in two space dimensions, without gravity but with surface tension. This is governed by the incompressible Euler's equations with boundary conditions on the water surface.

We first describe the equations. We denote the water domain at time $t$ by $\Omega(t)$, and the water surface at time $t$ by $\Gamma(t)$. We think of $\Gamma(t)$ as being either asymptotically flat at infinity or periodic. The fluid velocity is denoted by $u$ and the pressure is $p$. Then $u$ solves the Euler equations inside $\Omega(t)$,

$$
\left\{\begin{array}{l}
u_{t}+u \cdot \nabla u=\nabla p  \tag{1.1}\\
\operatorname{div} u=0 \\
u(0, x)=u_{0}(x)
\end{array}\right.
$$

while on the boundary we have the dynamic boundary condition

$$
\begin{equation*}
p=-2 \sigma \mathbf{H} \quad \text { on } \Gamma(t) \tag{1.2}
\end{equation*}
$$

and the kinematic boundary condition

$$
\begin{equation*}
\partial_{t}+u \cdot \nabla \text { is tangent to } \bigcup \Gamma(t) \tag{1.3}
\end{equation*}
$$

Here $\mathbf{H}$ is the mean curvature of the boundary and $\sigma$ represents the surface tension.
Under the additional assumption that the flow is irrotational, we can write $u$ in terms of a velocity potential $\phi$ as $u=\nabla \phi$, where $\phi$ is harmonic with appropriate decay at infinity. Thus $\phi$ is determined by its trace on the free boundary $\Gamma(t)$. Denote by $\eta$ the height of the water surface as a function of the horizontal coordinate. Following Zakharov's formulation, we introduce $\psi=\psi(t, x) \in \mathbf{R}$ to be the trace of the velocity potential $\phi$ on the boundary,

[^0]$\psi(t, x)=\phi(t, x, \eta(t, x))$. Then the fluid dynamics can be expressed in terms of a onedimensional evolution of the pairs of variables $(\eta, \psi)$, namely
\[

\left\{$$
\begin{array}{l}
\partial_{t} \eta-G(\eta) \psi=0  \tag{1.4}\\
\partial_{t} \psi-\mathbf{H}(\eta)+\frac{1}{2}|\nabla \psi|^{2}-\frac{1}{2} \frac{(\nabla \eta \cdot \nabla \psi+G(\eta) \psi)^{2}}{1+|\nabla \eta|^{2}}=0 .
\end{array}
$$\right.
\]

This is the Eulerian formulation of the capillary water wave equations.
1.1. Water waves in holomorphic coordinates. One main difficulty in the study of the above equation is the presence of the Dirichlet to Neumann operator $\mathcal{D}$, which depends on the free boundary. This is one of the motivations for our choice to use a different framework to study these equations, namely the holomorphic coordinates. These were originally introduced by Nalimov [33], and were heavily exploited by the authors in earlier work [20], [23] in the context of two dimensional gravity water waves. One can view the choice of coordinates (e.g. Lagrangian, Eulerian, holomorphic) as gauge fixing for the gauge group of changes of coordinates; then it becomes natural to study problems in the most favorable gauge.

The holomorphic coordinates are defined via a conformal map $\mathcal{F}: \mathbb{H} \rightarrow \Omega(t)$, where $\mathbb{H}$ is the lower half plane, $\mathbb{H}:=\{\alpha-i \beta: \beta>0\}$. Here $\mathcal{F}$ maps the real line into the free boundary $\Gamma(t)$. Thus the real coordinate $\alpha$ parametrizes the free boundary, which is denoted by $Z(t, \alpha)$. In order to uniquely determine the parametrization we impose a boundary condition at infinity,

$$
\lim _{\alpha \rightarrow \infty} Z(t, \alpha)-\alpha=0
$$

In the periodic case we simply ask for $Z(t, \alpha)-\alpha$ to be periodic. We call these the holomorphic coordinates.

In order to describe the velocity potential $\phi$ we use the function $Q=\phi+i \psi$ where $\psi$ represents the harmonic conjugate of $\phi$. Both functions $Z-\alpha$ and $Q$ admit bounded holomorphic extensions into the lower half plane, which implies that their Fourier transforms are supported in $(-\infty, 0]$. We call such functions holomorphic functions. They can be described by the relation $P f=f$, where $P$ represents the projector operator to negative frequencies. The water wave equation will define a flow in the class of holomorphic functions for the pair of variables $(W, Q)$ where $W=Z-\alpha$.

A full derivation of the holomorphic form of gravity water waves was included in an appendix to the paper [20]. The minor modifications which are necessary for the periodic case are also described there. The equations with surface tension accounted are quite similar, and are derived in the same fashion:

$$
\left\{\begin{array}{l}
W_{t}+F\left(1+W_{\alpha}\right)=0  \tag{1.5}\\
Q_{t}+F Q_{\alpha}+P\left[\frac{\left|Q_{\alpha}\right|^{2}}{J}\right]-\sigma P\left[\frac{-i}{2+W_{\alpha}+\bar{W}_{\alpha}} \frac{d}{d \alpha}\left(\frac{W_{\alpha}-\bar{W}_{\alpha}}{\left|1+W_{\alpha}\right|}\right)\right]=0
\end{array}\right.
$$

where

$$
\begin{equation*}
F=P\left[\frac{Q_{\alpha}-\bar{Q}_{\alpha}}{J}\right]_{2}, \quad J=\left|1+W_{\alpha}\right|^{2} \tag{1.6}
\end{equation*}
$$

Simplifying we obtain the fully nonlinear system

$$
\left\{\begin{array}{l}
W_{t}+F\left(1+W_{\alpha}\right)=0  \tag{1.7}\\
Q_{t}+F Q_{\alpha}+P\left[\frac{\left|Q_{\alpha}\right|^{2}}{J}\right]+i \sigma P\left[\frac{W_{\alpha \alpha}}{J^{1 / 2}\left(1+W_{\alpha}\right)}-\frac{\bar{W}_{\alpha \alpha}}{J^{1 / 2}\left(1+\bar{W}_{\alpha}\right)}\right]=0
\end{array}\right.
$$

The problem (1.7) is invariant with respect to translations, and also with respect to the scaling

$$
\begin{equation*}
(W(t, \alpha), Q(t, \alpha)) \rightarrow\left(\lambda^{-1} W\left(\lambda^{\frac{3}{2}} t, \lambda \alpha\right), \lambda^{-\frac{1}{2}} Q\left(\lambda^{\frac{3}{2}} t, \lambda \alpha\right)\right) . \tag{1.8}
\end{equation*}
$$

The Hamiltonian for this system is

$$
\mathcal{H}(W, Q)=\int \Im\left(Q \bar{Q}_{\alpha}\right)+\frac{1}{4} \sigma\left(J^{\frac{1}{2}}-1-\Re W_{\alpha}\right) d \alpha
$$

Since $W$ and $Q$ only appear in differentiated form in the equations above, differentiating with respect to $\alpha$ yields a self contained system for ( $W_{\alpha}, Q_{\alpha}$ ), namely

$$
\left\{\begin{array}{r}
W_{\alpha t}+b W_{\alpha \alpha}+\frac{1}{1+\bar{W}_{\alpha}}\left(Q_{\alpha \alpha}-\frac{Q_{\alpha}}{1+W_{\alpha}} W_{\alpha \alpha}\right)=-\left(1+W_{\alpha}\right) \bar{F}_{\alpha}-\left[\frac{\bar{Q}_{\alpha}}{1+\bar{W}_{\alpha}}\right]_{\alpha} \\
Q_{t \alpha}+b Q_{\alpha \alpha}+\frac{1}{1+\bar{W}_{\alpha}} \frac{Q_{\alpha}}{1+W_{\alpha}}\left(Q_{\alpha \alpha}-\frac{Q_{\alpha}}{1+W_{\alpha}} W_{\alpha \alpha}\right)+i \sigma P\left[\frac{W_{\alpha \alpha}}{J^{1 / 2}\left(1+W_{\alpha}\right)}\right]_{\alpha}= \\
\quad i \sigma P\left[\frac{\bar{W}_{\alpha \alpha}}{J^{1 / 2}\left(1+\bar{W}_{\alpha}\right)}\right]_{\alpha}-Q_{\alpha} \bar{F}_{\alpha}+\bar{P}\left[\frac{\left|Q_{\alpha}\right|^{2}}{J}\right]_{\alpha}
\end{array}\right.
$$

where the advection velocity $b$ is given by

$$
\begin{equation*}
b:=2 \Re P\left[\frac{Q_{\alpha}}{J}\right] . \tag{1.9}
\end{equation*}
$$

The terms on the right are mostly antiholomorphic and can be viewed as lower order when projected on the holomorphic functions. Examining the expression on the left one easily identifies the leading surface tension term in the second equation, added to a first order system. The first order system is degenerate, and has a double speed $b$. Then it is natural to diagonalize it. This is done exactly as in the case of gravity waves using the operator

$$
\begin{equation*}
\mathbf{A}(w, q):=(w, q-R w), \quad R:=\frac{Q_{\alpha}}{1+W_{\alpha}} \tag{1.10}
\end{equation*}
$$

The factor $R$ above has an intrinsic meaning, namely it is the complex velocity restricted on the water surface. We also remark that

$$
\mathbf{A}\left(W_{\alpha}, Q_{\alpha}\right)=(\mathbf{W}, R), \quad \mathbf{W}:=W_{\alpha}
$$

Thus, the pair $(\mathbf{W}, R)$ diagonalizes the differentiated system. Indeed, a direct computation yields the self-contained system

$$
\left\{\begin{array}{l}
\mathbf{W}_{t}+b \mathbf{W}_{\alpha}+\frac{(1+\mathbf{W}) R_{\alpha}}{1+\overline{\mathbf{W}}}=(1+\mathbf{W}) M  \tag{1.11}\\
R_{t}+b R_{\alpha}+\frac{i a}{1+\mathbf{W}}+i \sigma \frac{1}{1+\mathbf{W}} P\left[\frac{\mathbf{W}_{\alpha}}{J^{1 / 2}(1+\mathbf{W})}\right]_{\alpha}=i \sigma P\left[\frac{\overline{\mathbf{W}}_{\alpha}}{J^{1 / 2}(1+\overline{\mathbf{W}})}\right]_{\alpha}
\end{array}\right.
$$

where the real frequency-shift $a$ is given by

$$
\begin{equation*}
a:=i\left(\bar{P}\left[\bar{R} R_{\alpha}\right]-P\left[R \bar{R}_{\alpha}\right]\right), \tag{1.12}
\end{equation*}
$$

and the auxiliary function $M$ is given by

$$
\begin{equation*}
M:=\frac{R_{\alpha}}{1+\overline{\mathbf{W}}}+\frac{\bar{R}_{\alpha}}{1+\mathbf{W}}-b_{\alpha}=\bar{P}\left[\bar{R} Y_{\alpha}-R_{\alpha} \bar{Y}\right]+P\left[R \bar{Y}_{\alpha}-\bar{R}_{\alpha} Y\right] . \tag{1.13}
\end{equation*}
$$

Here we used the notation $Y:=\frac{W_{\alpha}}{1+W_{\alpha}}$. Both equations (1.7) and (1.11) will be used in the sequel.

Remark 1.1. For convenience we have written the equations with the surface tension $\sigma$ included. However, in our case $\sigma$ can be scaled out, so through the rest of the paper we will simply set $\sigma=1$.
1.2. Prior work. First of all, there is a large body of work devoted to the local wellposedness in the Cauchy problem for water wave equations in all combinations, with or without gravity, surface tension, finite or infinite depth, periodic or not.

This begins with the early work of Nalimov [33] (infinite bottom) and Yoshihara [40, 41], (finite bottom, with/without tension) for the small data problem. The first well-posedness results for large data are due to Wu [37,38] (no surface tension). Further results were later obtained by Christodoulou-Lindblad [11], Lannes [28], Coutand and Shkoller [14], Lindblad [29], Beyer-Günther [8], Schweizer [34] Ambrose and Masmoudi [6, Shatah and Zeng [36]. More recent work has also considered the role of dispersion in such problems, beginning with Christianson, Hur and Staffilani [10] and continuing to the work of Alazard, Burq and Zuily [1, 2, [5], which represents the current state of the art. In particular, it is the result in [1] that we rely on for local well-posedness, though even Nalimov's result would serve if we were to restrict ourselves to more regular data.

There is also considerable work done for traveling waves, which are known to exist in both two and three dimensions, see for instance Amick-Kirchgässner [7], Groves-Sun [17], and Buffoni-Groves-Sun-Wahlen [9, Groves-Wahlen [18]. However, all these results are concerned with a certain regime $\left(\beta>\frac{1}{3}\right)$ in gravity-capillary problems with either finite or infinite bottom. For a broader view, see also the recent book of Constantin [13]. To the best of our knowledge, there are no results on the existence of pure capillary solitary waves in our setting of infinite depth.

There are fewer long time results for the small data problem. The first results in this direction are due to Wu [39], who proved almost global existence of gravity waves in dimension two. The similar three dimensional problem was solved independently by Germain-Masmoudi-Shatah [16] and Wu [38]. Closer to our goal here, the three dimensional capillary water wave problem was shown to have global solutions by Germain-Masmoudi-Shatah [15].

Even more recently, Wu's two dimensional almost global result was improved to a global result in independent work by Ionescu-Pusateri [24, 25] and Alazard-Delort [3, 4]. Shortly after, the authors were able to provide shorter and simpler proofs, first for the almost global result in joint work with Hunter [20], and next for the global result [23]. The present article is a natural continuation of this work. We also note that some preliminary results on a related simplified model problem were very recently announced by Ionescu and Pusater ${ }^{11}$;

[^1]their model only deals with the simpler high frequency part of the problem, truncating off the more interesting low frequency part, which is the main thrust of the present article.
1.3. Main results. We first describe the function spaces that we use in order to describe the solutions to the capillary water waves. The scale $\dot{\mathcal{H}}^{s}$ of function spaces used in this article is defined by
$$
\dot{\mathcal{H}}^{s}=\dot{H}^{s} \times \dot{H}^{s-\frac{1}{2}}
$$

Here the energy corresponds to $s=1$, while the scaling is at $s=\frac{3}{2}$. On occasion we will also use the corresponding inhomogeneous spaces,

$$
\mathcal{H}^{s}=H^{s} \times H^{s-\frac{1}{2}}
$$

Our main goal here is to study the long time persistence of small data solutions. What we do not do here is to consider the local well-posedness problem; instead, for that we will rely on the local well-posedness result of Alazard-Burq-Zuily [1]. Their result is stated in Eulerian coordinates. However, at least for small data, it is straightforward to transfer it to the holomorphic coordinates, as the transition map is bounded in Sobolev spaces. For our purposes here it suffices to restrict ourselves to integer $s$; then we have:

Theorem 1 (Alazard-Burq-Zuily [1]). The system (1.7) is locally well-posed for small data in $\mathcal{H}^{k}$ for $k \geq 4$.

This result includes existence, uniqueness and $C^{1}$ dependence on data in a weaker topology (e.g. $\mathcal{H}^{k-1}$ ). A more precise version of this result in holomorphic coordinates, which also applies to large data, will be discussed elsewhere.

All of our results apply to water waves with data as in the above theorem. However, the bounds on the solutions will not depend as much on the low frequency regularity of the data, and we will be able to phrase that in terms of some homogeneous Sobolev norms.

For the estimates on the persistence of solutions we will follow an analogue of the set-up in [20] and introduce the control norms

$$
\begin{equation*}
A:=\|\mathbf{W}\|_{L^{\infty}}+\|Y\|_{L^{\infty}}+\left\|D^{-\frac{1}{2}} R\right\|_{L^{\infty} \cap B_{2}^{0, \infty}} \tag{1.14}
\end{equation*}
$$

respectively

$$
\begin{equation*}
B:=\left\|D^{\frac{1}{2}} \mathbf{W}_{\alpha}\right\|_{L^{\infty}}+\left\|R_{\alpha}\right\|_{L^{\infty}} \tag{1.15}
\end{equation*}
$$

We note that $A$ is scale invariant, and scales like the $\dot{\mathcal{H}}^{\frac{3}{2}}$ norm of $(W, Q) . B$ on the other hand, scales like the $\dot{\mathcal{H}}^{3}$ norm of $(W, Q)$. In the corresponding results in 20 we were able to use $B M O$ norms instead of $L^{\infty}$ in the corresponding definition of the $B$ norm. In this regard, the results here are slightly less accurate.

Our first result asserts that the persistence of solutions does not depend on the full Sobolev norm of the solutions, instead it is controlled by the weaker control norm $B$ :

Theorem 2. Let $n \geq 4$. Then solutions to the water wave equation (1.7) with $\mathcal{H}^{n}$ data, which is small in $\dot{\mathcal{H}}^{4} \cap \dot{\mathcal{H}}^{1}$, persist with uniform bounds in both $\mathcal{H}^{n}$ and $\dot{\mathcal{H}}^{4} \cap \dot{\mathcal{H}}^{1}$ for as long as the time integral $\int B$ remains small. The same result holds in the periodic setting.

In particular, we obtain the following cubic lifespan result:

Theorem 3. Let $\epsilon \ll 1$. Assume that the initial data for the equation (1.7) on either $\mathbb{R}$ or $\mathbb{S}^{1}$ satisfies

$$
\begin{equation*}
\|(\mathbf{W}(0), R(0))\|_{\dot{\mathcal{H}}^{4} \cap \dot{\mathcal{H}}^{1}} \leq \epsilon \tag{1.16}
\end{equation*}
$$

Then the solution exists on an $\epsilon^{-2}$ sized time interval $I_{\epsilon}=\left[0, T_{\epsilon}\right]$, and satisfies a similar bound. In addition, the estimates

$$
\sup _{t \in I_{\epsilon}}\|(\mathbf{W}(t), R(t))\|_{\dot{\mathcal{H}}^{n}} \lesssim\|(\mathbf{W}(0), R(0))\|_{\dot{\mathcal{H}}^{n}}, \quad n \geq 1
$$

hold in the same time interval whenever the right hand side is finite.
The proof of both theorems above is based on the cubic high frequency energy estimates in Section 4.

Next we turn our attention to the problem with small localized data, and show that in this case the solutions are global in time. To state the result we take advantage of the scale invariance of the equation (1.8). The generator of the scaling group is

$$
\mathbf{S}(W, Q)=\left((S-1) W,\left(S-\frac{1}{2}\right) Q\right), \quad S=\frac{3}{2} t \partial_{t}+\alpha \partial_{\alpha}
$$

Then $\mathbf{S}(W, Q)$ solve the linearized water wave equations, which are described later in Section 6 .

In order to obtain sufficient pointwise decay we need to use lower Sobolev norms, both for $(W, Q)$ and for $\mathbf{S}(W, Q)$. Precisely, we will work in the space $\dot{\mathcal{H}}^{\sigma}$ where $0<\sigma<\frac{1}{8}$ is a sufficiently small parameter. Then we define the weighted energy

$$
\begin{equation*}
\|(W, Q)(t)\|_{\mathcal{W H}_{\mathcal{H}}}^{2}:=\|(W, Q)(t)\|_{\dot{\mathcal{H}}^{10} \cap \dot{\mathcal{H}}^{\sigma}}^{2}+\|\mathbf{S}(W, Q)(t)\|_{\dot{\mathcal{H}}^{1} \cap \dot{\mathcal{H}}^{\sigma}}^{2} . \tag{1.17}
\end{equation*}
$$

Here we will use a stronger control norm, namely

$$
\begin{equation*}
\|(W, Q)\|_{X}:=\sum_{j=0,1,2,3,4}\left\|D^{j+\frac{1}{2}} W\right\|_{L^{\infty}}+\left\|D^{j} Q\right\|_{L^{\infty}} \tag{1.18}
\end{equation*}
$$

The $L^{\infty}$ bound for $W$ will be also controlled but in a more loose fashion, and will play a lesser role. Our global result is as follows:

Theorem 4. For each initial data $(W(0), Q(0))$ for the system (1.7) satisfying

$$
\begin{equation*}
\|(W, Q)(0)\|_{\mathcal{W H}}^{2} \leq \epsilon \ll 1 \tag{1.19}
\end{equation*}
$$

the solution is global and satisfies

$$
\begin{equation*}
\|(W, Q)(t)\|_{\mathcal{W H}}^{2} \leq C \epsilon t^{C \epsilon^{2}} \tag{1.20}
\end{equation*}
$$

as well as

$$
\begin{equation*}
\|(W, Q)\|_{X} \leq C \frac{\epsilon}{\sqrt{t}} \tag{1.21}
\end{equation*}
$$

and

$$
\begin{equation*}
\|W\|_{L^{\infty}} \leq C \epsilon\left(|\alpha|+t^{\frac{2}{3}}\right)^{\sigma-\frac{1}{2}} . \tag{1.22}
\end{equation*}
$$

The proof of the theorem uses a bootstrap argument. Precisely, it suffices to prove the conclusion of the theorem under the additional bootstrap assumptions

$$
\begin{equation*}
\|(W, Q)(t)\|_{\mathcal{W H}}^{2} \leq C \epsilon \epsilon^{\frac{1}{18}} \tag{1.23}
\end{equation*}
$$

as well as

$$
\begin{equation*}
\|(W, Q)\|_{X} \leq 2 C \frac{\epsilon}{\sqrt{t}} \tag{1.24}
\end{equation*}
$$

and

$$
\begin{equation*}
\|W\|_{L^{\infty}} \leq 2 C \epsilon\left(|\alpha|+t^{\frac{2}{3}}\right)^{\sigma-\frac{1}{2}} \tag{1.25}
\end{equation*}
$$

for a fixed large universal constant $C$ independent of $\epsilon$, and for $\epsilon$ small enough.
Now we are able to divide the proof into several steps.
(i) The high frequency part of the $(W, Q)$ energy estimate (i.e., the $\dot{\mathcal{H}}^{10}$ bound) in (1.20) is proved in Section 4, using our method of quasilinear modified energy estimates developed in [21], [20].
(ii) The low frequency part of the $(W, Q)$ energy estimate (i.e. the $\dot{\mathcal{H}}^{\sigma}$ bound) in (1.20) is proved in Section 5, using Shatah's normal form method [35].
(iii) The energy estimates for $S(W, Q)$ in (1.20) are proved in Section 6, where the linearized equations are considered. This is also done in two steps, first for the $\dot{\mathcal{H}}^{1}$ norm, using a quasilinear modified energy, and then for the $\dot{\mathcal{H}}^{\sigma}$ norm, using normal forms.
(iv) A preliminary set of pointwise bounds is obtained from the energy estimates via Klainerman-Sobolev type inequalities in Section [7. These have an additional $t^{c \epsilon^{2}}$ factor compared with (1.21), so are not quite sufficient to close the argument. However, they have additional decay away from the region $|\alpha| \approx t$, so they suffice outside a region $t^{-\delta} \leq|\alpha| / t \leq t^{\delta}$.
(v) The final pointwise bounds in (1.21) are obtained in the last section using the method of testing by wave packets developed in [22], [23].
Before we get to the above steps, in the next two sections we describe the classes of multilinear operators used in this paper, and we do the normal form computation for all the non-resonant quadratic and cubic interactions which are needed later on.
1.4. Further remarks. As mentioned above, this article is a natural continuation of authors' earlier work in [20], [22]. Compared to earlier work of Wu [39], Ionescu-Pusateri [24] and Alazard-Delort [3, 4] there are three key improvements in [20], [23].

- The use of holomorphic coordinates, which greatly simplifies the form of the equations and eliminates the use of the Dirichlet to Neumann map. This idea is due to Nalimov [33].
- The modified energy method in [20, which can be viewed as a quasilinear adaptation of Shatah's normal form method. This addresses the well known issue that normal form transformations are poorly adapted to quasilinear evolutions. The idea is that instead of transforming the equations, one can construct a modified energy which is both adapted to the quasilinear problem and provides cubic estimates.
- The method of testing by wave packets in [22, 23], which is a more efficient way to obtain asymptotic equations in problems which exhibit modified scattering asymptotics. One should compare this with the previous approaches. The first one, introduced by

Hayashi-Naumkin [19] and refined by Kato-Pusateri [26], was Fourier based. The Lindblad-Soffer [30] idea was to instead produce an asymptotic equation by looking at the solution along rays in the physical space.
All of these ideas come equally handy in the present paper. The main steps are as follows:
(i) Normal form analysis. The analysis here parallels the one for gravity waves, in that bilinear resonant interactions occur only when one of the frequencies is zero. Thus, in the normal form there is a singularity at frequency zero. In particular, there we need to use the full structure of the equations in order to insure that the normal form transformation remains manageable. A similar difficulty arises in the work of Germain-Masmoudi-Shatah [15] in higher dimension. One entirely expected difference, compared to our previous work [20], [23], is that here the normal form symbol is no longer a polynomial, so that we need to deal with multiplier type bilinear forms. This is relatively standard and arises in most problems, beginning with Shatah's original work [35].
(ii) High frequency analysis and energy estimates. The quasilinear modified energy method applies as in [20], and serves to prove high frequency energy estimates. One additional difficulty here is that the top three terms in the normal form energy expansion need to be corrected in a quasilinear fashion, unlike in our gravity waves paper [20] where only the top term needs to be adjusted.
(iii) Low frequency analysis and normal forms corrections. The low frequency analysis has a semilinear nature, and is treated in a manner which is based purely on normal forms. The idea is very simple, namely to use Shatah's normal form method to eliminate quadratic interactions. In order to gain enough control on the errors, we also need to go one step further, and eliminate as well certain cubic unbalanced non-resonant interactions. Our energy spaces $\dot{\mathcal{H}}^{\sigma}$ at low frequencies are chosen in a manner which is similar to Germain-Masmoudi-Shatah [15], though their motivation is somewhat different.
(iv) The asymptotic equations. These are used in order to extend the pointwise decay bounds past the exponential time. The bounds we obtain from Klainerman-Sobolev type estimates are strong enough both for very small frequencies (and low speeds) and for very large frequencies (and high speeds). Thus, we only need to consider the intermediate range of frequencies not very far from 1. There the method of testing by wave packets applies exactly as in [23].

Acknowledgements: The final part of this research was carried out while both authors were visiting the Haussdorf Institute in Bonn.

## 2. Paraproduct type multilinear operators

A key role in the analysis in this paper is played by paraproduct type translation invariant bilinear and multilinear forms. Since our state space consists of holomorphic functions, i.e., with negative spectrum, we will only consider operators acting on this space. We begin with bilinear forms, which are of two types:

- holomorphic, i.e., of the form

$$
\widehat{B(u, v)}(\zeta)=\int_{\zeta=\xi+\eta} m(\xi, \eta) \hat{u}(\xi) \hat{v}(\eta) d \xi
$$

- mixed, i.e., of the form

$$
\widehat{B(u, v)}(\eta)=1_{\eta>0} \int_{\eta=\zeta-\xi} m(\xi, \zeta) \hat{u}(\zeta) \overline{\hat{v}}(\xi) d \xi
$$

These represent paradifferential generalizations of the standard products $u v$, respectively $P(u \bar{v})$, restricted to the holomorphic class. Our bilinear symbols $m$ will always be homogeneous, and smooth away from $(0,0)$.

Definition 2.1. We denote by $\mathfrak{M}_{k}$ the class of symbols $m$ as above which are homogeneous of order $k \in \mathbb{Z}$ and smooth away from $(0,0)$. The corresponding classes of operators are denoted by $O P \mathfrak{M}_{k}^{(2,0)}$ for operators of holomorphic type, by $O P \mathfrak{M}_{k}^{(1,1)}$ for operators of mixed type, and by $O P \mathfrak{M}_{k}$ for combinations thereof. By $L_{k}^{(2,0)}, L_{k}^{(1,1)}$ and $L_{k}$ we denote operators in the respective classes.

Such bilinear and multilinear forms satisfy multiplicative estimates which are quite similar to product type bounds, see Coifman-Meyer [12], Kenig-Stein [27], Muscalu-Tao-Thiele [32], Muscalu [31:
Proposition 2.2. Let $L_{0}$ be an order zero bilinear form as above. Then we have

$$
\|L(f, g)\|_{L^{r}} \lesssim\|f\|_{L^{p}}\|g\|_{L^{q}}, \quad \frac{1}{p}+\frac{1}{q}=\frac{1}{r}, \quad 1<r<\infty \quad p, q>1
$$

We also need to work with trilinear forms in the sequel. There we have three types, which are denoted using the superscripts $(3,0),(2,1)$ respectively $(1,2)$. However, in order to deal with all the cases arising in this article, we need to enlarge slightly the class of homogeneous symbols we allow. Since we are only concerned with homogeneous symbols, it suffices to describe the zero order symbols. There are three such classes of symbols of order zero that we need to allow:

- smooth homogeneous symbols,
- compositions of two smooth bilinear symbols,
- polyhomogeneous symbols of the form

$$
\left|\xi_{1}\right|^{c_{1}}\left|\xi_{2}\right|^{c_{2}}\left|\xi_{3}\right|^{c_{3}}\left|\xi_{\text {out }}\right|_{4}^{c_{1}} m\left(\xi_{1}, \xi_{2}, \xi_{3}, \xi_{4}\right), \quad c_{1}, c_{2}, c_{3}, c_{4} \geq 0
$$

with homogeneous $m$.
Here $\xi_{\text {out }}:= \pm \xi_{1} \pm \xi_{2} \pm \xi_{3}$ represents the output frequency. For such symbols we also have the following result (see again [12, 27, 31, 32]):

Proposition 2.3. Let $L_{0}$ be an order zero trilinear form as above. Then we have

$$
\|L(f, g, h)\|_{L^{r}} \lesssim\|f\|_{L^{p}}\|g\|_{L^{q}}\|h\|_{L^{s}}, \quad \frac{1}{p}+\frac{1}{q}+\frac{1}{s}=\frac{1}{r}, \quad 1<r<\infty, \quad p, q, s>1
$$

Since our problem is a system and the two variables $(W, Q)$ correspond to different homogeneities, we will also need notations for homogeneous bilinear and trilinear forms. Precisely, for $k \in \mathbb{Z}$ we define classes $\left(\mathfrak{B}_{k}^{2}, \mathfrak{C}_{k}^{2}\right)$, respectively $\left(\mathfrak{B}_{k}^{3}, \mathfrak{C}_{k}^{3}\right)$ of bilinear and trilinear forms as follows:

- $\mathfrak{B}_{k}^{2}(W, Q)$ contains bilinear forms of the type $L_{k+1}(W, W)+L_{k}(Q, Q)$.
- $\mathfrak{C}_{k}^{2}(W, Q)$ contains bilinear forms of the type $L_{k+1}(W, Q)$.
- $\mathfrak{B}_{k}^{3}(W, Q)$ contains bilinear forms of the type $L_{k+2}(W, W, W)+L_{k+1}(W, Q, Q)$.
- $\mathfrak{C}_{k}^{3}(W, Q)$ contains bilinear forms of the type $L_{k+2}(W, W, Q)+L_{k+1}(Q, Q, Q)$.


## 3. Normal form expansions and corrections

In this section we collect most of our normal form computations. The goal here is twofold; first to use quadratic normal form corrections in order to eliminate the quadratic terms in the equation, and then to use cubic normal form corrections in order to eliminate certain non-resonant parts of cubic terms in the equation.

To understand these computations, one needs to start from the dispersion relation associated to the linear system

$$
\left\{\begin{array}{l}
W_{t}+Q_{\alpha}=0  \tag{3.1}\\
Q_{t}+i W_{\alpha \alpha}=0,
\end{array}\right.
$$

on holomorphic functions. Recast as a scalar equation this becomes

$$
\left(\partial_{t}^{2}+i \partial_{\alpha}^{3}\right) W=0,
$$

which immediately leads to the dispersion relation

$$
\tau= \pm|\xi|^{\frac{3}{2}}, \quad \xi<0
$$

Thus resonances in bilinear interactions correspond to zeroes of the expression $|\xi|^{\frac{3}{2}} \pm|\eta|^{\frac{3}{2}} \pm$ $|\xi+\eta|^{\frac{3}{2}}$. But this cannot vanish unless either $\xi$ or $\eta$ are zero. Consequently, all quadratic interactions are removable, but with an appropriate loss of derivatives at (the resonant) frequency zero. As a guideline, if $\xi$, and $\eta$ have dyadic sizes $\lambda_{0} \leq \lambda_{1}$, then in the worst case we have

$$
\left||\xi+\eta|^{\frac{3}{2}}-|\xi|^{\frac{3}{2}}-|\eta|^{\frac{3}{2}}\right| \approx \lambda_{0} \lambda_{1}^{\frac{1}{2}}
$$

Thus, compared to the quadratic component of the nonlinearity, the quadratic normal form looses one derivative at low frequency and half a derivative at high frequency. A similar analysis applies in the case of cubic energy errors. For later use, we observe that we have the relation

$$
\prod_{ \pm}|\xi|^{\frac{3}{2}} \pm|\eta|^{\frac{3}{2}} \pm|\xi+\eta|^{\frac{3}{2}}=\xi^{2} \eta^{2}\left(9 \xi^{2}+14 \xi \eta+9 \eta^{2}\right)
$$

The last expression above is elliptic, and will appear in the denominator of all symbols for bilinear normal form corrections later on.

Next we discuss trilinear terms. There we have four frequencies to deal with, $\xi_{1}, \xi_{2}$ and $\xi_{3}$ for the inputs, and $\xi_{0}= \pm \xi_{1} \pm \xi_{2} \pm \xi_{3}$ for the output. In this case we can have

$$
\left|\xi_{1}\right|^{\frac{3}{2}} \pm\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{1}\right|^{\frac{3}{2}} \pm\left|\xi_{2}\right|^{\frac{3}{2}}=0
$$

if and only if there are two pairs of equal frequencies and matching signs in the last relation. Fortunately in our analysis we only need to consider the case where the four dyadic frequencies are unbalanced,

$$
\lambda_{0} \ll \lambda_{1} \underset{10}{\leq} \lambda_{2} \approx \lambda_{3}
$$

Then the interactions are non-resonant, and we have as in the bilinear case

$$
\begin{equation*}
\left|\left|\xi_{1}\right|^{\frac{3}{2}} \pm\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{1}\right|^{\frac{3}{2}} \pm\left|\xi_{2}\right|^{\frac{3}{2}}\right| \gtrsim \lambda_{1} \lambda_{2}^{\frac{1}{2}} \tag{3.2}
\end{equation*}
$$

3.1. The main normal form transformation. We begin with the quadratic and cubic expansion in the equation (1.7), and then we compute the normal form transformation which eliminates the quadratic terms from the equation. Starting with

$$
F \approx Q_{\alpha}-Q_{\alpha} W_{\alpha}+P\left[\bar{Q}_{\alpha} W_{\alpha}-Q_{\alpha} \bar{W}_{\alpha}\right]+P\left[\left(Q_{\alpha}-\bar{Q}_{\alpha}\right)\left(4\left|\Re W_{\alpha}\right|^{2}-\left|W_{\alpha}\right|^{2}\right)\right]
$$

we compute the multilinear expansion:

$$
\left\{\begin{array}{l}
W_{t}+Q_{\alpha}=G^{(2)}+G^{(3)}+G^{(4+)}  \tag{3.3}\\
Q_{t}+i W_{\alpha \alpha}=K^{(2)}+K^{(3)}+K^{(4+)}
\end{array}\right.
$$

where the quadratic terms $\left(G^{(2)}, K^{(2)}\right) \in\left(\mathfrak{C}_{-1}^{2}\left(W_{\alpha}, Q_{\alpha}\right), \mathfrak{B}_{0}^{2}\left(W_{\alpha}, Q_{\alpha}\right)\right)$ are given by

$$
\left\{\begin{array}{l}
G^{(2)}:=P\left[Q_{\alpha} \bar{W}_{\alpha}-\bar{Q}_{\alpha} W_{\alpha}\right]  \tag{3.4}\\
K^{(2)}:=-Q_{\alpha}^{2}-P\left[\left|Q_{\alpha}\right|^{2}\right]+\frac{i}{2} P\left[W_{\alpha \alpha}\left(3 W_{\alpha}+\bar{W}_{\alpha}\right)-\bar{W}_{\alpha \alpha} W_{\alpha}\right]
\end{array}\right.
$$

and the cubic terms $\left(G^{(3)}, K^{(3)}\right)$ are given by

$$
\left\{\begin{align*}
G^{(3)}= & W_{\alpha}\left(Q_{\alpha} W_{\alpha}-P\left[\bar{Q}_{\alpha} W_{\alpha}-Q_{\alpha} \bar{W}_{\alpha}\right]\right)-P\left[\left(Q_{\alpha}-\bar{Q}_{\alpha}\right)\left(4\left|\Re W_{\alpha}\right|^{2}-\left|W_{\alpha}\right|^{2}\right)\right]  \tag{3.5}\\
K^{(3)}= & Q_{\alpha}\left(Q_{\alpha} W_{\alpha}-P\left[\bar{Q}_{\alpha} W_{\alpha}-Q_{\alpha} \bar{W}_{\alpha}\right]\right)+2 P\left[\Re \mathbf{W}_{\alpha}\left|Q_{\alpha}\right|^{2}\right] \\
& -i P\left[W_{\alpha \alpha}\left(\frac{15}{8} W_{\alpha}^{2}+\frac{3}{4}\left|W_{\alpha}\right|^{2}+\frac{3}{8} \bar{W}_{\alpha}^{2}\right)-\bar{W}_{\alpha \alpha}\left(\frac{3}{4}\left|W_{\alpha}\right|^{2}+\frac{3}{8} W_{\alpha}^{2}\right)\right]
\end{align*}\right.
$$

The role of the normal form transformation is to eliminate the quadratic terms $\left(G^{(2)}, K^{(2)}\right)$ from the equation (3.3). It is obtained as follows:

Proposition 3.1. The normal form transformation for the equation (3.3) is given by

$$
\left\{\begin{align*}
\tilde{W} & =W+W_{[2]}  \tag{3.6}\\
\tilde{Q} & =Q+Q_{[2]}
\end{align*}\right.
$$

where the bilinear forms $\left(W_{[2]}, Q_{[2]}\right) \in\left(\mathfrak{B}_{0}(W, Q), \mathfrak{C}_{0}(W, Q)\right)$ have the form

$$
\left\{\begin{align*}
W_{[2]} & =B^{h}(W, W)+C^{h}(Q, Q)+B^{a}(W, \bar{W})+C^{a}(Q, \bar{Q})  \tag{3.7}\\
Q_{[2]} & =A^{h}(W, Q)+A^{a}(W, \bar{Q})+D^{a}(Q, \bar{W}),
\end{align*}\right.
$$

with $A^{h}, A^{a}, B^{h}, B^{a}, D^{a} \in O P \mathfrak{M}^{1}$, while $C^{h}, C^{a} \in O P \mathfrak{M}^{0}$, whose symbols are as follows:

$$
\begin{gathered}
B^{h}=-i(\xi+\eta) \frac{\frac{9}{4}(\xi+\eta)^{2}-2 \xi \eta}{9(\xi+\eta)^{2}-4 \xi \eta}, \quad C^{h}=-i \frac{\frac{3}{2}(\xi+\eta)^{2}}{9(\xi+\eta)^{2}-4 \xi \eta} \\
A^{h}=i \frac{3 \xi^{3}-\frac{3}{2} \xi^{2} \eta-5 \xi \eta^{2}-\frac{9}{2} \eta^{3}}{9(\xi+\eta)^{2}-4 \xi \eta} \\
11
\end{gathered}
$$

respectively

$$
\begin{cases}A^{a}(\zeta, \eta)=\frac{3 i(\xi+\eta)\left(\xi^{2}+\frac{3}{2} \xi \eta+\frac{3}{2} \eta^{2}\right)}{9(\xi+\eta)^{2}-4 \xi \eta}, & B^{a}(\zeta, \eta)=\frac{-i(\xi+\eta)\left(\frac{9}{2} \xi^{2}+\frac{19}{2} \xi \eta+6 \eta^{2}\right)}{9(\xi+\eta)^{2}-4 \xi \eta} \\ C^{a}(\zeta, \eta)=\frac{-3 i(\xi+\eta)^{2}}{9(\xi+\eta)^{2}-4 \xi \eta}, & D^{a}(\zeta, \eta)=\frac{-i(\xi+\eta)\left(\frac{9}{2}(\xi+\eta)^{2}-4 \xi \eta\right)}{9(\xi+\eta)^{2}-4 \xi \eta}\end{cases}
$$

We postpone the proof of the Proposition 3.1 for the end of the section, and instead we discuss some consequences.

The main direct consequence of the normal form transformation is the fact that the normal form variables $(\tilde{W}, \tilde{Q})$ solve a cubic equation,

$$
\left\{\begin{array}{c}
\tilde{W}_{t}+\tilde{Q}_{\alpha}=\tilde{G}(W, Q)  \tag{3.8}\\
\tilde{Q}_{t}+i \tilde{W}_{\alpha \alpha}=\tilde{K}(W, Q)
\end{array}\right.
$$

where the expressions $(\tilde{G}, \tilde{K})$ contain only cubic and higher order terms.
These equations cannot be used directly at high frequencies, as they neglect the quasilinear character of the problem. However, they are very useful at low frequencies, where one can roughly view the problem as a semilinear equation. For later use we decompose them into cubic and higher order terms,

$$
\tilde{G}=\tilde{G}^{(3)}+\tilde{G}^{(4+)}, \quad \tilde{K}=\tilde{K}^{(3)}+\tilde{K}^{(4+)},
$$

where

$$
\left\{\begin{align*}
\tilde{G}^{(3)}=2 B^{h}\left(G^{(2)}, W\right) & +2 C^{h}\left(K^{(2)}, Q\right)+B^{a}\left(G^{(2)}, \bar{W}\right)+B^{a}\left(W, \bar{G}^{(2)}\right)  \tag{3.9}\\
& +\left(C^{a}\left(K^{(2)}, \bar{Q}\right)+C^{a}\left(Q, \bar{K}^{(2)}\right)\right)+G^{(3)}(W, Q) \\
\tilde{K}^{(3)}=A^{h}\left(W, K^{(2)}\right) & +A^{h}\left(G^{(2)}, Q\right)+A^{a}\left(G^{(2)}, \bar{Q}\right)+A^{a}\left(W, \bar{K}^{(2)}\right)+D^{a}\left(K^{(2)}, \bar{W}\right) \\
& +D^{a}\left(Q, \bar{G}^{(2)}\right)+K^{(3)}(W, Q)
\end{align*}\right.
$$

and

$$
\left\{\begin{aligned}
\tilde{G}^{(4+)}=2 B^{h}\left(G^{(3+)}, W\right) & +2 \sigma^{-1} C^{h}\left(K^{(3+)}, Q\right)+B^{a}\left(G^{(3+)}, \bar{W}\right)+B^{a}\left(W, \bar{G}^{(3+)}\right) \\
& +\sigma^{-1}\left(C^{a}\left(K^{(3+)}, \bar{Q}\right)+C^{a}\left(Q, \bar{K}^{(3+)}\right)\right)+G^{(4+)}(W, Q) \\
\tilde{K}^{(4+)}=A^{h}\left(W, K^{(3+)}\right) & +A^{h}\left(G^{(3+)}, Q\right)+A^{a}\left(G^{(3+)}, \bar{Q}\right)+A^{a}\left(W, \bar{K}^{(3+)}\right)+D^{a}\left(\bar{K}^{(3+)}, \bar{W}\right) \\
& +D^{a}\left(Q, \bar{G}^{(3+)}\right)+K^{(4+)}(W, Q) .
\end{aligned}\right.
$$

While the above expressions are somewhat more complicated than pure multiplication operators, for some of our purposes it will suffice to extract the leading order term in the normal form expression and treat the rest in a simpler manner. For the low frequency portion of the energy estimates we will be particularly interested in the contributions which contain undifferentiated $W$, and, to a lesser extent, those containing undifferentiated $Q$ 's. To compute those, we first consider the expansion for $(\tilde{W}, \tilde{Q})$, which is:

$$
\left\{\begin{align*}
\tilde{W} & =W-\frac{1}{2} \Re W W_{\alpha}-i\left(\frac{1}{6} Q^{2}+\frac{1}{3} \bar{Q} Q\right)+L_{-1}\left(W_{\alpha}, W_{\alpha}\right)+L_{-2}\left(Q_{\alpha}, Q_{\alpha}\right)  \tag{3.10}\\
\tilde{Q} & =Q-\frac{1}{2} \Re W Q_{\alpha}-\frac{1}{3} \Re Q W_{\alpha}+L_{-1}\left(W_{\alpha}, Q_{\alpha}\right) .
\end{align*}\right.
$$

Now we observe that only the time differentiation of the leading terms can yield expressions with undifferentiated $W$ or $Q$. One can see this with a computation as follows:

$$
\frac{d}{d t} L_{-1}\left(W_{\alpha}, Q_{\alpha}\right)=L_{0}\left(W_{t}, Q_{\alpha}\right)+L_{0}\left(W_{\alpha}, Q_{t}\right)
$$

Thus using (3.10) we can compute

$$
\left\{\begin{array}{l}
\tilde{G}^{(3)}=-\frac{1}{2} \Re W G^{(2), \alpha}+L_{0}\left(W_{\alpha}, W_{\alpha}, Q_{\alpha}\right)+L_{0}\left(Q, Q_{\alpha}, Q_{\alpha}\right)  \tag{3.11}\\
\tilde{K}^{(3)}=-\frac{1}{2} \Re W K^{(2), \alpha}-\frac{1}{3} \Re Q G^{(2), \alpha}+L_{0}\left(Q_{\alpha}, Q_{\alpha}, W_{\alpha}\right)+L_{0}\left(W_{\alpha}, W_{\alpha}, W_{\alpha \alpha}\right)
\end{array}\right.
$$

Finally, for the global pointwise estimates in the last section, we primarily need to understand the resonant interactions of three equal frequency waves. These are not always captured in the expansion in (3.10).

Proof of Proposition 3.1. We distinguish two types of quadratic terms on the right in (3.3), the holomorphic ones and the mixed ones. The normal forms for the two are completely separate, so we do two computations:
(i) Holomorphic terms: Here we work with the system

$$
\left\{\begin{array}{l}
W_{t}+Q_{\alpha}=\text { cubic } \\
Q_{t}+i W_{\alpha \alpha}=-Q_{\alpha}^{2}+\frac{3 i}{2} W_{\alpha \alpha} W_{\alpha}+\text { cubic }
\end{array}\right.
$$

By checking parity, our normal form must be

$$
\tilde{W}=W+B^{h}(W, W)+C^{h}(Q, Q), \quad \tilde{Q}=Q+A^{h}(W, Q)
$$

where $B^{h}$ and $C^{h}$ are symmetric bilinear forms with symbols $B^{h}(\xi, \eta), C^{h}(\xi, \eta)$ and $A^{h}$ is arbitrary.

We compute

$$
\left\{\begin{aligned}
\tilde{W}_{t}+\tilde{Q}_{\alpha}= & -2 B^{h}\left(W, Q_{\alpha}\right)-2 i C^{h}\left(W_{\alpha \alpha}, Q\right)+\partial_{\alpha} A^{h}(W, Q)+\text { cubic } \\
\tilde{Q}_{t}+i \tilde{W}_{\alpha \alpha}= & -A^{h}\left(Q_{\alpha}, Q\right)-i \sigma A^{h}\left(W, W_{\alpha \alpha}\right)+i \partial_{\alpha}^{2}\left(B^{h}(W, W)+C^{h}(Q, Q)\right)-Q_{\alpha}^{2} \\
& +\frac{3 i}{2} W_{\alpha \alpha} W_{\alpha}+\text { cubic. }
\end{aligned}\right.
$$

We denote the two input frequencies by $\xi$ and $\eta$. Then for the symbols we get

$$
\left\{\begin{array}{l}
2 \eta B^{h}-2 \xi^{2} C^{h}-(\xi+\eta) A^{h}=0 \\
\left(\xi A^{h}\right)_{s y m}+(\xi+\eta)^{2} C^{h}=-i \xi \eta \\
\left(\eta^{2} A^{h}\right)_{s y m}-(\xi+\eta)^{2} B^{h}=\frac{3 i}{4} \xi \eta(\xi+\eta)
\end{array}\right.
$$

Here sym stands for the symmetrization. From the first equation we get

$$
A^{h}=\frac{1}{\xi+\eta}\left(2 \eta B^{h}-2 \xi^{2} C^{h}\right)
$$

Hence

$$
\left(\xi A^{h}\right)_{s y m}=\frac{1}{\xi+\eta}\left(2 \xi \eta B^{h}-\left(\xi^{3}+\eta^{3}\right) C^{h}\right), \quad\left(\eta^{2} A^{h}\right)_{s y m}=\frac{1}{\xi+\eta}\left(\left(\xi^{3}+\eta^{3}\right) B^{h}-2 \xi^{2} \eta^{2} C^{h}\right)
$$

Replacing back into the original equations we get

$$
\left\{\begin{array}{l}
2 \xi \eta B^{h}+3 \xi \eta(\xi+\eta) C^{h}=-i \xi \eta(\xi+\eta) \\
3 \xi \eta(\xi+\eta) B^{h}+2 \xi^{2} \eta^{2} C^{h}=-\frac{3 i}{4} \xi \eta(\xi+\eta)^{2}
\end{array}\right.
$$

and after simplifications

$$
\left\{\begin{array}{l}
2 B^{h}+3(\xi+\eta) C^{h}=-i(\xi+\eta) \\
3(\xi+\eta) B^{h}+2 \xi \eta C^{h}=-\frac{3 i}{4}(\xi+\eta)^{2}
\end{array}\right.
$$

Solving this yields

$$
\begin{gathered}
A^{h}=i \frac{3 \xi^{3}-\frac{3}{2} \xi^{2} \eta-5 \xi \eta^{2}-\frac{9}{2} \eta^{3}}{9(\xi+\eta)^{2}-4 \xi \eta} \\
B^{h}=-i(\xi+\eta) \frac{\frac{9}{4}(\xi+\eta)^{2}-2 \xi \eta}{9(\xi+\eta)^{2}-4 \xi \eta}, \quad C^{h}=-i \frac{\frac{3}{2}(\xi+\eta)^{2}}{9(\xi+\eta)^{2}-4 \xi \eta}
\end{gathered}
$$

Here the denominator is always nonzero.
(ii) Mixed terms: Here we have

$$
\left\{\begin{array}{l}
W_{t}+Q_{\alpha}=P\left[Q_{\alpha} \bar{W}_{\alpha}-\bar{Q}_{\alpha} W_{\alpha}\right]+\text { cubic } \\
Q_{t}+i W_{\alpha \alpha}=-P\left[\left|Q_{\alpha}\right|^{2}\right]+\frac{i}{2} P\left[W_{\alpha \alpha} \bar{W}_{\alpha}-\bar{W}_{\alpha \alpha} W_{\alpha}\right]+\text { cubic }
\end{array}\right.
$$

By checking parity, our normal form must be

$$
\tilde{W}=W+B^{a}(W, \bar{W})+C^{a}(Q, \bar{Q}), \quad \tilde{Q}=Q+A^{a}(W, \bar{Q})+D^{a}(Q, \bar{W})
$$

where $B^{a}$ and $C^{a}$ are even bilinear forms and $A^{a}$ is arbitrary.
We compute

$$
\left\{\begin{aligned}
\tilde{W}_{t}+\tilde{Q}_{\alpha}= & -B^{a}\left(W, \bar{Q}_{\alpha}\right)-B^{a}\left(Q_{\alpha}, \bar{W}\right)-i C^{a}\left(W_{\alpha \alpha}, \bar{Q}\right)+i C^{a}\left(Q, \bar{W}_{\alpha \alpha}\right) \\
& +\partial_{\alpha} A^{a}(W, \bar{Q})+\partial_{\alpha} D^{a}(Q, \bar{W})+P\left[Q_{\alpha} \bar{W}_{\alpha}-\bar{Q}_{\alpha} W_{\alpha}\right]+c u b i c \\
\tilde{Q}_{t}+i \tilde{W}_{\alpha \alpha}= & -A^{a}\left(Q_{\alpha}, \bar{Q}\right)+i A^{a}\left(W, \bar{W}_{\alpha \alpha}\right)-D^{a}\left(Q, \bar{Q}_{\alpha}\right)-i D^{a}\left(W_{\alpha \alpha}, \bar{W}\right)-P\left[\left|Q_{\alpha}\right|^{2}\right] \\
& +i \partial_{\alpha}^{2}\left(B^{a}(W, \bar{W})+C^{a}(Q, \bar{Q})\right)+\frac{i}{2} P\left[W_{\alpha \alpha} \bar{W}_{\alpha}-\bar{W}_{\alpha \alpha} W_{\alpha}\right]+c u b i c .
\end{aligned}\right.
$$

We denote the two input frequencies by $\zeta$ and $\eta$, where $\eta$ is always associated to the function that is conjugated. Matching the like terms we get the symbol relations

$$
\left\{\begin{array}{l}
i \eta B^{a}+i \zeta^{2} C^{a}+i(\zeta-\eta) A^{a}=\zeta \eta \\
-i \zeta B^{a}-i \eta^{2} C^{a}+i(\zeta-\eta) D^{a}=-\zeta \eta \\
-i \zeta A^{a}+i \eta D^{a}-i(\zeta-\eta)^{2} C^{a}=\zeta \eta \\
-i \eta^{2} A^{a}+i \zeta^{2} D^{a}-i(\zeta-\eta)^{2} B^{a}=\frac{1}{2} \zeta \eta(\zeta+\eta)
\end{array}\right.
$$

After algebraic manipulations we pull out a factor of $\eta^{2}(\zeta-\eta)^{2}$ to obtain the simpler system

$$
\left[\begin{array}{cccc}
1 & -1 & \zeta+\eta & 1 \\
0 & \zeta & \eta^{2} & \eta-\zeta \\
0 & -2 & \eta & -1 \\
0 & 0 & 3 \zeta & 2
\end{array}\right]_{14}\left[\begin{array}{l}
A \\
B \\
C \\
D
\end{array}\right]=-i \zeta\left[\begin{array}{c}
0 \\
\eta \\
-\frac{3}{2} \\
2
\end{array}\right]
$$

This has solutions

$$
\begin{cases}A^{a}=\frac{3 i \zeta\left(\zeta^{2}-\frac{1}{2} \zeta \eta+\eta^{2}\right)}{9 \zeta^{2}-4 \zeta \eta+4 \eta^{2}}, & B^{a}=\frac{-i \zeta\left(\frac{9}{2} \zeta^{2}+\frac{1}{2} \zeta \eta+\eta^{2}\right)}{9 \zeta^{2}-4 \zeta \eta+4 \eta^{2}} \\ C^{a}=\frac{-3 i \zeta^{2}}{9 \zeta^{2}-4 \zeta \eta+4 \eta^{2}}, & D^{a}=\frac{-i \zeta\left(\frac{9}{2} \zeta^{2}-4 \zeta \eta+4 \eta^{2}\right)}{9 \zeta^{2}-4 \zeta \eta+4 \eta^{2}}\end{cases}
$$

Substituting $\zeta=\xi+\eta$ we obtain the relations from the proposition.
3.2. Cubic normal form corrections. Here we construct a cubic normal form correction for a trilinear non-resonant form. We will apply our result both to the water wave equation and to its linearization, so it is convenient to work with uncoupled variables ( $W_{\alpha}^{1}, Q_{\alpha}^{1}$ ), $\left(W_{\alpha}^{2}, Q_{\alpha}^{2}\right),\left(W_{\alpha}^{3}, Q_{\alpha}^{3}\right)$.

Proposition 3.2. Suppose that $\left(W_{\alpha}^{1}, Q_{\alpha}^{1}\right),\left(W_{\alpha}^{2}, Q_{\alpha}^{2}\right),\left(W_{\alpha}^{3}, Q_{\alpha}^{3}\right)$ solve the linear system (3.1) and have frequencies restricted to the range

$$
\left|\xi_{1}+\xi_{2}-\xi_{3}\right| \ll \min \left\{\left|\xi_{1}\right|,\left|\xi_{2}\right|\right\} .
$$

a) Consider trilinear forms of type $(2,1)$ or $(1,2)$,

$$
(G, K) \in\left(\mathfrak{C}_{-2}\left(\left(W_{\alpha}^{1} Q_{\alpha}^{1}\right),\left(W_{\alpha}^{2}, Q_{\alpha}^{2}\right),\left(W_{\alpha}^{3} Q_{\alpha}^{3}\right)\right), \mathfrak{B}_{-1}\left(\left(W_{\alpha}^{1} Q_{\alpha}^{1}\right),\left(W_{\alpha}^{2}, Q_{\alpha}^{2}\right),\left(W_{\alpha}^{3} Q_{\alpha}^{3}\right)\right)\right) .
$$

Then there exists trilinear forms

$$
\left(W_{[3]}, Q_{[3]}\right) \in\left(\mathfrak{B}_{0}\left(\left(W^{1}, Q^{1}\right),\left(W^{2}, Q^{2}\right),\left(W^{3}, Q^{3}\right)\right), \mathfrak{C}_{0}\left(\left(W^{1}, Q^{1}\right),\left(W^{2}, Q^{2}\right),\left(W^{3}, Q^{3}\right)\right)\right)
$$

so that we have

$$
\left\{\begin{array}{l}
W_{[3], t}+Q_{[3], \alpha}=G  \tag{3.12}\\
Q_{[3], t}+i W_{[3], \alpha \alpha}=K .
\end{array}\right.
$$

We note that there are more parity combinations possible in a result of this type. To shorten the computations, we confine ourselves to the situation above, which is the only one occurring in the present paper.

Proof. To limit the number of cases in our discussion we confine ourselves to $(2,1)$ forms, and also set $G=0$. The remaining cases are all quite similar. Then there are four terms in $K$,

$$
K=K_{1}\left(W_{\alpha}^{1}, W_{\alpha}^{2}, \bar{Q}_{\alpha}^{3}\right)+K_{2}\left(W_{\alpha}^{1}, Q_{\alpha}^{2}, W_{\alpha}^{3}\right)+K_{3}\left(Q_{\alpha}^{1}, W_{\alpha}^{2}, W_{\alpha}^{3}\right)+K_{4}\left(W_{\alpha}^{1}, W_{\alpha}^{2}, W_{\alpha}^{3}\right)
$$

Substituting directly into the equations, we would obtain an $8 \times 8$ system, which is fairly large. Hence it is convenient to diagonalize it first. For that we make the substitution

$$
Z_{ \pm}^{j}:=Q^{j} \pm i|D|^{\frac{1}{2}} W^{j},
$$

where $Z_{ \pm}^{j}$ solve the scalar equations

$$
\partial_{t} Z_{ \pm}^{j}= \pm i|D|^{\frac{3}{2}} Z_{ \pm}^{j} .
$$

Further, we set

$$
Z_{[3], \pm}:=Q_{[3]} \pm i|D|^{\frac{1}{2}} W_{[3]} .
$$

Then the system (3.12) reads

$$
\partial_{t} Z_{[3], \pm}= \pm i|D|^{\frac{3}{2}} Z_{ \pm}^{j}+K
$$

If we were to set

$$
K:=K_{ \pm, \pm, \pm}=Z_{ \pm}^{1} Z_{ \pm}^{2} \bar{Z}_{ \pm}^{3}
$$

then for $Z_{[3], \pm}$ we obtain the expression

$$
Z_{[3], \pm}=L_{ \pm, \pm, \pm, \pm}\left(Z_{ \pm}^{1}, Z_{ \pm}^{2}, \bar{Z}_{ \pm}^{3}\right),
$$

where the multilinear form $L_{ \pm, \pm, \pm, \pm}$has symbol

$$
L_{ \pm, \pm, \pm, \pm}\left(\xi_{0}, \xi_{1}, \xi_{2}, \xi_{3}, \xi_{4}\right)=\frac{-i}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}
$$

Here the signs on the bottom correspond to complex conjugates in the corresponding quadrilinear form. In our case we have an expression in $W^{i}$ and $Q^{i}$, which must be written in terms of $Z_{ \pm}^{i}$, and the final result must be reexpressed in terms of $W^{i}$ and $Q^{i}$. Thus we obtain a combination of symmetrizations and antisymmetrizations of the above symbol with respect to the four signs. Half of these are zero by symmetry. For the rest, we quickly list them and describe their size.

We begin with the terms in $Q_{[3]}$, for which we have the following symbols based on the arguments for inputs and for the outputs.

$$
\begin{aligned}
& L(W W W \rightarrow W W Q)=\sum_{ \pm} \frac{-\left( \pm\left|\xi_{3}\right|^{-\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}, \\
& L(W W W \rightarrow Q Q Q)=\sum_{ \pm} \frac{\left( \pm\left|\xi_{1}\right|^{-\frac{1}{2}}\right)\left( \pm\left|\xi_{2}\right|^{-\frac{1}{2}}\right)\left( \pm\left|\xi_{3}\right|^{-\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}, \\
& L(W Q Q \rightarrow Q Q Q)=\sum_{ \pm} \frac{-\left( \pm\left|\xi_{1}\right|^{-\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}, \\
& L(W Q Q \rightarrow W W Q)=\sum_{ \pm} \frac{-\left( \pm\left|\xi_{2}\right|^{\frac{-1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}, \\
& L(W Q Q \rightarrow Q W W)=\sum_{ \pm} \frac{-\left(\mp\left|\xi_{1}\right|^{\frac{1}{2}}\right)\left( \pm\left|\xi_{2}\right|^{-\frac{1}{2}}\right)\left( \pm\left|\xi_{3}\right|^{-\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}} .
\end{aligned}
$$

Here the signs on the top are matched to the signs associated to the same variable on the bottom. We need to understand the size of these symbols when $\left|\xi_{0}\right| \ll\left|\xi_{\text {med }}\right|:=$ $\min \left\{\left|\xi_{1}\right|,\left|\xi_{2}\right|,\left|\xi_{3}\right|\right\}$. We also denote $\left|\xi_{h i}\right|:=\max \left\{\left|\xi_{1}\right|,\left|\xi_{2}\right|,\left|\xi_{3}\right|\right\}$. We first look at the size of the denominators, for which we use the relation (3.2). This suffices if we have only high frequencies in the numerator, and we get a symbol bound of the type

$$
|L| \lesssim\left|\xi_{m e d}\right|^{-1}\left|\xi_{h i}\right|^{-k}
$$

where the integer $k$ is dictated by the corresponding homogeneity of $L$. It is also not difficult to see that all half integer powers disappear in the symmetrizations, and by taking a Taylor series at $\xi_{0}=0$ we are left with a sum of polyhomogeneous symbols and a smooth (i.e., with many derivatives) remainder.

Consider now the case when the medium frequency appears in the numerator with a negative power. Then the sum is antisymmetrized with respect to the medium frequency, so we get an extra cancellation, as in

$$
\begin{gathered}
\frac{|\xi|_{\text {med }}^{-\frac{1}{2}}}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}}+\left|\xi_{\text {med }}\right|^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}-\frac{|\xi|^{-\frac{1}{2}}}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}}-\left|\xi_{\text {med }}\right|^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}= \\
\frac{-2\left|\xi_{\text {med }}\right|}{\left( \pm\left|\xi_{0}\right|^{\frac{3}{2}}+\left|\xi_{\text {med }}\right|^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}\right)\left( \pm\left|\xi_{0}\right|^{\frac{3}{2}}-\left|\xi_{\text {med }}\right|^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}\right)}
\end{gathered}
$$

Then we obtain the same symbol bound as before.
We continue with the terms in $W_{[3]}$, for which we have the following symbols based on the arguments for inputs and for the outputs.

$$
\begin{aligned}
& L(W W W \rightarrow W W W)=\sum_{ \pm} \frac{-\left( \pm\left|\xi_{0}\right|^{-\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}, \\
& L(W W W \rightarrow W Q Q)=\sum_{ \pm} \frac{\left( \pm\left|\xi_{0}\right|^{-\frac{1}{2}}\right)\left( \pm\left|\xi_{2}\right|^{-\frac{1}{2}}\right)\left( \pm\left|\xi_{3}\right|^{-\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}, \\
& L(W Q Q \rightarrow W Q Q)=\sum_{ \pm} \frac{-\left( \pm\left|\xi_{0}\right|^{-\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}, \\
& L(W Q Q \rightarrow Q W Q)=\sum_{ \pm} \frac{-\left( \pm\left|\xi_{0}\right|^{-\frac{1}{2}}\right)\left( \pm\left|\xi_{1}\right|^{-\frac{1}{2}}\right)\left(\mp\left|\xi_{2}\right|^{\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}}, \\
& L(W Q Q \rightarrow W W W)=\sum_{ \pm} \frac{\left( \pm\left|\xi_{0}\right|^{-\frac{1}{2}}\right)\left( \pm\left|\xi_{2}\right|^{-\frac{1}{2}}\right)\left( \pm\left|\xi_{3}\right|^{-\frac{1}{2}}\right)}{ \pm\left|\xi_{0}\right|^{\frac{3}{2}} \mp|\xi|_{1}^{\frac{3}{2}} \mp\left|\xi_{2}\right|^{\frac{3}{2}} \pm\left|\xi_{3}\right|^{\frac{3}{2}}} .
\end{aligned}
$$

The size of these symbols is better than before, in spite of the bad factor $\left|\xi_{0}\right|^{-\frac{1}{2}}$. Indeed, the antisymmetrization with respect to $\xi_{0}$ yields a $\left|\xi_{0}\right|$ factor instead, and we obtain a very favorable bound

$$
|L| \lesssim\left|\xi_{h i}\right|^{k}
$$

and a matching polyhomogeneous expression. Thus the proof of the Proposition is concluded.

## 4. The quasilinear modified energy method at high frequencies

The main idea in this section is to use the normal form transformation constructed in the previous section in order to produce a cubic energy functional for our problem in $\dot{\mathcal{H}}^{k}$ for $k \geq 2$. The properties of this energy functional are summarized in the following proposition:

Proposition 4.1. For any $n \geq 3$ there exists an energy functional $E^{n,(3)}$ which has the following properties as long as $A \ll 1$ :
(i) Norm equivalence:

$$
E^{n,(3)}(\mathbf{W}, R)=(1+O(A)) E_{0}\left(\partial^{n-1} \mathbf{W}, \partial^{n-1} R\right)
$$

(ii) Cubic energy estimates:

$$
\frac{d}{d t} E^{n,(3)}(\mathbf{W}, R) \lesssim_{A} A B E^{n,(3)}(\mathbf{W}, R)
$$

The conclusion of Theorem 3 is obtained in a standard fashion from this proposition via Gronwall's inequality and Sobolev embeddings. Since $A$ and $B$ are also controlled by $\|(W, Q)\|_{X}$, it also serves to prove that the bootstrap assumption (1.24) implies the high frequency part of the $(W, Q)$ bound in (1.20), namely

$$
\begin{equation*}
\|(W, Q)\|_{\dot{\mathcal{H}}^{10}} \lesssim \epsilon t^{C \epsilon^{2}} \tag{4.1}
\end{equation*}
$$

Proof. The proof uses the modified energy method introduced in [21], [20], which is in some sense a quasilinear improvement of Shatah's normal form method [35]. The analysis begins with following two remarks:

- On one hand, one can construct a quasilinear energy functional $E_{n l}^{n}$ for our problem, which is equivalent to the $\dot{\mathcal{H}}^{n}$ energy of $(W, Q)$, and for which we have straightforward energy estimates. However, these estimates are quadratic, in the sense that

$$
\frac{d}{d t} E_{n l}^{n} \lesssim A B\|(W, Q)\|_{\mathcal{H}^{n}}^{2}
$$

- On the other hand, using the normal form variables $(\tilde{W}, \tilde{Q})$, one can define a normal form energy $E_{N F, 0}^{n}$, given by

$$
E_{N F, 0}^{n}=\int\left(\left|\tilde{W}^{(n)}\right|^{2}+\Im\left[\tilde{Q}^{(n)} \overline{\tilde{Q}}_{\alpha}^{(n)}\right]\right) d \alpha
$$

This satisfies cubic estimates, but they involve higher derivatives,

$$
\frac{d}{d t} E_{N F, 0}^{n} \lesssim{ }_{A} A B\|(W, Q)\|_{\dot{\mathcal{H}}^{n} \cap \dot{\mathcal{H}}^{n+3}}
$$

which do not close. Further, the normal form energy is not equivalent to the $\dot{\mathcal{H}}^{n}$ energy of $(W, Q)$, and also contains undifferentiated $W$ and $Q$ 's.
Our goal is to produce an energy functional $E^{n,(3)}$ which mixes the best features of both these energies. This means that its cubic expansion should match the cubic expansion of $E_{N F, 0}^{n}$, while its high frequency part must match the quasilinear energy. To achieve our goal we start with the normal form energy

$$
E_{N F, 0}^{n}=\int\left(\left|\tilde{W}^{(n)}\right|^{2}+\Im\left[\tilde{Q}^{(n)} \overline{\tilde{Q}}_{\alpha}^{(n)}\right]\right) d \alpha
$$

Since $(\tilde{W}, \tilde{Q})$ are normal form variables, this functional satisfies an energy equation of the form

$$
\begin{equation*}
\frac{d}{d t} E_{N F, 0}^{n}=\text { quartic }+ \text { higher }, \tag{4.2}
\end{equation*}
$$

but it has several defects:
(1) It is expressed in terms of $Q^{(n)}$ rather than the natural variable $R^{(n-1)}$.
(2) It is not equivalent to the linear energy $E_{\text {lin }}^{(2)}\left(\mathbf{W}^{(n-1)}, R^{(n-1)}\right)$.
(3) Its energy estimate has a loss of derivatives.

However, the last two issues concerning $E_{N F, 0}^{n}$ arise only at the level of quartic and higher order terms. This motivates our strategy, which is modify $E_{N F, 0}^{n}$ by quartic and higher terms to obtain a "good" energy $E^{n,(3)}$ without spoiling the cubic energy estimate (4.2). We carry out this procedure in two steps:
(i) We compute the cubic expansion of the normal form energy, separating a principal part, which only involves differentiation, and a lower order part, which uses bilinear multipliers.
(ii) We construct a modified normal form energy $E_{N F}^{n}$ that depends on ( $\mathbf{W}^{(n-1)}, R^{(n-1)}$ ) and is equivalent to the linearized energy $E_{\text {lin }}^{(2)}\left(\mathbf{W}^{(n-1)}, R^{(n-1)}\right)$; this addresses the issues (1) and (2) above, but not (3);
(iii) We consider the leading order part $E_{N F, h i g h}^{n}$ and modify that in a quasilinear fashion, in order to address the issue (3) above. This modification is in part inspired from the analysis of the linearized equation, and is needed due to the quasilinear nature of our problem. Thus, we obtain an energy $E^{n,(3)}$ with good cubic estimates.

Remark 4.2. The construction of the quasilinear modified energy in the current case turns out to be more involved than in the two dimensional gravitational non-surface tension water wave equations, see [20].

The expansion of the normal form energy $E_{N F, 0}^{n}$. We compute the leading part of $E_{N F, 0}^{n}$ and express it in terms of $(\mathbf{W}, R)$ and their derivatives; for this we retain the quadratic and cubic expressions that appear when expanding each of the terms $\left\|\partial^{n} \tilde{W}\right\|_{L^{2}}^{2},\left\|\partial^{n} \tilde{Q}\right\|_{\dot{H}^{\frac{1}{2}}}^{2}$ respectively.

We begin with the quadratic part of $E_{N F, 0}^{n}$, expressed in terms of $(W, Q)$, which is the integral

$$
I_{1}=\int\left|W^{(n)}\right|^{2}+\Im\left(\bar{Q}^{(n)} Q^{(n-1)}\right) d \alpha
$$

Next we look at the cubic part of $\left\|\partial^{n} \tilde{W}\right\|_{L^{2}}^{2}$, which is

$$
\begin{equation*}
\int_{\zeta=\xi+\eta} \bar{W}(\zeta) W(\xi) W(\eta)(\xi+\eta)^{2 n} B^{h}(\xi, \eta)+\bar{W}(\xi) W(\zeta) \bar{W}(\eta) \xi^{2 n} B(\zeta, \eta) d \xi d \eta+c . c . \tag{4.3}
\end{equation*}
$$

where $c . c$ stands for the complex conjugate, and is as follows

$$
\begin{equation*}
\int_{\zeta=\xi+\eta} W(\zeta) \bar{W}(\xi) \bar{W}(\eta)(\xi+\eta)^{2 n} \bar{B}^{h}(\xi, \eta)+W(\xi) \bar{W}(\zeta) W(\eta) \xi^{2 n} \bar{B}(\zeta, \eta) d \xi d \eta \tag{4.4}
\end{equation*}
$$

We add the first term in (4.3) with the last term in (4.4), and obtain

$$
\begin{equation*}
\int_{\zeta=\xi+\eta} \bar{W}(\zeta) W(\xi) W(\eta) \mathcal{B}_{\bar{W} W W}(\xi, \eta) d \xi d \eta+\int_{\zeta=\xi+\eta} W(\zeta) \bar{W}(\xi) \bar{W}(\eta) \overline{\mathcal{B}}_{\bar{W} W W}(\xi, \eta) d \xi d \eta \tag{4.5}
\end{equation*}
$$

where

$$
\begin{aligned}
\mathcal{B}_{\bar{W} W W}(\xi, \eta):= & (\xi+\eta)^{2 n} B^{h}(\xi, \eta)+\xi^{2 n} \bar{B}(\zeta, \eta) \\
= & \frac{i(\xi+\eta)}{9(\xi+\eta)^{2}-4 \xi \eta}\left[-(\xi+\eta)^{(2 n)}\left(\frac{9}{4}(\xi+\eta)^{2}-2 \xi \eta\right)\right. \\
& \left.\quad+\xi^{2 n}\left(\frac{9}{4} \xi^{2}+\frac{19}{4} \xi \eta+3 \eta^{2}\right)+\eta^{2}\left(\frac{9}{4} \eta^{2}+\frac{19}{4} \xi \eta+3 \xi^{2}\right)\right]
\end{aligned}
$$

Expanding the symbol $\mathcal{B}_{\bar{W} W W}$ we have
$\mathcal{B}_{\bar{W} W W}(\xi, \eta)=-i(\xi+\eta)^{n}\left[\left(\frac{n}{2}-\frac{1}{4}\right)\left(\xi^{n} \eta+\xi \eta^{n}\right)+\frac{1}{2}\left(\frac{5}{9} n+\frac{1}{9}\right)\left(\xi^{n-1} \eta^{2}+\xi^{2} \eta^{n-1}\right)\right]+\xi^{3} \eta^{3} \mathfrak{M}_{2 n-5}^{(2,0)}$.
Hence, the leading energy component generated by $\mathcal{B}_{\bar{W} W W}$ is

$$
\int-\left(n-\frac{1}{2}\right) \bar{W}^{(n)} W^{(n)} W_{\alpha}-\left(\frac{5}{9} n+\frac{1}{9}\right) \bar{W}^{(n)} W^{(n-1)} W_{\alpha \alpha} d \alpha
$$

Adding the complex conjugate gives the leading integral

$$
I_{2}=\int-(2 n-1) \bar{W}^{(n)} W^{(n)} \Re W_{\alpha}+\left(\frac{10}{9} n+\frac{2}{9}\right) \Im\left(\bar{W}^{(n)} W^{(n-1)}\right) \Im W_{\alpha \alpha} d \alpha
$$

The remainder has the form

$$
\tilde{I}_{2}=\Re \int \overline{\mathbf{W}} L_{2 n-6}\left(W_{\alpha \alpha \alpha}, W_{\alpha \alpha \alpha}\right) d \alpha
$$

There are other types of cubic terms appearing in the energy functional $E_{N F, 0}^{n}$ associated to the normal form equations (3.8), and we organize them in two categories:

- terms involving the factors $\bar{W} Q Q$, and their complex conjugates; they are cubic expressions tight to the bilinear forms $C^{h}$ and $A$,
- terms involving the factors $\bar{Q} W Q$, and their complex conjugates; they are cubic expressions corresponding to the bilinear forms $A^{h}, C$ and $D$.
Analogous to the previous computations we compute the symbol of each of the expressions in discussion, and obtain:

$$
\begin{aligned}
\mathcal{B}_{\bar{W} Q Q} & =(\xi+\eta)^{2 n} C^{h}(\xi, \eta)+\xi^{2 n} \bar{A}(\zeta, \eta) \\
& =\frac{-3 i(\xi+\eta)}{9(\xi+\eta)^{2}-4 \xi \eta}\left[\frac{1}{2}(\xi+\eta)^{2 n+1}-\xi^{2 n-1}\left(\xi^{2}+\frac{3}{2} \xi \eta+\frac{3}{2} \eta^{2}\right)\right]
\end{aligned}
$$

and also

$$
\begin{aligned}
\mathcal{B}_{\bar{Q} W Q}= & \xi^{2 n} \bar{C}(\zeta, \eta)+\zeta^{2 n-1} A^{h}(\xi, \eta)+\eta^{2 n-1} \bar{D}(\zeta . \xi) \\
= & \xi^{2 n} \frac{3 i(\xi+\eta)^{2}}{9(\xi+\eta)^{2}-4 \xi \eta}-i(\xi+\eta)^{2 n-1} \frac{3 \xi^{3}-\frac{3}{2} \xi^{2} \eta-5 \xi \eta^{2}-\frac{9}{2} \eta^{3}}{9(\xi+\eta)^{2}-4 \xi \eta} \\
& \quad-i \eta^{2 n-1} \frac{(\xi+\eta)\left(\frac{9}{2}(\xi+\eta)^{2}-4 \xi \eta\right)}{9 \xi^{2}+14 \xi \eta+9 \eta^{2}} .
\end{aligned}
$$

For both symbols we compute the expansion

$$
\mathcal{B}_{\bar{W} Q Q}=\frac{i}{3}\left(n-\frac{1}{4}\right)(\xi+\eta)^{n}\left(\xi^{n-1} \eta+\xi \eta^{n-1}\right)+\xi^{2} \eta^{2} \mathfrak{M}_{2 n-4}^{(2,0)},
$$

respectively

$$
\mathcal{B}_{\bar{Q} W Q}=i(\xi+\eta)^{n}\left(-\frac{1}{3}\left(2 n-\frac{7}{2}\right) \xi^{n-1} \eta+(n-1) \eta^{n-1} \xi-\left(\frac{17}{18} n-\frac{11}{18}\right) \eta^{n-2} \xi^{2}\right)+\eta^{2} \xi^{3} \mathfrak{M}_{2 n-5}^{(2,0)} .
$$

This gives the following leading energy components:

$$
I_{3}=2 \Re \int-i \frac{2}{3}\left(n-\frac{1}{4}\right) \bar{W}_{20}^{(n)} Q^{(n-1)} Q_{\alpha} d \alpha,
$$

respectively

$$
\begin{aligned}
I_{4}= & 2 \Re \int i \bar{Q}^{(n)}\left(-\frac{1}{3}\left(2 n-\frac{7}{2}\right) W^{(n-1)} Q_{\alpha}+(n-1) Q^{(n-1)} W_{\alpha}-\left(\frac{17}{18} n-\frac{11}{18}\right) Q^{(n-2)} W_{\alpha \alpha}\right) d \alpha \\
= & \int-2(n-1) \Re W_{\alpha} \Im\left(\bar{Q}^{(n)} Q^{(n-1)}\right)+\frac{2}{3}\left(2 n-\frac{7}{2}\right) \Im\left(\bar{W}^{(n)} Q^{(n-1)} \bar{Q}_{\alpha}\right) \\
& -\left(\frac{8}{9} n-\frac{2}{9}\right) \Im W_{\alpha \alpha}\left|Q^{(n-1)}\right|^{2} d \alpha,
\end{aligned}
$$

together with remainders which have the form

$$
\tilde{I}_{3}=\Re \int \overline{\mathbf{W}} L_{2 n-5}^{(2,0)}\left(Q_{\alpha \alpha}, Q_{\alpha \alpha}\right) d \alpha
$$

respectively

$$
\tilde{I}_{4}=\Re \int \bar{Q}_{\alpha} L_{2 n-6}^{(2,0)}\left(W_{\alpha \alpha \alpha}, Q_{\alpha \alpha}\right) d \alpha .
$$

Then the cubic leading expansion of the normal form energy is

$$
E_{N F, 0}^{n}=I_{1}+I_{2}+I_{3}+I_{4}+\tilde{I}_{2}+\tilde{I}_{3}+\tilde{I}_{4}+\text { quartic. }
$$

We remark here that, in the above expressions there are no more undifferentiated ( $W, Q$ )'s, and also that the highest order terms are at the level of the energy.
(ii) The modified normal form energy $E_{N F}^{n}$. The goal here is to replace $Q_{\alpha}$ by $R$ into the last expansion above. This is a direct substitution in the cubic expressions, where we simply take the sum

$$
\left(I_{2}+I_{3}+I_{4}+\tilde{I}_{2}+\tilde{I}_{3}+\tilde{I}_{4}\right)(R, \mathbf{W})
$$

However, some care must be taken with the second term in the quadratic part $I_{1}$. We have $Q_{\alpha}=R(1+\mathbf{W})$ therefore

$$
Q^{(n)}=R^{(n-1)}(1+\mathbf{W})+(n-1) R^{(n-2)} \mathbf{W}_{\alpha}+W^{(n)} R+\ldots
$$

Substituting into the corresponding part of $I_{1}$ we obtain

$$
\begin{aligned}
\int \Im\left(\bar{Q}^{(n)} Q^{(n-1)}\right) d \alpha=\int & (1+2 \Re \mathbf{W}) \Im\left(\bar{R}^{(n-1)} R^{(n-2)}\right)-(2 n-3) \bar{R}^{(n-2)} R^{(n-2)} \Im \mathbf{W}_{\alpha} \\
& +2 \Im\left(R^{(n-2)} \bar{W}^{(n)} \bar{R}\right) d \alpha+\left(\tilde{I}_{3}+\tilde{I}_{4}\right)(R, \mathbf{W})+\text { quartic. }
\end{aligned}
$$

The last two terms combine with $\left(I_{2}+I_{3}\right)(\mathbf{W}, R)$. Summarizing and reorganizing terms, the expressions $\left(I_{1}+I_{2}+I_{3}+I_{4}\right)(\mathbf{W}, R)$ are replaced by $J_{1}+J_{2}+J_{3}$ where

$$
\begin{aligned}
J_{1} & =\int(1-(2 n-1) \Re \mathbf{W})\left|\mathbf{W}^{(n-1)}\right|^{2}+(1-2(n-2) \Re \mathbf{W}) \Im\left(\bar{R}^{(n-1)} R^{(n-2)}\right) d \alpha \\
J_{2} & =\int-\frac{8}{3}\left(n-\frac{1}{4}\right) \Re R \Im\left(R^{(n-2)} \bar{W}^{(n)}\right) d \alpha \\
J_{3} & =\int \Im \mathbf{W}_{\alpha}\left[\left(\frac{10}{9} n+\frac{2}{9}\right) \Im\left(\overline{\mathbf{W}}^{(n-1)} \mathbf{W}^{(n-2)}\right)-\left(\frac{26}{9} n-\frac{29}{9}\right) R^{(n-2)} \bar{R}^{(n-2)}\right] d \alpha,
\end{aligned}
$$

and the lower order terms $I_{2}+I_{3}+I_{4}$ are replaced by $\tilde{J}_{1}+\tilde{J}_{2}+\tilde{J}_{3}$, which have the form

$$
\begin{gathered}
\tilde{J}_{1}=\Re \int \overline{\mathbf{W}} L_{2 n-6}^{(2,0)}\left(\mathbf{W}_{\alpha \alpha}, \mathbf{W}_{\alpha \alpha}\right) d \alpha, \quad \tilde{J}_{2}=\Re \int \overline{\mathbf{W}} L_{2 n-5}^{(2,0)}\left(R_{\alpha}, R_{\alpha}\right) d \alpha \\
\tilde{J}_{3}=\Re \int \bar{R} L_{2 n-6}^{(2,0)}\left(\mathbf{W}_{\alpha \alpha}, R_{\alpha}\right) d \alpha
\end{gathered}
$$

Thus our modified normal form energy has the form

$$
E_{N F}^{n}=J_{1}+J_{2}+J_{3}+\tilde{J}_{1}+\tilde{J}_{2}+\tilde{J}_{3}
$$

and, by construction, has the property that

$$
E_{N F}^{n}=E_{N F, 0}^{n}+q u a r t i c+\text { higher } .
$$

The quasilinear modified energy. As defined above, the remaining issue with the energy $E_{N F}^{n}$ is that its time derivative cannot be controlled at the same level due to the quasilinear character of the problem. The last modification below addresses this issue. We observe that these quasilinear modifications are only needed for the terms $J_{1}, J_{2}$ and $J_{3}$ above; the lower order terms $\tilde{J}_{1}, \tilde{J}_{2}, \tilde{J}_{3}$ will be left unchanged. The quasilinear corrections to $J_{1}, J_{2}$ and $J_{3}$ are defined as follows:

$$
\begin{gather*}
E_{1}=\int J^{-\left(n-\frac{1}{2}\right)}\left[\left|\mathbf{W}^{(n-1)}\right|^{2}+(4 n-3) \Im\left(\frac{\mathbf{W}_{\alpha}}{1+\mathbf{W}}\right) \Im\left(\overline{\mathbf{W}}^{(n-1)} \mathbf{W}^{(n-2)}\right)\right]  \tag{4.6}\\
\quad+J^{-(n-2)} \Im\left(\bar{R}^{(n-1)} R^{(n-2)}\right) d \alpha .
\end{gather*}
$$

Here we have added a lower order term in the square bracket, in order to obtain a bounded time derivative. This is the analogue of the lower order term arising in the operator $L$ in the study of the linearized problem later on. The remaining corrections are

$$
\begin{gather*}
E_{2}=\int-\frac{8}{3}\left(n-\frac{1}{4}\right) \Re R \Im\left((1+\mathbf{W})^{2} R^{(n-2)} \overline{\mathbf{W}}^{(n-1)}\right) d \alpha  \tag{4.7}\\
E_{3}=\int-\left(\frac{26}{9} n-\frac{29}{9}\right) \Im \mathbf{W}_{\alpha}\left(J^{-\left(n-\frac{1}{2}\right)} \Im\left(\overline{\mathbf{W}}^{(n-1)} \mathbf{W}^{(n-2)}\right)+J^{-(n-2)}\left|R^{(n-2)}\right|^{2}\right) d \alpha . \tag{4.8}
\end{gather*}
$$

Our final energy is

$$
\begin{equation*}
E^{n,(3)}=E_{1}+E_{2}+E_{3}+\tilde{J}_{1}+\tilde{J}_{2}+\tilde{J}_{3} \tag{4.9}
\end{equation*}
$$

We now proceed to prove that $E^{n,(3)}$ has the properties in the proposition. The energy equivalence property

$$
E^{n,(3)}=(1+O(A))\|(\mathbf{W}, R)\|_{\dot{\mathcal{H}}^{n-1}}^{2}=(1+O(A))\|(W, Q)\|_{\dot{\mathcal{H}}^{n}}^{2}
$$

follows easily by Sobolev embeddings, interpolation and Hölder's inequality (see also the similar argument in [20]).

It remains to consider the time derivative of $E^{n,(3)}$. By inspection we see that

$$
E^{n,(3)}=E_{N F}^{n}+q u a r t i c+\text { higher }=E_{N F, 0}^{n}+\text { quartic }+ \text { higher },
$$

therefore we have

$$
\frac{d}{d t} E^{n,(3)}=\text { quartic }+ \text { higher. }
$$

A good way to rephrase this is by introducing the truncation operator $\Lambda^{4}$ which selects the quartic + higher part of an expression in $(\mathbf{W}, R)$. Thus the above can be rewritten as

$$
\frac{d}{d t} E^{n,(3)}=\Lambda^{4} \frac{d}{d t} E^{n,(3)}=\Lambda^{4} \frac{d}{d t} E_{1}+\Lambda^{4} \frac{d}{d t} E_{2}+\Lambda^{4} \frac{d}{d t} E_{2}+\Lambda^{4} \frac{d}{d t} \tilde{J}_{1}+\Lambda^{4} \frac{d}{d t} \tilde{J}_{2}+\Lambda^{4} \frac{d}{d t} \tilde{J}_{3}
$$

Now we can separately estimate each term in the above sum. For the purpose of this computation we denote by err any term which does not contain a bilinear expression involving more derivatives than the energy, i.e., more that $\overline{\mathbf{W}}^{(n-1)} \mathbf{W}^{(n-1)}, \bar{R}^{(n-1)} R^{(n-2)}$, respectively $\overline{\mathbf{W}}^{(n-1)} R^{(n-2)}$. By the scale invariance of our problem all such terms have the same homogeneity and can all be estimated by Sobolev embeddings, interpolation and Hölder's inequality in a scale invariant fashion as follows:

$$
\left|\Lambda^{4} \mathrm{err}\right| \lesssim_{A} A B\|(\mathbf{W}, R)\|_{\mathcal{H}^{n-1}}^{2} .
$$

In particular we directly have

$$
\frac{d}{d t} \tilde{J}_{1}+\tilde{J}_{2}+\tilde{J}_{3}=\mathbf{e r r}
$$

which allows us to dispense with these terms. It remains to carefully compute the time derivative of each of $E_{1}, E_{2}$ and $E_{3}$, in order to insure that we obtain only err terms.
a) The time derivative of $E_{1}$. Differentiating any of the coefficients of the leading order terms yields err type expressions, so we can write

$$
\frac{d}{d t} E_{1}=E r_{1}+E r_{2}+\mathbf{e r r}
$$

where
$E r_{1}=\int 2 J^{-\left(n-\frac{1}{2}\right)} \Re\left(\overline{\mathbf{W}}^{(n-1)} \mathbf{W}_{t}^{(n-1)}\right)+2 J^{-(n-2)} \Im\left(\bar{R}^{(n-1)} R_{t}^{(n-2)}\right)+\partial_{\alpha} J^{2-n} \Im\left(\bar{R}^{(n-2)} R_{t}^{(n-2)}\right) d \alpha$,
and

$$
E r_{2}=\int 2(4 n-3) \Im\left(\frac{\mathbf{W}_{\alpha}}{1+\mathbf{W}}\right) \Im\left(\overline{\mathbf{W}}^{(n-1)} \mathbf{W}_{t}^{(n-2)}\right) d \alpha
$$

To compute these two expressions we begin with differentiating in the equations (1.11):

$$
\left\{\begin{aligned}
\mathbf{W}_{t}^{(n-1)} & =-b \mathbf{W}^{(n)}-\frac{1+\mathbf{W}}{1+\overline{\mathbf{W}}} R^{(n)}-n R^{(n-1)}\left(\frac{\mathbf{W}_{\alpha}}{1+\overline{\mathbf{W}}}-\frac{(1+\mathbf{W}) \overline{\mathbf{W}}_{\alpha}}{(1+\overline{\mathbf{W}})^{2}}\right)+\ldots \\
R_{t}^{(n-2)} & =-b R^{(n-1)}-i \mathbf{W}^{(n)} \frac{1}{J^{\frac{1}{2}}(1+\overline{\mathbf{W}})^{2}}+\frac{i}{2} \mathbf{W}^{(n-1)}\left(\frac{(5 n-4) \mathbf{W}_{\alpha}}{J^{\frac{1}{2}}(1+\mathbf{W})^{3}}+\frac{(n-2) \overline{\mathbf{W}}_{\alpha}}{J^{\frac{3}{2}}(1+\mathbf{W})}\right)+\ldots
\end{aligned}\right.
$$

where on the right we have kept only the terms which may contribute to the leading part of the time derivative of $E_{1}$. Thus integrating by parts we obtain

$$
\begin{aligned}
E r_{1} \approx & 2 \Re \int-J^{-\left(n-\frac{1}{2}\right)} \frac{1+\mathbf{W}}{1+\overline{\mathbf{W}}} R^{(n)} \bar{W}^{(n)}-J^{-(n-2)} \frac{1}{J^{1 / 2}(1+\overline{\mathbf{W}})^{2}} \bar{R}^{(n-1)} W^{(n+1)} \\
& +\bar{W}^{(n)} R^{(n-1)}\left[-n J^{-\left(n-\frac{1}{2}\right)}\left(\frac{\mathbf{W}_{\alpha}}{1+\overline{\mathbf{W}}}-\frac{(1+\mathbf{W}) \overline{\mathbf{W}}_{\alpha}}{(1+\overline{\mathbf{W}})^{2}}\right)\right. \\
& \left.+\frac{1}{2} J^{-(n-2)}\left(\frac{(5 n-4) \overline{\mathbf{W}}_{\alpha}}{J^{\frac{1}{2}}(1+\overline{\mathbf{W}})^{3}}+\frac{(n-2) \mathbf{W}_{\alpha}}{J^{\frac{3}{2}}(1+\overline{\mathbf{W})}}\right)+\partial_{\alpha} J^{2-n} \frac{1}{J^{1 / 2}(1+\overline{\mathbf{W}})^{2}}\right] d \alpha \\
\approx & 2 \Re \int-J^{-\left(n-\frac{3}{2}\right)} \frac{1}{(1+\overline{\mathbf{W}})^{2}}\left(R^{(n)} \bar{W}^{(n)}+R^{(n-1)} \bar{W}^{(n+1)}\right) \\
& +J^{-\left(n-\frac{3}{2}\right)} \bar{W}^{(n)} R^{(n-1)}\left[-n \frac{\mathbf{W}_{\alpha}}{J(1+\overline{\mathbf{W})}}+(3 n-1) \frac{\overline{\mathbf{W}}_{\alpha}}{(1+\overline{\mathbf{W}})^{3}}\right] d \alpha \\
= & 2\left(2 n-\frac{3}{2}\right) \Re \int J^{-\left(n-\frac{3}{2}\right)} \bar{W}^{(n)} R^{(n-1)}\left(-\frac{\mathbf{W}_{\alpha}}{J(1+\overline{\mathbf{W})}}+\frac{\overline{\mathbf{W}}_{\alpha}}{(1+\overline{\mathbf{W}})^{3}}\right) d \alpha \\
= & 2(4 n-3) \int J^{-\left(n-\frac{3}{2}\right)} \Im\left(\bar{W}^{(n)} R^{(n-1)} \frac{1}{\left(1+\overline{\mathbf{W})^{2}}\right) \Im\left(\frac{\mathbf{W}_{\alpha}}{1+\mathbf{W}}\right) d \alpha .}\right.
\end{aligned}
$$

A shorter computation gives

$$
E r_{2}=-\int 2(4 n-3) J^{-\left(n-\frac{3}{2}\right)} \Im\left(\bar{W}^{(n)} R^{(n-1)} \frac{1}{(1+\overline{\mathbf{W}})^{2}}\right) \Im\left(\frac{\mathbf{W}_{\alpha}}{1+\mathbf{W}}\right) d \alpha+\mathbf{e r r}
$$

which cancels $E r_{1}$ and leads to the desired bound

$$
\frac{d}{d t} E_{1}=\mathrm{err}
$$

b) The time derivative of $E_{3}$. Again, if the time derivative falls on the $\Re R$ coefficient, or on $J$, or on $\mathbf{W}$ then we get lower order contributions. It remains to consider the two terms when the time derivative applies to either $R^{(n-2)}$ or to $\mathbf{W}^{(n-1)}$. In both cases we need to consider only the leading order contributions,

$$
\mathbf{W}_{t}^{(n-1)}=-\frac{1+\mathbf{W}}{1+\overline{\mathbf{W}}} R^{(n)}+\ldots \quad R_{t}^{(n-2)}=-i \mathbf{W}^{(n)} \frac{1}{J^{\frac{1}{2}}(1+\overline{\mathbf{W}})^{2}}+\ldots
$$

Then the two terms exactly cancel and we obtain

$$
\frac{d}{d t} E_{2}=\mathrm{err} .
$$

b) The time derivative of $E_{2}$. Again, if the time derivative falls on $\Im \mathbf{W}_{\alpha}$ coefficient, or on $J$, then we get lower order contributions. Then we can write

$$
\frac{d}{d t} E_{2}=E r_{3}+E r_{4}+\mathbf{e r r}
$$

where

$$
E r_{3}=2 \int \Im \mathbf{W}_{\alpha} J^{-\left(n-\frac{1}{2}\right)} \Im\left(\bar{W}^{(n)} W_{t}^{(n-1)}\right) d \alpha
$$

and

$$
E r_{4}=2 \int \Im \mathbf{W}_{\alpha} J^{-(n-2)} \Re\left(\bar{R}^{(n-2)} R_{t}^{(n-2)}\right) d \alpha
$$

In both cases we need to consider only the leading order contributions of the time derivatives, which exactly cancel and we also obtain

$$
\frac{d}{d t} E_{2}=\mathrm{err} .
$$

The proof of the proposition is concluded.

## 5. Energy estimates at low frequency

Here we prove the $\dot{\mathcal{H}}^{\sigma}$ energy estimates for $(W, Q)$. For this we work directly with the equation (1.7), which we no longer need to treat it as a nonlinear problem. Instead we can apply directly the normal form transformation to eliminate the quadratic terms, and then do semilinear analysis on the remaining evolution, taking advantage of the high frequency bounds in the previous section.

Unfortunately the normal form transformation (3.6) does not suffice for our purposes here. This is largely due to the weaker pointwise control that we have on the function $W$, but also due to the fact that we are estimating $Q$ in a negative Sobolev space. For these reasons, we will have to remove certain cubic non-resonant interactions via a further cubic modification to the normal form. This motivates the following
Proposition 5.1. There exist normal form variables $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$, obtained by a further cubic modification of the normal form (3.6),

$$
\begin{equation*}
\tilde{\tilde{W}}=W+W_{[2]}+W_{[3]}, \quad \tilde{\tilde{Q}}=Q+Q_{[2]}+Q_{[3]}, \tag{5.1}
\end{equation*}
$$

where $\left(W_{[3]}, Q_{[3]}\right) \in\left(\mathfrak{B}_{0}^{3}(W, Q), \mathfrak{C}_{0}^{3}(W, Q)\right)$, with the following properties:
i) The $\dot{\mathcal{H}}^{\sigma}$ energies are equivalent,

$$
\begin{equation*}
\|(\tilde{W}, \tilde{\tilde{Q}})\|_{\mathcal{H}^{\sigma}} \approx_{A}\|(W, Q)\|_{\mathcal{H}^{\sigma}} \tag{5.2}
\end{equation*}
$$

(ii) The variables $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ solve a cubic equation:

$$
\left\{\begin{array}{l}
\tilde{\tilde{W}}_{t}+\tilde{\tilde{Q}}_{\alpha}=\tilde{\tilde{G}}  \tag{5.3}\\
\tilde{\tilde{Q}}_{t}+i \tilde{\tilde{W}}_{\alpha \alpha}=\tilde{\tilde{K}}
\end{array}\right.
$$

where the following estimates hold:

$$
\begin{gather*}
\|(\tilde{\tilde{G}}, \tilde{\tilde{K}})\|_{\dot{\mathcal{H}}^{\sigma}} \lesssim\|(W, Q)\|_{X}^{2}\|(W, Q)\|_{\dot{\mathcal{H}}^{2} \cap \dot{\mathcal{H}}^{\sigma}}  \tag{5.4}\\
\left\|\left(\tilde{\tilde{G}}^{(4+)}, \tilde{\tilde{K}}^{(4+)}\right)\right\|_{\dot{\mathcal{H}}^{\frac{1}{2}}} \lesssim t^{-\frac{1}{2}+2 \sigma}\|(W, Q)\|_{X}^{2}\|(W, Q)\|_{\dot{\mathcal{H}}^{2} \cap \dot{\mathcal{H}}^{\sigma}} . \tag{5.5}
\end{gather*}
$$

We remark that the last bound (5.5) is not used in the proof of the energy estimates. However, it will come handy in the last section, where we obtain the asymptotic equation.

Before proving the proposition, we show how to use it to conclude the proof of the $\dot{\mathcal{H}}^{\sigma}$ part of the energy bounds for $(W, Q)$ in (1.20) in our boootstrap argument. Precisely, our goal here is to prove the bound

$$
\begin{equation*}
\|(W, Q)\|_{\mathcal{H}^{\sigma}} \lesssim \epsilon t^{C \epsilon^{2}} \tag{5.6}
\end{equation*}
$$

under the initial data assumption (1.19)

$$
\begin{equation*}
\|(W, Q)(0)\|_{\dot{\mathcal{H}}^{\sigma} \cap \dot{\mathcal{H}}^{6}} \lesssim \epsilon, \tag{5.7}
\end{equation*}
$$

and the bootstrap assumptions (1.23), (1.24) and (1.25). Linear energy estimates for ( $\tilde{\tilde{W}}, \tilde{\tilde{Q}}$ ) show that

$$
\frac{d}{d t}\|(\tilde{W}, \tilde{\tilde{Q}})\|_{\mathcal{H}^{\sigma}} \lesssim\|(W, Q)\|_{X}^{2}\|(W, Q)\|_{\dot{\mathcal{H}}^{2} \cap \dot{\mathcal{H}}^{\sigma}}
$$

For the $\dot{\mathcal{H}}^{2}$ norm above we use the high frequency bound (4.1). Using also the energy equivalence (5.2), we obtain

$$
\frac{d}{d t}\|(\tilde{\tilde{W}}, \tilde{\tilde{Q}})\|_{\dot{\mathcal{H}}^{\sigma}} \lesssim \epsilon^{2} t^{-1}\left(\epsilon t^{C \epsilon^{2}}+\|(\tilde{\tilde{W}}, \tilde{\tilde{Q}})\|_{\dot{\mathcal{H}}^{\sigma}}\right)
$$

Hence by Gronwall's inequality we obtain

$$
\|(\tilde{\tilde{W}}, \tilde{\tilde{Q}})\|_{\dot{\mathcal{H}}^{\sigma}} \lesssim \epsilon t^{C \epsilon^{2}}
$$

Now we can return to (5.6) via the energy equivalence (5.2). The rest of the section is devoted to the proof of the proposition.
Proof of Proposition 5.1. We begin with some heuristic considerations. The straightforward approach to this proof would be to work directly with the normal form transformation defined by our quadratic normal form transformation,

$$
\tilde{W}=W+W_{[2]}, \quad \tilde{Q}=Q+Q_{[2]}
$$

which solve cubic equations,

$$
\left\{\begin{array}{c}
\tilde{W}_{t}+\tilde{Q}_{\alpha}=\tilde{G}(W, Q)  \tag{5.8}\\
\tilde{Q}_{t}+i \tilde{W}_{\alpha \alpha}=\tilde{K}(W, Q),
\end{array}\right.
$$

and then estimate the cubic terms $(\tilde{G}, \tilde{K})$ as in the proposition, by combining one $L^{2}$ bound with two $L^{\infty}$ bounds. However, this naive analysis fails for two reasons:
(i) The undifferentiated $W$ appears in the normal form. This is a problem because we do have neither an $L^{2}$ bound for $W$ at low frequencies, nor an $L^{\infty}$ bound for $W$ with $t^{-\frac{1}{2}}$ decay.
(ii) The expression $\tilde{K}$ needs to be estimated in a negative Sobolev space $\dot{H}^{\sigma-\frac{1}{2}}$, which is a problem at low frequencies, as it does not follow directly from a trilinear superposition of one $L^{2}$ bound and two $L^{\infty}$ bounds.
Based on these considerations, our strategy will be to separate the cubic terms in ( $\tilde{G}, \tilde{K}$ ) into a good portion and a bad portion so that
(a) The good portion of $(\tilde{G}, \tilde{K})$ can be estimated directly using one $L^{2}$ bound and two $L^{\infty}$ bounds.
(b) The bad portion of $(\tilde{G}, \tilde{K})$ is non-resonant, and thus can be eliminated with a further cubic normal form correction.

When implementing the above strategy we will keep in mind several principles:
I. The terms with undifferentiated $W$ in both equations are bad when $W$ has the low frequency, and need to be normalized out.
II. The undifferentiated terms in $\tilde{K}$ are bad at low frequency, and need to be normalized out when the three input frequencies are larger.
III. The linearization of the normalized equation will be used as the normalization of the linearized equation, so we need to make sure that our estimates still apply there. The difficulty is that for the normalized variables $(w, q)$ we only have access to the $L^{2}$ norm, and not to any decaying $L^{\infty}$ bound. Thus, in all multilinear estimates we have to allow for the case when any one of the terms admits only $L^{2}$ type bounds.
We begin with the normal form equations (3.8) for $(\tilde{W}, \tilde{Q})$, with $(\tilde{G}, \tilde{K})$ as in (3.9). For the expressions $\tilde{G}$ and $\tilde{K}$ we need to separate the worst terms at low frequency, namely the ones which contain an undifferentiated $W$ or $Q$ factor. This is done using the expansion (3.11). Based on this, we first express $\tilde{G}$ in the form

$$
\tilde{G}=\tilde{G}_{0}+\tilde{G}_{1}+\tilde{G}_{2},
$$

where $\tilde{G}_{0}$ and $\tilde{G}_{1}$ contain cubic terms with a $W$ factor, respectively without,

$$
\tilde{G}_{0}=-\frac{1}{2} \Re W G_{\alpha}^{(2)}, \quad \tilde{G}_{1}=L_{0}\left(W_{\alpha}, W_{\alpha}, Q_{\alpha}\right)+L_{0}\left(Q, Q_{\alpha}, Q_{\alpha}\right)+L_{0}\left(Q, W_{\alpha}, \mathbf{W}_{\alpha \alpha}\right)
$$

while $\tilde{G}_{2}$ contain terms which are quartic and higher. We further note that $\tilde{G}_{2}$ may contain a single undifferentiated factor.

For $\tilde{K}$ we need a better bound at low frequency, so we split it further as

$$
\tilde{K}=\tilde{K}_{0}+\tilde{K}_{1}+\tilde{K}_{2}+\tilde{K}_{3}
$$

where $\tilde{K}_{0}$ and $\tilde{K}_{1}$ contain all cubic terms with an undifferentiated factor,

$$
\tilde{K}_{0}=-\frac{1}{2} \Re W K_{\alpha}^{(2)}, \quad \tilde{K}_{1}=-\frac{1}{3} \Re Q G_{\alpha}^{(2)}
$$

$\tilde{K}_{2}$ contains the remaining cubic terms with all factors differentiated,

$$
\tilde{K}_{2}=L_{0}\left(W_{\alpha}, W_{\alpha}, W_{\alpha \alpha}\right)+L_{0}\left(W_{\alpha}, Q_{\alpha}, Q_{\alpha}\right)
$$

and $\tilde{K}_{3}$ contains all the the quartic terms. We observe that $\tilde{K}_{3}$ may contain at most one undifferentiated $W$ factor.

The terms $\tilde{G}_{0} . \tilde{K}_{0}$. These are the worst cubic terms, since we have less control on $W$ than on everything else. However, the co-factors $G_{\alpha}^{(2)}$ and $K_{\alpha}^{(2)}$ are differentiated, and also each of the factors in $G^{(2)}$ and $K^{(2)}$ are differentiated. This allows us to separate a single unfavorable case, namely when the $W$ factor has frequency less than the output frequency, and than both of the entries in $G^{(2)}$, respectively $K^{(2)}$. Precisely, we decompose

$$
\tilde{G}_{0}=\tilde{G}_{0}^{\text {good }}+\tilde{G}_{0}^{l h h \rightarrow h}, \quad \tilde{K}_{0}=\tilde{K}_{0}^{\text {good }}+\tilde{K}_{0}^{l h h \rightarrow h}
$$

where

$$
\tilde{G}_{0}^{l h h \rightarrow h}=\sum_{\lambda} P_{\gg \lambda}\left[W_{\lambda} G^{(2)}\left(W_{\gg}, Q_{\gg \lambda}\right)\right], \quad \tilde{K}_{0}^{l h h \rightarrow h}=\sum_{\lambda} P_{\gg \lambda}\left[W_{\lambda} K^{(2)}\left(W_{\gg \lambda}, Q_{\gg \lambda}\right)\right] .
$$

We can bound the terms $\left(\tilde{G}_{0}^{\text {good }}, \tilde{K}_{0}^{\text {good }}\right)$ as in (5.4) as follows. If the $W$ frequency is larger than the output frequency, then we can move half a derivative from the $G_{\alpha}^{(2)}$, respectively $K_{\alpha}^{(2)}$ onto $W$, obtaining terms of the form

$$
\left(D^{\frac{1}{2}} L_{0}^{l h h \rightarrow h}\left(D^{\frac{1}{2}} W, G^{(2)}\right), D^{\frac{1}{2}} L_{0}^{l h h \rightarrow h}\left(D^{\frac{1}{2}} W, K^{(2)}\right)\right)
$$

The half derivative in front is useful at low frequency in the second term, as it allows us to obtain the $\dot{H}^{\sigma-\frac{1}{2}}$ bound (at low frequency). Now we are left with a trilinear form where all three factors are at least half differentiated. Thus we can use an $L^{2}$ bound on any one of them, and an $L^{\infty}$ bound on the other two.

On the other hand, if one of the inputs of $\left(G^{(2)}, K^{(2)}\right)$ has frequency lower or comparable to $W$, then we can move half of its derivative to $W$, and we obtain an expression of the form

$$
\left(\partial_{\alpha} L_{0}^{l h h \rightarrow h}\left(D^{\frac{1}{2}} W, G^{(2)}\left((W, Q), D^{\frac{1}{2}}(W, Q)\right), D^{\frac{1}{2}} L_{0}^{l h h \rightarrow h}\left(\partial_{\alpha} W, K^{(2)}\left((W, Q), D^{\frac{1}{2}}(W, Q)\right)\right)\right)\right.
$$

Here all three factors inside are again at least half differentiated, so we can bound any one of them in $L^{2}$, and the remaining two in $L^{\infty}$.

It remains to consider the bad terms $\left(\tilde{G}_{0}^{l h h \rightarrow h}, \tilde{G}_{0}^{l h h \rightarrow h}\right)$; these are non-resonant, so we can factor them out with a cubic normal form correction. The simplest way to achieve this is to take advantage of the fact that $G^{(2)}$ and $K^{(2)}$ can be corrected with the normal form transform computed in Proposition 3.1. This leads us to define the first round of cubic normal form corrections as $\left(W_{[3], 0}^{l h h \rightarrow h}, Q_{[3], 0}^{l h h \rightarrow h}\right)$, which are defined by adding frequency localizations as above to the trilinear expressions

$$
W_{[3], 0}=-\frac{1}{2} \Re W W_{[2], \alpha}, \quad Q_{[3], 0}=-\frac{1}{2} \Re W Q_{[2], \alpha} .
$$

We have

$$
\begin{aligned}
W_{[3], 0, t}+Q_{[3], 0, \alpha}-\tilde{G}_{0} & =-\frac{1}{2} W_{[2], \alpha} \Re W_{t}-\frac{1}{2} \Re W_{\alpha} Q_{[2], \alpha}+\frac{1}{2} \Re W\left(G^{(2)}-W_{[2], t}-Q_{[2], \alpha}\right)_{\alpha} \\
& =\frac{1}{2} \Re Q_{\alpha} W_{[2], \alpha}-\frac{1}{2} \Re W_{\alpha} Q_{[2], \alpha}-\frac{1}{2} \Re G W_{[2], \alpha}-\frac{1}{2} \Re W\left(\tilde{G}-G^{(3+)}\right)_{\alpha} .
\end{aligned}
$$

The first two terms are cubic, and even contain an undifferentiated $W$; however, after the $l h h \rightarrow h$ localization we are left with a differentiated low frequency factor, so these terms are handled as discussed above, by moving a half derivative from the first, low frequency, factor to the undifferentiated factor in $W_{[2]}$ or $G_{[2]}$. The remaining terms are quartic, and may even contain two undifferentiated $W$ factors. But this is still acceptable, as we can bound them in $H^{1}$. Indeed, since $\sigma$ is small therefore we can place the undifferentiated factors in $L^{4}$ but still with some time decay, and bound each of the two differentiated factors in $L^{\infty}$ by $t^{-\frac{1}{2}}$.

Similarly we have

$$
\frac{d}{d t} Q_{[3], 0}+i W_{[3], 0}-\tilde{K}_{0}^{l h}=\frac{1}{2} \Re Q_{\alpha} Q_{[2], \alpha}-i \frac{1}{2} \Re W_{\alpha \alpha} W_{[2], \alpha}-\frac{1}{2} G Q_{[2], \alpha}-\frac{1}{2} \Re W\left(\tilde{K}-K^{(3+)}\right)_{\alpha}
$$

The first two terms are again cubic, and further, by the $l h h \rightarrow h$ frequency localization we can both move the derivative on $Q_{[2], \alpha}$, respectively $W_{[2], \alpha}$ onto the output, and still be left with a derivative onto the first, low frequency, factor. Thus we can bound them as above. The remaining terms are quartic, and may even contain two undifferentiated $W$ factors. But this is still acceptable, as we can bound them in $L^{2} \cap \dot{H}^{-1}$. To get the output one derivative lower than before, we again take advantage of the fact that the $l h h \rightarrow h$ frequency
localization allows us to move the derivative in the second factor onto the output. Hence it remains to estimate the remaining quadrilinear form in $H^{1}$, which is done as before.

The term $\tilde{G}_{1}$. This is simpler, as we can place either factor in $L^{2}$, and the remaining factors are directly bounded in $L^{\infty}$ by $t^{-\frac{1}{2}}\|(W, Q)\|_{X}$. Again, we bound these terms in the inhomogeneous Sobolev space $H^{1}$.

The term $\tilde{G}_{2}$. This is exactly as before. The three differentiated factors are bounded in either $L^{2}$ or $L^{\infty}$, while the extra fourth factor provides some additional time decay, even if it is only a $W$ factor.

The term $\tilde{K}_{1}$. Just as $\tilde{G}_{1}$, this can be estimated in $L^{2}$, which takes care of the high frequencies $(\geq 1)$. For low frequencies, we need to get a better bound than $L^{2}$. For this we commute the co-factor derivative as

$$
\tilde{K}_{1}=\frac{1}{2} \Re Q_{\alpha} K^{(2)}-\frac{1}{2} \partial_{\alpha}\left[\Re Q K^{(2)}\right] .
$$

The first term is moved into $\tilde{K}_{2}$, while the second is an exact derivative applied to a trilinear expression which can be placed in $L^{2}$ just as $\tilde{G}_{1}$.

The term $\tilde{K}_{2}$. This can be estimated directly in $L^{2}$, so it is good at high frequency $(\geq 1)$. It remains to consider the low frequencies. For this we recall that $\tilde{K}_{2}$ has all differentiated factors, more precisely

$$
\tilde{K}_{2}=\tilde{K}_{2}\left(W_{\alpha}, Q_{\alpha}\right) \in \mathfrak{B}_{-1}^{3}\left(W_{\alpha}, Q_{\alpha}\right)
$$

We split this into two parts, depending on whether the output frequency is smaller than all of the inputs,

$$
\tilde{K}_{2}=\tilde{K}_{2}^{\text {good }}+\tilde{K}_{2}^{h h h \rightarrow l},
$$

where

$$
\tilde{K}_{2}^{h h h \rightarrow l}=\sum_{\lambda<1} P_{\ll \lambda} \tilde{K}_{2}\left(W_{>\lambda, \alpha}, Q_{>\lambda, \alpha}\right) .
$$

In $\tilde{K}_{2}^{\text {good }}$ one of the factors has frequency equal or lower than the output so we can move a half derivative onto the output, and estimate the rest in $L^{2}$ using one $L^{2}$ and two $L^{\infty}$ bounds.

It remains to consider the only nontrivial term $\tilde{K}_{2}^{h h h \rightarrow l}$. This cannot be estimated directly in $\dot{H}^{\sigma-\frac{1}{2}}$ at low frequency, as the only way to gain improved summability is by trading off decay. However, it has the redeeming feature that the balance of the frequencies is so that the cubic interaction is non-resonant. This analysis was carried out in Proposition 3.2, which shows that we can find a further cubic normal form correction $\left(W_{[3], 1}^{h h h}, \tilde{Q}_{[3], 1}^{h h h \rightarrow l}\right) \in$ $\left(\mathfrak{B}_{0}^{3}(W, Q), \mathfrak{C}_{0}^{3}(W, Q)\right)$, which removes these terms. These are trilinear forms with the same frequency localization as $\tilde{K}_{2}^{h h h} \rightarrow l$. More precisely, we have

$$
\left\{\begin{align*}
W_{[3], 1}^{h h h} \rightarrow l & =L_{1}^{h h h \rightarrow l}(Q, Q, W)+L_{2}^{h h h \rightarrow l}(W, W, W)  \tag{5.9}\\
Q_{[3], 1}^{h h h \rightarrow l} & =L_{2}^{h h h \rightarrow l}(Q, W, W)+L_{1}^{h h h \rightarrow l}(Q, Q, Q) .
\end{align*}\right.
$$

Introducing these cubic terms removes the cubic error $\tilde{K}_{2}^{h h h \rightarrow l}$, but yields further quartic errors. However, these contain at most one $W$ factor, and thus can be included in $\tilde{K}_{3}$.

The term $\tilde{K}_{3}$. This can be easily estimated in $L^{2}$, which suffices at high frequency. Hence it remains to consider the low frequencies. The worst terms are those with one undifferentiated $W$, e.g., of the form

$$
L_{0}\left(W, Q_{\alpha}, Q_{\alpha}, W_{\alpha}\right)
$$

But for such a term we can use twice the Sobolev embedding to bound it $\underline{L}_{2}^{2}$, using Proposition 2.2, e.g., as in

$$
\begin{aligned}
\left\|L_{0}\left(W, Q_{\alpha}, Q_{\alpha}, W_{\alpha}\right)\right\|_{\dot{H}^{\sigma-\frac{1}{2}}} & \lesssim\left\|L_{0}\left(W, Q_{\alpha}, Q_{\alpha}, W_{\alpha}\right)\right\|_{L^{p}} \lesssim\|\tilde{W}\|_{L^{q}}\left\|\tilde{Q}_{\alpha}\right\|_{L^{\infty}}^{2}\left\|\tilde{W}_{\alpha}\right\|_{L^{2}} \\
& \lesssim t^{-1}\|(\tilde{W}, \tilde{Q})\|_{X}^{2}\|\tilde{W}\|_{\dot{H}^{\sigma}}\left\|\tilde{Q}_{\alpha}\right\|_{L^{2}},
\end{aligned}
$$

where

$$
\frac{1}{p}-\frac{1}{2}=\frac{1}{q}=\frac{1}{2}-\sigma .
$$

Summarizing, we set $W_{[3]}=W_{[3], 0}^{l h h \rightarrow h}+W_{[3], 1}^{h h h \rightarrow l}$ and $Q_{[3]}=Q_{[3], 0}^{l h h \rightarrow l}+Q_{[3], 1}^{h h h \rightarrow l}$, and define our final normal form variables

$$
\left\{\begin{array}{l}
\tilde{\tilde{W}}_{t}=W+W_{[2]}+W_{[3]}  \tag{5.10}\\
\tilde{Q}_{t}=Q+Q_{[2]}+Q_{[3]} .
\end{array}\right.
$$

We obtain a good system for $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ :

$$
\left\{\begin{array}{r}
\tilde{\tilde{W}}_{t}+\tilde{\tilde{Q}}_{\alpha}=\tilde{\tilde{G}}  \tag{5.11}\\
\tilde{\tilde{Q}}_{t}+i \tilde{\tilde{W}}_{\alpha \alpha}=\tilde{\tilde{K}}
\end{array}\right.
$$

where $(\tilde{\tilde{G}}, \tilde{\tilde{K}})$ admit a favorable estimate (5.4). For later use, we list their cubic parts $\left(\tilde{\tilde{G}}^{(3)}, \tilde{\tilde{K}}^{(3)}\right):$

$$
\left\{\begin{array}{l}
\tilde{\tilde{G}}=\tilde{G}_{0}^{\text {good }}+\tilde{G}^{1}+\frac{1}{2} P^{l h h \rightarrow h}\left(\Re Q_{\alpha} W_{[2], \alpha}-\Re W_{\alpha} Q_{[2], \alpha}\right)  \tag{5.12}\\
\tilde{\tilde{K}}=\tilde{K}_{0}^{\text {good }}+\tilde{K}_{1}+\tilde{K}_{2}^{\text {good }}+\frac{1}{2} P^{l h h \rightarrow h}\left(\Re Q_{\alpha} Q_{[2], \alpha}-i \Re W_{\alpha \alpha} W_{[2], \alpha}\right) .
\end{array}\right.
$$

Finally, the bound (5.5) for quartic and higher terms is an easy consequence of Proposition 2.2. Here it helps that no negative Sobolev norms need to be estimated. This concludes the proof of part (ii) of the proposition.

It remains to consider the energy equivalence in part (i). Here we need to bound the corrections $\left(W_{[2]}, Q_{[2]}\right)$ and $\left(W_{[3]}, Q_{[3]}\right)$ in $\dot{\mathcal{H}}^{\sigma}$. For this we use standard multiplicative estimates as in Proposition [2.2, combined with Sobolev embeddings. These estimates are somewhat tedious but routine, and are left for the reader.

[^2]
## 6. The linearized equation

Here we derive the linearized equation, and prove energy estimates for it, first in $\dot{\mathcal{H}}^{1}$ and then in $\dot{\mathcal{H}}^{\sigma}$.
6.1. The equations. The solutions for the linearized water wave equation around a solution $(W, Q)$ to the equation (1.7) are denoted by $(w, q)$. As in [20], it will be convenient to also switch to diagonal variables $(w, r)$, where

$$
r:=q-R w .
$$

We will employ the variables $(w, r)$ at high frequency, but we will return to $(w, q)$ for low frequency bounds.

The linearization of $R$ is

$$
\delta R=\frac{q_{\alpha}-R w_{\alpha}}{1+\mathbf{W}}=\frac{r_{\alpha}+R_{\alpha} w}{1+\mathbf{W}}
$$

while the linearization of $F$ can be expressed in the form

$$
\delta F=P[m-\bar{m}],
$$

where the auxiliary variable $m$ corresponds to differentiating $F$ with respect to the holomorphic variables,

$$
m:=\frac{q_{\alpha}-R w_{\alpha}}{J}+\frac{\bar{R} w_{\alpha}}{(1+\mathbf{W})^{2}}=\frac{r_{\alpha}+R_{\alpha} w}{J}+\frac{\bar{R} w_{\alpha}}{(1+\mathbf{W})^{2}}
$$

We denote also

$$
n:=\bar{R} \delta R=\frac{\bar{R}\left(q_{\alpha}-R w_{\alpha}\right)}{1+\mathbf{W}}=\frac{\bar{R}\left(r_{\alpha}+R_{\alpha} w\right)}{1+\mathbf{W}} .
$$

Further, introducing the real coefficient $c$ by

$$
i c:=\frac{\mathbf{W}_{\alpha}}{J^{\frac{1}{2}}(1+\mathbf{W})}-\frac{\overline{\mathbf{W}}_{\alpha}}{J^{\frac{1}{2}}(1+\overline{\mathbf{W}})},
$$

we have

$$
i \delta c=p-\bar{p},
$$

where

$$
p:=\frac{w_{\alpha \alpha}}{J^{1 / 2}(1+\mathbf{W})}-\left(\frac{3 \mathbf{W}_{\alpha}}{2 J^{1 / 2}(1+\mathbf{W})^{2}}-\frac{\overline{\mathbf{W}}_{\alpha}}{2 J^{3 / 2}}\right) w_{\alpha} .
$$

Then the linearized water wave equations take the form

$$
\left\{\begin{array}{l}
w_{t}+F w_{\alpha}+(1+\mathbf{W}) P[m-\bar{m}]=0  \tag{6.1}\\
q_{t}+F q_{\alpha}+Q_{\alpha} P[m-\bar{m}]+P[n+\bar{n}]+i P[p-\bar{p}]=0 .
\end{array}\right.
$$

Recalling that $b=F+\frac{\bar{R}}{1+\mathbf{W}}$ and replacing the $q$-equation with the corresponding $r$ equation, this becomes (see also the similar computation in [20]):

$$
\left\{\begin{array}{l}
\left(\partial_{t}+b \partial_{\alpha}\right) w+\frac{1}{1+\overline{\mathbf{W}}} r_{\alpha}+\frac{R_{\alpha}}{1+\overline{\mathbf{W}}} w=\mathcal{G}_{0}(w, r)  \tag{6.2}\\
\left(\partial_{t}+b \partial_{\alpha}\right) r-i \frac{a}{1+\mathbf{W}} w+i P p+\frac{w}{1+\mathbf{W}} \partial_{\alpha} P c=\mathcal{K}(w, r)
\end{array}\right.
$$

where

$$
\left\{\begin{aligned}
\mathcal{G}_{0}(w, r) & =(1+\mathbf{W})(P \bar{m}+\bar{P} m) \\
\mathcal{K}(w, r) & =\bar{P} n-P \bar{n}+i P \bar{p}
\end{aligned}\right.
$$

To rewrite this in a more useful form we introduce the operator $L$ given by

$$
\begin{aligned}
L & =\partial_{\alpha} J^{-\frac{1}{2}} \partial_{\alpha}-i c \partial_{\alpha}-i P c_{\alpha} \\
& =\partial_{\alpha} J^{-\frac{1}{2}} \partial_{\alpha}-i\left(c \partial_{\alpha}+\frac{1}{2} c_{\alpha}\right)-\frac{i}{2}\left(P c_{\alpha}-\bar{P} c_{\alpha}\right) .
\end{aligned}
$$

Both $c$ and the last coefficient $i\left(P c_{\alpha}-\bar{P} c_{\alpha}\right)$ are real, so $L$ is self-adjoint. We further note the quadratic expansion of $L$, namely

$$
\begin{equation*}
L \approx \partial_{\alpha}(1-\Re \mathbf{W}) \partial_{\alpha}-i\left(2 \Im \mathbf{W}_{\alpha} \partial_{\alpha}+\Im \mathbf{W}_{\alpha \alpha}\right)-\Re \mathbf{W}_{\alpha \alpha} \tag{6.3}
\end{equation*}
$$

Then our system takes the shorter form

$$
\left\{\begin{array}{l}
\left(\partial_{t}+b \partial_{\alpha}\right) w+\frac{1}{1+\overline{\mathbf{W}}^{2}} r_{\alpha}+\frac{R_{\alpha}}{1+\overline{\mathbf{W}}} w=\mathcal{G}_{0}(w, r)  \tag{6.4}\\
\left(\partial_{t}+b \partial_{\alpha}\right) r-i \frac{a}{1+\mathbf{W}} w+i P\left[\frac{L w}{1+\mathbf{W}}\right]=\mathcal{K}(w, r) .
\end{array}\right.
$$

It is interesting to also observe that after a seemingly innocuous cubic change in $\mathcal{G}_{0}$ we can also replace $\frac{R_{\alpha}}{1+\overline{\mathbf{W}}}$ by $P b_{\alpha}$. Then our system is rewritten as

$$
\left\{\begin{array}{l}
\left(\partial_{t}+b \partial_{\alpha}\right) w+\frac{1}{1+\overline{\mathbf{W}}} r_{\alpha}+P b w=\mathcal{G}(w, r)  \tag{6.5}\\
\left(\partial_{t}+b \partial_{\alpha}\right) r-i \frac{a}{1+\mathbf{W}} w+i P\left[\frac{L w}{1+\mathbf{W}}\right]=\mathcal{K}(w, r),
\end{array}\right.
$$

where the modified function $\mathcal{G}$ is given by

$$
\mathcal{G}=(1+\mathbf{W})(P \bar{m}+\bar{P} m)+w\left(\bar{P}\left[R_{\alpha} \bar{Y}\right]-P\left[R \bar{Y}_{\alpha}\right]\right)
$$

Projecting (6.2) onto the space of functions with the spectrum on the negative side of the real line, we obtain

$$
\left\{\begin{array}{l}
\left(\partial_{t}+\mathfrak{M}_{b} \partial_{\alpha}\right) w+P\left[\frac{1}{1+\overline{\mathbf{W}}} r_{\alpha}\right]+P b_{\alpha} w=G  \tag{6.6}\\
\left(\partial_{t}+\mathfrak{M}_{b} \partial_{\alpha}\right) r-i P\left[\frac{a}{1+\mathbf{W}} w\right]+i P\left[\frac{L w}{1+\mathbf{W}}\right]=K
\end{array}\right.
$$

where

$$
G(w, r):=P \mathcal{G}, \quad K(w, r):=P \mathcal{K} .
$$

The perturbative terms $G$ and $K$ are split into quadratic and higher terms as shown below

$$
G=G^{(2)}+G^{(3+)}, \quad K=K^{(2)}+K^{(3+)} .
$$

For the quadratic parts we have

$$
G^{(2)}(w, r)=P\left[R \bar{w}_{\alpha}-\mathbf{W} \bar{r}_{\alpha}\right], \quad K^{(2)}(w, r)=-P\left[R \bar{r}_{\alpha}\right]-i \frac{1}{2} P\left[\bar{w}_{\alpha \alpha} \mathbf{W}_{\alpha}-\bar{w}_{\alpha} \mathbf{W}\right] .
$$

The quartic and higher terms in $(G, K)$ are purely perturbative in our arguments, so we only need to consider some of the cubic terms. In the $w$ equation, only the $w$ terms are interesting, so we can set

$$
G^{(3)}=-P\left[\mathbf{W} \bar{R}_{\alpha} \bar{w}\right]-P\left[\left(P\left[R \overline{\mathbf{W}}_{\alpha}\right]-\bar{P}\left[R_{\alpha} \mathbf{W}\right] w\right]\right.
$$

In the $r$ equation, all undifferentiated cubic terms are relevant; there we set

$$
K^{(3)}=P\left[R\left(\overline{\mathbf{W}} \bar{r}_{\alpha}-\bar{R}_{\alpha} \bar{w}\right)\right] .
$$

Our main result for the linearized equation asserts that it is well-posed in $\dot{\mathcal{H}}^{1} \cap \dot{\mathcal{H}}^{\sigma}$ :
Theorem 5. Suppose that the solution $(W, Q) \in C\left(0, T ; \dot{\mathcal{H}}^{4} \cap \dot{\mathcal{H}}^{\sigma}\right)$ to the water wave equation is well defined in a time interval $[0, T]$ and satisfies the bounds

$$
\|(W, Q)(t)\|_{\dot{\mathcal{H}}^{3} \cap \dot{\mathcal{H}}^{\sigma}} \leq \epsilon t^{\delta}, \quad\|(W, Q)(t)\|_{X} \leq \epsilon t^{-\frac{1}{2}}
$$

with some fixed $\delta \ll 1$, and $\epsilon \ll \delta$. Then the solution $(w, q)$ to the linearized equation (6.1) satisfies the bounds

$$
\begin{equation*}
\|(w, q)(t)\|_{\dot{\mathcal{H}}^{1} \cap \dot{\mathcal{H}}^{\sigma}} \lesssim t^{C \epsilon^{2}}\|(w, q)(0)\|_{\dot{\mathcal{H}}^{1} \cap \dot{\mathcal{H}}^{\sigma}} \tag{6.7}
\end{equation*}
$$

We remark that one particular solution for the linearized equation is the scaling derivative $(w, q)=S(W, Q)$. Then, given the $S(W, Q)$ part of the initial data bound (1.20), we can conclude that we have

$$
\begin{equation*}
\|S(W, Q)\|_{\dot{\mathcal{H}}^{1} \cap \dot{\mathcal{H}}^{\sigma}} \lesssim \epsilon t^{C \epsilon^{2}} \tag{6.8}
\end{equation*}
$$

which is part of our bootstrap argument in the proof of Theorem 4.
Our proof of the theorem requires two steps. First we consider the high frequencies, for which we use the equation (6.6). In order to estimate the $\dot{\mathcal{H}}^{1}$ size of the solution $(w, r)$ we produce a quasilinear cubic $\dot{\mathcal{H}}^{1}$ energy, expressed in terms of the diagonal variables $(w, r)$, but whose evolution is governed by the full $\dot{\mathcal{H}}^{1} \cap \dot{\mathcal{H}}^{\sigma}$ size of $(w, q)$. The outcome of this analysis is contained in Proposition 6.1 below.

It remains to control the low frequencies, which is done using the equation (6.1), expressed in terms of the original $(w, q)$ variables. For these we instead use directly the normal form method, with some added cubic corrections; this calculation is carried at the level of the original variables $(w, q)$. The result is summarized in Proposition 6.2 below.

Finally, the conclusion of the Theorem is obtained by we putting together the two results in Proposition 6.1, respectively Proposition 6.2. Unlike the case of gravity waves, the transition between the two sets of variables $(w, r)$ and $(w, q)$ is harmless, due to the estimate

$$
\begin{equation*}
\|R w\|_{\dot{H}^{\frac{1}{2}} \cap \dot{H}^{\sigma-\frac{1}{2}}} \lesssim \epsilon\|w\|_{\dot{H}^{1} \cap \dot{H}^{\sigma}} . \tag{6.9}
\end{equation*}
$$

6.2. $\dot{\mathcal{H}}^{1}$ energy estimates. The goal of this section is to produce a cubic $\dot{\mathcal{H}}^{1}$ energy functional for the linearized equation. Precisely, we have

Proposition 6.1. There exists an energy functional $\mathbf{E}^{1}(w, r)$ with the following two properties:
(i) Energy equivalence:

$$
\begin{equation*}
\mathbf{E}^{1}(w, r)=(1+O(\epsilon))\|(w, q)\|_{33}^{2}+O(\epsilon)\|(w, q)\|_{\dot{\mathcal{H}}^{1}}^{2}+ \tag{6.10}
\end{equation*}
$$

(ii) Cubic energy estimates:

$$
\begin{equation*}
\frac{d}{d t} \mathbf{E}^{1}(w, r) \lesssim\|(W, Q)\|_{X}^{2}\left(\|(w, q)\|_{\dot{\mathcal{H}}^{1}}^{2}+\|(w, q)\|_{\dot{\mathcal{H}}^{\sigma}}^{2}\right) \tag{6.11}
\end{equation*}
$$

We remark that the above estimate is not self-contained, and it can be used only coupled with a similar $\dot{\mathcal{H}}^{\sigma}$ result. This issue is on one hand due to our definition of $R$, which involves the undifferentiated variable $w$. One could avoid this by redefining $r$ as $r=q-T_{R} w$. However, this would make our equations and analysis more complicated, and would serve little purpose in the present paper, where the $\dot{\mathcal{H}}^{\sigma}$ result is the primary one. Secondly, in order to define the normal form energy corrections we have to use the undifferentiated $w$ regardless. So a lower norm seems necessary for the cubic estimates in any case.
Proof. Naively we start with the linear energy $\|(w, r)\|_{\dot{\mathcal{L}}^{1}}^{2}$ and construct a suitable modification of it.There are three main difficulties in this process:
a) The equations are quasilinear, so a quasilinear correction is needed in order to account for the high frequencies.
b) The linear energy is not cubic, so a normal form type cubic correction is needed in order to eliminate cubic errors.
c) The $L^{2}$ norm of $w$ is not controlled, so quartic error terms containing undifferentiated $w$ cannot be controlled directly. A further quartic normal form correction to the energy needs to be used for such terms.

We will pursue these steps in the above order.
a) The natural quasilinear energy functional associated to the above system is obtained if we multiply the second equation by $i r_{\alpha}$ and the first by $L w$. These multipliers are matched so that the mixed $r_{\alpha} w$ terms cancel in the computation. Thus it is natural to define

$$
\begin{equation*}
E_{l i n}^{2}(w, r)=\int_{\mathbb{R}}-\Re(L w \cdot \bar{w})+\Im\left(r \partial_{\alpha} \bar{r}\right) d \alpha \tag{6.12}
\end{equation*}
$$

Now we compute the time derivative of the above energy. We use the second equation to write

$$
\frac{d}{d t} \int \Im\left(r \partial_{\alpha} \bar{r}\right) d \alpha=2 \Im \int\left(\partial_{t}+\mathfrak{M}_{b} \partial_{\alpha}\right) r \partial_{\alpha} \bar{r} d \alpha=2 \Re \int(i a w-L w) \frac{\bar{r}_{\alpha}}{1+\mathbf{W}}-i \mathcal{K} \overline{\mathcal{r}}_{\alpha} d \alpha
$$

To compute in the first equation we introduce the skew-adjoint operator

$$
N:=\partial_{t}+b \partial_{\alpha}+P b .
$$

Then we can write

$$
\frac{d}{d t} \int_{\mathbb{R}} \Re(L w \cdot \bar{w}) d \alpha=\Re \int-2 L w \frac{\bar{r}_{\alpha}}{1+\mathbf{W}}+2 \overline{\mathcal{G}} L w+[N, L] w \cdot \bar{w} d \alpha .
$$

Summing up, the mixed terms cancel, and we obtain

$$
\begin{equation*}
\frac{d}{d t} E_{l i n}^{2}(w, r)=2 \Re \int i \overline{\mathcal{K}} r_{\alpha}-\overline{\mathcal{G}} L w d \alpha+\int[N, L] w \cdot \bar{w} d \alpha+\int \frac{a w \bar{r}_{\alpha}}{1+\mathbf{W}} d \alpha \tag{6.13}
\end{equation*}
$$

We now successively consider the three integrals above, which are denoted by $I_{1}, I_{2}$ and $I_{3}$. Our goal will be to peel off good terms, retaining a leading part which will be rectified with further energy corrections. Here, by good terms we mean terms which can be estimated by the right hand side in (6.11).

The integral $I_{1}$. We begin with the $\mathcal{K}$ term. Since $r_{\alpha}$ is holomorphic, we can freely replace $\mathcal{K}$ with $K$, and then drop the projections. The only terms which cannot be readily estimated as in the proposition are the cubic terms. Thus for the corresponding part $I_{1}(\mathcal{K})$ of $I_{1}$ we obtain

$$
I_{1}(\mathcal{K})=2 \Re \int i r_{\alpha}\left(-\bar{R} q_{\alpha}+i \frac{1}{2} \overline{\mathbf{W}} w_{\alpha \alpha}-i \frac{1}{2} \overline{\mathbf{W}}_{\alpha} w_{\alpha}\right) d \alpha+\text { good }
$$

Next we consider the $\mathcal{G}$ term. Integrating by parts we rewrite it as

$$
I_{1}(\mathcal{G})=\int J^{-\frac{1}{2}} \overline{\mathcal{G}}_{\alpha} \cdot w_{\alpha}+\overline{\mathcal{G}}\left(i\left(c \partial_{\alpha}+\frac{1}{2} c_{\alpha}\right)+\frac{i}{2}\left(P c_{\alpha}-\bar{P} c_{\alpha}\right) d \alpha .\right.
$$

Here we recall that

$$
\mathcal{G}=(1+\mathbf{W})(P \bar{m}+\bar{P} m)+w\left(\bar{P}\left[R_{\alpha} \bar{Y}\right]-P\left[R \bar{Y}_{\alpha}\right]\right)
$$

For the first component of $\mathcal{G}$ we use the expression of $m$ in terms of $(w, q)$. Thus $\mathcal{G}_{\alpha}$ will contain higher derivatives of $w$ and $q$. But these are either $\bar{w}_{\alpha \alpha}, \bar{q}_{\alpha \alpha}$ and $\bar{q}_{\alpha}$ inside a $P$ projector, or $w_{\alpha \alpha}, q_{\alpha \alpha}$ and $q_{\alpha}$ inside a $\bar{P}$ projector. Thus the extra derivatives can be harmlessly shifted to their co-factor in our estimates, see e.g., Lemma 2.1, Appendix B in [20]. At the other end, however, we need to be more careful with the terms which contain undifferentiated $w$, as we only control $w$ in $\dot{H}^{\sigma}$ and not in $L^{2}$; for such terms we will use the Sobolev embedding $\dot{H}^{\sigma} \subset L^{p}$ and regain the lost integrability from one of the other factors.

To summarize, in $I_{1}(\mathcal{G})$ we can control all quintic and higher terms, and also all quartic terms which do not contain undifferentiated $w$. Thus we retain the cubic part of $I_{1}(\mathcal{G})$, which is the integral of $m \cdot w_{\alpha \alpha}$, as well as the quartic terms with a $w$ factor. Expanding these terms, we have

$$
\begin{aligned}
I_{1}(\mathcal{G})= & 2 \Re \int-w_{\alpha \alpha}\left(\bar{R} w_{\alpha}-\overline{\mathbf{W}} q_{\alpha}\right)-\bar{w}_{\alpha \alpha} w\left(P\left(R \overline{\mathbf{W}}_{\alpha}\right)-\bar{P}\left(R_{\alpha} \overline{\mathbf{W}}\right)\right) d \alpha \\
& +2 \Re \int w \bar{w}_{\alpha}\left(\bar{P}\left(R_{\alpha} \mathbf{W}\right)_{\alpha}-P\left(R \overline{\mathbf{W}}_{\alpha}\right)_{\alpha}\right)+i w P c_{\alpha} \bar{P}\left(\bar{R} w_{\alpha}-\overline{\mathbf{W}} q_{\alpha}\right) d \alpha+\text { good }
\end{aligned}
$$

The integral $I_{2}$. Here we need to compute the above (selfadjoint) commutator. We have

$$
\begin{aligned}
{[N, L]=} & {\left[\partial_{t}+b \partial_{\alpha}+P b_{\alpha}, \partial_{\alpha} J^{-\frac{1}{2}} \partial_{\alpha}-i c \partial_{\alpha}-i P c_{\alpha}\right] } \\
= & \partial_{\alpha}\left(\partial_{t}+b \partial_{\alpha}\right) J^{-\frac{1}{2}} \partial_{\alpha}-i\left(\partial_{t}+b \partial_{\alpha}\right) c \partial_{\alpha}-i\left(\partial_{t}+b \partial_{\alpha}\right) P c_{\alpha} \\
& -\partial_{\alpha} J^{-\frac{1}{2}}\left(b_{\alpha} \partial_{\alpha}+P b_{\alpha \alpha}\right)-\left(\partial_{\alpha} b_{\alpha}-\bar{P} b_{\alpha \alpha}\right) J^{-\frac{1}{2}} \partial_{\alpha}+i c\left(b_{\alpha} \partial_{\alpha}+P b_{\alpha \alpha}\right) \\
= & \partial_{\alpha}\left[\left(\partial_{t}+b \partial_{\alpha}\right) J^{-\frac{1}{2}}-2 J^{-\frac{1}{2}} b_{\alpha}\right] \partial_{\alpha}-i\left(c_{t}+b c_{\alpha}-c b_{\alpha}+J^{-\frac{1}{2}} H b_{\alpha \alpha}\right) \partial_{\alpha} \\
& -i\left(P c_{\alpha t}+b P c_{\alpha \alpha}-c P b_{\alpha \alpha}\right)-\partial_{\alpha}\left(J^{-\frac{1}{2}} P b_{\alpha \alpha}\right) .
\end{aligned}
$$

First of all, we need to compute the linear part of this operator using

$$
c \approx 2 \Im \mathbf{W}_{\alpha}, \quad b \approx 2 \Re R, \quad J^{-\frac{1}{2}} \approx 1-\Re \mathbf{W}
$$

Then we get

$$
\begin{equation*}
[N, L] \approx-3 \partial_{\alpha} \Re R_{\alpha} \partial_{\alpha} \tag{6.14}
\end{equation*}
$$

therefore we can write

$$
I_{2}=\int 3 \Re R_{\alpha}\left|w_{\alpha}\right|^{2} d \alpha+\text { quartic }+ \text { higher } .
$$

However, as before, we also need to retain the quartic terms with undifferentiated $w$. Even worse are the terms with $|w|^{2}$. Hence for the lower order terms in $[N, L]$ we need a good quadratic expansion. Our complete expansion for $[N, L]$ will be
$[N, L]=-3 \partial_{\alpha}\left(\Re R_{\alpha}+\right.$ quad $) \partial_{\alpha}+\left(L_{2}(\mathbf{W}, R)+\right.$ cubic $) \partial_{\alpha}+i \partial_{t}\left(\bar{R} R_{\alpha}\right)+\partial_{\alpha} L_{2}(\mathbf{W}, R)+$ cubic.
The quadratic part of the coefficient of $\partial_{\alpha}$ is easily seen to have the form $L_{2}(\mathbf{W}, R)$. It remains to compute the quadratic terms in the zero order term of the commutator,

$$
\gamma=i\left(P c_{\alpha t}+b P c_{\alpha \alpha}-c P b_{\alpha \alpha}\right)-\partial_{\alpha}\left(J^{-\frac{1}{2}} P b_{\alpha \alpha}\right)
$$

Precisely, we claim that we can write it in the form

$$
\gamma=i \partial_{t}\left(\bar{R} R_{\alpha}\right)+\partial_{\alpha} L_{2}(W, R)+\gamma_{3},
$$

where $\gamma_{2}=$ stands for a quadratic expression in $\mathbf{W}, R$ and their derivatives while $\gamma_{3}$ contains only cubic and higher terms in $(\mathbf{W}, R)$. Indeed, we have

$$
c \approx \Im\left(\mathbf{W}_{\alpha}(2-3 \mathbf{W}-\overline{\mathbf{W}})\right), \quad b \approx 2 \Re P[R(1-\mathbf{W})]
$$

while

$$
P c_{\alpha t}=-2 \Im R_{\alpha \alpha \alpha}+\partial_{\alpha} L_{2}(\mathbf{W}, R)
$$

therefore

$$
\begin{aligned}
\gamma & =(R+\bar{R}) \mathbf{W}_{\alpha \alpha \alpha}-\left(\mathbf{W}_{\alpha}-\overline{\mathbf{W}}_{\alpha}\right) R_{\alpha \alpha}+\partial_{\alpha} L_{2}(\mathbf{W}, R)+\gamma_{3} \\
& =i \partial_{t}\left(\bar{R} R_{\alpha}\right)+\overline{\mathbf{W}}_{\alpha \alpha} R_{\alpha}+\overline{\mathbf{W}}_{\alpha} R_{\alpha \alpha}+\partial_{\alpha} L_{2}(\mathbf{W}, R)+\gamma_{3} \\
& =i \partial_{t}\left(\bar{R} R_{\alpha}\right)+\partial_{\alpha} L_{2}(\mathbf{W}, R)+\gamma_{3}
\end{aligned}
$$

which concludes the proof of the expansion (6.15). Thus, for $I_{2}$ we obtain

$$
I_{2}=\Re \int-3 \Re R_{\alpha}\left|w_{\alpha}\right|^{2}+i \partial_{t}\left(R R_{\alpha}\right)|w|^{2}+w \bar{w}_{\alpha} L_{2}(\mathbf{W}, R) d \alpha+\text { good }
$$

The integral $I_{3}$. Here we simply retain the quartic part,

$$
I_{3}=-\Re \int w \bar{r}_{\alpha} a d \alpha
$$

Summing up the contributions from $I_{1}, I_{2}$ and $I_{3}$ and reorganizing terms, our energy computation so far reads as

$$
\frac{d}{d t} E_{l i n}^{2}(w, r)=E r_{1}+E r_{2}+E r_{3}+E r_{4}+\text { good }
$$

where $E r_{1}$ contains the holomorphic cubic terms,

$$
\begin{aligned}
E r_{1} & =2 \Re \int i r_{\alpha}\left(-\bar{R} r_{\alpha}+i \frac{1}{2} \overline{\mathbf{W}} w_{\alpha \alpha}-i \frac{1}{2} \overline{\mathbf{W}}_{\alpha} w_{\alpha}\right)-w_{\alpha \alpha}\left(\bar{R} w_{\alpha}-\overline{\mathbf{W}} r_{\alpha}\right) d \alpha \\
& =2 \Re \int-i q_{\alpha} \bar{R} q_{\alpha}+\frac{1}{2} q_{\alpha} \overline{\mathbf{W}} w_{\alpha \alpha}+\frac{1}{2} q_{\alpha} \overline{\mathbf{W}}_{\alpha} w_{\alpha}-\sigma w_{\alpha \alpha} \bar{R} w_{\alpha} d \alpha
\end{aligned}
$$

$E r_{2}$ contains the mixed cubic terms,

$$
E r_{2}=\int 3 \Re R_{\alpha} w_{\alpha} \bar{w}_{\alpha} d \alpha
$$

$E r_{3}$ contains the single remaining quartic $|w|^{2}$ term,

$$
E r_{3}=\Re \int \partial_{t}\left(i \bar{R} R_{\alpha}\right)|w|^{2} d \alpha
$$

and $E r_{4}$ contains the quartic terms with a single $w$ factor,

$$
E r_{4}=\Re \int w w_{\alpha} L_{2}(W, R)+w \bar{w}_{\alpha} L_{2}(W, R)+w q_{\alpha}\left(L_{1}(\mathbf{W}, \mathbf{W})+L_{0}(R, R)\right) d \alpha
$$

Now we successively correct the energy in order to cancel the four terms above.
The $E r_{1}$ term. To account for $E r_{1}$ we introduce a correction of the form

$$
C_{1}=2 \Re \int L_{1}^{1}(w, q, \bar{R})+L_{2}^{2}(w, w, \overline{\mathbf{W}})+L_{1}^{3}(q, q, \overline{\mathbf{W}}) d \alpha
$$

so that

$$
\begin{equation*}
\frac{d}{d t} C_{1}=E r_{1}+q u a r t i c \tag{6.16}
\end{equation*}
$$

Here the trililnear forms $L_{1}^{1}$ have smooth homogeneous symbols, where the lower index indicates the order. Thus, the quartic terms on the right in (6.16) may contain at most one undifferentiated factor, and, if that factor is $w$, then they can be included in $E r_{4}$.

This and the next $E r_{2}$ part are the counterparts here of the normal form calculation in Proposition 3.2, and are a consequence of the fact that bilinear interactions are non-resonant in our problem, except at frequency zero. Because of the resonance at frequency zero, it is very useful that all factors in the $E r_{1}$ and $E r_{2}$ integrands are differentiated. One could recast this calculation in terms of the outcome of Proposition 3.2, but it is more efficient to redo it directly.

Denoting the symbols of $L_{1}^{1}, L_{2}^{2}$ and $L_{1}^{3}$ by $m_{1}, m_{2}$, respectively $m_{3}$ for the three expressions, from the relation (6.16) we obtain the system

$$
\left\{\begin{aligned}
{\left[\eta^{2} m_{1}(\xi, \eta)\right]_{s y m}+(\xi+\eta) m_{2}(\xi, \eta) } & =\frac{1}{2} \xi \eta(\xi+\eta) \\
-(\xi+\eta)^{2} m_{1}(\xi, \eta)-2 \eta m_{2}(\xi, \eta)+2 \xi^{2} m_{3}(\xi, \eta) & =-\frac{1}{2} \xi \eta^{2} \\
-\left[\xi m_{1}(\xi, \eta)\right]_{s y m}+(\xi+\eta) m_{3}(\xi, \eta) & =-\xi \eta
\end{aligned}\right.
$$

Expanding the middle equation into a symmetric and an antisymmetric part we obtain

$$
\left\{\begin{aligned}
& {\left[\eta^{2} m_{1}(\xi, \eta)\right]_{s y m}+(\xi+\eta) m_{2}(\xi, \eta) }=\frac{1}{2} \xi \eta(\xi+\eta) \\
&-(\xi+\eta)^{2}\left[\eta^{2} m_{1}(\xi, \eta)\right]_{s y m}-\left(\eta^{3}+\xi^{3}\right) m_{2}(\xi, \eta)+2 \eta^{2} \xi^{2} m_{3}(\xi, \eta)=-\frac{1}{4} \xi \eta\left(\xi^{3}+\eta^{3}\right) \\
&-(\xi+\eta)^{2}\left[\xi m_{1}(\xi, \eta)\right]_{s y m}-2 \xi \eta m_{2}(\xi, \eta)+\left(\xi^{3}+\eta^{3}\right) m_{3}(\xi, \eta)=-\frac{1}{2} \xi^{2} \eta^{2} \\
&-\left[\xi m_{1}(\xi, \eta)\right]_{s y m}+(\xi+\eta) m_{3}(\xi, \eta)=-\xi \eta \\
& 37
\end{aligned}\right.
$$

The matrix of this system is equivalent to the matrix in Proposition 3.2. A short computation leads to

$$
\left\{\begin{aligned}
m_{2}=\frac{1}{4}\left(3 \xi^{2}+10 \xi \eta+3 \eta^{2}\right) \frac{\xi^{2}+3 \xi \eta+\eta^{2}}{9 \xi^{2}+14 \xi \eta+9 \eta^{2}}, & m_{3}=-2(\xi+\eta) \frac{\xi^{2}+3 \xi \eta+\eta^{2}}{9 \xi^{2}+14 \xi \eta+9 \eta^{2}} \\
{\left[\eta^{2} m_{1}(\xi, \eta)\right]_{s y m}=\frac{1}{2}(\xi+\eta)\left(\xi \eta-m_{2}\right), } & {\left[\xi m_{1}(\xi, \eta)\right]_{s y m}=\xi \eta+(\xi+\eta) m_{3} }
\end{aligned}\right.
$$

Solving for $m_{1}$ from the last two relations yields

$$
m_{1}=\frac{1}{\eta^{3}-\xi^{3}}\left(\xi \eta(\eta-\xi)(\eta+2 \xi)-(\xi+\eta)\left(\eta m_{2}+\xi^{2} m_{3}\right)\right)
$$

The last factor vanishes when $\xi=\eta$, and we obtain

$$
m_{1}=\frac{1}{\eta^{2}-\xi \eta+\xi^{2}}\left(\xi \eta(\eta+2 \xi)-\frac{(\xi+\eta)\left(8 \xi^{2}+13 \xi \eta-3 \eta^{2}\right)\left(\xi^{2}+3 \xi \eta+\eta^{2}\right)}{4\left(9 \xi^{2}+14 \xi \eta+9 \eta^{2}\right)}\right)
$$

Thus, the symbols $m_{1}, m_{2}$ and $m_{3}$ are all regular.
Finally, in order to prove (6.10) it suffices to verify that

$$
\left|C_{1}\right| \lesssim O(\epsilon)\|(w, r)\|_{\dot{\mathcal{H}}^{1} \cap \dot{\mathcal{H}}^{\sigma}}
$$

which is straightforward by Proposition 2.2.
The $E r_{2}$ term. Here we seek to find an energy correction which removes the main cubic error,

$$
E r_{2}=3 \int \Re R_{\alpha} w_{\alpha} \bar{w}_{\alpha} d \alpha
$$

Our first candidate is an energy correction of the form

$$
C_{2}=\int A(R, w, \bar{r})+B(R, r, \bar{w})+C(\mathbf{W}, w, \bar{w})+D(\mathbf{W}, r, \bar{r}) d \alpha
$$

Then for the symbols of $A, B, C, D$ we get the linear system

$$
\left\{\begin{aligned}
\zeta^{2} A-\eta^{2} B-\xi C & =\xi \eta \zeta \\
-\xi^{2} B-\eta C+\zeta^{2} D & =0 \\
-\xi^{2} A+\zeta C-\eta^{2} D & =0 \\
-\eta A+\zeta B-\xi D & =0
\end{aligned}\right.
$$

(where $\zeta=\xi+\eta$ ), which has solutions

$$
\begin{array}{ll}
A=\frac{6 \zeta^{3}}{9 \xi^{2}+14 \xi \eta+9 \eta^{2}}, & B=\frac{2 \zeta\left(-4 \xi^{2}+3 \xi \eta+3 \eta^{2}\right)}{9 \xi^{2}+14 \xi \eta+9 \eta^{2}} \\
C=\frac{\xi \zeta\left(6 \xi^{2}+6 \xi \eta+4 \eta^{2}\right)}{9 \xi^{2}+14 \xi \eta+9 \eta^{2}}, & D=\frac{-4 \xi \zeta^{2}}{9 \xi^{2}+14 \xi \eta+9 \eta^{2}}
\end{array}
$$

As defined, $C_{2}$ has the property that

$$
\frac{d}{d t} C_{2}=E r_{2}+q u a r t i c
$$

However, the quartic terms will include unbounded expressions involving $w_{\alpha} \bar{w}_{\alpha \alpha}$ and $r_{\alpha} \bar{r}_{\alpha}$. Thus we cannot work directly with $C_{2}$, and instead we need a quasilinear correction for it. In order to find this quasilinear correction we first separate a leading part for $C_{2}$, which is
obtained by taking the first term in the expansion of the symbols above near $\xi=0$. We obtain the differential trilinear form

$$
C_{2, \text { high }}=\int \frac{4}{3} \Re R \Im\left(w_{\alpha} \bar{r}\right)-\frac{4}{9} \Im \mathbf{W}_{\alpha}\left(\Im\left(w \bar{w}_{\alpha}\right)+|r|^{2}\right) d \alpha,
$$

which has the property that the reminder $C_{2, \text { low }}=C_{2}-C_{2, \text { high }}$ has the form

$$
C_{2, \text { low }}=\Re \int L_{0}\left(R_{\alpha}, w, \bar{r}\right)+L_{0}\left(R_{\alpha}, r, \bar{w}\right)+L_{0}\left(\mathbf{W}_{\alpha}, w, \bar{w}\right)+L_{-1}\left(\mathbf{W}_{\alpha}, r, \bar{r}\right) d \alpha
$$

This has the key property that its time derivative no longer contains unbounded expressions in $(w, r)$. The quasilinear modification of the term $C_{2, h i g h}$ is obtained in the same manner as in the high frequency bounds in Proposition 4.1, namely by setting

$$
\tilde{C}_{2, h i g h}=\int \frac{4}{3} \Re R \Im\left((1+\mathbf{W}) w_{\alpha} \bar{r}\right)-\frac{4}{9} \Im \mathbf{W}_{\alpha}\left(J^{-\frac{1}{2}} \Im\left(w \bar{w}_{\alpha}\right)+|r|^{2}\right)\left(\mathbf{W}_{\alpha} J^{-\frac{1}{2}} w \bar{w}_{\alpha}+i \mathbf{W}_{\alpha} r \bar{r}\right) d \alpha .
$$

Then we define the final correction

$$
\tilde{C}_{2}=\tilde{C}_{2, \text { high }}+C_{2, \text { low }},
$$

so that $\tilde{C}_{2}=C_{2}+$ quartic. Now we consider the error term

$$
\frac{d}{d t} \tilde{C}_{2}-E r_{2}=\text { quartic. }
$$

By construction this error term no longer contains any unbounded components, and any part of it which has a single undifferentiated $w$ can be included in $E r_{4}$. The only remaining issue is whether we obtain any $|w|^{2}$ contributions from the lower order terms in $A$ and $C$. These can arise only in the case when the time derivative applies on the conjugated factor, and no $\alpha$ derivatives apply to the $w$ factor. Thus this time we can replace $C_{2}$ with its leading low frequency part, obtained by setting $\eta=0$ in our symbols. This gives the expression

$$
C_{2, v l o w}=\frac{2}{3} \Re \int i R_{\alpha} w \bar{r}+\mathbf{W}_{\alpha \alpha} w \bar{w} d \alpha
$$

But from the equations (6.2) we have

$$
\partial_{t} r=i \mathbf{W}_{\alpha \alpha} w+\text { higher order }, \quad \partial_{t} w=-R_{\alpha} w+\text { higher order },
$$

which shows that the $|w|^{2}$ terms nicely cancel. We remark that this is not at all surprising. Had we done the $E r_{2}$ computations using the $(w, q)$ variables, such terms would not have arisen in the first place; however, this would have been very cumbersome for the high frequency analysis.

For (6.10) one also needs the bound

$$
\left|C_{2}\right| \lesssim O(\epsilon)\|(w, r)\|_{\dot{\mathcal{H}}^{1} \cap \dot{\mathcal{H}}^{\sigma}}
$$

which is a consequence by Proposition 2.2.
The $E r_{3}$ term. The term

$$
E r_{3}=\Re \int \partial_{t}\left(i \bar{R} R_{\alpha}\right)|w|^{2} d \alpha
$$

is corrected with

$$
C_{3}=\Re \int_{39}\left(i \bar{R} R_{\alpha}\right)|w|^{2} d \alpha
$$

This generates further quartic errors with a single undifferentiated $w$, which are placed in $E r_{4}$. It is also easily bounded as an error term in (6.10).

The $E r_{4}$ term. Here we need to consider quartic terms of the form

$$
\begin{aligned}
E r_{4}= & \Re \int w w_{\alpha} L_{2}(\mathbf{W}, R)+w \bar{w}_{\alpha} L_{2}(\mathbf{W}, R) \\
& +w q_{\alpha}\left(L_{1}(\mathbf{W}, \mathbf{W})+L_{0}(R, R)\right)+w \bar{q}_{\alpha}\left(L_{1}(\mathbf{W}, \mathbf{W})+L_{0}(R, R)\right) d \alpha
\end{aligned}
$$

Exactly as in the case of the low frequency bounds in Proposition 5.1, such terms can be estimated directly unless we have the lowest frequency on $w$. Thus it suffices to consider the bad part of $E r_{4}$, which has the form

$$
E r_{4, b a d}=\Re \int w G^{h h h \rightarrow l}\left(\left(w_{\alpha}, q_{\alpha}\right),\left(W_{\alpha}, Q_{\alpha}\right),\left(W_{\alpha}, Q_{\alpha}\right)\right) d \alpha
$$

with $G \in \mathfrak{C}_{0}^{3}$ and $G^{h h h \rightarrow l}$ defined as in Proposition 3.2, with three high frequency inputs going to a low frequency output. But this frequency balance insures that the above quartic form is non-resonant and can be removed with a normal form energy correction. To achieve this, for this trilinear form $G$ we apply Proposition 3.2. We obtain a pair of trilinear forms

$$
\left(W_{[3]}^{h h h \rightarrow l}, Q_{[3]}^{h h h \rightarrow l}\right) \in\left(\mathfrak{B}_{1}((w, q),(\mathbf{W}, Q),(W, Q)), \mathfrak{C}_{1}((w, q),(\mathbf{W}, Q),(W, Q))\right),
$$

so that we have

$$
\left\{\begin{array}{l}
W_{[3], t}^{h h h \rightarrow l}+Q_{[3], \alpha}^{h h h \rightarrow l}=F+\text { quartic }  \tag{6.17}\\
Q_{[3], t}^{h h h \rightarrow l}+i W_{[3], \alpha \alpha}^{h h h \rightarrow l}=\text { quartic } .
\end{array}\right.
$$

Then our energy correction is defined as

$$
C_{4}=\int w W_{[3]}^{h h h \rightarrow l}((w, q),(W, Q),(W, Q)) d \alpha .
$$

Differentiating this with respect to time and integrating by parts we obtain

$$
\frac{d}{d t} C_{4}-E r_{4, \text { bad }}=\int w_{\lambda, \alpha} Q_{[3]}^{h h h \rightarrow l}((w, q),(W, Q),(W, Q)) d \alpha+\text { quintic }
$$

where $Q$ has at most one undifferentiated factor. The quintic term is always easy to bound, and in the remaining quartic term we have a derivative on the low frequency factor, so this is also admits a favorable estimate.

Finally, by Proposition [2.2 it is not difficult to verify that $C_{4}$ is a negligible error term for (6.10).
6.3. Low frequency analysis and the normal form linearized equation. The goal of this section is to produce a cubic $\dot{\mathcal{H}}^{\sigma}$ energy functional for the linearized equation. Precisely,

Proposition 6.2. There exists an energy functional $\mathbf{E}^{\sigma}(w, q)$ with the following two properties:
(i) Energy equivalence:

$$
\begin{equation*}
\mathbf{E}^{\sigma}(w, q)=\left\|P_{<1}(w, q)\right\|_{\dot{\mathcal{H}}^{\sigma}}^{2}+O(\epsilon)\|(w, q)\|_{\dot{\mathcal{H}}^{\sigma}}^{2}, \tag{6.18}
\end{equation*}
$$

(ii) Cubic energy estimates:

$$
\begin{equation*}
\frac{d}{d t} \mathbf{E}^{\sigma}(w, q) \lesssim\|(W, Q)\|_{X}^{2}\|(w, q)\|_{\mathcal{H}^{\sigma}}^{2} . \tag{6.19}
\end{equation*}
$$

Proof. The quasilinear nature of the problem is no longer a factor in the estimate for low frequencies. Instead we can treat the equation as a semilinear equation, and only the quadratic and cubic terms matter. Then our starting point is the equation (6.1) for the ( $w, q$ ) variables. The motivation is that in this way all nonlinear terms contain only differentiated factors, which is convenient at low frequency.

To eliminate the quadratic terms and the bad cubic terms we will switch to normal form variables $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$. Rather than redo the computation from scratch, at this point it is very convenient to directly linearize the equation (5.11) and denote by ( $\tilde{\tilde{w}}, \tilde{\tilde{q}}$ ) the associated linearized variables.

Thus, ( $(\tilde{\tilde{w}}, \tilde{\tilde{q}})$ can be expressed as

$$
\left\{\begin{array}{l}
\tilde{\tilde{w}}=w+W_{[2]}((w, q),(W, Q))+W_{[3]}((w, q),(W, Q),(W, Q)) \\
\tilde{\tilde{q}}=q+Q_{[2]}((w, q),(W, Q))+Q_{[3]}((w, q),(W, Q),(W, Q)),
\end{array}\right.
$$

and their equation is obtained by linearizing the equation (5.11),

$$
\left\{\begin{array}{l}
\tilde{\tilde{w}}_{t}+\tilde{\tilde{q}}_{\alpha}=G_{l i n}(w, q) \\
\tilde{\tilde{q}}_{t}-i \tilde{\tilde{w}}_{\alpha \alpha}=K_{l i n}(w, q)
\end{array}\right.
$$

To conclude the proof, we define our low frequency energy as simply as

$$
\begin{equation*}
\mathbf{E}^{\sigma}(w, q):=\left\|P_{<1}(w, q)\right\|_{\dot{\mathcal{H}}^{\sigma}}^{2} . \tag{6.20}
\end{equation*}
$$

Then we need to prove the bounds

$$
\begin{gather*}
\| P_{<1}\left(W_{[2]}((w, q),(W, Q)), Q_{[2]}((w, q),(W, Q))\left\|_{\dot{\mathcal{H}}^{\sigma}} \lesssim \epsilon\right\|(w, q) \|_{\dot{\mathcal{H}}^{\sigma}}\right.  \tag{6.21}\\
\left.\left.\| P_{<1}\left(W_{[3]}((w, q),(W, Q)),(W, Q)\right), Q_{[3]}((w, q),(W, Q)),(W, Q)\right)\right)\left\|_{\dot{\mathcal{H}}^{\sigma}}\right\| \lesssim \epsilon(w, q) \|_{\dot{\mathcal{H}}^{\sigma}}
\end{gather*}
$$

respectively

$$
\begin{equation*}
\left\|P_{<1}\left(G_{l i n}, K_{l i n}\right)(w, q) W_{[2]}((w, q),(W, Q))\right\|_{\dot{\mathcal{H}}^{\sigma}} \lesssim\|(W, Q)\|_{X}^{2}\|(w, q)\|_{\dot{\mathcal{H}}^{\sigma}} . \tag{6.22}
\end{equation*}
$$

Proof of (6.21). This argument is relatively straightforward, once we separate the low and high frequencies of $(w, q)$. We do this for $\left(W_{[2]}, Q_{[2]}\right)$; the argument for ( $\left.W_{[3]}, Q_{[3]}\right)$ is similar.

Suppose that first that $(w, q)$ are supported at low frequency $(<1)$. Then we have control $\|w\|_{L^{p}}$ and $\|q\|_{L^{2}}$, as well as all their derivatives. On the other hand for the output it suffices to bound

$$
\left\|W_{[2]}((w, q),(W, Q))\right\|_{L^{2}}+\left\|Q_{[2]}((w, q),(W, Q))\right\|_{L^{q}} .
$$

This follows directly from the bilinear estimates in Proposition (2.2).
Suppose now that $(w, q)$ are supported at high frequencies ( $>1$ ). The bilinear forms $\left(W_{[2]}, Q_{[2]}\right),\left(W_{[3]}, Q_{[3]}\right)$ involve up to two derivatives of $(w, q)$, and we want to eliminate them using the fact that the output is localized at frequency 1. For that we write

$$
(w, q)=\partial_{\alpha}^{3}\left(w_{1}, q_{1}\right), \quad\left(w_{1}, q_{1}\right) \in H^{2}
$$

Then we use Leibniz's rule to write

$$
\begin{aligned}
W_{[2]}((w, q),(W, Q))= & W_{[2]}\left(\partial_{\alpha}^{2}(w, q),(W, Q)\right) \\
= & \partial_{\alpha}^{2} W_{[2]}\left(\left(w_{1}, q_{1}\right),(W, Q)\right)-2 \partial_{\alpha} W_{[2]}\left(\left(w_{1}, q_{1}\right), \partial_{\alpha}(W, Q)\right) \\
& +W_{[2]}\left(\left(w_{1}, q_{1}\right), \partial_{\alpha}^{2}(W, Q)\right) .
\end{aligned}
$$

The derivatives in front are bounded once the $P_{<1}$ localization is added, and we conclude again using the bilinear estimates in Proposition (2.2).

Proof of (6.22). This is a direct consequence of the proof of the estimate (5.4), where we were careful to insure that the estimates for each component can be proved by using only an $\dot{\mathcal{H}}^{\sigma} \cap \dot{\mathcal{H}}^{2}$ on an arbitrarily chosen factor.

This yields the desired conclusion directly provided that $(w, q)$ are at low frequency. If they are at high frequency, then we use Leibniz's rule as above in order to transfer the derivatives on either the output, or on the $(W, Q)$ factors.

## 7. Klainerman-Sobolev and pointwise bounds

Here we use the energy estimates to derive the pointwise bounds with $\epsilon$ loss. We begin by summarizing all the energy bounds we have at our disposal. From the energy estimates for $(W, Q)$ we have

$$
\begin{equation*}
\|(W, Q)\|_{\dot{\mathcal{H}}^{10} \cap \dot{\mathcal{H}}^{\sigma}} \lesssim \epsilon t^{c \epsilon^{2}} . \tag{7.1}
\end{equation*}
$$

Using Proposition 2.2, this transfers to the normal form variables ( $\tilde{W}, \tilde{\tilde{Q}}$ ) introduced in Proposition 5.1 with a two derivatives loss,

$$
\begin{equation*}
\|(\tilde{W}, \tilde{\tilde{Q}})\|_{\dot{\mathcal{H}}^{8} \cap \dot{\mathcal{H}}^{\sigma}} \lesssim \epsilon t^{c \epsilon^{2}} . \tag{7.2}
\end{equation*}
$$

In effect, if we also use the pointwise bootstrap assumption (1.24), then for the difference we get a better bound at low frequency,

$$
\begin{equation*}
\|(\tilde{\tilde{W}}-W, \tilde{\tilde{Q}}-Q)\|_{\dot{\mathcal{H}}^{\sigma}} \lesssim \epsilon^{2} t^{c \epsilon^{2}-\sigma}, \tag{7.3}
\end{equation*}
$$

and an even better bound at high frequency,

$$
\begin{equation*}
\|(\tilde{\tilde{W}}-W, \tilde{\tilde{Q}}-Q)\|_{\dot{\mathcal{H}}^{8} \cap \dot{\mathcal{H}}^{\frac{1}{2}}} \lesssim \epsilon^{2} t^{c \epsilon^{2}+\sigma-\frac{1}{2}} . \tag{7.4}
\end{equation*}
$$

These are proved using Proposition 2.2. The weaker bound at low frequency is due to the fact that the $\dot{H}^{\sigma-\frac{1}{2}}$ bound is obtained by a Sobolev embedding from the corresponding $L^{p}$ type bound, which in turn requires combining an $L^{2}$ bound with an $L^{q}$ bound rather than with $L^{\infty}$.

Also, from the analysis of the normal form equation in Proposition 5.1 we obtain

$$
\begin{equation*}
\left\|\left(\tilde{\tilde{W}}_{t}+\tilde{\tilde{Q}}_{\alpha}, \tilde{\tilde{Q}}_{t}+i \tilde{\tilde{W}}_{\alpha \alpha}\right)\right\|_{\dot{\mathcal{H}}^{\sigma}} \lesssim \epsilon t^{-1} t^{c \epsilon^{2}} . \tag{7.5}
\end{equation*}
$$

On the other hand, applying the bounds for the linearized equation to $(w, q)=\mathbf{S}(W, Q)$, and combining with the above we have

$$
\begin{equation*}
\|(S W, S Q)\|_{\dot{\mathcal{H}}^{\sigma} \cap \dot{\mathcal{H}}^{1}} \lesssim \epsilon e^{c \epsilon^{2} t} . \tag{7.6}
\end{equation*}
$$

Combining the above bound with (17.1) we can switch to the normal form variables ( $\tilde{\tilde{W}}, \tilde{\tilde{Q}}$ ),

$$
\begin{equation*}
\|(S \tilde{W}, S \tilde{\tilde{Q}})\|_{\dot{\mathcal{H}}^{\sigma}+\dot{\mathcal{H}}^{0}} \lesssim \epsilon t^{c \epsilon^{2}} . \tag{7.7}
\end{equation*}
$$

Finally, we can eliminate the time derivative from the last two relations to arrive at

$$
\begin{equation*}
\left\|\left(t \tilde{\tilde{Q}}_{\alpha}-\frac{2}{3} \alpha \tilde{W}_{\alpha}, i t \tilde{\tilde{W}}_{\alpha \alpha}-\frac{2}{3} \alpha \tilde{\tilde{Q}}_{\alpha}\right)\right\|_{\dot{\mathcal{H}}^{\sigma}+\dot{\mathcal{H}}^{0}} \lesssim \epsilon t^{c \epsilon^{2}} \tag{7.8}
\end{equation*}
$$

Our pointwise bounds will be derived from (7.2) and (7.8). In order to state them we introduce the notations

$$
\left\langle\frac{t}{\alpha}\right\rangle=\frac{t}{|\alpha|+t^{\frac{2}{3}}}, \quad \omega(\alpha, t)=\min \left\{\left(\frac{t}{\alpha}\right)^{\frac{1}{2}},\left\langle\frac{t}{\alpha}\right\rangle^{-\frac{1}{2}}\right\} .
$$

Then our main result is as follows:
Proposition 7.1. Assume that $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ satisfy (7.2) and (7.8). Then we have the pointwise bounds:
a) For $\tilde{\tilde{W}}$ we have

$$
\begin{equation*}
|\tilde{\tilde{W}}| \lesssim \epsilon\left[\omega(\alpha, t) t^{-\frac{1}{2}}\right]^{1-2 \sigma} t^{c \epsilon^{2}} \tag{7.9}
\end{equation*}
$$

respectively

$$
\begin{equation*}
\left|D^{j+\frac{1}{2}} \tilde{\tilde{W}}\right|+\left|D^{j} \tilde{\tilde{Q}}\right| \lesssim \epsilon \omega(\alpha, t) t^{-\frac{1}{2}} t^{c \epsilon^{2}}, \quad j=0,1,2,3,4 . \tag{7.10}
\end{equation*}
$$

We remark that once we have these bounds, it is straightforward to return to ( $W, Q$ ):
Corollary 7.2. Suppose that (7.1) and (7.8) hold. Then we also have

$$
\begin{equation*}
|\tilde{\tilde{W}}-W| \lesssim\left[\omega(\alpha, t) t^{-\frac{1}{2}}\right]^{1-2 \sigma} t^{-\frac{1}{4}} \tag{7.11}
\end{equation*}
$$

respectively

$$
\begin{equation*}
\left|D^{j+\frac{1}{2}}(W-\tilde{\tilde{W}})\right|+\left|D^{j}(Q-\tilde{\tilde{Q}})\right| \lesssim \omega(\alpha, t) t^{-\frac{1}{2}} t^{-\frac{1}{4}}, \quad j=0,1,2,3,4 \tag{7.12}
\end{equation*}
$$

In particular the bounds in the above proposition apply to $(W, Q)$ as well. Also $R^{(j)}$ satisfies the same pointwise bounds as $Q^{(j-1)}$ for $j=0,1,2,3$.

The proof of the Corollary is routine, and is left for the reader (see also the similar argument in [20]). The improvement in the bounds for the difference comes from its bilinear and trilinear character.

One consequence of the above proposition and corollary is that in our main bootstrap argument it suffices to replace $(W, Q)$ by $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ in (1.21). It also remains to prove (1.21) in a restricted region of the form $\left\{t^{-\delta} \leq|\alpha| / t \leq t^{\delta}\right\}$, where $\delta$ is a small universal constant. This requires $\epsilon^{2} \ll \delta$.
Proof of Proposition 7.1. To keep the notations simple, for this proof we drop the $\epsilon \epsilon^{c \epsilon^{2}}$ factor, and also drop the double tilde notation.

Our hypothesis is stable with respect to frequency localizations, so we can study first the frequency localized problem and then add up the results. By scaling it suffices to consider $(W, Q)$ which are localized at frequency 1 . Then we have:
Lemma 7.3. Suppose that $(W, Q)$ are localized at frequency 1 and satisfy

$$
\left\|\left(t Q_{\alpha}-\frac{2}{3} \alpha W_{\alpha}, i t W_{\alpha \alpha}-\frac{2}{3} \alpha Q_{\alpha}\right)\right\|_{L^{2}} \lesssim 1, \quad\|(Q, W)\|_{L^{2}} \lesssim \delta \leq 1
$$

Then we have the pointwise bound

$$
|W|+|Q| \lesssim \delta^{\frac{1}{2}} t^{-\frac{1}{2}}, \quad|\alpha| \approx t \geq \delta^{-1}
$$

respectively

$$
|W|+|Q| \lesssim \min \left\{\delta,(t+|\alpha|)^{-1}\right\}, \quad \text { otherwise. }
$$

Proof. We rewrite the relation in the Lemma as

$$
\left\|\left(t \tilde{Q}-\frac{2}{3} \alpha \tilde{W}, i t \tilde{W}_{\alpha}-\frac{2}{3} \alpha \tilde{Q}\right)\right\|_{L^{2}} \lesssim 1
$$

We consider several cases:
(i) $|t| \lesssim \delta^{-1}$. Then we can eliminate the $t$ factor from the first relation to obtain

$$
\|\alpha(W, Q)\|_{L^{2}} \lesssim 1,\|(W, Q)\|_{L^{2}} \lesssim \delta
$$

which easily yields the pointwise bound

$$
|(W, Q)| \lesssim \min \left\{\delta,|\alpha|^{-1}\right\}
$$

(ii) $t>\delta^{-1},|\alpha| \gg t$. There the operator $L$ is elliptic, and we obtain the elliptic bound

$$
\left\|\chi_{\alpha \gg t} \alpha(W, Q)\right\|_{L^{2}} \lesssim 1,
$$

which leads to the pointwise bound

$$
|(W, Q)| \leq|\alpha|^{-1}
$$

(iii) $t>\delta^{-1}, \alpha \ll t$. There the operator $L$ is again elliptic, and we obtain the elliptic bound

$$
\left\|\chi_{\alpha \ll t}(W, Q)\right\|_{L^{2}} \lesssim t^{-1}
$$

which leads to the pointwise bound

$$
|(W, Q)| \leq t^{-1}
$$

(iv) $t>\delta^{-1},|\alpha| \approx t$. There we combine the two terms in $L$ to obtain

$$
\left\|\left(\partial_{\alpha}+i \frac{4 \alpha^{2}}{9 t^{2}}\right) \chi_{|\alpha| \approx t} W\right\|_{L^{2}} \lesssim t^{-1}, \quad\|W\|_{L^{2}} \lesssim \delta
$$

By Cauchy-Schwarz inequality this yields

$$
|W| \lesssim \delta^{\frac{1}{2}} t^{-\frac{1}{2}}
$$

and the similar bound for $Q$ immediately follows.
Rescaling the above result, we obtain the following
Corollary 7.4. Suppose that $(W, Q)$ are localized at frequency $\lambda$ with

$$
\left\|\left(t Q_{\alpha}-\frac{2}{3} \alpha W_{\alpha}, i t W_{\alpha \alpha}-\frac{2}{3} \alpha Q_{\alpha}\right)\right\|_{\dot{\mathcal{H}}_{0}} \lesssim 1, \quad\|(W, Q)\|_{\dot{\mathcal{H}}_{0}} \lesssim \delta
$$

Then the hyperbolic (non elliptic) region is

$$
|\alpha| \approx \lambda^{\frac{1}{2}} t, \quad t>\delta^{-1} \lambda^{-\frac{3}{2}}
$$

and there we have the bound for the hyperbolic component $\left(W_{h y p}, Q_{h y p}\right)=\chi_{|\alpha| \approx \lambda^{\frac{1}{2}} t}(W, Q)$ :

$$
\begin{equation*}
\left|W_{h y p}\right| \lesssim \delta^{\frac{1}{2}}|\alpha|^{-\frac{1}{2}}, \quad\left|Q_{h y p}\right| \lesssim \delta^{\frac{1}{2}}|\alpha|^{\frac{1}{2}} t^{-1} \tag{7.13}
\end{equation*}
$$

Elsewhere we have a better bound for the remaining elliptic component, both pointwise

$$
\begin{equation*}
\left|W_{\text {ell }}\right| \lesssim \min \left\{\delta \lambda^{\frac{1}{2}}, \frac{1}{\left(|\alpha|+\lambda^{\frac{1}{2}} t\right) \lambda^{\frac{1}{2}}}\right\}, \quad\left|Q_{44}\right| \lesssim \min \left\{\delta \lambda, \frac{1}{\left(|\alpha|+\lambda^{\frac{1}{2}} t\right)}\right\} \tag{7.14}
\end{equation*}
$$

and in $L^{2}$ :

$$
\begin{equation*}
\left\|\left(\delta^{-1}+\lambda\left(\lambda^{\frac{1}{2}} t+|\alpha|\right)\right)\left(W_{\text {ell }}, \lambda^{-\frac{1}{2}} Q_{\text {ell }}\right)\right\| \lesssim 1 . \tag{7.15}
\end{equation*}
$$

To obtain the conclusion of the Proposition we consider a dyadic decomposition with respect to the dyadic frequency parameter $\lambda$,

$$
(W, Q)=\sum_{\lambda \text { dyadic }}\left(W_{\lambda}, Q_{\lambda}\right),
$$

and then a further decomposition into hyperbolic and elliptic components,

$$
\left(W_{\text {hyp }}, Q_{\text {hyp }}\right)=\sum_{\lambda \text { dyadic }}\left(W_{\lambda, \text { hyp }}, Q_{\lambda, \text { hyp }}\right) .
$$

Then the conclusion of the proposition is obtained by doing dyadic summation of the bounds in the above corollary with respect to the dyadic frequency $\lambda$.

First we consider frequencies $\lambda$ which are less than 1 . Then we do the summation with $\delta=1$ and an extra $\lambda^{-\sigma}$ factor. The non-elliptic regions are essentially disjoint, and span the range $t^{\frac{2}{3}} \lesssim|\alpha| \lesssim t$. There we get

$$
\begin{equation*}
\left|W_{<1, h y p}\right| \lesssim t^{-\frac{1}{2}}\left\langle\frac{t}{\alpha}\right\rangle^{\frac{1}{2}+\sigma} \tag{7.16}
\end{equation*}
$$

and also

$$
\begin{equation*}
\left|D^{\frac{1}{2}} W_{<1, h y p}\right|+\left|Q_{<1, h y p}\right| \lesssim t^{-\frac{1}{2}}\left\langle\frac{t}{\alpha}\right\rangle^{-\frac{1}{2}+\sigma} \tag{7.17}
\end{equation*}
$$

which only gets better for higher derivatives. In the elliptic case we get the sum

$$
\left|W_{\text {elliptic }}\right| \lesssim \sum_{\lambda<1} \lambda^{-\sigma} \min \left\{\lambda^{\frac{1}{2}}, \frac{1}{\left(|\alpha|+\lambda^{\frac{1}{2}} t\right) \lambda^{\frac{1}{2}}}\right\} .
$$

The sum is comparable to the maximum of the summands, which is attained at the balance point,

$$
\lambda\left(|\alpha|+\lambda^{\frac{1}{2}} t\right)=1
$$

That gives $\lambda=\left(|\alpha|+t^{\frac{2}{3}}\right)^{-1}$, therefore we obtain the pointwise bound

$$
\begin{equation*}
\left|W_{<1, e l l}\right| \lesssim\left(|\alpha|+t^{\frac{2}{3}}\right)^{\sigma-\frac{1}{2}} . \tag{7.18}
\end{equation*}
$$

The case of $Q$ or $D^{\frac{1}{2}} W$ is more favorable. We get the same threshold for $\lambda$ if $|\alpha|<t$, but the bound we get there is

$$
\begin{equation*}
\left|D^{\frac{1}{2}} W_{<1, e l l}\right|+\left|Q_{<1, e l l}\right| \lesssim t^{-1}\left\langle\frac{t}{\alpha}\right\rangle^{1+\sigma} \tag{7.19}
\end{equation*}
$$

while for $|\alpha|>t$ we simply get $|\alpha|^{-1}$. Both of these are better than needed. The bounds for higher derivatives of $W$ and $Q$ are better.

In a similar manner we have the $L^{2}$ bound

$$
\begin{equation*}
t\left\|D^{\sigma+2} W_{<1, e l l}\right\|_{L^{2}}+\left\|\alpha D^{\sigma+1} W_{<1, e l l}\right\|_{L^{2}}+\left\|D^{\sigma} W_{<1, e l l}\right\|_{L^{2}} \lesssim 1, \tag{7.20}
\end{equation*}
$$

and similarly for $D^{-\frac{1}{2}} Q_{<1, e l l}$. In effect the previous pointwise bounds follow by Bernstein's inequality from the $L^{2}$ bounds.

It remains to consider higher frequencies. There we work with the $L^{2}$ bound but set $\delta=\lambda^{-9}$. Thus we obtain a very good bound for the hyperbolic part,

$$
\begin{equation*}
\left|D^{4+\frac{1}{2}} W_{>1, h y p}\right|+\left|D^{4} Q_{>1, \text { hyp }}\right| \lesssim t^{-\frac{1}{2}}\left(\frac{t}{\alpha}\right)^{10}, \quad t>\alpha \tag{7.21}
\end{equation*}
$$

which suffices.
For the elliptic part we have the bound

$$
\begin{equation*}
\left|D^{3+\frac{1}{2}} W_{>1, e l l}\right|+\left|D^{3} Q_{>1, e l l}\right| \lesssim \sum_{\lambda>1} \lambda^{-3} \min \left\{\lambda^{\frac{1}{2}}, \frac{1}{\left(|\alpha|+\lambda^{\frac{1}{2}} t\right) \lambda^{\frac{1}{2}}}\right\} \lesssim(|\alpha|+t)^{-1} \tag{7.22}
\end{equation*}
$$

which yields the $\lambda=1$ value, and is no worse than the low frequency case. We also have the $L^{2}$ bound

$$
\begin{equation*}
\left\|t D^{2} W_{>1, e l l}\right\|_{L^{2}}+\left\|\alpha D W_{>1, e l l}\right\|_{L^{2}}+\left\|D^{6} W_{>1, e l l}\right\|_{L^{2}} \lesssim 1 \tag{7.23}
\end{equation*}
$$

## 8. The wave packet method and global pointwise bounds

In order to establish the global pointwise decay estimates we use the method of testing by wave packets, first introduced in paper [23] in the context of the one dimensional cubic NLS equation, and later used in [22] in the context of the two dimensional gravitational water waves.

Our starting point for the analysis is the same as in the previous section, namely the estimates (7.1)-(7.8). Consequently, we can also use the conclusion of the previous section, namely the bounds (7.9)-(7.12). For some portion of the arguments, we will also rely on the decomposition of $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ into elliptic and hyperbolic components, arising in the proof of Proposition 7.1 .

We succinctly revisit some details of the wave packet method; we pick a ray $\{\alpha=v t\}$ and establish decay along this ray by testing with a wave packet moving along the ray. A wave packet is an approximate solution to the linear system (3.1), with $O(1 / t)$ errors.

To motivate the definition of this packet we recall some useful facts. In view of the dispersion relation $\tau= \pm|\xi|^{\frac{3}{2}}$, a ray with velocity $v$ is associated with waves which have spatial frequency

$$
\xi_{v}=-\frac{4}{9} v^{2} .
$$

Secondly, for waves with initial data localized at the origin, the spatial frequency corresponding with a position $(\alpha, t)$ is

$$
\xi(\alpha, t)=-\frac{4}{9} \frac{\alpha^{2}}{t^{2}}
$$

This is associated with the phase function

$$
\phi(t, \alpha)=-\frac{4}{27} \frac{\alpha^{3}}{t^{2}} .
$$

Then our wave packets will be combinations of functions of the form
where $\chi$ is a smooth compactly supported bump function with integral one

$$
\begin{equation*}
\int \chi(y) d y=1 \tag{8.1}
\end{equation*}
$$

Our packets are localized around the ray $\{\alpha=v t\}$ on the scale $\delta \alpha=t^{\frac{1}{2}} v^{-\frac{1}{2}}$. We further remark that there is a threshold $v \approx t$ above which $\phi$ is essentially zero, and the above considerations are no longer relevant. We confine our analysis to the region where $\phi$ is strongly oscillatory,

$$
|v| \gg t^{-\frac{1}{6}}
$$

The power $\frac{1}{6}$ here is somewhat arbitrary, any choice less than $\frac{1}{3}$ would do. Under this assumption, the function $\mathbf{u}$ is strongly localized at frequency $\xi_{v}$.

We apply the method of testing by wave packets which we successfully used for the water wave equation in [22], and for the cubic NLS in [23]. Due the fact that we are dealing with a system, and we need to choose the two components to match. Our system is simple enough, so is suffices to first choose the $Q$ component and then use the first of the two linear equations in (3.1) to match $W$,

$$
(\mathbf{w}, \mathbf{q})=-\frac{27 i}{8 v^{2}}\left(-\mathbf{u}_{\alpha}, \mathbf{u}_{t}\right)
$$

Then we have

$$
\left\{\begin{array}{l}
\mathbf{w}=\frac{3 \alpha^{2}}{2 t^{2} v^{3}} \mathbf{u}+\frac{27 i}{8 v^{2}} \frac{1}{t^{\frac{1}{2}} v^{-1}} \chi^{\prime}\left(\frac{\alpha-v t}{t^{\frac{1}{2}} v^{-\frac{1}{2}}}\right) e^{i \phi}=\frac{3}{2 v} \mathbf{u}+O\left(v^{-\frac{1}{2}} t^{-\frac{1}{2}}\right) e^{i \phi}  \tag{8.2}\\
\mathbf{q}=\frac{\alpha^{3}}{t^{3} v^{3}} \mathbf{u}+\frac{27 i}{8 v^{2}} \frac{\alpha+v t}{2 t^{\frac{3}{2}} v^{-1}} \chi^{\prime}\left(\frac{\alpha-v t}{t^{\frac{1}{2}} v^{-\frac{1}{2}}}\right) e^{i \phi}=\mathbf{u}+O\left(v^{\frac{1}{2}} t^{-\frac{1}{2}}\right) e^{i \phi} .
\end{array}\right.
$$

The remainder terms on each of the two lines above are also bump functions on the $t^{\frac{1}{2}} v^{-\frac{1}{2}}$ scale, and are better by a $v^{\frac{1}{2}} t^{-\frac{1}{2}}$ factor. Because of this, they will play a negligible role in most of our analysis. However, we cannot discard them as they are crucial in improving the error in the second linear equation in (3.1), which is given by

$$
\begin{equation*}
\mathbf{k}:=\partial_{t} \mathbf{q}+i \partial_{\alpha}^{2} \mathbf{w}=-\frac{27 i}{8 v^{2}}\left(\partial_{t}^{2}-i \partial_{\alpha}^{3}\right) \mathbf{u} \tag{8.3}
\end{equation*}
$$

Indeed, computing the error in (8.3) we obtain

$$
\begin{equation*}
\mathbf{k}=e^{i \phi} \partial_{\alpha}\left[\frac{v^{\frac{1}{2}}(\alpha-v t)}{t} \chi-\frac{9 i}{8 t^{\frac{1}{2}}} \chi^{\prime}\right]+O\left(t^{-\frac{3}{2}}\right) \tag{8.4}
\end{equation*}
$$

The first term is the leading one, and, as expected, has size $t^{-1}$ times the size of $\mathbf{q}$; the remaining terms are better than $t^{-1}$ by an additional factor of $t^{-\frac{1}{2}}$ which shows that the choice of a such wave packet is a reasonable approximate solution for the linear system. Precisely, as in [22], our test packets ( $\mathbf{w}, \mathbf{q}$ ) are good approximate solutions for the linear system associated to our problem only on the dyadic time scale $\delta t \leq t$.

The outcome of testing the normal form solutions to the water wave system with the wave packet $(\mathbf{w}, \mathbf{q})$ is the scalar complex valued function $\gamma(t, v)$, defined in the region $\left\{|v| \leq t^{\delta}\right\}$, where $\delta \ll 1$ :

$$
\gamma(t, v)=\frac{1}{2}\langle(\tilde{\tilde{W}}, \tilde{\tilde{Q}}),(\mathbf{w}, \mathbf{q})\rangle_{\dot{H}^{\frac{1}{2}} \times L^{2}},
$$

which we will use as a good measure of the size of $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ along our chosen ray. Here it is important that we use the complex pairing in the inner product.

Now we have two tasks. Firstly, we need to show that $\gamma$ is a good representation of the pointwise size of $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ and their derivatives:
Proposition 8.1. Assume that (7.2) and (7.8) hold. Then in $\Omega:=\left\{t^{-\delta} \leq \frac{|\alpha|}{t} \leq t^{\delta}\right\}$ we have the following bounds for $\gamma$ :

$$
\begin{equation*}
\left\|\left(1+v^{2}\right)^{8} \gamma\right\|_{L_{v}^{2}}+\left\|v\left(1+v^{2}\right)^{-\frac{1}{2}} \partial_{v} \gamma\right\|_{L_{v}^{2}}+\left\|v^{\frac{1}{2}}\left(1+v^{2}\right)^{\frac{7}{2}} \gamma\right\|_{L^{\infty}} \lesssim \epsilon t^{C_{*}^{2} \epsilon^{2}} \tag{8.5}
\end{equation*}
$$

as well as the approximation bounds for $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ and their derivatives:

$$
\begin{equation*}
\left(|D|^{s+\frac{1}{2}} \tilde{\tilde{W}},|D|^{s} \tilde{\tilde{Q}}\right)(t, v t)=\left|\xi_{v}\right|^{s} t^{-\frac{1}{2}} e^{i \phi(t, v t)} \gamma(t, v)(\operatorname{sgn} v, 1)+\operatorname{err}_{s} \tag{8.6}
\end{equation*}
$$

where

$$
\begin{equation*}
\left\|\left(1+v^{2}\right)^{4-s} \operatorname{err}_{s}\right\|_{L_{v}^{2}}+\left\|\left(1+v^{2}\right)^{4-s} \operatorname{err}_{s}\right\|_{L^{\infty}} \lesssim \epsilon t^{-\frac{5}{8}+C_{*}^{2} \epsilon^{2}}, \quad 0 \leq s \leq 4 \tag{8.7}
\end{equation*}
$$

By virtue of the difference bounds (7.12), the estimates (8.6)-(8.7) also hold with ( $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ replaced by $(W, Q)$.

Secondly, we need to show that $\gamma$ stays bounded, which we do by establishing an asymptotic differential equation for it:
Proposition 8.2. Assume that the bounds (7.1)-(7.8) hold. Then within the set $\Omega$ the function $\gamma$ solves an asymptotic ode of the form

$$
\begin{equation*}
\dot{\gamma}=-\frac{8 i v^{5}}{81 t} \gamma|\gamma|^{2}+e r r_{\gamma} \tag{8.8}
\end{equation*}
$$

where err ${ }_{\gamma}$ satisfies the $L^{2}$ and $L^{\infty}$ bounds

$$
\begin{equation*}
\left\|\left(1+v^{2}\right)^{4} \operatorname{err}_{\gamma}\right\|_{L^{2}}+\left\|\left(1+v^{2}\right)^{4} \operatorname{err}_{\gamma}\right\|_{L^{\infty}} \lesssim \epsilon t^{-\frac{19}{18}} \tag{8.9}
\end{equation*}
$$

We now use the two propositions to conclude the proof of (1.21), and thus the proof of Theorem 4. By virtue of (8.6) and (8.7), in order to prove (1.21) it suffices to establish its analogue for $\gamma$, namely

$$
\begin{equation*}
|\gamma(t, v)| \lesssim \epsilon\left(1+v^{2}\right)^{-4} \quad \text { in } \Omega \tag{8.10}
\end{equation*}
$$

On the other hand, from (7.10), we directly obtain

$$
\begin{equation*}
|\gamma(t, v)| \lesssim \epsilon\left(1+v^{2}\right)^{-4} \omega(v, t) t^{C_{*}^{2} \epsilon} \text { in } \Omega \tag{8.11}
\end{equation*}
$$

Our goal now is to use the ode (8.8) in order to pass from the bound (8.11) to (8.10) along rays $\alpha=v t$. We consider three cases for $v$ :
(i) Suppose first that $v \approx 1$, i.e., $|\alpha| \approx t$. Then we initially have

$$
|\gamma(t)| \lesssim \epsilon, \quad t \approx 1
$$

Integrating (8.8) we conclude that

$$
|\gamma(t)| \lesssim \epsilon, \quad t \geq 1
$$

and then (8.10) follows.
(ii) Assume now that $v \ll 1$, i.e., $|\alpha| \ll t$. Then, as $t$ increases, the ray $\alpha=v t$ enters $\Omega$ at some point $t_{0}$ with $v \approx t_{0}^{-\frac{1}{9}}$. Then by (8.11), if $\epsilon$ is small enough then we obtain

$$
\left|\gamma\left(t_{0}, v\right)\right| \lesssim \epsilon v^{\frac{1}{2}} t_{0}^{C_{*}^{2} \epsilon} \lesssim \epsilon .
$$

We use this to initialize $\gamma$. For larger $t$ we use (8.8) to conclude that

$$
|\gamma(t)| \lesssim \epsilon+\int_{t_{0}}^{\infty} \epsilon s^{-\frac{19}{18}+C \epsilon^{2}} d s \approx \epsilon\left(1+t_{0}^{-\frac{1}{18}+C_{*}^{2} \epsilon^{2}}\right) \lesssim \epsilon, \quad t>t_{0}
$$

Then (8.10) follows.
(iii) Finally, consider the case $v \gg 1$, i.e., $|\alpha| \gg t$. Again, as $t$ increases, the ray $\alpha=v t$ enters $\Omega$ at some point $t_{0}$ with $v \approx t_{0}^{\frac{1}{9}}$, therefore by (8.11) we obtain

$$
\left|\gamma\left(t_{0}, v\right)\right| \lesssim \epsilon\left(1+v^{2}\right)^{-4} \omega t_{0}^{C_{*}^{2} \epsilon} \lesssim \epsilon\left(1+v^{2}\right)^{-4} .
$$

We use this to initialize $\gamma$. For larger $t$ we use (8.8) to conclude that

$$
|\gamma(t)| \lesssim\left(1+v^{2}\right)^{-4}\left(\epsilon+\int_{t_{0}}^{\infty} \epsilon s^{-\frac{19}{18}+C_{*}^{2} \epsilon^{2}}\right) \lesssim \epsilon\left(1+v^{2}\right)^{-4}, \quad t>t_{0}
$$

Then (8.10) again follows.
The remainder of the paper is devoted to the proof of the two propositions above.
Proof of Proposition 8.1. Here we prove Proposition 8.1, using the estimates (7.16)-(7.23) in the proof of Proposition 7.1. We write $\gamma$ as

$$
\gamma=\frac{1}{2} \int-i \tilde{\tilde{W}}_{\alpha} \overline{\mathbf{w}}+\tilde{\tilde{Q}} \overline{\mathbf{q}} d \alpha .
$$

The two terms in the integral are considered separately in the proof of (8.5), and the exact form of ( $\mathbf{w}, \mathbf{q}$ ) is not important. Further, for the purpose of proving 8.7) we can simplify somewhat the expression of $\gamma$. The lower order terms in ( $\mathbf{w}, \mathbf{q}$ ) in (8.2) are better by a factor of $v t^{-\frac{1}{2}}$, therefore we can readily replace $(\mathbf{w}, \mathbf{q})$ by their leading part, modulo errors which satisfy bounds which are $v t^{-\frac{1}{2}}$ better than (8.5)-(8.7). In view of these considerations, it suffices to prove Proposition 8.1 with $\gamma$ redefined as

$$
\begin{equation*}
\gamma(t, v)=\frac{1}{2} \int\left(-\frac{3 i}{2 v} \tilde{W}_{\alpha}+\tilde{\tilde{Q}}\right) \overline{\mathbf{u}} d \alpha \tag{8.12}
\end{equation*}
$$

We split $(\tilde{\tilde{W}}, \tilde{\tilde{Q}})$ into hyperbolic and elliptic components, as in the proof of Proposition 7.1. The elliptic components which are spatially localized near $\alpha=v t$ have frequencies away from $v^{2}$, therefore, given the localization of $\mathbf{u}$, we have

$$
\int\left(-\frac{3 i}{2 v} \tilde{\tilde{W}}_{\text {ell }, \alpha}+\tilde{\tilde{Q}}_{\text {ell }}\right) \overline{\mathbf{u}} d \alpha=O\left(t^{-N}\right) .
$$

It remains to consider the contributions from the hyperbolic components

$$
\left(\tilde{\tilde{W}}_{\text {hyp }}, \tilde{\tilde{Q}}_{\text {hyp }}\right)=\sum_{\lambda \text { dyadic }}\left(\tilde{\tilde{W}}_{\lambda, \text { hyp }}, \tilde{\tilde{Q}}_{\lambda, \text { hyp }}\right) .
$$

This is a diagonal sum in that each the terms are supported in essentially disjoint dyadic regions $\lambda \approx v^{2}$. Hence, modulo $t^{-N}$ errors, it suffices to fix the dyadic frequency $\lambda$, and
restrict $\alpha$ to the region $\alpha^{2} / t^{2} \approx \lambda$, which corresponds to $v^{2} \approx \lambda$. We note that the $L^{2}$ square summability with respect to $\lambda$ in (7.2), (7.8) yields the corresponding summation with respect to dyadic spatial regions in the proposition.

For $\left(\tilde{\tilde{W}}_{\lambda, \text { hyp }}, \tilde{\tilde{Q}}_{\lambda, \text { hyp }}\right)$ we have the following bounds which are consequences of (7.2), (7.8):

$$
\begin{gather*}
\left\|\left(v \tilde{\tilde{W}}_{\lambda, h y p}, \tilde{\tilde{Q}}_{\lambda, h y p}\right)\right\|_{L^{2}} \lesssim\left(1+v^{2}\right)^{-5} \epsilon t^{C \epsilon^{2}}  \tag{8.13}\\
\left\|\left(v\left(\tilde{\tilde{Q}}_{\lambda, h y p}-\frac{2 \alpha}{3 t} \tilde{\tilde{W}}_{\lambda, h y p}\right), i \tilde{\tilde{W}}_{\lambda, h y p, \alpha}-\frac{2 \alpha}{3 t} \tilde{\tilde{Q}}_{\lambda, h y p}\right)\right\|_{L^{2}} \lesssim \frac{\left(1+v^{2}\right)^{\frac{1}{2}}}{t v^{2}} \epsilon t^{C \epsilon^{2}} . \tag{8.14}
\end{gather*}
$$

Combining the two components in the last equation and using again the frequency localization, we obtain also

$$
\begin{equation*}
\left\|L\left(v \tilde{\tilde{W}}_{\lambda, h y p}, \tilde{\tilde{Q}}_{\lambda, h y p}\right)\right\|_{L^{2}} \lesssim \frac{\left(1+v^{2}\right)^{\frac{1}{2}}}{t v} \epsilon t^{C \epsilon^{2}} \tag{8.15}
\end{equation*}
$$

where we recall that

$$
L=\partial_{\alpha}-i \frac{4 \alpha^{2}}{9 t^{2}}
$$

is the operator which cancels the phase $e^{i \phi}$.
Now it is very easy to prove (8.5). The first bound (8.13) leads immediately to the first $L^{2}$ estimate in (8.5), while (8.15) yields the second $L^{2}$ estimate in (8.5). The latter fact is easily seen by integration by parts, after noting that $t L \mathbf{u}-\partial_{v} \mathbf{u}$ has the same form and size as $\mathbf{u}$. Finally, the pointwise bound in (8.5) follows directly by Cauchy-Schwarz inequality from the two $L^{2}$ bounds.

It remains to prove the error bound in (8.7). For that we first reduce the problem to either $\tilde{\tilde{W}}$ or $\tilde{\tilde{Q}}$. For that we use the two relations in (8.14) to conclude that $\gamma$ as defined in (8.12) is given by

$$
\gamma=\int \tilde{\tilde{Q}}_{\lambda, h y p} \overline{\mathbf{u}} d \alpha+O\left(t^{-\frac{1}{4}}\right)=\int-\frac{2 i}{3 v} \tilde{\tilde{W}}_{\lambda, h y p} \overline{\mathbf{u}} d \alpha+O\left(t^{-\frac{1}{4}}\right)
$$

We first prove the $\tilde{\tilde{Q}}_{\lambda, h y p}$ component of the bound (8.7) for $s=0$. For this it suffices to estimate the difference

$$
\operatorname{err}_{0}=e^{-i \phi(t, v t)} \tilde{\tilde{Q}}_{\lambda}(t, v t)-t^{-\frac{1}{2}} \int \tilde{\tilde{Q}}_{\lambda}(t, \alpha) \overline{\mathbf{u}}(\alpha) d \alpha
$$

and show that

$$
\begin{equation*}
\left.\left.\left\|\operatorname{err}_{0}\right\|_{L^{2}} \lesssim t^{\frac{1}{2}} v^{-\frac{1}{2}} \| L \tilde{\tilde{Q}}_{\lambda}(t, v t)\right)\left\|_{L^{2}}, \quad\right\| \operatorname{err}_{0}\left\|_{L^{\infty}} \lesssim t^{\frac{1}{4}} v^{-\frac{1}{4}}\right\| L \tilde{\tilde{Q}}_{\lambda}(t, v t)\right) \|_{L^{2}} \tag{8.16}
\end{equation*}
$$

Denoting $\left.u(t, \alpha)=e^{-i \phi(t, \alpha)} \tilde{\tilde{Q}}_{\lambda}(t, \alpha)\right)$ so that $u_{\alpha}=e^{-i \phi(t, \alpha)} L \tilde{\tilde{Q}}$, we rewrite the above difference as

$$
\operatorname{err}_{0}=t^{-\frac{1}{2}} \int(u(t, v t)-u(t, \alpha)) \overline{\mathbf{u}(t, \alpha) e^{-i \phi(t, \alpha)}} d \alpha
$$

Then the bound (8.16) immediately follows by writing the first difference in terms of the derivative of $u$ (see also the more detailed computations in [22,23]). To deal with with other values of $s$ one applies (8.16) to $D^{s} \tilde{\tilde{Q}}$, and computes

$$
\int|D|^{s} \tilde{\tilde{Q}} \overline{\mathbf{u}} d \alpha=\int_{50} \tilde{\tilde{Q}} \overline{|D|^{s} \mathbf{u}} d \alpha
$$

observing that the difference

$$
|D|^{s} \mathbf{u}-\left|\xi_{v}\right|^{s} \mathbf{u}
$$

has the same form as $\mathbf{u}$ but has size better by a $t^{-\frac{1}{2}} v^{\frac{1}{2}}$ factor. The argument for $\tilde{\tilde{W}}$ is entirely similar. Again, we refer the reader to the more detailed computations in [23].

Proof of Proposition 8.2. In view of the $\dot{\mathcal{H}}^{\frac{1}{2}}$ energy conservation for the linear system (3.1), we directly obtain the relation

$$
\dot{\gamma}(t)=\int i \tilde{\tilde{G}} \overline{\mathbf{w}}_{\alpha}+\tilde{\tilde{K}} \overline{\mathbf{q}}+\tilde{\tilde{Q}} \overline{\mathbf{k}} d \alpha .
$$

We successively consider all terms on the right. With the exception of a single term, namely the resonant part of $G$, see below, all contributions will be placed into the error term.
A. The contribution of $\overline{\mathrm{k}}$. This is

$$
I_{1}=\int \tilde{\tilde{Q}} e^{-i \phi}\left(\partial_{\alpha}\left[\frac{v^{\frac{1}{2}}(\alpha-v t)}{t} \chi+\frac{9 i}{8 t^{\frac{1}{2}}} \chi^{\prime}\right]+O\left(t^{-\frac{3}{2}}\right)\right) d \alpha
$$

The contribution of the $O\left(t^{-\frac{3}{2}}\right)$ error term is estimated directly by Cauchy-Schwarz inequality. Also, by (8.6) we can replace $\tilde{\tilde{Q}}$ in terms of $\gamma$, and the contribution of the error $\tilde{\tilde{Q}}-t^{-\frac{1}{2}} e^{i \phi} \gamma(t, v)$ is directly estimated in both $L^{2}$ and $L^{\infty}$ via (8.7). The contribution of $\gamma$, on the other hand, is written using integration by parts as

$$
\tilde{I}_{1}=t^{-\frac{1}{2}} \int-\gamma_{\alpha}\left[\frac{v^{\frac{1}{2}}(\alpha-v t)}{t} \chi+\frac{9 i}{8 t^{\frac{1}{2}}} \chi^{\prime}\right] d \alpha
$$

Now we can easily bound the last expression using (8.5).
B. The contributions of $\tilde{\tilde{G}}, \tilde{\tilde{K}}$. The quartic terms admit the better $L^{2}$ bound in (5.5), so their contributions are estimated by Cauchy-Schwarz inequality. It remains to consider their cubic parts, which are described in (5.12).

The analysis of the cubic terms will be unnecessarily long if one wants to list all the terms. Instead we adopt the same strategy as in [22] and classify them in resonant, non-resonant and null terms. For this we need the following heuristic analysis:
(i) in the physical space waves at frequency $\xi$ move with velocity $\pm \frac{3}{2}|\xi|^{\frac{1}{2}}$. Since our data is localized near the origin, it follows that the bulk of the solution at $(\alpha, t)$ is at space-time frequency $(\xi, \tau)=\left(-\frac{4 \alpha^{2}}{9 t^{2}}, \frac{2 \alpha}{3 t}\right)$. Thus the worst cubic interactions are those of waves with equal frequency.
(ii) In the frequency space, trilinear interactions of equal frequency waves $(\xi, \pm \sqrt{|\xi|})$ (with $\xi<0$ ) can only lead back to the characteristic set if exactly one complex conjugation is present.
This leads to the following classification of the cubic terms:
A. Non-resonant trilinear terms: these are either (A1) terms with no complex conjugates, or (A2) terms with two complex conjugates.
B. Resonant trilinear terms: terms with exactly one conjugation. As in [22] for such terms one may further define a notion of principal symbol, which is the leading coefficient in the expression obtained by substituting the factors in the trilinear form by the expressions in (8.6) 3. Thus one can isolate a linear subspace of resonant terms for which this symbol vanishes, which we call null terms. Hence on the full class of resonant trilinear terms we can further define an equivalence relation, modulo null terms.
Based on this, we seek to classify the terms in $\left(\tilde{\tilde{G}}^{3}(W, Q), \tilde{\tilde{K}}^{3}(W, Q)\right)$. To avoid cumbersome notations, we first classify the terms in $\left(\tilde{G}^{3}(W, Q), \tilde{K}^{3}(W, Q)\right)$. As we will see, the additional terms in the difference of the two do not contribute at all to the asymptotic equation, but only to the error term.

We begin our discussion with the quadratic terms in $G^{(2)}$ and $K^{(2)} . G^{(2)}$ contains only mixed terms, while $K^{(2)}$ contains both holomorphic and mixed terms. We decompose the latter into a holomorphic and a mixed part,

$$
K^{(2)}=K^{(2), h}+K^{(2), a} .
$$

The holomorphic part is

$$
K^{(2), h}=-Q_{\alpha}^{2}+\frac{3 i}{2} W_{\alpha \alpha} W_{\alpha}
$$

while the mixed parts are given by

$$
\left\{\begin{array}{l}
G^{(2)}=P\left[Q_{\alpha} \bar{W}_{\alpha}-\bar{Q}_{\alpha} W_{\alpha}\right] \\
K^{(2), a}=P\left[-\left|Q_{\alpha}\right|^{2}+\frac{i}{2}\left(W_{\alpha \alpha} \bar{W}_{\alpha}-\bar{W}_{\alpha \alpha} W_{\alpha}\right)\right] .
\end{array}\right.
$$

Conveniently, both of these terms are null terms, i.e., they vanish when we substitute all factors with their $\gamma$ approximations in (8.6). Thus, all their contributions to $\tilde{G}^{(3)}$ and $\tilde{K}^{(3)}$ are also classified as null. The expression $G^{(2)}$ also appears in $\left(G^{(3)}, K^{(3)}\right)$, so those contributions are also null. The remaining terms in $\left(G^{(3)}, K^{(3)}\right)$ are easy to classify.

It remains to consider the output of $K^{(2), h}$ in the bilinear expressions in (3.9). Most of those are resonant, so in the final analysis we are left with $C^{a}\left(K^{(2), h}, \bar{Q}\right)$ and $D^{a}\left(K^{(2), h}, \bar{W}\right)$. We consider the first of these expressions. Here the resonant interaction occurs when all three frequencies are equal, i.e., when the frequency of $K^{(2), h}$ is double the frequency of $Q$. Thus, out of the symbol $C^{a}(\xi, \eta)$ we can extract a leading, resonant term which has symbol $C^{a}(\xi, \xi)=-\frac{3 i}{8}$. Similarly, out of the symbol $D^{a}(\xi, \eta)$ we can extract a leading, resonant term which has symbol $C^{a}(\xi, \xi)=-\frac{7 i \xi}{8}$.

Based on this discussion, we decompose

$$
\left\{\begin{array}{l}
\tilde{G}^{(3)}=\tilde{G}_{r}^{(3)}+\tilde{G}_{n r}^{(3)}+\tilde{G}_{n u l l}^{(3)} \\
\tilde{K}^{(3)}=\tilde{K}_{r}^{(3)}+\tilde{K}_{n r}^{(3)}+\tilde{K}_{n u l l}^{(3)},
\end{array}\right.
$$

[^3]where
\[

\left\{$$
\begin{aligned}
\tilde{G}_{r}^{(3)}= & -\frac{3 i}{8} K^{(2), h} \bar{Q}, \\
\tilde{G}_{n r}^{(3)}= & 2 C^{h}\left(K^{(2), h}, Q\right)+C^{a}\left(Q, \bar{K}^{(2), h}\right)+B^{a}\left(G^{(2)}, \bar{W}\right)-Q_{\alpha} \bar{W}_{\alpha}{ }^{2}-\bar{Q}_{\alpha}\left|W_{\alpha}\right|^{2}, \\
\tilde{G}_{n u l l}^{(3)}= & 2 C^{h}\left(K^{(2), a}, Q\right)+C^{a}\left(Q, \bar{K}^{(2), a}\right)+2 B^{h}\left(G^{(2)}, W\right)+B^{a}\left(W, \bar{G}^{(2)}\right) \\
& +\left(C^{a}\left(K^{(2), h}, \bar{Q}\right)+\frac{3 i}{8} K^{(2), h} \bar{Q}\right)-W_{\alpha}\left(Q_{\alpha} \bar{W}_{\alpha}-\bar{Q}_{\alpha} W_{\alpha}\right) \\
\tilde{K}_{r}^{(3)}= & -\frac{7}{8} \bar{W}_{\alpha} K^{(2), h}+W_{\alpha}\left|Q_{\alpha}\right|^{2}-i\left(\frac{3}{4} W_{\alpha \alpha}\left|W_{\alpha}\right|^{2}-\frac{3}{8} \bar{W}_{\alpha \alpha} W_{\alpha}^{2}\right) \\
\tilde{K}_{n r}^{(3)}= & A^{h}\left(W, K^{(2), h}\right)+A^{a}\left(W, \bar{K}^{(2), h}\right)+Q_{\alpha}^{2} W_{\alpha}+\bar{W}_{\alpha}\left|Q_{\alpha}\right|^{2} \\
& -i\left(\frac{15}{8} W_{\alpha}^{2} W_{\alpha \alpha}+\frac{3}{8} W_{\alpha \alpha} \bar{W}_{\alpha}^{2}-\frac{3}{4} \bar{W}_{\alpha \alpha}\left|W_{\alpha}\right|^{2}\right) \\
\tilde{K}_{n u l l}^{(3)}= & A^{h}\left(G^{(2)}, Q\right)+A^{h}\left(W, K^{(2), a}\right)+A^{a}\left(G^{(2)}, \bar{Q}\right)+A^{a}\left(W, K^{(2), a}\right)+D^{a}\left(Q, \bar{G}^{(2)}\right) \\
& +D^{a}\left(K^{(2), a}, \bar{W}\right)+\left(\frac{7}{8} \bar{W}_{\alpha} K^{(2), a}+D^{a}\left(K^{(2), h}, \bar{W}\right)\right)-Q_{\alpha}\left(Q_{\alpha} \bar{W}_{\alpha}-\bar{Q}_{\alpha} W_{\alpha}\right) .
\end{aligned}
$$\right.
\]

Here the leading projection in all terms has been harmlessly discarded, since it can be moved onto the wave packets, which decay rapidly at positive frequencies,

$$
\|(\mathbf{w}, \mathbf{q})-P(\mathbf{w}, \mathbf{q})\|_{H^{N}} \lesssim t^{-N} .
$$

We will place all cubic contributions into the error term $\operatorname{err}_{\gamma}$ except for the contribution of the resonant part $\tilde{G}_{r}$ and $\tilde{K}_{r}$. We note that for the most part the exact form of the expressions above is irrelevant. The only significant matter is whether the coefficients of the terms in $\tilde{G}_{r}^{(3)}$ and $\tilde{K}_{r}^{(3)}$ are either real or purely imaginary, depending on the term's parity.

One obstacle which we would encounter, had we tried to work directly with $\left(\tilde{G}^{(3)}, \tilde{K}^{(3)}\right)$, is the presence of terms with undifferentiated $W$ factors; this is because our pointwise decay bounds for $W$ are worse than $t^{-\frac{1}{2}}$. In the proof of Proposition 5.1, these terms are exactly $\left(\tilde{G}_{0}, \tilde{K}_{0}\right)$ which were computed using the expansion (3.10). However, the bad part of these terms is eliminated via the cubic normal form correction $\left(W_{[3], 0}^{l h h}, \tilde{G}_{[3]}^{l h}, 0\right.$ allows us to replace the terms $\left(\tilde{G}_{0}, \tilde{K}_{0}\right)$ with the better part $\left(\tilde{G}_{0}^{\text {good }}, \tilde{K}_{0}^{\text {good }}\right)$, where we are allowed to move at least half a derivative onto the undifferentiated $W$ factor. The price to pay for this correction is the additional cubic term in the last terms in (5.12); this term still has components with undifferentiated $W$ factors, but shares the above property that we can freely move at least half a derivative onto this factor.

The remaining cubic correction in $\tilde{\tilde{K}}$, namely $\tilde{K}_{2}-\tilde{K}_{2}^{\text {good }}$, contains only differentiated factors $W_{\alpha}$ and $Q_{\alpha}$, and is restricted to the non-resonant case, where the three frequencies cannot be all equal.

The conclusion of the above discussion is that
a) The resonant part of $\left(\tilde{\tilde{G}}^{(3)}, \tilde{\tilde{K}}^{(3)}\right)$ is the same as the resonant part of $\left(\tilde{G}^{(3)}, \tilde{K}^{(3)}\right)$.
b) All the terms in $\tilde{\tilde{G}}^{(3)}$, respectively $\tilde{\tilde{K}}^{(3)}$ can all be expressed as trilinear expression

$$
M_{2}(Q, Q, Q), \quad M_{53}\left(D^{\frac{1}{2}} W, D^{\frac{1}{2}} W, Q\right)
$$

respectively

$$
M_{5 / 2}\left(Q, Q, D^{\frac{1}{2}} W\right), \quad M_{5 / 2}\left(D^{\frac{1}{2}} W, D^{\frac{1}{2}} W, D^{\frac{1}{2}} W\right)
$$

We remark that in view of the better difference bounds (7.4), and (7.12), we can easily replace $(W, Q)$ in $\left(\tilde{\tilde{G}}^{(3)}, \tilde{\tilde{K}}^{(3)}\right)$ by the normal form variables $(\tilde{W}, \tilde{\tilde{Q}})$, modulo errors which can be included in err $_{\gamma}$.

We separately consider the three cases below, namely null, non-resonant and resonant terms.

1. Null terms. These are trilinear forms as above, with two distinguishing features, namely that (i) they are of type $(2,1)$ and (ii) their symbol vanishes on the resonant set, i.e., when all the frequencies are equal. Thus we need the following:

Lemma 8.3. Let $M$ be a trilinear operator of type $(2,1)$ as above, with symbol $M\left(\xi_{1}, \xi_{2}, \xi_{3}\right)$ and satisfying the null condition

$$
M(\xi, \xi, \xi)=0
$$

Then we have

$$
\begin{equation*}
\left|\int M(\tilde{\tilde{Q}}, \tilde{\tilde{Q}}, \tilde{\tilde{Q}}) \overline{\mathbf{u}} d \alpha\right| \lesssim \epsilon^{3} t^{-\frac{9}{8}} \tag{8.17}
\end{equation*}
$$

and its analogue when some or all of the arguments are $D^{\frac{1}{2}} W$.
Proof. We separate each of the three factors into the hyperbolic part and the elliptic part, as in the proof of Proposition 7.1. We consider several cases.
a) Elliptic terms. If at least one elliptic term is present, then that term has better decay, so we can neglect the null condition and use directly Proposition 2.3, estimating

$$
\left\|M\left(\tilde{\tilde{Q}}_{e l l}, \tilde{\tilde{Q}}, \tilde{\tilde{Q}}\right)\right\|_{L^{p}} \lesssim t^{-\frac{9}{8}}, \quad 2 \leq p<\infty
$$

Then we bound the integral using Hölder's inequality for $p$ close to infinity.
It remains to consider $L\left(\tilde{\tilde{Q}}_{\text {hyp }}, \tilde{\tilde{Q}}_{\text {hyp }}, \tilde{\tilde{Q}}_{\text {hyp }}\right)$. Here the dyadic frequency pieces are matched to essentially disjoint spatial regions. We can restrict ourselves to frequencies $t^{-\frac{1}{6}} \leq \lambda \leq t^{\frac{1}{6}}$, as for the remaining frequencies we have a better bound (see Proposition 7.1), and we can group them together with the elliptic part.
b) Unbalanced frequencies. In this case we have spatial separation between the arguments of $M$. Separating variables in the symbol of $M$, for fixed dyadic frequencies $\lambda_{1}, \lambda_{2}$, $\lambda_{3}$ in the above range it suffices to look at $M$ with symbol of the form

$$
M(\xi)=l_{1}\left(\xi_{1}\right) l_{2}\left(\xi_{2}\right) l_{3}\left(\xi_{3}\right)
$$

where each of $l_{1}, l_{2}, l_{3}$ are smooth on the dyadic scale. Then their kernels are rapidly decreasing on the $\lambda_{j}^{-1}$ scale. But $\lambda_{j}^{-1}<t^{-\frac{1}{6}}$, while the supports of $\tilde{\tilde{Q}}_{\lambda_{j}, \text { hyp }}$ are at least $t^{\frac{5}{6}}$ separated. Thus for distinct $\lambda_{1}, \lambda_{2}, \lambda_{3}$ we obtain rapid decay,

$$
\left\|M\left(\tilde{\tilde{Q}}_{\lambda_{1}, h y p}, \tilde{\tilde{Q}}_{\lambda_{2}, h y p}, \tilde{\tilde{Q}}_{\lambda_{3}, h y p}\right)\right\|_{L^{2} \cap L^{\infty}} \lesssim \epsilon^{3} t^{-N}
$$

c) Balanced mismatched frequencies. Here we consider the case $\lambda_{1} \approx \lambda_{2} \approx \lambda_{3} \not \approx v^{2}$. Then the arguments of $M$ are spatially localized away from the support of $\mathbf{u}$, and arguing as in the previous case we see that the integral (8.17) decays rapidly.
d) Balanced matched frequencies. Here we consider the remaining case $\lambda_{1} \approx \lambda_{2} \approx$ $\lambda_{3} \not \approx v^{2}=\lambda$. It is only in this case that we need to use the null condition (8.17). Since all frequencies are comparable, the symbol of $M$ is smooth on the dyadic scale. Due to the null condition, we can decompose $M$ as a sum of symbols of the form

$$
M=\sum_{(i, j)}\left(\xi_{i}-\xi_{j}\right) M_{i j}(\xi)
$$

with $M_{i j}$ smooth. Separating variables we can factor out $M_{i j}$, and be left with, say, $M=$ $\xi_{1}-\xi_{2}$. Then we can write $M$ in the form

$$
M\left(\tilde{\tilde{Q}}_{\lambda, h y p}^{1}, \tilde{\tilde{Q}}_{\lambda, \text { hyp }}^{2}, \tilde{\tilde{Q}}_{\lambda, \text { hyp }}^{3}\right)=M \tilde{\tilde{Q}}_{\lambda, \text { hyp }}^{1} \tilde{\tilde{Q}}_{\lambda, \text { hyp }}^{2} \overline{\tilde{Q}}_{\lambda, \text { hyp }}^{3}-\tilde{\tilde{Q}}_{\lambda, \text { hyp }}^{1} L \tilde{\tilde{Q}}_{\lambda, \text { hyp }}^{2} \overline{\tilde{\tilde{Q}}}_{\lambda, \text { hyp }}^{3}
$$

Here $\tilde{\tilde{Q}}_{\lambda, \text { hyp }}^{i}$ are obtained by applying zero order multipliers to $\tilde{\tilde{Q}}$, so satisfy the same bounds as $\tilde{\tilde{Q}}$, as described in Section 7. Now we use the better $L^{2}$ bound for $M \tilde{\tilde{Q}}_{\lambda, \text { hyp }}^{1}$ in order to estimate it in $L^{2}$. A similar computation applies if one of the indices $(i, j)$ corresponds to the conjugated variable.
2. Non-resonant terms. These are trilinear forms as above, with the property that they are either of type $(3,0)$ or of type $(1,2)$. For these we have:

Lemma 8.4. Let $M$ be a trilinear operator of type $(3,0)$ or of type $(1,2)$ as above. Then we have

$$
\begin{equation*}
\left|\int M(\tilde{\tilde{Q}}, \tilde{\tilde{Q}}, \tilde{\tilde{Q}}) \overline{\mathbf{u}} d \alpha\right| \lesssim \epsilon^{3} t^{-\frac{9}{8}} \tag{8.18}
\end{equation*}
$$

and its analogue when some or all of the arguments are $D^{\frac{1}{2}} \tilde{\tilde{W}}$.
Proof. The elliptic case, the unbalanced case and the balanced mismatched case are similar to the previous Lemma, so we are left with the balanced matched case. Suppose we are in the $(3,0)$ case; the $(1,2)$ case is similar. Separating variables we reduce the problem to the case when $L=1$, and our integral is

$$
\int \tilde{\tilde{Q}}_{\lambda, h y p}^{1} \tilde{\tilde{Q}}_{\lambda, h y p}^{2} \tilde{\tilde{Q}}_{\lambda, h y p}^{3} \overline{\mathbf{u}} d \alpha
$$

Denoting by $\gamma^{j}$ the variables associated to $\tilde{\tilde{Q}}_{\lambda, h y p}^{i}$ as in Proposition 8.1. we can replace $\tilde{\tilde{Q}}_{\lambda, h y p}^{i}$ by $t^{-\frac{1}{2}} \gamma^{j} e^{i \phi}$ with a better error. Thus, we can replace our integral by

$$
t^{-\frac{3}{2}} \int \gamma^{1} \gamma^{2} \gamma^{3} \chi\left(\frac{\alpha-v t}{t^{\frac{1}{2}} v^{-\frac{1}{2}}}\right) e^{2 i \phi} d \alpha+e r r_{\gamma} .
$$

Here the important fact is that the phases did not cancel. Thus using nonstationary we can put one derivative on either $\gamma^{j}$ or on $\chi$, each of which gains at least a $t^{-\frac{1}{2}}$ factor. Then it suffices to conclude by Hölder's inequality.
3. Resonant terms. As we have organized our cubic nonlinearity, our non-resonant terms contain purely multiplicative terms. Using the approximation in Proposition 8.1, we
obtain the leading contribution in $\dot{\gamma}$. To compute that, we recall that

$$
\tilde{\tilde{Q}} \approx t^{-\frac{1}{2}} e^{i \phi} \gamma, \quad \tilde{W}_{\alpha} \approx-\frac{2 i \alpha}{3 t} t^{-\frac{1}{2}} e^{i \phi} \gamma
$$

Recalling that

$$
K^{(2), h}=-\tilde{\tilde{Q}}_{\alpha}^{2}+\frac{3 i}{2} \tilde{\tilde{W}}_{\alpha \alpha} \tilde{\tilde{W}}_{\alpha},
$$

the leading term in $\tilde{G}_{\text {res }}^{(3)}$ is computed as follows:

$$
\begin{aligned}
\tilde{G}_{r e s}^{(3)} & =-\frac{3 i}{8}\left(-\tilde{\tilde{Q}}_{\alpha}^{2}+\frac{3 i}{2} \tilde{\tilde{W}}_{\alpha \alpha} \tilde{\tilde{W}}_{\alpha}\right) \overline{\tilde{Q}} \\
& \approx \frac{i \alpha^{4}}{27 t^{4}} t^{-\frac{3}{2}} \gamma(t, v)|\gamma(t, v)|^{2} e^{i \phi} .
\end{aligned}
$$

A similar computation for $\tilde{K}_{\text {res }}^{(3)}$ gives

$$
\begin{aligned}
\tilde{K}_{r e s}^{(3)} & =-\frac{7}{8} \overline{\tilde{W}}_{\alpha}\left(-\tilde{\tilde{Q}}_{\alpha}^{2}+\frac{3 i}{2} \tilde{\tilde{W}}_{\alpha \alpha} \tilde{\tilde{W}}_{\alpha},\right)+\tilde{\tilde{W}}_{\alpha}\left|\tilde{\tilde{Q}}_{\alpha}\right|^{2}-i\left(\frac{3}{4} \tilde{\tilde{W}}_{\alpha \alpha}\left|\tilde{\tilde{W}}_{\alpha}\right|^{2}-\frac{3}{8} \overline{\tilde{W}}_{\alpha \alpha} \tilde{\tilde{W}}_{\alpha}^{2}\right) \\
& \approx-\frac{2 \alpha^{5} i}{27 t^{5}} t^{-\frac{3}{2}} \gamma(t, v)|\gamma(t, v)|^{2} e^{i \phi} .
\end{aligned}
$$

Then the leading contribution in $\dot{\gamma}$ is

$$
\begin{aligned}
I & =\int i \tilde{G}_{r e s}^{(3)} \overline{\mathbf{w}}_{\alpha}+\tilde{K}_{r e s}^{(3)} \overline{\mathbf{q}} d \alpha=\int\left(\tilde{K}_{\text {res }}^{(3)}+\frac{2 v}{3} \tilde{G}_{\text {res }}^{(3)}\right) \overline{\mathbf{u}} d \alpha+e r r_{\gamma} \\
& =\int-\frac{8 i v^{5}}{81} v^{-\frac{1}{2}} t^{-\frac{3}{2}} \chi\left(\frac{\alpha-v t}{t^{\frac{1}{2}} v^{-\frac{1}{2}}}\right) \gamma(t, \alpha)|\gamma(t, \alpha)|^{2} d \alpha+e r r_{\gamma} .
\end{aligned}
$$

Since $\chi$ has integral 1 and, by (8.5), we have good control in $L^{2}$ over the derivative of $\gamma$, the above integral is equal to

$$
I=-\frac{8 i v^{5}}{81 t} \gamma(t, \alpha)|\gamma(t, \alpha)|^{2}+E r r .
$$

Therefore the conclusion of the proposition follows.

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[^1]:    ${ }^{1}$ F. Pusateri, talk in the Banff workshop of May 11-16, 2014

[^2]:    ${ }^{2}$ As estimated here, this bound is borderline; however we can gain an additional small time decay factor by restricting the frequencies in $h h h \rightarrow l$ interactions to $\lambda_{\text {med }} \geq \sqrt{\lambda_{\text {out }} \lambda_{h i}}$.

[^3]:    ${ }^{3}$ Which corresponds to all three frequencies being equal.

