

## The Local Structure of Trans-Sasakian Manifolds (\*).

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**Summary.** – *In this paper, we completely characterize the local structure of trans-Sasakian manifolds of dimension  $\geq 5$  by giving suitable examples.*

### 0. – Introduction.

An almost Hermitian manifold  $V$  is called locally conformal Kähler (l.c.K.) if its metric is conformally related to a Kähler metric in some neighbourhood of every point of  $V$ . Such manifolds have been studied by various authors (see, for instance, [L], [GH], [V1], [V2] and [V3]).

In [O], J. A. OUBIÑA has studied a new class of almost contact metric structure, called trans-Sasakian, which is, in some sense, an analogue of a locally conformal Kähler structure on an almost Hermitian manifold (see definition in § 1).

On the other hand, in [ChG] the authors have introduced two subclasses of trans-Sasakian structures, the  $\mathcal{C}_5$  and  $\mathcal{C}_6$ -structures, which contain the Kenmotsu and Sasakian structures, respectively.

In this paper, we completely characterize the local nature of the trans-Sasakian structures on connected differentiable manifolds of dimension  $\geq 5$ . In section 1, we recall some results on almost contact metric manifolds. In section 2 and 3, we characterize the local nature of  $\mathcal{C}_5$  and  $\mathcal{C}_6$  structures, respectively (see Theorems 2.1 and 3.1), by using the techniques of [O]. In section 4 we prove that the trans-Sasakian structures are of class  $\mathcal{C}_5$  or  $\mathcal{C}_6$  (see Theorem 4.1). Finally, we obtain some examples of 3-dimensional trans-Sasakian structures which are neither of class  $\mathcal{C}_5$  nor  $\mathcal{C}_6$ .

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### 1. – Preliminaries.

Let  $V$  be a  $C^\infty$  almost Hermitian manifold with metric  $g$  and almost complex structure  $J$ . Denote by  $\mathfrak{X}(V)$  the Lie algebra of  $C^\infty$  vector fields on  $V$ . The Kähler form  $\Omega$  is given by  $\Omega(X, Y) = g(X, JY)$ ; and the Lee form is the 1-form  $\theta$  defined by  $\theta(X) = 1/(n-1) \delta\Omega(JX)$ , where  $\delta$  denotes the coderivate,  $\dim V = 2n$  and  $X, Y \in \mathfrak{X}(V)$ .

Recall that  $V$  is said to be Kähler if  $d\Omega = 0$  and  $N_J = 0$  and locally conformal Kähler (l.c.K.) if  $d\Omega = \theta \wedge \Omega$  and  $N_J = 0$ , where  $N_J$  denotes the Nijenhuis tensor of  $J$ .

On the other hand, let  $M$  be a  $C^\infty$  almost contact metric manifold with metric  $g$  and almost contact structure  $(\varphi, \xi, \eta)$ . Then we have,

$$\begin{aligned}\varphi^2 &= -I + \eta \otimes \xi, & \eta(\xi) &= 1, \\ g(\varphi X, \varphi Y) &= g(X, Y) - \eta(X)\eta(Y),\end{aligned}$$

for  $X, Y \in \mathfrak{X}(M)$ , where  $I$  denotes the identity transformation. The fundamental 2-form  $\Phi$  of the almost contact metric manifold  $(M, \varphi, \xi, \eta, g)$  is defined by  $\Phi(X, Y) = g(X, \varphi Y)$  for all  $X, Y \in \mathfrak{X}(M)$ .

An almost contact structure  $(\varphi, \xi, \eta)$  is said to be normal if the almost complex structure  $J$  on  $M \times \mathbf{R}$  given by

$$(1.1) \quad J(X, a d/dt) = (\varphi X - a\xi, \eta(X) d/dt),$$

where  $a$  is a  $C^\infty$  function on  $M \times \mathbf{R}$ , is integrable, which is equivalent to the condition  $N_\varphi + 2d\eta \otimes \xi = 0$ , where  $N_\varphi$  denotes the Nijenhuis torsion of  $\varphi$  (see [SH1] and [SH2]).

Now, let  $(\varphi, \xi, \eta, g)$  be an almost contact metric structure on  $M$ . We define an almost Hermitian structure  $(J, h)$  on  $M \times \mathbf{R}$ , where the almost complex structure  $J$  is given by (1.1) and  $h$  is the Riemannian metric following:

$$h((X, a d/dt), (Y, b d/dt)) = g(X, Y) + ab.$$

An almost contact metric structure  $(\varphi, \xi, \eta, g)$  is said to be trans-Sasakian (see [O]) if the almost Hermitian structure  $(J, h)$  on  $M \times \mathbf{R}$  is l.c.K.

In [O], the author proves that  $(\varphi, \xi, \eta, g)$  is a trans-Sasakian structure if and only if it is normal and

$$(1.2) \quad d\Phi = 2\alpha\eta \wedge \Phi,$$

$$(1.3) \quad d\eta = \beta\Phi,$$

where  $\alpha = \operatorname{div} \xi / (2n)$  and  $\beta = \delta\Phi(\xi) / (2n)$ .

An almost contact metric structure  $(\varphi, \xi, \eta, g)$  is said to be:

$\mathcal{C}_5$  if it is trans-Sasakian with  $\beta = 0$ ; Kenmotsu if it is  $\mathcal{C}_5$  with  $\alpha = 1$ ;  $\mathcal{C}_6$  if it is trans-Sasakian with  $\alpha = 0$ ; Sasakian if it is  $\mathcal{C}_6$  with  $\beta = 1$ ; cosymplectic if it is trans-Sasakian with  $\alpha = \beta = 0$  (see [B2], [ChG] and [K]).

We say that the almost contact structure  $(\varphi, \xi, \eta)$  has rank  $r$  if and only if the 1-form  $\eta$  has rank  $r$ . Consequently,  $(\varphi, \xi, \eta)$  has rank  $r = 2s$  if  $(d\eta)^s \neq 0$  and  $\eta \wedge (d\eta)^s = 0$ , and has rank  $r = 2s + 1$  if  $\eta \wedge (d\eta)^s \neq 0$  and  $(d\eta)^{s+1} = 0$ .

Let  $(M, \varphi, \xi, \eta, g)$  be an almost contact metric manifold and  $\sigma$  a positive differentiable function on  $M$ . We put,

$$g' = \sigma g + (1 - \sigma) \eta \otimes \eta.$$

Then,  $(\varphi, \xi, \eta, g')$  is also an almost contact metric structure on  $M$ . Moreover, if  $(\varphi, \xi, \eta, g)$  is trans-Sasakian and we denote by  $\Phi'$  the fundamental 2-form of the almost contact metric structure  $(\varphi, \xi, \eta, g')$ , we have:

$$(1.4) \quad d\Phi' = (d(\ln \sigma) + (\operatorname{div} \xi/n) \eta) \wedge \Phi',$$

$$(1.5) \quad d\eta = (\beta/\sigma) \Phi'.$$

AGREEMENT. – Through the rest of this paper,  $M$  always denotes a  $(2n + 1)$ -dimensional ( $n \geq 2$ ) connected manifold unless stated otherwise.

## 2. – $\mathcal{C}_5$ -structures.

In this section, we describe the local structure of manifolds of class  $\mathcal{C}_5$ . Before, we examine the following example:

EXAMPLE 1. – Let  $M$  be the product manifold  $L \times V$ , where  $L$  is the circle  $S^1$  or an open interval  $(a', b')$ ,  $-\infty \leq a' < b' \leq \infty$ , and  $(V, J, G)$  is a  $2n$ -dimensional Kählerian manifold. Let  $E$  be a nowhere vanishing vector field on  $L$ ,  $E^*$  its dual field of 1-forms and  $\sigma$  a positive function on  $L$ . Put

$$(2.1) \quad \begin{cases} \varphi(aE, X) = (0, JX), & \xi = (E, 0), & \eta = (E^*, 0), \\ g((aE, X), (bE, Y)) = \sigma G(X, Y) + ab, \end{cases}$$

where  $a$  and  $b$  are differentiable functions on  $M$ , and  $X, Y \in \mathfrak{X}(V)$ . Then it is not difficult to check that  $(\varphi, \xi, \eta, g)$  is an almost contact metric structure on  $M$  of class  $\mathcal{C}_5$ .

We remark that in the above example the 1-form  $(\operatorname{div} \xi) \eta = d(\ln \sigma^n)$  is closed. We generalize this result for trans-Sasakian manifolds.

Let  $(\varphi, \xi, \eta, g)$  be a trans-Sasakian structure on  $M$ , then

LEMMA 2.1. – *The 1-form  $(\operatorname{div} \xi) \eta$  is closed.*

PROOF. – From the definition of trans-Sasakian structure (see (1.2) and (1.3)), we obtain

$$(2.2) \quad d((\operatorname{div} \xi) \eta) \wedge \Phi = 0,$$

$$(2.3) \quad d((\operatorname{div} \xi) \eta) \wedge \eta = (\beta \operatorname{div} \xi) \eta \wedge \Phi.$$

Let  $p$  be a point of  $M$ . We shall prove that  $d((\operatorname{div} \xi) \eta)_p = 0$ . If  $\beta(p) = 0$ , we deduce the result from the relations (2.2) and (2.3), since  $\dim M \geq 5$ .

Now, we suppose that  $\beta(p) \neq 0$ . Let  $U$  be a neighbourhood of  $p$  such that  $\beta \neq 0$  on  $U$ . We can suppose that  $\beta > 0$  on  $U$ . Taking in (1.3) the exterior differential and using (1.2), one gets

$$(d\beta + \beta(\operatorname{div} \xi/n) \eta) \wedge \Phi = 0,$$

and since  $\operatorname{rang} \Phi \geq 4$  we obtain  $d\beta + \beta(\operatorname{div} \xi/n) \eta = 0$ , i.e.,  $d(\ln \beta) = -(\operatorname{div} \xi/n) \eta$  which also proves that  $d((\operatorname{div} \xi) \eta)_p = 0$ . ■

Let  $(M, \varphi, \xi, \eta, g)$  be an almost contact metric manifold of class  $\mathcal{C}_5$ . Next, we prove the following structure theorem, which generalizes a similar result obtained by KENMOTSU [K] for Kenmotsu manifolds.

**THEOREM 2.1.** – *The manifold  $M$  is locally the product  $(a', b') \times V$ , where  $(a', b')$  is an open interval and  $V$  is a  $2n$ -dimensional Kählerian manifold, on which the structure  $(\varphi, \xi, \eta, g)$  is given as in (2.1).*

**PROOF.** – Fix a point  $p \in M$ . From Lemma 2.1, there exists a neighbourhood  $U'$  of  $p$  on which  $d(\ln \sigma) = (\operatorname{div} \xi/n) \eta$ , for a certain positive function  $\sigma$ . Put,  $g' = (1/\sigma) g + (1 - 1/\sigma) \eta \otimes \eta$ . From the definition of structure of class  $\mathcal{C}_5$  and using (1.4) and (1.5),  $(\varphi, \xi, \eta, g')$  is cosymplectic on  $U'$ . Therefore the point  $p$  has a neighbourhood  $U = (a', b') \times V \subset U'$  such that  $(\varphi, \xi, \eta, g')$  is given on  $U$  by

$$\varphi(aE, X) = (0, JX), \quad \xi = (E, 0), \quad \eta = (E^*, 0),$$

$$g'((aE, X), (bE, Y)) = G(X, Y) + ab,$$

where  $(J, G)$  is a Kählerian structure on  $V$ ,  $E$  is a nowhere vanishing vector field on  $(a', b')$  and  $E^*$  its dual (see, for instance, [B1]). Finally, since  $g = \sigma g' + (1 - \sigma) \eta \otimes \eta$ , we see that the structure  $(\varphi, \xi, \eta, g)$  on  $U$  is given as in (2.1). ■

**REMARK.** – In [K], K. KENMOTSU has proved that a Kenmotsu manifold is not compact. However, taking in the example 1,  $L = S^1$ ,  $V$  a compact Kähler manifold,  $\eta$  the length element of the circle  $S^1$  and  $\sigma$  a positive function (not constant) on  $S^1$ , we obtain an almost contact metric structure of class  $\mathcal{C}_5$ , which is not Kenmotsu, on the compact manifold  $M = S^1 \times V$ .

Finally, we suppose that  $(\varphi, \xi, \eta, g)$  is an almost contact metric structure of class  $\mathcal{C}_5$  on a simply connected manifold  $M$ . From Lemma 2.1, we have  $(\operatorname{div} \xi/n) \eta = d(\ln \sigma)$  for a certain positive function  $\sigma$  on  $M$ . Put  $g' = (1/\sigma) g + (1 - 1/\sigma) \eta \otimes \eta$ . Then,  $(\varphi, \xi, \eta, g')$  is a cosymplectic structure on  $M$ . Consequently, from Proposition 2.3 of [FM], we deduce

PROPOSITION 2.1. – *A compact simply connected manifold can not admit a structure of class  $\mathcal{C}_5$ .*

3. –  $\mathcal{C}_6$ -structures.

An almost contact metric structure  $(\varphi, \xi, \eta, g)$  on  $M$  is said to be  $\gamma$ -Sasakian ( $\gamma \in \mathbf{R}$ ,  $\gamma \neq 0$ ) if it is normal and  $d\eta = \gamma\Phi$ , where  $\Phi$  is the fundamental 2-form (see [JV]). If  $(\varphi, \xi, \eta, g)$  is Sasakian then it is 1-Sasakian, and if it is  $\gamma$ -Sasakian or cosymplectic then it is of class  $\mathcal{C}_6$ . Next, we prove the converse.

LEMMA 3.1. – *If  $(\varphi, \xi, \eta, g)$  is an almost contact metric structure on  $M$  of class  $\mathcal{C}_6$ , then it is  $\gamma$ -Sasakian or cosymplectic.*

PROOF. – Taking in (1.3) the exterior differential, we get that  $d\beta \wedge \Phi = 0$  and, since  $M$  is connected and  $\dim M \geq 5$ , we obtain  $\beta = \gamma = \text{constant}$ . Thus, if  $\gamma \neq 0$ , the structure  $(\varphi, \xi, \eta, g)$  is  $\gamma$ -Sasakian and if  $\gamma = 0$ , it is cosymplectic. ■

Therefore, a not cosymplectic  $\mathcal{C}_6$  manifold is essentially a Sasakian manifold. In fact, if the structure  $(\varphi, \xi, \eta, g)$  is  $\gamma$ -Sasakian then the structure  $(\varphi, (1/\gamma)\xi, \gamma\eta, \gamma^2g)$  is Sasakian.

Now, let  $M$  be the product manifold  $L \times V$ , where  $L$  is the circle  $S^1$  or an open interval  $(a', b')$ ,  $-\infty \leq a' < b' \leq \infty$ , and  $(V, J, G)$  is an almost Hermitian manifold of dimension  $2n$ . Let  $E$  be a nowhere vanishing vector field on  $L$ ,  $E^*$  its dual field of 1-forms and  $\omega$  a 1-form on  $V$ .

Put,

$$(3.1) \quad \begin{cases} \varphi(aE, X) = (-\omega(JX)E, JX), & \xi = (E, 0), & \eta = (E^*, \omega), \\ g((aE, X), (bE, Y)) = G(X, Y) + ab + \omega(X)\omega(Y) + \omega(X)b + \omega(Y)a, \end{cases}$$

where  $a, b$  are differentiable functions on  $M$  and  $X, Y \in \mathfrak{X}(V)$ . By straightforward verification we can see that  $(\varphi, \xi, \eta, g)$  is an almost contact metric structure on  $M$ . Moreover, if we denote by  $N_J$  and  $N_\varphi$  the Nijenhuis tensors of  $J$  and  $\varphi$ , respectively, and by  $\Omega$  the Kähler form of  $(V, J, G)$ , then it is not difficult to check the following:

PROPOSITION 3.1.

$$(3.2) \quad N_\varphi((aE, X), (bE, Y)) + 2d\eta((aE, X), (bE, Y))(E, 0) = \\ = ((-\omega(N_J(X, Y)) - 2d\omega(JX, JY) + 2d\omega(X, Y))E, N_J(X, Y)),$$

$$(3.3) \quad \Phi((aE, X), (bE, Y)) = \Omega(X, Y),$$

for  $X, Y \in \mathfrak{X}(V)$  and  $a, b$  differentiable functions on  $M$ .

Next, we describe the local structure of manifolds of class  $\mathcal{C}_6$ . Previously, we examine the following example.

**EXAMPLE 2.** – Let  $M, V, L, J, E$  and  $E^*$  be as in example 1 and  $\omega$  a 1-form on  $V$ , such that  $d\omega = \beta\Omega$  where  $\beta$  is constant and  $\Omega$  the Kähler form of  $(V, J, G)$ . We define  $\varphi, \xi, \eta$  and  $g$  as in (3.1). Then, from (3.2) and (3.3) we deduce

- a) If  $\beta = 0$ ,  $(\varphi, \xi, \eta, g)$  is a cosymplectic structure.
- b) If  $\beta \neq 0$ ,  $(\varphi, \xi, \eta, g)$  is a  $\beta$ -Sasakian structure.

Now, we prove that the converse holds locally. Let  $(\varphi, \xi, \eta, g)$  be an almost contact metric structure of class  $\mathcal{C}_6$  on  $M$ , then

**THEOREM 3.1.** – *The manifold  $M$  is locally the product  $(a', b') \times V$ , where  $(a', b')$  is an open interval and  $V$  is a  $2n$ -dimensional Kählerian manifold, on which the structure  $(\varphi, \xi, \eta, g)$  is given as in Example 2.*

**PROOF.** – Fix a point  $p \in M$ . Let  $U$  be a coordinate neighbourhood of  $p$ , with coordinates  $(x^0, x^1, \dots, x^{2n})$  such that  $U = (-a, a) \times V$ ,  $x^0$  is the coordinate on  $(-a, a)$ ,  $(x^1, \dots, x^{2n})$  are the coordinates on  $V$  and  $\xi = \partial/\partial x^0$  on  $U$ . Let  $g_{ij}, \eta_i, \varphi_j^i$  be the components of  $g, \eta$  and  $\varphi$  in the coordinates  $(x^0, x^1, \dots, x^{2n})$ . From Lemma 3.1 we obtain the relations

$$\mathcal{L}_\xi g = \mathcal{L}_\xi \eta = \mathcal{L}_\xi \varphi = 0$$

where  $\mathcal{L}_\xi$  denotes the Lie derivate with respect to  $\xi$ . Using the above relations we deduce that the components  $g_{ij}, \eta_i, \varphi_j^i$  are independent of the coordinate  $x^0$ . Therefore they can be used to a description of an almost Hermitian structure on  $V$ . Thus, define

$$J(\partial/\partial x^j) = \sum_{i=1}^{2n} \varphi_j^i (\partial/\partial x^i) \quad j = 1, \dots, 2n,$$

$$G(\partial/\partial x^i, \partial/\partial x^j) = g_{ij} - \eta_i \eta_j, \quad i, j = 1, \dots, 2n.$$

It is clear that the pair  $(J, G)$  is an almost Hermitian structure on  $V$ . Moreover, if we put

$$\omega(\partial/\partial x^i) = \eta_i \quad (i = 1, \dots, 2n), \quad E = \partial/\partial x^0, \quad E^* = dx^0$$

then the almost contact metric structure  $(\varphi, \xi, \eta, g)$  on  $U$  and the almost Hermitian structure  $(J, G)$  on  $V$  are related by (3.1). Consequently, from relations (3.2) and (3.3), we deduce that  $(J, G)$  is a Kähler structure on  $V$ . Finally, from the definition of structure of class  $\mathcal{C}_6$ , we obtain  $d\omega = \beta\Omega$  with  $\beta$  constant, where  $\Omega$  is the Kähler form of  $(V, J, G)$ . ■

**4. – Trans-Sasakian manifolds.**

First, we study the rank of a trans-Sasakian structure

**PROPOSITION 4.1.** – *Let  $(M, \varphi, \xi, \eta, g)$  be a trans-Sasakian manifold and  $r$  the rank of  $(\varphi, \xi, \eta)$ . Then  $r$  cannot be even. Moreover, if  $r = 2s + 1$ , then  $s = 0$  or  $s = n$  and we have*

- a)  $(\varphi, \xi, \eta, g)$  is of class  $\mathcal{C}_5$  if and only if  $s = 0$ .*
- b)  $(\varphi, \xi, \eta, g)$  is of class  $\mathcal{C}_6$  not cosymplectic if and only if  $s = n$ .*

**PROOF.** – If  $r = 2s$ , from (1.3), we deduce that  $\beta \neq 0$  at every point. On the other hand, since  $\eta \wedge (d\eta)^s = 0$  and  $\eta \wedge \Phi^n \neq 0$  we obtain  $\beta = 0$ , which is a contradiction.

The assertion *a)* is evident.

Now, we suppose that  $r = 2s + 1$ ,  $s \neq 0$ . Then, it is clear that  $\beta \neq 0$  at every point and thus  $r = 2n + 1$ . From Lemma 2.1, the 1-form  $\alpha\eta = -(\operatorname{div} \xi / 2n) \eta$  is closed. Therefore, by using 1.3, we obtain

$$(4.1) \quad d\alpha \wedge \eta + \alpha\beta\Phi = 0,$$

and since  $\eta \wedge \Phi \neq 0$ , we deduce  $\alpha\beta = 0$ , *i.e.*,  $\alpha = 0$ . Consequently, the structure  $(\varphi, \xi, \eta, g)$  is of class  $\mathcal{C}_6$  not cosymplectic.

Conversely, if  $r = 2s + 1$  and  $(\varphi, \xi, \eta, g)$  is of class  $\mathcal{C}_6$  and it is not cosymplectic then  $\beta \neq 0$  and thus  $s = n$ . ■

Next, we prove that a trans-Sasakian structure is of class  $\mathcal{C}_5$  or  $\mathcal{C}_6$ .

**THEOREM 4.1.** – *If  $(\varphi, \xi, \eta, g)$  is a trans-Sasakian structure, it is of class  $\mathcal{C}_5$  or  $\mathcal{C}_6$ .*

**PROOF.** – Denote by  $A$  the following set

$$A = \{x \in M / \beta(x) = 0\},$$

where  $d\eta = \beta\Phi$ .

Let  $x_0$  be a point of  $A$ . From Lemma 2.1,  $2\alpha\eta = (\operatorname{div} \xi / n) \eta$  is a closed 1-form. Then, there exists an open neighbourhood  $U$  of  $x_0$  on which  $d(\ln \sigma) = 2\alpha\eta$ , for a certain positive function  $\sigma$ . Put,

$$(4.2) \quad g' = (1/\sigma)g + (1 - 1/\sigma)\eta \otimes \eta.$$

From relations (1.4), (1.5) and by using the Lemma 3.1 we obtain that the almost contact metric structure  $(\varphi, \xi, \eta, g')$  is of class  $\mathcal{C}_6$  and  $\beta/\sigma = c$  ( $c$  constant). Thus, since  $\beta(x_0) = 0$ ,  $c = 0$  and therefore  $U \subseteq A$ .

Consequently,  $A$  is an open subset of  $M$ . On the other hand, it is clear that  $A$  is closed in  $M$ . Therefore, from the connectedness of  $M$ , we deduce that  $A = M$  or  $A = \emptyset$ . If  $A = M$ ,  $(\varphi, \xi, \eta, g)$  is of class  $\mathcal{C}_5$  (in this case  $M$  may

also be cosymplectic) and if  $A = \phi$  the rank of the structure  $(\varphi, \xi, \eta)$  is  $2n + 1$  and hence, using the Proposition 4.1,  $(\varphi, \xi, \eta, g)$  is of class  $\mathcal{C}_6$ . ■

The Theorem 4.1 is not true for  $\dim M = 3$ . In fact, if  $(M, \varphi, \xi, \eta, g)$  is a 3-dimensional Sasakian manifold, and

$$g' = \sigma g + (1 - \sigma) \eta \otimes \eta,$$

where  $\sigma$  is a positive function on  $M$ , then

**PROPOSITION 4.2.** *–  $(\varphi, \xi, \eta, g')$  is a trans-Sasakian structure on  $M$ . Moreover, if  $\xi(\sigma) \neq 0$ , then  $(\varphi, \xi, \eta, g')$  is neither of class  $\mathcal{C}_5$  nor  $\mathcal{C}_6$ .*

**PROOF.** – It is clear that  $(\varphi, \xi, \eta, g')$  is a normal structure on  $M$ . Moreover, if  $\Phi'$  is the fundamental 2-form of the structure  $(\varphi, \xi, \eta, g')$ , we deduce, from (1.4) and (1.5), that

$$(4.3) \quad d\Phi' = d(\ln \sigma) \wedge \Phi',$$

$$(4.4) \quad d\eta' = (1/\sigma)\Phi'.$$

Now take a  $\varphi$ -bassis  $\{E_0, E_1, E_2\}$  for the structure  $(\varphi, \xi, \eta, g')$  and its dual basis of 1-forms  $\{E_0^* = \eta, E_1^*, E_2^*\}$ . Then,  $\Phi' = 2E_2^* \wedge E_1^*$  and  $d(\ln \sigma) = \xi(\ln \sigma) \eta + E_1(\ln \sigma) E_1^* + E_2(\ln \sigma) E_2^*$ . Thus,

$$(4.5) \quad d\Phi' = \xi(\ln \sigma) \eta \wedge \Phi'$$

and  $(\varphi, \xi, \eta, g')$  is a trans-Sasakian structure. Moreover, by using (4.4), we deduce that  $(\varphi, \xi, \eta, g')$  is not of class  $\mathcal{C}_5$ .

On the other hand, from (4.4) and (4.5),  $(\varphi, \xi, \eta, g')$  is of class  $\mathcal{C}_6$  if and only if  $\xi(\ln \sigma) = 0$ , *i.e.*,  $\xi(\sigma) = 0$ .

This ends the proof of the proposition. ■

Next, by using the Proposition 4.2, we give an example of trans-Sasakian structure which is neither of class  $\mathcal{C}_5$  nor  $\mathcal{C}_6$ .

Let  $H(1, 1)$  be the group of matrices of real numbers of the form

$$\begin{bmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{bmatrix},$$

where  $x, y, z \in \mathbf{R}$ .  $H(1, 1)$  is a connected simply connected nilpotent Lie group of dimension 3, which is called Heisenberg group (for an extensive study of Heisenberg groups see [H], [CFL]).

A basis for the left invariant 1-forms on  $H(1, 1)$  is given by

$$\alpha = dx, \quad \beta = dy, \quad \gamma = dz - x dy$$

and its dual basis of left invariant vector fields on  $H(1, 1)$  is given by

$$X = \partial/\partial x, \quad Y = \partial/\partial y + x\partial/\partial z, \quad Z = \partial/\partial z.$$

Define an almost contact metric structure  $(\varphi, \xi, \eta, g)$  on  $H(1, 1)$  by

$$\begin{aligned} \varphi X &= Y, & \varphi Y &= -X, & \xi &= Z, & \eta &= \gamma, \\ g &= 1/2(\alpha \otimes \alpha + \beta \otimes \beta + \gamma \otimes \gamma). \end{aligned}$$

Then,  $(\varphi, \xi, \eta, g)$  is a Sasakian structure on  $H(1, 1)$ .

Now, put

$$g' = e^z g + (1 - e^z) \eta \otimes \eta.$$

Then, by using the Proposition 4.2 (in this case  $\sigma = e^z$ ),  $(\varphi, \xi, \eta, g')$  is a trans-Sasakian structure on  $H(1, 1)$  which is neither of class  $\mathcal{C}_5$  nor  $\mathcal{C}_6$ .

Finally, since the unit sphere  $S^3$  carries an induced Sasakian structure as orientable hypersurface of  $\mathbf{R}^4$  (see, for instance, [B2]), we also can obtain, by using the Proposition 4.2, a trans-Sasakian structure on  $S^3$ , which is neither of class  $\mathcal{C}_5$  nor  $\mathcal{C}_6$ .

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