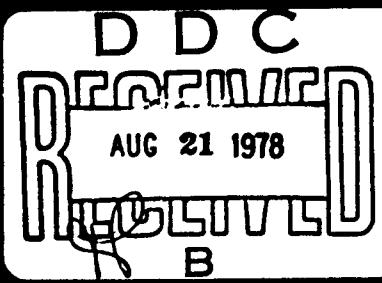


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20. ABSTRACT (Continue on reverse side if necessary and identify by block number) (1rs) This report presents a comprehensive documentation of experimental data generated for the ACT (Automatic Cannon Technology) Program (behind-armor data for long rod penetrators in the 20-40mm size). An adequate kinetic energy penetrator performance data base for long rod penetrators of various designs has been established. In addition, for some of the rounds, behind-target debris has been analyzed to supply a partial basis for debris characterization. <b>R</b>		

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## I. INTRODUCTION

The purpose of this report is to present a comprehensive documentation of experimental data generated in a small scale firing program within the ACT Project\*. Chief objectives were:

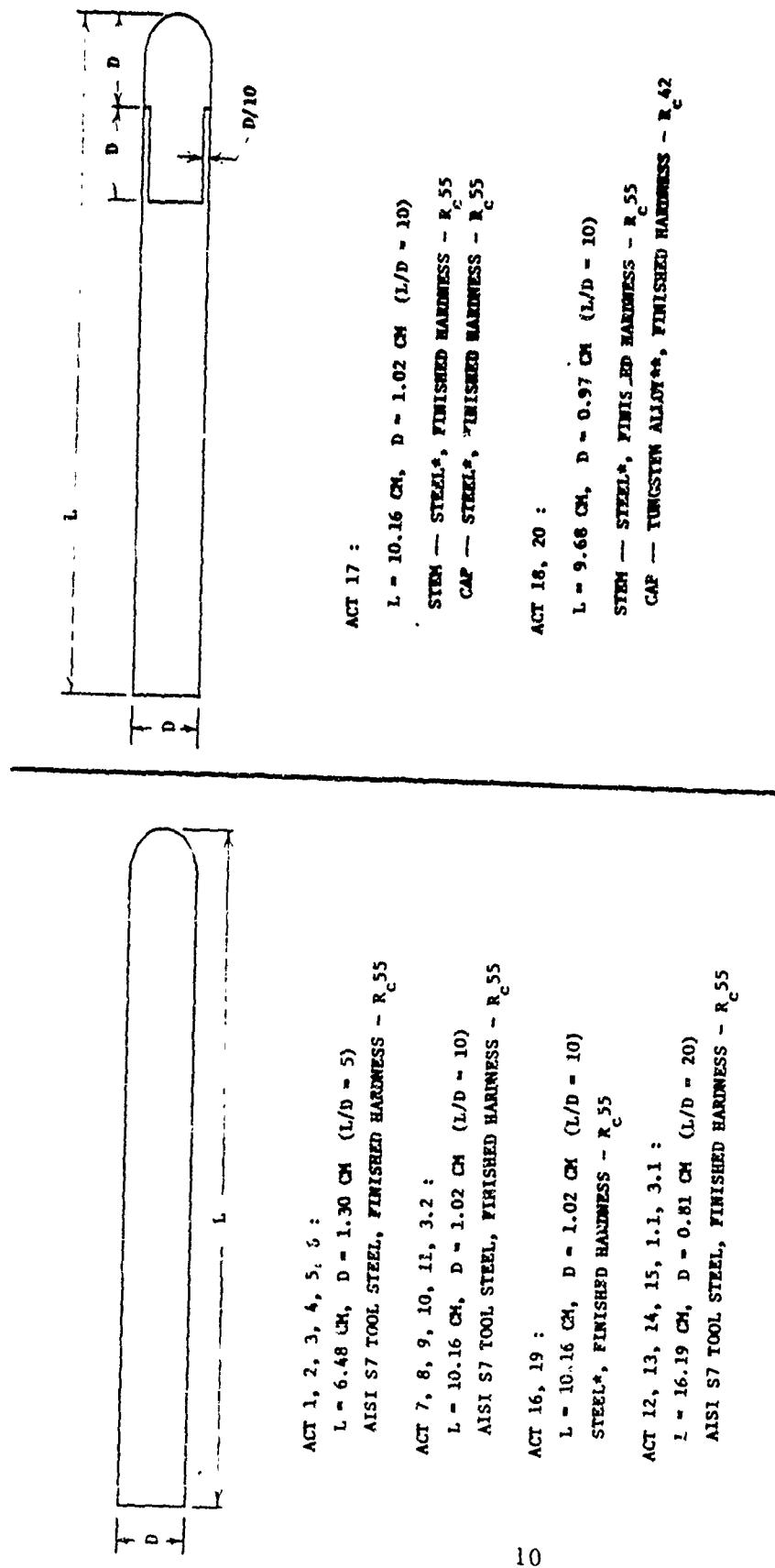
- to assure an adequate kinetic energy penetrator performance data base for various long rod penetrator designs and
- to describe behind-target debris - mass, trajectory, speed and type of individual fragments - associated with some rounds and to thereby supply a partial basis for debris characterization.

Targets used in the firing program were single plate rolled homogeneous armor (RHA) measuring 15.24 x 30.48cm for normal impact shots and 15.24 x 45.72cm for oblique incidence with thicknesses ranging from 1.91 to 5.08cm. Penetrators were rods (right circular cylinders with hemispherical noses) having length to diameter (L/D) ratios of 5, 10 and 20. The predominant penetrator composition was of monolithic AISI-S7 tool steel of finished hardness  $R_c$  55 but other designs and other materials were used to some extent; c.f. Figure 1 for penetrator characteristics. Impact obliquities were  $0^\circ$ ,  $45^\circ$  and  $60^\circ$ .

In large part, the essence of this report is confined to the five appendices; indeed, our most compelling purpose is to disseminate, for the first time in anywhere near complete form, data that this program has been sporadically yielding over several years.

Basic raw data from the shots is provided in Appendix A and is partitioned, according to penetrator/target situation, into 23 series labelled ACT 1 through ACT 20 and ACT 1.1, ACT 3.1 and ACT 3.2. Twenty-two of these series (all but ACT 3.2, in which there is only one round with an acceptable level of yaw) were considered suitable for determination of  $V_s$ ,  $V_r$  curves and limit velocities. Derived  $V_s$ ,  $V_r$  curves for these 22 cases are given in Appendix B. A summary of processed behind-target fragmentation data for selected rounds is supplied in Appendix C. In Appendix D we attempt, in a sequence of rough sketches, to illustrate the pre-impact and residual penetrators in perspective with an appropriate target plate section for each round of ACT 19. Appendix E provides (for the later set of shots) for a comparison between derived  $V_s$ ,  $V_r$  curves and a predictive model that has been formulated for dealing with long rod penetrators.

\*The wide-ranging "Automatic Cannon Technology" project of which the effort of concern here was but a small part.



\* This was ZINVAR-processed and would have been AISI S7 Tool Steel but for the lack of molybdenum as an alloying element.

\*\* 90% W, 7% Ni, 3% Fe, swaged 24Z

FIGURE 1. NOMINAL PENETRATOR CHARACTERISTICS

This program has unfolded in three phases involving distinctly different time periods, different range personnel and practices, and different project managers; such diversity has regrettably and inescapably been adverse to an orderly, coherent, productive effort. It is, for example, exceedingly difficult now to adjudge the quality of data generated early in the program, to interpret cryptic notes on old data sheets, or retrieve misplaced information. The case for standardization in data organization and in testing is clear.

## II. RESULTS AND COMMENTS

The experimental setup and multiple flash x-ray system used to record ballistic performance data are described in BRL Technical Note 1634<sup>1</sup>. A summary of ballistic limits and geometries for the various test series is given in Table I. Minutiae are to be found in Appendices A-E. In perusing the data, the following remarks should be kept in mind:

- a. The parameters  $a$ ,  $p$ , and  $V_g$  of Table I are derived from the "good" data of the series. By a "good" round is meant a shot for which total initial penetrator yaw does not exceed 2.5°.
- b. The penetrators in ACT 1 through ACT 15 (including ACT 1.1, ACT 3.1 and ACT 3.2) were of monolithic AISI-S7 tool steel having finished hardness of  $R_c$  55. The steel for ACT 16 through ACT 20 was also of finished hardness  $R_c$  55 and would have been AISI-S7 but for the inadvertent lack of molybdenum as an alloying agent.
- c. ACT 16 and ACT 19 employed monolithic steel penetrators; ACT 17 penetrators were of two-piece steel (steel cap on steel stem); and, in ACT 18 and ACT 20, the penetrators were steel ( $R_c$  55) with tungsten alloy caps ( $R_c$  42).
1. The steel used in rounds 231 through 268 (ACT 16 through ACT 20) was VIMVAR\* processed. The difference made by this change in processing is especially noticeable when comparing data for the steel used in some of the penetrators of ACT 11 had a very high inclusion rate (Figure 2), contributing no doubt to the large scatter in the data for this series. ACT 19 is a recreation of ACT 11 (with the slight difference in penetrator material noted previously and the different processing).

---

<sup>1</sup>Grabarek, C. and Herr, L., "X-Ray Multi-Flash System for Measurement of Projectile Performance at the Target", BRL TN 1634, September 1966 (AD 377657).

\*Vacuum Induction Melt, Vacuum Arc Remelt.

Table I. Ballistic Limit Velocities and Series Characteristics

Series	M	D	L/D	$\theta$	T	H	$V_x$	a	p
ACT 1	64.8	1.30	5	0	1.91	364	720	0.94	2.9
ACT 2	64.9	1.30	5	0	2.54	340	906	0.70	3.3
ACT 3	64.8	1.30	5	0	3.18	321	1130	1.00	2.0
ACT 4	64.8	1.30	5	0	3.81	321	1304	1.00	2.9
ACT 5	64.8	1.30	5	0	5.08	286	1568	1.00	1.8
ACT 6	64.8	1.30	5	60	2.54	340	1451	0.80	2.0
ACT 7	63.7	1.02	10	0	1.91	364	798	1.00	2.7
ACT 8	63.8	1.02	10	0	2.54	341	916	0.83	3.2
ACT 9	63.7	1.02	10	0	3.81	321	1234	0.93	3.8
ACT 10	63.7	1.02	10	0	5.10	288	1411	1.00	2.2
ACT 11	64.0	1.02	10	60	2.54	340	1296	1.00	1.9
ACT 12	64.7	0.81	20	0	2.54	340	997	1.00	3.3
ACT 13	64.7	0.81	20	0	3.81	321	1157	1.00	3.7
ACT 14	64.6	0.81	20	0	5.08	291	1296	1.00	2.8
ACT 15	64.5	0.81	20	60	2.54	340	1234	1.00	3.1
ACT 16	64.2	1.02	10	45	2.55	364	1095	0.94	3.4
ACT 17	64.1	1.02	10	0	3.83	331	1216	1.00	3.0
ACT 18	64.4	0.97	10	0	3.82	331	1097	1.00	3.4
ACT 19	64.3	1.02	10	60	2.54	358	1225	0.80	3.3
ACT 20	64.4	0.97	10	60	2.53	372	1229	0.82	5.4
ACT 1.1	64.7	0.81	20	0	1.91	364	879	1.00	5.8
ACT 3.1	64.7	0.81	20	0	3.18	321	1045	0.90	3.7

M - penetrator mass (g)

D - penetrator diameter (cm)

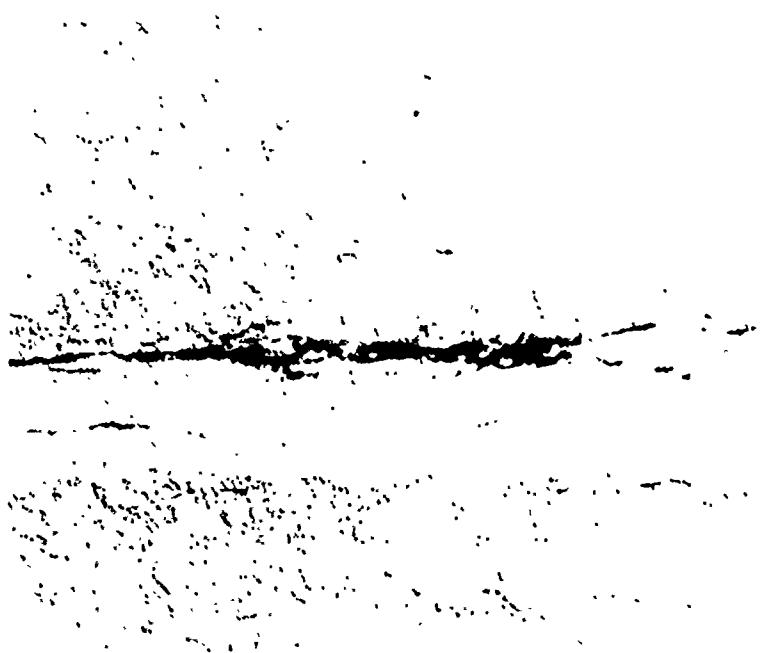
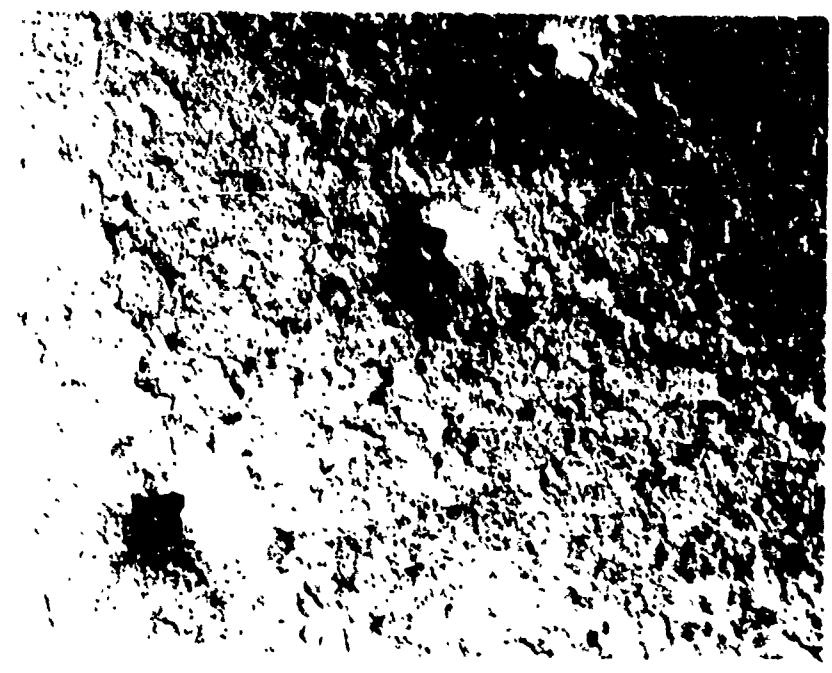
L - penetrator length (cm)

 $\theta$  - obliquity

T - target thickness (cm)

H - target hardness (BHN)

 $V_x$ , a, p - parameters derived from  $V_s$ ,  $V_r$  data and defined in Appendix B



C. Bearcat Trans. (Edge) 400X (P.L.)

C. Bearcat Long. 400X (P.L.)

Figure 2. Steel with High Inclusion Rate

e. Finally, we note that the  $V_s$ ,  $V_r$  tests from ACT 16 on are significantly more economical of shots .. there were no shots lost (in the sense of being unsuitable for deriving a  $V_s$ ,  $V_r$  curve) due to excessive yaw. Indeed, in rounds 231 through 268, only one round (234) proved unsuitable.

### III. FUTURE PLANS

Further exploitation of the data generated in the ACT program continues. A report on penetrator residual mass variation with impact energy and target geometry may be anticipated.

### ACKNOWLEDGMENT

The author acknowledges the contributions of Messrs. Antonio J. Ricchiazzi and Peter G. Morfogenis, the previous principal investigators for the terminal ballistics portion of the ACT Program. Thanks are also due to Messrs. John Koval and Dale Smith under whose supervision the experimental data was generated in the Terminal Ballistics Division Small Caliber Ranges. Messrs. Frank Dubois, John Cullum and Robert Schnick, among others, assisted in the reduction of the data.

**APPENDIX A**  
**BASIC RAW DATA**

## APPENDIX A: BASIC RAW DATA

### Notation:

#	Round number
M	Penetrator mass, grams
L	Penetrator length, centimeters
D	Penetrator diameter, centimeters
T	Target thickness, centimeters
H	Target hardness, BHN
$\alpha$	Vertical penetrator yaw at impact, degrees
$\beta$	Horizontal penetrator yaw at impact, degrees
$\delta$	Total penetrator yaw at impact, degrees
$V_s$	Striking penetrator velocity (speed), meters/second
$V_r$	Residual penetrator velocity (speed), meters/second
$M'_r$	Recovered residual penetrator mass, grams
$M''_r$	Estimated (from radiographs) residual penetrator mass, grams
$\Delta$	Mass loss of target plate, grams
$\lambda$	Cone angle of residual penetrator path, degrees
$\phi$	Phase angle of residual penetrator path, degrees

- Indicates that item is not applicable; e.g., cone angle, etc.  
if  $V_r = 0$
- ^ Indicates that item is applicable but unknown

### Key to Remarks:

- 1 - Total yaw exceeds  $2\frac{1}{2}^\circ$ , round not used in  $V_\lambda$  determination
- 2 - Perforation but  $V_r$  not obtainable, round not used in  $V_\lambda$  determination
- 3 - Non-perforation, small bulge in rear target surface
- 4 - Non-perforation, large bulge in rear target surface
- 5 - Non-perforation, rear target surface fractured
- 6 - Rod slightly bent at launch
- 7 - Perforation, penetrator severely shattered
- 8 - Penetrator made from "dirty material"

ACT 1       $\theta = 0$       L/D = 5

#	M	L	D	T	H	$\alpha$	$\beta$	6	$V_S$	$V_R$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	Remarks
81	64.82	6.49	1.30	1.91	364	0.3	1.5	1.5	682	0	-	-	-	-	-	3
85	64.74	6.48	1.30	1.91	364	0.8	1.0	1.3	690	0	-	-	-	15	-	-
82	64.76	6.49	1.30	1.91	364	0.4	-1.2	1.3	721	81	^	^	50	^	^	-
80	64.59	6.48	1.30	1.91	364	0.7	0.4	0.8	748	384	^	43.0	40	12.1	315	-
79	65.01	6.48	1.30	1.91	364	-0.1	1.2	1.2	763	429	^	42.3	^	3.7	332	-
84	64.87	6.48	1.30	1.91	364	0.2	-1.3	1.3	809	609	^	46.7	55	3.4	304	-
83	65.03	6.48	1.30	1.91	364	0.7	2.6	2.6	917	548	^	42.2	^	2.6	306	1
85	64.77	6.47	1.30	1.81	364	-1.9	-1.9	2.7	1053	730	^	40.2	^	3.5	337	1

ACT 2       $\theta = 0$       L/D = 5

#	M	L	D	T	H	$\alpha$	$\beta$	6	$V_S$	$V_R$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	Remarks
20	65.03	6.47	1.30	2.54	340	-0.5	-1.5	1.6	853	0	-	-	-	29	-	3
19	64.98	6.49	1.30	2.54	340	-0.7	-2.7	2.8	879	249	22.3	30.0	45	7.9	4	1
18	64.68	6.48	1.30	2.54	340	1.9	-0.2	1.9	913	213	19.7	28.0	60	6.3	45	-
17	64.81	6.48	1.30	2.54	340	0.3	-0.7	0.8	942	363	17.8	26.1	45	7.0	16	-
16	65.07	6.48	1.30	2.54	340	0.6	0.9	1.0	986	367	28.1	33.0	103	6.8	42	-
15	64.81	6.47	1.30	2.54	340	0.1	0.4	0.4	987	474	25.4	33.6	62	1.7	276	-
14	65.06	6.48	1.30	2.54	340	-0.9	1.0	1.3	1022	525	^	36.6	69	6.0	182	-
13	64.98	6.48	1.30	2.54	340	-1.0	0.6	1.2	1124	624	^	^	55	^	^	-
12	65.02	6.48	1.30	2.54	340	0.6	1.0	1.2	1272	737	^	34.1	124	1.2	173	-

ACT 3       $\theta = 0$       L/D = 5

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$\frac{V_x}{V_T}$	$\frac{M'_T \cdot M''_T}{V_T}$	$\Delta$	$\lambda$	$\phi$	Remarks
48	64.90	6.48	1.30	3.18	321	0.0	-0.3	0.3	1111	0	-	-	-	-	-
47	64.71	6.48	1.30	3.18	321	-0.4	-0.7	0.8	1130	36	22.0	34.3	^	4.1	398
46	65.05	6.48	1.30	3.18	321	-2.0	-0.2	2.0	1137	65	^	34.4	^	11.2	210
45	64.52	6.47	1.30	3.18	321	-2.1	0.1	2.1	1164	223	22.9	18.4	^	3.8	46
44	64.78	6.47	1.30	3.18	321	-2.3	1.2	2.6	1185	314	18.8	26.8	65	5.1	104 1
43	65.00	6.48	1.30	3.18	321	-1.2	0.4	1.3	1241	465	^	31.4	65	7.9	168
42	64.73	6.47	1.30	3.18	321	0.6	-0.3	0.6	1304	661	^	34.2	46	3.5	276
41	64.38	6.47	1.30	3.18	321	0.6	0.4	0.7	1362	849	^	36.8	52	3.5	136
ACT 4 $\theta = C$ L/D = 5															
#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$\frac{V_x}{V_T}$	$\frac{M'_T \cdot M''_T}{V_T}$	$\Delta$	$\lambda$	$\phi$	Remarks
26	64.71	6.48	1.30	3.81	321	-1.8	0.0	1.8	1259	0	-	-	-	-	-
29	64.79	6.48	1.30	3.81	321	-1.8	0.5	1.8	1283	0	-	-	-	-	4
28	64.84	6.48	1.30	3.81	321	-0.2	0.4	0.4	1306	198	^	25.3	^	10.9	80
27	64.78	6.48	1.30	3.81	321	-0.6	-0.1	0.6	1330	514	21.3	25.3	22	5.2	222

#	M	θ = 0			L/D = 5			β	δ	V <sub>S</sub>	V <sub>R</sub>	M' <sub>R</sub>	M'' <sub>R</sub>	Δ	λ	φ	Remarks	
		L	D	T	H	α	-3.5	8.3	1455	C	-	-	40	-	-	-	-	-
105	64.91	6.47	1.31	5.08	203	7.5	-3.5	-2.8	3.1	1470	C	-	-	-	-	-	-	1.3
106	64.92	6.47	1.31	5.08	286	-1.5	-2.8	1.8	1.8	1503	O	-	-	-	-	-	-	1.3
107	64.75	6.48	1.29	5.08	286	0.0	1.8	2.6	2.6	1512	O	-	-	-	-	-	-	4.5
108	64.92	6.46	1.31	5.08	203	-0.5	2.5	2.6	1.6	1526	O	-	-	-	-	-	-	1.4
109	64.96	6.48	1.30	5.08	203	1.5	-0.5	1.1	1.1	1553	O	-	-	-	-	-	-	4
136	64.71	6.48	1.30	5.08	286	0.8	-0.8	3.2	3.2	1555	O	-	-	-	-	-	-	1
134	64.70	6.48	1.30	5.08	286	2.3	2.0	0.3	0.3	1566	O	-	-	-	-	-	-	1.4,5
132	65.03	6.47	1.30	5.08	302	-0.3	0.0	-1.5	5.0	1567	O	-	-	-	-	-	-	1
111	64.65	6.48	1.30	5.08	286	-1.5	5.0	5.2	1.7	1587	162	<	<	<	<	<	<	1.5
135	64.92	6.48	1.30	5.08	286	-0.8	-1.5	6.2	6.2	1585	O	-	-	-	-	-	-	1.5
120	64.45	6.48	1.30	5.08	293	-5.5	-2.8	5.8	5.8	1591	>	<	<	<	<	<	1.2	
110	64.95	6.48	1.30	5.08	286	-4.7	3.4	1.6	1.6	1595	143	<	<	<	<	<	<	1
125	64.92	6.47	1.30	5.08	302	-0.4	-16.3	16.8	16.8	1595	O	-	-	0	-	-	-	1.4
131	64.68	6.47	1.30	5.08	286	1.5	0.5	1.3	1.3	1611	298	<	<	27	<	<	<	1
114	64.22	6.42	1.30	5.08	286	6.0	11.0	12.5	12.5	1598	O	-	-	19	<	<	<	1.4
121	64.85	6.47	1.30	5.08	293	8.0	1.9	8.2	8.2	1611	298	<	<	16.9	<	<	<	1.4
126	64.63	6.48	1.30	5.08	302	3.8	7.8	8.7	8.7	1618	O	-	-	-	-	-	-	1
130	64.61	6.47	1.30	5.08	286	1.3	1.3	1.8	1.8	1620	O	-	-	60	<	<	<	1
128	64.84	6.47	1.30	5.08	302	0.7	0.7	0.7	0.7	1620	>	<	<	55	<	<	<	2
123	64.85	6.48	1.30	5.08	293	-4.4	-0.4	4.5	4.5	1629	<	<	<	45	<	<	<	1.2
122	64.73	6.48	1.30	5.08	293	-4.4	-0.4	4.5	4.5	1630	44	<	<	24	<	<	<	1

## ACT 5 (Continued)

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_s$	$V_T$	$M'_T$	$M''_T$	$\Delta$	$\lambda$	$\phi$	Remarks
118	64.97	6.38	1.30	5.08	302	1.0	-4.6	4.7	1630	474	84	7.7	56	1		
129	64.68	6.47	1.30	5.08	302	1.0	-4.8	4.9	1632	478	45	^	^	1		
112	64.87	6.48	1.30	5.08	286	-4.0	-0.5	4.0	1634	0	-	-	40	-	1.5	
119	65.22	6.48	1.30	5.08	302	1.2	-3.7	3.9	1638	^	^	-	45	^	1.2	
132	64.70	6.48	1.30	5.08	302	-2.5	-2.3	3.4	1639	262	^	^	59	^	1	
124	64.76	6.48	1.30	5.08	302	-2.5	-3.8	4.5	1642	0	-	-	4	-	1.4,5	
117	64.76	6.47	1.30	5.08	302	-1.7	-1.0	2.0	1644	308	^	9.9	58	^		
115	64.81	6.47	1.30	5.08	286	-0.9	-8.0	8.0	1646	128	^	10.5	40	3.7	277	
171	64.59	6.47	1.30	5.08	293	-2.0	-1.8	2.7	1650	373	^	^	38	^	1	
127	64.80	6.48	1.30	5.08	302	-2.3	1.3	2.6	1652	517	^	10.7	^	7.8	282	
116	64.84	6.48	1.30	5.08	302	-0.3	0.5	0.5	1667	391	^	15.7	106	15.0	0	
113	64.45	6.48	1.30	5.08	286	0.3	-0.8	0.8	1679	532	^	^	40	^	7	
172	64.62	6.48	1.30	5.08	302	0.0	-0.3	0.3	1832	973	^	^	65	^		
137	64.85	6.48	1.30	5.08	286	0.5	-0.5	0.7	1941	1283	^	^	40	^		

ACT 6		$\theta = 60$		$L/D = 5$		$\alpha$	$\beta$	$\delta$	$V_S$	$V_r$	$M_x'$	$M_T'$	$\Delta$	$\lambda$	$\phi$	Remarks
#	M	L	D	T	H											
189	64.98	6.48	1.30	2.54	340	3.3	2.8	4.3	1349	0	-	-	40	-	-	1
205	65.11	6.48	1.30	2.54	340	10.0	-1.3	10.1	1448	0	-	-	44	-	-	1
192	64.73	6.48	1.30	2.54	340	-2.0	0.3	2.0	1451	0	-	-	70	-	-	
191	63.84	6.38	1.30	2.54	340	0.5	3.5	3.5	1461	277	11.6	^	115	^	^	1
193	64.90	6.48	1.30	2.54	340	0.9	1.2	1.5	1462	197	^	16.2	119	44.0	0	
206	64.91	6.46	1.30	2.54	340	0.5	0.8	0.9	1505	348	14.1	^	148	^	^	
190	64.65	6.48	1.30	2.54	340	0.2	-0.1	0.2	1520	398	12.5	20.9	150	40.1	356	
199	64.54	6.48	1.30	2.54	340	2.6	-2.1	3.3	1546	568	^	16.9	165	34.7	13	1
198	64.71	6.47	1.30	2.54	340	-0.7	0.2	0.7	1558	351	^	17.5	195	41.7	0	
194	64.97	6.48	1.30	2.54	340	-5.0	-5.3	7.3	1565	0	-	-	88	-	-	1
200	64.86	6.48	1.30	2.54	340	-0.4	2.0	2.1	1575	453	^	15.1	180	39.1	0	
197	64.85	6.48	1.30	2.54	340	0.7	1.6	1.7	1576	470	^	17.4	140	39.5	0	
195	64.66	6.48	1.30	2.54	340	3.0	4.7	5.6	1581	^	^	^	112	^	^	1,2
203	64.75	6.47	1.30	2.54	340	-2.8	-1.3	3.1	1712	704	^	12.1	175	26.8	17	1,7
201	64.39	6.48	1.30	2.54	340	2.0	7.6	7.8	1753	901	^	15.0	215	21.3	346	1
204	64.60	6.44	1.30	2.54	340	0.5	-1.2	1.3	1841	948	^	15.1	235	29.8	2	

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_s$	$V_r$	$M'_r \cdot M''_z$	$\Delta$	$\lambda$	$\phi$	Remarks
66	63.90	10.24	1.02	1.91	364	-1.5	0.8	1.7	625	0	-	-	7	-	-
67	63.88	10.15	1.02	1.91	364	-0.5	-0.5	0.7	671	0	-	-	11	-	-
68	63.95	10.15	1.02	1.91	364	-1.8	-0.8	1.9	738	0	-	-	17	-	-
72	63.55	10.13	1.02	1.91	364	-0.3	0.5	0.6	751	0	-	-	21	-	3
87	63.53	10.15	1.02	1.91	364	0.5	-1.3	1.3	783	0	-	-	5	-	-
73	63.89	10.13	1.02	1.91	364	0.8	0.3	0.8	785	0	-	-	~	-	3
75	63.80	10.16	1.02	1.91	364	0.0	1.0	1.0	789	0	-	-	10	-	-
78	63.75	10.17	1.02	1.91	364	0.0	-0.5	0.5	792	0	-	-	10	-	-
74	63.74	10.15	1.02	1.91	364	.8	-0.5	0.9	800	0	-	-	~	-	3
71	63.42	10.15	1.02	1.91	364	-0.2	0.0	0.2	801	379	30.8	31.3	~	6.3	240
69	63.80	10.19	1.02	1.91	364	-0.3	-0.3	0.4	811	0	-	-	17	-	-
88	63.67	10.16	1.02	1.91	364	2.1	-1.2	2.5	828	493	~	28.9	46	11.4	312
70	63.82	10.19	1.02	1.91	364	0.0	1.2	1.2	852	467	~	39.2	42	2.4	358
77	63.60	10.16	1.02	1.91	364	-0.1	1.1	1.1	1002	712	~	42.4	40	0.6	164
76	63.69	10.16	1.02	1.91	364	0.5	0.7	0.9	1361	1229	~	22.5	65	0.8	111

ACT 8		$\theta = 0$		L/D = 10												Remarks		
#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$V_R$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	-	-	-
10	63.62	10.16	1.02	2.54	340	-2.0	0.0	2.0	915	0	-	-	41	-	-	-	3	
8	63.57	10.16	1.02	2.54	340	2.0	5.3	5.6	930	0	-	-	33	-	-	-	1,3	
11	63.60	10.16	1.02	2.54	340	-	-	-	937	0	-	-	14	-	-	-	1,3	
9	63.63	10.16	1.02	2.54	340	-1.2	-0.8	1.4	955	432	23.2	25.3	50	9.1	179			
7	63.67	10.16	1.02	2.54	340	0.8	-	-	956	246	19.3	21.6	60	3.1	29	1		
6	63.52	10.15	1.02	2.54	340	-0.4	-0.5	4.5	984	317	24.7	26.7	48	3.4	155	1		
5	64.48	10.16	1.02	2.54	340	-1.2	-1.6	2.0	1053	594	25.8	30.8	50	9.5	262			
4	63.57	10.16	1.02	2.54	340	-0.7	1.4	1.6	1103	690	32.7	36.1	65	1.6	133			
3	63.55	10.16	1.02	2.54	340	-2.1	2.8	4.2	1137	753	31.6	35.6	67	6.3	141	1		
1	63.63	10.16	1.02	2.54	340	-1.7	-0.6	1.8	1219	910	-	39.1	82	2.9	191			
ACT 9		$\theta = 0$		L/D = 10												Remarks		
#	M	I	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$V_R$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	-	-	-
35	63.58	10.16	1.02	2.81	321	-1.0	0.5	1.1	1195	0	-	-	15	-	-	-	4,5	
34	63.56	10.16	1.02	3.81	321	-1.3	-2.3	2.6	1211	128	19.0	21.0	31	12.4	290	1		
33	63.63	10.16	1.02	3.81	321	-1.0	1.0	1.4	1237	313	12.1	15.0	30	6.0	78			
32	63.56	10.16	1.02	3.81	321	-0.5	0.7	0.8	1243	501	18.5	23.0	20	7.4	112			
31	63.58	10.17	1.02	3.81	321	-0.1	0.9	0.9	1366	907	20.5	21.8	26	11.3	179			
30	63.61	10.15	1.02	3.81	321	5.6	2.6	6.1	1384	868	24.4	27.2	47	12.4	18	1		

ACT 10     $\theta = 0$  $L/D = 10$ 

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_{S_r}$	$M_{T_r}'$	$M_T''$	$V_{T_r}$	$M_T'$	$\Delta$	$\lambda$	$\phi$	Remarks
94	62.94	10.26	1.02	5.16	302	-7.6	-3.1	8.2	1294	0	-4	-	-	-	-	-	1
100	63.57	10.17	1.03	5.21	286	9.1	2.2	9.3	1312	0	-	-	17	-	-	-	1
95	64.33	10.17	1.03	5.44	293	-3.7	-7.5	6.4	1318	0	-	-	-	-	-	-	1
98	63.65	10.06	1.04	5.38	286	4.5	-1.7	4.8	1374	0	-	-	-	-	-	-	2
142	64.30	10.16	1.02	5.08	286	0.5	0.3	0.6	1383	0	-	-	-	-	-	-	3
147	60.85	10.15	0.97	5.08	286	-0.3	1.5	1.5	1402	0	-	-	-	-	-	-	1
99	63.73	10.16	1.02	5.38	286	-2.7	7.6	8.0	1405	0	-	-	-	-	-	-	2
145	64.24	10.16	1.02	5.08	286	-0.8	0.3	0.8	1410	^	-	-	-	-	-	-	4
142	64.00	10.17	1.02	5.08	286	0.3	1.0	1.0	1414	290	-	-	-	-	-	-	4.5
141	64.03	10.14	1.02	5.08	286	-2.0	0.8	2.1	1416	0	-	-	-	-	-	-	4.5
146	64.28	10.17	1.02	5.08	286	-2.3	-0.3	2.3	1418	0	-	-	-	-	-	-	1
144	63.71	10.15	1.01	5.08	286	0.5	0.5	0.7	1422	255	-	-	-	-	-	-	2
140	64.31	10.15	1.02	5.38	286	0.0	-0.5	0.5	1422	375	-	-	-	-	-	-	2
102	63.56	10.17	1.03	5.21	302	-1.0	1.0	1.4	1439	^	-	-	-	-	-	-	2
139	64.18	10.16	1.02	5.08	286	0.0	-0.3	0.3	1450	251	-	-	-	-	-	-	1
138	64.10	10.17	1.02	5.08	286	-0.8	0.0	0.8	1454	628	-	-	-	-	-	-	1
103	63.73	10.06	1.02	5.21	302	0.5	0.5	0.6	1464	0	-	-	-	-	-	-	2
97	63.40	10.13	1.01	5.44	283	8.4	-7.6	11.3	1528	0	-	-	-	-	-	-	1
148	63.91	10.15	1.02	5.08	286	0.0	-0.3	0.3	1531	772	-	-	-	-	-	-	1
153	64.25	10.16	1.02	5.08	286	0.0	0.5	0.5	1765	1286	-	-	70	-	-	-	1

ACT 11     $\theta = 60$ 

L/D = 10

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_{S_x}$	$V_{T_x}$	$M'_x$	$M''_x$	$V_x$	$\Delta$	$\lambda$	$\phi$	Remarks
225	63.93	10.03	1.02	2.54	340	-1.0	-0.5	1.1	1268	0	-	-	-34	-	-	-	4,8
223	64.25	10.21	1.02	2.54	340	-	-	-	1294	0	-	-	-	23	-	-	1
216	63.91	10.06	1.03	2.54	340	0.5	-0.5	0.7	1304	367	16.3	-	-	78	<	<	4,8
218	64.00	10.19	1.02	2.54	340	-0.5	-1.3	1.4	1307	0	-	-	-	41	-	-	4,8
222	64.07	10.36	1.02	2.54	340	-1.3	0.5	1.4	1309	0	-	-	-	50	-	-	3,8
221	64.37	10.30	1.02	2.54	340	-1.8	-2.0	2.7	1310	0	-	-	-	55	-	-	1
220	63.86	10.11	1.03	2.54	340	0.0	0.8	0.8	1323	581	18.7	-	-	98	<	<	8
217	64.28	10.32	1.02	2.54	340	1.0	-0.5	1.1	1329	-	<	<	-	73	<	<	2,8
183	63.90	10.15	1.02	2.54	340	-0.8	-0.8	1.1	1333	0	-	-	-	40	-	-	4
177	64.01	10.16	1.02	2.54	340	-0.5	0.0	0.5	1339	0	-	-	-	42	-	-	4
185	64.30	10.15	1.02	2.54	340	1.5	0.3	1.5	1339	427	<	18.8	-	80	<	<	7,8
224	64.00	10.18	1.03	2.54	340	0.8	-0.8	1.1	1352	586	<	<	-	98	<	<	8
184	64.20	10.16	1.02	2.54	340	-0.3	0.0	0.3	1358	-	<	<	-	58	<	<	1
132	63.82	10.16	1.02	2.54	340	1.3	2.3	2.6	1361	151	<	15.6	-	76	<	<	1
180	63.68	10.16	1.02	2.54	340	-1.3	0.3	1.3	1361	212	<	7.8	-	65	<	<	1
186	64.10	10.15	1.02	2.54	340	-2.8	-0.8	2.9	1365	0	-	-	-	85	<	<	1
178	63.82	10.26	1.01	2.54	340	-1.0	-0.5	1.1	1366	-	<	<	-	85	<	<	1
181	64.16	10.16	1.02	2.54	340	-1.0	1.3	1.6	1370	171	<	12.0	-	155	<	<	8
179	63.72	10.17	1.02	2.54	340	0.0	-1.8	1.8	1398	678	<	16.4	-	70	<	<	1
226	63.99	10.15	1.02	2.54	340	0.3	-0.3	0.4	1504	907	<	12.8	-	111	<	<	8
234	63.47	10.17	1.02	2.54	364	-	-	-	1538	-	<	<	-	118	<	<	1

ACT 12     $\theta = 0$     L/D = 20

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_s$	$V_r$	$M_x'$	$M_x''$	$\Delta$	$\lambda$	$\phi$	Remarks
24	64.85	16.06	0.81	2.54	340	-0.8	0.5	0.9	990	0	-	-	28	-	-	-
25	64.63	16.07	0.81	2.54	340	0.0	0.6	0.6	998	125	19.8	19.8	32	3.9	224	
23	64.84	16.06	0.81	2.54	340	0.0	1.0	1.0	1011	428	26.7	25.2	28	19.3	311	
22	64.67	16.06	0.81	2.54	340	-0.7	0.6	0.8	1090	776	^	37.2	40	2.6	49	
21	64.70	16.06	0.81	2.54	340	-2.0	-0.5	2.0	1154	886	^	40.4	58	8.6	206	6

ACT 13     $\theta = 0$     L/D = 20

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_s$	$V_1$	$M_x'$	$M_x''$	$\Delta$	$\lambda$	$\phi$	Remarks
38	64.81	16.20	0.81	3.81	321	-0.3	1.0	1.6	1130	0	-	-	38	-	-	3
40	64.64	16.20	0.81	3.81	321	-1.3	0.8	1.5	1148	0	-	-	^	-	-	4
39	64.67	16.19	0.81	3.81	321	-1.1	0.5	1.2	1160	338	16.3	16.5	20	8.5	226	
37	64.73	16.19	0.81	3.81	321	-0.8	0.5	0.9	1234	834	29.5	29.7	17	4.5	153	
36	64.82	16.19	0.81	3.81	321	1.0	0.9	1.3	1327	1025	34.2	34.6	42	4.9	9	

AC1	14	$\theta = 0$	L/D = 20															Remarks
			M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$V_T$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	
173	63.99	15.99	0.87	5.08	302	0.0	0.3	0.3	1270	0	-	-	-	-	-	-	-	3
164	64.69	16.19	0.81	5.08	286	1.3	0.3	1.3	1296	0	-	-	-	-	-	-	-	4.5
162	64.76	16.19	0.81	5.08	286	0.3	0.8	0.8	1296	0	-	-	-	-	-	-	-	20
161	64.74	16.20	0.81	5.08	293	0.5	0.0	0.5	1297	469	-	13.4	40	-	-	-	-	2
158	64.75	16.20	0.81	5.08	286	-0.3	0.0	0.3	1315	215	-	11.1	26	-	-	-	-	2
174	64.86	16.06	0.82	5.08	293	0.0	0.3	0.3	1316	-	-	-	60	-	-	-	-	-
163	64.70	16.19	0.81	5.08	286	0.0	0.5	0.5	1318	383	-	13.3	13	-	-	-	-	-
165	64.89	16.19	0.81	5.08	286	0.0	1.0	1.0	1322	-	-	-	23	-	-	-	-	-
176	64.56	16.06	0.82	5.08	302	-0.5	0.0	0.5	1326	234	-	12.0	40	-	-	-	-	-
156	64.67	16.20	0.81	5.08	293	0.5	1.0	1.1	1327	502	-	16.7	5	-	-	-	-	-
175	64.63	16.06	0.81	5.08	293	-0.3	-1.0	1.0	1328	378	-	12.7	10	-	-	-	-	-
160	64.50	16.19	0.81	5.08	293	0.3	0.3	0.4	1329	-	-	-	0	-	-	-	-	-
166	64.86	16.19	0.81	5.08	286	0.0	0.3	0.3	1331	-	-	-	21	-	-	-	-	-
167	64.69	16.19	0.81	5.08	286	0.0	0.8	0.8	1347	796	-	19.0	10	-	-	-	-	-
159	64.75	16.20	0.81	5.08	286	0.0	0.3	0.3	1361	-	-	-	0	-	-	-	-	-
157	64.80	16.19	0.81	5.08	293	0.0	-0.3	0.3	1364	842	21.0	-	50	-	-	-	-	-
155	64.88	16.20	0.82	5.08	286	0.0	0.5	0.5	1400	948	-	23.7	43	-	-	-	-	-
168	64.77	16.19	0.81	5.08	293	-0.5	-0.5	0.7	1500	-	-	-	30	-	-	-	-	-
170	64.57	16.20	0.81	5.08	283	1.8	-0.5	1.8	1566	1183	-	23.5	-	-	-	-	-	-

ACT 15     $\theta = 6.0$     L/D = 20

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_s$	$V_r$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	Remarks
208	64.20	15.75	0.81	2.54	340	0.5	0.3	0.6	1227	0	-	-	38	-	-	-
211	64.63	16.05	0.81	2.54	340	-0.3	0.0	0.3	1234	0	-	-	26	-	-	-
215	64.33	16.05	0.81	2.54	340	0.5	-0.3	0.6	1242	707	22.3	^	46	^	^	-
213	64.40	16.04	0.81	2.54	340	0.8	-0.3	0.8	1260	735	21.3	^	48	^	^	-
214	64.56	16.04	0.81	2.54	340	0.0	0.8	0.8	1261	0	-	-	32	-	-	-
210	64.75	16.06	0.81	2.54	340	0.3	0.3	0.4	1263	564	^	^	69	^	^	-
212	64.62	16.05	0.81	2.54	340	1.0	1.0	1.4	1271	725	18.8	^	61	^	^	-

ACT 16     $\theta = 4.5$     L/D = 10

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_s$	$V_r$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	Remarks
240	64.37	10.25	1.02	2.55	364	-0.8	-0.1	0.3	1061	0	-	-	29	-	-	-
239	64.00	10.25	1.02	2.55	364	-0.9	-0.4	1.0	1096	199	8.1	10.7	51	35.0	0	-
238	64.11	10.25	1.02	2.55	364	-0.4	0.2	0.4	1138	536	11.8	14.2	0	21.6	356	-
232	64.31	10.24	1.02	2.56	364	1.1	1.0	1.5	1187	744	16.7	19.1	94	32.1	353	-
233	64.42	10.24	1.02	2.56	364	-0.9	0.0	0.9	1205	815	19.1	21.1	99	20.2	0	-
231	64.33	10.24	1.02	2.54	364	-0.9	-0.5	1.0	1213	857	17.7	19.1	69	15.0	356	-
235	64.31	10.24	1.02	2.56	364	0.5	0.5	0.7	1431	1166	30.3	30.2	120	6.0	354	-
234	64.29	10.24	1.02	2.56	364	1.0	0.6	1.2	1433	1161	29.5	31.0	113	8.9	354	-
237	64.40	10.25	1.02	2.55	364	-0.5	-2.1	2.1	1542	1280	30.0	32.4	129	5.7	43	-
236	63.88	10.25	1.02	2.56	364	0.8	-0.2	0.8	1828	1575	32.2	32.7	206	1.0	262	-

ACT 17		$\epsilon = 0$		$L/D = 10$												Remarks	
#	M	L	D	T	H	a	b	$V_S$	$V_R$	$M'_T$	$M''_T$	$\Delta$	$\lambda$	$\phi$			
246	63.82	10.22	1.02	3.84	321	-0.2	0.0	0.2	1196	0	-	53	-	-	-		
245	64.02	10.22	1.02	3.83	321	-0.2	0.0	0.2	1217	139	9.9	13.8	26	10.0	348		
241	64.22	10.24	1.02	3.85	340	-0.6	-0.3	0.6	1244	507	12.5	17.1	55	7.7	214		
242	64.15	10.23	1.02	3.83	321	0.2	0.8	0.8	1246	530	12.1	14.0	-	2.8	83		
243	64.30	10.23	1.02	3.81	340	-0.2	0.0	0.2	1462	1200	22.0	25.1	86	0.2	213		
244	64.09	10.24	1.02	3.83	340	-1.0	0.0	2.0	1809	1548	31.0	32.7	125	0.7	61		
ACT 18		$\epsilon = 0$		$L/D = 10$												Remarks	
#	M	L	D	T	H	a	b	$V_S$	$V_R$	$M'_T$	$M''_T$	$\Delta$	$\lambda$	$\phi$			
254	64.36	9.62	0.97	3.83	340	0.1	0.0	0.1	1095	0	-	-	-	-	-		
253	64.37	9.69	0.97	3.82	321	0.1	-0.1	0.2	1097	54	8.6	10.3	1	7.4	0		
252	64.73	9.69	0.97	3.81	340	0.2	-0.2	0.3	1097	-	8.1	-	9	-	-		
251	64.58	9.69	0.97	3.82	321	0.4	0.2	0.4	1125	478	11.6	10.7	17	4.3	299		
250	64.42	9.67	0.97	3.82	321	-0.4	0.2	0.5	1185	868	19.8	16.5	37	1.4	173		
249	64.44	9.69	0.97	3.83	332	0.5	-0.1	0.6	1257	1033	25.3	26.4	45	0.5	104		
247	64.00	9.68	0.97	3.84	321	-0.1	0.0	2.1	1258	1045	23.1	22.5	34	1.2	341		
248	64.40	9.67	0.97	3.83	321	-0.1	-0.3	0.4	1269	1047	26.6	30.5	54	0.7	28		
255	64.80	9.69	0.97	3.82	340	-0.5	0.3	0.6	1377	1194	28.2	29.0	70	0.7	249		
256	64.54	9.68	0.97	3.82	340	0.3	0.0	0.3	1627	1485	31.7	31.9	107	0.4	174		
257	64.28	9.68	0.97	3.83	340	-1.8	0.5	1.8	1789	1586	32.4	34.0	113	1.4	80		

## ACT 19    e = 60    L/D = 10

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$V_T$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	Remarks
264	64.36	10.25	1.02	2.54	364	-0.4	-0.5	1201	0	-	-	-	14	-	-	-
263	64.43	10.26	1.02	2.53	364	0.0	0.1	1227	204	8.6	8.5	68	39.3	0		
262	64.29	10.26	1.02	2.56	351	0.0	0.6	1282	509	13.6	15.0	97	37.3	0		
261	64.06	10.25	1.02	2.53	364	0.4	0.7	1360	768	20.7	22.4	96	23.0	1		
265	64.04	10.22	1.02	2.54	364	0.1	-0.2	1471	997	18.5	20.2	98	16.1	2		
260	64.34	10.25	1.02	2.55	340	-0.5	0.4	1489	903	19.6	20.1	118	11.7	2		
259	64.20	10.26	1.02	2.54	351	-0.8	0.1	1647	1145	16.8	18.3	156	5.2	6		
258	64.35	10.25	1.02	2.53	364	-	-	1800	1285	13.6	-	171	-	-		

ACT 20     $\theta = 60$     L/D = 10

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$V_T$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	Remarks
268	64.35	9.69	0.97	2.54	387	-0.8	0.5	1201	2	-	-	59	-	-	-	-
266	64.46	9.70	0.97	2.53	364	-0.1	0.1	1331	898	21.4	22.6	91	16.1	1		
267	64.42	9.69	0.97	2.53	364	-1.1	0.5	1758	1399	22.9	24.0	176	2.6	350		

ACT 1.1     $\theta = 0$     L/D = 20

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$V_T$	$M_T'$	$M_T''$	$\Delta$	$\lambda$	$\phi$	Remarks
89	64.84	16.19	0.81	1.91	364	0.0	0.5	856	0	-	-	-	-	-	-	4
92	64.57	16.19	0.81	1.91	364	0.5	0.8	865	0	-	-	128	-	-	-	-
91	64.68	16.19	0.81	1.91	364	-1.9	1.1	882	445	24.4	34	5.2	93	6		
93	64.65	16.19	0.81	1.91	364	-0.8	0.6	886	555	33.7	^	4.1	177			

ACT 5.1     $\theta = 0$               L/D = 20

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$V_T$	$M'_T$	$M''_T$	$\Delta$	$\lambda$	$\phi$	Remarks
56	64.67	16.19	0.81	3.18	321	-0.5	0.5	1022	0	-	-	-	-	-	-	4
59	64.73	16.19	0.81	3.18	321	-0.8	0.8	1.1	1025	0	-	-	-	-	-	6
57	64.76	16.19	0.81	3.18	321	-0.3	0.5	0.6	1038	0	-	-	-	-	-	4
60	64.63	16.19	0.81	3.18	321	0.5	0.8	3.9	1045	0	-	-	-	-	-	-
55	64.75	16.19	0.81	3.18	321	0.0	0.3	0.3	1061	503	25.0	^	^	^	^	-
50	64.72	16.19	0.81	3.18	321	^	^	1081	^	24.0	^	35	^	^	^	1.2
53	64.77	16.19	0.81	3.18	321	-0.2	0.8	0.8	1087	597	^	28.7	^	3.2	^	14

ACT 5.2     $\theta = 0$               L/D = 10

#	M	L	D	T	H	$\alpha$	$\beta$	$\delta$	$V_S$	$V_T$	$M'_T$	$M''_T$	$\Delta$	$\lambda$	$\phi$	Remarks
65	63.77	10.15	1.02	3.18	321	-0.6	0.8	1.0	1146	566	26.9	25.5	^	2.8	148	-
63	63.90	10.16	1.02	3.18	321	1.2	3.6	3.8	1185	684	^	32.6	25	11.1	70	1
61	63.60	10.19	1.02	3.18	321	-1.0	5.6	5.7	1198	623	20.8	21.0	^	19.4	101	1
64	63.57	10.15	1.02	3.18	321	-0.7	3.7	3.8	1201	638	^	29.1	35	8.0	70	1
62	63.69	10.19	1.02	3.18	321	-0.6	4.2	4.3	1214	662	^	22.4	^	11.3	84	1

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APPENDIX B

DERIVED  $V_s$ ,  $V_r$  CURVES

## APPENDIX B: DERIVED $V_s$ , $V_r$ CURVES

This section is comprised of the  $V_s$ ,  $V_r$  curves derived from the experimental data of Appendix A. The standard form used to represent dependence of residual velocity on striking velocity is

$$V_r = \begin{cases} 0, & \text{if } 0 \leq V_s \leq V_\ell \\ a(V_s^p - V_\ell^p)^{1/p}, & \text{if } V_s > V_\ell \end{cases}$$

with the constraints,  $p > 1$  and  $0 \leq a \leq 1$ .

Values for the limit velocity,  $V_\ell$ , and the other parameters,  $a$  and  $p$ , are derived via a non-linear least squares algorithm which extracts an optimal adaptation of the form to the data. For an elaboration on the above form and related methodology, see BRL Report 1852<sup>2</sup>. There is available at the Terminal Ballistics Division of the BRL a program in BASIC, called "Impact", which contains the algorithm and provides graphic capability; we have used this program to derive parameters for our various data sets and to generate the following figures.  $V_s$ ,  $V_r$  data corresponding to rounds for which the total yaw of the penetrator at impact exceeded  $2\frac{1}{2}^\circ$  was excluded from this analysis. In each figure "S" denotes the root mean square error associated with the fit of form to data.

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<sup>2</sup>Lambert, J. P. and Jonas, G. H., "Towards Standardization in Terminal Ballistic Testing: Velocity Representation", BRL Report 1852, January 1976 (AD A021389).

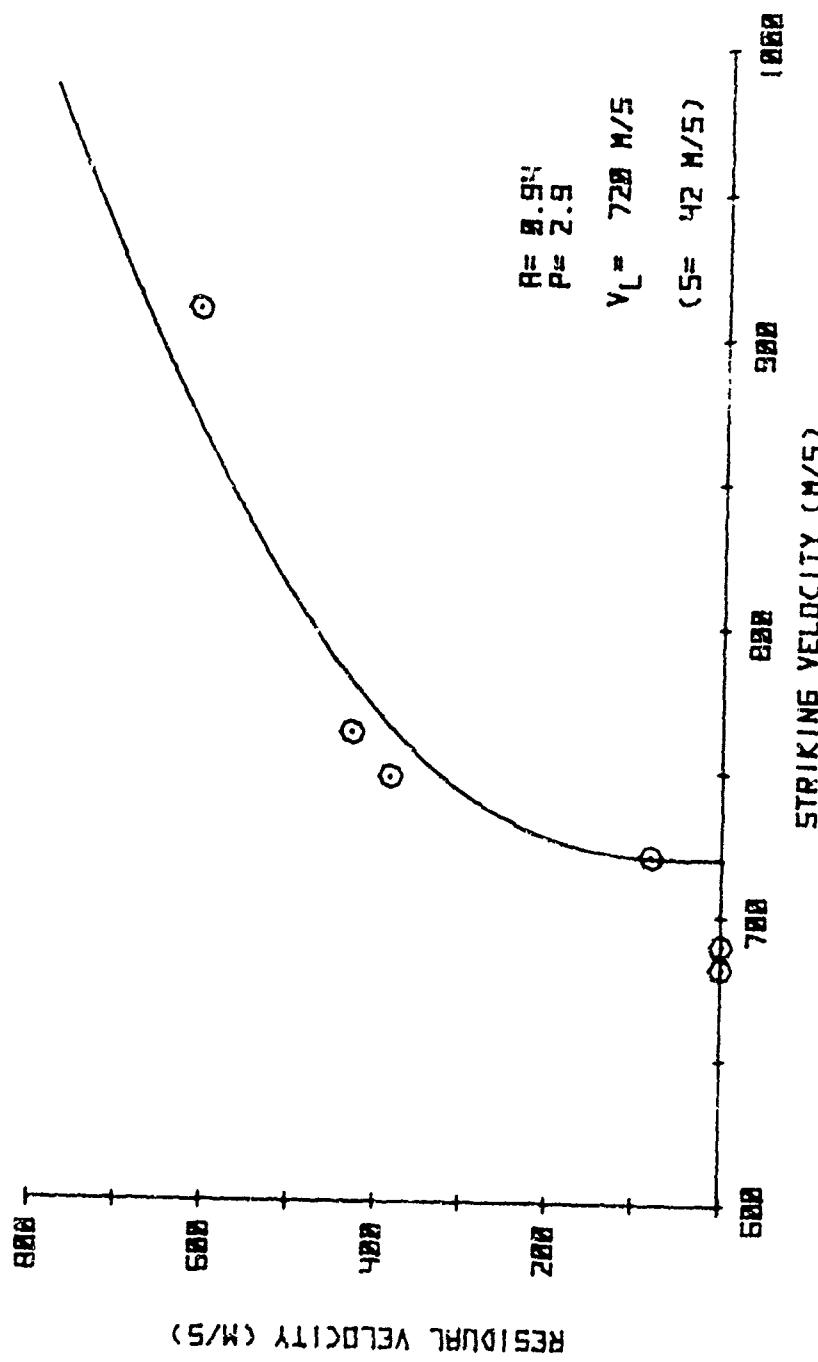


FIGURE B-1.  $V_S/V_R$  CURVE AND DATA FOR RCT I

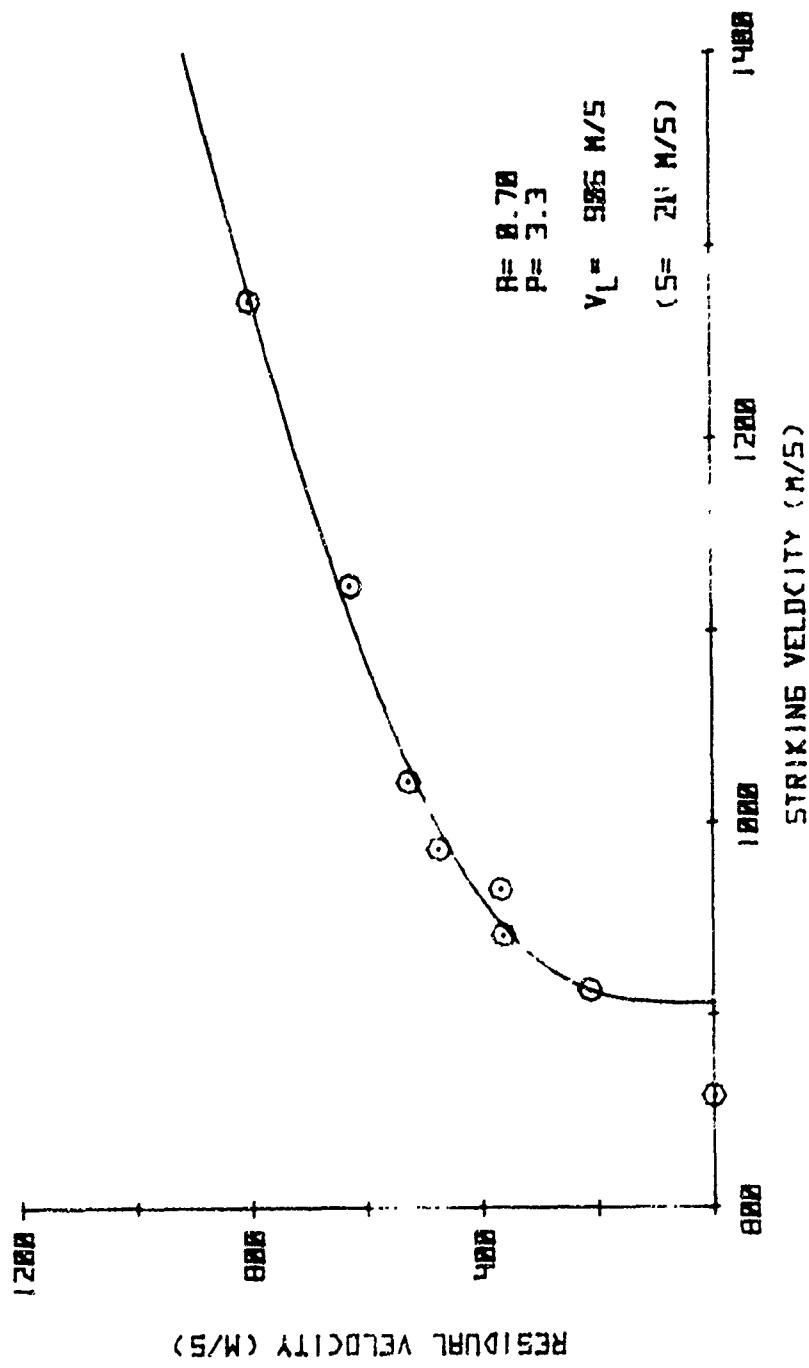


FIGURE B-2.  $V_S, V_R$  CURVE AND DATA FOR ACT 2

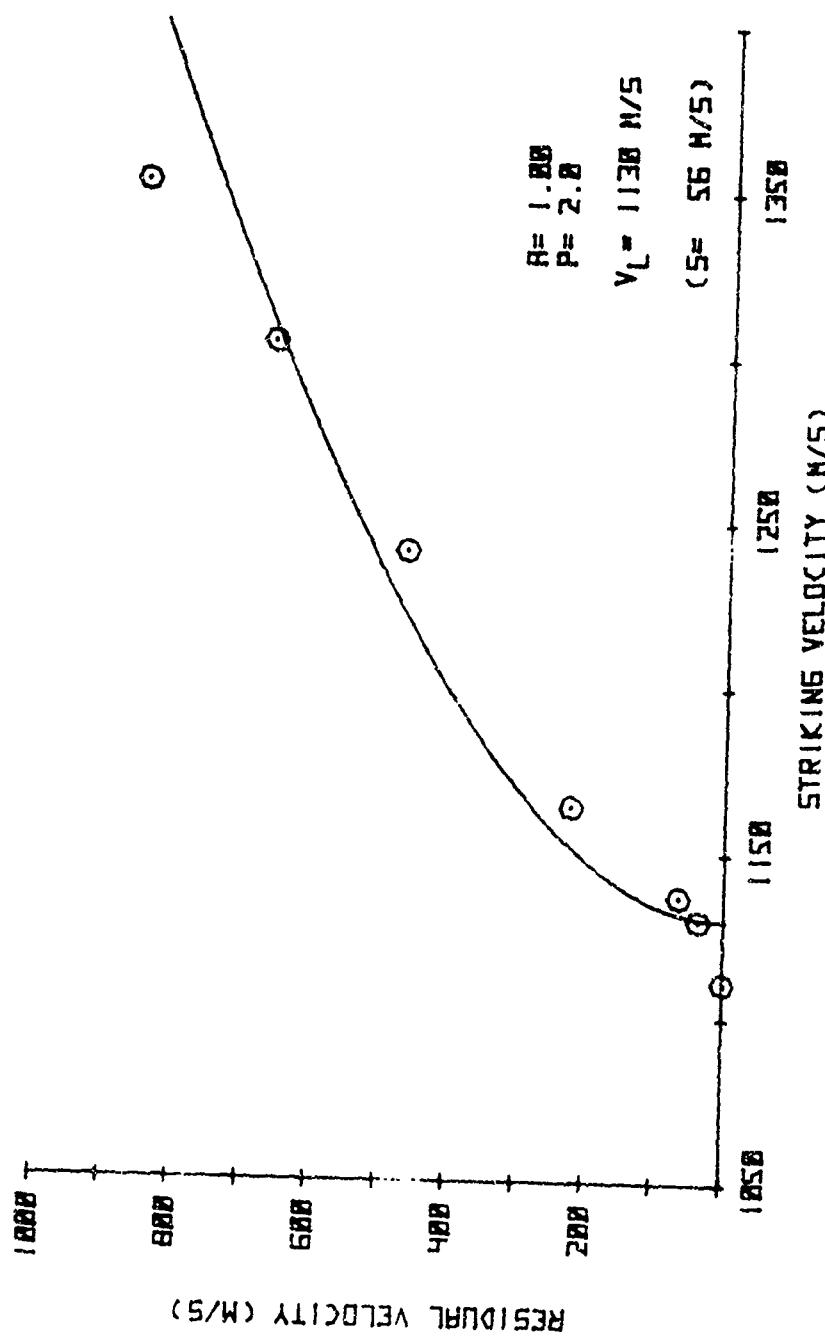


FIGURE B-3.  $V_S, V_R$  CURVE AND DATA FOR RCT 3

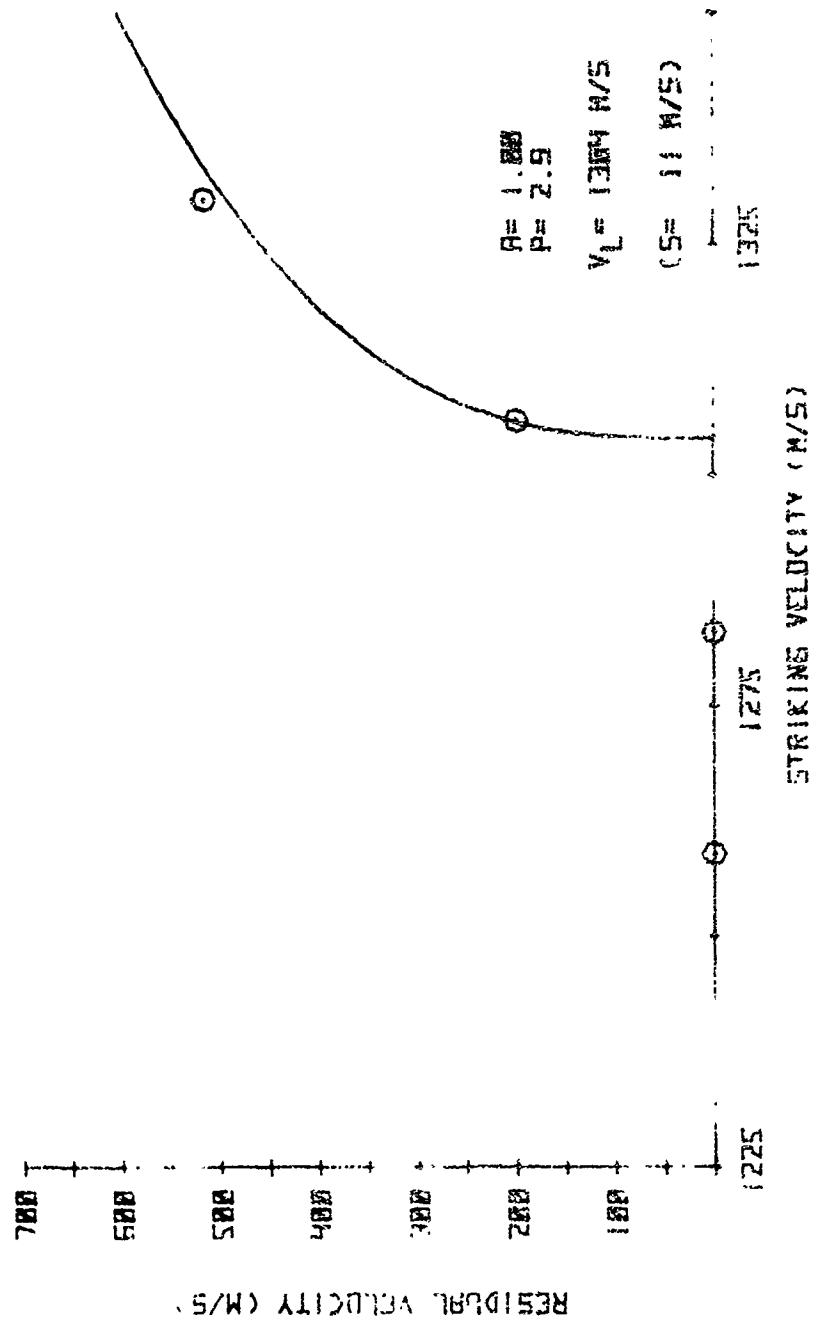


FIGURE B-4.  $V_s/V_p$  CURVE AND DATA FOR TEST 4

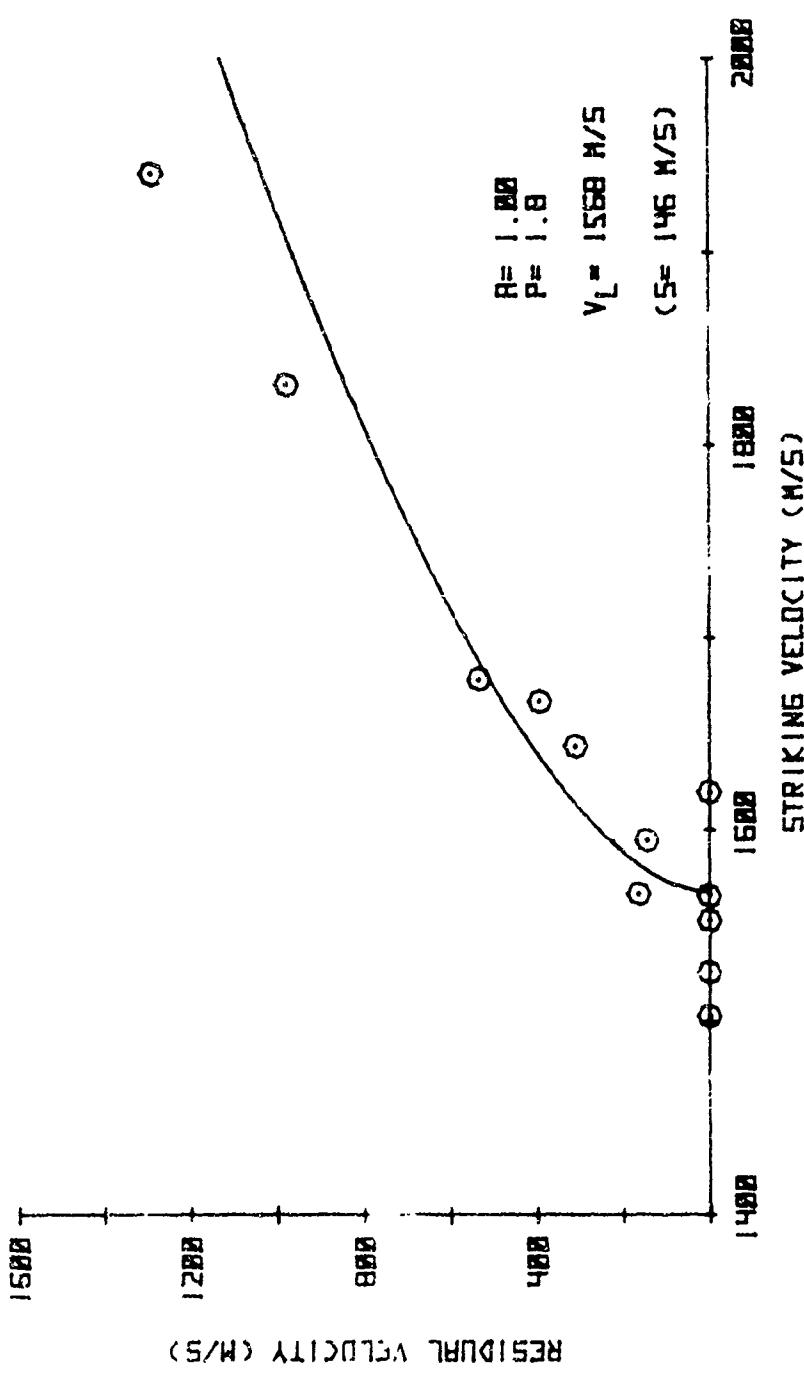


FIGURE B-5.  $V_S/V_R$  CURVE AND DATA FOR ACT 5

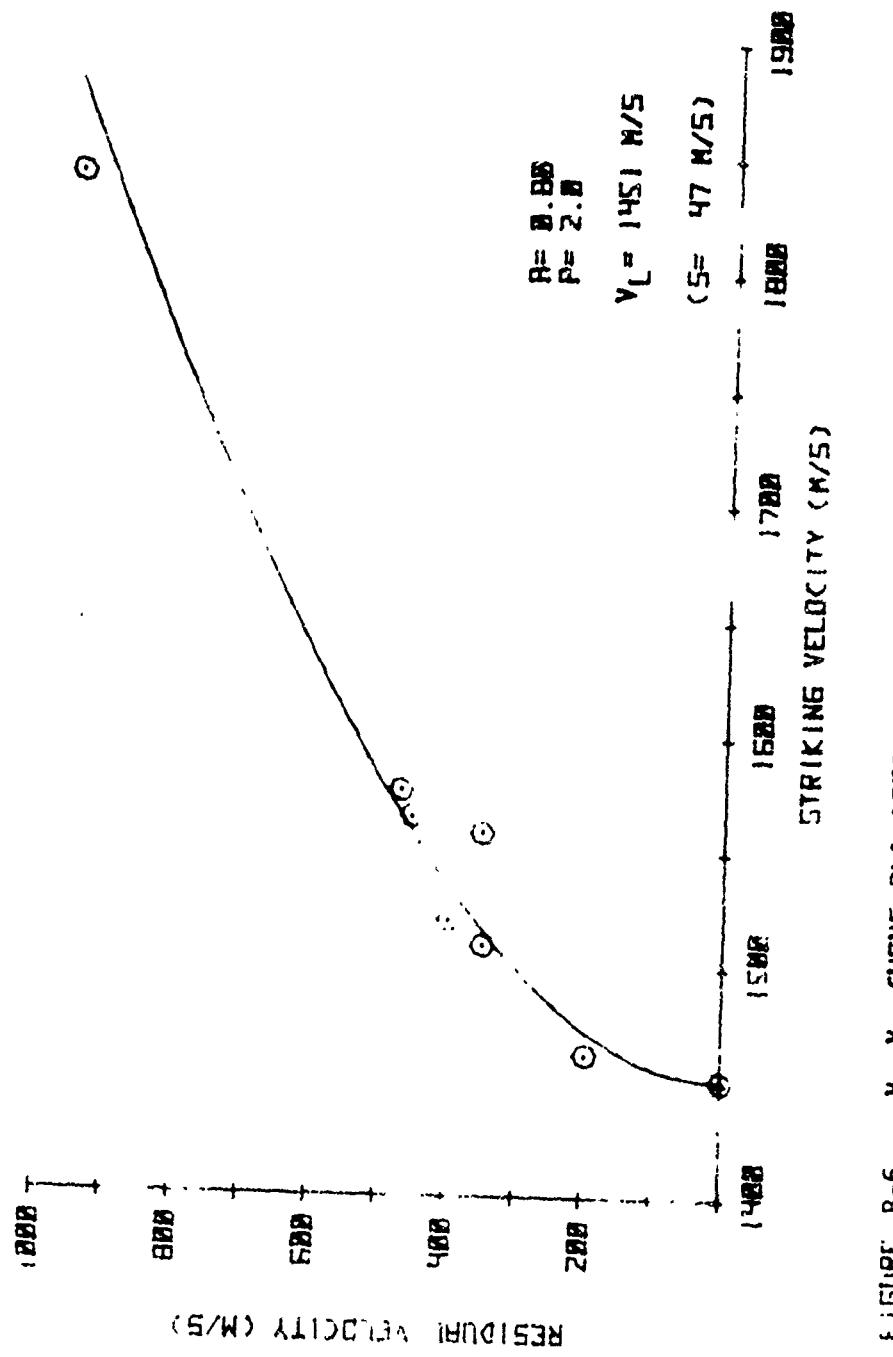


FIGURE B-6.  $V_L/V_R$  CURVE AND DATA FOR ACT 6

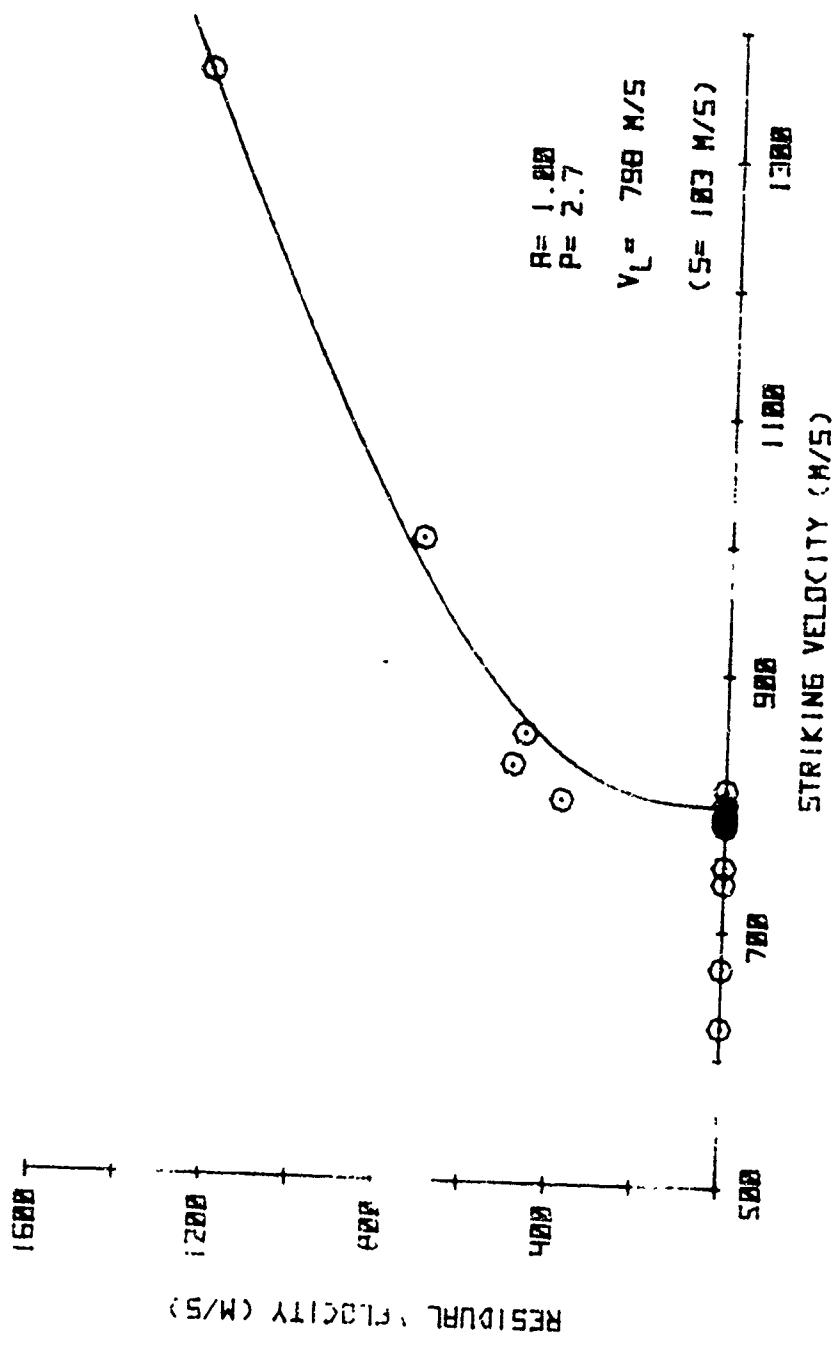
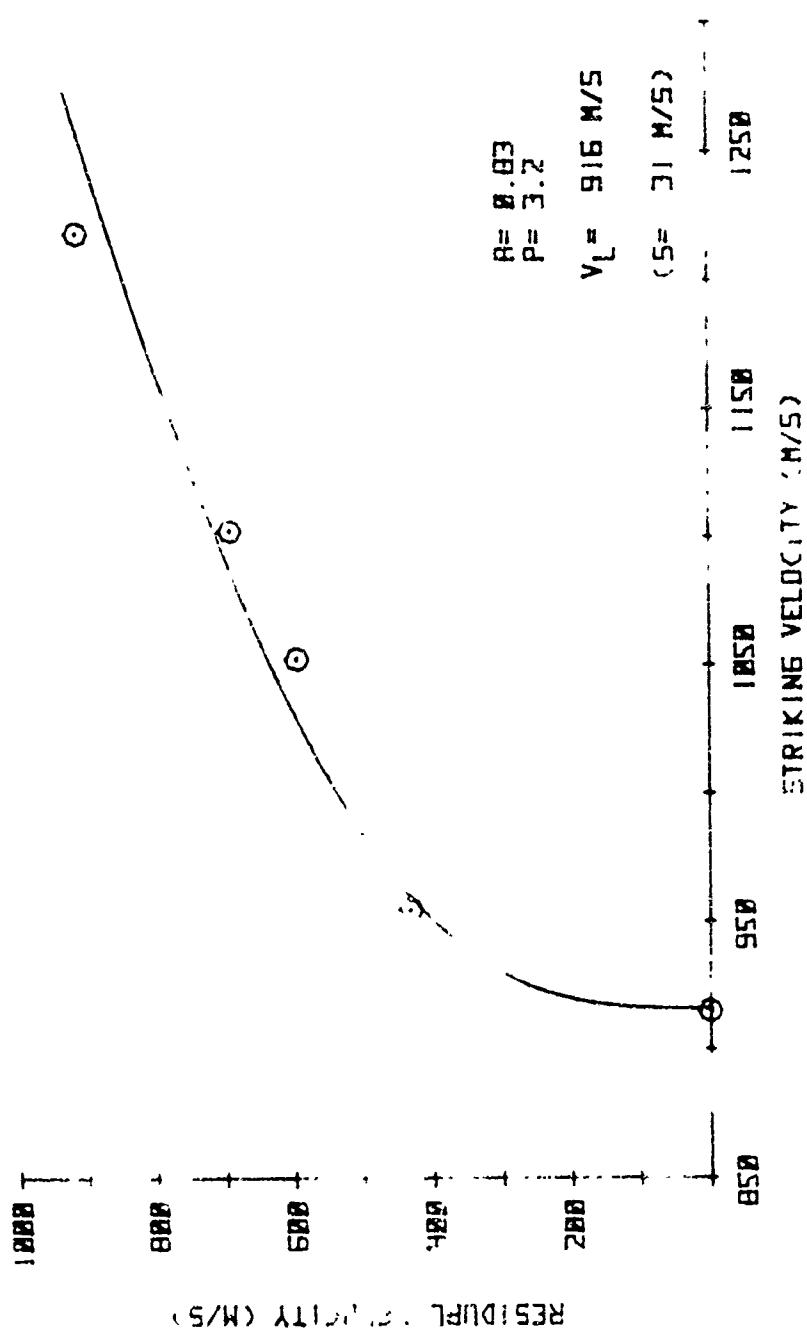


FIGURE 8-7.  $V_S$ ,  $V_R$  CURVE AND DATA FOR ACT 7

FIGURE B-8.  $V_S$ ,  $V_R$  CURVE AND DATA FOR RCT B



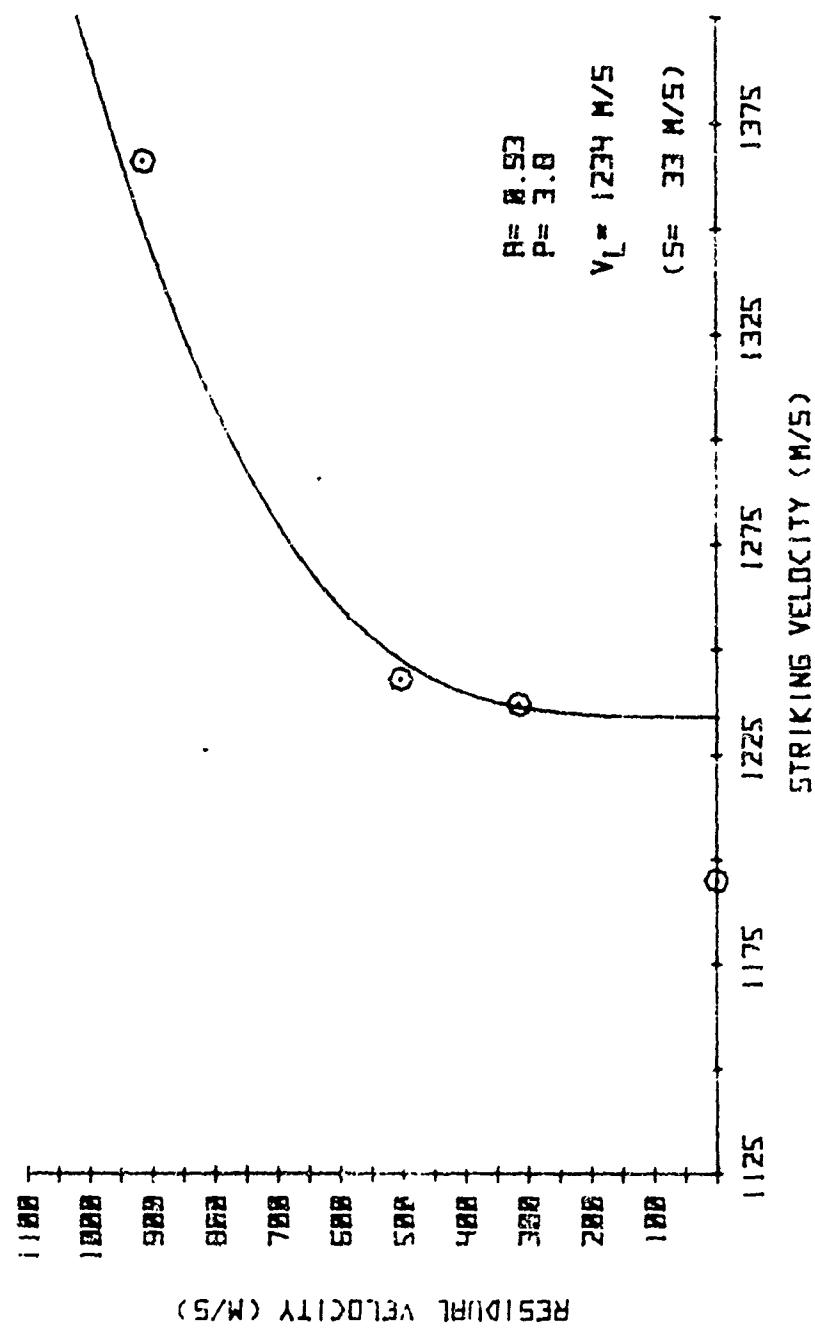


FIGURE B-9.  $V_s/V_R$  CURVE AND DATA FOR ACT 9

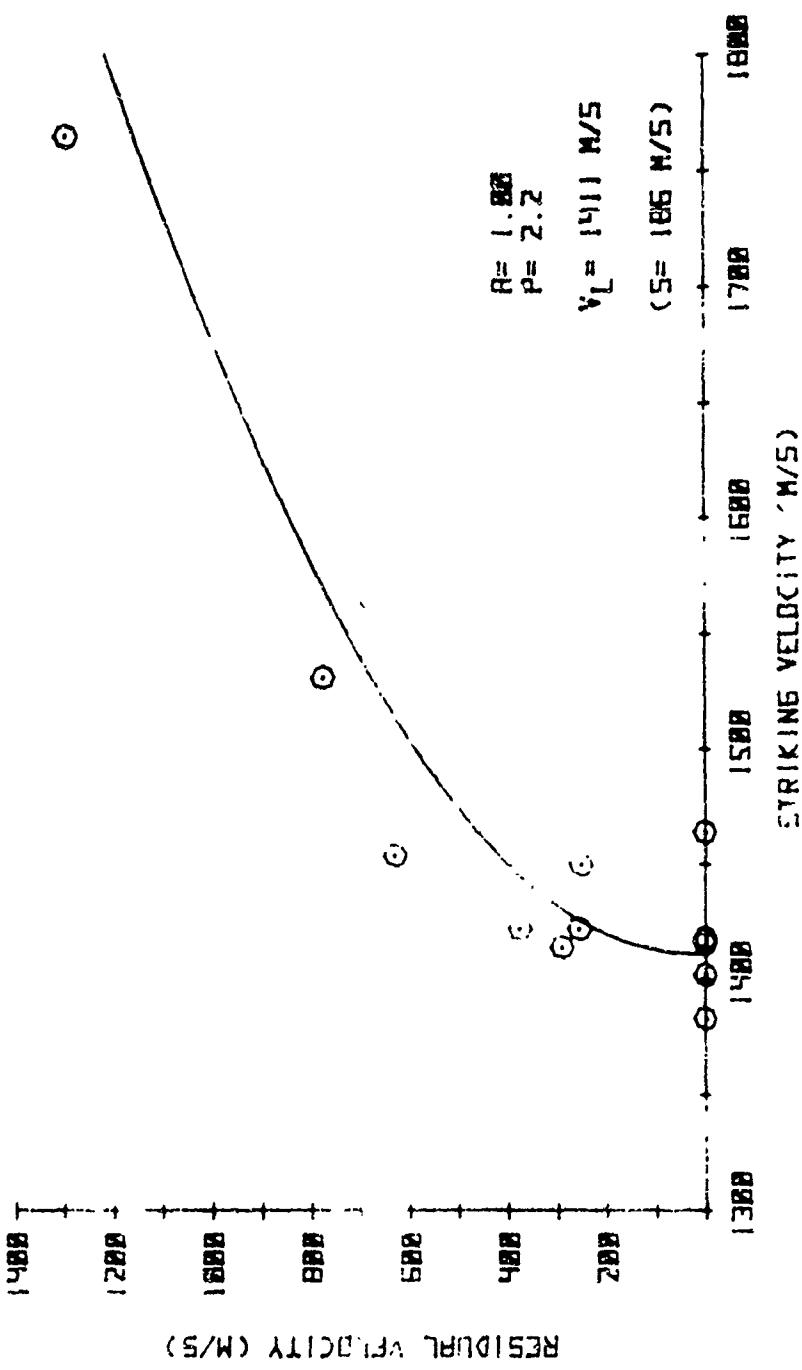
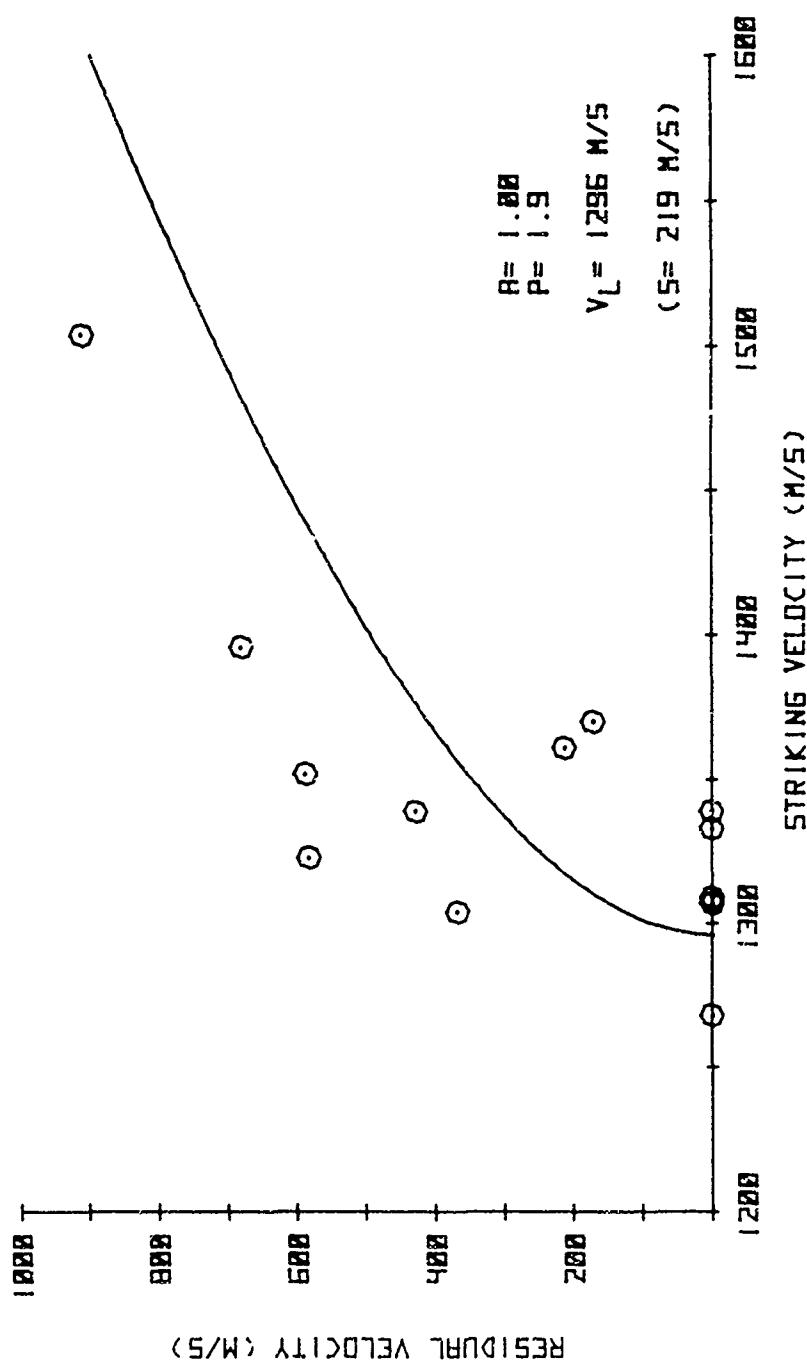


FIGURE B-10.  $V_S, V_R$  CURVE AND DATA FOR RCT 12

FIGURE B-11.  $V_S/V_R$  CURVE AND DATA FOR ACT II



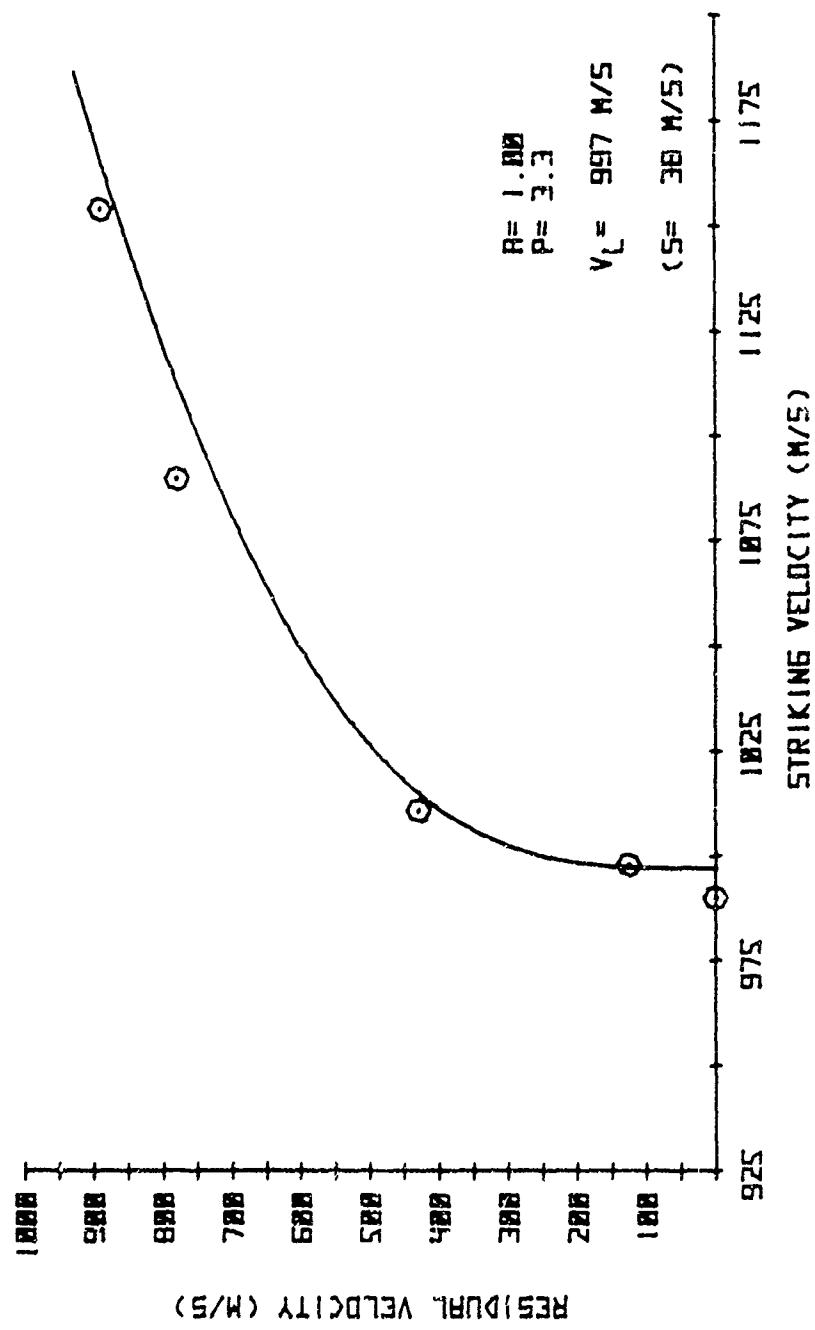


FIGURE B-12.  $V_S, V_R$  CURVE AND DATA FOR RCT 12

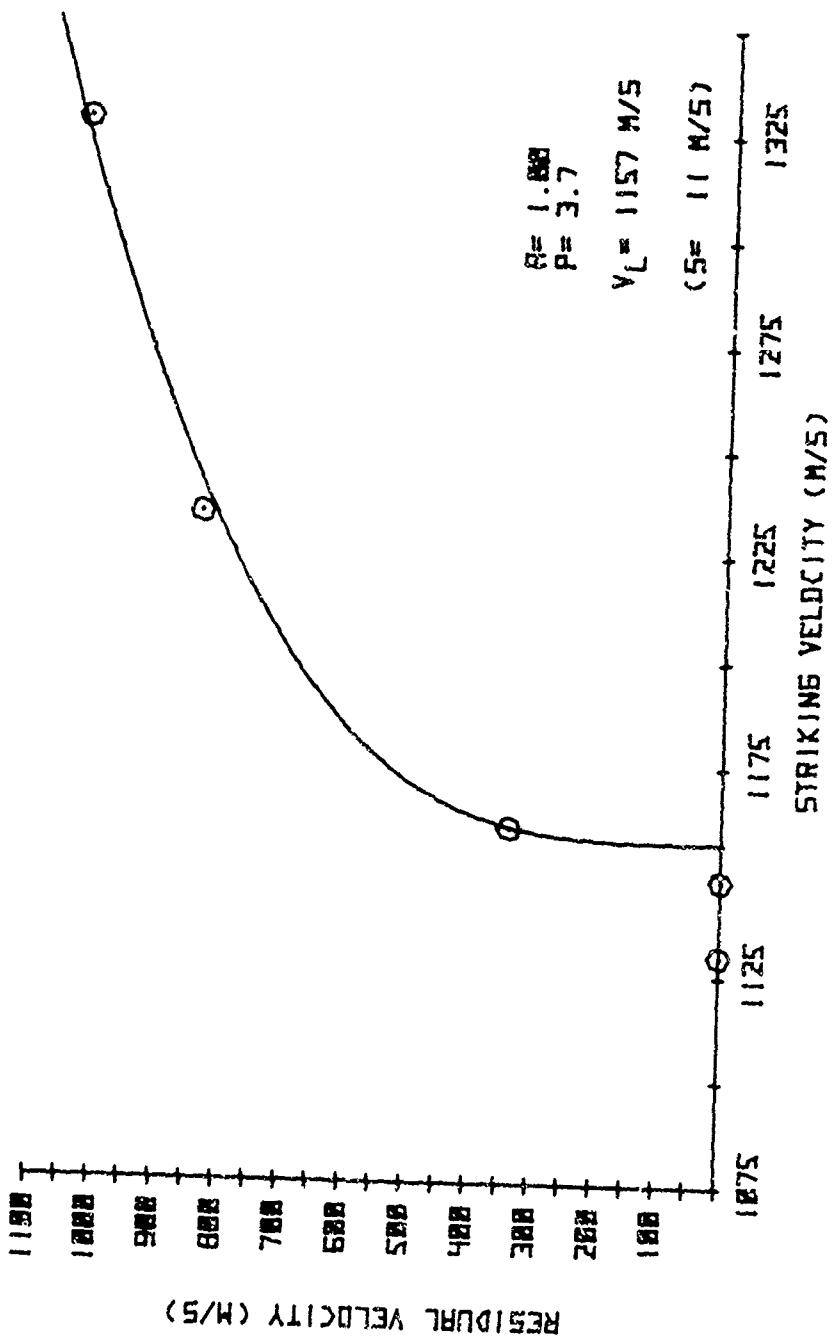


FIGURE B-13.  $V_S, V_R$  CURVE AND DATA FOR RCT 13

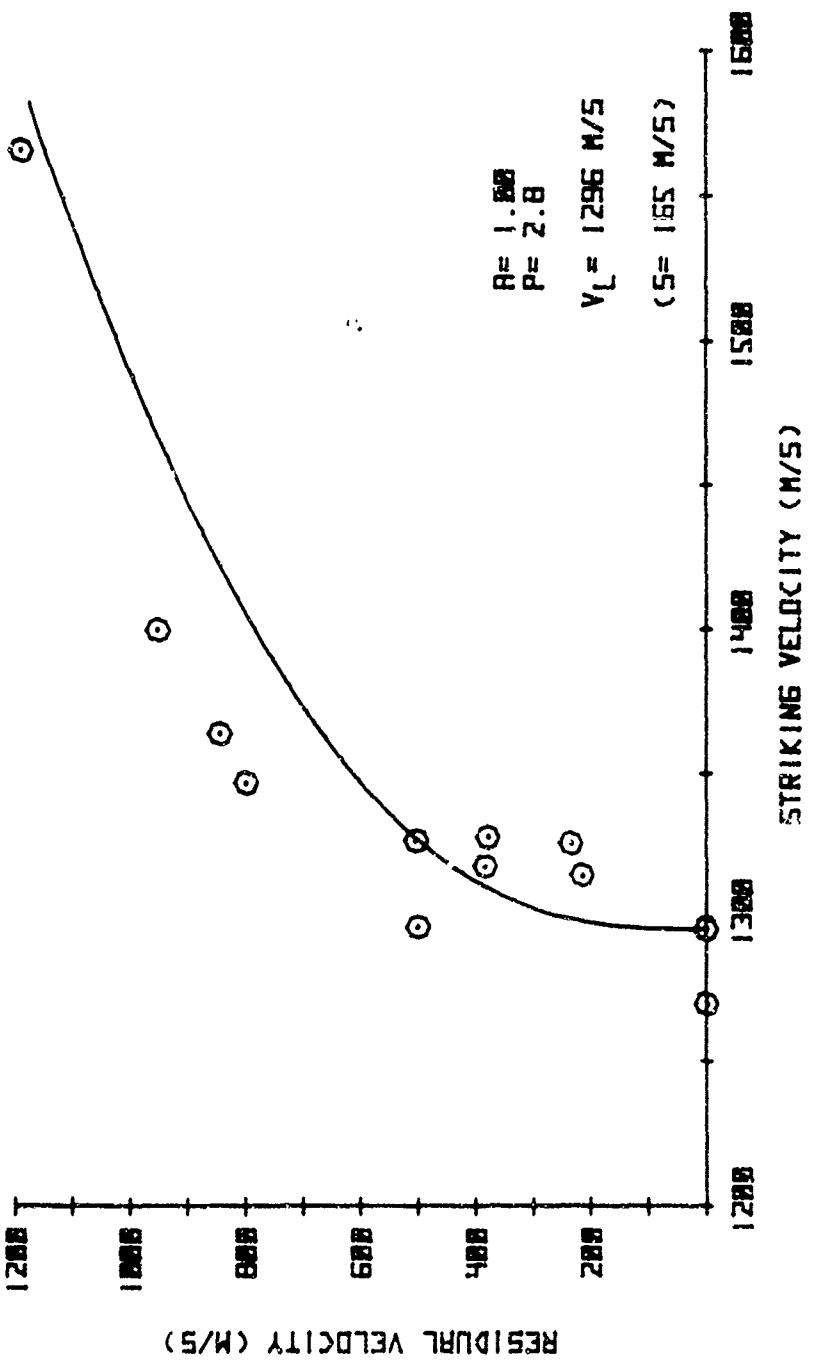
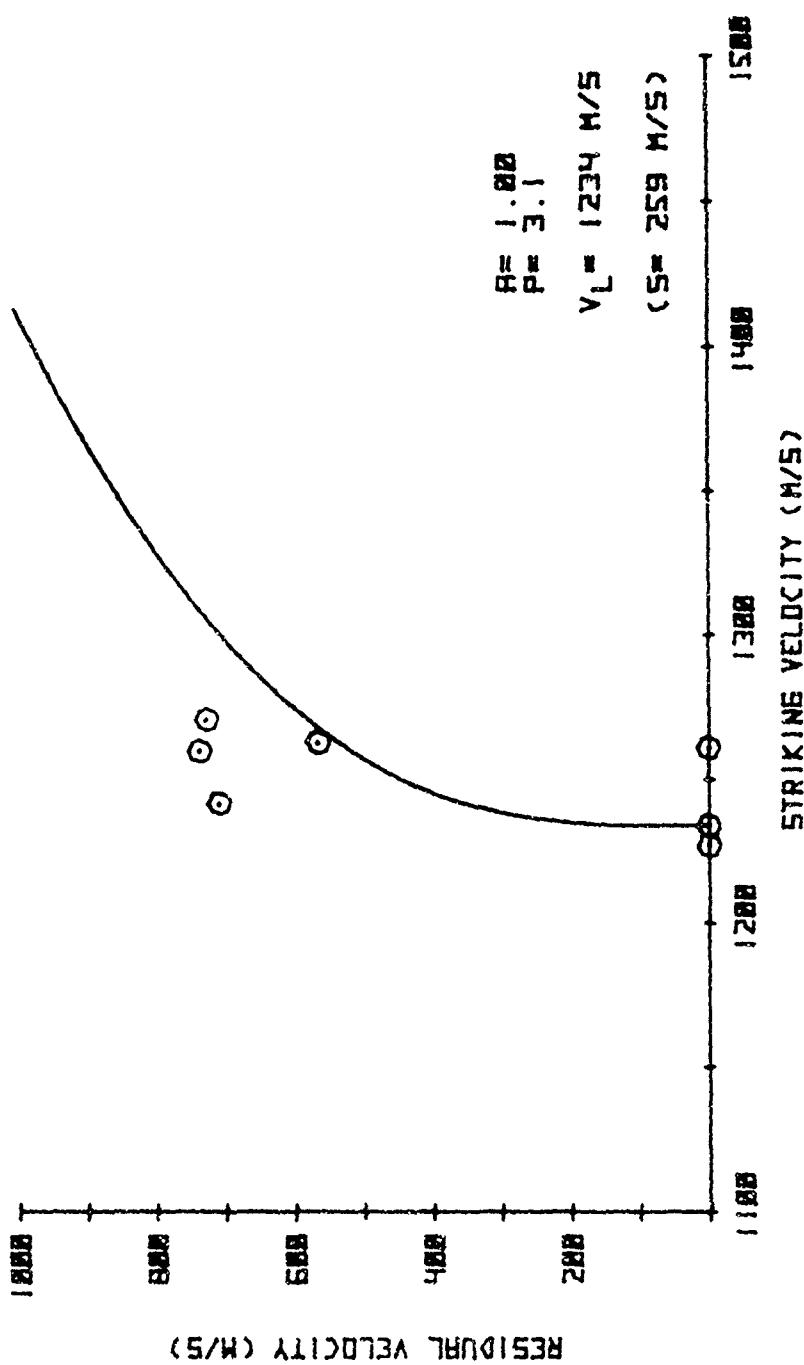


FIGURE B-14.  $V_S, V_R$  CURVE AND DATA FOR RCT 14

FIGURE B-15.  $V_S/V_R$  CURVE AND DATA FOR ACT 15



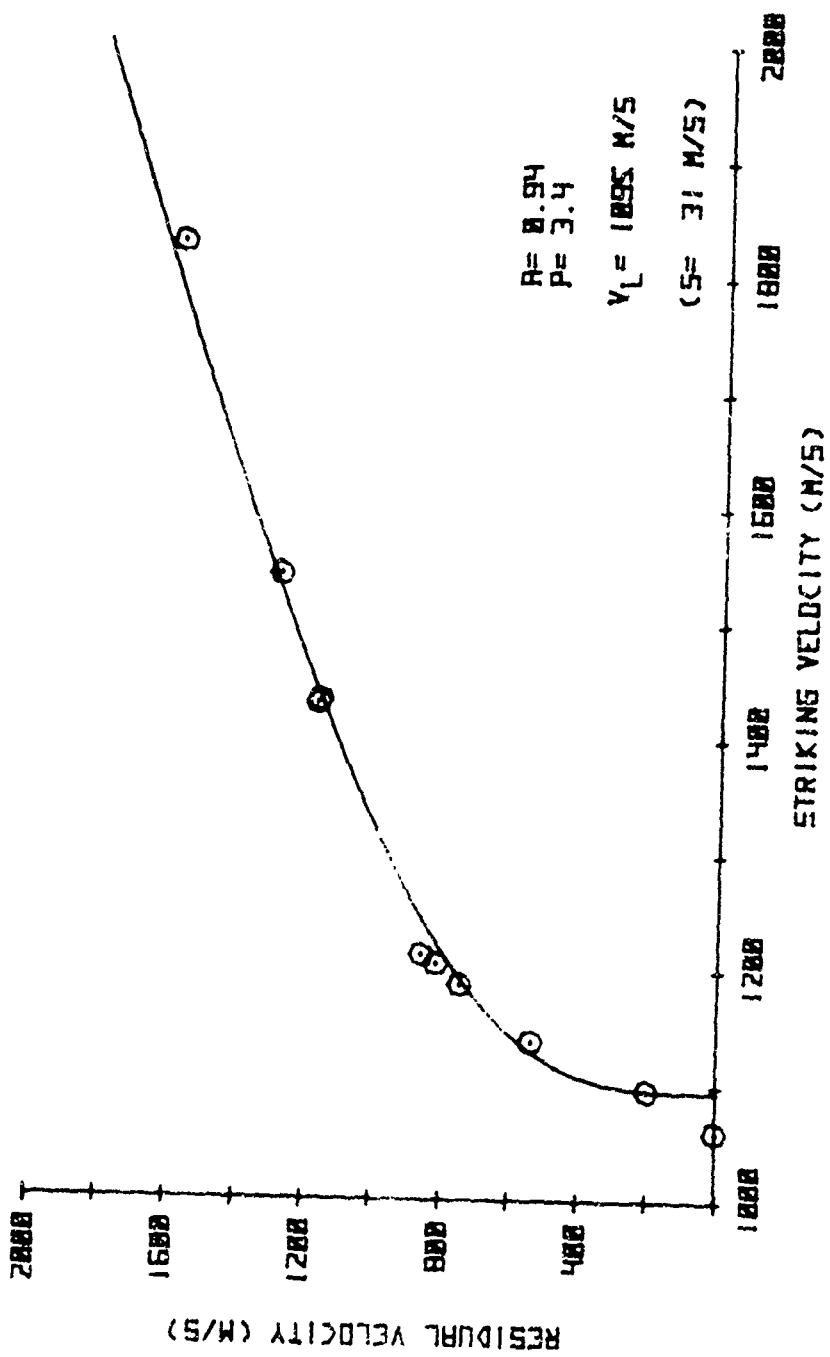


FIGURE B-16.  $V_S, V_R$  CURVE AND DATA FOR RCT 15

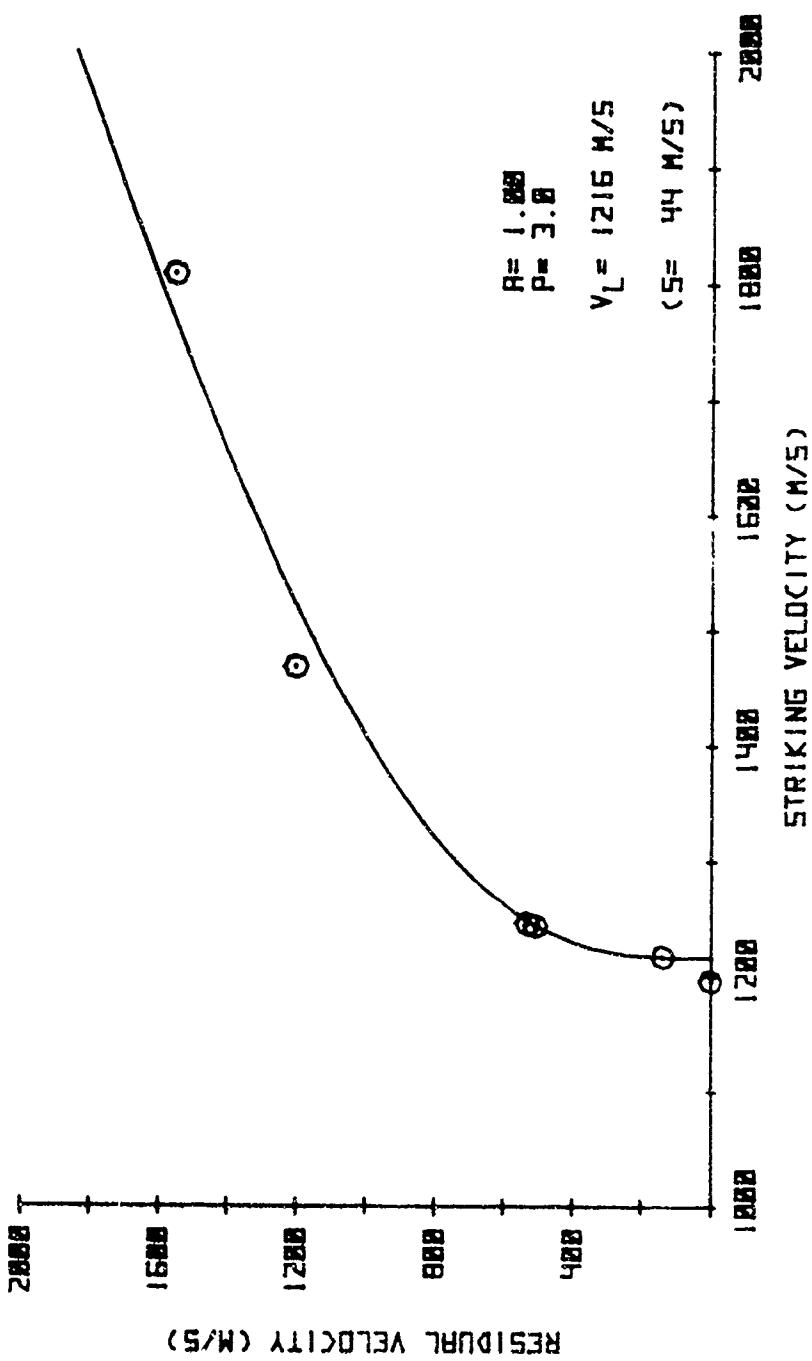


FIGURE 8-17.  $V_S$ ,  $V_R$  CURVE AND DATA FOR RCT 17

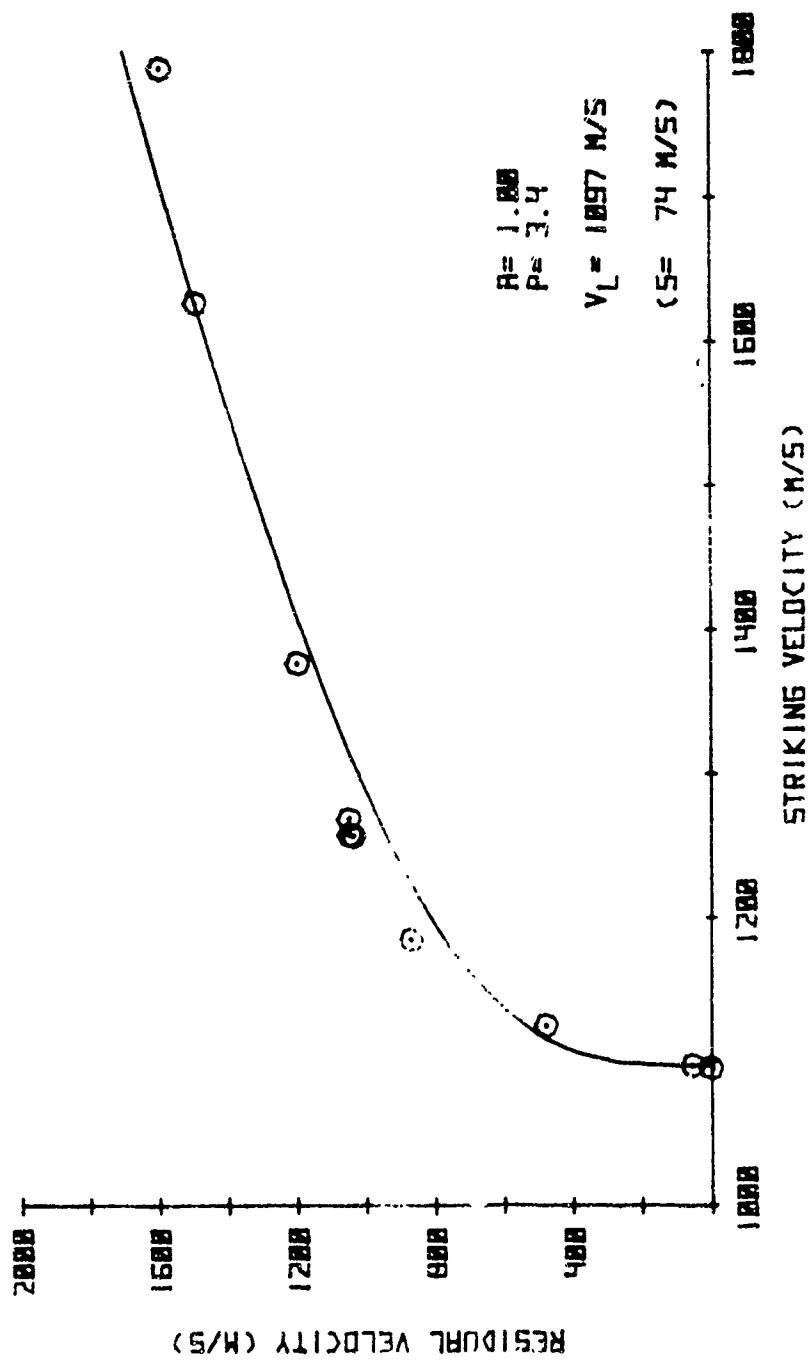


FIGURE B-18.  $V_S, V_R$  CURVE AND DATA FOR RCT 18

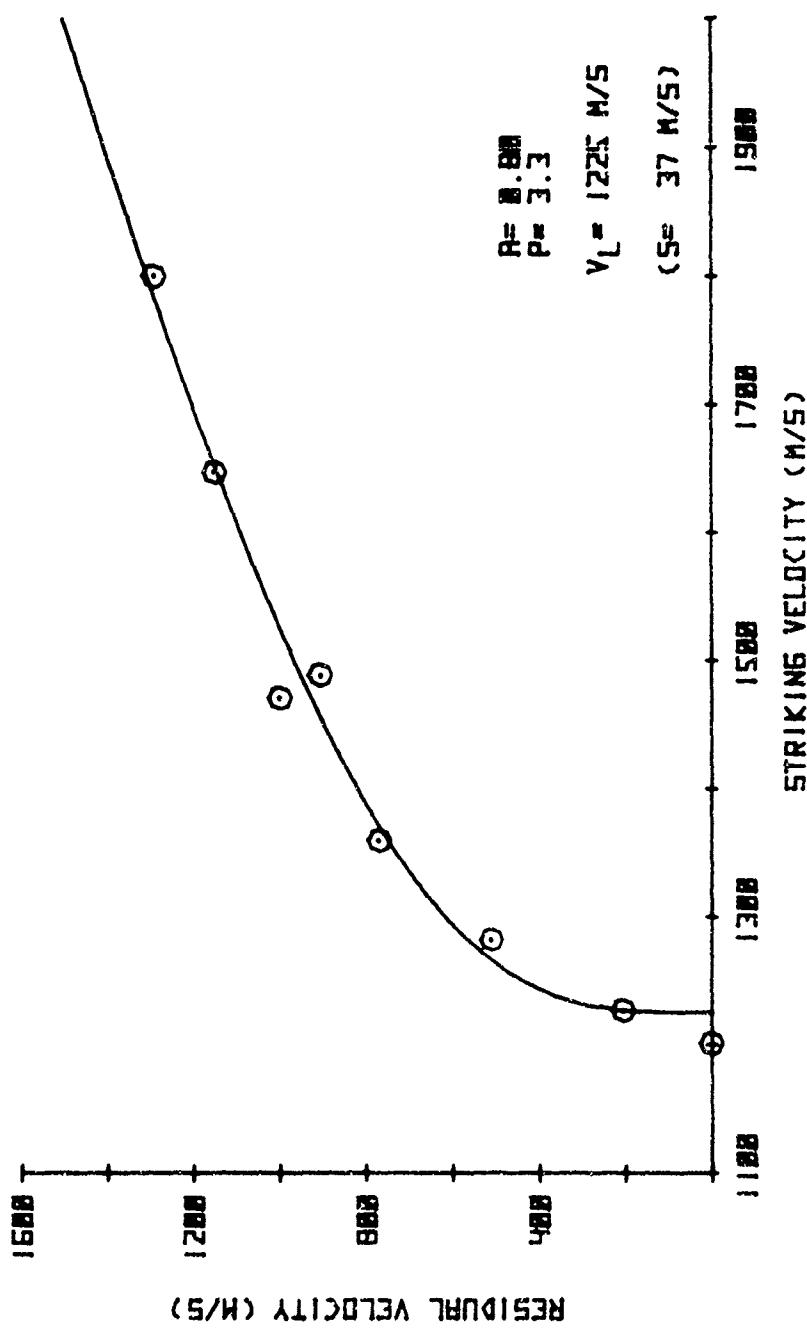


FIGURE B-19.  $V_S/V_R$  CURVE AND DATA FOR RCT 19

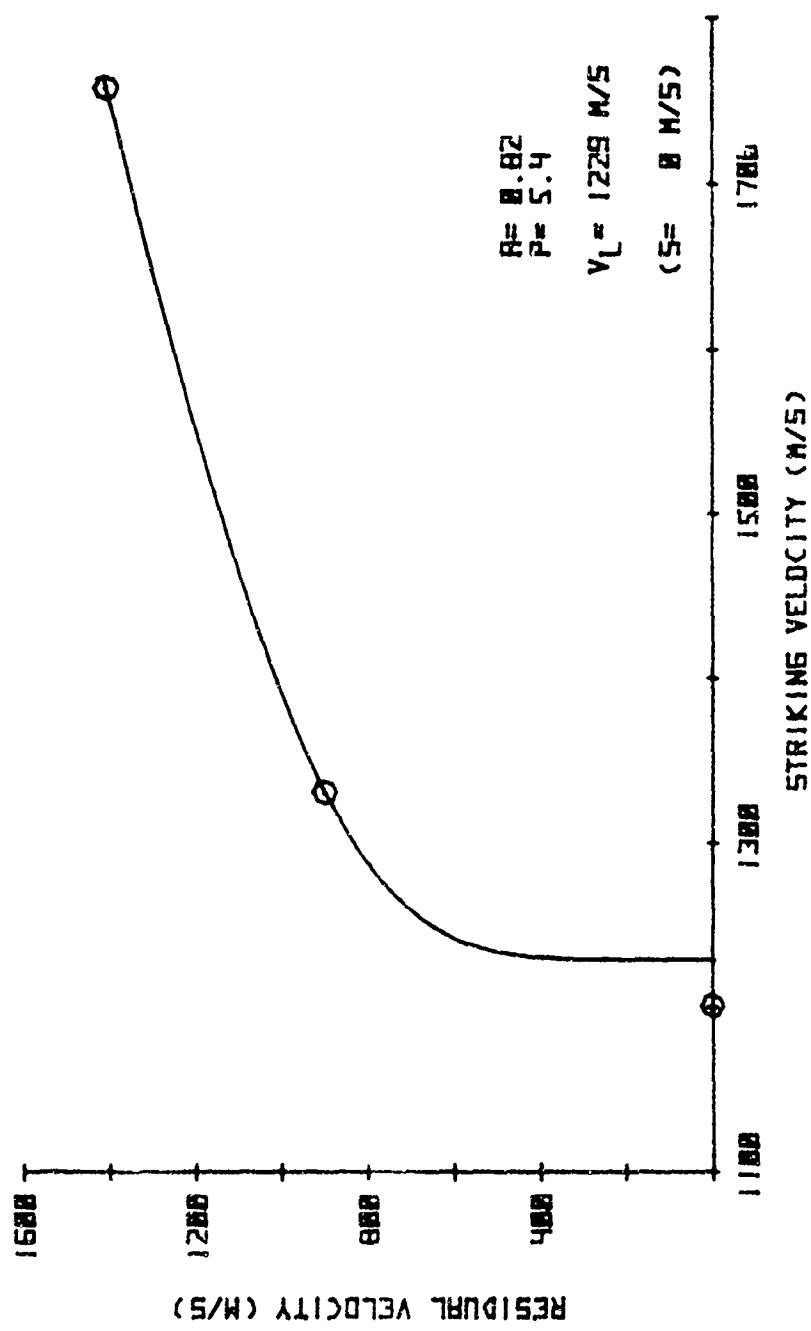


FIGURE B-20.  $V_S/V_R$  CURVE AND DATA FOR RCT 2B

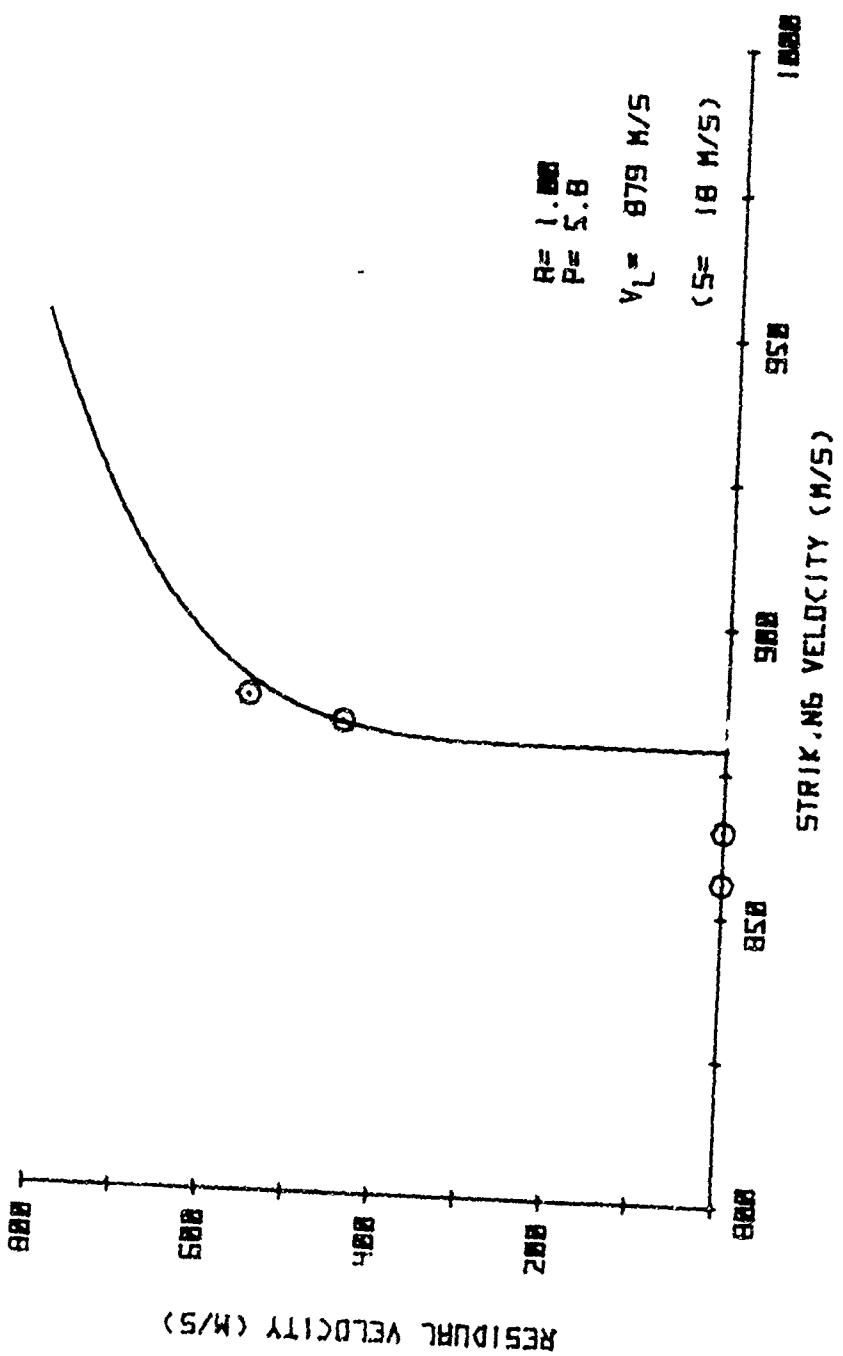


FIGURE B-21.  $V_S/V_R$  CURVE AND DATA FOR RCT 1.1

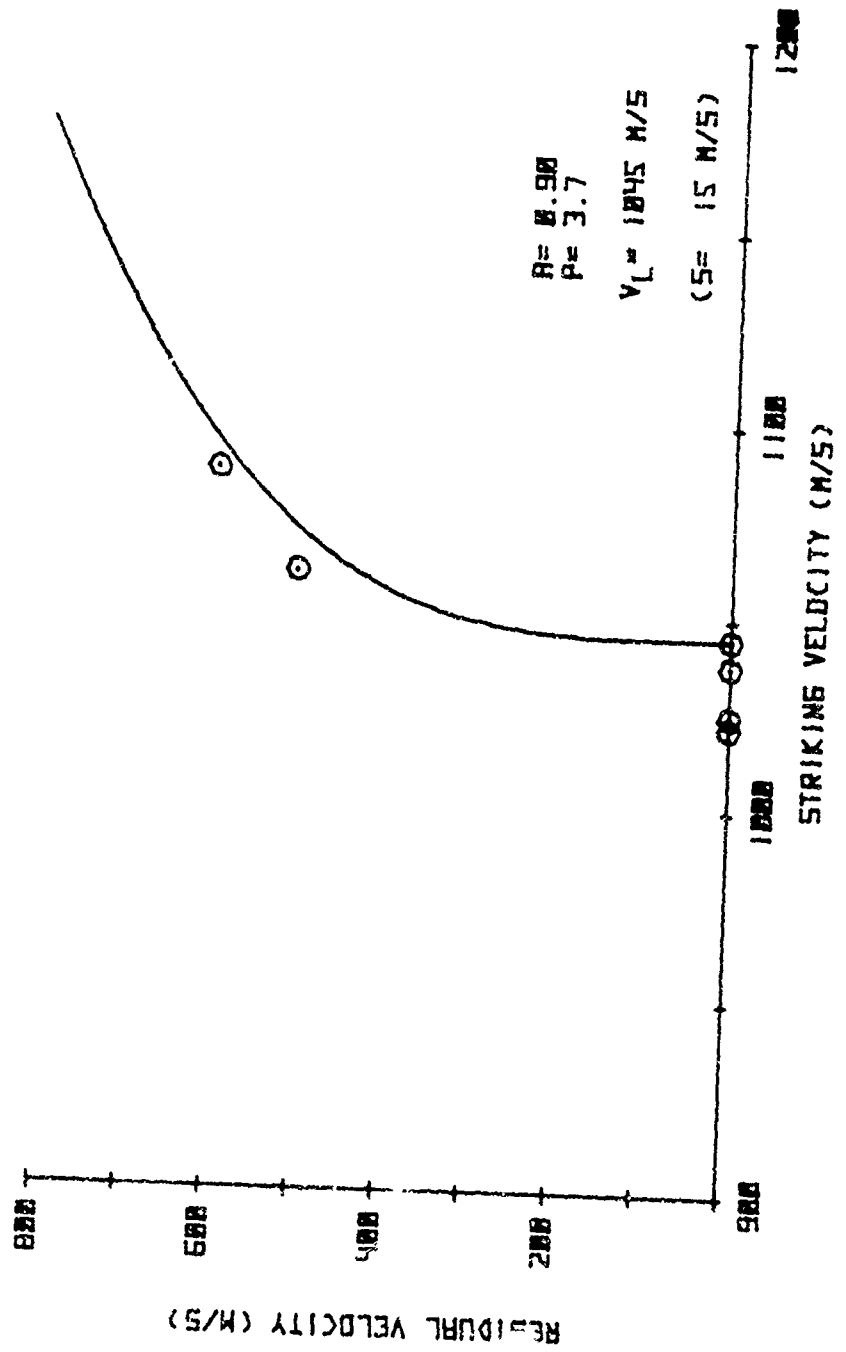


FIGURE B-22.  $V_S$ ,  $V_R$  CURVE AND DATA FOR RCT 3.1

APPENDIX C  
FRAGMENT DATA

## APPENDIX C: FRAGMENT DATA

Summary of processed<sup>3</sup> behind-target fragmentation data for 29 selected rounds.

### Notation

- Type      - P: penetrator fragment  
          - T: target fragment (spall particle)
- Cone     - Cone angle of fragment trajectory: the acute angle between the fragment path and the initial penetrator path. c.f., Figure C-1.
- Phase    - Phase angle of fragment trajectory: the angle, between 0 and 360 degrees and measured clockwise as perceived from the target hole, between the vertical upward direction and the projection of the fragment path on a plane behind the target orthogonal to the initial penetrator path. c.f., Figure C-1.

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<sup>3</sup>Arbuckle, A. L., Herr, E. L. and Ricchiazzi, A. J., "A Computerized Method of Obtaining Behind-the-Target Data from Orthogonal Flash Radiographs" BRL Memorandum Report 2264, January 1973 (AD 308362L).

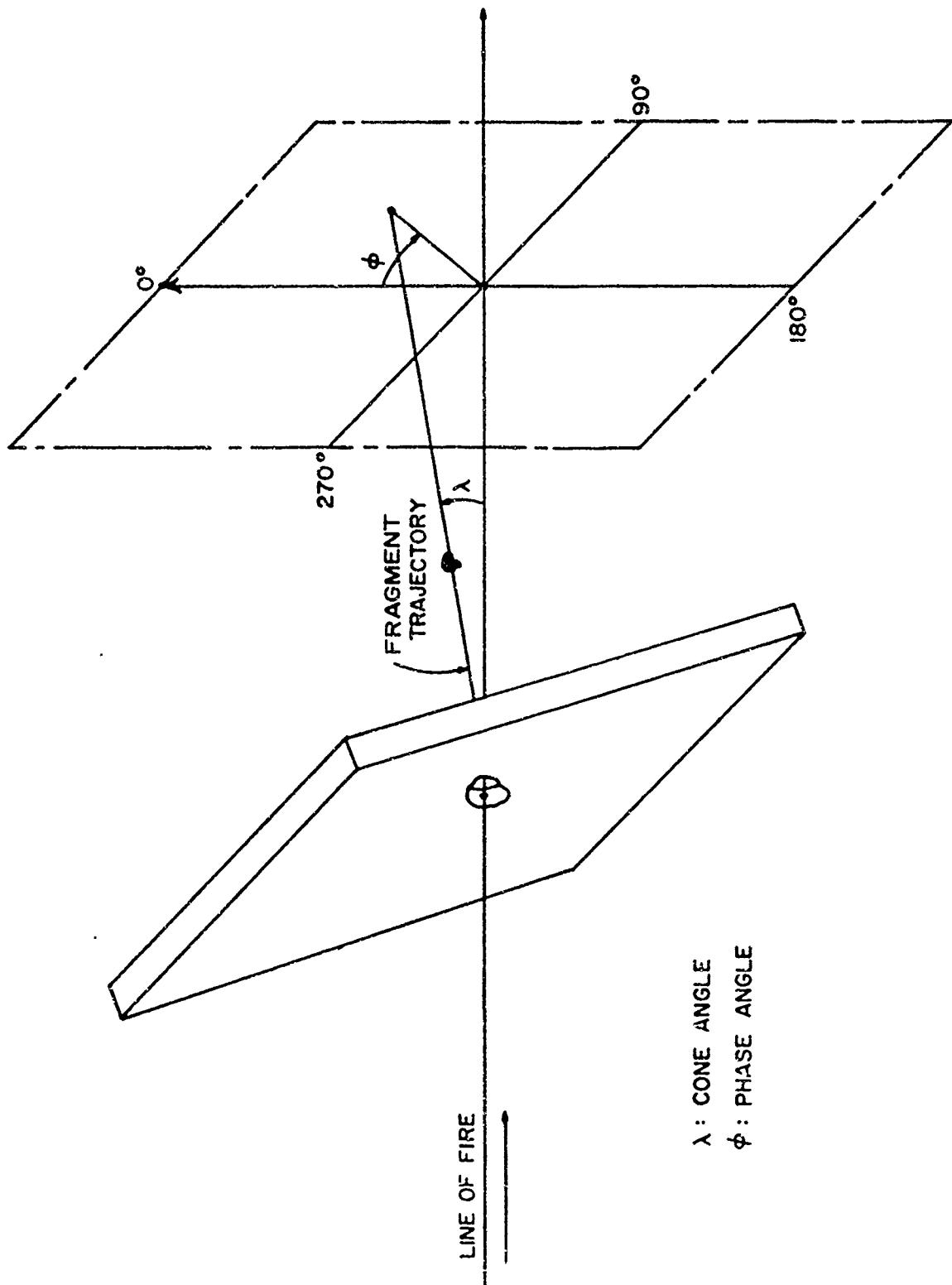


FIGURE C-1. COORDINATE SYSTEM DEPICTING ANGLES  $\lambda$  AND  $\phi$

ROUND 116 (ACT 5)			
TYPE	SPEED (N/S)	MASS (GR)	CONE (DEG)
P	189	11.4	20
T	379	0.2	71
T	371	0.3	62
T	511	0.3	71
T	482	0.4	78
T	402	0.5	61
T	465	0.6	70
T	443	1.0	69
R	406	1.5	65
T	259	3.2	24

ROUND 130 (ACT 5)			
TYPE	SPEED (N/S)	MASS (GR)	CONE (DEG)
P	389	18.8	1
T	450	0.1	11
T	311	0.1	7
T	361	0.1	7
T	368	0.1	11
T	363	0.1	14
T	365	0.1	10
T	407	0.8	6
T	418	0.8	10
T	372	0.2	15
T	368	0.2	6
T	366	0.2	5
T	437	0.2	10
T	407	0.4	12
T	310	0.4	5
T	360	0.4	9
T	241	0.5	7
T	348	0.5	5
T	322	0.5	4
T	281	0.5	7
R	301	0.6	8

ROUND 118 (ACT 5)			
TYPE	SPEED (N/S)	MASS (GR)	CONE (DEG)
P	430	7.7	9
T	492	0.3	14
T	530	0.4	3
T	500	1.6	12
T	491	1.9	7
T	504	2.2	16
T	502	7.6	8
R	518	9.5	5

ROUND 130 (CONT'D)		
TYPE	SPEED (K/S)	PHASE (DEG)
T	350	0.6
T	355	0.9
T	366	0.9
T	350	1.0
T	348	1.4
T	312	1.7
T	357	2.0
T	384	8.1
T	385	11.7
		10

ROUND 132 (CONT'D)		
TYPE	SPEED (K/S)	PHASE (DEG)
T	171	0.1
T	172	0.1
T	287	0.1
T	242	0.2
T	286	0.2
T	207	0.2
T	283	0.2
T	211	0.2
T	207	0.2
T	250	0.2
T	171	0.2
T	286	0.2
T	237	0.2
T	211	0.3
T	241	0.3
T	165	0.3
T	282	0.4
T	211	0.4
T	250	0.4
T	194	0.4

ROUND 132 (ACT 5)		
TYPE	SPEED (K/S)	PHASE (DEG)
P	187	10.6
T	200	0.1
T	242	0.1
T	259	0.1
T	237	0.1
T	211	0.1
T	286	0.1
T	11	11
T	28	28
T	38	38
T	35	35
T	38	38
T	35	35
T	38	38

ROUTE 132 (cont'd)		
TYPE	SPD (KTS)	CONE (DEG)
		PHASE (DEG)
T	1.65	0.4
T	1.57	0.4
T	2.13	0.4
T	1.95	0.4
T	2.15	0.4
T	2.20	0.5
T	1.98	0.5
T	1.91	0.6
T	2.22	0.6
T	1.56	0.8
T	2.27	0.9
T	1.62	1.0
T	2.00	1.1
T	2.05	1.2
T	1.75	1.4
T	2.05	1.6
T	2.22	1.6
T	2.05	3.1
T	2.45	8.6
T	2.64	9.4
T	2.21	18.7
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ROUTE 133 (act 6)		
TYPE	SPD (KTS)	CONE (DEG)
P	114	23.6
T	135	0.1
T	159	0.8
T	113	0.3
T	112	0.3
T	137	0.4
T	133	0.4
T	115	0.5
T	144	0.8
T	142	1.6
T	56	4.6
T	58	5.8
	13	176

TYPE	ROUND 135 (ACT 5)	
	NAME (SER.)	GONE (SER.)
R	17.7	26 237
T	191	0.1 5 193
T	157	0.1 3 198
T	172	0.2 5 207
T	173	0.2 3 23
T	164	0.2 3 248
T	174	0.2 5 208
T	161	0.3 4 260
T	171	0.3 5 26
T	147	0.4 6 285
T	153	0.5 8 211
T	170	0.6 6 282
T	188	0.8 6 281
T	180	0.7 6 281
T	17	7.5 10 281

TYPE	ROUND 137 (ACT 5)	
	NAME (SER.)	GONE (SER.)
R	231	0.1 19 0
T	268	0.1 19 0
T	264	0.1 19 0
T	262	0.1 19 0
T	261	0.1 19 0
T	260	0.1 19 0
T	259	0.1 19 0
T	258	0.1 19 0
T	257	0.1 19 0
T	256	0.1 19 0
T	255	0.1 19 0
T	254	0.1 19 0
T	253	0.1 19 0
T	252	0.1 19 0
T	251	0.1 19 0
T	250	0.1 19 0
T	249	0.1 19 0
T	248	0.1 19 0
T	247	0.1 19 0
T	246	0.1 19 0
T	245	0.1 19 0
T	244	0.1 19 0
T	243	0.1 19 0
T	242	0.1 19 0
T	241	0.1 19 0
T	240	0.1 19 0
T	239	0.1 19 0
T	238	0.1 19 0
T	237	0.1 19 0
T	236	0.1 19 0
T	235	0.1 19 0
T	234	0.1 19 0
T	233	0.1 19 0
T	232	0.1 19 0
T	231	0.1 19 0

TYPE	SOUND 137 (CHTB)			SOUND 138 (ACT 16)		
	SPEED (KTS)	ANGLE (DEG)	PHASE	SPEED (KTS)	ANGLE (DEG)	PHASE
R	788	0.4	28	774	0.1	20
T	813	0.4	17	677	0.2	20
T	795	0.4	16	465	0.3	21
T	834	0.5	18	468	0.3	21
T	1405	0.3	5	453	0.3	20
T	820	0.3	15	367	0.4	9
T	888	0.3	13	315	0.4	14
T	1382	0.3	7	307	0.4	16
T	837	0.3	11	293	0.4	16
T	1314	0.3	14	241	0.4	27
T	827	0.3	27	0	0	157
T	854	1.1	19	0	0	11
T	1144	1.2	18	230	0.5	11
T	858	1.3	14	235	0.7	11
T	1034	1.7	16	475	0.8	13
T	1126	1.7	28	448	0.8	28
T	1388	2.1	8	488	1.0	21
K	1403	4.1	5	507	1.3	17
K	1083	4.5	19	508	1.7	18
K	1389	4.5	7	521	2.2	8
K				538	2.6	12

ROUND 138 (ACT 10)				ROUND 140 (ACT 10)			
TYPE	SPEED (M/S)	TIME (SEC)	PHASE (SEC)	TYPE	SPEED (M/S)	TIME (SEC)	PHASE (SEC)
T	550	2.3	50	T	214	0.1	17
T	449	3.7	50	T	213	0.2	17
T	438	5.7	9	T	205	0.3	18
T	367	7.8	8	T	208	0.3	13
				T	160	0.4	20
				T	153	0.4	18
				T	142	0.5	19
				T	265	0.5	10
				T	143	0.5	19
				T	272	0.5	11
				T	270	0.6	3
				T	260	0.7	9
				T	191	0.8	3
				T	344	0.9	3

ROUND 142 (ACT 10)				ROUND 144 (ACT 10)			
TYPE	SPEED (M/S)	TIME (SEC)	PHASE (SEC)	TYPE	SPEED (M/S)	TIME (SEC)	PHASE (SEC)
T	200	5.1	5	T	227	0.6	5
T	201	5	130	T	348	0.6	12
T				T	371	1.1	4
				T	368	1.1	4
				T	365	0.6	13
				T	360	0.6	14

TYPE	NAME 153 (CONT)		
	NAME	PHASE (DEG)	CONE (DEG)
T	1801	1.0	5
T	1802	1.0	5
T	955	1.2	9
T	1079	1.2	13
T	1084	1.3	10
T	1087	1.3	9
T	1090	2.0	13
T	951	2.0	21
T	872	1.5	17
T	1014	2.4	6
T	988	2.4	16
T	921	2.4	17
T	932	2.5	18
T	1015	2.6	13
R	1388	5.1	8
R	1391	5.1	2
T	111	5.1	27

TYPE	NAME 153 (ACT 10)		
	NAME	PHASE (DEG)	CONE (DEG)
T	310	0.3	11
T	357	0.3	13
T	46	0.3	17
T	56	0.4	18
T	17	0.4	18
T	0	0.5	17
T	205	0.5	10
T	924	0.5	13
T	925	0.5	6
T	940	0.5	11
T	376	0.5	16
T	1104	0.5	11
T	203	0.5	13
T	985	0.5	10
T	918	0.5	13
T	819	0.5	16
T	818	0.5	13
T	875	0.7	20
T	971	0.7	19
T	791	0.8	12
T	954	0.8	12
T	844	0.8	24
T	1385	0.8	5
T	982	0.8	26
T	913	0.9	41
T	794	0.9	23
T	1041	1.0	14

ROUTE 155 (ACT 14)			ROUTE 155 (ACT 14)			ROUTE 155 (ACT 14)		
TYPE	SPEED (KTS)	CONE (DEG)	TYPE	SPEED (KTS)	CONE (DEG)	TYPE	SPEED (KTS)	CONE (DEG)
T	409	0.2	T	419	8	T	451	0.2
R	380	0.5	T	435	0.2	T	455	17
R	405	0.8	T	383	28	T	502	2.7
T	387	1.3	T	10	309	T	490	2.8
T	394	1.5	T	16	35	T	302	2.4
T	348	1.6	T	12	305	T	403	3.6
T	364	2.0	T	14	309	T	412	3.7
T	305	2.2	T	7	348			
T	380	2.6	T	20	36			
T	444	2.6	T	10	303			
T	705	4.2	T	9	114			
R	313	4.4	T	1	180			
T	321	6.1	T	2	24			
T	272	6.7	T	0	26			
T	272	11.3	T	1	26			
TYPE	SPEED (KTS)	CONE (DEG)	TYPE	SPEED (KTS)	CONE (DEG)	TYPE	SPEED (KTS)	CONE (DEG)
T	546	0.1	T	13	5	T	500	1.7
T	549	0.3	T	14	360	T	548	3.2
T	482	0.3	T	18	357	T	711	4.5

ROUND 152 (ACT 14)			ROUND 153 (ACT 15)		
TYPE	SPEED (ft/s)	TIME (sec)	TYPE	SPEED (ft/s)	TIME (sec)
P	314	8.3	T	640	0.1
T	340	11	T	305	0.1
T	302	0.1	T	188	0.1
T	305	0.1	T	186	0.1
T	315	0.1	T	182	0.1
T	304	0.1	T	207	0.1
T	245	0.1	T	10	308
T	245	0.1	T	15	151
T	245	0.1	T	6	843
T	245	0.1	T	5	0
T	231	0.1	T	4	52
T	249	0.2	T	7	190
T	231	0.3	T	13	168
T	275	0.3	T	270	0
T	358	0.3	T	53	0
T	304	0.3	T	7	131
T	190	0.4	T	13	0
T	321	0.4	T	30	0
T	310	0.4	T	37	0
T	305	0.4	T	55	0
ROUND 154 (ACT 16)			ROUND 155 (ACT 17)		
TYPE	SPEED (ft/s)	TIME (sec)	TYPE	SPEED (ft/s)	TIME (sec)
T	414	0.1	T	474	0.2
T	338	0.2	T	507	0.3
T	488	0.4	T	335	0.4
T	324	0.4	T	384	0.4

ROUND 181 (ACT 14)			
TYPE	PHASE (DEG) (CR)	CONE (DEG) (CR)	PHASE (DEG)
T	538	0.4	7
T	538	0.4	5
T	348	0.4	7
T	346	0.6	7
T	373	0.7	14
T	491	1.9	17
T	302	1.9	10
T	405	3.3	16
T	448	3.4	17
R	524	5.4	2
T	492	5.5	12

ROUND 187 (ACT 14)			
TYPE	PHASE (DEG) (CR)	CONE (DEG) (CR)	PHASE (DEG)
T	572	0.1	21
T	575	0.1	21
T	728	1.0	6
T	517	0.3	12
T	680	0.4	10
T	471	0.5	17
T	536	0.6	9
T	687	0.8	11
T	628	0.9	24
T	618	1.2	7
T	500	1.3	1
T	437	1.5	1
T	506	1.6	35
T	609	2.1	15
T	571	2.3	15
T	683	2.4	9
T	726	2.5	10
T	782	2.5	11
T	784	4.2	8
T	620	4.6	11
T	582	5.6	11

ROUND 183 (ACT 14)			
TYPE	PHASE (DEG) (CR)	CONE (DEG) (CR)	PHASE (DEG)
T	378	0.1	6
T	350	0.2	10
T	344	0.4	10
T	341	0.4	9
T	420	1.0	8

TYPE	ROUND 170 (ACT 14)		
	SPEED (IN/S)	PHASE (deg)	CONE (deg)
T	1159	0.1	7
T	1182	0.1	8
T	878	0.1	11
R	1804	0.2	8
T	888	0.3	10
T	811	0.4	9
T	872	0.4	11
T	887	0.5	7
R	1121	0.5	11
T	853	0.5	9
T	1063	0.5	15
T	918	0.5	19
R	1128	5.0	9
T	1881	0.6	2
T	912	0.6	0
T	820	0.7	10
T	885	0.7	6
T	1072	0.7	8
T	1113	0.8	14
T	1003	0.8	15
T	702	1.0	0
T	881	1.1	16

TYPE	ROUND 170 (ACT 14)		
	SPEED (IN/S)	PHASE (deg)	CONE (deg)
T	853	1.1	9
T	772	1.3	10
T	882	1.2	4
T	813	1.2	12
T	1203	1.3	6
T	1006	1.4	6
T	815	1.9	11
T	862	1.9	5
T	803	1.9	11
T	781	2.0	5
T	859	2.1	7
T	860	2.1	2
T	860	2.1	2
T	860	2.1	2
T	860	2.1	2
TYPE	ROUND 175 (ACT 14)		
TYPE	SPEED (IN/S)	PHASE (deg)	CONE (deg)
T	886	0.2	15
T	480	0.2	7
T	481	0.2	7
T	491	0.7	8
T	100	1.1	6

ROUND 176 (ACT 13)			ROUND 176 (ACT 14)		
TYPE	SPEED (KTS)	PHASE (DEG)	TYPE	SPEED (KTS)	PHASE (DEG)
T	415	8.2	T	515	0.1
X	368	3.1	T	590	0.1
T	168	4.7	T	577	0.1
T	173	4.9	T	594	0.1
		0	T	363	0.1
		16	T	428	0.1
		140	T	444	0.1
		16	T	518	0.1
		21	T	461	0.2
T	323	0.1	T	521	0.2
T	291	0.1	T	503	0.2
T	303	0.1	T	485	0.2
T	240	0.1	T	422	0.2
T	285	0.2	T	355	0.2
T	219	0.3	T	465	0.2
T	237	0.2	T	707	0.2
T	381	0.3	T	488	0.2
T	254	0.3	T	323	0.2
T	407	0.3	T	300	0.2
T	285	0.3	T	362	0.2
		5	T	362	0.2
		0			0

GROUP 173 (CONT)		PHASE (DEG)	14	326	344	360	365	6	365	6	365	365	15	314	3	359	0	364	365	365	0	1	1		
		CONE (DEG)	30	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4		
		MAG (DEG)	0.4	0.4	0.4	0.4	0.5	0.5	0.5	0.5	0.6	0.6	0.6	0.7	0.8	0.8	0.8	0.9	0.9	0.9	0.9	0.9	1.1		
		SPEED (KTS)	531	531	505	577	609	600	395	403	377	365	401	405	377	367	365	420	363	364	405	674			
		TYPE	T	T	T	T	R	T	T	T	T	T	T	T	T	T	T	T	T	T	T	T			
GROUP 173 (CONT)		PHASE (DEG)	345	345	360	347	348	36	365	5	0	4	346	346	351	365	0	364	0	7	12	333	345	0	
		CONE (DEG)	30	30	30	51	57	57	4	41	49	49	43	48	52	49	51	55	55	55	50	51	50		
		MAG (DEG)	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.4	0.4		
		SPEED (KTS)	408	403	436	471	0.2	476	0.2	390	0.2	391	0.2	402	0.3	429	0.3	433	0.3	444	0.3	395	0.3	444	0.4
		TYPE	T	T	T	T	T	T	T	T	T	T	T	T	T	T	T	T	T	T	T	R	T		

ROUND 181 (ACT 11)		ROUND 182		ROUND 183 (CHFD)	
PHASE (SEG)	CONE (SEG)	PHASE (SEG)	CONE (SEG)	PHASE (SEG)	CONE (SEG)
SPEED (M/S)		SPEED (M/S)		SPEED (M/S)	
35	14	36	11	36	14
37	314	37	314	37	314
38	0	38	0	38	0
39	0	39	0	39	0
40	11	40	11	40	11
41	28	41	28	41	28
42	28	42	28	42	28
43	23	43	23	43	23
44	23	44	23	44	23
45	0	45	0	45	0
46	19	46	19	46	19
47	22	47	22	47	22
48	22	48	22	48	22
49	0	49	0	49	0
50	347	50	347	50	347
51	0	51	0	51	0
52	347	52	347	52	347
53	0	53	0	53	0
54	347	54	347	54	347
55	0	55	0	55	0
56	347	56	347	56	347
57	0	57	0	57	0
58	347	58	347	58	347
59	0	59	0	59	0
60	347	60	347	60	347
61	0	61	0	61	0
62	347	62	347	62	347
63	0	63	0	63	0
64	347	64	347	64	347
65	0	65	0	65	0
66	347	66	347	66	347
67	0	67	0	67	0
68	347	68	347	68	347
69	0	69	0	69	0
70	347	70	347	70	347
71	0	71	0	71	0
72	347	72	347	72	347
73	0	73	0	73	0
74	347	74	347	74	347
75	0	75	0	75	0
76	347	76	347	76	347
77	0	77	0	77	0
78	347	78	347	78	347
79	0	79	0	79	0
80	347	80	347	80	347
81	0	81	0	81	0

ROUND 181 (CHTB)				ROUND 182 (CHTB)			
TYPE	SPEED (KTS)	MASS (KG)	PHASE (DEG)	TYPE	SPEED (KTS)	MASS (KG)	PHASE (DEG)
T	167	1.7	51	358	T	367	1.0
T	281	5.1	39	338	T	400	1.0
R	363	2.8	35	335	T	513	1.3
T	262	4.3	39	342	T	388	3.1
T	289	10.7	49	0	T	428	6.2
T	264	11.4	45	0	T	388	23
T	215	12.2	61	0	ROUND 180 (ACT 6)		
ROUND 185 (ACT 11)				TYPE	SPEED (KTS)	MASS (KG)	PHASE (DEG)
TYPE	SPEED (KTS)	MASS (KG)	PHASE (DEG)	T	365	0.1	364
T	364	0.1	34	T	368	0.2	36
T	437	0.1	40	T	365	0.2	34
T	320	0.2	38	T	363	0.2	36
T	547	0.3	41	T	364	0.2	36
T	378	0.2	50	T	368	0.2	37
T	311	0.4	71	T	365	0.2	36
T	440	0.4	53	T	422	0.5	364
T	365	0.5	44	T	369	0.5	44
T	469	0.8	57	T	278	0.5	36
T	368	0.9	34	T	368	0.6	367
T	324	1.0	35	T	368	0.6	36

ROUND 190 (CONT'D)			ROUND 191 (CONT'D)		
TYPE	SPEED (M/S)	MAGS (G's)	CONE (DEG)	PHASE (DEG)	CONE (DEG)
T	351	0.6	23	0	364
T	355	0.7	24	10	54
T	361	0.7	24	13	49
T	369	0.7	23	0	16
T	378	0.7	54	0	6
T	388	0.8	26	0	361
T	391	0.8	50	0	362
T	392	1.0	51	0	364
T	393	1.0	29	23	364
T	395	1.0	43	363	3
T	396	1.8	51	0	1
T	397	1.8	44	0	371
T	398	1.8	44	0	371
T	399	5.0	35	0	371
T	400	6.7	49	0	371
T	401	7.5	75	0	371
T	407	16.5	69	0	371
TYPE	SPEED (M/S)	MAGS (G's)	CONE (DEG)	PHASE (DEG)	CONE (DEG)
T	364	0.3	54	364	
T	442	0.4	49	442	
T	364	0.4	53	364	
T	333	0.4	49	333	
T	367	0.5	53	367	
T	371	0.7	53	371	
T	348	0.7	53	348	
T	371	0.7	53	371	
T	400	0.8	53	400	
T	347	0.8	53	347	
T	361	0.8	54	361	
T	331	0.9	54	331	
T	378	0.9	54	378	
T	364	1.0	55	364	
T	371	1.0	55	371	
T	349	1.0	55	349	
T	342	1.2	48	342	
T	367	1.3	48	367	
T	462	1.8	55	462	
T	344	2.6	53	344	
T	360	2.7	52	360	
T	136	3.3	41	136	
T	202	3.4	41	202	

ROUND 199 (ACT 6)			ROUND 200 (ACT 6)			ROUND 201 (ACT 6)					
TYPE	SPEED (ft/s)	MAGS (ft)	CONF (DEG)	TYPE	SPEED (ft/s)	MAGS (ft)	CONF (DEG)	TYPE	SPEED (ft/s)	MAGS (ft)	CONF (DEG)
T	610	0.1	37	349	T	331	4.4	42	341		
T	584	0.2	29	352	T	285	5.3	38	333		
T	581	0.2	28	344	T	247	5.6	36	351		
T	556	0.2	33	354	T	136	8.3	18	0		
T	485	0.3	83	15	T	281	13.7	58	1		
T	519	0.3	26	12	T	107	24.0	51	0		
R	625	0.4	37	354							
T	346	0.5	26	17							
R	559	0.5	35	1							
T	416	0.6	68	0							
T	487	0.7	23	358	T	573	0.1	10	14		
T	472	0.8	18	21							
T	576	0.9	23	359	T	574	0.1	10	17		
T	550	1.3	26	327	T	594	0.1	13	28		
T	576	1.8	34	346	T	603	0.1	46	5		
R	685	1.9	43	6	T	615	0.2	38	342		
R	686	1.9	44	9	R	697	0.2	32	341		
T	623	1.9	27	358	R	705	0.2	32	3		
R	614	2.1	26	0	T	649	0.3	36	337		
T	526	2.9	27	361	T	645	0.3	30	336		
					T	608	0.3		328		

ROUND 213 (CHTD)			ROUND 213 (CHTD)		
TYPE	SPEED (K/S)	MASS (GR)	TYPE	SPEED (K/S)	MASS (GR)
T	708	0.3	T	690	0.3
R	630	0.3	R	641	0.3
T	641	0.3	T	680	1.4
R	737	0.3	T	657	1.5
T	734	0.4	R	636	1.8
R	728	0.4	R	636	1.8
R	735	0.4	T	643	1.9
T	668	0.4	R	689	2.2
R	722	0.4	R	539	2.3
T	634	0.6	T	577	2.6
T	498	0.7	T	615	2.7
T	623	0.7	R	685	2.7
SUS	505	0.7	R	731	2.8
T	727	0.7	R	565	2.9
T	475	0.7	R	693	3.1
T	722	0.7	T	592	3.1
R	691	0.7	R	680	5.0
T	708	0.7	R	538	5.4

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**APPENDIX D**  
**PENETRATION SKETCHES FOR ACT 19**

#### APPENDIX D: PENETRATION SKETCHES FOR ACT 19

We attempt, in a sequence of rough sketches, to illustrate the pre-impact and residual penetrator (and/or "plug") and target plate section for rounds 258 through 265 (which constitute ACT 19). Figures are (roughly) 3/4 of actual size and the attempt is to convey approximate positioning and shape. In each sketch the initial penetrator position (with respect to the target plate) is representative of the situation 50  $\mu$ sec before impact and (except for Round 264) the residual penetrator suggests the situation 50  $\mu$ sec after perforation is complete (i.e., after the tail of the penetrator clears the rear target surface).

We recall that ACT 19 involves L/D of 10 monolithic steel penetrators impacting 1" RHA at 60° obliquity.  $M_r$  is used to denote recovered residual penetrator mass. Ordering of the sketches reflects an increasing sequence of striking velocities.

Following the sketches is a photograph of the sectioned target plates for these shots together with a representative original penetrator and recovered residual penetrators. In the photograph  $\Delta$  is used to denote mass loss of the target plate. In a few cases there is a small discrepancy between the velocities given in the sketches and those on the photograph - those in the sketches are derived from a later, presumably more careful "reading" of the radiographs and are regarded as the official values. The sequence of rounds in the photograph is as follows:

top row, left to right - Rounds 264, 263, 262, 261

bottom row, left to right - Rounds 265, 260, 259, 258

*Remarks: Each plate shows an indentation on the upper front surface - these "lips" were formed by pusher plates impacting the targets and are not consequent to penetrator/target interaction.*

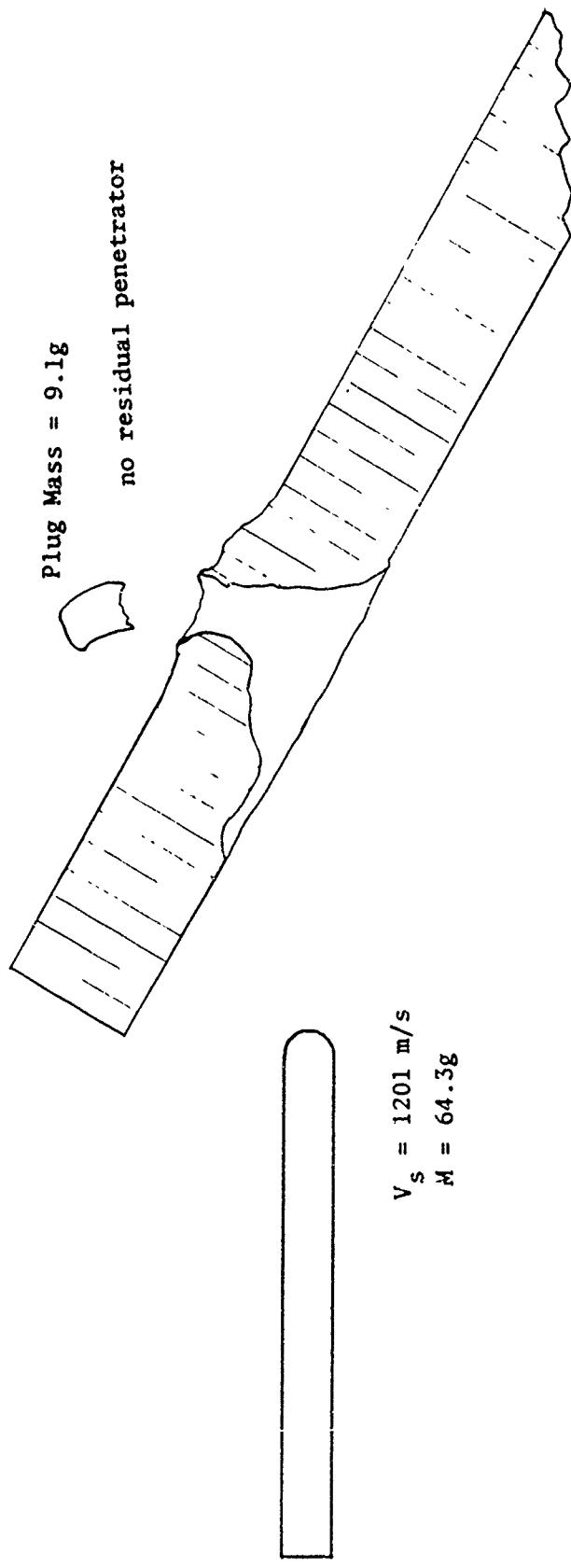


Figure D-1. Sketch for Round 264

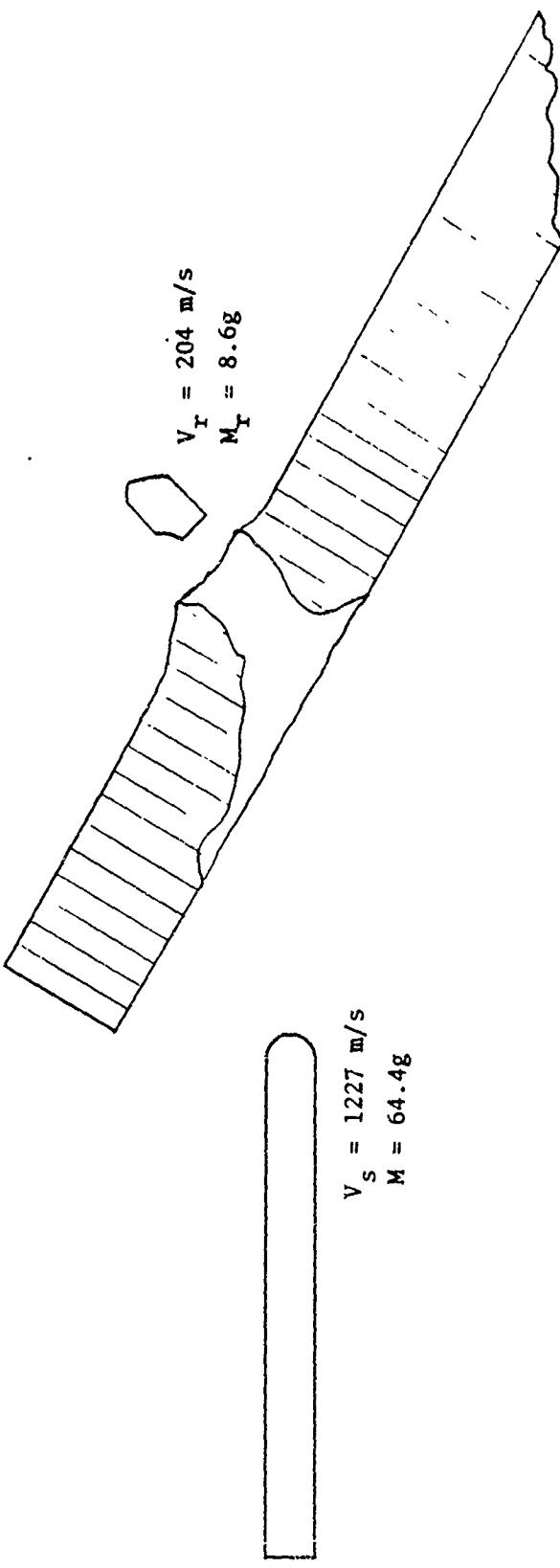


Figure D-2. Sketch for Round 263

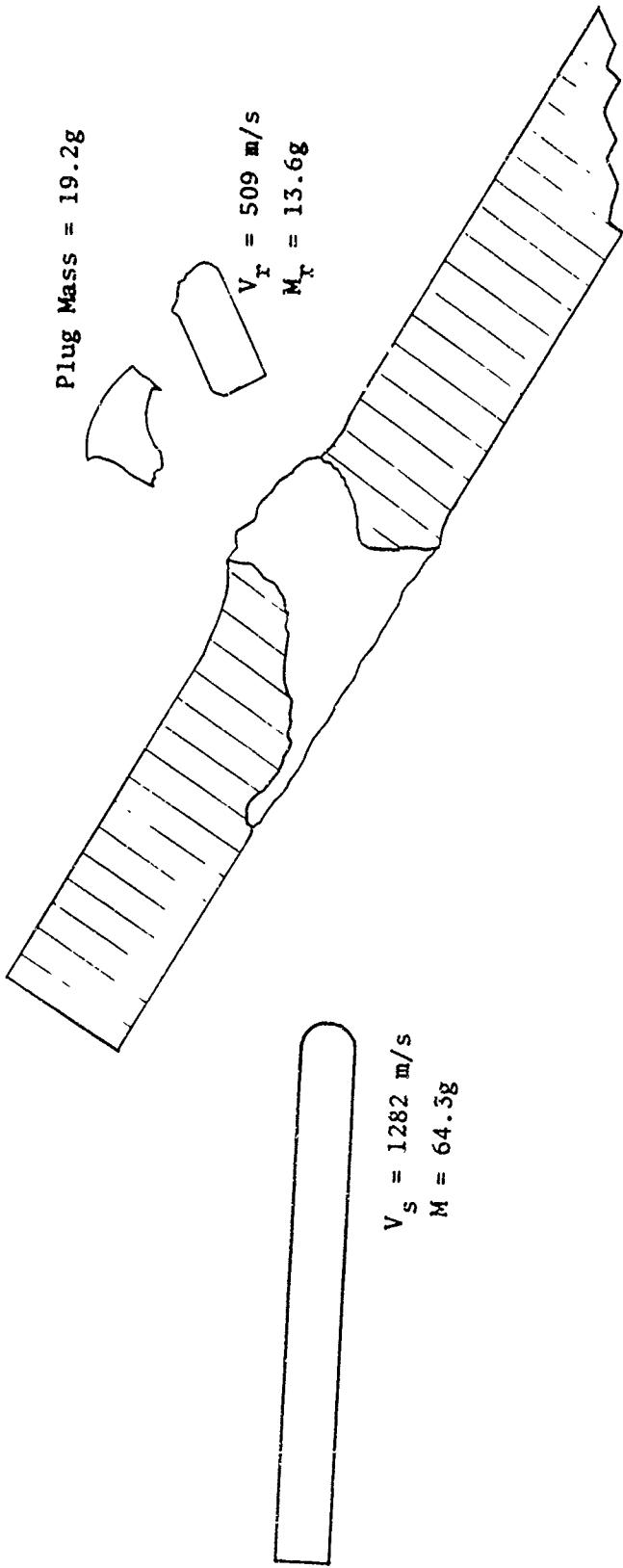


Figure D-3. Sketch for Round 262

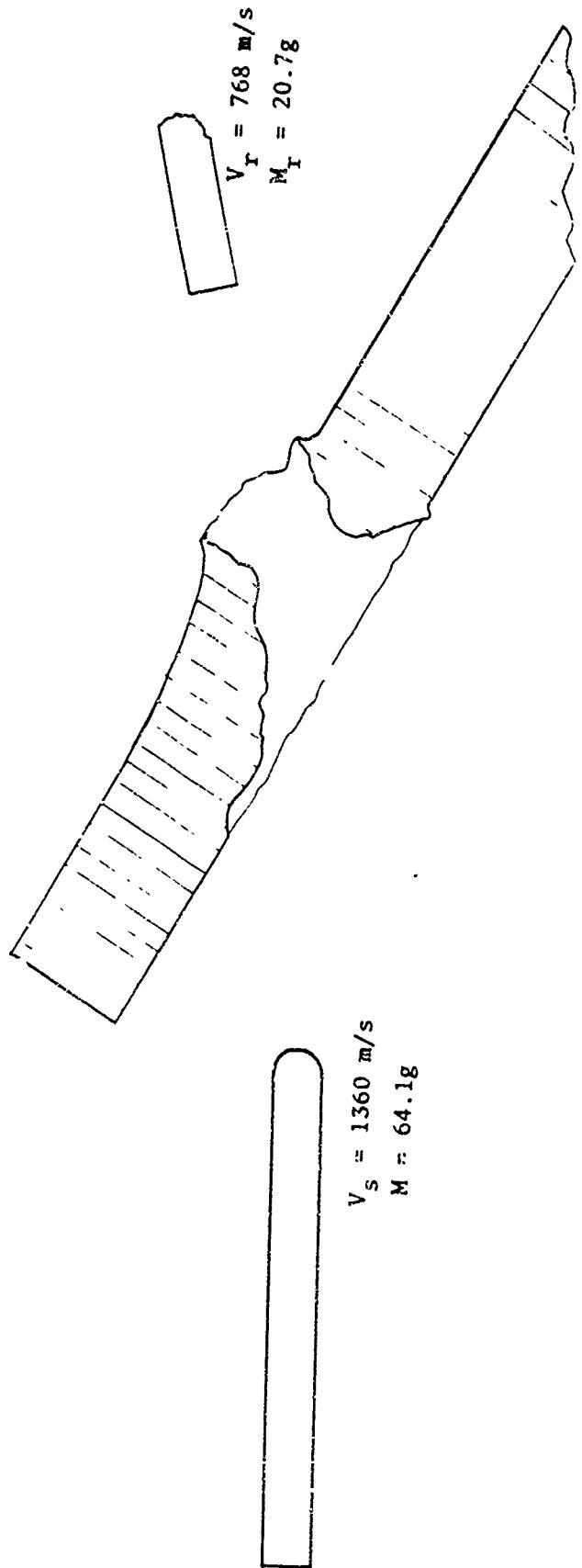


Figure D-4. Sketch for Round 261

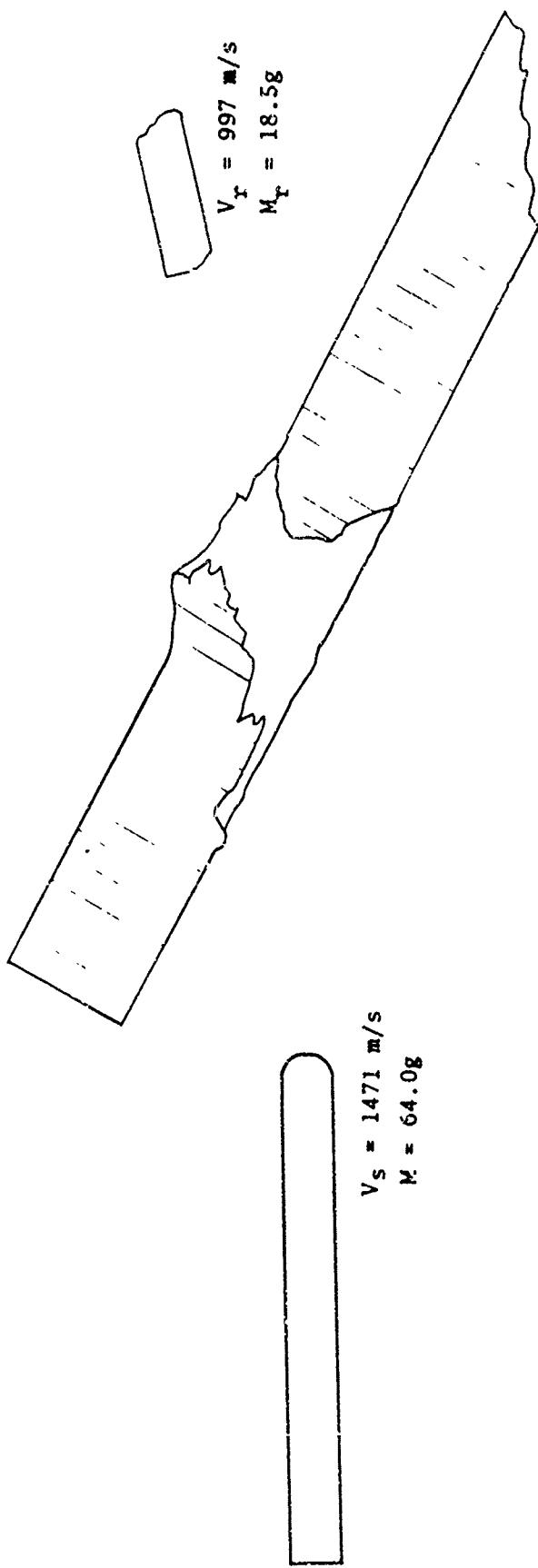


Figure D-5. Sketch for Round 265

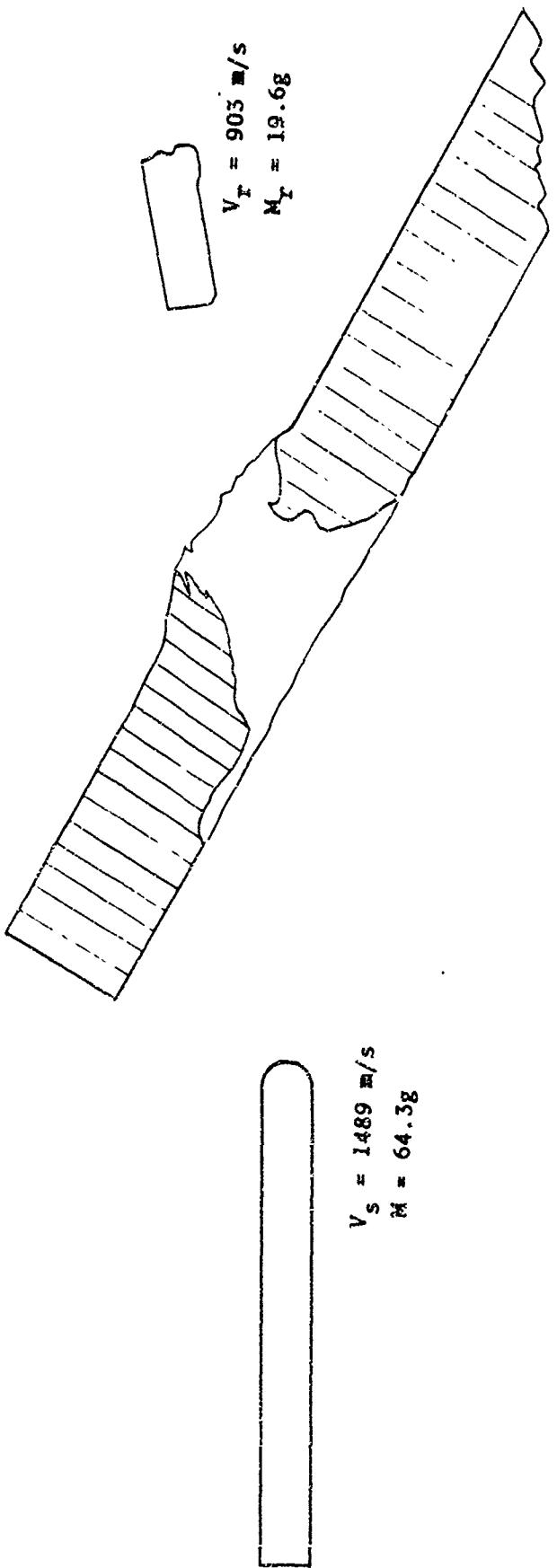


Figure D-6. Sketch for Round 260

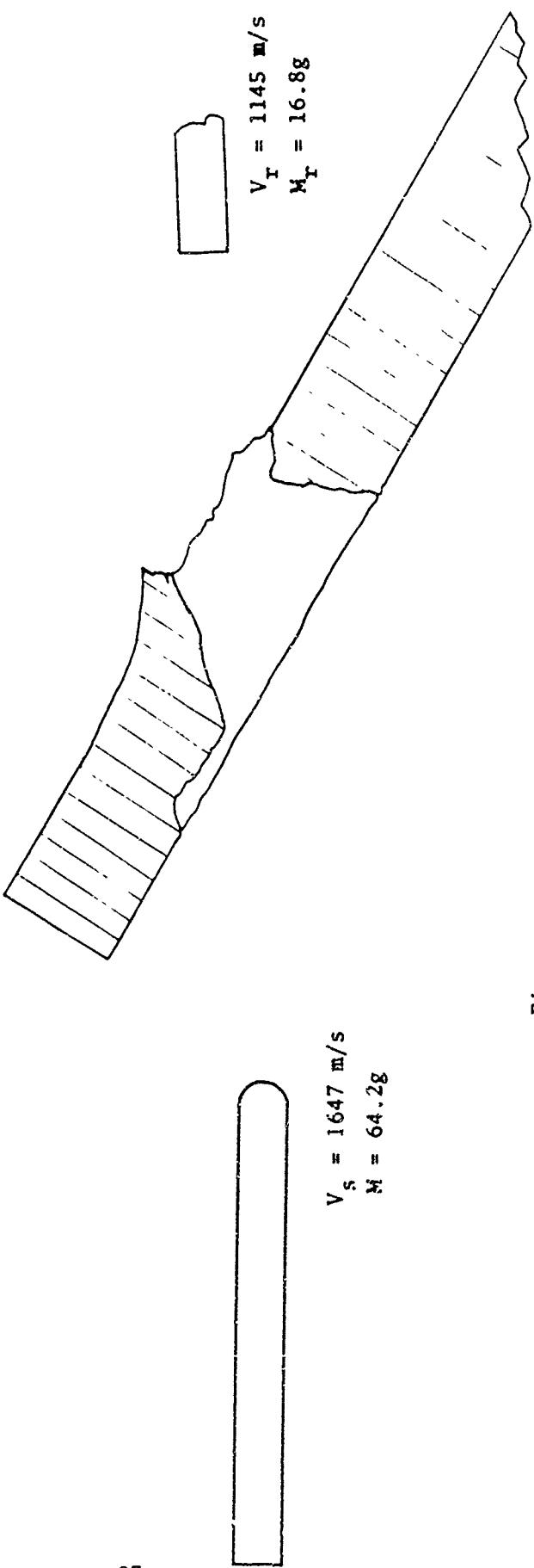


Figure D-7. Sketch for Round 259

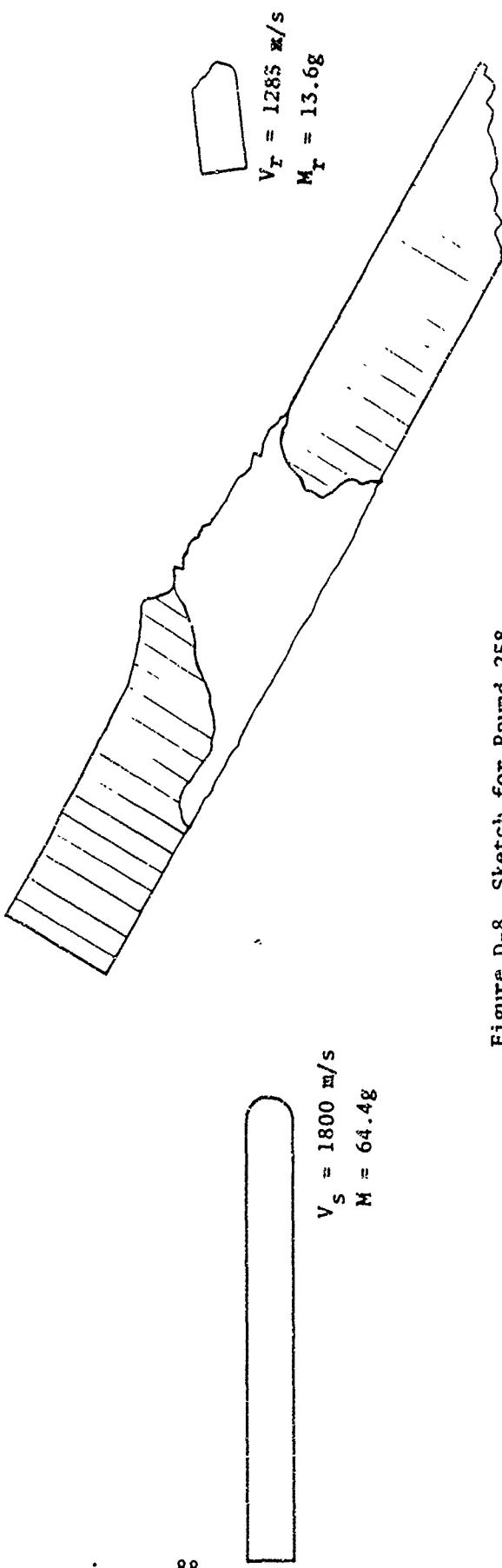


Figure D-8. Sketch for Round 258



Figure D-9. Photograph of Sectioned Targets and Residual Penetrators for ACT 19

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**APPENDIX E**  
**PREDICTED CURVES**

## APPENDIX E: PREDICTED CURVES

A predictive scheme has been formulated for obtaining limit velocity and  $V_s$ ,  $V_r$  curve estimates for situations involving long rod penetrators and single plate RHA targets<sup>4</sup>; pertinent equations are given below. For the final phase of this firing program, these equations were used to generate initial estimates of limit velocity (and of the full  $V_s$ ,  $V_r$  relationship). Figures on the following pages provide for graphic comparison between the  $V_s$ ,  $V_r$  curve predicted for the nominal situation and that derived from the experimental data for each of ACTS 16, 17, 18 and 19. In each case the data and predicted curve are graphed, and the derived curve, which also appears in Appendix B, is plotted as a dashed curve.

The predictive scheme is specified by:

$$V_r = \begin{cases} 0, & \text{if } 0 \leq V_s \leq V_x \\ a(V_s^p - V_x^p)^{1/p}, & \text{if } V_s > V_x \end{cases}$$

where

$$a = \frac{M}{M+M'/3}, \quad p = 2 + z/3,$$

$$\text{and } V_x = 4000 \left( \frac{L}{D} \right)^{1.5} \sqrt{f(z) \cdot \frac{D^3}{M}},$$

$$z = \frac{T}{D} \sec^{75} \theta, \quad f(z) = z + e^{-z} - 1.$$

$$M' = \frac{\rho \pi}{4} D^3 \cdot z, \quad \rho = 7.8,$$

and where L, D, T are in centimeters, M in grams,  $V_x$  in m/s.

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<sup>4</sup>Lambert, J. P., "A Residual Velocity Predictive Model for Long Rod Penetrators", to appear.

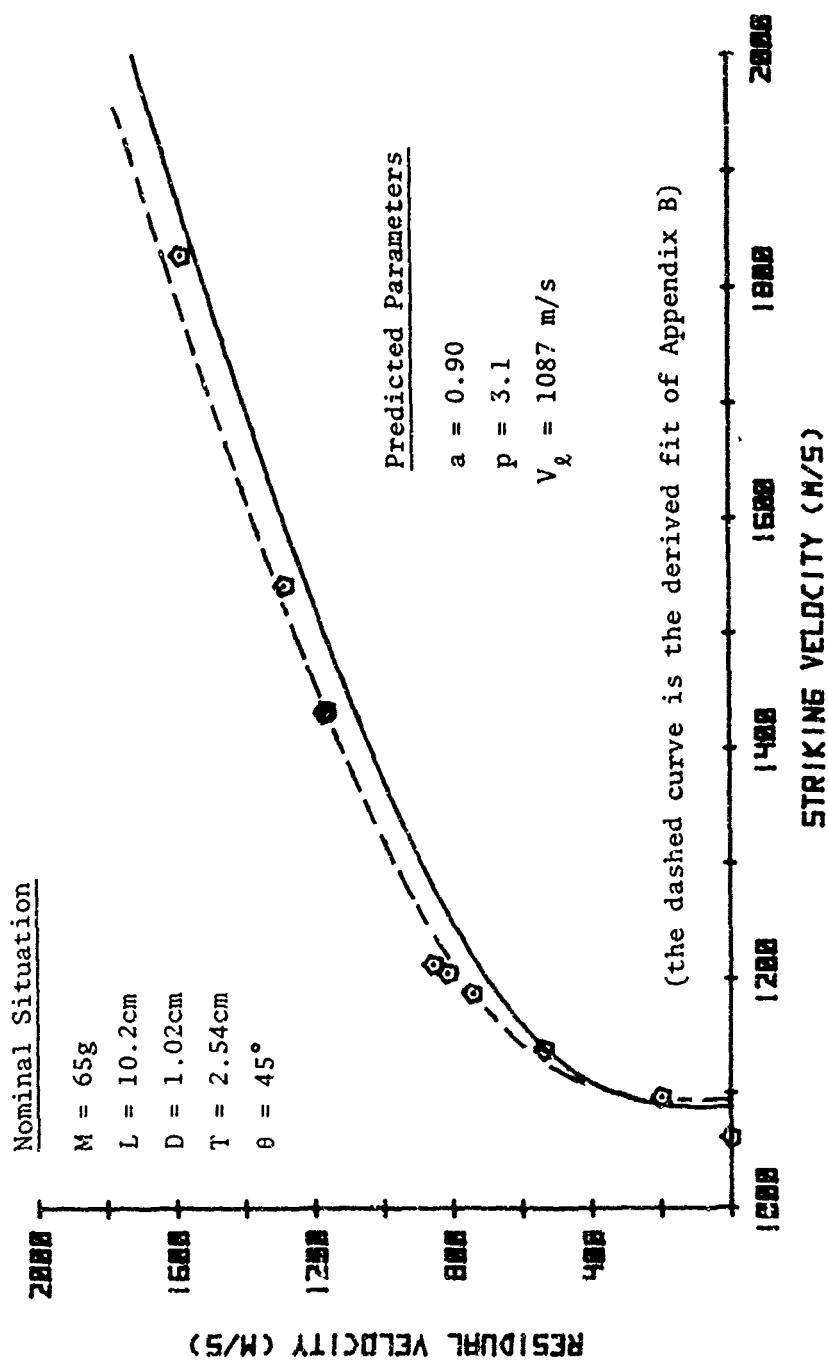


Figure E-1. Predicted  $V_s$ ,  $V_r$  Curve for ACT 16

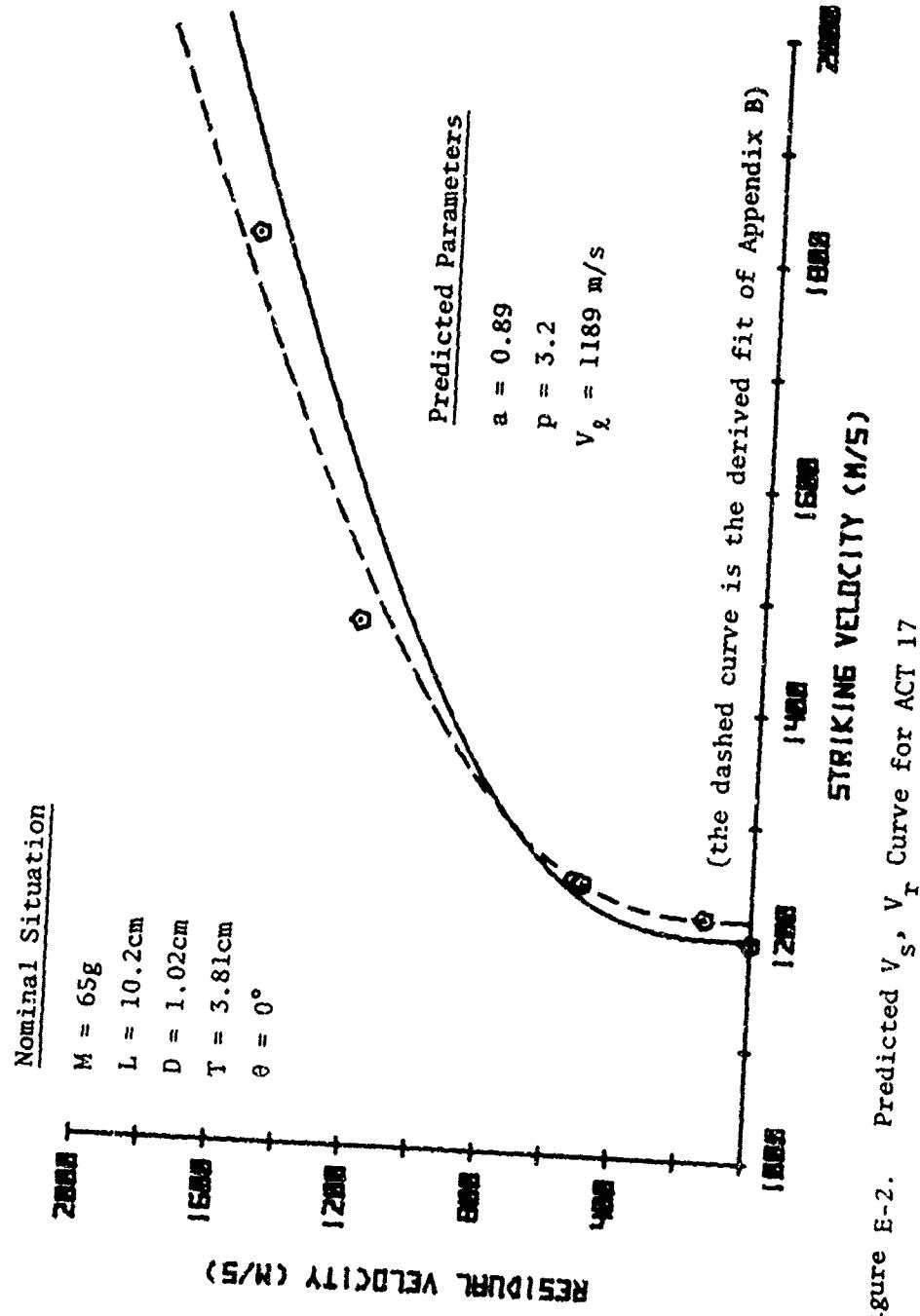


Figure E-2. Predicted  $V_s$ ,  $V_r$  Curve for ACT 17

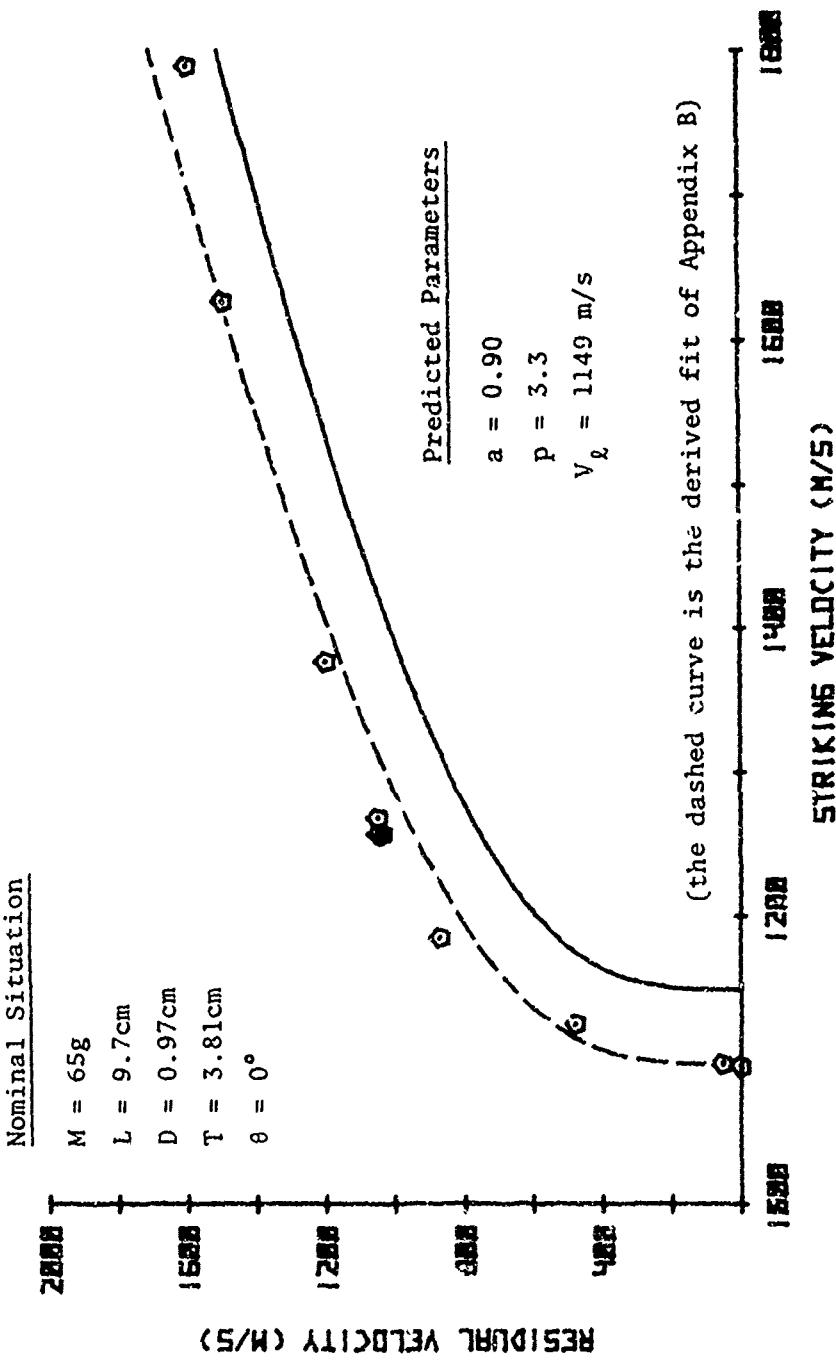


Figure E-3. Predicted  $V_s$ ,  $V_r$  Curve for ACT 18

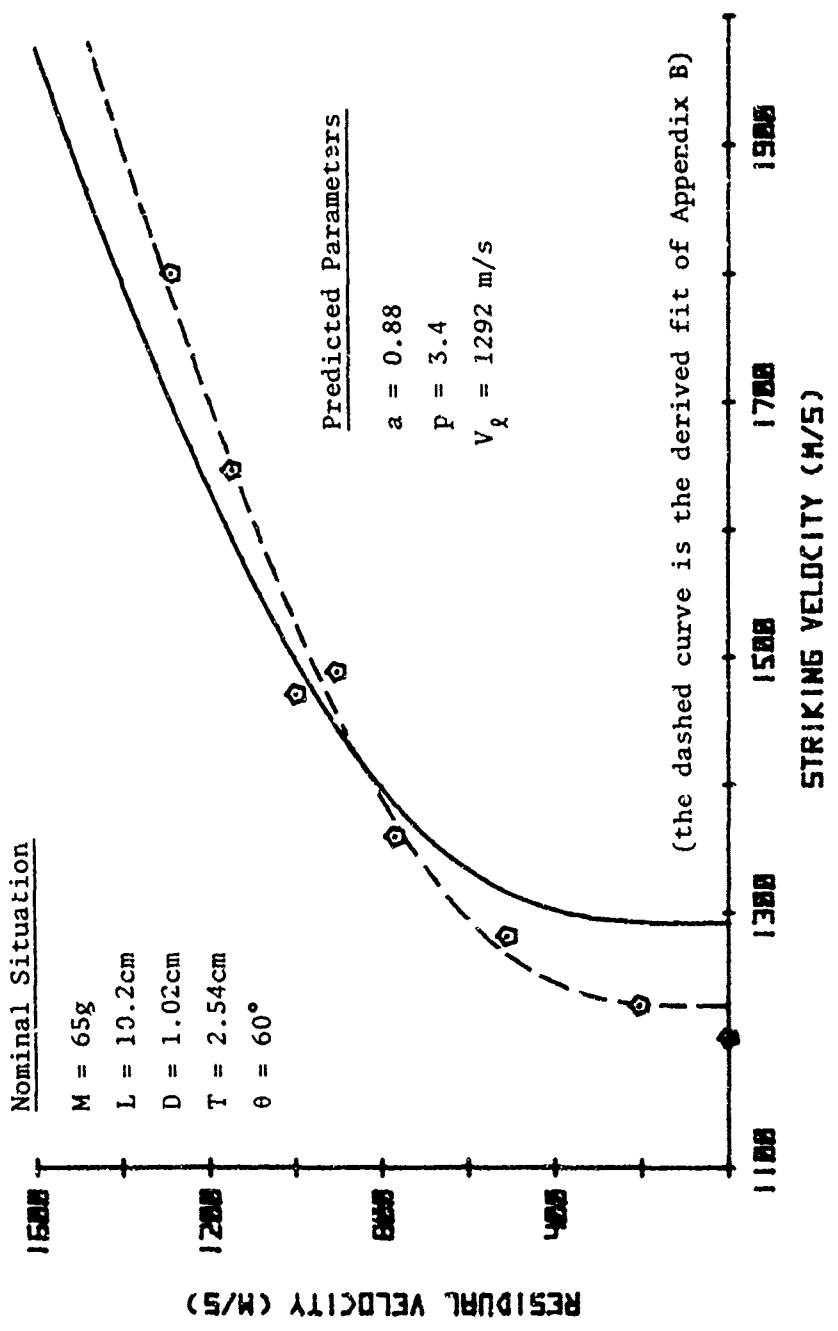


Figure E-4. Predicted  $V_s$ ,  $V_r$  Curve for ACT 19

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