The validity of weighted automata

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The results presented in this talk are based on a joint work with

Sylvain Lombardy (Univ. Bordeaux)

and have been published in International Journal of Algebra and Computation, vol. 23 (4).

Work supported by ANR Project 10-INTB-0203 VAUCANSON 2.

Outline

This work addresses, and proposes a solution to, the problem of ε -transition removal in weighted automata.

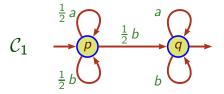
The problem lies in effectivity.

The solution is based on a new, and more constrained, definition of the validity of weighted automata.

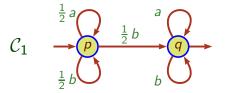
The definition insures that algorithms are successful on valid automata.

In some (interesting) cases, we are able to establish that success of algorithms implies validity of automata.

This solution provides a sound theoretical framework for the algorithms implemented in $\ensuremath{\mathrm{VAUCANSON}}.$

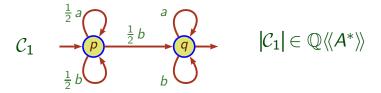


- Weight of a path c: product of the weights of transitions in c
- ▶ Weight of a word *w*: *sum* of the weights of paths with label *w*



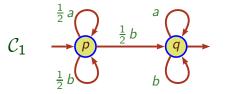
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 $\frac{1}{2} p \xrightarrow{\frac{1}{2}b} p \xrightarrow{\frac{1}{2}a} p \xrightarrow{\frac{1}{2}b} q \xrightarrow{1}$ $\frac{1}{2} p \xrightarrow{\frac{1}{2}b} q \xrightarrow{a} q \xrightarrow{b} q \xrightarrow{1}$ $bab \longmapsto \frac{1}{2} + \frac{1}{8} = \frac{5}{8} = \langle 0.101 \rangle_2 \qquad |C_1|: A^* \longrightarrow \mathbb{Q}$



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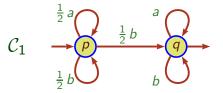
$$\frac{1}{\longrightarrow} p \xrightarrow{\frac{1}{2}b} p \xrightarrow{\frac{1}{2}a} p \xrightarrow{\frac{1}{2}b} q \xrightarrow{1}$$
$$\xrightarrow{1} p \xrightarrow{\frac{1}{2}b} q \xrightarrow{a} q \xrightarrow{b} q \xrightarrow{1}$$
$$|\mathcal{C}_1| = \frac{1}{2}b + \frac{1}{4}ab + \frac{1}{2}ba + \frac{3}{4}bb + \frac{1}{8}aab + \frac{1}{4}aba + \frac{3}{8}abb + \frac{1}{2}baa + \dots$$

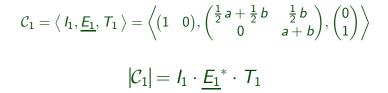


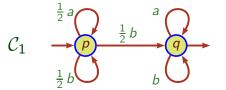
$$\mathcal{C}_{1} = \left\langle I_{1}, \underline{E_{1}}, T_{1} \right\rangle = \left\langle \begin{pmatrix} 1 & 0 \end{pmatrix}, \begin{pmatrix} \frac{1}{2}a + \frac{1}{2}b & \frac{1}{2}b \\ 0 & a+b \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\rangle$$

 $\mathcal{A} = \langle I, \underline{E}, T \rangle \qquad \underline{E} = \text{incidence matrix}$ $\underline{E}_{p,q} = \sum \{ \mathbf{wl}(e) \mid e \quad \text{transition from } p \text{ to } q \}$ $\underline{E}_{p,q}^{n} = \sum \{ \mathbf{wl}(c) \mid c \quad \text{computation from } p \text{ to } q \text{ of length } n \}$ $\underline{E}^{*} = \sum_{n \in \mathbb{N}} \underline{E}^{n}$

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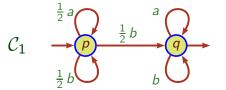






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$$|C_{1}| = I_{1} \cdot E_{1}^{*} \cdot T_{1}$$

Every \mathbb{K} -automaton defines a series in $\mathbb{K}\langle\!\langle A^* \rangle\!\rangle$ whose coefficients are effectively computable



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Every \mathbb{K} -automaton defines a series in $\mathbb{K}\langle\!\langle A^* \rangle\!\rangle$ whose coefficients are effectively computable Where is the problem ?

We want to deal with automata whose transitions may be labelled by the empty word ε

Theorem

Every ε -NFA is equivalent to an NFA

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Usefulness of ε -transitions:

Preliminary step for many constructions on NFA's:

- Product and star of position automata
- Thompson construction
- Construction of the universal automaton
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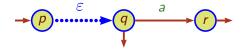
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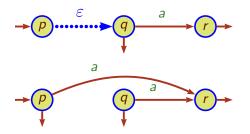
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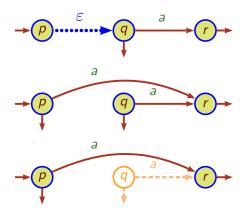
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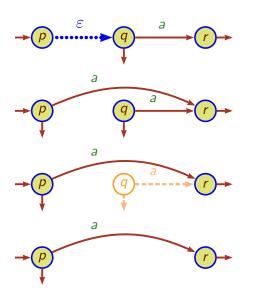
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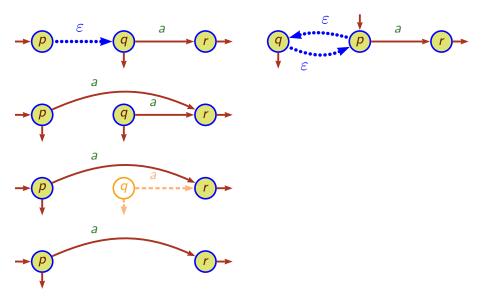
Removal of ε -transitions is implemented in all automata software

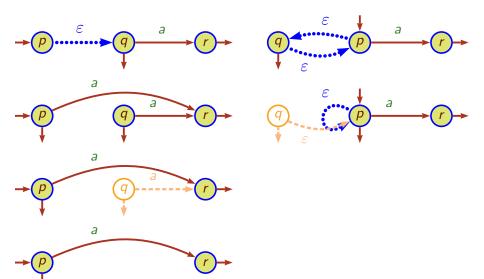


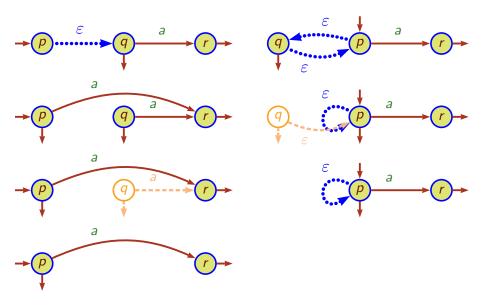


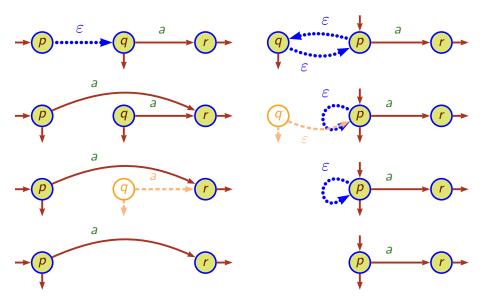












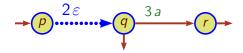
Theorem Every ε -NFA is equivalent to an NFA A proof $\mathcal{A} = \langle I, E, T \rangle$ E transition matrix of \mathcal{A} Entries of \underline{E} = subsets of $A \cup \{\varepsilon\}$ $L(\mathcal{A}) = I \cdot E^* \cdot T$ $\underline{E} = \underline{E}_0 + \underline{E}_n$ $L(\mathcal{A}) = I \cdot (\underline{E}_0 + \underline{E}_p)^* \cdot T = I \cdot (\underline{E}_0^* \cdot \underline{E}_p)^* \cdot \underline{E}_0^* \cdot T$ $\mathcal{A} = \langle I, \underline{E}, T \rangle$ equivalent to $\mathcal{B} = \langle I, \underline{E}_0^* \cdot \underline{E}_p, \underline{E}_0^* \cdot T \rangle$

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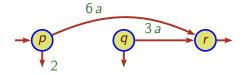
One *proof* = several *algorithms* for *computing* \underline{E}_0^* or $\underline{E}_0^* \cdot \underline{E}_p$

Question

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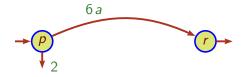
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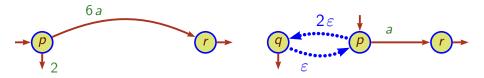
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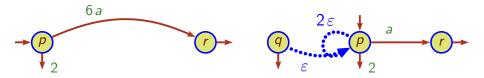
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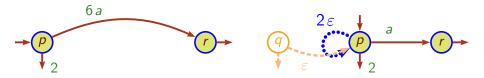
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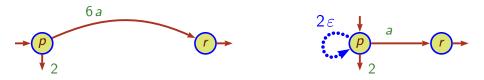
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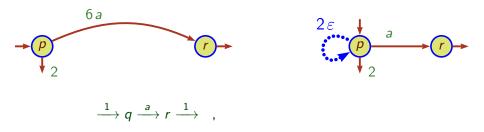
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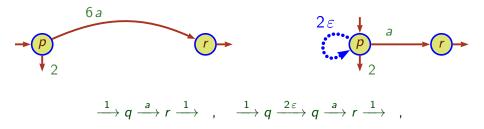
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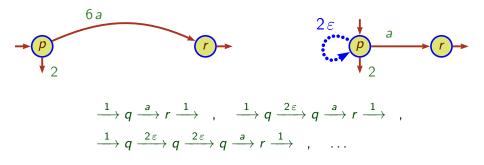
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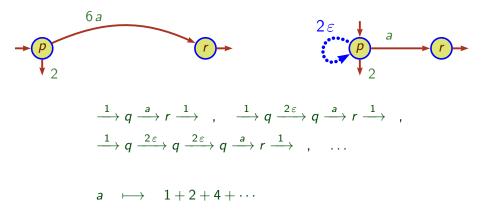
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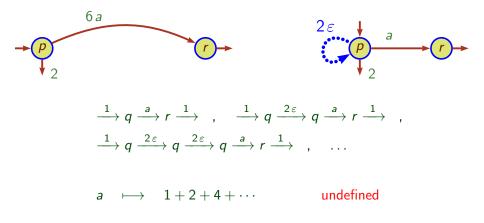
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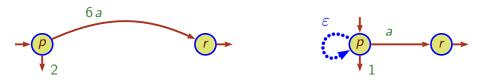
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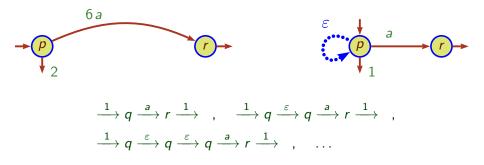
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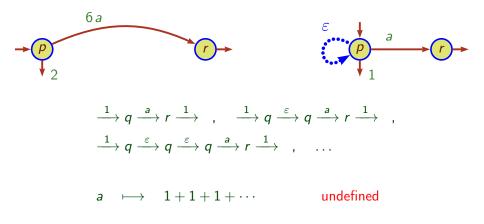
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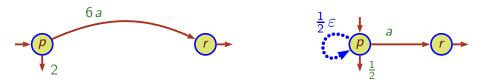
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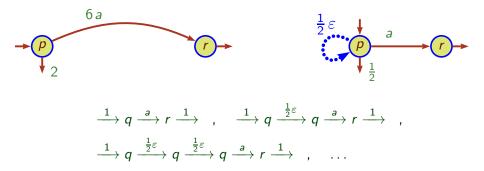
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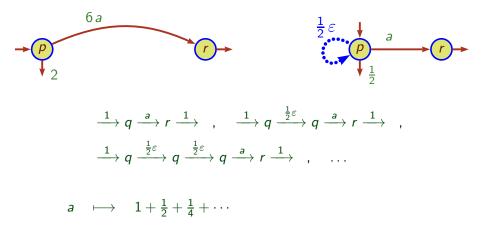
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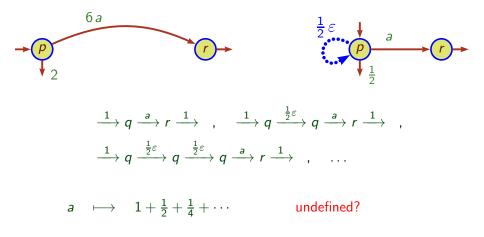
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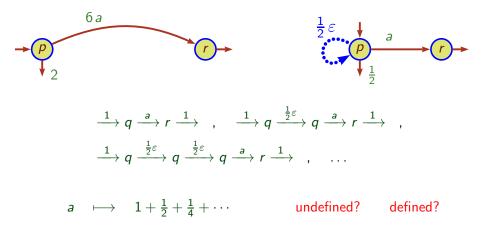
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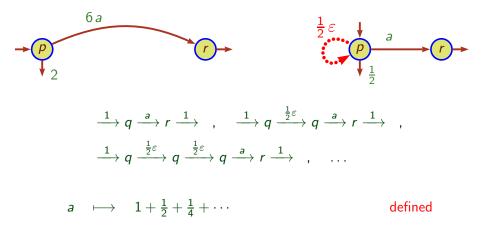
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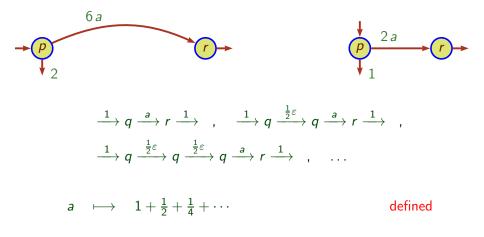
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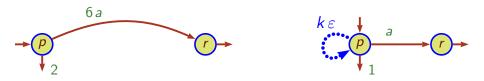
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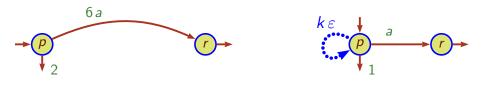
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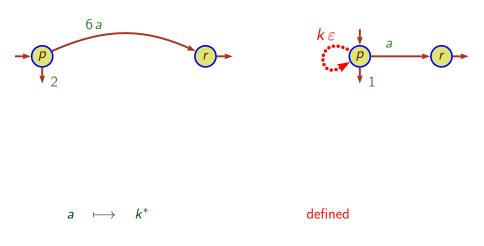


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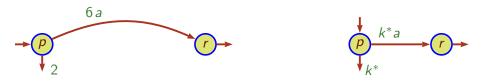




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Is every ε -WFA is equivalent to a WFA?

certainly not !

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New questions

Which ε -WFAs have a *well-defined* behaviour? i.e. are *valid* ?

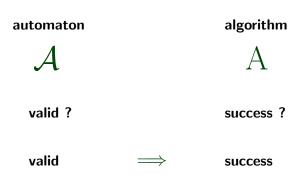
How to compute the behaviour of a *valid* ε -WFA ?

How to decide if an ε -WFA is *valid*?

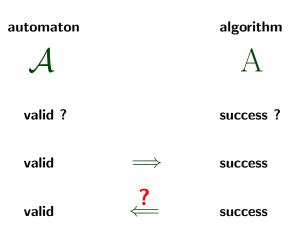
A chicken and egg problem



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$$\begin{split} \mathcal{A} &= \langle \ensuremath{\mathbb{K}}, \ensuremath{Q}, \ensuremath{A}, \ensuremath{E}, \ensuremath{I}, \ensuremath{T} \ensuremath{\rangle} \rangle & \text{possibly with ε-transitions} \\ u &\in \ensuremath{A^*} & \text{paths labelled by u in \mathcal{A} possibly infinitely many} \\ \langle |\mathcal{A}|, \ensuremath{u} \ensuremath{\rangle} & \text{sum of weights of computations labelled by u in \mathcal{A} } \end{split}$$

 $\begin{array}{ll} \mathcal{A} = \langle \, \mathbb{K}, \, Q, \, A, \, E, \, I, \, T \, \rangle & \text{possibly with } \varepsilon \text{-transitions} \\ u \in \mathcal{A}^* & \text{paths labelled by } u \text{ in } \mathcal{A} & \text{possibly infinitely many} \\ \langle |\mathcal{A}|, \, u \rangle & \text{sum of weights of computations labelled by } u \text{ in } \mathcal{A} \\ \text{Trivial case} \end{array}$

Every u in A^* is the label of a finite number of paths

 $\mathcal{A} = \langle \mathbb{K}, Q, A, E, I, T \rangle$ possibly with ε -transitions $u \in A^*$ paths labelled by u in \mathcal{A} possibly infinitely many $\langle |\mathcal{A}|, u \rangle$ sum of weights of computations labelled by u in \mathcal{A} Trivial case Every u in A^* is the label of a finite number of paths € **no circuits** of ε -transitions in \mathcal{A} acyclic \mathbb{K} -automata

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 \mathcal{A} not acyclic \Rightarrow weight of u in \mathcal{A} may be an infinite sum.

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Second solution Accepting the idea of infinite sums

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Second solution Accepting the idea of infinite sums

Topological point of view

Infinite sums are given a meaning via a topology on \mathbb{K} Topology on \mathbb{K} defines a topology on $\mathbb{K}\langle\!\langle A^* \rangle\!\rangle$ Topology allows to define summable families in $\mathbb{K}\langle\!\langle A^* \rangle\!\rangle$

$$\begin{split} \mathcal{A} &= \langle \, \mathbb{K}, Q, A, E, I, T \, \rangle & \text{possibly with } \varepsilon \text{-transitions} \\ \mathsf{P}_{\mathcal{A}} & \text{set of all paths in } \mathcal{A} \\ |\mathcal{A}| \text{ well-defined } & \qquad \mathbf{WL}(\mathsf{P}_{\mathcal{A}}) \text{ summable} \end{split}$$

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Definition taken in previous works (Lombardy, S. 03 –)

- Yields a consistent theory
- Two pitfalls for effectivity
 - effective computation of a summable family may not be possible
 - effective computation may give values to non summable families

Valid weighted automata

 $\begin{array}{ll} \mathcal{A} = \langle \, \mathbb{K}, Q, A, E, I, T \, \rangle & \text{possibly with } \varepsilon \text{-transitions} \\ E^* & \textit{free monoid generated by } E \\ \mathsf{P}_{\mathcal{A}} & \textit{set of paths in } \mathcal{A} & (\mathsf{local}) \text{ rational subset of } E^* \\ \end{array}$

DefinitionR rational family of paths of \mathcal{A} $R \in \operatorname{RatE}^* \land R \subseteq \operatorname{P}_{\mathcal{A}}$

Definition \mathcal{A} is valid iff $\forall R$ rational family of paths of \mathcal{A} , **WL**(R) is summable

Valid weighted automata

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If ${\mathcal A}$ is valid, then 'every' removal algorithm on ${\mathcal A}$ is successful

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Remark

If every (rational) subfamily of a summable family in K is summable, then validity is equivalent to well-definition of behaviour Eg. R , Q .

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Reminder

We do not know yet how to decide whether

a $\,\,\mathbb{Q}$ - or an $\,\,\mathbb{R}$ -automaton is valid.

Straightforward cases

- $\begin{array}{c} \blacktriangleright \text{ Non starable semirings (eg. } \mathbb{N}, \mathbb{Z}) \\ \mathcal{A} \text{ valid } \iff \mathcal{A} \text{ acyclic} \end{array}$
- Complete topological semirings (eg. \mathcal{N}) every \mathcal{A} valid
- Rationally additive semirings (eg. $\operatorname{Rat} A^*$) every \mathcal{A} valid
- Locally closed commutative semirings
 every \mathcal{A} valid

Definition \mathbb{K} topological, ordered, positive semiring (TOPS)is star-domain downward closed (SDC) if $\forall k, h \in \mathbb{K}, k < h$ h starable \Rightarrow k starable

 $\begin{array}{l} \mbox{Definition} \\ \mathbb{K} \mbox{ topological, ordered, positive semiring (TOPS)} \\ & \mbox{ is star-domain downward closed (SDC) if} \\ & \forall k,h \in \mathbb{K}, \ k < h \qquad h \mbox{ starable } \implies k \mbox{ starable} \end{array}$

 \mathbb{N} , \mathcal{N} , \mathbb{Q}_+ , \mathbb{R}_+ , \mathbb{Z} min, $\operatorname{Rat} A^*$,... \mathbb{N}_{∞} , (binary) positive decimals,... are TOPS SDC are TOPS not SDC

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Theorem

K topological, ordered, positive, star-domain downward closed A K-automaton is valid if, and only if, the state-by-state ε-removal algorithm succeeds

 $\begin{array}{l} \mbox{Definition} \\ \mbox{If \mathcal{A} is a \mathbb{Q}- or \mathbb{R}-automaton,} \\ & \mbox{then $abs(\mathcal{A})$ is a \mathbb{Q}_{+}- or \mathbb{R}_{+}-automaton} \end{array}$

Theorem

A \mathbb{Q} - or \mathbb{R} -automaton \mathcal{A} is valid if and only if $abs(\mathcal{A})$ is valid.

Hidden parts

- The problematic examples
- The removal algorithm itself:
 - Termination issues (weighted versus Boolean cases)
 - Complexity issues
- Automata and expressions validity
- 'Infinitary' axioms : strong, star-strong semirings
- Links with the 'axiomatic' approach (Bloom-Ésik-Kuich) : Th: A starable star-strong semiring is an iteration semiring.
- References to previous work (on removal algorithm):
 - Iocally closed srgs (Ésik–Kuich), k-closed srgs (Mohri)
 - links with other algorithms: shortest-distance algorithm (Mohri), state-elimination method (Hanneforth–Higueira)

Conclusion

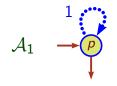
- Semiring structure is weak, topology does not help so much.
- This weakness imposes a restricted definition of validity, in order to guarantee success of validity algorithms.
- Axiomatic approach does not allow to deal wit most common numerical semirings: Zmin, Q
- On 'usual' semirings, the new definition of validity coincides with the former one.

Conclusion (2)

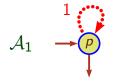
- Apart the trivial cases, and the TOPS SCD case, decision of validity is never granted, and has to be established.
- On 'usual' semirings, validity is decidable.
- The new definition of validity fills the 'effectivity gap' left open by the former one.

Hidden parts

The problematic examples





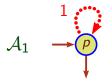


$$(1)^* = +\infty$$



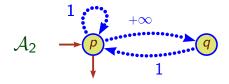


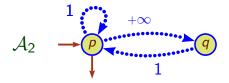


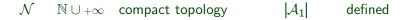


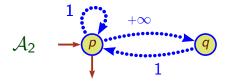
 $(1)^* = \mathsf{undefined}$

$$\begin{split} \mathbb{N} & \quad \text{natural integers} & |\mathcal{A}_1| & \text{not defined} \\ \mathcal{N} & \mathbb{N} \cup +\infty & \text{compact topology} & |\mathcal{A}_1| & \text{defined} \\ \mathbb{N}_\infty & \mathbb{N} \cup +\infty & \text{discrete topology} & |\mathcal{A}_1| & \text{not defined} \\ \end{split}$$

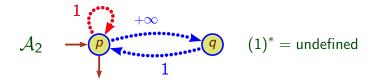








\mathcal{N}	$\mathbb{N}\cup+\infty$	compact topology	$ \mathcal{A}_1 $	defined
\mathbb{N}_{∞}	$\mathbb{N}\cup+\infty$	discrete topology	$ \mathcal{A}_1 $	defined





V

 \mathbb{S} equipped with the discrete topology

 $0_{\mathbb{S}}$, y, and $\infty_{\mathbb{S}}$ starable $x=y^2$ x not starable

V

$$\mathcal{A}_{3} \xrightarrow{\mathbf{y}} \mathcal{A}_{3}$$
$$\mathbb{S} \subset \mathbb{N}^{2\times 2}, \quad x = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = 1_{\mathbb{S}}, \quad y = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad x + y = \infty_{\mathbb{S}} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

 \mathbb{S} equipped with the discrete topology

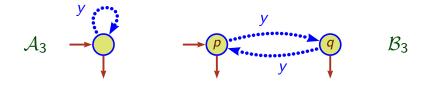
 $0_{\mathbb{S}}$, y, and $\infty_{\mathbb{S}}$ starable $x=y^2$ x not starable

$$\mathcal{A}_3 \longrightarrow \bigcup_{\infty_S}$$

$$\mathbb{S} \subset \mathbb{N}^{2 \times 2}, \quad x = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}_{\mathbb{S}}, \quad y = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad x + y = \infty_{\mathbb{S}} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

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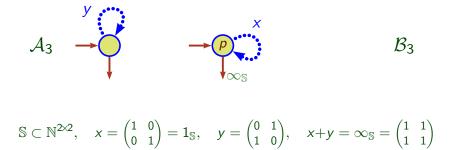
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$$\mathbb{S} \subset \mathbb{N}^{2 \times 2}, \quad x = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1}_{\mathbb{S}}, \quad y = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad x + y = \infty_{\mathbb{S}} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

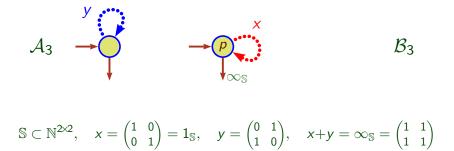
S equipped with the discrete topology

 $\mathbb{0}_{\mathbb{S}}$, y, and $\infty_{\mathbb{S}}$ starable $x=y^2$ x not starable



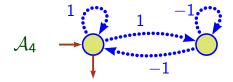
S equipped with the discrete topology

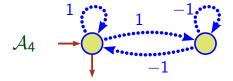
 $\mathbb{O}_{\mathbb{S}}$, y, and $\infty_{\mathbb{S}}$ starable $x=y^2$ x not starable



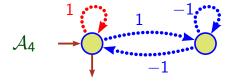
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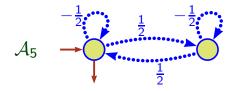


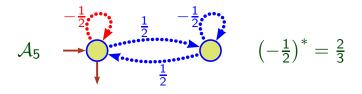


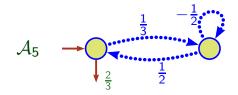
$$\mathcal{A}_{4} = \left\langle I_{4}, \underline{E_{4}}, T_{4} \right\rangle = \left\langle \begin{pmatrix} 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ -1 & -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\rangle$$
$$|\mathcal{A}_{4}| = I_{4} \cdot \underline{E_{4}}^{*} \cdot T_{4}$$
$$\underline{E_{4}}^{2} = 0 \implies \underline{E_{4}}^{*} = \begin{pmatrix} 2 & 1 \\ -1 & 0 \end{pmatrix} \implies |\mathcal{A}_{4}| = 2$$

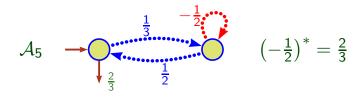


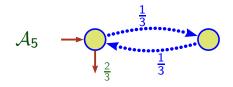
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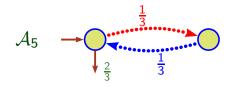




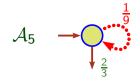












 $\left(\tfrac{1}{9}\right)^* = \tfrac{9}{8}$

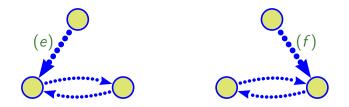




$$\mathcal{A}_{5} = \left\langle I_{5}, \underline{E_{5}}, T_{5} \right\rangle = \left\langle (1 \quad 0), \begin{pmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\rangle$$
$$\left| \mathcal{A}_{5} \right| = I_{5} \cdot \underline{E_{5}}^{*} \cdot T_{5}$$
$$\underline{E_{5}}^{3} = \underline{E_{5}} \implies \underline{E_{5}}^{*} \text{ undefined } \Longrightarrow \left| \mathcal{A}_{5} \right| \text{ undefined}$$

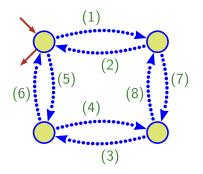
- The problematic examples
- The removal algorithm itself:
 - Termination issues (weighted versus Boolean cases)
 - Complexity issues

Termination issues



weighted ε -removal procedure does not terminate if newly created ε -transitions are stored in a stack

Termination issues



weighted ε -removal procedure does not terminate if newly created ε -transitions are stored in a queue

- The problematic examples
- The removal algorithm itself:
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 - Complexity issues
- Automata and expressions validity

'Kleene' theorem

Automata	\iff	Expressions
\mathcal{A}	\iff	E
Weighted automata	\iff	Weighted expressions

'Kleene' theorem



Notion of a valid expression

 $\mathsf{E} \ \textit{valid} \qquad \Longleftrightarrow \qquad \mathsf{c}(\mathsf{E}) \ \textit{well-defined}$

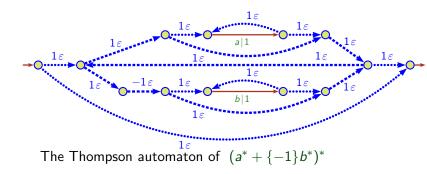
 $c(\mathsf{E})\,$ computed by a bottom-up traversal of the syntactic tree of $\,\mathsf{E}\,$

- Valid \mathcal{A} yields valid E
- Valid E yields valid \mathcal{A}
- Valid E may yield non valid A with Thompson construction

with Glushkov construction with Thompson construction

- Valid A yields valid E
- Valid E yields valid A
- Valid E may yield non valid A with Thompson construction

with Glushkov construction with Thompson construction



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Definition

A topological semiring is a *strong* semiring

if the product of two summable families is a summable family

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Definition

A topological semiring is a *strong* semiring

if the product of two summable families is a summable family

Theorem

 \mathbb{K} strong semiring $s \in \mathbb{K}\langle\!\langle A^* \rangle\!\rangle$ starable iff $s_0 \in \mathbb{K}$ starable

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Definition

A topological semiring is a *strong* semiring

if the product of two summable families is a summable family

Definition

A topological semiring is a *star-strong* semiring if the star of a summable family, whose sum is starable, is summable

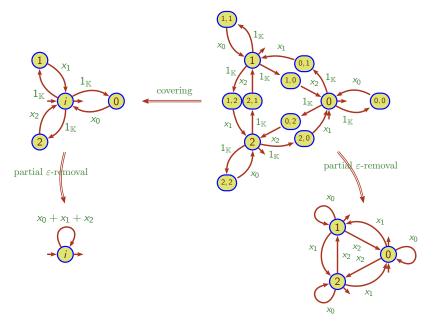
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Theorem

A starable star-strong semiring is an iteration semiring

Group identities



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- 'Infinitary' axioms : strong, star-strong semirings
- ► Links with the 'axiomatic' approach (Bloom-Ésik-Kuich):
- References to previous work (on removal algorithm):
 - locally closed srgs (Ésik–Kuich), k-closed srgs (Mohri)
 - links with other algorithms: shortest-distance algorithm (Mohri), state-elimination method (Hanneforth-Higueira)