# Two-sample test of high dimensional means under dependence 

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#### Abstract

Summary. The paper considers in the high dimensional setting a canonical testing problem in multivariate analysis, namely testing the equality of two mean vectors. We introduce a new test statistic that is based on a linear transformation of the data by the precision matrix which incorporates the correlations between the variables. The limiting null distribution of the test statistic and the power of the test are analysed. It is shown that the test is particularly powerful against sparse alternatives and enjoys certain optimality. A simulation study is carried out to examine the numerical performance of the test and to compare it with other tests given in the literature. The results show that the test proposed significantly outperforms those tests in a range of settings.


Keywords: Covariance matrix; Extreme value distribution; High dimensional test; Hypothesis testing; Limiting null distribution; Power; Precision matrix; Testing equality of mean vectors

## 1. Introduction

A canonical testing problem in multivariate analysis is that of testing the equality of two mean vectors $\boldsymbol{\mu}_{1}$ and $\boldsymbol{\mu}_{2}$ based on independent random samples, one from a distribution with mean $\boldsymbol{\mu}_{1}$ and covariance matrix $\boldsymbol{\Sigma}$ and another from a distribution with mean $\boldsymbol{\mu}_{2}$ and the same covariance matrix $\boldsymbol{\Sigma}$. This testing problem arises in many scientific applications, including genetics, econometrics and signal processing. In the Gaussian setting where one observes $\mathbf{X}_{k} \sim$ IID $N_{p}\left(\boldsymbol{\mu}_{1}, \boldsymbol{\Sigma}\right), k=1, \ldots, n_{1}$, and $\mathbf{Y}_{k} \sim$ IID $N_{p}\left(\boldsymbol{\mu}_{2}, \boldsymbol{\Sigma}\right), k=1, \ldots, n_{2}$, the classical test for testing the hypotheses

$$
\begin{equation*}
H_{0}: \boldsymbol{\mu}_{1}=\boldsymbol{\mu}_{2} \quad \text { versus } \quad H_{1}: \boldsymbol{\mu}_{1} \neq \boldsymbol{\mu}_{2} \tag{1}
\end{equation*}
$$

is Hotelling's $T^{2}$-test with the test statistic given by

$$
T^{2}=\frac{n_{1} n_{2}}{n_{1}+n_{2}}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})^{\prime} \hat{\boldsymbol{\Sigma}}^{-1}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})
$$

[^0]where $\overline{\mathbf{X}}=n_{1}^{-1} \sum_{k=1}^{n_{1}} \mathbf{X}_{k}$ and $\overline{\mathbf{Y}}=n_{2}^{-1} \sum_{k=1}^{n_{2}} \mathbf{Y}_{k}$ are the sample means and $\hat{\boldsymbol{\Sigma}}$ is the sample covariance matrix. The properties of Hotelling's $T^{2}$-test have been well studied in the conventional low dimensional setting. It enjoys desirable properties when the dimension $p$ is fixed. See, for example, Anderson (2003).

In many contemporary applications, high dimensional data, whose dimension is often comparable with or even much larger than the sample size, are commonly available. Examples include genomics, medical imaging, risk management and Web search problems. In such high dimensional settings, classical methods designed for the low dimensional case either perform poorly or are no longer applicable. For example, the performance of Hotelling's $T^{2}$-test is unsatisfactory when the dimension is high relative to the sample sizes.

Several proposals for correcting Hotelling's $T^{2}$-statistic have been introduced in high dimensional settings. For example, Bai and Saranadasa (1996) proposed to remove $\hat{\boldsymbol{\Sigma}}^{-1}$ in $T^{2}$ and introduced a new statistic based on the squared Euclidean norm $\|\overline{\mathbf{X}}-\overline{\mathbf{Y}}\|_{2}^{2}$. Srivastava and Du (2008) and Srivastava (2009) constructed test statistics by replacing $\hat{\boldsymbol{\Sigma}}^{-1}$ with the inverse of the diagonal of $\hat{\boldsymbol{\Sigma}}$. Chen and Qin (2010) introduced a test statistic by removing the cross-product terms $\sum_{i=1}^{n_{1}} \mathbf{X}_{i}^{\prime} \mathbf{X}_{i}$ and $\sum_{i=1}^{n_{2}} \mathbf{Y}_{i}^{\prime} \mathbf{Y}_{i}$ in $\|\overline{\mathbf{X}}-\overline{\mathbf{Y}}\|_{2}^{2}$. All of these test statistics are based on an estimator of $\left(\boldsymbol{\mu}_{1}-\boldsymbol{\mu}_{2}\right)^{\mathrm{T}} \mathbf{A}\left(\boldsymbol{\mu}_{1}-\boldsymbol{\mu}_{2}\right)$ for some given positive definite matrix $\mathbf{A}$. We shall call these test statistics sum-of-squares type statistics as they all aim to estimate the squared Euclidean norm $\left\|\mathbf{A}^{1 / 2}\left(\mu_{1}-\mu_{2}\right)\right\|_{2}^{2}$.

It is known that tests based on the sum-of-squares type statistics can have good power against the 'dense' alternatives, i.e. under the alternative hypothesis $H_{1}$ the signals in $\mu_{1}-\mu_{2}$ spread out over a large number of co-ordinates. For a range of applications including anomaly detection, medical imaging and genomics, however, the means of the two populations are typically either identical or are quite similar in the sense that they possibly differ in only a small number of coordinates. In other words, under the alternative $H_{1}$, the difference of the two means $\boldsymbol{\mu}_{1}-\boldsymbol{\mu}_{2}$ is sparse. For example, for ultrasonic flaw detection in highly scattering materials, many scattering centres such as grain boundaries produce echoes and the ensemble of these echoes is usually defined as background noise, whereas small cracks, flaws or other metallurgical defects would be defined as signals. See, for example, Zhang et al. (2000). In this case, it is natural to take $\boldsymbol{\mu}_{1}-\boldsymbol{\mu}_{2}$ to be sparse when the metallurgical defects exist. Similarly, for detection of hydrocarbons in materials, instantaneous spectral analysis is often used to detect hydrocarbons through low frequency shadows, which are usually considered as sparse signals. See Castagna et al. (2003). In medical imaging, magnetic resonance imaging is commonly used for breast cancer detection. It is used to visualize microcalcifications, which can be an indication of breast cancer. The signals are rare in such applications; see James et al. (2001). Another application is the shape analysis of brain structures, in which the differences in shape, if any, are commonly assumed to be confined to a small number of isolated regions inside the whole brain. This is equivalent to the sparse alternative. See Cao and Worsley (1999) and Taylor and Worsley (2008). In these sparse settings, tests based on the sum-of-squares type statistics are not powerful. For example, the three tests that were mentioned earlier all require $\left(n_{1}+n_{2}\right)\left\|\mu_{1}-\mu_{2}\right\|_{2}^{2} / p^{1 / 2} \rightarrow \infty$ for any of the tests to be able to distinguish between the null and the alternative hypotheses with probability tending to 1 .

The goal of this paper is to develop a test that performs well in general and is particularly powerful against sparse alternatives in the high dimensional setting under dependence. To explore the advantages of the dependence between the variables, we introduce a new test statistic that is based on a linear transformation of the observations by the precision matrix $\boldsymbol{\Omega}$. Suppose for the moment that the precision matrix $\boldsymbol{\Omega}=\boldsymbol{\Sigma}^{-1}$ is known. For testing the null hypothesis $H_{0}$ : $\boldsymbol{\mu}_{1}=\boldsymbol{\mu}_{2}$, we first transform the samples $\left\{\mathbf{X}_{k} ; 1 \leqslant k \leqslant n_{1}\right\}$ and $\left\{\mathbf{Y}_{k} ; 1 \leqslant k \leqslant n_{2}\right\}$ by multiplying
with $\boldsymbol{\Omega}$ to obtain the transformed samples $\left\{\boldsymbol{\Omega} \mathbf{X}_{k} ; 1 \leqslant k \leqslant n_{1}\right\}$ and $\left\{\boldsymbol{\Omega} \mathbf{Y}_{k} ; 1 \leqslant k \leqslant n_{2}\right\}$. The new test statistic is then defined to be the maximum of the squared two-sample $t$-statistics of the transformed observations $\left\{\boldsymbol{\Omega} \mathbf{X}_{k} ; 1 \leqslant k \leqslant n_{1}\right\}$ and $\left\{\boldsymbol{\Omega} \mathbf{Y}_{k} ; 1 \leqslant k \leqslant n_{2}\right\}$. We shall first show that the limiting null distribution of this test statistic is the extreme value distribution of type I , and we then construct an asymptotically $\alpha$-level test based on the limiting distribution. It is shown that this test enjoys certain optimality and uniformly outperforms two other natural tests against sparse alternatives. The asymptotic properties including the power of the tests are investigated in Section 3.

The covariance matrix $\boldsymbol{\Sigma}$ and the precision matrix $\boldsymbol{\Omega}$ are typically unknown in practice and thus need to be estimated. Estimation of $\boldsymbol{\Sigma}$ and $\boldsymbol{\Omega}$ in the high dimensional setting has been well studied in the last few years. See, for example, Yuan and Lin (2007), Bickel and Levina (2008), Rothman et al. (2008), Ravikumar et al. (2008), Cai et al. (2010), Yuan (2010), Cai and Liu (2011), Cai et al. (2011) and Cai and Yuan (2012). In particular, when $\boldsymbol{\Omega}$ is sparse, it can be well estimated by the constrained $l_{1}$-minimization method that was proposed in Cai et al. (2011). When such information is not available, the adaptive thresholding procedure that was introduced in Cai and Liu (2011) can be applied to estimate $\boldsymbol{\Sigma}$ and its inverse is then used to estimate $\Omega$. The estimate of $\Omega$ is then plugged into the test statistic mentioned above to yield a data-driven procedure. In principle, other 'good' estimators of $\boldsymbol{\Omega}$ can also be used. It is shown that, under regularity conditions, the data-driven test performs asymptotically as well as the test based on the oracle statistic and thus shares the same optimality.

A simulation study is carried out to investigate the numerical performance of the proposed test in a wide range of settings. The numerical results show that the power of the test proposed uniformly and significantly dominates those of the tests based on the sum-of-squares type statistics when either $\boldsymbol{\Sigma}$ or $\boldsymbol{\Omega}$ is sparse. When both $\boldsymbol{\Sigma}$ and $\boldsymbol{\Omega}$ are non-sparse, the proposed test with the inverse of the adaptive thresholding estimator of $\boldsymbol{\Sigma}$ still significantly outperforms the sum-of-squares type tests.

The rest of the paper is organized as follows. After reviewing basic notation and definitions, Section 2 introduces the new test statistics. Theoretical properties of the tests proposed are investigated in Section 3. Limiting null distributions of the test statistics and the power of the tests, both for the case that the precision matrix $\boldsymbol{\Omega}$ is known and the case that $\boldsymbol{\Omega}$ is unknown, are analysed. Extensions to the non-Gaussian distributions are given in Section 4. A simulation study is carried out in Section 5 to investigate the numerical performance of the tests. Discussions of the results and other related work are given in Section 6. The proofs of the main results are delegated to Appendix A. Additional simulation results and theoretical analysis are given in the on-line supplementary material.

The program that was used to analyse the data can be obtained from
http://wileyonlinelibrary.com/journal/rss-datasets

## 2. Methodology

This section considers the testing problem in the setting of Gaussian distributions. Extensions to the non-Gaussian case will be discussed in Section 4. We shall first present our testing procedure in the oracle setting in Section 2.1 where the precision matrix $\boldsymbol{\Omega}$ is assumed to be known. In addition, two other natural testing procedures are introduced in this setting. A data-driven procedure is given in Section 2.2 for the general case of the unknown precision matrix $\boldsymbol{\Omega}$ by using an estimator of the precision matrix $\Omega$.

We begin with basic notation and definitions. For a vector $\boldsymbol{\beta}=\left(\beta_{1}, \ldots, \beta_{p}\right)^{\prime} \in \mathbb{R}^{p}$, define
the $l_{q}$-norm by $|\boldsymbol{\beta}|_{q}=\left(\Sigma_{i=1}^{p}\left|\beta_{i}\right|^{q}\right)^{1 / q}$ for $1 \leqslant q \leqslant \infty$ with the usual modification for $q=\infty$. A vector $\boldsymbol{\beta}$ is called $k$ sparse if it has at most $k$ non-zero entries. For a matrix $\boldsymbol{\Omega}=\left(\omega_{i, j}\right)_{p \times p}$, the matrix 1-norm is the maximum absolute column sum, $\|\boldsymbol{\Omega}\|_{L_{1}}=\max _{1 \leqslant j \leqslant p} \Sigma_{i=1}^{p}\left|\omega_{i, j}\right|$, the matrix elementwise infinity norm is defined to be $|\boldsymbol{\Omega}|_{\infty}=\max _{1 \leqslant i, j \leqslant p}\left|\omega_{i, j}\right|$ and the elementwise $l_{1}$-norm is $\|\boldsymbol{\Omega}\|_{1}=\Sigma_{i=1}^{p} \Sigma_{j=1}^{p}\left|\omega_{i, j}\right|$. For a matrix $\boldsymbol{\Omega}$, we say that $\boldsymbol{\Omega}$ is $k$ sparse if each row or column has at most $k$ non-zero entries. We shall denote the difference $\boldsymbol{\mu}_{1}-\boldsymbol{\mu}_{2}$ by $\delta$ so the null hypothesis can be equivalently written as $H_{0}: \delta=0$. For two sequences of real numbers $\left\{a_{n}\right\}$ and $\left\{b_{n}\right\}$, write $a_{n}=O\left(b_{n}\right)$ if there is a constant $C$ such that $\left|a_{n}\right| \leqslant C\left|b_{n}\right|$ holds for all sufficiently large $n$, write $a_{n}=o\left(b_{n}\right)$ if $\lim _{n \rightarrow \infty}\left(a_{n} / b_{n}\right)=0$, and write $a_{n} \asymp b_{n}$ if there are positive constants $c$ and $C$ such that $c \leqslant a_{n} / b_{n} \leqslant C$ for all $n \geqslant 1$.

### 2.1. Oracle procedures

Suppose that we observe independent $p$-dimensional random samples

$$
\begin{aligned}
& \mathbf{x}_{1}, \ldots, \mathbf{x}_{n_{1}} \stackrel{\operatorname{IID}}{\sim} N\left(\boldsymbol{\mu}_{1}, \boldsymbol{\Sigma}\right), \\
& \mathbf{Y}_{1}, \ldots, \mathbf{Y}_{n_{2}} \stackrel{\mathrm{ID}}{\sim} N\left(\boldsymbol{\mu}_{2}, \boldsymbol{\Sigma}\right)
\end{aligned}
$$

where the precision matrix $\boldsymbol{\Omega}=\boldsymbol{\Sigma}^{-1}$ is known. In this case, the null hypothesis $H_{0}: \delta=0$ is equivalent to $H_{0}: \boldsymbol{\Omega} \boldsymbol{\delta}=0$. An unbiased estimator of $\boldsymbol{\Omega} \boldsymbol{\delta}$ is the sample mean vector $\boldsymbol{\Omega}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})=$ : $\overline{\mathbf{Z}}=\left(\bar{Z}_{1}, \ldots, \bar{Z}_{p}\right)^{\prime}$. We propose to test the null hypothesis $H_{0}: \delta=0$ on the basis of test statistic

$$
\begin{equation*}
M_{\Omega}=\frac{n_{1} n_{2}}{n_{1}+n_{2}} \max _{1 \leqslant i \leqslant p} \frac{\bar{Z}_{i}^{2}}{\omega_{i, i}} \tag{2}
\end{equation*}
$$

At first sight, the test statistic $M_{\Omega}$ is not the most intuitive choice for testing $H_{0}: \delta=0$. We first briefly illustrate the motivation on the linear transformation of the data by the precision matrix. Under a sparse alternative, the power of a test mainly depends on the magnitudes of the signals (non-zero co-ordinates of $\boldsymbol{\delta}$ ) and the number of the signals. It will be shown in Appendix A that $(\boldsymbol{\Omega})_{i}$ is approximately equal to $\delta_{i} \omega_{i, i}$ for all $i$ in the support of $\delta$. The magnitudes of the nonzero signals $\delta_{i}$ are then transformed to $\left|\delta_{i}\right| \omega_{i, i}^{1 / 2}$ after normalization by the standard deviation of the transformed variable $(\boldsymbol{\Omega} \mathbf{X})_{i}$. In comparison, the magnitudes of the signals in the original data are $\left|\delta_{i}\right| / \sigma_{i, i_{1}}^{1 / 2}$. It can be seen from the elementary inequality $\omega_{i, i} \sigma_{i, i} \geqslant 1$ for $1 \leqslant i \leqslant p$ that $\left|\delta_{i}\right| \omega_{i, i}^{1 / 2} \geqslant\left|\delta_{i}\right| / \sigma_{i, i}$, i.e. such a linear transformation magnifies the signals and the number of the signals owing to the dependence in the data. The transformation thus helps to distinguish the null and alternative hypotheses. The advantage of this linear transformation will be proved rigorously in Appendix A. In the context of signal detection under a Gaussian mixture model, Hall and Jin (2010) introduced the innovated higher criticism procedure which is also based on the transformation of a precision matrix. We should note that the innovated higher criticism procedure is only for the purpose of detection, and it does not provide an asymptotically $\alpha$-level test.

The asymptotic null distribution of $M_{\Omega}$ will be studied in Section 3. Note that $M_{\Omega}$ is the maximum of $p$ dependent normal random variables. It is well known that the limiting distribution of the maximum of $p$ independent $\chi_{1}^{2}$ random variables after normalization is the extreme value distribution of type I. This result was generalized by Berman (1964) to the dependent case, where the limiting distribution for the maximum of a stationary sequence was considered. In the setting of the present paper, the precision matrix $\boldsymbol{\Omega}$ does not have any natural order and the result in Berman (1964) thus does not apply. We shall prove by using different techniques
that $M_{\Omega}$ still converges to the extreme value distribution of type I under the null hypothesis $H_{0}$.

More generally, for a given invertible $p \times p$ matrix $\mathbf{A}$, the null hypothesis $H_{0}: \delta=0$ is equivalent to $H_{0}: \mathbf{A} \boldsymbol{\delta}=0$. Set $\delta^{\mathbf{A}}=\left(\delta_{1}^{\mathbf{A}}, \ldots, \delta_{p}^{\mathbf{A}}\right)^{\prime}:=\mathbf{A}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})$. Denote the covariance matrix of $\mathbf{A X}$ by $\mathbf{B}=\left(b_{i, j}\right)$ and define the test statistic

$$
\begin{equation*}
M_{\mathbf{A}}=\frac{n_{1} n_{2}}{n_{1}+n_{2}} \max _{1 \leqslant i \leqslant p} \frac{\left(\delta_{i}^{\mathbf{A}}\right)^{2}}{b_{i, i}} \tag{3}
\end{equation*}
$$

The most natural choices of $\mathbf{A}$ are arguably $\mathbf{A}=\boldsymbol{\Omega}^{1 / 2}$ and $\mathbf{A}=\mathbf{I}$. In the case $\mathbf{A}=\boldsymbol{\Omega}^{1 / 2}$, the components of $\boldsymbol{\Omega}^{1 / 2} \mathbf{X}$ and $\boldsymbol{\Omega}^{1 / 2} \mathbf{Y}$ are independent. Set $\overline{\mathbf{W}}=\left(\bar{W}_{1}, \ldots, \bar{W}_{p}\right)^{\prime}:=\boldsymbol{\Omega}^{1 / 2}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})$. It is natural to consider the test statistic

$$
\begin{equation*}
M_{\Omega^{1 / 2}}=\frac{n_{1} n_{2}}{n_{1}+n_{2}} \max _{1 \leqslant i \leqslant p} \bar{W}_{i}^{2} \tag{4}
\end{equation*}
$$

As we shall show later the test based on $M_{\Omega}$ uniformly outperforms the test based on $M_{\Omega^{1 / 2}}$ for testing against sparse alternatives.

Another natural choice is $\mathbf{A}=\mathbf{I}$, i.e. the test is directly based on the difference of the sample means $\overline{\mathbf{X}}-\overline{\mathbf{Y}}$. Set $\bar{\delta}=\left(\bar{\delta}_{1}, \ldots, \bar{\delta}_{p}\right)^{\prime}:=\overline{\mathbf{X}}-\overline{\mathbf{Y}}$ and define the test statistic

$$
\begin{equation*}
M_{\mathbf{I}}=\frac{n_{1} n_{2}}{n_{1}+n_{2}} \max _{1 \leqslant i \leqslant p} \frac{\bar{\delta}_{i}^{2}}{\sigma_{i, i}} \tag{5}
\end{equation*}
$$

where $\sigma_{i, i}$ are the diagonal elements of $\boldsymbol{\Sigma}$. Here $M_{\mathbf{I}}$ is the maximum of the squared two-sample $t$-statistics based on the samples $\left\{\mathbf{X}_{k}\right\}$ and $\left\{\mathbf{Y}_{k}\right\}$ directly. It will be shown that the test based on $M_{\mathbf{I}}$ is uniformly outperformed by the test based on $M_{\Omega}$ for testing against sparse alternatives.

### 2.2. Data-driven procedure

We have so far focused on the oracle case in which the precision matrix $\boldsymbol{\Omega}$ is known. However, in most applications $\boldsymbol{\Omega}$ is unknown and thus needs to be estimated. We consider in this paper two procedures for estimating the precision matrix. When $\Omega$ is known to be sparse, the constrained $l_{1}$-minimization for inverse matrix estimation (CLIME) estimator that was proposed in Cai et al. (2011) is used to estimate $\boldsymbol{\Omega}$ directly. If such information is not available, we first estimate the covariance matrix $\boldsymbol{\Sigma}$ by the inverse of the adaptive thresholding estimator $\hat{\boldsymbol{\Sigma}}^{*}$ that was introduced in Cai and Liu (2011), and then estimate $\Omega$ by $\left(\hat{\boldsymbol{\Sigma}}^{*}\right)^{-1}$.

We first consider the CLIME estimator. Let $\boldsymbol{\Sigma}_{n}$ be the pooled sample covariance matrix

$$
\left(\hat{\sigma}_{i, j}\right)_{p \times p}=\boldsymbol{\Sigma}_{n}=\frac{1}{n_{1}+n_{2}}\left\{\sum_{k=1}^{n_{1}}\left(\mathbf{X}_{k}-\overline{\mathbf{X}}\right)\left(\mathbf{X}_{k}-\overline{\mathbf{X}}\right)^{\prime}+\sum_{k=1}^{n_{2}}\left(\mathbf{Y}_{k}-\overline{\mathbf{Y}}\right)\left(\mathbf{Y}_{k}-\overline{\mathbf{Y}}\right)^{\prime}\right\} .
$$

Let $\hat{\boldsymbol{\Omega}}_{1}=\left(\hat{\omega}_{i, j}^{1}\right)$ be a solution of the optimization problem

$$
\min \|\boldsymbol{\Omega}\|_{1} \quad \text { subject to }\left|\boldsymbol{\Sigma}_{n} \boldsymbol{\Omega}-\mathbf{I}\right|_{\infty} \leqslant \lambda_{n}
$$

where $\|\cdot\|_{1}$ is the elementwise $l_{1}$-norm, and $\lambda_{n}=C\{\log (p) / n\}$ for some sufficiently large constant $C$. In practice, $\lambda_{n}$ can be chosen through cross-validation. See Cai et al. (2011) for further details. The estimator of the precision matrix $\boldsymbol{\Omega}$ is defined to be $\hat{\boldsymbol{\Omega}}=\left(\hat{\omega}_{i, j}\right)_{p \times p}$, where

$$
\hat{\omega}_{i, j}=\hat{\omega}_{j, i}=\hat{\omega}_{i, j}^{1} I\left(\left|\hat{\omega}_{i, j}^{1}\right| \leqslant\left|\hat{\omega}_{j, i}^{1}\right|\right)+\hat{\omega}_{j, i}^{1} I\left(\left|\hat{\omega}_{i, j}^{1}\right|>\left|\hat{\omega}_{j, i}^{1}\right|\right) .
$$

The estimator $\hat{\Omega}$ is called the CLIME estimator and can be implemented by linear programming.

It enjoys desirable theoretical and numerical properties. See Cai et al. (2011) for more details on the properties and implementation of this estimator.

When the precision matrix $\boldsymbol{\Omega}$ is not known to be sparse, we estimate $\boldsymbol{\Omega}$ by $\hat{\boldsymbol{\Omega}}=\left(\hat{\boldsymbol{\Sigma}}^{*}\right)^{-1}$, the inverse of the adaptive thresholding estimator of $\boldsymbol{\Sigma}$. The adaptive thresholding estimator $\hat{\boldsymbol{\Sigma}}^{*}=\left(\hat{\sigma}_{i, j}^{*}\right)_{p \times p}$ is defined by

$$
\hat{\sigma}_{i, j}^{*}=\hat{\sigma}_{i, j} I\left(\left|\hat{\sigma}_{i, j}\right| \geqslant \lambda_{i, j}\right)
$$

with $\lambda_{i, j}=\delta \sqrt{ }\left\{\hat{\theta}_{i, j} \log (p) / n\right\}$, where

$$
\begin{aligned}
& \hat{\theta}_{i, j}=\frac{1}{n_{1}+n_{2}}\left[\sum_{k=1}^{n_{1}}\left\{\left(X_{k i}-\bar{X}^{i}\right)\left(X_{k j}-\bar{X}^{j}\right)-\hat{\sigma}_{i, j}\right\}^{2}+\sum_{k=1}^{n_{2}}\left\{\left(Y_{k i}-\bar{Y}^{i}\right)\left(Y_{k j}-\bar{Y}^{j}\right)-\hat{\sigma}_{i, j}\right\}^{2}\right], \\
& \bar{X}^{i}=n_{1}^{-1} \sum_{k=1}^{n_{1}} X_{k i} \\
& \bar{Y}^{i}=n_{2}^{-1} \sum_{k=1}^{n_{2}} Y_{k i}
\end{aligned}
$$

is an estimate of $\theta_{i, j}=\operatorname{var}\left\{\left(X_{i}-\mu_{i}\right)\left(X_{j}-\mu_{j}\right)\right\}$. Here $\delta$ is a tuning parameter which can be taken as fixed at $\delta=2$ or can be chosen empirically through cross-validation. This estimator is easy to implement and it enjoys desirable theoretical and numerical properties. See Cai and Liu (2011) for more details on the properties of this estimator.

For testing the hypothesis $H_{0}: \boldsymbol{\mu}_{1}=\boldsymbol{\mu}_{2}$ in the case of unknown precision matrix $\boldsymbol{\Omega}$, motivated by the oracle procedure $M_{\Omega}$ given in Section 2.1, our final test statistic is $M_{\hat{\Omega}}$ defined by

$$
\begin{equation*}
M_{\hat{\Omega}}=\frac{n_{1} n_{2}}{n_{1}+n_{2}} \max _{1 \leqslant i \leqslant p} \frac{\hat{z}_{i}^{2}}{\hat{\omega}_{i, i}^{(0)}}, \tag{6}
\end{equation*}
$$

where $\hat{\mathbf{Z}}=\left(\hat{Z}_{1}, \ldots, \hat{Z}_{p}\right)^{\prime}:=\hat{\boldsymbol{\Omega}}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})$ and

$$
\hat{\omega}_{i, i}^{(0)}=\frac{n_{1}}{n_{1}+n_{2}} \hat{\omega}_{i, i}^{(1)}+\frac{n_{2}}{n_{1}+n_{2}} \hat{\omega}_{i, i}^{(2)}
$$

with

$$
\begin{gather*}
\left(\hat{\omega}_{i, j}^{(1)}\right):=\frac{1}{n_{1}} \sum_{k=1}^{n_{1}}\left(\hat{\boldsymbol{\Omega}} \mathbf{X}_{k}-\overline{\mathbf{X}}_{\hat{\boldsymbol{\Omega}}}\right)\left(\hat{\boldsymbol{\Omega}} \mathbf{X}_{k}-\overline{\mathbf{X}}_{\hat{\boldsymbol{\Omega}}}\right)^{\prime}, \\
\left(\hat{\omega}_{i, j}^{(2)}\right):=\frac{1}{n_{2}} \sum_{k=1}^{n_{2}}\left(\hat{\boldsymbol{\Omega}} \mathbf{Y}_{k}-\overline{\mathbf{Y}}_{\hat{\boldsymbol{\Omega}}}\right)\left(\hat{\boldsymbol{\Omega}} \mathbf{Y}_{k}-\overline{\mathbf{Y}}_{\hat{\boldsymbol{\Omega}}}\right)^{\prime}, \\
\overline{\mathbf{X}}_{\hat{\boldsymbol{\Omega}}}=n_{1}^{-1} \sum_{k=1}^{n_{1}} \hat{\boldsymbol{\Omega}} \mathbf{X}_{k} \\
\overline{\mathbf{Y}}_{\hat{\boldsymbol{\Omega}}}=n_{2}^{-1} \sum_{k=1}^{n_{2}} \hat{\boldsymbol{\Omega}} \mathbf{Y}_{k} . \tag{7}
\end{gather*}
$$

It will be shown in Section 3 that $M_{\hat{\Omega}}$ and $M_{\Omega}$ have the same asymptotic null distribution and power under certain regularity conditions. Other estimators of the precision matrix $\boldsymbol{\Omega}$ can also be used to construct a good test. See more discussion in Section 3.2.2.

Remark 1. The CLIME estimator $\hat{\boldsymbol{\Omega}}$ is positive definite with high probability when $\lambda_{\min }(\boldsymbol{\Omega})>$ $c>0$. However, for a given realization, $\hat{\boldsymbol{\Omega}}$ is not guaranteed to be positive definite. The testing
procedure still works even when $\hat{\boldsymbol{\Omega}}$ is not positive definite as the procedure uses $\hat{\boldsymbol{\Omega}}$ directly. If a positive semidefinite or positive definite estimator is still desired, the following simple additional step leads to an estimator of $\boldsymbol{\Omega}$ which is positive definite and achieves the same rate of convergence.

Write the eigendecomposition of $\hat{\boldsymbol{\Omega}}$ as $\hat{\boldsymbol{\Omega}}=\Sigma_{i=1}^{p} \hat{\lambda}_{i} v_{i} v_{i}^{\prime}$, where the $\hat{\lambda}_{i}$ s and $v_{i}$ s are respectively the eigenvalues and eigenvectors of $\hat{\boldsymbol{\Omega}}$. Set $\hat{\lambda}_{i}^{*}=\max \left\{\hat{\lambda}_{i}, 0 \log (p) / n\right\}$ and define $\hat{\boldsymbol{\Omega}}^{+}=\Sigma_{i=1}^{p} \hat{\lambda}_{i}^{*} v_{i} v_{i}^{\prime}$. Then $\hat{\boldsymbol{\Omega}}^{+}$is positive definite and attains the same rate of convergence. This method can also be applied to the adaptive thresholding estimator $\hat{\boldsymbol{\Sigma}}^{*}$ to ensure the positive definiteness of the estimator. See, for example, Cai and Zhou (2011) and Cai and Yuan (2012). All the results in the present paper hold with the estimator $\hat{\Omega}$ replaced by $\hat{\Omega}^{+}$.

## 3. Theoretical analysis

We now turn to the analysis of the properties of $M_{\Omega}$ and $M_{\hat{\Omega}}$ including the limiting null distribution and the power of the corresponding tests. It is shown that the test based on $M_{\hat{\Omega}}$ performs as well as that based on $M_{\Omega}$ and enjoys certain optimality under regularity conditions. The asymptotic null distributions of $M_{\Omega^{1 / 2}}$ and $M_{\mathbf{I}}$ are also derived and the power of the corresponding tests is studied.

### 3.1. Asymptotic distributions of the oracle test statistics

We first establish the asymptotic null distributions for the oracle test statistics $M_{\boldsymbol{\Omega}}, M_{\boldsymbol{\Omega}^{1 / 2}}$ and $M_{\mathbf{I}}$. Let $\mathbf{D}_{1}=\operatorname{diag}\left(\sigma_{1,1}, \ldots, \sigma_{p, p}\right)$ and $\mathbf{D}_{2}=\operatorname{diag}\left(\omega_{1,1}, \ldots, \omega_{p, p}\right)$, where $\sigma_{k, k}$ and $\omega_{k, k}$ are the diagonal entries of $\boldsymbol{\Sigma}$ and $\boldsymbol{\Omega}$ respectively. The correlation matrix of $\mathbf{X}$ and $\mathbf{Y}$ is then $\boldsymbol{\Gamma}=\left(\gamma_{i, j}\right)=$ $\mathbf{D}_{1}^{-1 / 2} \boldsymbol{\Sigma} \mathbf{D}_{1}^{-1 / 2}$ and the correlation matrix of $\boldsymbol{\Omega} \mathbf{X}$ and $\boldsymbol{\Omega} \mathbf{Y}$ is $\mathbf{R}=\left(r_{i, j}\right)=\mathbf{D}_{2}^{-1 / 2} \boldsymbol{\Omega} \mathbf{D}_{2}^{-1 / 2}$. To obtain the limiting null distributions, we assume that the eigenvalues of the covariance matrix $\boldsymbol{\Sigma}$ are bounded from above and below, and the correlations in $\boldsymbol{\Gamma}$ and $\mathbf{R}$ are bounded away from -1 and 1 . More specifically we assume the following conditions.

Condition 1. $C_{0}^{-1} \leqslant \lambda_{\min }(\boldsymbol{\Sigma}) \leqslant \lambda_{\max }(\boldsymbol{\Sigma}) \leqslant C_{0}$ for some constant $C_{0}>0$.
Condition 2. $\max _{1 \leqslant i<j \leqslant p}\left|\gamma_{i, j}\right| \leqslant r_{1}<1$ for some constant $0<r_{1}<1$.
Condition 3. $\max _{1 \leqslant i<j \leqslant p}\left|r_{i, j}\right| \leqslant r_{2}<1$ for some constant $0<r_{2}<1$.
Condition 1 on the eigenvalues is a common assumption in the high dimensional setting. Conditions 2 and 3 are also mild. For example, if $\max _{1 \leqslant i<j \leqslant p}\left|r_{i, j}\right|=1$, then $\Sigma$ is singular. The following theorem states the asymptotic null distributions for the three oracle statistics $M_{\Omega}$, $M_{\boldsymbol{\Omega}^{1 / 2}}$ and $M_{\mathbf{I}}$.

Theorem 1. Let the test statistics $M_{\boldsymbol{\Omega}}, M_{\boldsymbol{\Omega}^{1 / 2}}$ and $M_{\mathrm{I}}$ be defined as in equations (2), (4) and (5) respectively.
(a) Suppose that conditions 1 and 3 hold. Then, for any $x \in \mathbb{R}$,

$$
P_{H_{0}}\left[M_{\boldsymbol{\Omega}}-2 \log (p)+\log \{\log (p)\} \leqslant x\right] \rightarrow \exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\}, \quad \text { as } p \rightarrow \infty
$$

(b) For any $x \in \mathbb{R}$,

$$
P_{H_{0}}\left[M_{\Omega^{1 / 2}}-2 \log (p)+\log \{\log (p)\} \leqslant x\right] \rightarrow \exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\}, \quad \text { as } p \rightarrow \infty
$$

(c) Suppose that conditions 1 and 2 hold. Then, for any $x \in \mathbb{R}$,

$$
P_{H_{0}}\left[M_{\mathbf{I}}-2 \log (p)+\log \{\log (p)\} \leqslant x\right] \rightarrow \exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\}, \quad \text { as } p \rightarrow \infty
$$

Theorem 1 holds for any fixed sample sizes $n_{1}$ and $n_{2}$ and it shows that $M_{\boldsymbol{\Omega}}, M_{\boldsymbol{\Omega}^{1 / 2}}$ and $M_{\mathbf{I}}$ have the same asymptotic null distribution. On the basis of the limiting null distribution, three asymptotically $\alpha$-level tests can be defined as follows:

$$
\begin{aligned}
\Phi_{\alpha}(\boldsymbol{\Omega}) & =I\left[M_{\boldsymbol{\Omega}} \geqslant 2 \log (p)-\log \{\log (p)\}+q_{\alpha}\right], \\
\Phi_{\alpha}\left(\boldsymbol{\Omega}^{1 / 2}\right) & =I\left[M_{\boldsymbol{\Omega}^{1 / 2}} \geqslant 2 \log (p)-\log \{\log (p)\}+q_{\alpha}\right], \\
\Phi_{\alpha}(\mathbf{I}) & =I\left[M_{\mathbf{I}} \geqslant 2 \log (p)-\log \{\log (p)\}+q_{\alpha}\right],
\end{aligned}
$$

where $q_{\alpha}$ is the $(1-\alpha)$-quantile of the type I extreme value distribution with the cumulative distribution function

$$
\exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\}
$$

i.e.

$$
q_{\alpha}=-\log (\pi)-2 \log \left\{\log (1-\alpha)^{-1}\right\}
$$

The null hypothesis $H_{0}$ is rejected if and only if $\Phi_{\alpha}(\cdot)=1$. Although the asymptotic null distribution of the test statistics $M_{\boldsymbol{\Omega}}, M_{\mathbf{I}}$ and $M_{\boldsymbol{\Omega}^{1 / 2}}$ are the same, the power of the tests $\Phi_{\alpha}(\boldsymbol{\Omega})$, $\Phi_{\alpha}\left(\boldsymbol{\Omega}^{1 / 2}\right)$ and $\Phi_{\alpha}(\mathbf{I})$ are quite different. We show in section 1 in the on-line supplementary material that the power of $\Phi_{\alpha}(\boldsymbol{\Omega})$ uniformly dominates those of $\Phi_{\alpha}\left(\boldsymbol{\Omega}^{1 / 2}\right)$ and $\Phi_{\alpha}(\mathbf{I})$ when testing against sparse alternatives, and the results are briefly summarized in Section 3.2.3.

### 3.2. Asymptotic properties of $\Phi_{\alpha}(\Omega)$ and $\Phi_{\alpha}(\hat{\Omega})$

In this section, the asymptotic power of $M_{\Omega}$ is analysed and the test $\Phi_{\alpha}(\boldsymbol{\Omega})$ is shown to be minimax rate optimal. In practice, $\Omega$ is unknown and the test statistic $M_{\hat{\Omega}}$ should be used instead of $M_{\Omega}$. Define the set of $k_{p}$-sparse vectors by

$$
\mathcal{S}\left(k_{p}\right)=\left\{\delta: \sum_{j=1}^{p} I\left(\delta_{j} \neq 0\right)=k_{p}\right\} .
$$

Throughout the section, we analyse the power of $M_{\Omega}$ and $M_{\hat{\Omega}}$ under the alternative
$H_{1}: \delta \in \mathcal{S}\left(k_{p}\right)$ with $k_{p}=p^{r}, 0 \leqslant r<1$, and the non-zero locations are randomly uniformly drawn from $\{1, \ldots, p\}$.

Under $H_{1}$, we let $\left(\mathbf{X}-\boldsymbol{\mu}_{1}, \mathbf{Y}-\boldsymbol{\mu}_{2}\right)$ be independent with the non-zero locations of $\boldsymbol{\delta}$. As discussed in Section 1, the condition on the non-zero co-ordinates in $H_{1}$ is mild. Similar conditions have been imposed in Hall and Jin $(2008,2010)$ and Arias-Castro et al. (2011). We show that, under certain sparsity assumptions on $\Omega, M_{\hat{\Omega}}$ performs as well as $M_{\boldsymbol{\Omega}}$ asymptotically. For the following sections, we assume that $n_{1} \asymp n_{2}$ and write $n=n_{1} n_{2} /\left(n_{1}+n_{2}\right)$.

### 3.2.1. Asymptotic power and optimality of $\Phi_{\alpha}(\boldsymbol{\Omega})$

The asymptotic power of $\Phi_{\alpha}(\boldsymbol{\Omega})$ is analysed under certain conditions on the separation between
$\boldsymbol{\mu}_{1}$ and $\boldsymbol{\mu}_{2}$. Furthermore, a lower bound is derived to show that this condition is minimax rate optimal to distinguish $H_{1}$ and $H_{0}$ with probability tending to 1 .

Theorem 2. Suppose that condition 1 holds. Under the alternative $H_{1}$ with $r<\frac{1}{4}$, if $\max _{i}\left|\delta_{i} / \sigma_{i, i}^{1 / 2}\right| \geqslant \sqrt{ }\{2 \beta \log (p) / n\}$ with $\beta \geqslant 1 / \min _{i}\left(\sigma_{i, i} \omega_{i, i}\right)+\varepsilon$ for some constant $\varepsilon>0$, then as $p \rightarrow \infty$

$$
P_{H_{1}}\left\{\Phi_{\alpha}(\boldsymbol{\Omega})=1\right\} \rightarrow 1
$$

We shall show that the condition $\max _{i}\left|\delta_{i} / \sigma_{i, i}^{1 / 2}\right| \geqslant \sqrt{ }\{2 \beta \log (p) / n\}$ is minimax rate optimal for testing against sparse alternatives. First we introduce some conditions.

Condition 4.
(a) $k_{p}=p^{r}$ for some $r<\frac{1}{2}$ and $\boldsymbol{\Omega}=\boldsymbol{\Sigma}^{-1}$ is $s_{p}$ sparse with $s_{p}=O\left\{\left(p / k_{p}^{2}\right)^{\gamma}\right\}$ for some $0<\gamma<1$, or
(b) $k_{p}=p^{r}$ for some $r<\frac{1}{4}$.

Condition 5. $\|\boldsymbol{\Omega}\|_{L_{1}} \leqslant M$ for some constant $M>0$.
Define the class of $\alpha$-level tests by

$$
\mathcal{T}_{\alpha}=\left\{\Phi_{\alpha}: P_{H_{0}}\left(\Phi_{\alpha}=1\right) \leqslant \alpha\right\}
$$

The following theorem shows that the condition $\max _{i}\left|\delta_{i} / \sigma_{i, i}^{1 / 2}\right| \geqslant \sqrt{ }\{2 \beta \log (p) / n\}$ is minimax rate optimal.

Theorem 3. Assume that conditions 4(a) (or 4(b)) and 5 hold. Let $\alpha, \nu>0$ and $\alpha+\nu<1$. Then there is a positive constant $c$ such that, for all sufficiently large $n$ and $p$,

$$
\inf _{\delta \in \mathcal{S}\left(k_{p}\right) \cap\left\{|\delta|_{\infty} \geqslant c \sqrt{ }\{\log (p) / n\}\right\}} \sup _{\Phi_{\alpha} \in \mathcal{T}_{\alpha}} P\left(\Phi_{\alpha}=1\right) \leqslant 1-\nu .
$$

Theorem 3 shows that, if $c$ is sufficiently small, then any $\alpha$-level test is unable to reject the null hypothesis correctly uniformly over $\delta \in \mathcal{S}\left(k_{p}\right) \cap\left\{|\delta|_{\infty} \geqslant c \sqrt{ }\{\log (p) / n\}\right\}$ with probability tending to 1 . So the order of the lower bound $\max _{i}\left|\delta_{i} / \sigma_{i, i}^{1 / 2}\right| \geqslant \sqrt{ }\{2 \beta \log (p) / n\}$ cannot be improved.

### 3.2.2. Asymptotic properties and optimality of $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$

We now analyse the properties of $M_{\hat{\Omega}}$ and the corresponding test including the limiting null distribution and the asymptotic power. We shall assume that the estimator $\hat{\boldsymbol{\Omega}}=\left(\hat{\omega}_{i, j}\right)$ has at least a logarithmic rate of convergence

$$
\begin{gather*}
\|\hat{\boldsymbol{\Omega}}-\boldsymbol{\Omega}\|_{L_{1}}=o_{\mathrm{P}}\left\{\frac{1}{\log (p)}\right\}, \\
\max _{1 \leqslant i \leqslant p}\left|\hat{\omega}_{i, i}-\omega_{i, i}\right|=o_{\mathrm{P}}\left\{\frac{1}{\log (p)}\right\} . \tag{8}
\end{gather*}
$$

This is a rather weak requirement on $\hat{\boldsymbol{\Omega}}$ and, as will be shown later, can be easily satisfied by the CLIME estimator or the inverse of the adaptive thresholding estimator for a wide range of covariance or precision matrices. We shall show that under condition (8) $M_{\hat{\Omega}}$ has the same limiting null distribution as $M_{\boldsymbol{\Omega}}$. Define the corresponding test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ by

$$
\Phi_{\alpha}(\hat{\Omega})=I\left[M_{\hat{\Omega}} \geqslant 2 \log (p)-\log \{\log (p)\}+q_{\alpha}\right] .
$$

The following theorem shows that $M_{\hat{\Omega}}$ and $M_{\Omega}$ have the same asymptotic distribution and power under condition (8), and so the test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ is also minimax rate optimal.

Theorem 4. Suppose that $\hat{\boldsymbol{\Omega}}$ satisfies condition (8) and conditions 1 and 3 hold.
(a) Then under the null hypothesis $H_{0}$, for any $x \in \mathbb{R}$,

$$
P_{H_{0}}\left[M_{\hat{\Omega}}-2 \log (p)+\log \{\log (p)\} \leqslant x\right] \rightarrow \exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\}, \quad \text { as } n, p \rightarrow \infty
$$

(b) Under the alternative hypothesis $H_{1}$ with $r<\frac{1}{6}$, we have, as $n, p \rightarrow \infty$,

$$
\frac{P_{H_{1}}\left\{\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})=1\right\}}{P_{H_{1}}\left\{\Phi_{\alpha}(\boldsymbol{\Omega})=1\right\}} \rightarrow 1
$$

Furthermore, if $\max _{i}\left|\delta_{i} / \sigma_{i, i}^{1 / 2}\right| \geqslant \sqrt{ }\{2 \beta \log (p) / n\}$ with $\beta \geqslant 1 / \min _{i}\left(\sigma_{i, i} \omega_{i, i}\right)+\varepsilon$ for some constant $\varepsilon>0$, then

$$
P_{H_{1}}\left\{\Phi_{\alpha}(\hat{\Omega})=1\right\} \rightarrow 1, \quad \text { as } n, p \rightarrow \infty
$$

As mentioned earlier, condition (8) is quite weak and is satisfied by the CLIME estimator or the inverse of the adaptive thresholding estimator for a wide range of precision or covariance matrices. It is helpful to give a few examples of collections of precision or covariance matrices for which condition (8) holds.

We first consider the following class of precision matrices that satisfy an $l_{q}$-ball constraint for each row or column. Let $0 \leqslant q<1$ and define

$$
\begin{equation*}
\mathcal{U}_{q}\left(s_{p, 1}, M_{p}\right)=\left\{\boldsymbol{\Omega} \succ 0:\|\boldsymbol{\Omega}\|_{L_{1}} \leqslant M_{p}, \max _{1 \leqslant j \leqslant p} \sum_{i=1}^{p}\left|\omega_{i, j}\right|^{q} \leqslant s_{p, 1}\right\} \tag{9}
\end{equation*}
$$

The class $\mathcal{U}_{q}\left(s_{p, 1}, M_{p}\right)$ covers a range of precision matrices as the parameters $q, s_{p, 1}$ and $M_{p}$ vary. Using the techniques in Cai et al. (2011), proposition 1 below shows that condition (8) holds for the CLIME estimator if $\Omega \in \mathcal{U}_{q}\left(s_{p}, M_{p}\right)$ with

$$
\begin{equation*}
s_{p, 1}=o\left\{\frac{n^{(1-q) / 2}}{M_{p}^{1-q} \log (p)^{(3-q) / 2}}\right\} \tag{10}
\end{equation*}
$$

We now turn to the covariance matrices. Consider a large class of covariance matrices defined by, for $0 \leqslant q<1$,

$$
\begin{equation*}
\mathcal{U}_{q}^{*}\left(s_{p, 2}, M_{p}\right)=\left\{\boldsymbol{\Sigma}: \Sigma \succ 0,\left\|\boldsymbol{\Sigma}^{-1}\right\|_{L_{1}} \leqslant M_{p}, \max _{i} \sum_{j=1}^{p}\left(\sigma_{i, i} \sigma_{j, j}\right)^{(1-q) / 2}\left|\sigma_{i, j}\right|^{q} \leqslant s_{p, 2}\right\} \tag{11}
\end{equation*}
$$

Matrices in $\mathcal{U}_{q}^{*}\left(s_{p, 2}\right)$ satisfy a weighted $l_{q}$-ball constraint for each row or column. Let $\hat{\boldsymbol{\Omega}}=\left(\hat{\boldsymbol{\Sigma}}^{*}\right)^{-1}$, where $\hat{\boldsymbol{\Sigma}}^{*}$ is the adaptive thresholding estimator that was defined in Section 2.2. Then proposition 1 below shows that condition (8) is satisfied by $\hat{\boldsymbol{\Omega}}$ if $\boldsymbol{\Sigma} \in \mathcal{U}_{q}^{*}\left(s_{p, 2}, M_{p}\right)$ with

$$
\begin{equation*}
s_{p, 2}=o\left\{\frac{n^{(1-q) / 2}}{M_{p}^{2} \log (p)^{(3-q) / 2}}\right\} . \tag{12}
\end{equation*}
$$

Besides the class of covariance matrices $\mathcal{U}_{q}^{*}\left(s_{p, 2}, M_{p}\right)$ that is given in expression ( 11 ), condition (8) is also satisfied by the inverse of the adaptive thresholding estimator $\hat{\boldsymbol{\Omega}}=\left(\hat{\boldsymbol{\Sigma}}^{*}\right)^{-1}$ over the class of bandable covariance matrices defined by

$$
\mathcal{F}_{\alpha}\left(M_{1}, M_{2}\right)=\left\{\boldsymbol{\Sigma}: \boldsymbol{\Sigma} \succ 0,\left\|\boldsymbol{\Sigma}^{-1}\right\|_{L_{1}} \leqslant M_{1}, \max _{j} \sum_{i:|i-j|>k}\left|\sigma_{i, j}\right| \leqslant M_{2} k^{-\alpha}, \text { for } k \geqslant 1\right\}
$$

where $\alpha>0, M_{1}>0$ and $M_{2}>0$. This class of covariance matrices arises naturally in time series analysis. See Cai et al. (2010) and Cai and Zhou (2012).

Proposition 1. Suppose that $\log (p)=o\left(n^{1 / 3}\right)$ and condition 1 holds. Then the CLIME estimator for $\boldsymbol{\Omega} \in \mathcal{U}_{q}\left(s_{p, 1}, M_{p}\right)$ with expression (10) satisfies condition (8). Similarly, the inverse of the adaptive thresholding estimator of $\boldsymbol{\Sigma} \in \mathcal{U}_{q}^{*}\left(s_{p, 2}, M_{p}\right)$ with equation (12) or $\boldsymbol{\Sigma} \in \mathcal{F}_{\alpha}\left(M_{1}, M_{2}\right)$ with $\log (p)=o\left(n^{\alpha /(4+3 \alpha)}\right)$ satisfies condition (8).

We should note that the conditions (8), (10) and (12) are technical conditions and they can be further weakened. For example, the following result holds without imposing a sparsity condition on $\Omega$.

Theorem 5. Let $\hat{\boldsymbol{\Omega}}$ be the CLIME estimator. Suppose that conditions 1 and 3 hold and $\min _{i} \omega_{i, i} \geqslant c$ for some $c>0$. If $\|\boldsymbol{\Omega}\|_{L_{1}} \leqslant M_{p}$ and

$$
\begin{equation*}
M_{p}^{2}=o\left\{\sqrt{ } n / \log (p)^{3 / 2}\right\} \tag{13}
\end{equation*}
$$

then

$$
P_{H_{0}}\left\{\Phi_{\alpha}(\hat{\Omega})=1\right\} \leqslant \alpha+o(1), \quad \text { as } n, p \rightarrow \infty
$$

Furthermore, if $\max _{i}\left|\delta_{i} / \sigma_{i, i}^{1 / 2}\right| \geqslant \sqrt{ }\{2 \beta \log (p) / n\}$ with $\beta \geqslant 1 / \min _{i}\left(\sigma_{i, i} \omega_{i, i}\right)+\varepsilon$ for some constant $\varepsilon>0$, then

$$
P_{H_{1}}\left\{\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})=1\right\} \rightarrow 1, \quad \text { as } n, p \rightarrow \infty
$$

### 3.2.3. Power comparison of the oracle tests

The tests $\Phi_{\alpha}(\boldsymbol{\Omega})$ and $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ are shown in Sections 3.2.1 and 3.2.2 to be minimax rate optimal for testing against sparse alternatives. Under some additional regularity conditions, it can be shown that the test $\Phi_{\alpha}(\boldsymbol{\Omega})$ is uniformly at least as powerful as both $\Phi_{\alpha}\left(\boldsymbol{\Omega}^{1 / 2}\right)$ and $\Phi_{\alpha}(\mathbf{I})$, and the results are stated in proposition 1 in the on-line supplementary material. Furthermore, we show that, for a class of alternatives, the test $\Phi_{\alpha}(\boldsymbol{\Omega})$ is strictly more powerful than both $\Phi_{\alpha}\left(\boldsymbol{\Omega}^{1 / 2}\right)$ and $\Phi_{\alpha}(\mathbf{I})$. For further details, see propositions 2 and 3 in the on-line supplementary material. However, we should also note that the relative performance of the three oracle tests $\Phi_{\alpha}(\boldsymbol{\Omega})$, $\Phi_{\alpha}\left(\boldsymbol{\Omega}^{1 / 2}\right)$ and $\Phi_{\alpha}(\mathbf{I})$ is not clear in the non-sparse case. It is possible, for example, when $k_{p}=p^{r}$ for some $r>\frac{1}{2}$, that $\Phi_{\alpha}(\boldsymbol{\Omega})$ might be outperformed by $\Phi_{\alpha}\left(\boldsymbol{\Omega}^{1 / 2}\right)$ or $\Phi_{\alpha}(\mathbf{I})$.

## 4. Extension to non-Gaussian distributions

We have so far focused on the Gaussian setting and studied the asymptotic null distributions and power of the tests. In this section, the results for the tests $\Phi_{\alpha}(\boldsymbol{\Omega})$ and $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ are extended to non-Gaussian distributions.

We require some moment conditions on the distributions of $\mathbf{X}$ and $\mathbf{Y}$. Let $\mathbf{X}$ and $\mathbf{Y}$ be two $p$-dimensional random vectors satisfying

$$
\mathbf{X}=\boldsymbol{\mu}_{1}+\mathbf{U}_{1} \quad \text { and } \quad \mathbf{Y}=\boldsymbol{\mu}_{2}+\mathbf{U}_{2}
$$

where $\mathbf{U}_{1}$ and $\mathbf{U}_{2}$ are independent and identically distributed random vectors with mean 0 and covariance matrix $\boldsymbol{\Sigma}=\left(\sigma_{i, j}\right)_{p \times p}$. Let $\mathbf{V}_{j}=\boldsymbol{\Omega} \mathbf{U}_{j}=:\left(V_{1 j}, \ldots, V_{p j}\right)^{\prime}$ for $j=1,2$. The moment conditions are divided into two cases: the sub-Gaussian-type tails and polynomial-type tails.

Condition 6 (sub-Gaussian-type tails). Suppose that $\log (p)=o\left(n^{1 / 4}\right)$. There exist some constants $\eta>0$ and $K>0$ such that

$$
E\left\{\exp \left(\eta V_{i 1}^{2} / \omega_{i, i}\right)\right\} \leqslant K \quad \text { and } \quad E\left\{\exp \left(\eta V_{i 2}^{2} / \omega_{i, i}\right)\right\} \leqslant K \quad \text { for } 1 \leqslant i \leqslant p
$$

Condition 7 (polynomial-type tails). Suppose that for some constants $\gamma_{0}, c_{1}>0, p \leqslant c_{1} n^{\gamma_{0}}$, and for some constants $\varepsilon>0$ and $K>0$

$$
E\left|V_{i 1} / \omega_{i, i}^{1 / 2}\right|^{2 \gamma_{0}+2+\varepsilon} \leqslant K \quad \text { and } \quad E\left|V_{i 2} / \omega_{i, i}^{1 / 2}\right|^{2 \gamma_{0}+2+\varepsilon} \leqslant K \quad \text { for } 1 \leqslant i \leqslant p
$$

Theorem 6. Suppose that conditions 1, 3 and 6 (or 7) hold. Then under the null hypothesis $H_{0}$, for any $x \in \mathbb{R}$,

$$
P_{H_{0}}\left[M_{\Omega}-2 \log (p)+\log \{\log (p)\} \leqslant x\right] \rightarrow \exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\}, \quad \text { as } n, p \rightarrow \infty
$$

Theorem 6 shows that $\Phi_{\alpha}(\boldsymbol{\Omega})$ is still an asymptotically $\alpha$-level test when the distribution is non-Gaussian. When $\boldsymbol{\Omega}$ is unknown, as in the Gaussian case, the CLIME estimator $\hat{\boldsymbol{\Omega}}$ in Cai et al. (2011) or the inverse of adaptive thresholding estimator $\left(\hat{\boldsymbol{\Sigma}}^{*}\right)^{-1}$ can be used. The following theorem shows that the test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ shares the same optimality as $\Phi_{\alpha}(\boldsymbol{\Omega})$ in the non-Gaussian setting.

Theorem 7. Suppose that conditions 1, 3, 6 (or 7) and (8) hold.
(a) Under the null hypothesis $H_{0}$, for any $x \in \mathbb{R}$,

$$
P_{H_{0}}\left[M_{\hat{\boldsymbol{\Omega}}}-2 \log (p)+\log \{\log (p)\} \leqslant x\right] \rightarrow \exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\}, \quad \text { as } n, p \rightarrow \infty
$$

(b) Under hypothesis $H_{1}$ and the conditions of theorem 2, we have

$$
P_{H_{1}}\left\{\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})=1\right\} \rightarrow 1, \quad \text { as } n, p \rightarrow \infty
$$

## 5. Simulation study

In this section, we consider the numerical performance of the proposed test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ and compare it with several other tests, including the tests based on the sum-of-squares type statistics in Bai and Saranadasa (1996), Srivastava and Du (2008) and Chen and Qin (2010) and the commonly used Hotelling's $T^{2}$-test. These tests are denoted respectively by BS, SD, CQ and $T^{2}$ respectively in the rest of this section.

The test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ is easy to implement. A range of covariance structures are considered in the simulation study, including the settings where the covariance matrix $\boldsymbol{\Sigma}$ is sparse, the precision matrix $\boldsymbol{\Omega}$ is sparse, and both $\boldsymbol{\Sigma}$ and $\boldsymbol{\Omega}$ are non-sparse. In the case when $\boldsymbol{\Omega}$ is known to be sparse, the CLIME estimator in Cai et al. (2011) is used to estimate it, whereas the inverse of the adaptive thresholding estimator in Cai and Liu (2011) is used to estimate $\boldsymbol{\Omega}$ when such information is not available. The simulation results show that the test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ significantly and uniformly outperforms the other four tests when either $\boldsymbol{\Sigma}$ or $\boldsymbol{\Omega}$ is sparse, and the test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ still outperforms the other four tests even when both $\boldsymbol{\Sigma}$ and $\boldsymbol{\Omega}$ are non-sparse.

Without loss of generality, we shall always take $\boldsymbol{\mu}_{2}=\mathbf{0}$ in the simulations. Under the null hypothesis, $\boldsymbol{\mu}_{1}=\boldsymbol{\mu}_{2}=\mathbf{0}$, whereas, under the alternative hypothesis, we take $\boldsymbol{\mu}_{1}=\left(\mu_{11}, \ldots, \mu_{1 p}\right)^{\prime}$ to have $m$ non-zero entries with the support $S=\left\{l_{1}, \ldots, l_{m}: l_{1}<l_{2}<\ldots<l_{m}\right\}$ uniformly and randomly drawn from $\{1, \ldots, p\}$. Two values of $m$ are considered: $m=\lfloor 0.05 p\rfloor$ and $m=\lfloor\sqrt{ } p\rfloor$. Here $\lfloor x\rfloor$ denote the largest integer that is no greater than $x$. For each of these two values of $m$, and for any $l_{j} \in S$, two settings of the magnitude of $\mu_{1, l_{j}}$ are considered: $\mu_{1, l_{j}}= \pm \sqrt{ }\{\log (p) / n\}$ with equal probability and $\mu_{1, l_{j}}$ has magnitude randomly uniformly drawn from the interval $[-\sqrt{ }\{8 \log (p) / n\}, \sqrt{ } 8 \log (p) / n]$. We take $\mu_{1, k}=0$ for $k \in S^{\mathrm{C}}$.

The specific models for the covariance structure are given as follows. Let $\mathbf{D}=\left(d_{i, j}\right)$ be a diagonal matrix with diagonal elements $d_{i, i}=\operatorname{Unif}(1,3)$ for $i=1, \ldots, p$. Denote by $\lambda_{\min }(\mathbf{A})$ the minimum eigenvalue of a symmetric matrix $\mathbf{A}$. The following three models where the precision matrix $\boldsymbol{\Omega}$ is sparse are considered.
(a) Model 1 (block diagonal $\boldsymbol{\Omega}$ ): $\boldsymbol{\Sigma}=\left(\sigma_{i, j}\right)$ where $\sigma_{i, i}=1, \sigma_{i, j}=0.8$ for $2(k-1)+1 \leqslant i \neq j \leqslant 2 k$, where $k=1, \ldots,[p / 2]$ and $\sigma_{i, j}=0$ otherwise.
(b) Model 2 ('bandable' $\boldsymbol{\Sigma}$ ): $\boldsymbol{\Sigma}=\left(\sigma_{i, j}\right)$ where $\sigma_{i, j}=0.6^{|i-j|}$ for $1 \leqslant i, j \leqslant p$.
(c) Model $3(\operatorname{banded} \boldsymbol{\Omega})$ : $\boldsymbol{\Omega}=\left(\omega_{i, j}\right)$ where $\omega_{i, i}=2$ for $i=1, \ldots, p, \omega_{i, i+1}=0.8$ for $i=1, \ldots, p-$ $1, \omega_{i, i+2}=0.4$ for $i=1, \ldots, p-2, \omega_{i, i+3}=0.4$ for $i=1, \ldots, p-3, \omega_{i, i+4}=0.2$ for $i=$ $1, \ldots, p-4, \omega_{i, j}=\omega_{j, i}$ for $i, j=1, \ldots, p$ and $\omega_{i, j}=0$ otherwise.

We also consider two models where the covariance matrix $\boldsymbol{\Sigma}$ is sparse.
(d) Model 4 (sparse $\boldsymbol{\Sigma}$ ): $\boldsymbol{\Omega}=\left(\omega_{i, j}\right)$ where $\omega_{i, j}=0.6^{|i-j|}$ for $1 \leqslant i, j \leqslant p . \boldsymbol{\Sigma}=\mathbf{D}^{1 / 2} \boldsymbol{\Omega}^{-1} \mathbf{D}^{1 / 2}$.
(e) Model 5 (sparse $\boldsymbol{\Sigma}$ ): $\boldsymbol{\Omega}^{1 / 2}=\left(a_{i, j}\right)$ where $a_{i, i}=1, a_{i, j}=0.8$ for $2(k-1)+1 \leqslant i \neq j \leqslant 2 k$, where $k=1, \ldots,[p / 2]$, and $a_{i, j}=0$ otherwise. $\boldsymbol{\Omega}=\mathbf{D}^{1 / 2} \boldsymbol{\Omega}^{1 / 2} \boldsymbol{\Omega}^{1 / 2} \mathbf{D}^{1 / 2}$ and $\boldsymbol{\Sigma}=\boldsymbol{\Omega}^{-1}$.

In addition, three models where neither $\boldsymbol{\Sigma}$ nor $\boldsymbol{\Omega}$ is sparse are considered. In model $\mathbf{6}, \boldsymbol{\Sigma}$ is a sparse matrix plus a perturbation of a non-sparse matrix $\mathbf{E}$. The entries of $\boldsymbol{\Sigma}$ in model 7 decay as a function of the lag $|i-j|$, which arises naturally in time series analysis. Model 8 considers a non-sparse rank 3 perturbation to a sparse matrix which leads to a non-sparse covariance matrix $\boldsymbol{\Sigma}$. The simulation results show that the proposed test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ still significantly outperforms the other four tests under these non-sparse models.
(f) Model 6 (non-sparse case): $\boldsymbol{\Sigma}^{*}=\left(\sigma_{i, j}^{*}\right)$ where $\sigma_{i, i}^{*}=1, \sigma_{i, j}^{*}=0.8$ for $2(k-1)+1 \leqslant i \neq$ $j \leqslant 2 k$, where $k=1, \ldots,[p / 2]$, and $\sigma_{i, j}^{*}=0$ otherwise. $\boldsymbol{\Sigma}=\mathbf{D}^{1 / 2} \boldsymbol{\Sigma}^{*} \mathbf{D}^{1 / 2}+\mathbf{E}+\delta \mathbf{I}$ with $\delta=$ $\left|\lambda_{\min }\left(\mathbf{D}^{1 / 2} \boldsymbol{\Sigma}^{*} \mathbf{D}^{1 / 2}+\mathbf{E}\right)\right|+0.05$, where $\mathbf{E}$ is a symmetric matrix with the support of the off-diagonal entries chosen independently according to the Bernoulli(0.3) distribution with the values of the non-zero entries drawn randomly from $\operatorname{Unif}(-0.2,0.2)$.
(g) Model 7 (non-sparse case): $\boldsymbol{\Sigma}^{*}=\left(\sigma_{i, j}^{*}\right)$ where $\sigma_{i, i}^{*}=1$ and $\sigma_{i, j}^{*}=|i-j|^{-5} / 2$ for $i \neq j$. $\boldsymbol{\Sigma}=\mathbf{D}^{1 / 2} \boldsymbol{\Sigma}^{*} \mathbf{D}^{1 / 2}$.
(h) Model 8 (non-sparse case): $\boldsymbol{\Sigma}=\mathbf{D}^{1 / 2}\left(\mathbf{F}+\mathbf{u}_{1} \mathbf{u}_{1}^{\prime}+\mathbf{u}_{2} \mathbf{u}_{2}^{\prime}+\mathbf{u}_{3} \mathbf{u}_{3}^{\prime}\right) \mathbf{D}^{1 / 2}$, where $\mathbf{F}=\left(f_{i, j}\right)$ is a $p \times$ $p$ matrix with $f_{i, i}=1, f_{i, i+1}=f_{i+1, i}=0.5$ and $f_{i, j}=0$ otherwise, and $\mathbf{u}_{i}$ are orthonormal vectors for $i=1,2,3$.

Under each model, two independent random samples $\left\{\mathbf{X}_{k}\right\}$ and $\left\{\mathbf{Y}_{l}\right\}$ are generated with the same sample size $n=100$ from two multivariate normal distributions with means $\boldsymbol{\mu}_{1}$ and $\boldsymbol{\mu}_{2}$ respectively and a common covariance matrix $\boldsymbol{\Sigma}$. The dimension $p$ takes values $p=50,100,200$. The power and level of significance are calculated from 1000 replications.

The numerical results on the proposed test $\Phi_{\alpha}(\hat{\Omega})$ and test BS, SD, CQ and $T^{2}$ under models $1-5$ are summarized in Tables 1 and 2. Table 1 compares the empirical sizes of the tests. It can be seen that the estimated sizes are reasonably close to the nominal level 0.05 for all the tests. Table 2, which compares the powers, shows that the new test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$, based on either the CLIME estimator of sparse $\boldsymbol{\Omega}$ or the inverse of the adaptive thresholding estimator of sparse $\boldsymbol{\Sigma}$, uniformly and significantly outperforms the other four tests over all dimensions ranging from 50 to 200 . The powers of these tests are significantly lower than that of $\Phi_{\alpha}(\hat{\Omega})$. These numerical results confirm the theoretical analysis that was given in the last section.

Table 3 summarizes the sizes and powers for the non-sparse cases. We report here only the cases when the magnitudes of the signals vary under the alternative. The performance of the
Table 1. Empirical sizes based on 1000 replications with $\alpha=0.05$ and $n=100$

| Test | Results for the following models and values of p: |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Model 1 |  |  | Model 2 |  |  | Model 3 |  |  | Model 4 |  |  | Model 5 |  |  |
|  | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ |
| $T^{2}$ | 0.04 | 0.06 | - | 0.04 | 0.04 | - | 0.04 | 0.05 | - | 0.05 | 0.06 | - | 0.05 | 0.05 |  |
| BS | 0.06 | 0.07 | 0.06 | 0.07 | 0.06 | 0.06 | 0.06 | 0.05 | 0.04 | 0.07 | 0.07 | 0.06 | 0.06 | 0.06 | 0.05 |
| SD | 0.06 | 0.07 | 0.06 | 0.07 | 0.06 | 0.06 | 0.06 | 0.05 | 0.02 | 0.07 | 0.07 | 0.06 | 0.06 | 0.06 | 0.05 |
| CQ | 0.06 | 0.07 | 0.06 | 0.06 | 0.06 | 0.07 | 0.06 | 0.05 | 0.02 | 0.07 | 0.07 | 0.06 | 0.06 | 0.06 | 0.05 |
| $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ | 0.05 | 0.05 | 0.06 | 0.04 | 0.05 | 0.06 | 0.05 | 0.06 | 0.06 | 0.04 | 0.05 | 0.06 | 0.03 | 0.04 | 0.03 |

Table 2. Powers of the tests based on 1000 replications with $\alpha=0.05$ and $n=100$

| Test | Results for the following models and values of p: |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Model 1 |  |  | Model 2 |  |  | Model 3 |  |  | Model 4 |  |  | Model 5 |  |  |
|  | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ |
| $m=0.05 p$ with fixed magnitude |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $T^{2}$ | 0.22 | 0.41 | - | 0.17 | 0.27 | - | 0.14 | 0.26 | - | 0.14 | 0.21 | - | 0.34 | 0.39 | - |
| BS | 0.11 | 0.19 | 0.27 | 0.11 | 0.13 | 0.24 | 0.12 | 0.28 | 0.44 | 0.10 | 0.15 | 0.23 | 0.07 | 0.07 | 0.07 |
| SD | 0.11 | 0.19 | 0.27 | 0.11 | 0.13 | 0.24 | 0.12 | 0.27 | 0.44 | 0.10 | 0.15 | 0.27 | 0.07 | 0.07 | 0.07 |
| CQ | 0.11 | 0.19 | 0.27 | 0.11 | 0.13 | 0.24 | 0.12 | 0.27 | 0.44 | 0.10 | 0.15 | 0.23 | 0.07 | 0.07 | 0.07 |
| $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ | 0.36 | 0.70 | 0.89 | 0.26 | 0.41 | 0.66 | 0.21 | 0.40 | 0.62 | 0.18 | 0.28 | 0.61 | 0.57 | 0.66 | 1.00 |
| $m=\sqrt{ } p$ with fixed magnitude |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $T^{2}$ | 0.85 | 0.81 | - | 0.64 | 0.67 | - | 0.63 | 0.57 | - | 0.58 | 0.49 | - | 0.81 | 0.85 | - |
| BS | 0.30 | 0.36 | 0.40 | 0.23 | 0.28 | 0.35 | 0.49 | 0.59 | 0.63 | 0.26 | 0.30 | 0.36 | 0.08 | 0.08 | 0.08 |
| SD | 0.30 | 0.36 | 0.40 | 0.23 | 0.28 | 0.35 | 0.50 | 0.59 | 0.63 | 0.29 | 0.29 | 0.35 | 0.08 | 0.08 | 0.09 |
| CQ | 0.30 | 0.35 | 0.39 | 0.22 | 0.28 | 0.35 | 0.49 | 0.59 | 0.63 | 0.26 | 0.30 | 0.35 | 0.08 | 0.08 | 0.08 |
| $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ | 0.82 | 0.89 | 0.96 | 0.58 | 0.79 | 0.76 | 0.49 | 0.57 | 0.68 | 0.52 | 0.69 | 0.68 | 0.77 | 0.93 | 0.99 |
| $m=0.05 p$ with varied magnitude |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $T^{2}$ | 0.19 | 0.44 | - | 0.08 | 0.45 | - | 0.15 | 0.27 | - | 0.13 | 0.14 | - | 0.19 | 0.08 | - |
| BS | 0.11 | 0.21 | 0.32 | 0.08 | 0.21 | 0.31 | 0.13 | 0.29 | 0.51 | 0.10 | 0.11 | 0.23 | 0.07 | 0.06 | 0.06 |
| SD | 0.11 | 0.22 | 0.32 | 0.08 | 0.21 | 0.31 | 0.13 | 0.29 | 0.51 | 0.10 | 0.11 | 0.27 | 0.07 | 0.06 | 0.06 |
| CQ | 0.11 | 0.21 | 0.32 | 0.08 | 0.21 | 0.32 | 0.13 | 0.29 | 0.52 | 0.10 | 0.11 | 0.24 | 0.07 | 0.06 | 0.06 |
| $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ | 0.35 | 0.76 | 0.94 | 0.12 | 0.85 | 0.88 | 0.24 | 0.51 | 0.84 | 0.22 | 0.30 | 0.76 | 0.44 | 0.11 | 0.40 |
| $m=\sqrt{ } p$ with varied magnitude |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $T^{2}$ | 0.63 | 0.70 | - | 0.72 | 0.75 | - | 0.59 | 0.56 | - | 0.29 | 0.74 | - | 0.28 | 0.95 | - |
| BS | 0.23 | 0.34 | 0.44 | 0.27 | 0.42 | 0.38 | 0.51 | 0.52 | 0.72 | 0.12 | 0.39 | 0.38 | 0.07 | 0.08 | 0.08 |
| SD | 0.23 | 0.34 | 0.44 | 0.27 | 0.42 | 0.38 | 0.51 | 0.52 | 0.72 | 0.15 | 0.37 | 0.41 | 0.07 | 0.09 | 0.08 |
| CQ | 0.23 | 0.33 | 0.44 | 0.26 | 0.41 | 0.37 | 0.51 | 0.51 | 0.72 | 0.12 | 0.39 | 0.38 | 0.07 | 0.08 | 0.08 |
| $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ | 0.71 | 0.90 | 0.97 | 0.80 | 0.91 | 0.87 | 0.54 | 0.70 | 0.92 | 0.47 | 0.96 | 0.94 | 0.30 | 1.00 | 1.00 |

Table 3. Empirical sizes and powers for models $6-8$ with $\alpha=0.05$ and $n=100$, based on 1000 replications

| Test | Results for the following models and values of p: |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Model 6 |  |  | Model 7 |  |  | Model 8 |  |  |
|  | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ | $p=50$ | $p=100$ | $p=200$ |
| Size |  |  |  |  |  |  |  |  |  |
| $T^{2}$ | 0.05 | 0.05 | - | 0.05 | 0.05 | - | 0.04 | 0.04 | - |
| BS | 0.07 | 0.07 | 0.05 | 0.07 | 0.06 | 0.05 | 0.06 | 0.06 | 0.06 |
| SD | 0.08 | 0.05 | 0.05 | 0.08 | 0.06 | 0.05 | 0.05 | 0.05 | 0.06 |
| CQ | 0.07 | 0.07 | 0.05 | 0.07 | 0.06 | 0.06 | 0.06 | 0.06 | 0.06 |
| $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ | 0.05 | 0.05 | 0.05 | 0.02 | 0.02 | 0.03 | 0.03 | 0.02 | 0.03 |
| Power when $m=0.05 p$ |  |  |  |  |  |  |  |  |  |
| $T^{2}$ | 0.14 | 0.37 | - | 0.17 | 0.43 | - | 0.31 | 0.40 | - |
| BS | 0.10 | 0.22 | 0.24 | 0.09 | 0.12 | 0.20 | 0.07 | 0.10 | 0.16 |
| SD | 0.10 | 0.21 | 0.26 | 0.09 | 0.13 | 0.20 | 0.07 | 0.09 | 0.16 |
| CQ | 0.10 | 0.22 | 0.23 | 0.09 | 0.12 | 0.20 | 0.07 | 0.11 | 0.16 |
| $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ | 0.16 | 0.40 | 0.46 | 0.14 | 0.41 | 0.80 | 0.20 | 0.50 | 0.84 |
| Power when $m=\sqrt{ } p$ |  |  |  |  |  |  |  |  |  |
| $T^{2}$ | 0.47 | 0.23 | - | 0.49 | 0.59 | - | 0.53 | 1.00 | - |
| BS | 0.17 | 0.13 | 0.46 | 0.16 | 0.18 | 0.20 | 0.11 | 0.15 | 0.16 |
| SD | 0.14 | 0.14 | 0.57 | 0.16 | 0.17 | 0.20 | 0.12 | 0.14 | 0.16 |
|  | 0.16 | 0.13 | 0.46 | 0.15 | 0.18 | 0.20 | 0.11 | 0.14 | 0.16 |
| $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ | 0.24 | 0.26 | 0.77 | 0.37 | 0.57 | 0.53 | 0.38 | 0.73 | 0.85 |

tests is similar to that in the case of fixed magnitude. It can be seen from Table 3 that the sizes of the sum-of-squares type tests tend to be larger than the nominal level 0.05 whereas the sizes of the new test $\Phi_{\alpha}(\boldsymbol{\Omega})$ are smaller than the nominal level. Thus, the new test has smaller type I error probability than those of the sum-of-squares type tests. For the models where both $\boldsymbol{\Sigma}$ and $\boldsymbol{\Omega}$ are non-sparse, the power of the proposed test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ is not as high as in the sparse cases. However, similar phenomena are observed in Table 3 when comparing the powers with the other tests. The tests based on the sum-of-squares test statistics are not powerful against the sparse alternatives, and they are still significantly outperformed by the new test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$.

More extensive simulations were carried out in the non-sparse settings as well as for nonGaussian distributions. We also compare the proposed test with the tests based on some other estimators of the precision matrices. In particular, we consider non-sparse covariance structures by adding to the covariance or precision matrices in models $1-5$ a perturbation of a nonsparse matrix $\mathbf{E}$, where $\mathbf{E}$ is a symmetric matrix with $30 \%$ random non-zero entries drawn from Unif( $-0.2,0.2$ ). Furthermore, simulations for five additional non-sparse covariance models are carried out. The comparisons are consistent with the cases that are reported here. For brevity, these simulation results are given in the on-line supplementary material.

In summary, the numerical results show that the proposed test $\Phi_{\alpha}(\hat{\Omega})$ is significantly and uniformly more powerful than the other four tests in the settings where either $\boldsymbol{\Sigma}$ or $\boldsymbol{\Omega}$ is sparse. When both $\boldsymbol{\Sigma}$ and $\boldsymbol{\Omega}$ are non-sparse, the test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ still outperforms the sum-of-squares type tests. On the basis of these numerical results, we recommend using the test $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ with the

CLIME estimator of $\boldsymbol{\Omega}$ when $\boldsymbol{\Omega}$ is known to be sparse and using $\Phi_{\alpha}(\hat{\boldsymbol{\Omega}})$ with the inverse of the adaptive thresholding estimator of $\boldsymbol{\Sigma}$ when such information is not available.

## 6. Discussion

In the present paper it is assumed that the two populations have the same covariance matrix. More generally, suppose that we observe $\mathbf{X}_{k} \sim{ }^{\mathrm{IID}} N_{p}\left(\boldsymbol{\mu}_{1}, \boldsymbol{\Sigma}_{1}\right), k=1, \ldots, n_{1}$, and $\mathbf{Y}_{k} \sim^{\text {IID }} N_{p}\left(\boldsymbol{\mu}_{2}, \boldsymbol{\Sigma}_{2}\right), k=1, \ldots, n_{2}$, and we wish to test $H_{0}: \boldsymbol{\mu}_{1}=\boldsymbol{\mu}_{2}$ versus $H_{1}: \boldsymbol{\mu}_{1} \neq \boldsymbol{\mu}_{2}$. To apply the procedure proposed in this paper, one needs first to test $H_{0}: \boldsymbol{\Sigma}_{1}=\boldsymbol{\Sigma}_{2}$ versus $H_{1}: \boldsymbol{\Sigma}_{1} \neq \boldsymbol{\Sigma}_{2}$. For this, for example, the test that is introduced in Cai et al. (2013) can be used. If the null hypothesis $H_{0}: \Sigma_{1}=\Sigma_{2}$ is rejected, the test proposed in this paper is not directly applicable. However, a modified version of the procedure can still be used. Note that the covariance matrix of $\overline{\mathbf{X}}-\overline{\mathbf{Y}}$ is $\boldsymbol{\Sigma}_{1} / n_{1}+\boldsymbol{\Sigma}_{2} / n_{2}$. To apply the test procedure in Section 2, one needs to estimate $\left\{\boldsymbol{\Sigma}_{1}+\left(n_{1} / n_{2}\right) \boldsymbol{\Sigma}_{2}\right\}^{-1}$. When both $\boldsymbol{\Sigma}_{1}$ and $\boldsymbol{\Sigma}_{2}$ are sparse, the inverse can be estimated well by $\left\{\hat{\boldsymbol{\Sigma}}_{1, \text { thr }}+\left(n_{1} / n_{2}\right) \hat{\boldsymbol{\Sigma}}_{2 \text {,thr }}\right\}^{-1}$ by using the adaptive thresholding estimators $\boldsymbol{\Sigma}_{1, \text { thr }}$ and $\boldsymbol{\Sigma}_{2, \text { thr }}$ that were introduced in Cai and Liu (2011). Similarly, when both $\boldsymbol{\Sigma}_{1}$ and $\boldsymbol{\Sigma}_{2}$ are bandable, $\left\{\boldsymbol{\Sigma}_{1}+\left(n_{1} / n_{2}\right) \boldsymbol{\Sigma}_{2}\right\}^{-1}$ can also be estimated well. A more interesting problem is the estimation of $\left\{\boldsymbol{\Sigma}_{1}+\left(n_{1} / n_{2}\right) \boldsymbol{\Sigma}_{2}\right\}^{-1}$ when the precision matrices $\boldsymbol{\Omega}_{1}$ and $\boldsymbol{\Omega}_{2}$ are sparse.

Besides testing the means and covariance matrices of two populations, another interesting and related problem is the testing of the equality of two distributions based on the two samples, i.e. we wish to test $H_{0}: \mathbb{P}_{1}=\mathbb{P}_{2}$ versus $H_{1}: \mathbb{P}_{1} \neq \mathbb{P}_{2}$, where $\mathbb{P}_{i}$ is the distribution of $N_{p}\left(\boldsymbol{\mu}_{i}, \boldsymbol{\Sigma}_{i}\right)$, $i=1,2$. We shall report the details of the results elsewhere in the future as a significant amount of additional work is still needed.

The asymptotic properties in Section 3.2 rely on the assumption that the locations of the non-zero entries of $\boldsymbol{\mu}_{1}-\boldsymbol{\mu}_{2}$ are uniformly drawn from $\{1, \ldots, p\}$. When this assumption does not hold, the asymptotic power results may fail. A simple solution is first to apply a random permutation to the co-ordinates of $\boldsymbol{\mu}_{1}-\boldsymbol{\mu}_{2}$ (and correspondingly to the co-ordinates of $\overline{\mathbf{X}}-$ $\overline{\mathbf{Y}}$ ) so that the non-zero locations are uniformly drawn from $\{1, \ldots, p\}$, and apply the testing procedures to the permuted data and the results given in Section 3.2 then hold.

It is well known that the convergence rate in distribution of the extreme-value-type statistics is slow. There are several possible ways to improve the rate of convergence. See, for example, Hall (1991), Liu et al. (2008) and Birnbaum and Nadler (2012). It is interesting to investigate whether these methods can be applied to improve the convergence rate of our test statistic. We leave this to future work.

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## Appendix A: Proof of main results

We prove the main results in this section. The proofs of some of the main theorems rely on a few additional
technical lemmas. These technical results are collected in Appendix A. 1 and they are proved in the on-line supplementary material.

## A.1. Technical lemmas

Lemma 1 (Bonferroni inequality). Let $A=\cup_{t=1}^{p} A_{t}$. For any $k<[p / 2]$, we have

$$
\sum_{t=1}^{2 k}(-1)^{t-1} E_{t} \leqslant P(A) \leqslant \sum_{t=1}^{2 k-1}(-1)^{t-1} E_{t},
$$

where $E_{t}=\Sigma_{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p} P\left(A_{i_{1}} \cap \ldots \cap A_{i_{t}}\right)$.
Lemma 2 (Berman, 1962). If $X$ and $Y$ have a bivariate normal distribution with expectation 0 , unit variance and correlation coefficient $\rho$, then

$$
\lim _{c \rightarrow \infty} \frac{P(X>c, Y>c)}{\left\{2 \pi(1-\rho)^{1 / 2} c^{2}\right\}^{-1} \exp \left\{-c^{2} /(1+\rho)\right\}(1+\rho)^{1 / 2}}=1
$$

uniformly for all $\rho$ such that $|\rho| \leqslant \delta$, for any $\delta, 0<\delta<1$.
Lemma 3. Suppose that condition 1 holds and $\boldsymbol{\Sigma}$ has all diagonal elements equal to 1 . Then for $p^{r}$-sparse $\delta$, with $r<\frac{1}{4}$ and non-zero locations $l_{1}, \ldots, l_{m}, m=p^{r}$, randomly and uniformly drawn from $\{1, \ldots, p\}$, we have, for any $2 r<a<1-2 r$, as $p \rightarrow \infty$,

$$
\begin{equation*}
P\left\{\max _{i \in H}\left|\frac{(\boldsymbol{\Omega})_{i}}{\sqrt{ } \omega_{i, i}}-\delta_{i} \sqrt{ } \omega_{i, i}\right|=O\left(p^{r-a / 2}\right) \max _{i \in H}\left|\delta_{i}\right|\right\} \rightarrow 1, \tag{14}
\end{equation*}
$$

and

$$
\begin{equation*}
P\left\{\max _{i \in H} \mid\left(\boldsymbol{\Omega}^{1 / 2} \delta_{i}-a_{i, i} \delta_{i}\left|=O\left(p^{r-a / 2}\right) \max _{i \in H}\right| \delta_{i} \mid\right\} \rightarrow 1,\right. \tag{15}
\end{equation*}
$$

where $\boldsymbol{\Omega}^{1 / 2}=:\left(a_{i, j}\right)$ and $H$ is the support of $\delta$.
Lemma 4. Let $Y_{i} \sim N\left(\mu_{i}, 1\right)$ be independent for $i=1, \ldots, n$. Let $a_{n}=o\left\{\log (n)^{-1 / 2}\right\}$. Then
uniformly in the means $\mu_{i}, 1 \leqslant i \leqslant n$. If $Y_{i}$ is replaced by $\left|Y_{i}\right|$, then condition (16) still holds.
Lemma 5 (Baraud, 2002). Let $\mathcal{F}$ be some subset of $l_{2}(J)$. Let $\mu_{\rho}$ be some probability measure on $\mathcal{F}_{\rho}=$ $\{\theta \in \mathcal{F},\|\theta\| \geqslant \rho\}$ and let $P_{\mu_{\rho}}=\int P_{\theta} \mathrm{d} \mu_{\rho}(\theta)$. Assuming that $P_{\mu_{\rho}}$ is absolutely continuous with respect to $P_{0}$, we define $L_{\mu_{\rho}}(y)=\mathrm{d} P_{\mu_{\rho}}(y) / \mathrm{d} P_{0}$. For all $\alpha>0, \nu \in[0,1-\alpha]$, if $E_{0}\left\{L_{\mu_{\rho^{*}}}^{2}(Y)\right\} \leqslant 1+4(1-\alpha-\nu)^{2}$, then

$$
\forall \rho \leqslant \rho^{*}, \inf _{\Phi_{\alpha}} \sup _{\theta \in \mathcal{F}_{\rho}} P_{\theta}\left(\Phi_{\alpha}=0\right) \geqslant \nu .
$$

## A.2. Proof of theorem 1

Because we standardize the test statistic first, we shall let $\left(Z_{1}, \ldots, Z_{p}\right)^{\prime}$ be a zero-mean multivariate normal random vector with covariance matrix $\boldsymbol{\Omega}=\left(\omega_{i, j}\right)_{1 \leqslant i, j \leqslant p}$ and diagonal $\omega_{i, i}=1$ for $1 \leqslant i \leqslant p$. To prove theorem 1, it suffices to prove the following lemma.

Lemma 6. Suppose that $\max _{1 \leqslant i \neq j \leqslant p}\left|\omega_{i, j}\right| \leqslant r<1$ and $\max _{j} \Sigma_{i=1}^{p} \omega_{i, j}^{2} \leqslant C_{0}$. Then for any $x \in \mathbb{R}$ as $p \rightarrow \infty$

$$
\begin{gather*}
P\left[\max _{1 \leqslant i \leqslant p} Z_{i}^{2}-2 \log (p)+\log \{\log (p)\} \leqslant x\right] \rightarrow \exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\},  \tag{17}\\
P\left(\max _{1 \leqslant i \leqslant p} Z_{i} \leqslant \sqrt{ }[2 \log (p)-\log \{\log (p)\}+x]\right) \rightarrow \exp \left\{-\frac{1}{2 \sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\} . \tag{18}
\end{gather*}
$$

Proof. We need only to prove expression (17) because the proof of expression (18) is similar. Set $x_{p}=$ $2 \log (p)-\log \{\log (p)\}+x$. By lemma 1 , we have, for any fixed $k \leqslant[p / 2]$,

$$
\begin{equation*}
\sum_{t=1}^{2 k}(-1)^{t-1} E_{t} \leqslant P\left(\max _{1 \leqslant i \leqslant p}\left|Z_{i}\right| \geqslant \sqrt{ } x_{p}\right) \leqslant \sum_{t=1}^{2 k-1}(-1)^{t-1} E_{t}, \tag{19}
\end{equation*}
$$

where $E_{t}=\Sigma_{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p} P\left(\left|Z_{i_{1}}\right| \geqslant \sqrt{ } x_{p}, \ldots,\left|Z_{i_{t}}\right| \geqslant \sqrt{ } x_{p}\right)=: \Sigma_{1 \leqslant i_{1}<\ldots i_{t} \leqslant p} P_{i_{1}, \ldots, i_{t}}$. Define $\mathcal{I}=\left\{1 \leqslant i_{1}<\ldots<\right.$ $\left.i_{t} \leqslant p: \max _{1 \leqslant k<l \leqslant t}\left|\operatorname{cov}\left(Z_{i_{k}}, Z_{i l}\right)\right| \geqslant p^{-\gamma}\right\}$, where $\gamma>0$ is a sufficiently small number to be specified later. For $2 \leqslant d \leqslant t-1$, define

$$
\begin{aligned}
\mathcal{I}_{d}= & \left\{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p: \operatorname{card}(S)=d, \text { where } S \text { is the largest subset of }\left\{i_{1}, \ldots, i_{t}\right\}\right. \text { such that } \\
& \left.\forall i_{k} \neq i_{l} \in S,\left|\operatorname{cov}\left(Z_{i_{k}}, Z_{i_{i}}\right)\right|<p^{-\gamma}\right\} .
\end{aligned}
$$

For $d=1$, define $\mathcal{I}_{1}=\left\{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p:\left|\operatorname{cov}\left(Z_{i_{k}}, Z_{i_{l}}\right)\right| \geqslant p^{-\gamma}\right.$ for every $\left.1 \leqslant k<l \leqslant t\right\}$. So we have $\mathcal{I}=$ $\cup_{d=1}^{t-1} \mathcal{I}_{d}$. Let $\operatorname{card}\left(\mathcal{I}_{d}\right)$ denote the total number of the vectors $\left(i_{1}, \ldots, i_{t}\right)$ in $\mathcal{I}_{d}$. We can show that card $\left(\mathcal{I}_{d}\right) \leqslant$ $C p^{d+2 \gamma t}$. In fact, the total number of the subsets of $\left\{i_{1}, \ldots, i_{t}\right\}$ with cardinality $d$ is $C_{p}^{d}$. For a fixed subset $S$ with cardinality $d$, the number of $i$ such that $\left|\operatorname{cov}\left(Z_{i}, Z_{j}\right)\right| \geqslant p^{-\gamma}$ for some $j \in S$ is no more than $C d p^{2 \gamma}$. This implies that $\operatorname{card}\left(\mathcal{I}_{d}\right) \leqslant C p^{d+2 \gamma t}$. Define $\mathcal{I}^{\mathrm{c}}=\left\{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p\right\} \backslash \mathcal{I}$. Then the number of elements in the $\operatorname{sum} \Sigma_{\left(i_{1}, \ldots, i_{t}\right) \in \mathcal{I} c} P_{i_{1}, \ldots, i_{t}}$ is $C_{p}^{t}-O\left(\Sigma_{d=1}^{t-1} p^{d+2 \gamma t}\right)=C_{p}^{t}-O\left(p^{t-1+2 \gamma t}\right)=\{1+o(1)\} C_{p}^{t}$.

To prove lemma 6, it suffices to show that

$$
\begin{equation*}
P_{i_{1}, \ldots, i_{t}}=\{1+o(1)\} \pi^{-t / 2} p^{-t} \exp \left(-\frac{t x}{2}\right) \tag{20}
\end{equation*}
$$

uniformly in $\left(i_{1}, \ldots, i_{t}\right) \in \mathcal{I}^{\mathrm{c}}$ and, for $1 \leqslant d \leqslant t-1$,

$$
\begin{equation*}
\sum_{\left(i_{1}, \ldots, i_{i}\right) \in \mathcal{I}_{d}} P_{i_{1}, \ldots, i_{t}} \rightarrow 0 \tag{21}
\end{equation*}
$$

Putting expressions (19)-(21) together, we obtain that

$$
\begin{equation*}
\{1+o(1)\} S_{2 k} \leqslant P\left(\max _{1 \leqslant i \leqslant p}\left|Z_{i}\right| \geqslant \sqrt{ } x_{p}\right) \leqslant\{1+o(1)\} S_{2 k-1}, \tag{22}
\end{equation*}
$$

where

$$
S_{k}=\sum_{t=1}^{k}(-1)^{t-1} \frac{1}{t!} \pi^{-t / 2} \exp \left(-\frac{t x}{2}\right)
$$

Note that

$$
\lim _{k \rightarrow \infty} S_{k}=1-\exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\}
$$

By letting $p \rightarrow \infty$ first and then $k \rightarrow \infty$ in condition (13), we prove lemma 6.
We now prove equation (20). Let $\mathbf{z}=\left(z_{i_{1}}, \ldots, z_{i_{t}}\right)^{\prime}$ and $|\mathbf{z}|_{\text {min }}=\min _{1 \leqslant j \leqslant t}\left|z_{i_{j}}\right|$. Write

$$
P_{i_{1}, \ldots, i_{t}}=\frac{1}{(2 \pi)^{t / 2} \operatorname{det}\left(\boldsymbol{\Omega}_{t}\right)^{1 / 2}} \int_{|\mathbf{z}|_{\min } \geqslant \sqrt{ } x_{p}} \exp \left(-\frac{1}{2} \mathbf{z}^{\prime} \boldsymbol{\Omega}_{t}^{-1} \mathbf{z}\right) \mathrm{d} \mathbf{z}
$$

where $\boldsymbol{\Omega}_{t}$ is the covariance matrix of $\mathbf{Z}=\left(Z_{i_{1}}, \ldots, Z_{i_{t}}\right)^{\prime}$, and $\boldsymbol{\Omega}_{t}=\left(a_{k l}\right)_{t \times t}$, where $a_{k l}=\operatorname{cov}\left(Z_{i_{k}}, Z_{i_{l}}\right)$. Since $i_{1}, \ldots, i_{t} \in \mathcal{I}^{\mathrm{c}}, a_{k, k}=1$ and $\left|a_{k l}\right|<p^{-\gamma}$ for $k \neq l$. Write

$$
\begin{align*}
\int_{|\mathbf{z}|_{\min } \geqslant \sqrt{ } x_{p}} \exp \left(-\frac{1}{2} \mathbf{z}^{\prime} \boldsymbol{\Omega}_{t}^{-1} \mathbf{z}\right) \mathrm{d} \mathbf{z}= & \int_{|z| \min \geqslant \sqrt{ } x_{p}, \||z|^{2} \gg \log (p)^{2}} \exp \left(-\frac{1}{2} \mathbf{z}^{\prime} \boldsymbol{\Omega}_{t}^{-1} \mathbf{z}\right) \mathrm{d} \mathbf{z} \\
& +\int_{|\mathbf{z}| \min \geqslant \sqrt{ } x_{p}, \||z|^{2} \leqslant \log (p)^{2}} \exp \left(-\frac{1}{2} \mathbf{z}^{\prime} \boldsymbol{\Omega}_{t}^{-1} \mathbf{z}\right) \mathrm{d} \mathbf{z} . \tag{23}
\end{align*}
$$

Then

$$
\begin{equation*}
\int_{x_{p},\|z\|^{2}>\log (p)^{2}} \exp \left(-\frac{1}{2} \mathbf{z}^{\prime} \mathbf{\Omega}_{t}^{-1} \mathbf{z}\right) \mathrm{d} \mathbf{z} \leqslant C \exp \left\{-\frac{\log (p)^{2}}{2 t}\right\} \leqslant C p^{-2 t} \tag{24}
\end{equation*}
$$

uniformly in $\left(i_{1}, \ldots, i_{t}\right) \in \mathcal{I}^{\text {c }}$. For the second part of the sum in equation (23), note that

$$
\begin{equation*}
\left\|\boldsymbol{\Omega}_{t}^{-1}-\mathbf{I}\right\|_{2} \leqslant\left\|\boldsymbol{\Omega}_{t}^{-1}\right\|_{2}\left\|\boldsymbol{\Omega}_{t}-\mathbf{I}\right\|_{2} \leqslant C p^{-\gamma} . \tag{25}
\end{equation*}
$$

Let $A=\left\{|\mathbf{z}|_{\text {min }} \geqslant \sqrt{ } x_{p},\|\mathbf{z}\|^{2} \leqslant \log (p)^{2}\right\}$. It follows that

$$
\begin{align*}
\int_{A} \exp \left(-\frac{1}{2} \mathbf{z}^{\prime} \boldsymbol{\Omega}_{t}^{-1} \mathbf{z}\right) \mathrm{d} \mathbf{z} & =\int_{A} \exp \left(-\frac{1}{2} \mathbf{z}^{\prime}\left(\boldsymbol{\Omega}_{t}^{-1}-\mathbf{I}\right) \mathbf{z}-\frac{1}{2}\|\mathbf{z}\|^{2}\right) \mathrm{d} \mathbf{z} \\
& =\left[1+O\left\{p^{-\gamma} \log (p)^{2}\right\}\right] \int_{A} \exp \left(-\frac{1}{2}\|\mathbf{z}\|^{2}\right) \mathrm{d} \mathbf{z} \\
& =\left[1+O\left\{p^{-\gamma} \log (p)^{2}\right\}\right] \int_{|\mathbf{z}|_{\min } \geqslant \sqrt{ } x_{p}} \exp \left(-\frac{1}{2}\|\mathbf{z}\|^{2}\right) \mathrm{d} \mathbf{z}+C p^{-2 t}, \tag{26}
\end{align*}
$$

uniformly in $\left(i_{1}, \ldots, i_{t}\right) \in \mathcal{I}^{\mathrm{c}}$. This, together with expressions (23) and (24), implies result (20).
It remains to prove expression (21). For $S \subset \mathcal{I}_{d}$ with $d \geqslant 1$, without loss of generality, we can assume that $S=\left\{i_{t-d+1}, \ldots, i_{t}\right\}$. By the definition of $S$ and $\mathcal{I}_{d}$, for any $k \in\left\{i_{1}, \ldots, i_{t-d}\right\}$, there is at least one $l \in S$ such that $\left|\operatorname{cov}\left(Z_{k}, Z_{l}\right)\right| \geqslant p^{-\gamma}$. We divide $\mathcal{I}_{d}$ into two parts:

$$
\begin{aligned}
\mathcal{I}_{d, 1}= & \left\{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p \text { : there exists a } k \in\left\{i_{1}, \ldots, i_{t-d}\right\} \text { such that, for some } l_{1}, l_{2} \in S \text { with } l_{1} \neq l_{2},\right. \\
& \left.\left|\operatorname{cov}\left(Z_{k}, Z_{l_{1}}\right)\right| \geqslant p^{-\gamma} \text { and }\left|\operatorname{cov}\left(Z_{k}, Z_{l_{2}}\right)\right| \geqslant p^{-\gamma}\right\}
\end{aligned}
$$

and $\mathcal{I}_{d, 2}=\mathcal{I}_{d} \backslash \mathcal{I}_{d, 1}$. Clearly, $\mathcal{I}_{1,1}=\emptyset$ and $\mathcal{I}_{1,2}=\mathcal{I}_{1}$. Moreover, we can show that $\operatorname{card}\left(\mathcal{I}_{d, 1}\right) \leqslant C p^{d-1+2 \gamma t}$. For any $\left(i_{1}, \ldots, i_{t}\right) \in \mathcal{I}_{d, 1}$,

$$
P\left(\left|Z_{i_{1}}\right| \geqslant \sqrt{ } x_{p}, \ldots,\left|Z_{i_{t}}\right| \geqslant \sqrt{ } x_{p}\right) \leqslant P\left(\left|Z_{i_{t-d+1}}\right| \geqslant \sqrt{ } x_{p}, \ldots,\left|Z_{i_{t}}\right| \geqslant \sqrt{ } x_{p}\right)=O\left(p^{-d}\right) .
$$

Hence, by letting $\gamma$ be sufficiently small,

$$
\begin{equation*}
\sum_{\mathcal{I}_{d, 1}} P_{i_{1}, \ldots, i_{t}} \leqslant C p^{-1+2 \gamma t}=o(1) . \tag{27}
\end{equation*}
$$

For any $\left(i_{1}, \ldots, i_{t}\right) \in \mathcal{I}_{d, 2}$, without loss of generality, we assume that $\left|\operatorname{cov}\left(Z_{i_{1}}, Z_{i_{1-d+1}}\right)\right| \geqslant p^{-\gamma}$. Note that

$$
P\left(\left|Z_{i_{1}}\right| \geqslant \sqrt{ } x_{p}, \ldots,\left|Z_{i_{t}}\right| \geqslant \sqrt{ } x_{p}\right) \leqslant P\left(\left|Z_{i_{1}}\right| \geqslant \sqrt{ } x_{p},\left|Z_{i_{t-d+1}}\right| \geqslant \sqrt{ } x_{p}, \ldots,\left|Z_{i_{t}}\right| \geqslant \sqrt{ } x_{p}\right) .
$$

Let $\mathbf{U}_{l}$ be the covariance matrix of ( $Z_{i_{1}}, Z_{i_{t-d+1}}, \ldots, Z_{i_{t}}$ ). We can show that $\left\|\mathbf{U}_{l}-\overline{\mathbf{U}}_{l}\right\|_{2}=O\left(p^{-\gamma}\right)$, where $\overline{\mathbf{U}}_{l}=\operatorname{diag}\left(\mathbf{D}, I_{d-1}\right)$ and $\mathbf{D}$ is the covariance matrix of $Z_{i_{1}}$ and $Z_{i_{1-d+1}}$. Using arguments similar to those in expressions (23)-(26), we can obtain

$$
\begin{aligned}
P\left(\left|Z_{i_{1}}\right| \geqslant \sqrt{ } x_{p},\left|Z_{i_{t-d+1}}\right|\right. & \left.\geqslant \sqrt{ } x_{p}, \ldots,\left|Z_{i_{i}}\right| \geqslant \sqrt{ } x_{p}\right) \\
& \leqslant\{1+o(1)\} P\left(\left|Z_{i_{1}}\right| \geqslant \sqrt{ } x_{p},\left|Z_{i_{t-d+1}}\right| \geqslant \sqrt{ } x_{p}\right) O\left(p^{-d+1}\right) \leqslant C p^{-2 /(1+r)} O\left(p^{-d+1}\right),
\end{aligned}
$$

where the last inequality follows from lemma 2 and the assumption $\max _{1 \leqslant i \neq j \leqslant p}\left|\omega_{i, j}\right| \leqslant r<1$. Thus, by letting $\gamma$ be sufficiently small,

$$
\begin{equation*}
\sum_{\mathcal{I}_{d, 2}} P_{i_{1}, \ldots, i_{t}} \leqslant C p^{d+2 \gamma t-d+1-2 /(1+r)}=o(1) . \tag{28}
\end{equation*}
$$

Combining expressions (27) and (28), we prove expression (21). The proof of lemma 6 is then complete.

## A.3. Proof of theorem 2

It suffices to prove $P\left[\max _{1 \leqslant i \leqslant p}\left|(\Omega)_{i} / \sqrt{ } \omega_{i, i}\right| \geqslant \sqrt{ }\{(2+\varepsilon / 2) \log (p) / n\}\right] \rightarrow 1$. By lemma 3 and the condition $\max _{i}\left|\delta_{i} / \sigma_{i, i}^{1 / 2}\right| \geqslant \sqrt{ }\{2 \beta \log (p) / n\}$ with $\beta \geqslant 1 / \min _{i}\left(\sigma_{i, i} \omega_{i, i}\right)+\varepsilon$ for some constant $\varepsilon>0$, we can obtain $\max _{1 \leqslant i \leqslant p}\left|(\boldsymbol{\Omega})_{i} / \sqrt{ } \omega_{i, i}\right| \geqslant \sqrt{ }\{(2+\varepsilon / 2) \log (p) / n\}$ with probability tending to 1 . So theorem 2 follows.

## A.4. Proof of theorem 3

First we assume that $k_{p}=o\left(p^{r}\right)$ for some $r<\frac{1}{4}$, and we can obtain a similar argument if $k_{p}=O\left(p^{r}\right)$ for some $r<\frac{1}{2}$ and $\boldsymbol{\Omega}=\boldsymbol{\Sigma}^{-1}$ is $s_{p}$ sparse with $s_{p}=O\left\{\left(p / k_{p}^{2}\right)^{\gamma}\right\}$ for some $0<\gamma<1$. Let $\mathcal{M}_{s, p}$ denote the set of all subsets of $\{1, \ldots, p\}$ with cardinality $k_{p}$. Let $\hat{m}$ be a random set of $\{1, \ldots, p\}$, which is uniformly distributed on $\mathcal{M}$. Let $\omega_{j}, 1 \leqslant j \leqslant p$, be independent identically distributed variables with $P\left(\omega_{j}=1\right)=P\left(\omega_{j}=-1\right)=\frac{1}{2}$. We construct a class of $\delta=\boldsymbol{\mu}_{1}-\boldsymbol{\mu}_{2}$ by letting $\boldsymbol{\mu}_{1}=0$ and $\delta=-\boldsymbol{\mu}_{2}$ satisfy $\delta=\left(\delta_{1}, \ldots, \delta_{p}\right)^{\prime}$ with $\delta_{j}=\left(\rho / \sqrt{k_{p}}\right) \omega_{j} \mathbf{1}_{j \in \hat{m}}$,
where $\rho=c \sqrt{ }\left\{k_{p} \log (p) / n\right\}$ and $c>0$ is sufficiently small that will be specified later. Clearly, $|\delta|_{2}=\rho$. Let $\mu_{\rho}$ be the distribution of $\delta$. Note that $\mu_{\rho}$ is a probability measure on $\left\{\delta \in \mathcal{S}_{k_{p}}:|\delta|=\rho\right\}$. We now calculate the likelihood ratio

$$
L_{\mu_{\rho}}=\frac{\mathrm{d} P_{\mu_{\rho}}}{\mathrm{d} P_{0}}\left(\left\{\mathbf{X}_{n}, \mathbf{Y}_{n}\right\}\right) .
$$

It is easy to see that $L_{\mu_{\rho}}=E_{\hat{m}, \omega}\left[\exp \left\{-\mathbf{Z}^{\prime} \delta \sqrt{ } n-(n / 2) \delta^{\prime} \boldsymbol{\Omega} \delta\right\}\right]$, where $\mathbf{Z}$ is a multivariate normal vector with mean 0 and $\operatorname{cov}(\mathbf{Z})=\boldsymbol{\Omega}$, and is independent with $\hat{m}$ and $\boldsymbol{\Omega}$. For any fixed $\hat{m}=m$, let $\boldsymbol{\delta}_{m}^{i}, 1 \leqslant i \leqslant 2^{k_{p}}$, be all the possible values of $\delta$, i.e. $P\left(\delta=\delta_{m}^{i} \mid \hat{m}=m\right)=2^{-k_{p}}$. Thus

$$
E_{\hat{m}, \omega}\left\{\exp \left(-\mathbf{Z}^{\prime} \boldsymbol{\delta} \sqrt{ } n-\frac{n}{2} \boldsymbol{\delta}^{\prime} \boldsymbol{\Omega} \boldsymbol{\delta}\right)\right\}=\frac{1}{\binom{p}{k_{p}}} \frac{1}{2^{k_{p}}} \sum_{m \in \mathcal{M}} \sum_{i=1}^{2^{k_{p}}} \exp \left\{-\mathbf{Z}^{\prime} \boldsymbol{\delta}_{(m)}^{(i)} \sqrt{ } n-\frac{n}{2} \boldsymbol{\delta}_{(m)}^{(i)} \boldsymbol{\Omega} \boldsymbol{\delta}_{(m)}^{(i)}\right\} .
$$

It follows that

$$
\begin{aligned}
& E\left(L_{\mu_{p}}^{2}\right)=E\left[\frac{1}{\binom{p}{k_{p}}} \frac{1}{2^{k_{p}}} \sum_{m \in \mathcal{M}} \sum_{i=1}^{2^{k_{p}}} \exp \left\{-\mathbf{Z}^{\prime} \boldsymbol{\delta}_{(m)}^{(i)}-\frac{n}{2} \boldsymbol{\delta}_{(m)}^{(i))^{\prime}} \boldsymbol{\Omega} \boldsymbol{\delta}_{(m)}^{(i)}\right\}\right]^{2} \\
& =\frac{1}{\binom{p}{k_{p}}^{2}} \frac{1}{2^{2 k_{p}}} E\left[\sum_{m, m^{\prime} \in \mathcal{M}} \sum_{i, j=1}^{2^{k_{p}}} \exp \left\{-\mathbf{Z}^{\prime}\left(\boldsymbol{\delta}_{(m)}^{(i)}+\boldsymbol{\delta}_{\left(m^{\prime}\right)}^{(j)}\right) \sqrt{ } n-\frac{n}{2}\left(\boldsymbol{\delta}_{(m)}^{(i)^{\prime}} \boldsymbol{\Omega} \boldsymbol{\delta}_{(m)}^{(i)}+\boldsymbol{\delta}_{\left(m^{\prime}\right)}^{\left(j^{\prime}\right)} \boldsymbol{\Omega} \boldsymbol{\delta}_{\left(m^{\prime}\right)}^{(j)}\right)\right\}\right] \\
& =\frac{1}{\binom{p}{k_{p}}^{2}} \frac{1}{2^{2 k_{p}}} \sum_{m, m^{\prime} \in \mathcal{M}} \sum_{i, j=1}^{2^{k_{p}}}\left[\exp \left\{-\frac{n}{2}\left(\boldsymbol{\delta}_{(m)^{(i)}}^{(i)} \boldsymbol{\Omega} \boldsymbol{\delta}_{(m)}^{(i)}+\boldsymbol{\delta}_{\left(m^{\prime}\right)}^{(j)^{\prime}} \boldsymbol{\Omega} \boldsymbol{\delta}_{\left(m^{\prime}\right)}^{(j)}\right)\right\} \exp \left\{\frac{n}{2}\left(\boldsymbol{\delta}_{(m)}^{(i)^{\prime}}+\boldsymbol{\delta}_{\left(m^{\prime}\right)}^{\left.(j)^{\prime}\right)} \boldsymbol{\Omega}\left(\boldsymbol{\delta}_{(m)}^{(i)}+\boldsymbol{\delta}_{\left(m^{\prime}\right)}^{(j)}\right)\right\}\right]\right. \\
& =\frac{1}{\binom{p}{k_{p}}^{2}} \frac{1}{2^{2 k_{p}}} \sum_{m, m^{\prime} \in \mathcal{M}} \sum_{i, j=1}^{2^{k_{p}}} \exp \left(n \boldsymbol{\delta}_{(m)}^{(i)^{\prime}} \boldsymbol{\Omega} \boldsymbol{\delta}_{\left(m^{\prime}\right)}^{(j)}\right)=\frac{1}{\binom{p}{k_{p}}^{2}} \frac{1}{2^{2 k_{p}}} \sum_{m, m^{\prime} \in \mathcal{M}} \sum_{i, j=1}^{2^{k_{p}}} \exp \left(\frac{n \rho^{2}}{k_{p}} \sum_{k \in m, l \in m^{\prime}} a_{k, l} \omega_{k}^{(i)} \omega_{l}^{(j)}\right),
\end{aligned}
$$

where $\left(\rho / \sqrt{ } k_{p}\right)\left(\omega_{k}^{(i)} I_{k \in m}\right):=\boldsymbol{\delta}_{(m)}^{(i)}$ and $\boldsymbol{\Omega}=\left(a_{k l}\right)_{p \times p}$. Thus

$$
\begin{aligned}
E\left(L_{\mu_{\rho}}^{2}\right) & =\frac{1}{\binom{p}{k_{p}}^{2}} \frac{1}{2^{2 k_{p}}} \sum_{m, m^{\prime} \in \mathcal{M}} 2^{k_{p}} \prod_{k, l=1}^{k_{p}}\left\{\exp \left(\frac{n \rho^{2}}{k_{p}} a_{k l}\right)+\exp \left(-\frac{n \rho^{2}}{k_{p}} a_{k l}\right)\right\} \\
& =\frac{1}{\binom{p}{k_{p}}^{2}} \sum_{m, m^{\prime} \in \mathcal{M}} \prod_{k \in m, l \in m^{\prime}} \cosh \left(\frac{n \rho^{2}}{k_{p}} a_{k l}\right) \leqslant \frac{1}{\binom{p}{k_{p}}^{2}} \sum_{m, m^{\prime} \in \mathcal{M}} \prod_{k \in m, l \in m^{\prime}} \exp \left(\frac{n \rho^{2}}{k_{p}}\left|a_{k l}\right|\right) .
\end{aligned}
$$

For every $m$, let $B:=B_{m}=\left\{l:\left|a_{k, l}\right| \geqslant M / d, k \in m\right\}$, where $d=\left(p / k_{p}^{2}\right)^{1-\gamma}$ and $\gamma$ is sufficiently small. For every $k$, the number of $l$ such that $\left|a_{k l}\right| \geqslant M / d$ is at most $d$. Hence

$$
\begin{aligned}
E\left(L_{\mu_{\rho}}^{2}\right) & \leqslant \frac{1}{\binom{p}{k_{p}}^{2}} \sum_{m \in \mathcal{M}} \sum_{j=0}^{k_{p}} I\left(\left|m^{\prime} \cap B\right|=j\right) \exp \left(\sum_{k \in m, l \in m^{\prime}} \frac{n \rho^{2}}{k_{p}}\left|a_{k l}\right|\right) \\
& =\frac{1}{\binom{p}{k_{p}}^{2}} \sum_{m \in \mathcal{M}} \sum_{j=0}^{k_{p}} I\left(\left|m^{\prime} \cap B\right|=j\right) \exp \left(\sum_{k \in m, l \in m^{\prime} \cap B} \frac{n \rho^{2}}{k_{p}}\left|a_{k l}\right|+\sum_{k \in m, l \in m^{\prime} \cap B^{c}} \frac{n \rho^{2}}{k_{p}}\left|a_{k l}\right|\right) \\
& \leqslant \frac{1}{\binom{p}{k_{p}}^{2}} \sum_{m \in \mathcal{M}} \sum_{j=0}^{k_{p}}\binom{k_{p} d}{j}\binom{p-k_{p}}{k_{p}-j} \exp \left\{\frac{M n \rho^{2}}{k_{p}} j+\frac{M k_{p}^{2} \log (p)}{d}\right\} \\
& \leqslant \frac{1}{\binom{p}{k_{p}}^{2}} \sum_{j=0}^{k_{p}}\binom{k_{p} d}{j}\binom{p-k_{p}}{k_{p}-j} \exp \left\{\frac{M n \rho^{2}}{k_{p}} j+\frac{M k_{p}^{2} \log (p)}{d}\right\} \\
& \leqslant\{1+o(1)\} \sum_{j=0}^{k_{p}}\binom{k_{p}}{j} \frac{\left(d k_{p}\right)^{j}}{p^{j}} \exp \left\{\frac{M n \rho^{2}}{k_{p}} j+\frac{M k_{p}^{2} \log (p)}{d}\right\}
\end{aligned}
$$

$$
=\{1+o(1)\}\left(1+\frac{d k_{p} t}{p}\right)^{k_{p}} \exp \left\{\frac{M k_{p}^{2} \log (p)}{d}\right\}
$$

where $t=\exp \left(M n \rho^{2} / k_{p}\right)=p^{M c^{2}}$. It follows that

$$
\begin{aligned}
E\left(L_{\mu_{\rho}}^{2}\right) & \leqslant\{1+o(1)\} \exp \left\{k_{p} \log \left(1+\frac{d k_{p} t}{p}\right)+\frac{M k_{p}^{2} \log (p)}{d}\right\} \\
& \leqslant\{1+o(1)\} \exp \left\{k_{p} \frac{d k_{p} t}{p}+\frac{M k_{p}^{2} \log (p)}{d}\right\} \leqslant 1+4(1-\alpha-\nu)^{2}
\end{aligned}
$$

by letting $c$ be sufficiently small. If $k_{p}=O\left(p^{r}\right)$ for some $r<\frac{1}{2}$ and $\boldsymbol{\Omega}=\boldsymbol{\Sigma}^{-1}$ is $s_{p}$ sparse with $s_{p}=O\left\{\left(p / k_{p}^{2}\right)^{\gamma}\right\}$ for some $0<\gamma<1$, we let $B:=B_{m}=\left\{l: a_{k, l} \neq 0, k \in m\right\}$. Then we can similarly obtain

$$
\begin{aligned}
E\left(L_{\mu_{\rho}}^{2}\right) & \leqslant \frac{1}{\binom{p}{k_{p}}^{2}} \sum_{m \in \mathcal{M}} \sum_{j=0}^{k_{p}} I\left(\left|m^{\prime} \cap B\right|=j\right) \exp \left(\sum_{k \in m, l \in m^{\prime}} \frac{n \rho^{2}}{k_{p}}\left|a_{k l}\right|\right) \\
& \leqslant \frac{1}{\binom{p}{k_{p}}^{2}} \sum_{m \in \mathcal{M}} \sum_{j=0}^{k_{p}} I\left(\left|m^{\prime} \cap B\right|=j\right) \exp \left(\frac{M n \rho^{2}}{k_{p}} j\right) \leqslant\{1+o(1)\}\left(1+\frac{s_{p} k_{p} t}{p}\right)^{k_{p}} .
\end{aligned}
$$

So we can still obtain $E\left(L_{\mu_{\rho}}^{2}\right) \leqslant 1+4(1-\alpha-\nu)^{2}$ by letting $c$ be sufficiently small. Theorem 3 now follows from lemma 5.

## A.5. Proof of theorem 4

We only prove part (b) of theorem 4 in this section; part (a) follows from the proof of part (b) directly. Without loss of generality, we assume that $\sigma_{i, i}=1$ for $1 \leqslant i \leqslant p$. Define the event $\mathbf{A}=\left\{\max _{1 \leqslant i \leqslant p}\left|\delta_{i}\right| \leqslant\right.$ $8 \sqrt{ }\{\log (p) / n\}\}$. By conditions in theorem 4 , we have

$$
\max _{1 \leqslant i \leqslant p}\left|\hat{\omega}_{i, i}^{(0)}-\omega_{i, i}\right|=o_{P}\{1 / \log (p)\}
$$

Hence, as in the proof of proposition 1, part (i), in the on-line supplementary material, it is easy to show that $P\left(M_{\hat{\Omega}} \in R_{\alpha}, \mathbf{A}^{\mathrm{c}}\right)=P\left(\mathbf{A}^{\mathrm{c}}\right)+o(1)$ and $P\left(M_{\boldsymbol{\Omega}} \in R_{\alpha}, \mathbf{A}^{\mathrm{c}}\right)=P\left(\mathbf{A}^{\mathrm{c}}\right)+o(1)$. Note that $\hat{\boldsymbol{\Omega}}(\overline{\mathbf{X}}-\hat{\mathbf{Y}})=$ $(\hat{\boldsymbol{\Omega}}-\boldsymbol{\Omega})(\overline{\mathbf{X}}-\overline{\mathbf{Y}}-\boldsymbol{\delta})+(\hat{\boldsymbol{\Omega}}-\boldsymbol{\Omega}) \boldsymbol{\delta}+\boldsymbol{\Omega}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})$. On $\mathbf{A}$, we have

$$
|(\hat{\boldsymbol{\Omega}}-\boldsymbol{\Omega})(\overline{\mathbf{X}}-\overline{\mathbf{Y}}-\boldsymbol{\delta})+(\hat{\boldsymbol{\Omega}}-\boldsymbol{\Omega}) \boldsymbol{\delta}|_{\infty}=o_{P}\left[\frac{1}{\sqrt{ }\{n \log (p)\}}\right]
$$

To prove theorem 4, it suffices to show that

$$
\begin{equation*}
P\left(\max _{1 \leqslant i \leqslant p}\left|Z_{i}^{\mathrm{o}}\right| \geqslant \sqrt{ } x_{p}+a_{n}, \mathbf{A}\right)=P\left(\max _{1 \leqslant i \leqslant p}\left|Z_{i}^{\mathrm{o}}\right| \geqslant \sqrt{ } x_{p}, \mathbf{A}\right)+o(1) \tag{29}
\end{equation*}
$$

for any $a_{n}=o\left\{\log (p)^{-1 / 2}\right\}$, where $Z_{i}^{o}=(\boldsymbol{\Omega} \mathbf{Z})_{i} / \sqrt{ } \omega_{i, i}$ is defined in the proof of proposition 1, part (i), in the on-line supplementary material. From the proof of proposition 1, part (i), let $H=\operatorname{supp}(\boldsymbol{\delta})=\left\{l_{1}, \ldots, l_{p^{r}}\right\}$; then we can obtain

$$
\begin{gathered}
P\left(\max _{1 \leqslant i \leqslant p}\left|Z_{i}^{o}\right| \geqslant \sqrt{ } x_{p}+a_{n}, \mathbf{A}\right)=\alpha P(\mathbf{A})+(1-\alpha) P\left(\max _{i \in H}\left|Y_{i}\right| \geqslant \sqrt{ } x_{p}+a_{n}, \mathbf{A}\right)+o(1), \\
P\left(\max _{1 \leqslant i \leqslant p}\left|Z_{i}^{o}\right| \geqslant \sqrt{ } x_{p}, \mathbf{A}\right)=\alpha P(\mathbf{A})+(1-\alpha) P\left(\max _{i \in H}\left|Y_{i}\right| \geqslant \sqrt{ } x_{p}, \mathbf{A}\right)+o(1)
\end{gathered}
$$

where, given $\delta, Y_{i}, i \in H$, are independent normal random variables with unit variance. This, together with lemma 4, implies equation (29).

## A.6. Proof of theorem 6

Let $\left(V_{1}, \ldots, V_{p}\right)^{\prime}$ be a zero-mean random vector with covariance matrix $\boldsymbol{\Omega}=\left(\omega_{i, j}\right)$ and diagonal $\omega_{i, i}=1$ for $1 \leqslant i \leqslant p$ satisfying moment conditions 6 or 7 . Let $\hat{V}_{l i}=V_{l i} I\left(\left|V_{l i}\right| \leqslant \tau_{n}\right)$ for $l=1, \ldots, n$, where $\tau_{n}=$ $2 \eta^{-1 / 2} \sqrt{ } \log (p+n)$ if condition 6 holds and $\tau_{n}=\sqrt{ } n / \log (p)^{8}$ if condition 7 holds. Let $W_{i}=\Sigma_{l=1}^{n} V_{l i} / \sqrt{ } n$ and $\hat{W}_{i}=\sum_{l=1}^{n} \hat{V}_{l i} / \sqrt{ } n$. Then
$P\left\{\max _{1 \leqslant i \leqslant p}\left|W_{i}-\hat{W}_{i}\right| \geqslant \frac{1}{\log (p)}\right\} \leqslant P\left(\max _{1 \leqslant i \leqslant p} \max _{1 \leqslant l \leqslant n}\left|V_{l i}\right| \geqslant \tau_{n}\right) \leqslant n p \max _{1 \leqslant i \leqslant p} P\left(\left|V_{1 i}\right| \geqslant \tau_{n}\right)=O\left(p^{-1}+n^{-\varepsilon / 8}\right)$.

Note that

$$
\begin{equation*}
\left|\max _{1 \leqslant i \leqslant p} W_{i}^{2}-\max _{1 \leqslant i \leqslant p} \hat{W}_{i}^{2}\right| \leqslant 2 \max _{1 \leqslant i \leqslant p}\left|W_{i}\right| \max _{1 \leqslant i \leqslant p}\left|W_{i}-\hat{W}_{i}\right|+\max _{1 \leqslant i \leqslant p}\left|W_{i}-\hat{W}_{i}\right|^{2} . \tag{31}
\end{equation*}
$$

By expressions (30) and (31), it is enough to prove that, for any $x \in R$, as $p \rightarrow \infty$

$$
P\left[\max _{1 \leqslant i \leqslant p} \hat{W}_{i}^{2}-2 \log (p)+\log \{\log (p)\} \leqslant x\right] \rightarrow \exp \left\{-\frac{1}{\sqrt{ } \pi} \exp \left(-\frac{x}{2}\right)\right\} .
$$

It follows from lemma 1 that, for any fixed $k \leqslant[p / 2]$,

$$
\begin{align*}
\sum_{t=1}^{2 k}(-1)^{t-1} \sum_{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p} P\left(\left|\hat{W}_{i_{1}}\right| \geqslant x_{p}, \ldots,\right. & \left.\left|W_{i_{t}}\right| \geqslant x_{p}\right) \leqslant P\left(\max _{1 \leqslant i \leqslant p}\left|\hat{W}_{i}\right| \geqslant x_{p}\right) \\
& \leqslant \sum_{t=1}^{2 k-1}(-1)^{t-1} \sum_{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p} P\left(\left|\hat{W}_{i_{1}}\right| \geqslant x_{p}, \ldots,\left|W_{i_{t}}\right| \geqslant x_{p}\right) . \tag{32}
\end{align*}
$$

Define $|\hat{\mathbf{W}}|_{\text {min }}=\min _{1 \leqslant 1 \leqslant t}\left|\hat{W}_{i l}\right|$. Then, by theorem 1 in Zaïtsev (1987), we have

$$
\begin{equation*}
P\left(|\hat{\mathbf{W}}|_{\min } \geqslant x_{p}\right) \leqslant P\left\{|\mathbf{Z}|_{\min } \geqslant x_{p}-\varepsilon_{n} \log (p)^{-1 / 2}\right\}+c_{1} d^{5 / 2} \exp \left\{-\frac{n^{1 / 2} \varepsilon_{n}}{c_{2} d^{3} \tau_{n} \log (p)^{1 / 2}}\right\} \tag{33}
\end{equation*}
$$

where $c_{1}>0$ and $c_{2}>0$ are absolute constants, $\varepsilon_{n} \rightarrow 0$ which will be specified later and $\mathbf{Z}=\left(Z_{i_{1}}, \ldots, Z_{i_{t}}\right)^{\prime}$ is a $t$-dimensional normal vector as defined in theorem 1 . Because $\log (p)=o\left(n^{1 / 4}\right)$, we can let $\varepsilon \rightarrow 0$ sufficiently slowly such that

$$
\begin{equation*}
c_{1} d^{5 / 2} \exp \left\{-\frac{n^{1 / 2} \varepsilon_{n}}{c_{2} d^{3} \tau_{n} \log (p)^{1 / 2}}\right\}=O\left(p^{-M}\right) \tag{34}
\end{equation*}
$$

for any large $M>0$. It follows from expressions (32), (33) and (34) that

$$
\begin{equation*}
P\left(\max _{1 \leqslant i \leqslant p}\left|\hat{W}_{i}\right| \geqslant x_{p}\right) \leqslant \sum_{t=1}^{2 k-1}(-1)^{t-1} \sum_{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p} P\left\{|Z|_{\min } \geqslant x_{p}-\varepsilon_{n} \log (p)^{-1 / 2}\right\}+o(1) . \tag{35}
\end{equation*}
$$

Similarly, using theorem 1 in Zaïtsev (1987) again, we can obtain

$$
\begin{equation*}
P\left(\max _{1 \leqslant i \leqslant p}\left|\hat{W}_{i}\right| \geqslant x_{p}\right) \geqslant \sum_{t=1}^{2 k}(-1)^{t-1} \sum_{1 \leqslant i_{1}<\ldots<i_{t} \leqslant p} P\left\{|Z|_{\min } \geqslant x_{p}-\varepsilon_{n} \log (p)^{-1 / 2}\right\}-o(1) . \tag{36}
\end{equation*}
$$

So, by expressions (35) and (36) and the proof of theorem 1, the theorem is proved.

## A.7. Proof of theorem 7

(a) Part (a) follows from the proof of theorem 4.
(b) Note that $\hat{\boldsymbol{\Omega}}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})=(\hat{\boldsymbol{\Omega}}-\boldsymbol{\Omega})(\overline{\mathbf{X}}-\overline{\mathbf{Y}}-\boldsymbol{\delta})+(\hat{\boldsymbol{\Omega}}-\boldsymbol{\Omega}) \boldsymbol{\delta}+\boldsymbol{\Omega}(\overline{\mathbf{X}}-\overline{\mathbf{Y}})$. It suffices to prove that

$$
P\left[\max _{1 \leqslant i \leqslant p}\left|(\hat{\boldsymbol{\Omega}} \delta)_{i} \sqrt{ } n / \sqrt{ } \omega_{i, i}+\boldsymbol{\Omega}(\overline{\mathbf{X}}-\overline{\mathbf{Y}}-\delta)_{i} \sqrt{ } n / \sqrt{ } \omega_{i, i}\right| \geqslant \sqrt{ }\{\rho \log (p)\}\right] \rightarrow 1
$$

for some $\rho>2$. For this, we need only to show that

$$
P\left[\max _{1 \leqslant i \leqslant p}\left|(\hat{\boldsymbol{\Omega}} \delta)_{i} / \sqrt{ } \omega_{i, i}\right| \geqslant \sqrt{ }\{(2+\varepsilon / 4) \log (p) / n\}\right] \rightarrow 1
$$

Note that

$$
\left.\max _{1 \leqslant i \leqslant p}\left|(\hat{\boldsymbol{\Omega}} \delta)_{i} / \sqrt{ } \omega_{i, i}\right| \geqslant \max _{1 \leqslant i \leqslant p} \mid \boldsymbol{\Omega} \delta\right)_{i} / \sqrt{ } \omega_{i, i}\left|+o_{P}(1) \max _{1 \leqslant i \leqslant p}\right| \delta_{i}\left|\geqslant\left\{1+o_{P}(1)\right\} \max _{1 \leqslant i \leqslant p}\right|(\boldsymbol{\Omega} \delta)_{i} / \sqrt{ } \omega_{i, i} \mid .
$$

By the condition $\max _{i}\left|\delta_{i} / \sigma_{i, i}^{1 / 2}\right| \geqslant \sqrt{ }\{2 \beta \log (p) / n\}$ with $\beta \geqslant 1 / \min _{i}\left(\sigma_{i, i} \omega_{i, i}\right)+\varepsilon$ for some constant $\varepsilon>0$, we can obtain $\max _{1 \leqslant i \leqslant p}\left|(\Omega \delta)_{i} / \sqrt{ } \omega_{i, i}\right| \geqslant \sqrt{ }\{(2+\varepsilon / 2) \log (p) / n\}$ with probability tending to 1. This proves part (b).

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## Supporting information

Additional 'supporting information' can be found in the on-line version of this article: 'Supplement to "Two-sample test of high dimensional means under dependency"".


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