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USING GRAVITATIONAL-WAVE STANDARD SIRENS

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ABSTRACT

Gravitational waves (GWs) from supermassive binary black hole (BBH) in-spirals are potentially powerful standard sirens (the GW analog to standard candles; see work of B. Schutz). Because these systems are well modeled, the space-based GW observatory *LISA* will be able to measure the luminosity distance (but not the redshift) to some distant massive BBH systems with 1%–10% accuracy. This accuracy is largely limited by pointing error: GW sources are generally poorly localized on the sky. Localizing the binary independently (e.g., through association with an electromagnetic counterpart) greatly reduces this positional error. An electromagnetic counterpart may also allow determination of the event’s redshift. In this case, BBH coalescence would constitute an extremely precise (better than 1%) standard candle visible to high redshift. In practice, gravitational lensing degrades this precision, although the candle remains precise enough to provide useful information about the distance-redshift relation. Even if very rare, these GW standard sirens would complement, and increase confidence in, other standard candles.

Subject headings: black hole physics — cosmology: observations — cosmology: theory — galaxies: nuclei —
gravitational lensing — gravitational waves

Online material: color figures

1. INTRODUCTION

One of the major challenges to cosmology for the foreseeable future is to understand “dark energy,” the mysterious component responsible for the apparent accelerating expansion of our universe (Riess et al. 1998; Perlmutter et al. 1999; Tonry et al. 2003; Knop et al. 2003). Dark energy can be parameterized by its contribution to the universe’s energy density, Ω_X , and its equation-of-state ratio, $w(z)$. Of particular interest are measurements that probe $w(z)$, testing whether the dark energy is a true cosmological constant [$w(z) = -1$] or whether it arises, for example, from an evolving field (e.g., Caldwell et al. 1998; Armendariz-Picon et al. 2000).

One of our best observational probes of the dark energy is the distance-redshift relation, which maps the expansion history of the universe. Much of our knowledge of this relation comes from observations of distant Type Ia supernovae (SNe). These SNe serve as standard candles: their observed intensity can be calibrated to tell us their luminosity distance, D_L (Phillips 1993; Riess et al. 1995; Wang et al. 2003). As the redshift of a SN (or its host) can also be measured, each SN puts a point on the distance-redshift curve. Future surveys (e.g., *Supernova Acceleration Probe*,¹ *Large Synoptic Survey Telescope*²) are expected to measure thousands of Type Ia SNe, mapping the distance-redshift curve over a large span of redshift with good statistical significance.

Type Ia SNe are excellent standard candles, with (calibrated) peak brightness thought to be known to about 15%. One possible

objection to SNe as standard candles is the absence of a solid theoretical underpinning. Of particular concern is the possibility of evolution in SN brightnesses, leading to unknown systematic errors (Drell et al. 2000). In this article, we discuss a completely independent standard candle: the gravitational-wave (GW) driven in-spiral of massive binary black holes (BBHs). As GW detections can be thought of as aural rather than optical (Hughes 2003), a more appropriate term for a GW standard candle is a “standard siren.”³ Because BBH systems are relatively simple and well modeled (at least in the early “in-spiral” phase of their coalescence), the GWs they generate determine the source’s luminosity distance with high accuracy: typically $\delta D_L/D_L \sim 1\%–10\%$, with most of the uncertainty arising from correlations with pointing errors (Hughes 2002). BBH merger events will follow the mergers of galaxies and pregalactic structures at high redshift (Volonteri et al. 2003; Koushiappas & Zentner 2005). Although the merger rate is poorly understood, the *Laser Interferometer Space Antenna (LISA)* is expected to measure at least several events over its mission, especially as it is sensitive to these waves to enormous distances (Richstone 1998; Haehnelt 1998).

Since GWs do not provide the redshift of the source, BBH GW measurements alone do not probe the distance-redshift relation. However, as first noted by Bernard Schutz, should some kind of “electromagnetic” (EM) counterpart to a BBH GW event be identified, the situation changes drastically (Schutz 1986, 2002). First, by determining the source position, many correlations that set the distance error are broken. The error then drops immensely—below 0.5%–1% in many cases. Second, a

¹ See <http://snap.lbl.gov>.

² See <http://www.lsst.org>.

³ We thank Sterl Phinney and Sean Carroll for suggesting this term.

counterpart could determine the source's redshift. A BBH GW source coupled with an EM counterpart could therefore constitute an exceedingly good standard siren.⁴ We comment at this point that, to date, there has not been a great deal of careful analysis regarding the nature of EM counterparts that may accompany a GW event. We briefly discuss in §§ 3 and 5 some ideas that have been presented to date regarding the form that counterparts may take. We hope that the promise of this high-quality candle will motivate additional thinking on this issue.

In practice, gravitational lensing will limit the quality of this candle. GWs are lensed by intervening matter exactly as electromagnetic waves are lensed (Marković 1993; Wang et al. 1996; Takahashi & Nakamura 2003). As the waves propagate through our inhomogeneous universe, they are magnified (or demagnified), inducing some error in our inferred luminosity distance to the source. As we discuss in § 4, the distribution of errors is such that a BBH candle will most likely be comparable in quality to a Type Ia SN standard candle. However—and we strongly emphasize this point—the BBH candle will have entirely different systematics from SNe. Concordance between the two types of measurement could thus alleviate concerns about evolutionary effects in Type Ia SNe and greatly increase one's confidence in all standard candles.

2. DISTANCE DETERMINATION WITH BBH GWs AND LISA

Massive BBH coalescences are among the most luminous events in the universe. That luminosity (peaked at $\sim 10^{57}$ ergs s^{-1}) is radiated in GWs, which couple very weakly to matter. The planned space-based GW detector *LISA* will be sensitive to these BBH waves in the frequency band $(10^{-5} - 10^{-4}) \lesssim f \lesssim 0.1$ Hz, making measurement possible from binaries with total masses $m_1 + m_2 \sim 10^3 - 10^6 M_\odot$ (Danzmann et al. 1998) out to redshifts of at least $z \sim 5 - 10$ and possibly beyond (Hughes 2002; Vecchio 2004). In this section we discuss how *LISA* measurements determine the distance to a source, summarizing our model of the waveform and *LISA*'s sensitivity and response, and discussing the measurement precision we expect from measuring merging black hole populations.

2.1. Merging Black Hole GWs

For this paper, the most interesting epoch of BBH coalescence is the *in-spiral*, when the binary's members are widely separated and slowly spiral together due to back-reaction from GW emission. The GWs from this epoch are well modeled using the post-Newtonian approximation (roughly speaking, an expansion in inverse separation of a binary's members; see Blanchet 2002 and references therein for a more detailed discussion). We do not discuss waves from the *merger* (in which the holes come into contact, forming a single body) or from the *ring-down* (the final, simple stage of the ring-down, in which the merged binary is well modeled as a single, distorted black hole), as they do not substantially impact distance determination.

In-spiral GWs encode the luminosity distance to a binary, its position on the sky, its orientation, and information about certain combinations of masses and spins (see Arun et al. 2004

and Blanchet et al. 2004 for up-to-date discussion and details). The in-spiral does *not* encode a source's cosmological redshift. Redshift is instead entangled with the binary's evolution. For example, the masses (m_1, m_2) impact orbital evolution as timescales ($Gm_1/c^3, Gm_2/c^3$). These timescales redshift, so the measured masses redshift; a binary with masses (m_1, m_2) at redshift z is indistinguishable from a local binary with masses $[(1+z)m_1, (1+z)m_2]$ (modulo amplitude). This reflects the fact that general relativity has no absolute scale.

In a reference frame centered on the solar system's barycenter, the strongest harmonic of the in-spiral GW's two polarizations has the form

$$h_+ = \frac{2\mathcal{M}_z^{5/3} [\pi f(t)]^{2/3}}{D_L} \left[1 + (\hat{L} \cdot \hat{n})^2 \right] \cos[\Phi(t)], \quad (1)$$

$$h_\times = \frac{4\mathcal{M}_z^{5/3} [\pi f(t)]^{2/3} (\hat{L} \cdot \hat{n})}{D_L} \sin[\Phi(t)]. \quad (2)$$

The mass parameter $\mathcal{M}_z = (1+z)(m_1 m_2)^{3/5} / (m_1 + m_2)^{1/5}$ is the binary's redshifted "chirp mass," so called because it largely sets the rate at which the binary's members spiral toward each other, determining the "chirp" of the orbital frequency. The phase $\Phi(t)$ depends on intrinsic binary parameters: the masses and spins of its members (e.g., Poisson & Will 1995). It depends particularly strongly on \mathcal{M}_z ; as a consequence, phase-coherent measurements of the waves will determine the chirp mass with great precision (Finn & Chernoff 1993; Cutler & Flanagan 1994). The wave frequency $f(t) = (1/2\pi)d\Phi/dt$. The unit vector \hat{n} points from the center of the barycenter frame to the system and hence defines its position on the sky; \hat{L} points along the binary's orbital angular momentum and hence defines its orientation. Notice that the luminosity distance D_L appears in combination with these two angular factors. Determining D_L thus requires fixing these angles. As we now discuss, *LISA* is able to do so by virtue of its orbital motion.

2.2. Merger GWs as Measured by LISA

LISA consists of three spacecraft, arranged in orbits about the Sun such that they form an equilateral triangle (roughly; the arm lengths are in general not equal, and in fact oscillate, albeit with periods much longer than those of the GWs we aim to observe). This triangle "rolls" as the spacecraft move through their individual orbits, preserving the triangular formation. The centroid of the constellation shares Earth's orbit, lagging by 20° , so that it takes 1 yr to orbit the Sun. Figure 1 shows a schematic of the orbital configuration (see Danzmann et al. [1998] for a detailed discussion of the *LISA* mission and its orbital configuration).

At least in the low-frequency limit ($f < c/L$, where L is arm length), *LISA* can very usefully be regarded as two GW detectors; the time-varying arm length data, $(\delta L_1, \delta L_2, \delta L_3)$, can be used to synthesize outputs for two equivalent L-shaped detectors, with 90° arms. These "equivalent detectors" are rotated by 45° with respect to each other (see Cutler [1998] for details and derivation of this viewpoint). The data stream $s_{I,II}$ of these two equivalent detectors is given by a weighted sum of the two GW polarizations, plus noise,

$$s_{I,II}(t) = \frac{\sqrt{3}}{2} \left[F_{I,II}^+(t) h_+(t) + F_{I,II}^\times(t) h_\times(t) \right] + n_{I,II}(t). \quad (3)$$

The prefactor $\sqrt{3}/2$ in this expression enters when converting the "real" interferometer response to that of the synthesized equivalent detectors. The antenna functions $F_{I,II}^{+, \times}$ depend on the

⁴ It may also be possible to use the *distributions* of observed binaries for cosmology, obviating the need for an EM counterpart (Chernoff & Finn 1993; Finn 1996; Wang & Turner 1997). Unless the event rate is much higher than currently expected, however, the statistical errors associated with these distributions suggest that these methods will not achieve accuracy sufficient to measure properties of the dark energy equation of state, our primary focus. Certainly other cosmologically interesting measurements could be made.

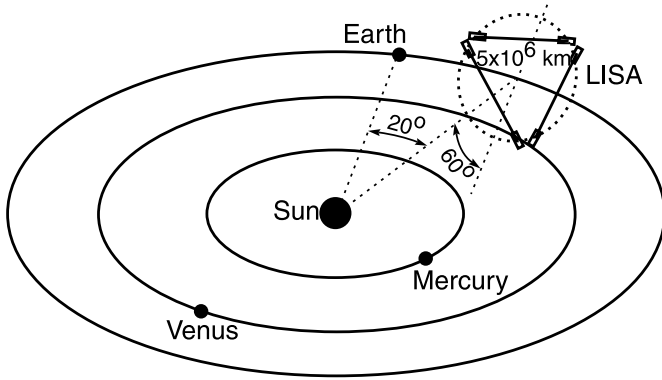


FIG. 1.—Illustration of the *LISA* antenna’s orbit. The constellation “rolls” as its centroid orbits the sun, completing one full revolution for each orbit.

orientation and position of the source relative to the antenna. Because of the antenna’s orbital motion, the position and orientation of the source relative to the antenna is continually changing. The motion of the detector thus modulates the measured signal; the exact nature of the modulation depends on the position and orientation of the source. We write the response functions as time-dependent functions to reflect this modulation. Note also that the waveform phasing is modified in an important manner by the antenna’s motion: the orbital motion causes frequency as well as amplitude modulation (see Cutler [1998] for further discussion).

We take the noises in the equivalent detectors, $n_{I,II}(t)$, to be uncorrelated, Gaussian random processes, with the same rms values:

$$\langle n_I n_{II} \rangle = 0; \quad \langle n_I^2 \rangle = \langle n_{II}^2 \rangle. \quad (4)$$

In all of our analysis, we use the same noise model as that used by Barack & Cutler (2004; see their eqs. [48]–[54]). In our calculations, it is necessary to introduce a low-frequency cutoff: a frequency at which the sensitivity to GWs rapidly degrades. This cutoff has important implications for determining which binaries *LISA* can measure; the frequency support of a binary’s GW spectrum is inversely proportional to its mass. In other words, more massive binaries will radiate at lower frequencies than less massive binaries. The low-frequency cutoff thus determines the *maximum* binary black hole mass accessible to *LISA* measurements. It also determines the amount of time for which a binary’s waves are in band; a binary that may only be in band for a few days when $f_{\text{low}} = 10^{-4}$ Hz may be in band for many months when $f_{\text{low}} = 3 \times 10^{-5}$ Hz.

Unless stated otherwise, we have set $f_{\text{low}} = 10^{-4}$ Hz for the results we present here. This is a somewhat conservative choice; some members of the *LISA* mission design community (particularly P. Bender) argue that *LISA* should have good sensitivity down to frequencies $f \sim 10^{-5}$ Hz. Accordingly, we have put $f_{\text{low}} = 3 \times 10^{-5}$ Hz in several of our calculations. We flag such cases when appropriate.

To understand more clearly how *LISA* extracts the luminosity distance from measurements of a binary black hole in-spiral, it is useful to rewrite somewhat schematically the measured form of the in-spiral as

$$h_{I,II}^{\text{meas}}(t) = \frac{\mathcal{M}_z^{5/3} f(t)^{2/3}}{D_L} \mathcal{F}_{I,II}(\text{“angles”}, t) \times \cos[\Phi(t) + \varphi_{I,II}(\text{“angles”}, t)]. \quad (5)$$

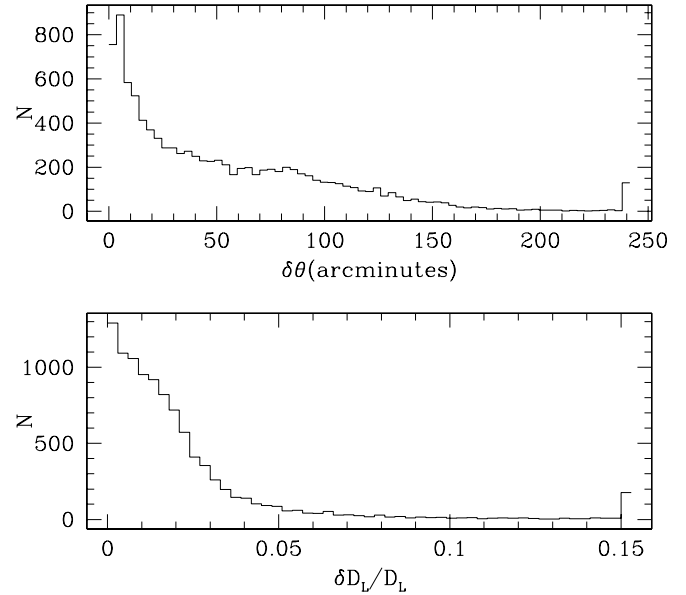


FIG. 2.—Pointing and distance error distributions for measurements at $z = 1$ of a binary of masses $m_1 = 10^5 M_\odot$ and $m_2 = 6 \times 10^5 M_\odot$. These distributions were made by Monte Carlo simulations of 10,000 *LISA* BBH measurements, randomly distributing the binaries’ positions, orientations, and merger times; see Hughes (2002) for details. The top distribution shows that the most likely position error boxes have sides $\delta\theta \lesssim 10'$, spreading out to $\delta\theta \gtrsim 3^\circ$. The distance distribution peaks at $\delta D_L / D_L \lesssim 1\%$, with most of the distribution confined to $\delta D_L / D_L \lesssim 5\%$.

We have subsumed the angle-dependent factors $(\hat{L} \cdot \hat{n})$ and $F_{I,II}^{+, \times}$ into the schematic functions $\mathcal{F}_{I,II}$ (“angles”, t); we leave the dependence on t in these functions as a reminder that the constellation’s motion modulates the waveform. We have likewise written the phase modulations imposed by the detector’s response and motion in the schematic form $\varphi_{I,II}$ (“angles”, t).

From the form of equation (5) we see that the luminosity distance is very strongly correlated with the redshifted chirp mass, \mathcal{M}_z , and the various angles that set the instantaneous waveform amplitude. As already mentioned, \mathcal{M}_z is typically determined with extremely high precision because it fixes the phase evolution; typically, $\delta \mathcal{M}_z / \mathcal{M}_z \lesssim 0.01\%$ (see Hughes [2002] and Vecchio [2004] for examples specific to *LISA*).

The modulations induced by *LISA*’s orbital motion make it possible to measure sky position for events that last for at least a fair fraction of *LISA*’s orbit. We estimate the accuracy with which position (among other parameters) is determined, using a maximum likelihood parameter estimation formalism (Finn 1992); from the detector’s response to a given gravitational wave, we construct the variance-covariance matrix Σ^{ab} . Diagonal elements of this matrix represent the rms error $\langle (\delta\chi^a)^2 \rangle$ in a source parameter χ^a ; off-diagonal components describe the degree to which errors in parameters χ^a and χ^b are correlated (see Hughes [2002] for discussion specifically tailored to this application).

2.3. Measurement Accuracy Distributions

To assess distance and position accuracy, we have estimated the accuracy with which these parameters are measured for a wide range of binary masses. For each set of masses, we randomly distribute the sky position and orientation of 10,000 such binaries. We then calculate the fractional accuracy with which distance is determined for each binary, $\delta D_L / D_L$, as well as the angular sky position error $\delta\theta$. Figure 2 shows the distribution we

TABLE 1
MEASUREMENT PRECISION AT $z = 1$ WITH $f_{\text{low}} = 10^{-4}$ Hz

m_1 (M_\odot)	m_2 (M_\odot)	$\delta D_L/D_L$ (5%, 25%, 50%, 90%)	$\delta\theta$ (5%, 25%, 50%, 90%) (arcmin)			
			(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)
10^4	10^4	(0.005, 0.010, 0.014, 0.042)	(14.3, 28.3, 48.5, 117)			
	3×10^4	(0.003, 0.008, 0.013, 0.037)	(11.0, 22.1, 41.6, 111)			
	6×10^4	(0.003, 0.007, 0.013, 0.036)	(9.05, 19.1, 40.4, 109)			
3×10^4	10^5	(0.005, 0.007, 0.013, 0.035)	(7.85, 18.3, 39.5, 110)			
	10^5	(0.002, 0.006, 0.013, 0.029)	(5.26, 14.6, 37.4, 120)			
	10^5	(0.002, 0.006, 0.012, 0.037)	(4.07, 12.9, 35.0, 120)			
6×10^4	10^5	(0.002, 0.005, 0.012, 0.034)	(3.36, 11.7, 33.4, 117)			
	3×10^5	(0.001, 0.005, 0.012, 0.035)	(2.71, 10.6, 33.1, 116)			
	6×10^5	(0.001, 0.006, 0.014, 0.044)	(2.82, 12.0, 38.8, 120)			
10^5	10^6	(0.002, 0.009, 0.017, 0.053)	(3.89, 18.5, 50.9, 126)			
	10^6	(0.002, 0.013, 0.026, 0.087)	(4.65, 29.7, 71.0, 172)			
	10^6	(0.003, 0.019, 0.035, 0.122)	(5.60, 39.2, 93.6, 220)			
3×10^5	10^6	(0.004, 0.024, 0.043, 0.149)	(6.36, 52.2, 118, 271)			
	10^6					
	10^6					

find in these quantities for binaries with $m_1 = 10^5 M_\odot$ and $m_2 = 6 \times 10^5 M_\odot$ at $z = 1$. We find that the typical position determination is relatively poor; these binaries are fixed to an error box that, at best, is $\sim 5'$ on a side. In most cases, the resolution is substantially worse. The distance determination, by contrast, is quite good: half of these events have their distance determined with precision $\delta D_L/D_L \lesssim 1\%$.

Table 1 summarizes the parameter determination distributions we find for a wide range of masses. For $\delta D_L/D_L$ and $\delta\theta$, we give the 5%, 25%, 50%, and 90% likelihood values from the distributions predicted by our Monte Carlo calculation. For example, for binaries with $m_1 = 3 \times 10^4 M_\odot$ and $m_2 = 10^5 M_\odot$ at $z = 1$, 25% of all events have $\delta D_L/D_L \lesssim 0.006$ and localize the source to $\delta\theta \lesssim 14.6'$; 90% of all events with these masses and redshifts have $\delta D_L/D_L \lesssim 0.029$ and localize the source to $\delta\theta \lesssim 120'$.

Notice that, in this table, the best pointing and distance determination occurs for binaries that have a total (redshifted) mass $(1+z)(m_1 + m_2) \simeq \text{several} \times 10^5 M_\odot$. Two competing effects drive this behavior. First, for small binaries the amplitude of the GWs is smaller; the degradation of their parameter determination is due to reduced signal-to-noise ratio. Larger binaries are more interesting. When such binaries enter *LISA*'s sensitive band, they are closer to their final merger; much less in-spiral remains once *LISA* begins measuring their waves. They therefore do not exhibit as many cycles of detector-motion-

TABLE 2
MEASUREMENT PRECISION AT $z = 1$ WITH $f_{\text{low}} = 3 \times 10^{-5}$ Hz

m_1 (M_\odot)	m_2 (M_\odot)	$\delta D_L/D_L$ (5%, 25%, 50%, 90%)	$\delta\theta$ (5%, 25%, 50%, 90%) (arcmin)			
			(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)
10^5	10^5	(0.002, 0.005, 0.012, 0.036)	(3.35, 11.4, 33.2, 117)			
	3×10^5	(0.001, 0.005, 0.011, 0.034)	(2.68, 10.4, 31.0, 107)			
	6×10^5	(0.001, 0.005, 0.010, 0.032)	(2.71, 9.85, 29.7, 103)			
3×10^5	10^6	(0.001, 0.005, 0.010, 0.031)	(3.27, 10.5, 29.1, 101)			
	10^6	(0.001, 0.004, 0.009, 0.028)	(2.45, 8.77, 25.8, 89.9)			
	10^6	(0.001, 0.004, 0.009, 0.026)	(2.25, 8.5, 24.8, 84.3)			
6×10^5	10^6	(0.001, 0.004, 0.009, 0.026)	(2.39, 9.05, 25.3, 83.5)			
	3×10^6	(0.002, 0.006, 0.011, 0.034)	(4.56, 12.6, 34.6, 93.8)			
	6×10^6	(0.003, 0.008, 0.016, 0.051)	(7.16, 20.6, 45.9, 110)			
10^6	10^7	(0.003, 0.011, 0.021, 0.071)	(9.20, 27.0, 57.1, 136)			

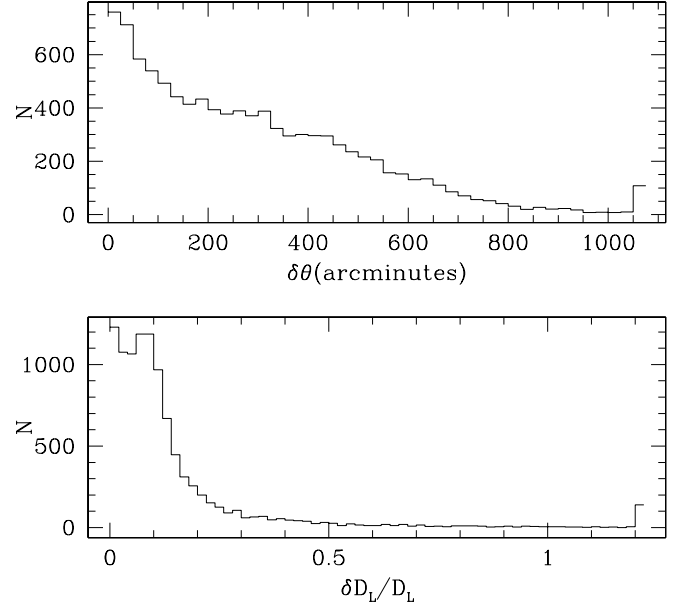


FIG. 3.—Pointing and distance error distributions for measurements at $z = 3$ of a binary of masses $m_1 = 10^5 M_\odot$ and $m_2 = 6 \times 10^5 M_\odot$. The distribution for position error is so broad that we cannot really identify a “most likely” position error; however, most of the distribution lies at $\delta\theta \lesssim 10^\circ$. The distance distribution peaks at $\delta D_L/D_L \lesssim 10\%$, with most of the distribution confined to $\delta D_L/D_L \lesssim 30\%$.

induced modulation, so their position angles are not as well determined. In particular, we find that distance and position determination rapidly degrades as binaries are made more massive than $(1+z)(m_1 + m_2) \gtrsim \text{a few} \times 10^6 M_\odot$.

The poor parameter determination tendency of large binaries can be repaired somewhat by improving *LISA*'s low-frequency sensitivity. If the antenna has good sensitivity at lower frequencies, the span of data containing good information about the in-spiral can be lengthened. Table 2 shows how well we measure distance and position when f_{low} is reduced from 10^{-4} to 3×10^{-5} Hz. We now find that the distance is determined very precisely for binaries with total mass of several $\times 10^6 M_\odot$. Sky position error is no worse than that achieved at lower masses, $\delta\theta \lesssim 10'$ in the best cases, and is more typically a factor of a few larger than this.

The same general story holds as we move to larger redshift. Figure 3 duplicates the content of Figure 2, but with binaries at redshift $z = 3$. Likewise, Tables 3 and 4 duplicate the content

TABLE 3
MEASUREMENT PRECISION AT $z = 3$ WITH $f_{\text{low}} = 10^{-4}$ Hz

m_1 (M_\odot)	m_2 (M_\odot)	$\delta D_L/D_L$ (5%, 25%, 50%, 90%)	$\delta\theta$ (5%, 25%, 50%, 90%) (arcmin)			
			(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)	(5%, 25%, 50%, 90%)
10^4	10^4	(0.013, 0.029, 0.051, 0.143)	(37.7, 78.2, 158, 422)			
	3×10^4	(0.010, 0.026, 0.050, 0.135)	(27.2, 66.8, 150, 428)			
	6×10^4	(0.008, 0.024, 0.050, 0.145)	(22.0, 57.7, 140, 442)			
3×10^4	10^5	(0.008, 0.024, 0.050, 0.142)	(19.3, 55.4, 143, 465)			
	10^5	(0.006, 0.019, 0.044, 0.131)	(12.6, 44.5, 125, 444)			
	10^5	(0.006, 0.021, 0.044, 0.128)	(10.1, 42.6, 132, 429)			
6×10^4	10^5	(0.005, 0.024, 0.049, 0.141)	(9.55, 44.8, 144, 430)			
	3×10^5	(0.007, 0.034, 0.069, 0.213)	(11.3, 69.9, 193, 485)			
	6×10^5	(0.008, 0.044, 0.087, 0.287)	(17.5, 96.1, 240, 593)			
10^5	10^6	(0.009, 0.058, 0.111, 0.378)	(23.4, 127, 304, 734)			

TABLE 4
MEASUREMENT PRECISION AT $z = 3$ WITH $f_{\text{low}} = 3 \times 10^{-5}$ Hz

m_1 (M_\odot)	m_2 (M_\odot)	$\delta D_L/D_L$ (5%, 25%, 50%, 90%)	$\delta\theta$
			(5%, 25%, 50%, 90%) (arcmin)
10^4	10^4	(0.013, 0.029, 0.050, 0.136)	(37.4, 76.0, 156, 423)
	3×10^4	(0.010, 0.026, 0.050, 0.137)	(26.5, 62.7, 149, 437)
	6×10^4	(0.009, 0.024, 0.049, 0.140)	(21.9, 57.8, 141, 441)
3×10^4	10^5	(0.007, 0.023, 0.049, 0.139)	(19.0, 55.3, 143, 465)
	10^5	(0.006, 0.019, 0.043, 0.135)	(12.4, 43.6, 124, 429)
	10^5	(0.005, 0.018, 0.040, 0.126)	(10.4, 38.8, 114, 404)
6×10^4	10^5	(0.004, 0.016, 0.038, 0.120)	(8.85, 34.7, 106, 384)
	3×10^5	(0.004, 0.016, 0.035, 0.108)	(8.26, 32.4, 98.7, 360)
	6×10^5	(0.005, 0.016, 0.035, 0.105)	(10.9, 36.0, 100, 346)
3×10^5	10^6	(0.006, 0.017, 0.035, 0.106)	(15.2, 41.6, 105, 349)
	10^6	(0.005, 0.017, 0.034, 0.100)	(12.2, 37.3, 101, 327)
	10^6	(0.006, 0.019, 0.039, 0.115)	(13.1, 42.1, 120, 336)
6×10^5	10^6	(0.007, 0.025, 0.049, 0.146)	(16.9, 55.5, 145, 359)
	3×10^6	(0.009, 0.040, 0.077, 0.240)	(24.8, 89.1, 208, 507)
	6×10^6	(0.014, 0.063, 0.116, 0.392)	(35.4, 142, 322, 757)

of Tables 1 and 2, respectively, with all binaries placed at $z = 3$. The overall parameter determinations are worsened, as we would expect; these sources are much farther away, and so have greatly reduced signal-to-noise ratios. In addition, the larger cosmological redshift shifts the signal to lower frequencies, where much of it is lost in low-frequency noise. To quantify the impact of this effect, in Table 4 we present results showing what happens when we lower f_{low} from 10^{-4} to 3×10^{-5} Hz. All cases with $m_1 + m_2 \geq 6 \times 10^5 M_\odot$ are substantially improved by this fix. Good low-frequency performance will be important for measuring high-redshift binaries. The best pointing accuracy we find is $\delta\theta \lesssim 40'$; $\delta\theta \sim 1^\circ$ or larger is more typical. The luminosity distance can still be determined quite well; we find errors of a few percent in the best cases, and $\delta D_L/D_L \lesssim 15\%$ is quite common.

It is worth emphasizing at this point that the results we present here are most likely somewhat conservative. By taking into account other GW harmonics (Moore & Hellings 2002) and properly accounting for the high-frequency structure of *LISA*'s response (Seto 2002), the pointing accuracy and thus distance accuracy can be improved by a factor of a few. Properly accounting for modulations induced by spin-orbit and spin-spin coupling can also improve pointing accuracy and thus distance determination, in some cases significantly (Vecchio 2004).

Using a determination of D_L , we can *infer* the redshift by using knowledge of the universe's geometry (the Hubble constant, mean density of matter Ω_m , and density of dark energy Ω_Λ ; Hughes 2002). This makes interesting analyses possible (e.g., we can map the distribution of black hole masses as a function of redshift), but presupposes rather than measures the distance-redshift relation.

3. THE IMPACT OF A COUNTERPART

Parameter estimation improves dramatically when an EM counterpart to a BBH GW event can be identified. The counterpart will almost certainly be pinpointed with far greater accuracy than is possible with GWs. Correlations between position and distance are then broken, greatly reducing the distance error. An example of this improvement is shown for $z = 1$ in Figure 4. The distribution of distance errors peaks near $\delta D_L/D_L \sim 0.1\%$ and is largely confined to $\delta D_L/D_L \lesssim 1\%$. Similar results are seen for $z = 3$ (Fig. 5), albeit with precision degraded by a

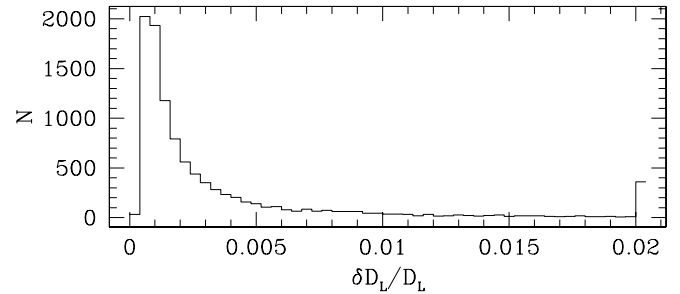


FIG. 4.—Distance errors for BBH measurements at $z = 1$ with $m_1 = 10^5 M_\odot$ and $m_2 = 6 \times 10^5 M_\odot$, assuming that an electromagnetic counterpart allows precise sky position determination. The peak error is at $\delta D_L/D_L \sim 0.1\%$ and is almost entirely confined to $\delta D_L/D_L \lesssim 0.5\%$.

factor of a few due to a lower signal-to-noise ratio. Comparing to the lower panel of Figures 2 and 3, we see that associating the event with a counterpart improves distance accuracy by roughly an order of magnitude. This rough level of improvement holds over a wide band of mass and redshift.

A correlated GW/EM measurement will be particularly important if the counterpart provides a redshift as well as an improved D_L . Such a measurement would constitute a powerful standard candle, probing the distance-redshift relation in a manner complementary to other candles, such as Type Ia supernovae. Assuming a flat universe and a Hubble constant $h_0 = 0.65$, we ask how well the matter density Ω_m and dark energy equation-of-state ratio w can be measured. Figure 6 shows estimated likelihood contours (1σ) in the (Ω_m, w) plane. The dotted line shows the contour expected for measurements of 3,000 SNe evenly distributed within $0.7 < z < 1.7$ (reasonable choices for the *Supernova/Acceleration Probe [SNAP]*); the solid contour is for two GW events, one each at $z = 1$ and 3. (We discuss the dashed line below.) Redshift and distance are measured with such accuracy that the contours are extremely tight even for only a small number of sources.

We emphasize the current poor understanding of EM counterparts to BBH GW events, although the possibility of such counterparts has been discussed for quite some time (e.g., Begelman et al. 1980). Milosavljević & Phinney (2005) have recently examined the evolution of gas in the environment of a merging binary and show that there is likely to be a delayed electromagnetic afterglow. They find that the merging binary carves a hollow region in the volume of circumbinary gas. The binary separation shrinks faster than the inner edge of the hollowed region; thus, as the coalescence proceeds, there should be no substantial accretion of material onto the system. The gas falls onto

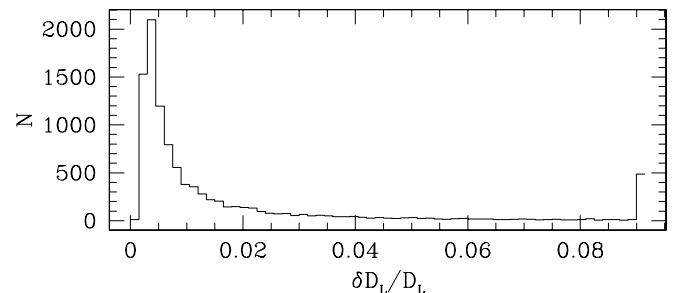


FIG. 5.—Distance errors for BBH measurements at $z = 3$ with $m_1 = 10^5 M_\odot$ and $m_2 = 6 \times 10^5 M_\odot$, assuming that an electromagnetic counterpart allows precise sky position determination. The peak error is at $\delta D_L/D_L \sim 0.5\%$ and is almost entirely confined to $\delta D_L/D_L \lesssim 2\%$.

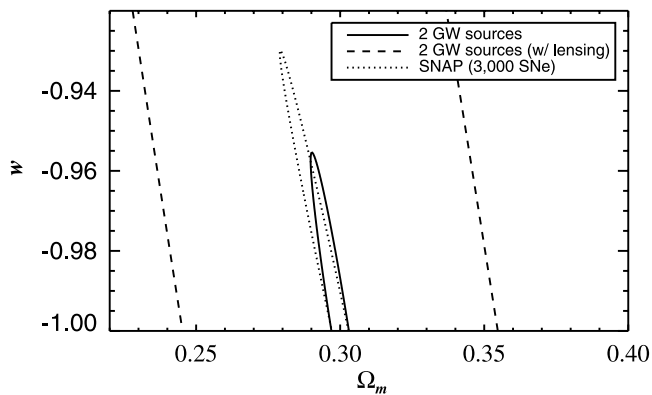


FIG. 6.—Likelihood contours for measurement of the matter density Ω_m and dark energy equation-of-state parameter w (with the pressure and density of the dark energy related by $p = w\rho$). We assume that the universe is flat, and that the underlying model has $\Omega_m = 0.3$ and $w = -1$. The two GW sources are at $z = 1$ and 3, while the SNAP SNe are evenly distributed within $0.7 < z < 1.7$. [See the electronic edition of the *Journal* for a color version of this figure.]

the merged remnant several years after the merger, leading to an afterglow that should be measurable by next-generation X-ray telescopes.

Other models suggest that there may be an electromagnetic precursor to the merger rather than a delayed glow. One example is discussed by Armitage & Natarajan (2002). They argue that gas is driven onto the larger member of the binary by the secondary’s in-spiral, leading to super-Eddington accretion. In this model, much of the inner disk may be expelled from the system in a high-velocity ($\sim 10^4$ km s $^{-1}$) outflow. Such strong outflows could flag a recent or impending merger. A similar family of models (Sillanpää et al. 1988; Lehto & Valtonen 1996) explains periodic variations in the BL Lac object OJ 287 by a tight, eccentric binary system with mass ratio of about 1:100. Flaring outbursts from this quasar are explained as arising from the secondary periodic crossing of the primary’s accretion disk. Given the great payoff that would follow from associating a counterpart to a GW event, we strongly advocate continuing to develop and refine models of BBH mergers.

It is worth noting that, for a small fraction of binaries (assuming a sufficiently high event rate), *LISA* will provide an error box of $\lesssim 5'$ and an estimate of the time of merger about a day in advance. Regardless of the state of theoretical predictions, we imagine that in such cases there will be great interest in searching the GW source error box for any observational counterparts to the merger. Indeed, as we briefly discuss in § 5, the number of relevant galaxies in the *LISA* error box may be fairly small, so associating an EM counterpart with the GW event may be tractable.

4. GRAVITATIONAL LENSING

Having discussed the impressive quality of GW standard sirens, we turn now to an important caveat: the impact of gravitational lensing on the distance measurement. GWs are lensed exactly as EM radiation is lensed. Since we expect BBH events to come from rather large redshift ($z \gtrsim 1$), weak lensing in the GW data sets should be common (Marković 1993; Wang et al. 1996; in addition to the occasional strongly lensed source).

A lens with magnification μ will distort the inferred luminosity distance to the source; if the true distance is D_L , we measure $D_L/\sqrt{\mu}$, incurring a “systematic” error $\Delta D_L/D_L = 1 - 1/\sqrt{\mu}$. We estimate the error such lensing is likely to introduce by convolving this quantity with the expected magnification

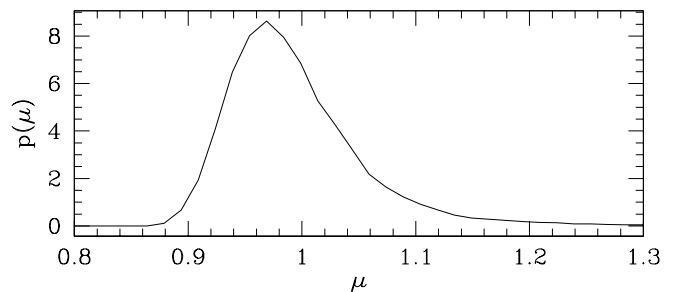


FIG. 7.—Differential probability of magnification by gravitational lensing, $p(\mu)$, for sources at $z = 1.5$ in a concordance universe (see Wang et al. [2002] for details).

distribution, $p(\mu)$ (Holz & Wald 1998; Wang et al. 2002); an example of this distribution is shown in Figure 7. Using parameters appropriate to a Λ CDM model of the universe, we find a mean error at $z = 2$ of $\langle \Delta D_L/D_L \rangle \simeq 0.005$, with a standard deviation $\langle (\Delta D_L/D_L)^2 \rangle^{1/2} \simeq 0.05$. The dashed line in Figure 6 shows the contour we expect from the two GW sources when lensing errors are included. The parameter accuracies are significantly degraded.

Of course, this magnification bias affects *all* standard candles, not just GWs. The rate of Type Ia SNe, however, is high enough to sufficiently sample the entire lensing distribution and thus average away the bias. Missions such as *SNAP* are designed to observe thousands of SNe at high redshift, in large part to overcome gravitational lensing. Indeed, this may allow one to measure the lensing signal well enough to infer characteristics of the lensing matter (Metcalf & Silk 1999; Seljak & Holz 1999). This is unlikely to be the case with BBH GWs; the rate of mergers will likely be much lower than that of SNe (Richstone 1998; Haehnelt 1998), so we cannot count on enormous numbers of events. We also emphasize that we do not expect to be able to correct for gravitational lensing effects on a case-by-case basis (Dalal et al. 2003). Lensing, therefore, will introduce an insurmountable error of $\sim 5\%$ – 10% for each individual high-redshift event, significantly greater than the intrinsic distance error.

5. IDENTIFYING THE COUNTERPART

In order to provide data on the distance-redshift curve, a GW event must be associated with an “electromagnetic” counterpart—GWs provide an accurate measure of luminosity distance but give no direct information about redshift. This is the weakest link in our analysis; we do not know whether such counterparts exist. However, a simple counting argument suggests that the number of relevant galaxies in the *LISA* error cube may be fairly small. We approximate the redshift distribution of source galaxies by

$$\frac{dN}{dR d\Omega} \propto R^\alpha \exp\left[-(R/R_*)^\beta\right], \quad (6)$$

where R is the comoving distance; we take $\alpha = 1$, $\beta = 4$, and $R_* = c/H_0$ (Kaiser 1992; Hu 1999). We normalize this to a projected number density of

$$\frac{dN}{d\Omega} = \int dR \frac{dN}{dR d\Omega} \simeq 300 \text{ galaxies arcmin}^{-2}, \quad (7)$$

approximating the Hubble Deep Field (Williams et al. 1996).

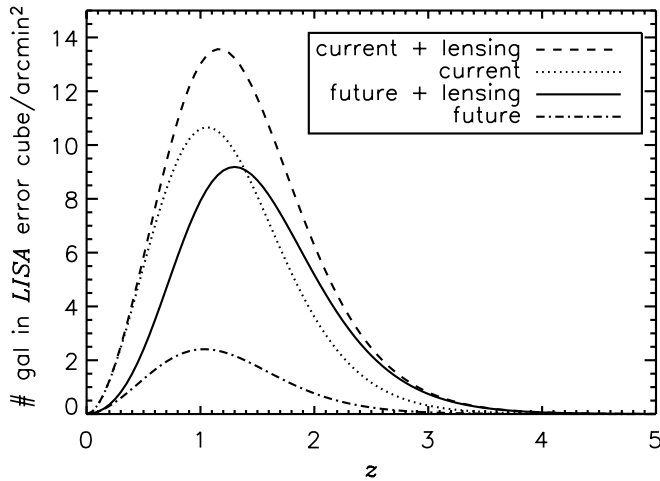


FIG. 8.—Number of candidate host galaxies per square arcminute of the *LISA* error cube for a supermassive binary black hole coalescence event, as a function of redshift of the event. The dotted line utilizes current uncertainties in cosmological parameters (Spergel et al. 2003). The dot-dashed line represents possible future improvements in these parameters (1% in Ω_m , Ω_Λ , and H_0). The dashed line includes the degradation in the depth of the error cube due to gravitational lensing, for current cosmological uncertainties. The solid line represents future cosmological uncertainties, with the inclusion of gravitational lensing degradation. The 1' *LISA* sky position error considered here is optimistic, although not implausible (see text). This choice allows for a straightforward scaling of the curves to larger positional errors. [See the electronic edition of the *Journal* for a color version of this figure.]

As we have discussed extensively, a GW measurement of a binary black hole merger determines the position on the sky to within some error $\delta\theta$ and the luminosity distance to within some error δD_L . By assuming a cosmological model, we can convert the measured luminosity distance and its error to any other desired cosmic distance measure. Denoting $\delta R(\delta D_L; \delta \text{cosmology})$ the error in comoving distance due to both the GW measurement error and the uncertainty in cosmological parameters, the number of galaxies that lie in the three-dimensional GW error cube is

$$N_{\text{error cube}} \simeq \frac{dN}{dR d\Omega} \delta\theta^2 \delta R(\delta D_L; \delta \text{cosmology}). \quad (8)$$

Figure 8 shows four realizations of $N_{\text{error cube}}$ as a function of GW event redshift, z . We have scaled to a near best-case pointing accuracy of $\delta\theta = 1'$; we emphasize that this is an optimistic, although not implausible, pointing error. From the tables it is apparent that about 5% of binaries with masses and redshifts in the *LISA* sweet spot have positional errors $\delta\theta \lesssim 5'$. As discussed toward the end of § 2.3, these results may be conservative; accounting for spin-induced precessional effects may allow certain degeneracies to be broken and improve *LISA*'s pointing accuracy (Vecchio 2004). (A fiducial pointing error of 1' also makes it very simple, by eq. [8], to scale to larger values.) The number of galaxies decreases significantly as uncertainties in cosmological parameters are reduced (as is to be expected by the time that *LISA* is operating). In Figure 8 we include the curve for the current state of errors on cosmological parameters, as well as for expected future, percent-level measurements. As discussed in § 4, gravitational lensing adds a further, insurmountable error to the GW measurement of δD_L . We approximate the lensing effects by a Gaussian in magnification, with variance given by $\sigma_{\text{lensing}} = 0.088z$ (Holz & Linder 2005). Although this expression is strictly appropriate only for high source statistics (as otherwise the lensing distribution is

non-Gaussian), it is a sufficiently good approximation for present purposes. With the inclusion of lensing errors in addition to cosmological parameter uncertainties, we find $\lesssim 10$ –20 potential counterpart galaxies in 1 arcmin² of the *LISA* error cube.

The number of candidate host objects for a galactic binary black hole merger is thus likely to be tractable. What remains is to find a way to identify which of the dozen or so candidate objects is in fact the host of the merger. Useful models exploring the signatures that may constitute “precursors” of the merger exist (Armitage & Natarajan 2002; Sillanpää et al. 1988; Lehto & Valtonen 1996); we are hopeful that such models can be extended to the ranges of mass and mass ratio of binaries that are likely to be observationally interesting to *LISA*.

The remnant of the merger is very likely to have an irregular morphology. In addition, the host galaxy may be in an active phase. Milosavljević & Phinney (2005) have recently developed a model for the late X-ray afterglow of a BBH merger. Kocsis et al. (2005) consider a scenario in which a merger remnant is associated with a quasar, and argue that in this case the paucity of quasars will make the identification of a counterpart significantly easier. In both of these models the merger remnant “lights up” and is thus relatively easy to identify in the positional error box. Even if the remnant does not light up, other information will help winnow the list of candidate host galaxies. For example, the GWs will measure the masses of the black holes with good accuracy; by using properties such as the $M_{\text{BH}}\text{-}\sigma$ relation we can estimate specific properties (e.g., kinematics, luminosity) that the host galaxy would be expected to have.

Observations of the *LISA* error boxes will no doubt be undertaken, regardless of the state of theoretical predictions. It is only by such direct observations that we will determine whether or not EM counterparts to BBH GW sources can be identified.

6. CONCLUSIONS

Because of their potential as an independent set of standard candles, BBH GW standard sirens can make an important contribution to programs to map the distance-redshift relation over a large span of redshift. Although the intrinsic precision of these candles is phenomenal, this precision will be limited in practice because of gravitational lensing. With lensing taken into account, the accuracy of the BBH GW candle is comparable to (or perhaps slightly better than) a Type Ia SN. It is sobering to note that we are already approaching the point at which lensing, rather than intrinsic dispersion, limits our ability to use standard candles.

We emphasize that the systematics of BBH events are entirely different from those of Type Ia SNe. As such, the greatest impact of BBH standard sirens may be to verify, and thereby increase our confidence in, other standard candles. The utility of these GW standard sirens depends on the identification of an electromagnetic counterpart, through which a redshift to the source can be determined. It is not unlikely that, at least for some of the best-observed systems, a counterpart will be found. If this is the case, the BBH GW source would become an exceptionally precise standard siren.

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