

Using Sampling Methods to Improve Binding Site Predictions

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Abstract. Currently the best algorithms for transcription factor binding site prediction are severely limited in accuracy. In previous work we combine random selection under-sampling into SMOTE over-sampling technique, working with several classification algorithms from machine learning field to integrate binding site predictions. In this paper, we improve the classification result with the aid of Tomek links as an either under-sampling or cleaning technique.

1 Introduction

In this paper, we address the problem of dealing with imbalanced data in the context of improving the identification of transcription factor binding sites on sequences of DNA using different sampling techniques. There are many different algorithms to search for binding sites [8] in current use. However, most of them produce a high rate of false positive predictions. This is problematic for practicing biologists who wish to validate these results - testing a prediction is costly. In [8], we attempt to reduce these false positive predictions using classification techniques taken from the field of machine learning.

One of difficulties in this work is due to the imbalanced dataset. The data has two classes labeled as either binding sites or non-binding sites, with about 93% being non-binding sites. In previous work, we combine random selection under-sampling and SMOTE over-sampling techniques. Here we extend this to use Tomek links as an under-sampling method.

2 Problem Domain

One of the most exciting and active areas of research in biology currently, is understanding how the exquisitely fine resolution of gene expression regulation is at the molecular level. Cis-regulatory DNA elements form the nodes connecting the genes in the regulatory networks, controlling many important biological phenomena, and as such are an essential focus of research in this field.

One set of regulatory interactions are those between a class of DNA-binding proteins known as transcription factors and short sequences of DNA which are

bound by the proteins by virtue of their three dimensional conformation. Transcription factors will bind to a number of different but related sequences. Unfortunately, this complicates the problem of predicting the cis-regulatory elements from out of the random background of the non-coding DNA sequences.

The current state of the art algorithms for transcription factor binding site prediction are, in spite of recent advances, still severely limited in accuracy. There is however good reason to believe that the predictions from these different classes of algorithms are complementary and could be integrated to improve the quality of predictions. In the work described here we take the results from the 12 aforementioned algorithms and combine them into 1 feature vector. More details about these 12 algorithms can be seen in [8]. We then investigate whether the integrated classification results of the algorithms can produce better classifications than any one algorithm alone (see Figure 1).

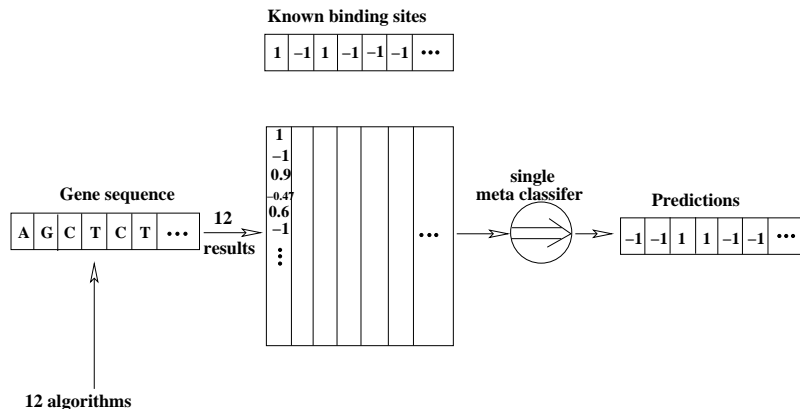


Fig. 1: The 12 algorithms give their own prediction for each sequence position and one such column is shown. The 12 results are combined as an input to a classifier.

3 Sampling Techniques for Imbalanced Dataset Learning

The data (a large sample of annotated yeast promoter sequences) consists of 68910 12-ary real vectors each with an associated binary label. In this work, we use the first 2/3 as a training set and the last 1/3 the test set. Amongst the data there are repeated vectors, some with the same label (repeated items) and some with different labels (inconsistent items). It is obviously unhelpful to have these repeated or inconsistent items in the training set, so they are removed. However there is no change in the case of the test set.

3.1 Sampling techniques

Since the dataset is imbalanced, the supervised classification algorithms will be expected to over predict the majority class, namely the non-binding site category. There are various methods of dealing with *imbalanced* data [5], classified as algorithm-based and data-based methods. So far we concentrate on the data-based method.

In [1], the authors evaluated 10 different samplings methods on 13 UCI imbalanced datasets using the C4.5 learning algorithm. They showed experimentally that in general over-sampling methods provide more accurate results than under-sampling methods. Moreover, they proposed that *Tomek links* [9] and *Wilson's Edited Nearest Neighbour Rule* (ENN) [10] can be used to clean up noisy data after over-sampling with SMOTE [3].

- Tomek links

Tomek links are links between 2 points (I_i, I_j) from different classes that are closer together than any other pair from the 2 classes involving I_i or I_j . The distance between the two patterns is $d(I_i, I_j)$. If for any other patterns I_l in the dataset $d(I_i, I_j)$ satisfies $d(I_i, I_j) < d(I_i, I_l)$ or $d(I_i, I_j) < d(I_j, I_l)$, then the pair (I_i, I_j) is called a Tomek link . When Tomek links are used as an under-sampling method, only patterns from the majority class are removed. However, when used for removing noisy data, items may be removed from both classes.

- ENN

ENN removes a pattern if the majority of its K nearest neighbours are not in its class. here we use $K = 3$.

- SMOTE

The aim of the SMOTE method is to synthetise new patterns by applying majority voting to each of the attributes of the K -nearest neighbours of each patterns in the minority class.

In [8] we apply Random selection (R) under-sampling for the majority class (negative examples) and SMOTE (S) over-sampling for the minority class (positive examples), denoted by $R-S$. Here our aim is to improve classification results using more competitive sampling techniques on the training set. We apply a new combination of Tomek links and SMOTE for under- and over-samplings, respectively, denoted by $T-S$. In order to investigate whether points located near the decision boundary have a negative effect on training, or represent noise, we additionally used Tomek links and ENN to remove data from both classes after sampling, denoted by $T-S(Tomek)$, $R-S(Tomek)$, $T-S(ENN)$ and $R-S(ENN)$.

Since the data is a mixed set of binary and continuous features, we apply *Heterogeneous Value Difference Metric* (HVDM) [11] for calculating distances. The actual ratio of minority to majority class is determined by the under-sampling rate of the majority class. According to our previous experience, we set the final ratio to a half, which has previously been shown to work well [8].

4 Classifier Performance

To evaluate classifiers used in this work, we apply a range of standard reference metrics defined in Table 1, where N is the number of true negative samples; FP is false positive samples; FN is false negative samples; TP is true positive samples.

Table 1: Definitions of several common performance metrics

$$\begin{aligned} \text{Recall} &= \frac{\text{TP}}{(\text{TP} + \text{FN})} , & \text{Precision} &= \frac{\text{TP}}{(\text{TP} + \text{FP})} , \\ \text{F-Score} &= \frac{2 \cdot \text{Recall} \cdot \text{Precision}}{\text{Recall} + \text{Precision}} , & \text{FP_Rate} &= \frac{\text{FP}}{\text{FP} + \text{TN}} , \\ \text{CC} &= \frac{\text{TP} \cdot \text{TN} - \text{FN} \cdot \text{FP}}{\sqrt{(\text{TP} + \text{FN})(\text{TN} + \text{FP})(\text{TP} + \text{FP})(\text{TN} + \text{FN})}} . \end{aligned}$$

5 Experiments and Results

5.1 Experiments

We test these sampling methods on three learning algorithms: Single Layer Networks (SLN) [2], the Support Vector Machine (SVM) [7] and Rules Sets derived from C4.5 decision trees [6]. The SVM experiments were completed using LIBSVM¹. The C4.5-Rules experiments were undertaken using C4.5 software from [6]. C4.5-Rules is a companion program to C4.5. It creates rules sets by post-processing decision trees generated using the C4.5 algorithm first. The SLN was implemented using the NETLAB toolbox². All user-specified parameters are chosen using cross-validations. These results are compared with the best base algorithm, which is the one with the highest F-Score among the 12 base algorithms, majority voting and weighted majority voting (see [8] for further details).

5.2 Results

Table 2 shows that almost all F-Scores with R-S(ENN) and R-S(Tomek) are improved when compared with each corresponding classifier on samplings from R-S. The SVM with R-S(Tomek) samplings gives the overall best F-Score and CC value, and also decreases the FP-Rate compared with simple R-S samplings. In addition, using Tomek links as a cleaning method decreases the FP-Rate compared to no cleaning. McNemar's test [4] is taken to compare the classification

¹

<http://www.csie.ntu.edu.tw/~cjlin/libsvm>

²

<http://www.ncrg.aston.ac.uk/netlab/>

Table 2: Performance metrics reported for the unfiltered possible binding sites with inputs sampled using random selection for under-sampling and SMOTE for over-sampling.

Input	Classifier	Recall	Precision	F-Score	FP_Rate	CC
No smapling	best Alg.	0.400	0.222	0.285	0.106	0.226
	MV	0.151	0.298	0.200	0.027	0.171
	WMV	0.244	0.374	0.295	0.031	0.260
R-S	SLN	0.248	0.365	0.295	0.033	0.258
	SVM	0.305	0.326	0.315	0.048	0.266
	C4.5-Rules	0.274	0.287	0.280	0.052	0.227
R-S(ENN)	SLN	0.298	0.340	0.318	0.044	0.270
	SVM	0.318	0.323	0.321	0.051	0.270
	C4.5-Rules	0.287	0.306	0.296	0.049	0.245
R-S(Tomek)	SLN	0.253	0.389	0.306	0.030	0.273
	SVM	0.283	0.383	0.325	0.034	0.286
	C4.5-Rules	0.224	0.326	0.265	0.035	0.225

results of R-S with R-S(Tomek) on the SVM. The P-value is less than 0.0001. The difference is considered to be extremely statistically significant.

Table 3 shows that SLN and C4.5-Rules with T-S(ENN) and T-S(Tomek) samplings are better than their corresponding classifier with T-S samplings. But the SVM performs better on T-S samplings considering all of F-Score, FP-Rate and the CC value.

It can be seen from Tables 2 and 3 that the best results of F-score and CC are all obtained from the SVM. Overall, R-S(Tomek) and T-S working with the SVM performs best considering F-Score, FP-Rate and the CC value together.

6 Conclusions

The first point to be made is that the Tomek links method improves performance when used for under-sampling of the majority class with the SLN and SVM classifiers, without considering to clean up samplings. The second conclusion is that the Tomek links method is also useful when used for removing noisy data, as the SMOTE is applied for over-sampling and random selection for under-sampling with the SLN and SVM classifiers.

References

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Table 3: Performance metrics reported for the unfiltered possible binding sites with inputs sampled using Tomek link for under-sampling and SMOTE for over-sampling.

Input	Classifier	Recall	Precision	F-Score	FP_Rate	CC
No smapling	best Alg.	0.400	0.222	0.285	0.106	0.226
	MV	0.151	0.298	0.200	0.027	0.171
	WMV	0.244	0.374	0.295	0.031	0.260
T-S	SLN	0.250	0.387	0.304	0.030	0.270
	SVM	0.294	0.369	0.327	0.038	0.285
	C4.5-Rules	0.240	0.238	0.238	0.059	0.179
T-S(ENN)	SLN	0.307	0.348	0.326	0.044	0.280
	SVM	0.332	0.303	0.317	0.058	0.263
	C4.5-Rules	0.278	0.254	0.265	0.062	0.207
T-S(Tomek)	SLN	0.265	0.397	0.318	0.030	0.284
	SVM	0.292	0.342	0.315	0.043	0.269
	C4.5-Rules	0.265	0.251	0.258	0.060	0.200

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