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# Variance Function Estimation in Regression: The Effect of Estimating the Mean 

Technical Report \#4

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# Variance Function Estimation in Regression: <br> The Effect of Estimating the Mean 

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SUMMARY
We consider estimation of a variance function $g$ in regression problems. Such estimation requires simultaneous estimation of the mean function $f$. We obtain sharp results on the extent to which the smoothness of $f$ influences best rates of convergence for estimating $g$. For example, in nonparametric regression with two derivatives on $g$, "classical" rates of convergence are possible if and only if the unknown' $f$ satisfies a Lipschitz condition of order $\frac{1}{3}$ or more. If a parametric model is known for $g$, then $g$ may be estimated $n^{\frac{1}{2}}$ consistently if and only if $f$ is Lipschitz of order $\frac{1}{2}$ or more. Optimal rates of convergence are attained by kernel estimators.

Keywords: Heteroscedasticity; Nonparametric Regression; Rates of Convergence; Variance Functions.

## 1. INTRODUCTION

Consider a heteroscedastic regression problem of the form

$$
\begin{equation*}
Y_{i}=f\left(x_{i}\right)+g\left(x_{i}\right)^{\frac{1}{2} \epsilon_{i}}, \quad 1 \leq i \leq n, \tag{1.1}
\end{equation*}
$$

where the design variables $x_{i}$ may be either regularly or randomly spaced, and where the $\epsilon_{i}$ 's are independent with zero mean and unit variance. Estimation of the variance function $g$ is important in many contexts. Besides the classic need to estimate variance so as to compute weighted least squares estimates of the mean function $f$, variance function estimates are needed in quality control (Box \& Ramirez, 1987); immunoassay (Butt, 1984); prediction, where knowledge of $g$ is required to supply confidence intervals for $f$ (Carroll, 1987); calibration (Watters, Spiegelman \& Carroll, 1987); and the estimation of detection limits (Carroll, Davidson \& Smith, 1987). These applications are discussed in detail by Carroll \& Ruppert (1988). In the present paper we provide a concise description of the effect which not knowing $f$ has on estimation of $g$.

The results are curious and unexpected. For example, if $f$ is not known parametrically but has at least half a derivative (i.e. satisfies a Lipschitz condition of order $\frac{1}{2}$ or more), then $g$ can be estimated with an accuracy which would be optimal if $f$ were completely known. This result applies to problems where $g$ is known parametrically, and also to problems where $g$ must be estimated nonparametrically. However, the result fails if $f$ is so rough that it does not have half a derivative. There, the roughness of $f$ completely determines the convergence rate if $g$ has known parametric form, and influences the rate if $g$ is known nonparametrically. These remarks apply to optimal estimators of $g$, as well as to kernel estimators. We show that kernel estimators achieve best possible rates of convergence.

In more detail, the fastest achievable $L^{2}$ rate of convergence is

$$
\begin{equation*}
\max \left(n^{-2 v_{2}\left(\left(2 v_{2}+1\right)\right.}, n^{i i_{1},\left(2 \nu_{2}: 1\right)}\right) \tag{1.2}
\end{equation*}
$$

if $f$ has $\nu_{1}$ derivatives and $g$ has $\nu_{2}$ derivatives. If $\nu_{1} \geq \frac{1}{2}$, this equals $n^{-2 \nu_{2} /\left(2 \nu_{2}+1\right)}$ and so does not depend on $\nu_{1}$. Rates in the case where $g$ is known parametrically may be obtained by taking $\nu_{2}=\infty$ in (1.2), in which event (1.2) becomes $\max \left(n^{-1}, n^{-4 \nu_{1} /\left(2 \nu_{1}+1\right)}\right)$. The latter equals $n^{-1}$ if $\nu_{1} \geq \frac{1}{2}$.

Section 2 presents these conclusions in detail for the case where design points $x_{i}$ in (1.1) are regularly spaced. Section 3 outlines analogous results for the case of random designs.

## 2. REGULAR DESIGN

2.1 Introduction. In this section we take the model to be

$$
\begin{equation*}
Y_{i}=f(i / n)+g(i / n)^{\frac{1}{2}} \epsilon_{i}, \quad 1 \leq i \leq n, \tag{2.1}
\end{equation*}
$$

where $f$ and $g$ are bounded functions on the interval $[0,1], g \geq 0$, and $\epsilon_{1}, \epsilon_{2}, \ldots$ are independent random variables with zero mean, unit variance and uniformly bounded fourth moment. Given $\nu>0$, write $\langle\nu\rangle$ for the largest integer strictly less than $\nu$. We say that a function $a$, such as $f$ or $g$, is $\nu$-smooth if (i) derivatives $a^{(0)}, \ldots, a^{((\nu))}$ exist and are bounded on $[0,1]$; and (ii) $a^{((\nu\rangle)}$ satisfies a Lipschitz condition of order $\nu-\langle\nu\rangle$ on $[0,1]$ :

$$
\left|a^{((\nu))}(x)-a^{((\nu))}(y)\right| \leq C|x-y|^{\nu-\langle\nu\rangle}, \quad \text { all } x, y \in[0,1] .
$$

A function with $k$ bounded derivatives on $[0,1]$ is $k$-smooth.
In subsection 2.2 we show that if $f$ is $\nu_{1}$-smooth and $g$ is $\nu_{2}$-smooth, then kerneltype estimators of $g$ converge in mean square at rate $\max \left(n^{-2 \nu_{2} /\left(2 \nu_{2}+1\right)}, n^{-4 \nu_{1} /\left(2 \nu_{1}+1\right)}\right)$. Subsection 2.3 demonstrates that if the errors $\epsilon_{i}$ are Gaussian then this rate is optimal, in the sense that no estimator can converge to $g$ more rapidly in mean square. Subsection 2.4 treats the case $\nu_{2}=\infty$, which amounts to postulating a parametric model for $g$.
2.2 Kernel-type estimators. We begin by defining an analogue of a kernel sequence for regular designs. Suppose $0<h \leq 1$, and $m \geq 0$ is an integer. Let $c_{k}=c_{k}(h, m)$,
$-\infty<k<\infty$, be constants satisfying

$$
\begin{align*}
& \left|c_{k}\right| \leq C h, c_{k}=0 \text { for }|k| \geq C h^{-1}, \quad \Sigma_{k} c_{k}=1 \\
& \quad \text { and } \Sigma_{k} k^{i} c_{k}=0 \text { for } 1 \leq i \leq m, \tag{2.2}
\end{align*}
$$

where the constant $C$ does not depend on $h$. Then $\Sigma_{k}|k|^{\alpha}\left|c_{k}\right| \leq 2 C^{\alpha+2} h^{-\alpha}$ for each $\alpha \geq 0$, and $\Sigma_{k} c_{k}^{2} \leq 2 C^{3} h$. The $c_{k}$ 's may be constructed starting from a smooth function $K$, vanishing outside the interval $[-1,1]$ and satisfying $\int K(x) d x=1, \int x^{i} K(x) d x=0$ for $1 \leq i \leq m$. Minor adjustments to $K$, giving a new function $K_{1}$ say, ensure that at least for small $h, c_{k}=h K_{1}(h k)$ yields an appropriate sequence of constants. For example, if $m=0$ or 1 , take $K$ to be a bounded, continuous density, symmetric about the origin and vanishing outside $[-1,1]$. Define $\kappa(h)$ by $\kappa(h)^{-1} \equiv \Sigma_{k} h K(h k)$, so that $\kappa(h) \rightarrow 1$ as $h \rightarrow 0$. Then $c_{k} \equiv \kappa(h) h K^{\prime}(h k)$ satisfies pur conditions on $c_{k}$.

Next we define an estimator of $f$. Suppose the data $Y_{i}, 1 \leq i \leq n$, are generated by model (2.1). If the mean function $f$ is $\nu_{1}$-smooth, choose a sequence of constants $a_{k} \equiv c_{k}\left(h_{1},\left\langle\nu_{1}\right\rangle\right)$ satisfying condition (2.2), and put

$$
\begin{equation*}
\hat{f}(i / n) \equiv \Sigma_{k} a_{k} Y_{i+k}, \quad 0 \leq i \leq n \tag{2.3}
\end{equation*}
$$

where $Y_{j}$ is defined to be zero if $j<1$ or $j>n$. Use linear interpolation on $\hat{f}(i / n)$ to construct $\hat{f}(x)$ for general $x \in[0,1]$. We show in Appendix (i) that if $f$ is $\nu_{1}$-smooth and $g$ is bounded, and if $h_{1} \rightarrow 0$ and $n h_{1} \rightarrow \infty$ as $n \rightarrow \infty$, then for each $0<\delta<\frac{1}{2}$,

$$
\begin{align*}
\sup _{\delta \leq x \leq 1-\delta}|E \hat{f}(x)-f(x)| & =O\left\{\left(n h_{1}\right)^{-\nu_{1}}\right\}  \tag{2.4}\\
\sup _{\delta \leq x \leq 1-6} \operatorname{var}\{\hat{f}(x)\} & =O\left(h_{1}\right) \tag{2.5}
\end{align*}
$$

Therefore the mean squared error of $\hat{f}$ satisfies

$$
\begin{equation*}
\sup _{\delta \leq x \leq 1-\delta} E\{\hat{f}(x)-f(x)\}^{2}=O\left\{h_{1}+\left(n h_{1}\right)^{-2 \nu_{1}}\right\} \tag{2.6}
\end{equation*}
$$

which is minimized at $O\left(n^{-2 \nu_{1} /\left(2 \nu_{1}+1\right)}\right)$ by choosing $h_{1}$ to be of size $n^{-2 \nu_{1} /\left(2 \nu_{1}+1\right)}$.

Now we construct estimators of $g$. The estimated residuals are

$$
\hat{r}_{i} \equiv Y_{i}-\hat{f}(i / n), \quad 1 \leq i \leq n
$$

Our hope is that $\hat{r}_{i}$ will be close to the "true" residual, $r_{i} \equiv Y_{i}-f(i / n)=g(i / n)^{\frac{1}{\frac{1}{2}} \epsilon_{i}}$. (Define $r_{i}=\hat{r}_{i}=0$ if $i<1$ or $i>n$.) Of course, $r_{i}^{2}$ admits the model type (2.1):

$$
\begin{equation*}
r_{i}^{2}=g(i / n)+g(i / n) \eta_{i}, \quad 1 \leq i \leq n, \tag{2.7}
\end{equation*}
$$

where $\eta_{i}^{2} \equiv \epsilon_{i}^{2}-1$ are independent and identically distributed with zero mean. If the $r_{i}$ 's were observable, we could estimate $g$ from $\left\{r_{i}^{2}\right\}$ in exactly the same way that we estimated $f$ from $\left\{Y_{i}\right\}$ : assuming $g$ to be $\nu_{2}$-smooth, choose a sequence of constants $b_{k} \equiv c_{k}\left(h_{2},\left\langle\nu_{2}\right\rangle\right)$ satisfying (2.2), and put

$$
\tilde{g}(i / n) \equiv \Sigma_{k} b_{k} r_{i+k}^{2}, \quad 1 \leq i \leq n
$$

Construct $\bar{g}(x)$ by linear interpolation. We see directly from (2.6) that if $h_{2} \rightarrow 0$ and $n h_{2} \rightarrow \infty$ then

$$
\begin{equation*}
\sup _{\delta \leq x \leq 1-\delta} E\{\tilde{g}(x)-g(x)\}^{2}=O\left\{h_{2}+\left(n h_{2}\right)^{-2 \nu_{2}}\right\} \tag{2.8}
\end{equation*}
$$

Of course, $\tilde{g}$ is not a realistic estimator, since the true residuals are not observable. If we replace true residuals by their estimates we obtain the practical estimator,

$$
\begin{equation*}
\hat{g}(i / n) \equiv \Sigma_{k} b_{k} \hat{r}_{i+k}^{2}, \quad 1 \leq i \leq n \tag{2.9}
\end{equation*}
$$

Construct $\hat{g}(x)$ by linear interpolation. We show in Appendix (ii) that for each $0<\delta<\frac{1}{2}$,

$$
\begin{equation*}
\sup _{\delta \leq x \leq 1-\delta} E\{\hat{g}(x)-g(x)\}^{2}=O\left[\left\{h_{2}+\left(n h_{2}\right)^{-2 \nu_{2}}\right\}+\left\{h_{1}+\left(n h_{1}\right)^{-2 \nu_{1}}\right\}^{2}\right] . \tag{2.10}
\end{equation*}
$$

The second term on the right-hand side of (2.10) distinguishes that expression from (2.8), and is a consequence of our imperfect knowledge about $f$. Notice that it is the square of the right-hand side of (2.6).

To optimize the rate at which the right-hand side of (2.10) converges to zero, choose $h_{i}$ of size $n^{-2 \nu_{i} /\left(2 \nu_{i}+1\right)}$ for $i=1$ and 2 . Then

$$
\begin{equation*}
\sup _{\delta \leq x \leq 1-\delta} E\{\hat{g}(x)-g(x)\}^{2}=O\left\{\max \left(n^{-2 \nu_{2} /\left(2 \nu_{2}+1\right)}, n^{-4 \nu_{i} /\left(2 \nu_{1}+1\right)}\right)\right\} \tag{2.11}
\end{equation*}
$$

A necessary and sufficient condition for the term in $\nu_{2}$ here to dominate, is $4 \nu_{1} /\left(2 \nu_{1}+1\right) \geq$ $2 \nu_{2} /\left(2 \nu_{2}+1\right)$, or equivalently,

$$
\begin{equation*}
\nu_{1} \geq \nu_{2} /\left\{2\left(\nu_{2}+1\right)\right\} \tag{2.12}
\end{equation*}
$$

Should this condition fail, the rate of convergence of $\bar{g}$ to $g$ is limited by smoothness (or more correctly, lack of smoothness) of $f$, not by smoothness of $g$. On the other hand, if (2.12) holds then the rate of convergence of $\hat{g}$ to $g$ is determined by smoothness of $g$. Note that $\nu_{2} /\left\{2\left(\nu_{2}+1\right)\right\}<\frac{1}{2}$ for all $\nu_{2}>0$, and so condition (2.12) is assured if $\nu_{1} \geq \frac{1}{2}$ - that is, if $f$ has at least "half a derivative".
2.3 Optimal rates of convergence. Let $\mathcal{C}(\nu, B)$ denoted the class of $\nu$-smooth functions $a:[0,1] \rightarrow \mathbb{R}$, such that $\sup \left|a^{(j)}\right| \leq B$ for $0 \leq j \leq\langle\nu\rangle$ and

$$
\left|a^{((\nu))}(x)-a^{((\nu))}(y)\right| \leq B|x-y|^{\nu-\langle\nu)}, \quad \text { all } x, y \in[0,1]
$$

Write $\mathcal{C}_{+}(\nu, B)$ for the set of $a \in \mathcal{C}(\nu, B)$ with $a \geq 0$. We showed in Subsection 2.1 that if $f \in \mathcal{C}\left(\nu_{1}, B\right)$ and $g \in \mathcal{C}_{+}\left(\nu_{2}, B\right)$, then we may construct a nonparametric estimator $\hat{g}$ of $g$ such that

$$
\sup _{\delta \leq x \leq 1-\delta} E\{\hat{g}(x)-g(x)\}^{2}=O\left\{\max \left(n^{-2 \nu_{2} /\left(2 \nu_{2}+1\right)}, n^{-4 \nu_{1} /\left(2 \nu_{1}+1\right)}\right)\right\}
$$

for each $\delta \in\left(0, \frac{1}{2}\right)$. See (2.11). It is a simple matter to sharpen our proof of this result so that it applies uniformly in $f$ and $g$ :

$$
\sup _{f \in \mathcal{C}\left(\nu_{1}, B\right), g \in \mathcal{C}_{+}\left(\nu_{2}, B\right)} \sup _{\delta \leq x \leq 1-\delta} E_{f, g}\{\hat{g}(x)-g(x)\}^{2}=O\left\{\max \left(n^{-2 \nu_{2} /\left(2 \nu_{2}+1\right)}, n^{-4 \nu_{1} /\left(2 \nu_{1}+1\right)}\right)\right\}
$$

We claim that this rate of convergence is best possible, in the following sense. If $\hat{g}$ is any nonparametric estimator of $g$, if $0<x_{0}<1$, and if the errors $\epsilon_{i}$ are Gaussian, then for some $C>0$ and all sufficiently large $n$,

$$
\begin{equation*}
M \equiv \sup _{f \in C\left(\nu_{1}, B\right), g \in C_{+}\left(\nu_{2}, B\right)} E_{f, g}\left\{\hat{g}\left(x_{0}\right)-g\left(x_{0}\right)\right\}^{2} \geq C \max \left(n^{-2 \nu_{7} /\left(2 \nu_{2}+1\right)}, n^{-4 \nu_{1} /\left(2 \nu_{2}+1\right)}\right) \tag{2.13}
\end{equation*}
$$

This statement is a combination of two results, declaring that

$$
\begin{equation*}
M_{n} \geq C n^{-2 \nu_{2} /\left(2 \nu_{1}+1\right)} \tag{2.14}
\end{equation*}
$$

and

$$
\begin{equation*}
M_{n} \geq C n^{-4 \nu_{1} /\left(2 \nu_{1}+1\right)} \tag{2.15}
\end{equation*}
$$

respectively. The first of these inequalities has a relatively simple proof, which we now outline. Take $f \equiv 0$, so that we observe the "true" residuals $r_{i} \equiv g(i / n)^{\frac{1}{2}} \epsilon_{i}$. The sequence $r_{1}^{2}, \ldots, r_{n}^{2}$ is sufficient tor $g$. Therefore the problem is that of estimating $g$ under model (2.7). Techniques described by Stone (1980) are easily modified to produce the inequality

$$
\sup _{g \in C_{+}\left(\nu_{2}, B\right)} E_{g}\left\{\hat{g}\left(x_{0}\right)-g\left(x_{0}\right)\right\}^{2} \geq C n^{-2 \nu_{2} /\left(2 \nu_{2}+1\right)},
$$

where $\hat{g}$ is any nonparametric estimator of $g$ based on $r_{1}^{2}, \ldots, r_{n}^{2}$, and where $f \equiv 0$. This gives (2.14). Appendix (iii) presents a proof of (2.15).
2.4 Parametric model for variance. In some circumstances it is appropriate to consider a parametric model for $g$, such as $g(x) \equiv \exp (c x+d)$. As far as rates of convergence go, this amounts to taking $\nu_{2}=\infty$ in the preceding work, as we now relate.

Suppose $g$ has known parametric form. If $f$ were available we could compute the "true" residuals $r_{i} \equiv Y_{i}-f(i / n)$, and from them compute an estimator $\tilde{g}$ satisfying $E\{\tilde{g}(x)-g(x)\}^{2}=O\left(n^{-1}\right)$. More practically, assume $f$ is $\nu_{1}$-smooth and compute our kernel-type estimator $\hat{f}$, defined at (2.3). Calculate the estimated residuals $\hat{r}_{i} \equiv Y_{i}-\hat{f}(i / n)$. Since the constants $a_{k}$ in (2.3) vanish for $|k| \geq C h_{1}^{-1}$ (see (2.2)), we avoid "edge effects"
by using only those $\hat{r}_{i}$ 's with $C h_{1}^{-1} \leq i \leq n-C i_{1}^{-1}$. Modify $\hat{g}$ by (i) including only these indices $i$, and (ii) replacing $r_{i}$ by $\hat{r}_{i}$. Call the new estimator $\hat{g}$. Then for each $0<\delta<\frac{1}{2}$,

$$
\begin{equation*}
\sup _{\delta \leq x \leq 1-6} E\{\hat{g}(x)-g(x)\}^{2}=O\left[n^{-1}+\left\{h_{1}+\left(n h_{1}\right)^{-2 \downarrow} \cdot\right\}^{2}\right] . \tag{2.16}
\end{equation*}
$$

This is an analogue of (2.10). To optimize the rate of convergence of the right-hand side, choose $h_{1}$ to be of size $n^{-2 \nu_{1} /\left(2 \nu_{1}+1\right)}$, obtaining

$$
\begin{equation*}
\sup _{\delta \leq x \leq 1-\delta} E\{\hat{g}(x)-g(x)\}^{2}=O\left\{\max \left(n^{-1}, n^{-4 \nu_{1} /\left(2 \nu_{1}+1\right)}\right)\right\} \tag{2.17}
\end{equation*}
$$

This is just (2.11) with $\nu_{2}=\infty$.
A necessary and sufficient condition for the $n^{-1}$ term to dominate the right-hand side of (2.17), is $\nu_{1} \geq \frac{1}{2}$; this is just (2.12) with $\nu_{2}=\infty$. If $\nu_{1}<\frac{1}{2}$, or equivalently if $f$ has "less than half a derivative", then estimation of even a parametric $g$ is a nonparametric problem with nonparametric rates of convergence. When $\nu_{1}=\frac{1}{2}, E\{\hat{g}(x)-g(x)\}^{2}=O\left(n^{-1}\right)$, although constants $C_{1}$ and $C_{2}$ in asymptotic formulae such as

$$
E\{\tilde{g}(x)-g(x)\}^{2} \sim C_{1}(x) n^{-1}, \quad E\{\hat{g}(x)-g(x)\}^{2} \sim C_{2}(x) n^{-1}
$$

can differ. But when $\nu_{1}>\frac{1}{2}$, our imperfect knowledge about $f$ vanishes from the asymptotics, and

$$
\begin{equation*}
E\{\tilde{g}(x)-g(x)\}^{2}=\{1+o(1)\} E\{\hat{g}(x)-g(x)\}^{2}=O\left(n^{-1}\right) \tag{2.18}
\end{equation*}
$$

as $n \rightarrow \infty$. (This result has an analogue in the nonparametric case, when $\nu_{1}>\nu_{2} /\left\{2\left(\nu_{2}+\right.\right.$ 1) \}.)

It is tedious to verify all these formulae in the general case, owing to the wide variety of possible parametric models and associated estimators. We treat only the case $g=g(x) \equiv$ $\sigma^{2}$ (constant) on $[0,1]$. Here, $\tilde{g} \equiv n^{-1} \Sigma_{1 \leq i \leq n} r_{i}^{2}$ and, with $m$ denoting the smallest integer greater than $\mathrm{Ch}_{1}^{-1}$,

$$
\begin{aligned}
\hat{g} \equiv(n-2 m)^{-1} \sum_{i=m}^{n-m+1} \hat{r}_{i}^{2}= & (n-2 m)^{-1} \cdot \sum_{i=m}^{n-m+1} r_{i}^{2}+(n-2 m)^{-1} \sum_{i=m}^{n-m+1}\{\hat{f}(i / n) \\
& -f(i / n)\}^{2}+2 g^{\frac{1}{2}}(n-2 m)^{-1} \sum_{i=m}^{n-m+1} \epsilon_{i}\{f(i / n)-\hat{f}(i / n)\}
\end{aligned}
$$

Writing $B_{i} \equiv E \hat{f}(i / n)-f(i / n)$ for bias, and $\tilde{g}_{m} \equiv(n-2 m)^{-1} \Sigma_{m \leq i \leq n-m+1} r_{i}^{2}$, we obtain

$$
\begin{aligned}
\left(\bar{g}-\bar{g}_{m}\right)^{2} \leq & C n^{-2}\left[\left(\sum_{i=m}^{n-m+1} B_{i}^{2}\right)^{2}+\left\{\sum_{i=m}^{n-m+1}\left(\Sigma_{k} a_{k} \epsilon_{i+k}\right)^{2}\right\}^{2}\right. \\
& \left.+\left(\sum_{i=m}^{n-m+1} B_{i} \epsilon_{i}\right)^{2}+\left\{\sum_{i=m}^{n-m+1} \epsilon_{i}\left(\Sigma_{k} a_{k} \epsilon_{i+k}\right)\right\}^{2}\right]
\end{aligned}
$$

Now, $\left|B_{i}\right|=O\left\{\left(n h_{1}\right)^{-2 \nu_{1}}\right\}$ uniformly in $m \leq i \leq n-m+1$, and so

$$
E\left(\hat{g}-\tilde{g}_{m}\right)^{2}=O\left[\left\{h_{1}+\left(n h_{1}\right)^{-2 \nu_{1}}\right\}^{2}\right]+o\left(n^{-1}\right)
$$

Results (2.16)-(2.18) follow from this formula.
The lower bound (2.13), this time with $\nu_{2}=\infty$, continues to hold in parametric circumstances such as the one above. In fact, our proof of (2.13) in Appendix (iii) is applicable to the parametric case.

## 3. RANDOM DESIGN

We now consider kernel regression estimators in the random design case. Let $h$ be the density of the design. Typically, when $h$ is known it is relatively easy to show that the $L^{2}$ rate of convergence satisfies (1.2). We concentrate instead on the case of an unknown design density. Under (2.12), we show that one can estimate the variance function $g$ as accurately as though $f$ were known.

Observe independent pairs ( $Y_{i}, x_{i}$ ), $1 \leq i \leq n$. The $x_{i}$ 's have common density $h$, and given $\left\{x_{i}\right\}, Y_{i}=f\left(x_{i}\right)+g\left(x_{i}\right)^{\frac{1}{2}} \epsilon_{i}$. The $\epsilon_{i}$ 's are assumed to have mean zero, variance one, and uniformly bounded fourth moments. Given $\nu>0$, define $\langle\nu\rangle$ and " $\nu$-smoothness" as in Subsection 2.1. Assume $f$ is $\nu_{1}$-smooth and $g$ is $\nu_{2}$-smooth, where $\nu_{1}>0$ and $\nu_{2}>0$. Suppose that, uniformly in a neighborhood of $x_{0}$, the density $d$ of $x$ is $\left\{\max \left(\nu_{1}, \nu_{2}\right)\right\}$ smooth and bounded away from zero and infinity. For $j=1,2$, let $K_{j}$ be continuous functions with support $[-1,1]$, integrating to one, uniformly Lipschitz continuous of order one, and with $i$ 'th moment equal to zero for $1 \leq i \leq\left\langle\nu_{j}\right\rangle$. Let $h_{j} \equiv n^{-1 /\left(2 \nu_{j}+1\right)}$ for $j=1,2$.

Define

$$
\hat{d}_{j}(x) \equiv\left(n h_{j}\right)^{-1} \sum_{k=1}^{n} K_{j}\left\{\left(x_{k}-x\right) / h_{j}\right\}, \quad \hat{d}_{1 i}(x) \equiv\left(n h_{1}\right)^{-1} \sum_{k \neq i} K_{1}\left\{\left(x_{k}-x\right) / h_{1}\right\} .
$$

A kernel regression estimator of $f$ is

$$
\hat{f}_{i}(x) \equiv\left(n h_{1}\right)^{-1} \sum_{k \neq i} Y_{k} K\left\{\left(x_{k}-x\right) / h_{1}\right\} / \hat{d}_{1 i}(x)
$$

If the mean function $f$ were known, a kernel regression estimator of $g$ would be

$$
\tilde{g}(x) \equiv\left(n h_{2}\right)^{-1} \sum_{i=1}^{n}\left\{Y_{i}-f\left(x_{i}\right)\right\}^{2} K_{2}\left\{\left(x_{i}-x\right) / h_{2}\right\} / \hat{d}_{2}(x)
$$

If $f$ is unknown, the natural analogue of $\tilde{g}$ is

$$
\hat{g}(x) \equiv\left(n h_{2}\right)^{-1} \sum_{i=1}^{n}\left\{Y_{i}-\hat{f}_{i}\left(x_{i}\right)\right\}^{2} K_{2}\left\{\left(x_{i}-x\right) / h_{2}\right\} / \hat{d}_{2}(x)
$$

Classical results on kernel regression function estimation may be used to prove that $\left|\tilde{g}\left(x_{0}\right)-g\left(x_{0}\right)\right|=O_{p}\left(n^{-\nu_{2} /\left(2 \nu_{2}+1\right)}\right)$; this is the analogue of (2.8) for an optimal choice of window size $h_{2}$. In analogy with (2.11),

$$
\begin{equation*}
\left|\hat{g}\left(x_{0}\right)-g\left(x_{0}\right)\right|=O_{p}\left\{\max \left(n^{-\nu_{2} /\left(2 \nu_{2}+1\right)}, n^{-2 \nu_{1} /\left(2 \nu_{1}+1\right)}\right)\right\} . \tag{3.1}
\end{equation*}
$$

As in Section 2, a necessary and sufficient condition for the term in $\nu_{2}$ here to dominate, is $\nu_{1} \geq \nu_{2} /\left\{2\left(\nu_{2}+1\right)\right\}$. If this inequality is strict then $\hat{g}$ is asymptotically equivalent to the "ideal" estimator $\tilde{g}$, in the sense that

$$
\begin{equation*}
\left|\hat{g}\left(x_{0}\right)-\tilde{g}\left(x_{0}\right)\right|=o_{p}\left(n^{-\nu_{2} /\left(2 \nu_{2}+1\right)}\right) . \tag{3.2}
\end{equation*}
$$

To prove (3.2), first observe from Stute (1984) that

$$
\sup _{|x--0| \leq c}\left\{\left|\hat{d}_{j}(x)-d(x)\right|\right\}=O_{p}\left(n^{-\nu_{j} /\left(2 \nu_{j}+1\right)} \log n\right)
$$

for some $c>0$. From this it follows that

$$
\begin{equation*}
\sup _{\left|x-x_{0}\right| \leq c^{1 \leq i \leq n}} \max _{1 i}\left|\hat{d}_{1 i}(x)-d(x)\right|=O_{p}\left(n^{-\nu_{1} /\left(2 \nu_{1}+1\right)} \log n\right) . \tag{3.3}
\end{equation*}
$$

Therefore to prove (3.2) it suffices to show that

$$
\begin{equation*}
\max \left(\left|A_{n}\right|,\left|B_{n}\right|\right)=o_{p}\left(n^{-\nu_{2} /\left(2 \nu_{2}+1\right)}\right), \tag{3.4}
\end{equation*}
$$

where

$$
\begin{aligned}
& A_{n} \equiv\left(n h_{2}\right)^{-1} \sum_{i=1}^{n}\left\{\hat{f}_{i}\left(x_{i}\right)-f\left(x_{i}\right)\right\}^{2} K_{2}\left\{\left(x_{i}-x_{0}\right) / h_{2}\right\}, \\
& B_{n} \equiv\left(n h_{2}\right)^{-1} \sum_{i=1}^{n} g\left(x_{i}\right)^{\frac{1}{2}} \epsilon_{i}\left\{\hat{f}_{i}\left(x_{i}\right)-f\left(x_{i}\right)\right\} K_{2}\left\{\left(x_{i}-x_{0}\right) / h_{2}\right\} .
\end{aligned}
$$

Appendix (iv) sketches a proof of (3.4).
The rate of convergence described by (3.1) is optimal. In fact, if the density $d$ is fixed, if $\mathcal{C}\left(\nu_{1}, B\right)$ and $\mathcal{C}_{+}\left(\nu_{2}, B\right)$ are the function classes defined in Subsection 2.3 but with interval $[0,1]$ replaced by $(-\infty, \infty)$, and if $\hat{g}$ is any nonparametric estimator of $g$, then for some $C>0$,
$\liminf _{n \rightarrow \infty} \sup _{j \in \mathcal{C}\left(\nu_{1}, B\right), g \in \mathcal{C}_{+}\left(\nu_{2}, B\right)} P_{f, g}\left\{\left|\hat{g}\left(x_{0}\right)-g\left(x_{0}\right)\right|>C \max \left(n^{-\nu_{2} /\left(2 \nu_{2}+1\right)}, n^{-2 \nu_{1} /\left(2 \nu_{2}+1\right)}\right)\right\}$ $>0$.
This is an analogue of (2.13), and has an almost identical proof.
All the results above have versions for parametric estimation of $g$, corresponding to $\nu_{\mathbf{2}}=\infty$. In this circumstance we usually do not require parametric knowledge about the design density $d$, since parametric estimation of $g$ does not involve estimation of $d$. It is usually sufficient to ask that $d$ be $\nu_{1}$-smooth.

## ACKNOWLEDGEMENT

The work of R.J. Carroll was supported by the U.S. Air Force Office of Scientific Research and performed while visiting the Institute of Advanced Studies at the Australian National University.

> Appendix (i): Proof of (2.4) and (2.5).

Since $\cdot \hat{f}$ is defined by interpolation from $\hat{f}(i / n)$, it suffices to show that

$$
\begin{equation*}
\sup _{\delta n \leq i \leq n-\delta n}|E \hat{f}(i / n)-f(i / n)|=O\left\{\left(n h_{1}\right)^{-\nu_{1}}\right\}, \sup _{n \leq i \leq n-\delta n} \operatorname{var}\{\hat{f}(i / n)\}=O\left(h_{1}\right) \tag{A.1}
\end{equation*}
$$

Observe from definition (2.3) and properties of $\left\{a_{k}\right\}$ that

$$
E \hat{f}(i / n)-f(i / n)=\Sigma_{k} a_{k}\left(\left\langle\nu_{1}\right)!\right)^{-1}(k / n)^{\left\langle\nu_{1}\right\rangle}\left[f^{\left(\left\langle\nu_{1}\right)\right)}\left\{\left(i+\theta_{k} k\right) / n\right\}-f^{\left(\left(\nu_{1}\right)\right\rangle}(i / n)\right],
$$

where $0 \leq \theta_{k} \leq 1$. Since $f$ is $\nu_{1}$-smooth then $\left|f^{\left(\left(\nu_{1}\right)\right)}(x)-f^{\left(\left(\nu_{1}\right\rangle\right)}(y)\right| \leq C_{1}|x-y|^{\nu_{1}-\left\langle\nu_{1}\right)}$, from which it follows that

$$
\begin{aligned}
|E \hat{f}(i / n)-f(i / n)| & \leq C_{1} \Sigma_{k}\left|(k / n)^{\left\langle\nu_{1}\right)} a_{k}\right||k / n|^{\nu_{1}-\left(\nu_{1}\right\rangle} \\
& =C_{1} n^{-\nu_{1}} \Sigma_{k}|k|^{\nu_{1}}\left|a_{k}\right| \leq C_{2}\left(n h_{1}\right)^{-\nu_{1}}
\end{aligned}
$$

which gives the first part of (A.1). The second part follows from

$$
\operatorname{var}\{\hat{f}(i / n)\}=\Sigma a_{k}^{2} g\{(i+k) / n\} \leq(\sup g) \Sigma a_{k}^{2}=O\left(h_{1}\right)
$$

Appendix (ii): Proof of (2.10).
Put $D_{i} \equiv E \hat{f}(i / n)-f(i / n), \Delta_{i} \equiv \Sigma_{k} a_{k} g\{(i+k) / n\}^{\frac{1}{2}} \epsilon_{i+k}$. Then $\hat{r}_{i}=g(i / n)^{\frac{1}{2}} \epsilon_{i}-$ $D_{i}-\Delta_{i}$, so that $\hat{g}(i / n)-g(i / n)=\Sigma_{1 \leq j \leq 6} S_{j}$, where

$$
\begin{gathered}
S_{1} \equiv \Sigma_{l} b_{l} g\{(i+l) / n\}\left(\epsilon_{i+l}^{2}-1\right), \quad S_{2} \equiv \Sigma_{l} b_{l} D_{i+l}^{2}, \quad S_{3} \equiv \Sigma_{l} b_{l} \Delta_{i+l}^{2} \\
S_{4} \equiv-2 \Sigma_{l} b_{l} g\{(i+l) / n\}^{\frac{1}{2}} D_{i+l} \epsilon_{i+l}, \quad S_{5} \equiv-2 \Sigma_{l} b_{l} g\{(i+l) / n\}^{\frac{1}{2}} \epsilon_{i+l} \Delta_{i+l} \\
S_{6} \equiv 2 \Sigma_{l} b_{l} D_{i+l} \Delta_{i+l}
\end{gathered}
$$

It suffices to show that

$$
\begin{equation*}
\sup _{\delta n \leq i \leq n-\delta n, 1 \leq j \leq 6}\left[\left\{E S_{j}(i)\right\}^{2}+\operatorname{var} S_{j}(i)\right]=O\left\{h_{2}+\left(n h_{2}\right)^{-2 \nu_{2}}+h_{1}^{2}+\left(n h_{1}\right)^{-4 \nu_{1}}\right\} \tag{A.2}
\end{equation*}
$$

Observe that $E\left(S_{j}\right)=0$ for $j=1,4$ and $6 ;\left|D_{i}\right|=O\left\{\left(n h_{1}\right)^{-\nu_{i}}\right\}$, by (A.1); $E\left(\Delta_{i}^{2}\right)=$ $O\left(\Sigma a_{k}^{2}\right)=O\left(h_{1}\right) ;$ and $E\left(\epsilon_{i} \Delta_{i}\right)=a_{0} g(i / n)=O\left(h_{1}\right)$. Therefore $E\left(S_{2}\right)=O\left\{\left(n h_{1}\right)^{-2 \nu_{1}}\right\}$, $E\left(S_{3}\right)=O\left(h_{1}\right)=E\left(S_{3}\right)$. Hence, each $\left(E S_{j}\right)^{2}$ admits the bound claimed in (A.2). Trivially, $\operatorname{var}\left(S_{1}\right)=O\left(\Sigma b_{l}^{2}\right)=O\left(h_{2}\right), \operatorname{var}\left(S_{2}\right)=0, \operatorname{var}\left(S_{4}\right)=O\left(\Sigma b_{1}^{2}\right)=O\left(h_{2}\right)$. Furthermore,

$$
\begin{aligned}
E\left(S_{3}^{2}\right)= & \Sigma_{l_{1}} \Sigma_{l_{2}} \Sigma_{k_{1}} \ldots \Sigma_{k_{4}} b_{l_{1}} b_{l_{2}} a_{k_{1}} \ldots a_{k_{4}}\left[g\left\{\left(i+l_{1}+k_{1}\right) / n\right\} g\left\{\left(i+l_{1}+k_{2}\right) / n\right\}\right. \\
& \left.\times g\left\{\left(i+l_{2}+k_{3}\right) / n\right\} g\left\{\left(i+l_{2}+k_{4}\right) / n\right\}\right]^{\frac{1}{2}} E\left(\epsilon_{i+l_{1}+k_{1}} \epsilon_{i+l_{1}+k_{2}} \epsilon_{i+l_{2}+k_{3}} \epsilon_{i+l_{2}+k_{4}}\right) .
\end{aligned}
$$

The expectation on the right-hand side vanishes unless either $k_{1}=k_{2}$ and $k_{3}=k_{4}$; or $l_{1}-l_{2}=k_{3}-k_{1}=k_{1}-k_{2}$; or $l_{1}-l_{2}=k_{4}-k_{1}=k_{3}-k_{2}$. In the first case, all nonzero terms eicept those corresponding to $k_{1}=k_{2}=k_{3}=k_{1}$, cancel perfectly from the difference $E\left(S_{3}^{2}\right)-\left(E S_{3}\right)^{2}$; and in the second and third cases, once $l_{1}, l_{2}, k_{1}$ and $k_{2}$ are given, $k_{3}$ and $k_{4}$ are completely determined. Therefore, since $\left|a_{k}\right| \leq C_{1} h_{1}$,

$$
\begin{aligned}
\operatorname{var}\left(S_{3}\right) & \leq C_{2}\left(\Sigma_{l_{1}} \Sigma_{l_{2}} \Sigma_{k}\left|b_{l_{1}} b_{l_{2}} a_{k}\right| h_{1}^{3}+\Sigma_{l_{2}} \Sigma_{l_{2}} \Sigma_{k_{1}} \Sigma_{k_{2}}\left|b_{l_{1}} b_{l_{2}} a_{k_{1}} a_{k_{2}}\right| h_{1}^{2}\right) \\
& =O\left(h_{1}^{2}\right)
\end{aligned}
$$

Similar but simpler arguments show that $\operatorname{var}\left(S_{5}\right)=\dot{O}\left(h_{1}^{2}+h_{2}\right), \operatorname{var}\left(S_{6}\right)=O\left\{h_{1}\left(n h_{1}\right)^{-2 \nu_{1}}\right\}$. Hence, each $\operatorname{var}\left(S_{j}\right)$ admits the bound claimed in (A.2).

## Appendix (iii): Proof of (2.15).

We may assume that $\nu_{1} \leq \frac{1}{2}$ and $\nu_{2} \geq \nu_{1}$, for otherwise (2.15) follows from (2.14). For simplicity we further suppose that $B>2$. Let $\psi$ be a nondegenerate, twice-differentiable function on $(-\infty, \infty)$ satisfying $\psi(x)=0$ for $x \leq 0$ and $x \geq 1$, and sup $\left|\psi^{\prime}\right| \leq 1$. Fix $c_{1}>0$, and write $m_{1}, m$ for integers such that $m_{1} \sim c_{1} n^{2 \nu_{1} /\left(2 \nu_{1}+1\right)}, m_{1} m \leq n$ and $m_{1} m \sim n$. Then $m \sim c_{1}^{-1} n^{1 /\left(2 \nu_{1}+1\right)}$. Put $\delta_{1} \equiv m_{1} / n$ and $\delta \equiv \delta_{1}^{2 \nu_{2}}$. Let $I_{1}, \ldots, I_{m}$ be a sequence of 0 's and 1 's, and define $f=f\left(\cdot \mid I_{1}, \ldots, I_{m}\right)$ by

$$
\begin{gather*}
f\left[\left\{(i-1) m_{1}+j\right\} / n\right]=\delta^{\frac{1}{2}} I_{i} \psi\left(j / n \delta_{1}\right) \text { if } 1 \leq i \leq m \text { and } 1 \leq j \leq m_{1}  \tag{A.3}\\
f(x)=0 \text { if } x \leq 0 \text { or } x \geq m_{1} m / n
\end{gather*}
$$

Write $\mathcal{F}$ for the set of all such $f$ 's. Define constant functions $g_{0} \equiv 1$ and $g_{1} \equiv 1+c_{2} \delta$, where $c_{2} \neq 0$, and let $\mathcal{G}=\left\{g_{0}, g_{1}\right\}$. For large $n, \mathcal{F} \subseteq \mathcal{C}\left(\nu_{1}, B\right)$ and $\mathcal{G} \subseteq \mathcal{C}_{+}\left(\nu_{2}, B\right)$.

We claim that if $0<x_{0}<1$ and $\hat{g}$ is a nonparametric estimator of $g$,

$$
\begin{equation*}
\sup _{f \in \mathcal{F}, g \in \mathcal{C}} E_{f, g}\left\{\hat{g}\left(x_{0}\right)-g\left(x_{0}\right)\right\}^{2} \geq C n^{-4 \nu_{1} /\left(2 \nu_{2}+1\right)} \tag{A.4}
\end{equation*}
$$

where $C>0$. It suffices to prove this result for estimators which are functions of $Y_{i}$ for $i \leq m_{1} m$. Let $I_{1}, \ldots, I_{m}$ be independent symmetric $0-1$ variables, independent also of the
$\epsilon_{i}$ 's. For these $l_{i}$ 's, write $f^{*}$ for the (random) function defined as $f$ at (A.3), and let $J$ denote the likelihood ratio rule for discriminating beiween the hypotheses

$$
H_{0}: Y_{i}=f^{*}(i / n)+g_{0}(i / n)^{\frac{1}{2}} \epsilon_{i}, \quad H_{1}: Y_{i}=f^{*}(i / n)+g_{1}(i / n)^{\frac{1}{2}} \epsilon_{i}
$$

Define $\hat{J}=0$ if $\left|\hat{g}\left(x_{0}\right)-g_{0}\left(x_{0}\right)\right| \leq\left|\hat{g}\left(x_{0}\right)-g_{1}\left(x_{0}\right)\right|$, and $\hat{J}=1$ otherwise. Write $P_{i}$ and $E_{i}$ for probability and expectation under $H_{i}$. Then

$$
\begin{aligned}
\sup _{f \in \mathcal{F}, g \in \mathcal{G}} E_{f, g}\left\{\hat{g}\left(x_{0}\right)-g\left(x_{0}\right)\right\}^{2} & \geq \max _{i=1,2} E_{i}\left\{\hat{g}\left(x_{0}\right)-g_{i}\left(x_{0}\right)\right\}^{2} \\
\geq\left(\frac{1}{2} c_{2} \delta\right)^{2} \max \left\{P_{0}(\hat{J}=1), P_{1}(\hat{J}=0)\right\} & \geq \frac{1}{8}\left(c_{2} \delta\right)^{2}\left\{P_{0}(\hat{J}=1)+P_{2}(\hat{J}=0)\right\} \\
& \geq \frac{1}{8}\left(c_{2} \delta\right)^{2}\left\{P_{0}(J=1)+P_{1}(J=0)\right\},
\end{aligned}
$$

by the optimality of the likelihood ratio rule. Therefore (A.4) will follow if we prove

$$
\begin{equation*}
\liminf _{n \rightarrow \infty} P_{0}(J=1)>0 \tag{A.5}
\end{equation*}
$$

Let $(g, H)$ denote either $\left(g_{0}, H_{0}\right)$ or $\left(g_{1}, H_{1}\right)$. If $k=(i-1) m_{1}+j$ where $1 \leq i \leq m$ and $1 \leq j \leq m_{1}$, write $Y_{i j}$ for $Y_{k}$ and $\epsilon_{i j}$ for $\epsilon_{k}$. Assuming standard normal errors $\epsilon_{i j}$, the likelihood of $H$ given $Y_{1}, \ldots, Y_{m_{1} m}$ is proportional to

$$
L(H) \equiv g^{-m_{1} m / 2} \prod_{i=1}^{m}\left(\exp \left(-\frac{1}{2} g^{-1} \sum_{j=1}^{m_{1}} Y_{i j}^{2}\right)+\exp \left[-\frac{1}{2} g^{-1} \sum_{j=1}^{m_{1}}\left\{Y_{i j}-\delta^{\frac{1}{2}} \psi\left(j / n \delta_{1}\right)\right\}^{2}\right]\right) .
$$

If $H_{0}$ is true then

$$
\begin{aligned}
& L(H)=g^{-m_{1} m / 2} \exp \left(-\frac{1}{2} g^{-1} \Sigma_{i} \Sigma_{j} \epsilon_{i j}^{2}\right) \\
\times & \Pi_{i}\left[\exp \left\{-\frac{1}{2} I_{i}\left(d_{1}+2 d_{1}^{\frac{1}{2}} N_{i}\right) g^{-1}\right\}+\exp \left\{-\frac{1}{2}\left(1-I_{i}\right)\left(d_{1}-2 d_{1}^{\frac{1}{2}} N_{i}\right) g^{-1}\right\}\right]
\end{aligned}
$$

where $d_{1} \equiv \delta \Sigma_{j} \psi^{2}\left(j / n \delta_{1}\right) \sim d \equiv c_{1}^{2 \nu_{1}+1} \int \psi^{2}$, and $N_{i} \equiv d_{j}^{-\frac{1}{2}} \delta^{\frac{1}{2}} \Sigma_{j} \psi\left(j / n \delta_{1}\right) \epsilon_{i j}$ is standard normal. Therefore, using the symmetry of $N_{i}$,
$R \equiv 2 \log \left\{L\left(H_{1}\right) / L\left(H_{0}\right)\right\}=m_{1} m\left(1-g_{1}^{-1}+\log g_{1}^{-1}\right)-2\left(g_{1}^{-1}-1\right) m D+o_{p}\left(m_{1} m \delta^{2}+m \delta\right)$, where $D \equiv E\left[\left\{1+\exp \left(\frac{1}{2} d+d^{\frac{1}{2}} N_{1}\right)\right\}^{-1}\left(\frac{1}{2} d+d^{\frac{1}{2}} N_{1}\right)\right]$. Note that

$$
\left|g_{1}^{-1}-1\right|\left|\Sigma_{i} \Sigma_{j}\left(\epsilon_{i j}^{2}-1\right)\right|=O_{p}\left\{\left(m_{1} m \delta^{2}\right)^{\frac{1}{2}}\right\}=o_{p}\left(m_{1} m \delta^{2}\right)
$$

Choose $c_{1}$ so that $D \neq 0$, let $c_{3}>0$ and put $c_{2} \equiv c_{3} \operatorname{sgn}(D)$. Since $g_{1}=1+c_{2} \delta$ then

$$
R=-\frac{1}{2} m_{1} m \delta^{2} c_{3}^{2}\left\{1+v_{p}(1)\right\}+m \delta c_{3}|D|\left\{1+o_{p}(1)\right\}
$$

Choose $c_{3}$ so small that $c_{4} \equiv c_{3}|D|-\frac{1}{2} c_{1}^{2 \nu_{1}+1} c_{3}^{2}>0$. Then $R \sim c_{4} m \delta \rightarrow \infty$, so that $P_{0}(J=1) \rightarrow 1$, proving (A.5).

Appendix (iv): Sketch proof of (3.4).
Let $s(x) \equiv f(x) d(x)$ and $\hat{s}_{i}(x) \equiv \hat{f}_{i}(x) \hat{d}_{1 i}(x)$. Assume $\nu_{1}>\nu_{2} /\left\{2\left(\nu_{2}+1\right)\right\}$, and put $\xi_{n} \equiv \max \left(n^{-2 \nu_{1} /\left(2 \nu_{1}+1\right)}, n^{-2 \nu_{2} /\left(2 \nu_{2}+1\right)}\right)(\log n)^{2}$. Equation (3.4) will follow if $\left|A_{n}\right|=O_{p}\left(\xi_{n}\right)$, $\left|B_{n}\right|=O_{p}\left(\xi_{n}\right)$. Dropping the argument $x$,

$$
\begin{gather*}
\hat{f}_{i}-f=\left(\hat{s}_{i}-s\right) / d-\left(\hat{s}_{i}-s\right)\left(\hat{d}_{1 i}-d\right) /\left(d \hat{d}_{1 i}\right)-s\left(\hat{d}_{1 i}-d\right) /\left(d \hat{d}_{1 i}\right) \\
=\left(\hat{s}_{i}-s\right) / d-\left(\hat{s}_{i}-s\right)\left(\hat{d}_{1 i}-d\right) /\left(d \hat{d}_{1 i}\right)-s\left(\hat{d}_{1 i}-d\right) / d^{2} \\
+s\left(\hat{d}_{1 i}-d\right)^{2} /\left(d^{2} \hat{d}_{1 i}\right) \tag{A.6}
\end{gather*}
$$

For $A_{n}$, note that

$$
\left(\hat{f}_{i}-f\right)^{2} \leq 10\left\{\left(\hat{s}_{i}-s\right)^{2} / d^{2}+\left(\hat{s}_{i}-s\right)^{2}\left(\hat{d}_{1 i}-d\right)^{2} /\left(d \hat{d}_{1 i}\right)^{2}+(s / d)^{2}\left(\hat{d}_{1 i}-d\right)^{2} / \hat{d}_{1 i}^{2}\right\}
$$

This bounds $A_{n}$ by the sum of three terms, say $A_{n 1}, A_{n 2}$ and $A_{n 3}$. By (3.3), $A_{n 3}=O_{p}\left(\xi_{n}\right)$. If we show that $A_{n 1}=O_{p}\left(\xi_{n}\right)$, the same easily follows for $A_{n 2}$ by (3.3). Define

$$
\begin{aligned}
& v_{1}\left(x_{i}\right) \equiv\left(n h_{1}\right)^{-1} \sum_{k \neq i}\left\{f\left(x_{k}\right)-f\left(x_{i}\right)\right\} K_{1}\left\{\left(x_{k}-x_{i}\right) / h_{1}\right\} / d\left(x_{i}\right) \\
& v_{2}\left(x_{i}\right) \equiv\left(n h_{1}\right)^{-1} \sum_{k \neq i} g\left(x_{k}\right)^{\frac{1}{2}} \epsilon_{i} K_{1}\left\{\left(x_{k}-x_{i}\right) / h_{1}\right\} / d\left(x_{i}\right) \\
& v_{3}\left(x_{i}\right) \equiv f\left(x_{i}\right)\left\{\hat{d}_{1 i}\left(x_{i}\right)-d\left(x_{i}\right)\right\} / d\left(x_{i}\right)
\end{aligned}
$$

Since $Y_{k}-f\left(x_{i}\right)=f\left(x_{k}\right)-f\left(x_{i}\right)+g\left(x_{k}\right)^{\frac{1}{2}} \epsilon_{k}$ then $A_{n 1} \leq A_{n 11}+A_{n 12}+A_{n 13}$, where

$$
A_{n 1 j}=10\left(n \delta_{2}\right)^{-1} \sum_{i=1}^{n}\left|K_{2}\left\{\left(x_{i}-x_{0}\right) / \delta_{2}\right\}\right| v_{j}^{2}\left(x_{i}\right)
$$

By (3.3) for the last and moment calculations for the first two, it is seen that each $A_{n 1 i}=$ $O_{p}\left(\xi_{n}\right)$.

To study $B_{n}$, split it into four terms $B_{n 1}+B_{n 2}+B_{n 3}+B_{n 4}$ based on (A.6). Cising (3.3), $B_{n 4}=O_{p}\left(\xi_{n}\right)$. Since $E B_{n 3}=0$, one proves that $B_{n 3}=O_{p}\left(\xi_{n}\right)$ by showing that $\operatorname{var}\left(B_{n 3}\right)=O\left(\xi_{n}^{2}\right)$, which is an easy calculation. For $B_{n 2}$ apply Cauchy-Schwarz, (3.3) and the arguments used to bound $A_{n 1}$, to show that $B_{n 2}=O_{p}\left(\xi_{n}\right)$. This leaves us to study $B_{n 1}$. Now $B_{n 1}=B_{n 11}+B_{n 12}+B_{n 13}$, where

$$
B_{n 1 j}=\left(n h_{2}\right)^{-1} \sum_{i=1}^{n} g\left(x_{i}\right)^{\frac{1}{2}} \epsilon_{i} K_{2}\left\{\left(x_{i}-x_{0}\right) / h_{2}\right\} v_{j}\left(x_{i}\right) .
$$

Each of these random variables has mean zero and variance $O\left(\xi_{n}^{2}\right)$, completing the proof.

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