

Vertical Contracting with Informational Opportunism

By VIANNEY DEQUIEDT AND DAVID MARTIMORT

ONLINE APPENDIX

APPENDIX B: THE REVELATION PRINCIPLE UNDER BILATERAL CONTRACTING

Section B.B1 describes the most general class of bilateral contracts that could be envisioned in our framework. Section B.B2 derives a set of new incentive constraints that apply to the principal if one wants to characterize implementable allocations. Because this Appendix is of general interest beyond the specific vertical contracting problem under scrutiny, we will slightly generalize the presentation and allow for $n \geq 2$ agents. For ease of notations, we denote the principal's and the agents' utility functions respectively as:

$$\mathcal{V}(\mathbf{q}, \mathbf{t}) = \sum_{i=1}^n t_i - C(\mathbf{q}) \text{ and } \mathcal{U}_i(\mathbf{q}, \mathbf{t}, \theta_i) = u_i(\mathbf{q}, \theta_i) - t_i.$$

B1. Mechanisms and Timing

In the main text, our presentation of the bilateral contracting setup focused on deterministic nonlinear prices because such mechanisms echo real world practices in vertical contracting arrangements and because they have been extensively used in the vertical contracting literature. In this Appendix, we extend the scope of our analysis by allowing for stochastic mechanisms and more general communication protocols.

A bilateral mechanism \mathcal{B}_i ruling the relationship between the principal and agent A_i is a triplet consisting of a message space \mathcal{M}_i^a for A_i (with generic message m_i^a), a message space \mathcal{M}_i^p for the principal (with generic message m_i^p) and a (joint) distribution $\sigma_i(m_i^a, m_i^p)$ of agent A_i 's payment and output on the compact set $\mathcal{Q}_i \times \mathcal{T}_i$. We will denote $d\sigma_i(q_i, t_i | m_i^a, m_i^p)$ the corresponding measure. For future reference, let $\Delta(\mathcal{E})$ denote the set of probability measures on any arbitrary set \mathcal{E} .

Let $\mathbf{m}^a = (m_1^a, \dots, m_n^a) \in \mathcal{M}^a = \mathcal{M}_1^a \times \dots \times \mathcal{M}_n^a$ be an array of messages sent by the agents to the principal and $\mathbf{m}^p = (m_1^p, \dots, m_n^p) \in \mathcal{M}^p = \mathcal{M}_1^p \times \dots \times \mathcal{M}_n^p$ be an array of messages sent by the principal to each of his agents respectively. Let also $\mathcal{B} = (\mathcal{B}_1, \dots, \mathcal{B}_n)$ be an array of bilateral mechanisms with the corresponding array of distributions $(\sigma_1(m_1^a, m_1^p), \dots, \sigma_n(m_n^a, m_n^p))$ induced by the respective messages of the agents and the principal in each bilateral relationship.

Payoffs are defined as expectations over the relevant mixtures. For instance, we denote agent A_i 's expected payoff when his type is θ_i , the messages are $\mathbf{m}^a = (m_1^a, \dots, m_n^a)$ and $\mathbf{m}^p = (m_1^p, \dots, m_n^p)$, and the distribution of payments and outputs is induced by the bilateral contracts $(\sigma_1(m_1^a, m_1^p), \dots, \sigma_n(m_n^a, m_n^p))$ by:

$$\mathcal{U}_i(\sigma_1(m_1^a, m_1^p), \dots, \sigma_n(m_n^a, m_n^p), \theta_i) = \int \mathcal{U}_i(\mathbf{q}, \mathbf{t}, \theta_i) d\sigma_1(t_1, q_1 | m_1^a, m_1^p) \dots d\sigma_n(t_n, q_n | m_n^a, m_n^p).$$

We will sometimes use the notation $\mathcal{U}_i(\sigma_i(m_i^a, m_i^p), \sigma_{-i}(m_{-i}^a, m_{-i}^p), \theta_i)$ to isolate the role played by the bilateral mechanism \mathcal{B}_i . Similarly, the principal's expected payoff writes as $\mathcal{V}(\sigma_1(m_1^a, m_1^p), \dots, \sigma_n(m_n^a, m_n^p))$ where:

$$\mathcal{V}(\sigma_1(m_1^a, m_1^p), \dots, \sigma_n(m_n^a, m_n^p)) = \int \mathcal{V}(\mathbf{q}, \mathbf{t}) d\sigma_1(t_1, q_1 | m_1^a, m_1^p) \dots d\sigma_n(t_n, q_n | m_n^a, m_n^p).$$

The contracting game generalizes that presented in the main text. First, agents privately learn their types. Second, the principal (publicly) offers the bilateral contracts \mathcal{B} . Third, each agent A_i accepts or refuses his own offer \mathcal{B}_i . If he refuses, he gets a payoff that is normalized to zero. Fourth, agents simultaneously send their messages $\mathbf{m}^a = (m_1^a, \dots, m_n^a)$ to the principal. Finally, knowing the vector of agents' messages \mathbf{m}^a , the principal optimally chooses to send back the messages $\mathbf{m}^{p*}(\mathbf{m}^a) = (m_1^{p*}(\mathbf{m}^a), \dots, m_n^{p*}(\mathbf{m}^a))$ in each relationship.

B2. The Principal's Ex Post Incentive Constraints

We now characterize the set of allocations that can be achieved as perfect Bayesian equilibria of the contracting game when the principal offers any possible menu of bilateral contracts \mathcal{B} .

Let $m_i^{a*}(\theta_i)$ be agent A_i 's optimal reporting strategy (which is possibly mixed) when his type is θ_i . Thus, m_i^{a*} maps Θ into $\Delta(\mathcal{M}_i^a)$. Let also $\mathbf{m}^{a*}(\theta) = (m_1^{a*}(\theta_1), \dots, m_n^{a*}(\theta_n))$ be the array of such strategies. We denote by $\text{supp } m_i^{a*}(\theta_i)$ the support of $m_i^{a*}(\theta_i)$, i.e., the set of messages sent with positive probability by type θ_i . Let $\mathbf{m}^{p*}(\mathbf{m}^a)$ be principal P 's optimal pure reporting strategy when he observes the messages \mathbf{m}^a . Thus, \mathbf{m}^{p*} maps \mathcal{M}^a into \mathcal{M}^p . Observe that the principal does not randomize among the messages he sends back to the agents at this last stage of the game. This restricts the possible continuation equilibria (we make this restriction explicit in the definition of Lemma B.1 below) but is consistent with the idea that the relationship is run with bilateral contracts and the principal cannot indirectly correlate plays in those relationships by himself correlating the messages he sends back to the agents.

We denote agent A_i 's expected payoff when the vector of types is (θ_i, θ_{-i}) , other agents play the (possibly) mixed strategies $m_{-i}^{a*}(\theta_{-i})$, the principal plays $\mathbf{m}^{p*}(\mathbf{m}^a)$ and agent A_i sends message m_i^a by:

$$\begin{aligned} & \mathcal{U}_i(\sigma_i(m_i^a, m_i^{p*}(m_i^a, m_{-i}^{a*}(\theta_{-i}))), \sigma_{-i}(m_{-i}^{a*}(\theta_{-i}), m_{-i}^{p*}(m_i^a, m_{-i}^{a*}(\theta_{-i}))), \theta_i) \\ &= \int \mathcal{U}_i(\sigma_1(m_1^a, m_1^{p*}(m_i^a, m_{-i}^{a*}(\theta_{-i}))), \dots, \sigma_n(m_n^a, m_n^{p*}(m_i^a, m_{-i}^{a*}(\theta_{-i}))), \theta_i) \\ & \quad \times dm_1^{a*}(m_1^a|\theta_1) \dots dm_{i-1}^{a*}(m_{i-1}^a|\theta_{i-1}) dm_{i+1}^{a*}(m_{i+1}^a|\theta_{i+1}) \dots dm_n^{a*}(m_n^a|\theta_n). \end{aligned}$$

Finally, we denote the principal's expected payoff when the vector of types is θ , agents play the (possibly) mixed strategies $\mathbf{m}^{a*}(\theta)$ and the principal plays $\mathbf{m}^{p*}(\mathbf{m}^a)$ by:

$$\begin{aligned} & \mathcal{V}(\sigma_1(m_1^{a*}(\theta_1), m_1^{p*}(\mathbf{m}^{a*}(\theta))), \dots, \sigma_n(m_n^{a*}(\theta_n), m_n^{p*}(\mathbf{m}^{a*}(\theta)))) \\ &= \int \mathcal{V}(\sigma_1(m_1^a, m_1^{p*}(\mathbf{m}^a)), \dots, \sigma_n(m_n^a, m_n^{p*}(\mathbf{m}^a))) dm_1^{a*}(m_1^a|\theta_1) \dots dm_n^{a*}(m_n^a|\theta_n). \end{aligned}$$

For a given set of bilateral contracts $\mathcal{B} = (\mathcal{B}_1, \dots, \mathcal{B}_n)$, a continuation equilibrium where offers are accepted (sometimes in short a *continuation equilibrium*) is described as follows.

LEMMA B.1: Fix any arbitrary set of bilateral mechanisms \mathcal{B} . A continuation equilibrium is a pair $(\mathbf{m}^{a*}, \mathbf{m}^{p*})$ such that:

- The agents' reporting strategies $\mathbf{m}^{a*} = (m_1^{a*}, \dots, m_n^{a*})$ form a Bayesian equilibrium given the principal's optimal choice \mathbf{m}^{p*} if and only if for any $m_i^a \in \text{supp } m_i^{a*}(\theta_i)$

$$E_{\theta_{-i}} \left(\mathcal{U}_i(\sigma_i(m_i^a, m_i^{p*}(m_i^a, m_{-i}^{a*}(\theta_{-i}))), \sigma_{-i}(m_{-i}^{a*}(\theta_{-i}), m_{-i}^{p*}(m_i^a, m_{-i}^{a*}(\theta_{-i}))), \theta_i) | \theta_i \right)$$

(B1)

$$\geq E_{\theta_{-i}} \left(\mathcal{U}_i(\sigma_i(\hat{m}_i^a, m_i^{p*}(\hat{m}_i^a, m_{-i}^{a*}(\theta_{-i}))), \sigma_{-i}(m_{-i}^{a*}(\theta_{-i}), m_{-i}^{p*}(\hat{m}_i^a, m_{-i}^{a*}(\theta_{-i}))), \theta_i) | \theta_i \right) \quad \forall \hat{m}_i^a \in \mathcal{M}_i^a;$$

- Agents accept their offers:

$$(B2) \quad E_{\theta_{-i}} \left(\mathcal{U}_i(\sigma_i(m_i^a, m_i^{p*}(m_i^a, m_{-i}^{a*}(\theta_{-i}))), \sigma_{-i}(m_{-i}^{a*}(\theta_{-i}), m_{-i}^{p*}(m_i^a, m_{-i}^{a*}(\theta_{-i}))), \theta_i) | \theta_i \right) \geq 0;$$

- The principal's reporting strategy $\mathbf{m}^{p*}(\mathbf{m}^a) = (m_1^{p*}(\mathbf{m}^a), \dots, m_n^{p*}(\mathbf{m}^a))$ is any (pure) selection within his best-response correspondence:

(B3)

$$\mathcal{V}(\sigma_1(m_1^a, m_1^{p*}(\mathbf{m}^a)), \dots, \sigma_n(m_n^a, m_n^{p*}(\mathbf{m}^a))) \geq \mathcal{V}(\sigma_1(m_1^a, \hat{m}_1^p), \dots, \sigma_n(m_n^a, \hat{m}_n^p)) \quad \forall (\hat{m}_1^p, \dots, \hat{m}_n^p) \in \mathcal{M}^p.$$

Proof of Lemma B.1. Take any arbitrary set of bilateral mechanisms $\mathcal{B} = (\mathcal{B}_1, \dots, \mathcal{B}_n)$ with the corresponding array of distributions $(\sigma_1(m_1^a, m_1^p), \dots, \sigma_n(m_n^a, m_n^p))$. Consider also a perfect Bayesian continuation equilibrium following acceptance. Such continuation is a pair of strategy $\{\mathbf{m}^{a*}, \mathbf{m}^{p*}\}$ and a belief system $d\mu(\theta|\mathbf{m}^a)$ that altogether satisfy the following conditions.

- The principal updates his beliefs on the agents' types following Bayes' rule whenever possible, i.e, when $\mathbf{m}^a \in \text{supp } m_1^{a*}(\theta_1) \times \dots \times \text{supp } m_n^{a*}(\theta_n)$ for some $(\theta_1, \dots, \theta_n)$. Otherwise, beliefs are arbitrary. Let $d\mu(\theta|\mathbf{m}^a)$ denote the updated belief system following any arbitrary message m^a .
- Given any such vector m (either on- or off- equilibrium) and the corresponding posterior beliefs, the principal chooses messages $\mathbf{m}^{p*}(\mathbf{m}^a)$ in his best-response correspondence such that:

$$(B4) \quad \mathbf{m}^{p*}(\mathbf{m}^a) \in \arg \max_{\mathbf{m}^p \in \mathcal{M}^p} \int_{\Theta} \mathcal{V}(\sigma_1(m_1^a, \hat{m}_1^p), \dots, \sigma_n(m_n^a, \hat{m}_n^p)) d\mu(\theta|\mathbf{m}^a)$$

Since in a private values context the agents' types do not enter directly into the principal's utility function, expectations do not matter and (B4) can be expressed as the pointwise optimization (B3).

- A_i with type θ_i sends messages according to the mixed strategy $\mathbf{m}_i^{a*}(\theta_i)$ anticipating the principal's best response $\mathbf{m}^{p*}(\mathbf{m}^a)$. The mixed strategies $(m_1^{a*}(\theta_1), \dots, m_n^{a*}(\theta_n))$ form a Bayesian-Nash equilibrium which gives (B1). Acceptance then follows from (B2). ■

An array of bilateral contracts $\mathcal{B} = (\mathcal{B}_1, \dots, \mathcal{B}_n)$ with the corresponding distributions of payments and outputs in each bilateral relationship $(\sigma_1(m_1^a, m_1^p), \dots, \sigma_n(m_n^a, m_n^p))$ and a continuation equilibrium $\{\mathbf{m}^{a*}, \mathbf{m}^{p*}\}$ altogether induce a (possibly stochastic) allocation:

$$(\sigma_1(m_1^{a*}(\theta_1), m_1^{p*}(\mathbf{m}^{a*}(\theta))), \dots, \sigma_n(m_n^{a*}(\theta_n), m_n^{p*}(\mathbf{m}^{a*}(\theta))),$$

where, in case of mixed reporting strategies, the notation $m_i^{p*}(\mathbf{m}^{a*}(\theta))$ (respectively the notation $\sigma_i(m_i^{a*}(\theta_i), m_i^{p*}(\mathbf{m}^{a*}(\theta)))$) denotes the distribution over \mathcal{M}_i^p (resp. over $\mathcal{Q}_i \times \mathcal{T}_i$) induced by the strategies \mathbf{m}^{p*} and \mathbf{m}^{a*} . Direct revelation mechanisms are helpful to characterize such allocations. A (bilateral) direct revelation mechanism $\tilde{\sigma}_i(\hat{\theta}_i, \hat{\theta}_{-i})$ indeed specifies a distribution on A_i 's payment and output as a function of reports $(\hat{\theta}_i, \hat{\theta}_{-i})$ where the first item $\hat{\theta}_i \in \Theta$ is A_i 's own report on his own type whereas $\hat{\theta}_{-i} \in \Theta^{n-1}$ is the principal's report on what he has learned from other agents. Let $\tilde{\sigma} = (\tilde{\sigma}_1, \dots, \tilde{\sigma}_n)$ be a collection of such bilateral direct mechanisms. For further references, let also $\tilde{\sigma}_k(\hat{\theta}_k, (\hat{\theta}_i, \hat{\theta}_{-i-k}))$ denote the distribution of payments and outputs in the bilateral relationship between A_k and the principal when the former reports $\hat{\theta}_k$, and the latter reports $\hat{\theta}_i$ on A_i (for $i \neq k$) and $\hat{\theta}_{-i-k}$ on others. Formally, the distribution on transfers and outputs in the bilateral relationship between A_i and the principal is given by:

$$(B5) \quad \tilde{\sigma}_i(\hat{\theta}_i, \hat{\theta}_{-i}) = \sigma_i(m_i^{a*}(\hat{\theta}_i), m_i^{p*}(\mathbf{m}^{a*}(\hat{\theta}_i, \hat{\theta}_{-i})));$$

and we also have

$$(B6) \quad \tilde{\sigma}_k(\hat{\theta}_k, (\hat{\theta}_i, \hat{\theta}_{-i-k})) = \sigma_k(m_k^{a*}(\hat{\theta}_k), m_k^{p*}(\mathbf{m}^{a*}(\hat{\theta}_i, \hat{\theta}_{-i}))).$$

PROPOSITION B.1: *In a private values context, any allocation achieved at a continuation equilibrium $\{\mathbf{m}^{a*}, \mathbf{m}^{p*}\}$ with the offer and acceptance of the bilateral contracts \mathcal{B} can also be implemented through a collection of bilateral direct mechanisms $\tilde{\sigma} = (\tilde{\sigma}_1, \dots, \tilde{\sigma}_n)$ satisfying (B5) and (B6) and such that:*

- 1) *The agents' participation constraints hold:*

$$(B7) \quad E_{\theta_{-i}} (\mathcal{U}_i(\tilde{\sigma}_1(\theta_1, (\theta_i, \theta_{-1-i})), \dots, \tilde{\sigma}_i(\theta_i, \theta_{-i}), \dots, \tilde{\sigma}_n(\theta_n, (\theta_i, \theta_{-i-n})), \theta_i) | \theta_i) \geq 0;$$

- 2) *The agents' Bayesian incentive compatibility constraints hold:*

$$E_{\theta_{-i}} (\mathcal{U}_i(\tilde{\sigma}_1(\theta_1, (\theta_i, \theta_{-1-i})), \dots, \tilde{\sigma}_i(\theta_i, \theta_{-i}), \dots, \tilde{\sigma}_n(\theta_n, (\theta_i, \theta_{-i-n})), \theta_i) | \theta_i)$$

$$(B8) \quad \geq E_{\theta_{-i}} \left(\mathcal{U}_i(\tilde{\sigma}_1(\theta_1, (\hat{\theta}_i, \theta_{-1-i})), \dots, \tilde{\sigma}_i(\hat{\theta}_i, \theta_{-i}), \dots, \tilde{\sigma}_n(\theta_n, (\hat{\theta}_{-i}, \hat{\theta}_{-i-n})), \theta_i) | \theta_i \right) \quad \forall (\theta_i, \hat{\theta}_i, \theta_{-i});$$

3) The principal's ex post incentive compatibility constraints (EPIC) hold:

$$(B9) \quad \mathcal{V}(\tilde{\sigma}_1(\theta_1, \theta_{-1}), \dots, \tilde{\sigma}_i(\theta_i, \theta_{-i}), \dots, \tilde{\sigma}_n(\theta_n, \theta_{-n})) \\ \geq \mathcal{V}(\tilde{\sigma}_1(\theta_1, \hat{\theta}_{-1}), \dots, \tilde{\sigma}_i(\theta_i, \hat{\theta}_{-i}), \dots, \tilde{\sigma}_n(\theta_n, \hat{\theta}_{-n})) \quad \forall (\theta, \hat{\theta}_{-1}, \dots, \hat{\theta}_{-n}).$$

Proof of Proposition B.1. First, it is routine to check that the agents' Bayesian incentive constraints (B1) imply (B8). From the definition (B5) and the incentive constraint (B1), we get:

$$\begin{aligned} & E_{\theta_{-i}} \left(\mathcal{U}_i(\tilde{\sigma}_1(\theta_1, (\theta_i, \theta_{-1-i})), \dots, \tilde{\sigma}_i(\theta_i, \theta_{-i}), \dots, \tilde{\sigma}_n(\theta_n, (\theta_{-i}, \theta_{-i-n})), \theta_i) | \theta_i \right) = \\ & E_{\theta_{-i}} \left(\mathcal{U}_i(\sigma_1(m_1^{a*}(\theta_1), m_1^{p*}(\mathbf{m}^{a*}(\theta_i, \theta_{-i}))), \dots, \sigma_i(m_i^{a*}(\theta_i), m_i^{p*}(\mathbf{m}^{a*}(\theta_i, \theta_{-i}))), \dots, \sigma_n(m_n^{a*}(\theta_n), m_n^{p*}(\mathbf{m}^{a*}(\theta_i, \theta_{-i}))), \theta_i) | \theta_i \right) \\ & \geq \\ & E_{\theta_{-i}} \left(\mathcal{U}_i(\sigma_1(m_1^{a*}(\theta_1), m_1^{p*}(\mathbf{m}^{a*}(\hat{\theta}_i, \theta_{-i}))), \dots, \sigma_i(m_i^{a*}(\hat{\theta}_i), m_i^{p*}(\mathbf{m}^{a*}(\hat{\theta}_i, \theta_{-i}))), \dots, \sigma_n(m_n^{a*}(\theta_n), m_n^{p*}(\mathbf{m}^{a*}(\hat{\theta}_i, \theta_{-i}))), \theta_i) | \theta_i \right) \\ (B10) \quad & = E_{\theta_{-i}} \left(\mathcal{U}_i(\tilde{\sigma}_1(\theta_1, (\hat{\theta}_i, \theta_{-1-i})), \dots, \tilde{\sigma}_i(\hat{\theta}_i, \theta_{-i}), \dots, \tilde{\sigma}_n(\theta_n, (\hat{\theta}_{-i}, \theta_{-i-n})), \theta_i) | \theta_i \right) \quad \forall (\theta_i, \hat{\theta}_i, \theta_{-i}) \end{aligned}$$

where the first and the last equalities follow from using (B5) and (B6) respectively and the middle inequality follows from (B1) using $\hat{m}_i^a = m_i^{a*}(\hat{\theta}_i)$.

Then, observe that the direct bilateral mechanisms are now acceptable when (B7) holds.

Turning now to the principal's ex post incentive constraints, observe now that using (B5) gives us:

$$(B11) \quad \mathcal{V}(\tilde{\sigma}_1(\theta_1, \theta_{-1}), \dots, \tilde{\sigma}_i(\theta_i, \theta_{-i}), \dots, \tilde{\sigma}_n(\theta_n, \theta_{-n})) = \mathcal{V}(\sigma_1(m_1^{a*}(\theta_1), m_1^{p*}(\mathbf{m}^{a*}(\theta))), \dots, \sigma_n(m_n^a(\theta_n), m_n^{p*}(\mathbf{m}^{a*}(\theta)))) \\ = \int \mathcal{V}(\sigma_1(m_1^a, m_1^{p*}(\mathbf{m}^a)), \dots, \sigma_n(m_n^a, m_n^{p*}(\mathbf{m}^a))) dm_1^{a*}(m_1^a | \theta_1) \dots dm_n^{a*}(m_n^a | \theta_n).$$

Using (B3), we know that for any $\mathbf{m}^a = (m_1^a, \dots, m_n^a)$:

$$\mathcal{V}(\sigma_1(m_1^a, m_1^{p*}(\mathbf{m}^a)), \dots, \sigma_n(m_n^a, m_n^{p*}(\mathbf{m}^a))) \geq \mathcal{V}(\sigma_1(m_1^a, \hat{m}_1^p), \dots, \sigma_n(m_n^a, \hat{m}_n^p)) \quad \forall \hat{\mathbf{m}}^p = (\hat{m}_1^p, \dots, \hat{m}_n^p).$$

Taking in particular $\hat{m}_i^p = m_i^{p*}(m_i^a, \hat{\mathbf{m}}_{-i}^a)$ where $\hat{\mathbf{m}}_{-i}^a \in \text{supp } m_{-i}^{a*}(\hat{\theta}_{-i})$ for some $\hat{\theta}_{-i}$, we get:

$$\mathcal{V}(\sigma_1(m_1^a, m_1^{p*}(\mathbf{m}^a)), \dots, \sigma_n(m_n^a, m_n^{p*}(\mathbf{m}^a))) \geq \mathcal{V}(\sigma_1(m_1^a, m_1^{p*}(m_1^a, \hat{\mathbf{m}}_{-1}^a)), \dots, \sigma_n(m_n^a, m_n^{p*}(m_n^a, \hat{\mathbf{m}}_{-n}^a))).$$

By integrating over the relevant mixtures, we thus obtain:

$$(B12) \quad \int \mathcal{V}(\sigma_1(m_1^a, m_1^{p*}(\mathbf{m}^a)), \dots, \sigma_n(m_n^a, m_n^{p*}(\mathbf{m}^a))) dm_1^{a*}(m_1^a | \theta_1) \dots dm_n^{a*}(m_n^a | \theta_n) \geq \\ \int \mathcal{V}(\sigma_1(m_1^a, m_1^{p*}(m_1^a, \hat{\mathbf{m}}_{-1}^a)), \dots, \sigma_n(m_n^a, m_n^{p*}(m_n^a, \hat{\mathbf{m}}_{-n}^a))) dm_1^{a*}(m_1^a | \theta_1) dm_{-1}^{a*}(\hat{m}_{-1}^a | \hat{\theta}_{-1}) \dots dm_n^{a*}(m_n^a | \theta_n) dm_{-n}^{a*}(\hat{m}_{-n}^a | \hat{\theta}_{-n}).$$

Gathering (B11) and (B12), we finally get:

$$\begin{aligned}
 & \mathcal{V}(\tilde{\sigma}_1(\theta_1, \theta_{-1}), \dots, \tilde{\sigma}_i(\theta_i, \theta_{-i}), \dots, \tilde{\sigma}_n(\theta_n, \theta_{-n})) \\
 & \geq \mathcal{V}(\sigma_1(m_1^{a*}(\theta_1), m_1^{p*}(\mathbf{m}^{a*}(\theta_1, \hat{\theta}_{-1}))), \dots, \sigma_n(m_n^a(\theta_n), m_n^{p*}(\mathbf{m}^{a*}(\theta_n, \hat{\theta}_{-n})))) \\
 (B13) \quad & = \mathcal{V}(\tilde{\sigma}_1(\theta_1, \hat{\theta}_{-1}), \dots, \tilde{\sigma}_i(\theta_i, \hat{\theta}_{-i}), \dots, \tilde{\sigma}_n(\theta_n, \hat{\theta}_{-n})) \quad \forall (\theta, \hat{\theta}_{-1}, \dots, \hat{\theta}_{-n}).
 \end{aligned}$$

where the last equality follows from using (B5). ■

Proposition 1 in the text is a direct consequence of the more general statement Proposition B.1.

The Revelation Principle obtained in this dynamic environment with limited commitment differs from that presented in Myerson (1986)⁶¹ in two respects. Following his general methodology for dynamic games of incomplete information, there is no loss of generality in using direct revelation mechanisms where informed players send reports on their information at any stage to a central mediator and then obey his recommendations (which may possibly involve communication strategies towards their principal which are mixtures as in Strausz, 2006, for instance). Here, we keep decentralized communication and the final allocation is implemented with an array of direct revelation mechanisms. Second, with mediated communication and the corresponding centralized direct mechanisms, the agents use pure strategies in reporting to the mediator who then recommends them to mix their reports to the principal. In our framework, it could also be *a priori* interesting to let agents misrepresent their types with some probability. However, mixing is worthless with private values. The principal's payoff does not depend directly on the agents' types but only indirectly through payments and outputs. The principal's beliefs on the agents' types following their reports do not affect how he chooses outputs at the last stage of the game. This leads to a simple version of the Revelation Principle where agents play pure strategies and the principal chooses an ex post optimal output.⁶²

FOR ONLINE PUBLICATION. APPENDIX C: ALTERNATIVE ASSUMPTIONS

This section first proposes two extensions of the framework developed in Section III. In the first one, we use a specific information structure, slightly different from that in the main text, and show that, with strong correlation, the incentive problem is no longer regular and the principal's opportunism may have almost no cost for the vertical structure. In the second scenario, we instead depart from the main text by investigating optimal contracts in the case of a zero-one decision. It allows us to give a clear upper bound on types correlation that is consistent with regularity of the incentive problem. Finally, this section also comes back to the framework of Section IV.B and study the irrelevance of extended mechanisms.

C1. Strong Correlation

We now consider the polar case of a strong correlation and show that EPIC may have much less impact in such context. To make this point as tractable as possible, we depart from our previous information structure and now adopt the following expression of conditional distributions:

$$(C1) \quad \tilde{F}(\theta_{-i}|\theta_i) = \begin{cases} (1-h)F(\theta_{-i}) & \text{if } \theta_{-i} < \theta_i \\ h + (1-h)F(\theta_{-i}) & \text{if } \theta_{-i} \geq \theta_i \end{cases}$$

⁶¹See Myerson, R., 1986, "Multistage Games with Communication", *Econometrica*, (54): p323-358.

⁶²Notice that in Proposition B.1 as well as in Proposition 1, the direct mechanisms may be stochastic. However, in our analysis of the main text, each time the Revelation Principle is used to derive optimal contracts, the incentive problem is such that non-local incentive compatibility is never a binding constraint for the optimal mechanism when the incentive problem is regular. In a similar setting with one agent and a finite type set, it is known (see Strausz, R., 2006, "Deterministic vs Stochastic Mechanisms in Principal-Agent Models", *Journal of Economic Theory*, (128): p308-314.) that optimal mechanisms are deterministic, so that there is no loss of generality in restricting attention to deterministic direct mechanisms or deterministic nonlinear wholesale prices.

where $h \in [0, 1]$ and $F(\cdot)$ is still the unconditional cumulative distribution. In other words, the distribution puts a Dirac mass on the diagonal $\theta_1 = \theta_2$. We will be particularly interested in the limiting case of perfect correlation where h approaches 1.

Ex post incentive compatible mechanisms are still of the form given in (9). In particular, let us consider the ex post incentive compatible mechanism $\{t_i^h(\theta), q_i^h(\theta)\}_{\theta \in \Theta^n}$ such that:

$$t_i^h(\theta) = \begin{cases} C(q^{fb}(\theta_i)) + hW^{fb}(\theta_i) \\ hW^{fb}(\theta_i) \end{cases} \quad \text{and} \quad q_i^h(\theta) = \begin{cases} q^{fb}(\theta_i) & \text{if } \theta_{-i} = \theta_i \\ 0 & \text{if } \theta_{-i} \neq \theta_i \end{cases}$$

where $W^{fb}(\theta_i) = R(q^{fb}(\theta_i)) - C(q^{fb}(\theta_i)) - \theta_i q^{fb}(\theta_i)$ is the (non-negative) first-best surplus with type θ_i .

That mechanism yields payoff $hW^{fb}(\theta_i)$ to the principal when A_i ' type is θ_i . It rewards agents only if their reports agree which, given the information structure, arises with positive probability only if they both tell the truth. The mechanism is also structured to extract all surplus from the agents. From this remark, we immediately get:

PROPOSITION C.1: *Assume that the information structure is as in (C1). The principal's expected payoff with the mechanism $\{(t_i^h(\theta), q_i^h(\theta))\}_{\theta \in \Theta^n}$ converges toward its first-best value $2E_{\theta_i}(W^{fb}(\theta_i))$ as h converges to one.*

Proof of Proposition C.1. The mechanism $\{t_i^h(\theta), q_i^h(\theta)\}_{\theta \in \Theta^n}$ is ex post incentive compatible for the principal and gives him payoff $hE_{\theta_i}(W^{fb}(\theta_i))$ when dealing with A_i . This payoff converges towards the first-best expected payoff as h converges to one. It remains to be checked whether this mechanism is Bayesian incentive compatible and individually rational. First, participation constraints hold since, by telling the truth, A_i with type θ_i gets:

$$U_i(\theta_i) = hW^{fb}(\theta_i) + (1-h) \times 0 - hW^{fb}(\theta_i) = 0.$$

Second, Bayesian incentive compatibility constraints hold since the non-negativity of the first-best surplus implies:

$$U_i(\theta_i) = 0 \geq h \times 0 + (1-h) \times 0 - hW^{fb}(\hat{\theta}_i) \quad \forall \hat{\theta}_i \neq \theta_i.$$

■

C2. 0-1 Projects

We now suppose that the principal wants to procure a unitary project from each of his retailers. The net return on the project is thus linear and can be written as Sq_i where $q_i \in [0, 1]$ now stands for the (verifiable) probability of undertaking the project (and where $R - C = S$). In such an environment, EPIC requires using a payment schedule which is linear in that probability:

$$T_i(q_i, \hat{\theta}_i) = Sq_i - H_i(\hat{\theta}_i).$$

We shall now assume that

$$(C2) \quad \theta_i < S \text{ and } \varphi(\theta_i, \bar{\theta}) < S < \varphi(\theta_i, \underline{\theta}).$$

The first condition above ensures that it is always optimal to realize the project under complete information while the second condition requires that the other agent's type must be sufficiently "bad news" so as to be the case under asymmetric information.

PROPOSITION C.2: *Assume that*

$$(C3) \quad \tilde{f}(\bar{\theta}|\theta_i) - (S - \theta_i)\tilde{f}_{\theta_i}(\bar{\theta}|\theta_i) \geq 0 \quad \forall \theta_i \in \Theta.$$

Then the incentive problem is regular and the optimal decision rule satisfies:

$$(C4) \quad q_i^{sb}(\theta_i, \theta_{-i}) = \begin{cases} 1 & \text{if } S \geq \varphi(\theta_i, \theta_{-i}), \\ 0 & \text{otherwise.} \end{cases}$$

Proof of Proposition C.2. Proceeding as in the Proof of Proposition 2 and assuming that the principal's problem is regular, but taking into account the linearity yields the following maximand:

$$(\mathcal{P}) : \max_{\mathbf{q}(\cdot) \in [0,1]} \int_{\Theta^2} \tilde{f}(\theta) \left(\sum_{i=1}^2 \left(\left(1 + \frac{F(\theta_i)}{f(\theta_i)} \frac{\tilde{f}_{\theta_i}(\theta_{-i}|\theta_i)}{\tilde{f}(\theta_{-i}|\theta_i)} \right) (S - \theta_i) - \frac{F(\theta_i)}{f(\theta_i)} \right) q_i(\theta) \right) d\theta.$$

Pointwise optimization gives the optimal decision rule defined by (C4). From the fact that $\varphi(\theta_i, \theta_{-i})$ is increasing in θ_i and decreasing in θ_{-i} and because (C2) holds, there exists a non-decreasing function $\eta(\theta_i)$ such that $S = \varphi(\theta_i, \eta(\theta_i))$. Condition (C4) can finally be rewritten as:

$$(C5) \quad q_i^{sb}(\theta_i, \theta_{-i}) = \begin{cases} 1 & \text{if } \theta_{-i} \geq \eta(\theta_i), \\ 0 & \text{otherwise.} \end{cases}$$

With this specification of the decision rule, we can write:

$$U_i^{sb}(\theta_i) = \max_{\hat{\theta}_i \in \Theta} E \left((S - \theta_i) q_i^{sb}(\hat{\theta}_i, \theta_{-i}) | \theta_i \right) - H_i(\hat{\theta}_i) = \max_{\hat{\theta}_i \in \Theta} (S - \theta_i) (1 - \tilde{F}(\eta(\hat{\theta}_i) | \theta_i)) - H_i(\hat{\theta}_i).$$

Because $U_i^{sb}(\theta_i)$ so defined is absolutely continuous, it is almost everywhere differentiable and at any point of differentiability, satisfies:

$$(C6) \quad \dot{U}_i^{sb}(\theta_i) = -(1 - \tilde{F}(\eta(\theta_i) | \theta_i)) - (S - \theta_i) \tilde{F}_{\theta_i}(\eta(\theta_i) | \theta_i).$$

Moreover, absolute continuity also implies:

$$(C7) \quad U_i^{sb}(\theta_i) - U_i^{sb}(\hat{\theta}_i) = \int_{\theta_i}^{\hat{\theta}_i} \left(1 - \tilde{F}(\eta(\tilde{\theta}_i) | \tilde{\theta}_i) + (S - \tilde{\theta}_i) \tilde{F}_{\theta_i}(\eta(\tilde{\theta}_i) | \tilde{\theta}_i) \right) d\tilde{\theta}_i.$$

Incentive compatibility follows when:

$$(C8) \quad \begin{aligned} U_i^{sb}(\theta_i) - U_i^{sb}(\hat{\theta}_i) &\geq (S - \theta_i) (1 - \tilde{F}(\eta(\hat{\theta}_i) | \theta_i)) - (S - \hat{\theta}_i) (1 - \tilde{F}(\eta(\hat{\theta}_i) | \hat{\theta}_i)) \\ &= \int_{\theta_i}^{\hat{\theta}_i} \left(1 - \tilde{F}(\eta(\hat{\theta}_i) | \tilde{\theta}_i) + (S - \tilde{\theta}_i) \tilde{F}_{\theta_i}(\eta(\hat{\theta}_i) | \tilde{\theta}_i) \right) d\tilde{\theta}_i. \end{aligned}$$

Gathering (C7) and (C8), incentive compatibility holds when:

$$(C9) \quad \int_{\theta_i}^{\hat{\theta}_i} \left(\int_{\eta(\hat{\theta}_i)}^{\eta(\tilde{\theta}_i)} ((S - \tilde{\theta}_i) \tilde{f}_{\theta_i}(x | \tilde{\theta}_i) - \tilde{f}(x | \tilde{\theta}_i)) dx \right) d\tilde{\theta}_i \geq 0.$$

Because $\eta(\cdot)$ is non-decreasing, a sufficient condition for (C9) to hold is

$$(C10) \quad \tilde{f}(\theta_{-i} | \theta_i) - (S - \theta_i) \tilde{f}_{\theta_i}(\theta_{-i} | \theta_i) \geq 0 \quad \forall (\theta_i, \theta_{-i}) \in \Theta^2.$$

Integrating this latter condition over $[\eta(\theta_i), \bar{\theta}]$, we obtain:

$$(C11) \quad 1 - \tilde{F}(\eta(\theta_i)|\tilde{\theta}_i) + (S - \theta_i)\tilde{F}_{\theta_i}(\eta(\theta_i)|\theta_i) \geq 0 \quad \forall \theta_i \in \Theta.$$

This shows that the right-hand side of (C6) is negative and the participation constraint (16) is binding at the optimal contract as requested in a regular problem.

Because MLRP holds, $\frac{\tilde{f}_{\theta_i}(\theta_{-i}|\theta_i)}{\tilde{f}(\theta_{-i}|\theta_i)} \leq \frac{\tilde{f}_{\theta_i}(\bar{\theta}|\theta_i)}{\tilde{f}(\bar{\theta}|\theta_i)}$ for all θ_{-i} and, moreover, $\frac{\tilde{f}_{\theta_i}(\bar{\theta}|\theta_i)}{\tilde{f}(\bar{\theta}|\theta_i)}$ is non-negative. From this, it follows that a sufficient condition for (C10) is that it holds at $\theta_{-i} = \bar{\theta}$ as requested by (C3). ■

C3. Extended Mechanisms with Secret Contracts

We now investigate whether the principal would like to deviate to a richer class of bilateral contracts to possibly communicate with retailer A_i the endogenous information he has on the private offers he makes to A_{-i} . Denote thus by \mathcal{M}_i any arbitrary compact message space available to the principal to communicate with A_i and by $\{T_i(q_i, m_i, \hat{\theta}_i)\}_{\{\hat{\theta}_i \in \Theta, m_i \in \mathcal{M}_i\}}$ a menu of so extended nonlinear schemes. We assume that $T_i(q_i, m_i, \hat{\theta}_i)$ is upper semi-continuous in m_i to ensure existence of an optimum at the last stage of the game. Finally, denote by $\mathbf{m}^*(\hat{\theta}) = (m_1^*(\hat{\theta}), m_2^*(\hat{\theta}))$ a selection within the principal's correspondence of best responses to the messages $\hat{\theta} = (\hat{\theta}_1, \hat{\theta}_2)$ sent by the agents. Ex post optimality for the principal implies:

$$(C12) \quad (\mathbf{q}^*(\theta), \mathbf{m}^*(\theta)) \in \arg \max_{\mathbf{q} \in \mathcal{Q}, \mathbf{m} \in \prod_{i=1}^2 \mathcal{M}_i} \sum_{i=1}^2 T_i(q_i, m_i, \theta_i)$$

where the maximum above is achieved by compactness of \mathcal{M}_i and upper semi-continuity in p_i . Let us define the new direct mechanism $(t_i^s(\theta), q_i^s(\theta)) = (T_i(\mathbf{q}_i^*(\theta), m_i^*(\theta), \theta_i), q_i^*(\theta))$. Such a mechanism does not use "extended" reports from the principal and satisfies the agent's Bayesian incentive compatibility constraints. The optimality condition (C12) becomes:

$$\theta \in \arg \max_{\theta \in \Theta^2} \sum_{i=1}^2 t_i^s(\theta_i, \hat{\theta}_{-i}).$$

The new mechanism $(t_i^s(\theta), q_i^s(\theta))$ is thus ex post incentive compatible. This shows that there is no point in enlarging the set of mechanisms available to the principal.